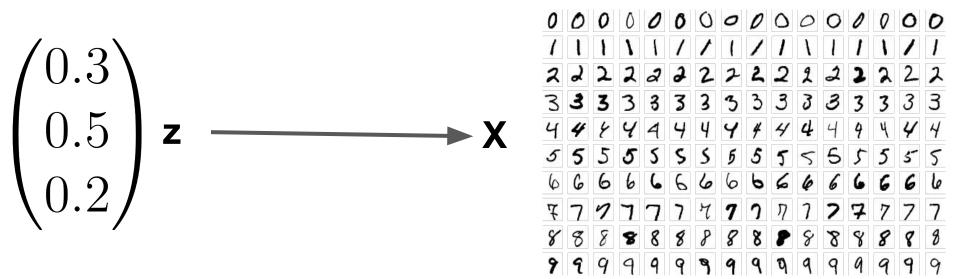
Auto-Encoding Variational Bayes

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Problem scenario

Let us consider some dataset $\mathbf{X} = \{\mathbf{x}^{(i)}\}_{i=1}^{N}$ consisting of N i.i.d. samples of some continuous or discrete variable \mathbf{x} . We assume that the data are generated by some random process, involving an unobserved continuous random variable \mathbf{z} . The process consists of two steps: (1) a value $\mathbf{z}^{(i)}$ is generated from some prior distribution $p_{\boldsymbol{\theta}^*}(\mathbf{z})$; (2) a value $\mathbf{x}^{(i)}$ is generated from some conditional distribution $p_{\boldsymbol{\theta}^*}(\mathbf{x}|\mathbf{z})$.



Marginal likelihood

Given a set of independent identically distributed data points $\mathbf{X}=(x_1,\ldots,x_n)$, where $x_i\sim p(x|\theta)$ according to some probability distribution parameterized by θ , where θ itself is a random variable described by a distribution, i.e. $\theta\sim p(\theta\mid\alpha)$, the marginal likelihood in general asks what the probability $p(\mathbf{X}\mid\alpha)$ is, where θ has been marginalized out (integrated out):

$$p(\mathbf{X} \mid lpha) = \int_{a} p(\mathbf{X} \mid heta) \, p(heta \mid lpha) \, \, \mathrm{d} heta$$

$$\int p_{\boldsymbol{\theta}}(\mathbf{z}) p_{\boldsymbol{\theta}}(\mathbf{x}|\mathbf{z}) d\mathbf{z}$$

In our case:

Problems with existing methods

- 1. Intractability: the case where the integral of the marginal likelihood $p_{\theta}(\mathbf{x}) = \int p_{\theta}(\mathbf{z}) p_{\theta}(\mathbf{x}|\mathbf{z}) d\mathbf{z}$ is intractable (so we cannot evaluate or differentiate the marginal likelihood), where the true posterior density $p_{\theta}(\mathbf{z}|\mathbf{x}) = p_{\theta}(\mathbf{x}|\mathbf{z})p_{\theta}(\mathbf{z})/p_{\theta}(\mathbf{x})$ is intractable (so the EM algorithm cannot be used), and where the required integrals for any reasonable mean-field VB algorithm are also intractable. These intractabilities are quite common and appear in cases of moderately complicated likelihood functions $p_{\theta}(\mathbf{x}|\mathbf{z})$, e.g. a neural network with a nonlinear hidden layer.
- 2. *A large dataset*: we have so much data that batch optimization is too costly; we would like to make parameter updates using small minibatches or even single datapoints. Sampling-based solutions, e.g. Monte Carlo EM, would in general be too slow, since it involves a typically expensive sampling loop per datapoint.

Method

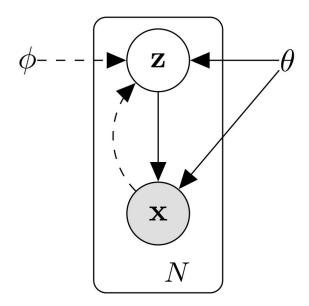


Figure 1: The type of directed graphical model under consideration. Solid lines denote the generative model $p_{\theta}(\mathbf{z})p_{\theta}(\mathbf{x}|\mathbf{z})$, dashed lines denote the variational approximation $q_{\phi}(\mathbf{z}|\mathbf{x})$ to the intractable posterior $p_{\theta}(\mathbf{z}|\mathbf{x})$. The variational parameters ϕ are learned jointly with the generative model parameters θ .

Probabilistic encoder definition

$$p_{\theta}(z|x) \longrightarrow q_{\phi}(z|x)$$

Probabilistic decoder definition

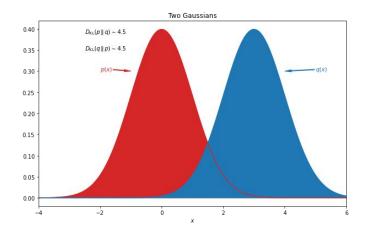
$$p_{\theta}(x|z)$$

This solves intractability!

