

Thesis proposal

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The proposal for my thesis, *Simulation models for predictive ecology*

1 Introduction

P1

Within
the
last
several
hundred
years,
human
activity
have
rapidly
changed
Earth's
atmosphere,
oceans,
and
surface.
Greenhouse
gas
emissions
have
caused
an
increase
the
temperature
of
both
Earth's
surface
and
oceans
(resulting
in

2 P2

3 However, robust forecasting of ecological processes will change in the future is, to say the least, quite
4 difficult. This difficulty is compounded by a few factors, the first being that sampling ecosystems is not
5 easy. Ecological data is often biased, and noisy, spatially and temporally sparse. As a result *ecosystem*
6 *monitoring* (Makiola *et al.* 2020) has emerged as an imperative. Developing a system for ecological
7 observation, which is able to coordinate across locations. (**AndyUrbanBiomonitoring?** paper).

8

9 The second major challenge in forecasting ecosystems is that the underlying dynamics of most ecological
10 processes are fundamentally unknown (and unknowable) and instead must be inferred.

11 Much of the history of quantitatively modeling ecosystems have been done in the language of dynamical
12 systems, describing how the value of an observable state of the system, represented by a vector of numbers
13 $[x_1, x_2, \dots, x_n]^T = \vec{x}$ changes as over time. It turns out to be much more effective to, rather than attempt to
14 directly model $\vec{x}(t)$ itself, to instead describe how \vec{x} changes from one timestep to the next, yielding
15 models in the form of differential equations in continuous-time settings— $\frac{dx}{dt} = f(x)$ —or difference
16 equations in discrete-time settings— $x_t = f(x_{t-1})$ —where $f : \mathbb{R}^n \rightarrow \mathbb{R}^n$ is an arbitrary function describing
17 how the system changes on a moment-to-moment basis (e.g. in the context of communities, f could be
18 Lotka-Volterra, Holling-Type-III or DeAngelis-Beddington functional response). The form of this
19 functional response in real systems is effectively unknown, and some forms are inherently more
20 “forecastable” than others (Chen *et al.* 2019).

P3

However,
we
run
into
many
problems
when
aiming
to
apply
this
type
of
model
to
empirical
data
in
ecology.

The
initial
success
of
ODE
models
can
be
traced
back
to
the
larger
program
of
ontological
reductionism,
which
became
the
de
facto
approach
model
physical
sciences
after
its
early
success
in
physics,
which,

But
ecosystems
are
perhaps
the
quintessential
example
of
system
that
cannot
be
understood
simply
by
iterative
reduction
of its
components.
Emergent
phenomena,
mechanisms
at
different
scales,
etc.

Some
have
been
explored
in
the
ecological
literature:
(1)
Some
applications
of
dynamic
models
in
ecology
assume
long-
run
equilibrium.
(2)
Stochasticity

(3)

Ecological

processes

vary

across

more

variables

than

the

tools

of

analytic

models

are

suited

for.

As

the

number

of

variables

in an

analytic

model

increases,

so

does

the

ability

of

the

scientist

to

21 *P4*

22 The term *ecological forecasting* implicitly creates an analogy between predicting how ecosystems will
23 change in the future by using the term “forecasting”—the most immediate analog being the success story
24 of weather forecasting via numerical weather prediction (NWP).

25 Although it is become almost hack to complain about the dang weather forecast being wrong, over the
26 least 50 years the (**Bauer2015QuiRev?**).

27 The success of NWP, and the Earth observations that support it should serve as a template for
28 development of a system for monitoring Earth’s biodiversity. Much like ecology, NWP is faced with
29 high-dimensional systems that are governed by different mechanisms at different scales.

30 Much as one would not aim to forecast the weather in Quebec by applying Navier-Stokes. NWP has
31 worked because it incorporates information about data and meteorological processes collected at
32 difference scales into models that. Use of computational methods in NWP.

33 Transition to simulation as the solution: shift toward approach of building models that *generate* data.
34 (resolving the semantic ambuity of what differentiates “mechanistic” vs “phenomological” models is out
35 of scope for now).

36 More broadly a reflection reflect ecology lagging behind the statistical methods used in sciences that face
37 similar challenges (many dimensions, many mechanisms at different scales, each with stochasticity).
38 Chaotic dynamics emerge from simple analytic models, and . Whether ecosystems actually exhibit chaotic
39 behavior is a different question.

P5

But
forecasting
isn't
the
only
difficult
problem
here.

Transition
to
theme
of
optimization
given
unknown
information.

A
forecast
gives
us a
range
of
future
values
with
uncertainty
around
them.

Further
a
convenient
property
that a
forecasting
model's
uncertainty
goes
up
over
time (if
we

In face
of
uncertainty,
decision
making
is an
optimization
problem.

We
have
some
goal
state
for the
future,
and
some
estimate
of
what
the
state of
the
world
will be
given a
set of
actions.

Frame
optimization
problem
mathematically
an

Indeed
Marx's
most
well
known
quote
that
“philosophers
have
hitherto
only
interpreted
the
world
in
various
ways;
the
point
is to
change
it.”

and a
necessary
step
toward
establishing
a just
and
sustainable
world.

[Figure 1 about here.]

P6 – final intro para

Three major components here: 1) Ecosystem monitoring, 2) Forecasting using the products of that monitoring, and 3) Choosing the best possible mitigation strategy.

This flow is outlined in the left panel of fig. 1

Chapter One: Forecasting the spatial uncoupling of a plant-pollinator network

Plants and pollinators form interaction networks, called the “architecture of biodiversity” (**Jordano2007?**).

The stability, function, and persistence of ecosystems relies on the structure of these interactions.

Anthropogenic change threatens to unravel these networks. Two aspects to this change: spatial and temporal. Spatially, range shifts along elevational gradient, and temporally, phenological shifts.

The issue is that we don’t really know what interactions are like now. So not only do we need to predict with data that is spatially and temporally sparse and likely to contain many interaction “false-negatives” (**Strydom2021?**)

54 This chapter uses several years of data on bee-flower phenology and interactions, combined with spatial
55 records of species occurrence via GBIF, to forecast how much overlap there will be between
56 plants/pollinators in space/time.

57 In stages, (1) take data from multiple sites to predict a spatial metaweb of *Bombus*-flower interactions
58 across Colorado. (2) Predict how these spatial distributions will change under CMIP6. and (3) quantify the
59 lack of overlap between species for which there is a predicted

60 **CH1 concept figure**

61 **Data**

62 System description: lots of data on *Bombus* (bumblebees) and wildflowers. Three different sites, (7/7/3)
63 years each, each covering an elevational gradient.

64 **Methods**

65 Split the process into parts.

- 66 1) Building an interaction prediction model.
- 67 2) Make it spatial based on distributions.
- 68 3) Forecast distributions based on CMIP6.

69 **Preliminary Results**

- 70 1) we got a tree

71 Transition to next chapter by discussing uncertainty in interaction prediction across space.

72 **CH2 optimizing sampling of interactions**

73 This chapter quantifies the relationship between a given species relative abundance and the sampling
74 effort needed to adequately understand this species distribution and interactions.

75 For a given sample of interaction data, and proposes a method for optimizing spatial sampling of a
76 possible interaction between species as a function of the estimated distribution of both species.

77 **Methods**

- 78 • the missing link paper, turn this into optimizing with two different SDMs
- 79 • relative abundance and its effect on false negative
- 80 • non-independent associations in samples
- 81 • simulate species distribution and efficacy of detection given a set of observation points where the
82 dist from observation site decays.
- 83 • optimize set of repeated sampling locations L for a *known* distribution D .
- 84 • address SDM not being the territory

85 **Results**

86 **In-progress results**

87 **CH3 optimizing corridor placement**

88 This chapter proposes an algorithm for optimizing restoration across space
89 (corridorplacement/restoration effort) given a raster where each cell indicates land-cover. The
90 optimization method uses the result of a simulated process (specifically occupancy dynamics in the
91 landscape) and uses simulated annealing to estimate the global optimum of the targetstate (specifically
92 mean-time-to-extinction for the occupancy dynamics example).

93 **Methods**

- 94 • land cover -> resistance -> extinction time
- 95 • simulated annealing to optimize landscape optimization

CH4 a software note on the resulting packages.

(MetacommunityDynamics.jl: a virtual laboratory for community ecology): a collection of modules in the Julia language for different aspects of metacommunity ecology, including most of the code used for the preceding chapters.