Kullback-Leibler divergence

The Kullback-Leibler divergence is a measure of the dissimilarity between two probability distributions.

$$D_{\mathrm{KL}}(p \parallel q) + H(p) = H(p,q)$$



Variational lower bound

 $\log p_{\boldsymbol{\theta}}(\mathbf{x}^{(i)}) = D_{KL}(q_{\boldsymbol{\phi}}(\mathbf{z}|\mathbf{x}^{(i)})||p_{\boldsymbol{\theta}}(\mathbf{z}|\mathbf{x}^{(i)})) + \mathcal{L}(\boldsymbol{\theta}, \boldsymbol{\phi}; \mathbf{x}^{(i)})$ $\log p_{\boldsymbol{\theta}}(\mathbf{x}^{(i)}) \geq \mathcal{L}(\boldsymbol{\theta}, \boldsymbol{\phi}; \mathbf{x}^{(i)})$

Now we can optimize
$$\mathcal{L}(oldsymbol{ heta},oldsymbol{\phi};\mathbf{x}^{(i)})$$
 instead!

But the gradient of L can't be approximated well with Monte-Carlo methods



Idea of reparametrization

$$\widetilde{\mathbf{z}} \sim q_{\phi}(\mathbf{z}|\mathbf{x}) \Longrightarrow \widetilde{\mathbf{z}} = g_{\phi}(\boldsymbol{\epsilon}, \mathbf{x}) \quad \text{with} \quad \boldsymbol{\epsilon} \sim p(\boldsymbol{\epsilon})$$

- 1. Tractable inverse CDF. In this case, let $\epsilon \sim \mathcal{U}(\mathbf{0}, \mathbf{I})$, and let $g_{\phi}(\epsilon, \mathbf{x})$ be the inverse CDF of $q_{\phi}(\mathbf{z}|\mathbf{x})$. Examples: Exponential, Cauchy, Logistic, Rayleigh, Pareto, Weibull, Reciprocal, Gompertz, Gumbel and Erlang distributions.
- 2. Analogous to the Gaussian example, for any "location-scale" family of distributions we can choose the standard distribution (with location = 0, scale = 1) as the auxiliary variable ϵ , and let $g(.) = \text{location} + \text{scale} \cdot \epsilon$. Examples: Laplace, Elliptical, Student's t, Logistic, Uniform, Triangular and Gaussian distributions.
- 3. Composition: It is often possible to express random variables as different transformations of auxiliary variables. Examples: Log-Normal (exponentiation of normally distributed variable), Gamma (a sum over exponentially distributed variables), Dirichlet (weighted sum of Gamma variates), Beta, Chi-Squared, and F distributions.

Stochastic Gradient Variational Bayes estimator

We can now form Monte Carlo estimates of expectations of some function $f(\mathbf{z})$ w.r.t. $q_{\phi}(\mathbf{z}|\mathbf{x})$ as follows:

$$\mathbb{E}_{q_{\phi}(\mathbf{z}|\mathbf{x}^{(i)})}[f(\mathbf{z})] = \mathbb{E}_{p(\epsilon)}\left[f(g_{\phi}(\epsilon, \mathbf{x}^{(i)}))\right] \simeq \frac{1}{L} \sum_{i=1}^{L} f(g_{\phi}(\epsilon^{(i)}, \mathbf{x}^{(i)})) \quad \text{where} \quad \epsilon^{(l)} \sim p(\epsilon) \quad (5)$$

We apply this technique to the variational lower bound (eq. (2)), yielding our generic Stochastic Gradient Variational Bayes (SGVB) estimator $\widetilde{\mathcal{L}}^A(\boldsymbol{\theta}, \boldsymbol{\phi}; \mathbf{x}^{(i)}) \simeq \mathcal{L}(\boldsymbol{\theta}, \boldsymbol{\phi}; \mathbf{x}^{(i)})$:

$$\widetilde{\mathcal{L}}^{A}(\boldsymbol{\theta}, \boldsymbol{\phi}; \mathbf{x}^{(i)}) = \frac{1}{L} \sum_{l=1}^{L} \log p_{\boldsymbol{\theta}}(\mathbf{x}^{(i)}, \mathbf{z}^{(i,l)}) - \log q_{\boldsymbol{\phi}}(\mathbf{z}^{(i,l)} | \mathbf{x}^{(i)})$$