- TK conceptual figure with interfaces between what I’m writing / have contributed to and linked with other libraries
- Observatories.jl, Corridors.jl, MCD.jl

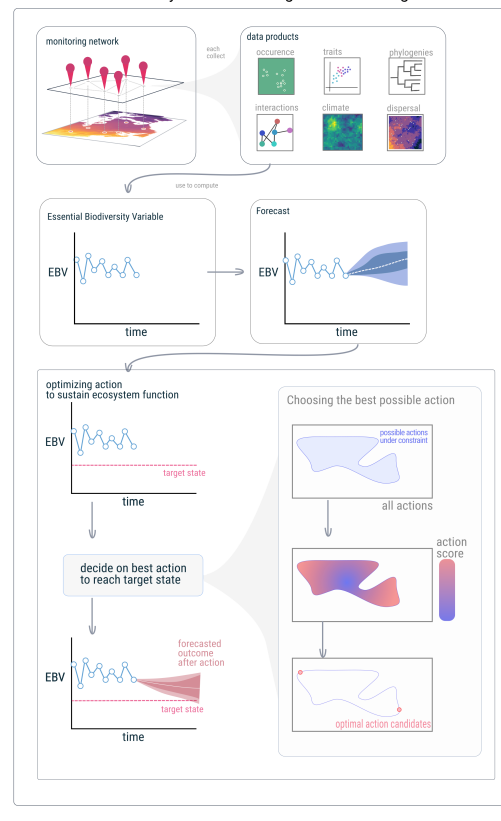
concl

// this is a discussion para An oft applied definition of the origin of is “the application of the scientific method to natural history.” Since its origin ecology has been a descriptive science. This is a natural by-product of the immense variability of Earth’s biosphere. emerged to explain particular phenomena at particular scales. In recent years, there has been an interest in an epistemological shift in ecology. To shift ecology into a predictive science. The justification for this shift is twofold: (1) bogged down philosophy of science, by further rooting our understanding of ecosystem function and dynamics in an ability to predict their structure (Dietze 2017). and (2) the practical need for models for *ecological forecasting*.

References

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- Makiola, A., Compson, Z.G., Baird, D.J., Barnes, M.A., Boerlijst, S.P., Bouchez, A., *et al.* (2020). Key Questions for Next-Generation Biomonitoring. *Frontiers in Environmental Science*, 7.

A framework for ecosystem monitoring and forecasting



Simulation models for predictive ecology

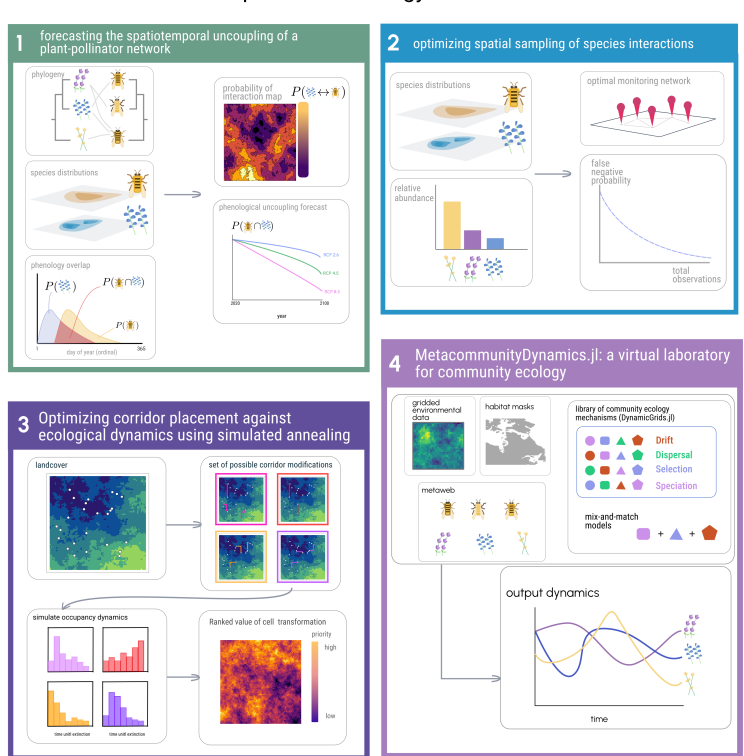


Figure 1: thesis concept