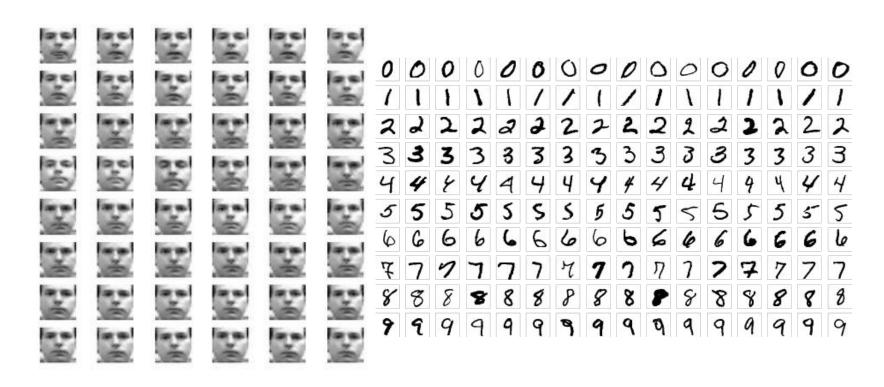
where $\mathbf{z}^{(i,l)} = g_{\phi}(\boldsymbol{\epsilon}^{(i,l)}, \mathbf{x}^{(i)})$ and $\boldsymbol{\epsilon}^{(l)} \sim p(\boldsymbol{\epsilon})$ (6)

Auto-Encoding Variational Bayesian algorithm

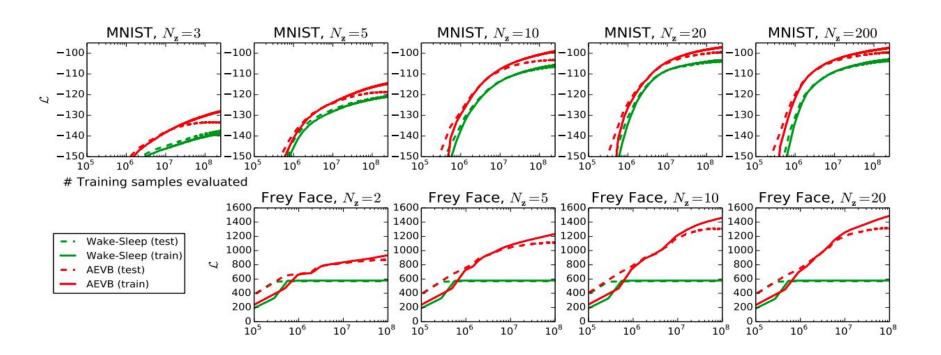
Algorithm 1 Minibatch version of the Auto-Encoding VB (AEVB) algorithm. Either of the two SGVB estimators in section 2.3 can be used. We use settings M=100 and L=1 in experiments.

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\begin{array}{l} \boldsymbol{\theta}, \boldsymbol{\phi} \leftarrow \text{Initialize parameters} \\ \textbf{repeat} \\ \textbf{X}^M \leftarrow \text{Random minibatch of } M \text{ datapoints (drawn from full dataset)} \\ \boldsymbol{\epsilon} \leftarrow \text{Random samples from noise distribution } p(\boldsymbol{\epsilon}) \\ \textbf{g} \leftarrow \nabla_{\boldsymbol{\theta}, \boldsymbol{\phi}} \widetilde{\mathcal{L}}^M(\boldsymbol{\theta}, \boldsymbol{\phi}; \mathbf{X}^M, \boldsymbol{\epsilon}) \text{ (Gradients of minibatch estimator (8))} \\ \boldsymbol{\theta}, \boldsymbol{\phi} \leftarrow \text{Update parameters using gradients g (e.g. SGD or Adagrad [DHS10])} \\ \textbf{until convergence of parameters } (\boldsymbol{\theta}, \boldsymbol{\phi}) \\ \textbf{return } \boldsymbol{\theta}, \boldsymbol{\phi} \end{array}
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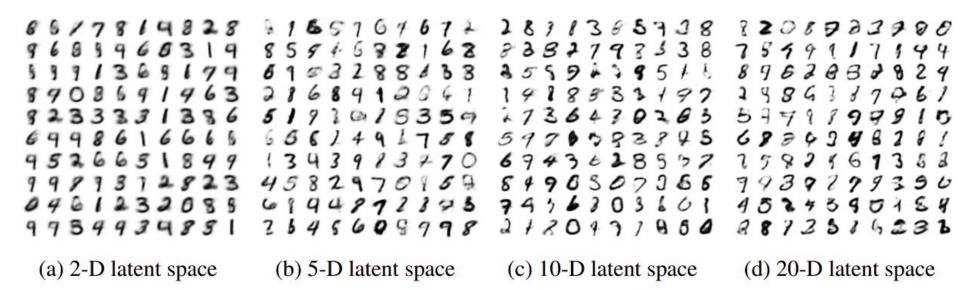
Frey Face and MNIST Datasets



Results for Frey Face and MNIST:



Visualisations of learned data manifold for generative models with two-dimensional latent space, learned with AEVB.



Thank you for attention

