

Importing Libraries and Dataset

```
In [ ]: import pandas as pd
import numpy as np
import matplotlib.pyplot as plt
import cv2 as cv
import os
import csv
import math
import tensorflow as tf
from tensorflow import keras
import skimage
from skimage.feature import greycomatrix, greycoprops
from skimage import io
from datetime import datetime
from functools import reduce
import datetime as dt
import seaborn as sns
from itertools import chain
from sklearn.model_selection import train_test_split
from sklearn.preprocessing import LabelEncoder, MinMaxScaler
from sklearn.metrics import confusion_matrix, accuracy_score, classification_report
from imblearn.over_sampling import RandomOverSampler
from sklearn.svm import SVC
from sklearn.linear_model import LogisticRegression
from keras.layers import CuDNNLSTM, Dense, Dropout, LSTM
from sklearn.ensemble import RandomForestClassifier
import warnings
warnings.simplefilter(action='ignore', category=FutureWarning)
```

```
In [ ]: ## Vehicle 1 ##
v1_lin_acc = pd.read_csv("16/aceleracaoLinear_terra.csv")
v1_acc = pd.read_csv("16/acelerometro_terra.csv")
v1_magneto = pd.read_csv("16/campoMagnetico_terra.csv")
v1_gyro = pd.read_csv("16/giroscopio_terra.csv")
v1_label = pd.read_csv("16/groundTruth.csv")

## Vehicle 2 ##
v2_lin_acc = pd.read_csv("17/aceleracaoLinear_terra.csv")
v2_acc = pd.read_csv("17/acelerometro_terra.csv")
v2_magneto = pd.read_csv("17/campoMagnetico_terra.csv")
v2_gyro = pd.read_csv("17/giroscopio_terra.csv")
v2_label = pd.read_csv("17/groundTruth.csv")

## Vehicle 3 ##
v3_lin_acc = pd.read_csv("20/aceleracaoLinear_terra.csv")
v3_acc = pd.read_csv("20/acelerometro_terra.csv")
v3_magneto = pd.read_csv("20/campoMagnetico_terra.csv")
v3_gyro = pd.read_csv("20/giroscopio_terra.csv")
v3_label = pd.read_csv("20/groundTruth.csv")

## Vehicle 4 ##
v4_lin_acc = pd.read_csv("21/aceleracaoLinear_terra.csv")
v4_acc = pd.read_csv("21/acelerometro_terra.csv")
v4_magneto = pd.read_csv("21/campoMagnetico_terra.csv")
v4_gyro = pd.read_csv("21/giroscopio_terra.csv")
v4_label = pd.read_csv("21/groundTruth.csv")
```

Data Preprocessing

```
In [ ]: new_label_column_names = ["event", "start_time", "end_time"]
new_lin_acc_names = ["timestamp", "time_nano", "x_lin_acc", "y_lin_acc", "z_lin_acc"]
new_acc_names = ["timestamp", "time_nano", "x_acc", "y_acc", "z_acc"]
new_magneto_names = ["timestamp", "time_nano", "x_magneto", "y_magneto", "z_magneto"]
new_gyro_names = ["timestamp", "time_nano", "x_gyro", "y_gyro", "z_gyro"]

v1_label.columns = v2_label.columns = v3_label.columns = v4_label.columns = new_label_column_names
v1_lin_acc.columns = v2_lin_acc.columns = v3_lin_acc.columns = v4_lin_acc.columns = new_lin_acc_names
v1_acc.columns = v2_acc.columns = v3_acc.columns = v4_acc.columns = new_acc_names
v1_magneto.columns = v2_magneto.columns = v3_magneto.columns = v4_magneto.columns = new_magneto_names
v1_gyro.columns = v2_gyro.columns = v3_gyro.columns = v4_gyro.columns = new_gyro_names

old_label_names = ["evento_nao_agressivo", "curva_direita_agressiva", "curva_esquerda_agressiva"]
new_label_names = ["Non aggressive", "Agressive right turn", "Agressive left turn", "Aggressive right lane change"]

v1_label["event"] = v1_label["event"].replace(old_label_names, new_label_names)
v2_label["event"] = v2_label["event"].replace(old_label_names, new_label_names)
v3_label["event"] = v3_label["event"].replace(old_label_names, new_label_names)
v4_label["event"] = v4_label["event"].replace(old_label_names, new_label_names)

v1_label
```

```
Out[ ]:
```

| | event | start_time | end_time |
|----|------------------------------|------------|----------|
| 0 | Non aggressive | 2.0 | 6.5 |
| 1 | Agressive right turn | 19.5 | 23.5 |
| 2 | Non aggressive | 30.0 | 33.5 |
| 3 | Agressive right turn | 95.0 | 98.0 |
| 4 | Agressive left turn | 247.0 | 251.5 |
| 5 | Agressive left turn | 348.7 | 352.3 |
| 6 | Non aggressive | 485.0 | 489.0 |
| 7 | Agressive left turn | 496.0 | 499.5 |
| 8 | Agressive right turn | 587.0 | 590.0 |
| 9 | Agressive left turn | 750.0 | 753.8 |
| 10 | Agressive right turn | 840.7 | 844.0 |
| 11 | Agressive right turn | 980.0 | 983.2 |
| 12 | Agressive left turn | 1087.4 | 1090.9 |
| 13 | Aggressive right lane change | 1139.8 | 1142.0 |
| 14 | Aggressive right lane change | 1201.0 | 1202.9 |
| 15 | Aggressive right lane change | 1211.4 | 1213.5 |

```
In [ ]: v1_label["event"] = v1_label["event"].replace(old_label_names, new_label_names)
v2_label["event"] = v2_label["event"].replace(old_label_names, new_label_names)
v3_label["event"] = v3_label["event"].replace(old_label_names, new_label_names)
v4_label["event"] = v4_label["event"].replace(old_label_names, new_label_names)
```

```
In [ ]: len(v1_lin_acc), len(v1_acc), len(v1_gyro), len(v1_magneto["time_nano"].unique()), len(v1_gyro["time_nano"].unique())
```

```
Out[ ]: (64645,
        64645,
        64645,
        64645,
        20675,
        20675,
        20675,
        20675,
        30014,
        30014,
        30014,
        30014,
        41178,
        41178,
        41178,
        41178)
```

```
In [ ]: v1_magneto['time_centiseconds'] = (np.array(v1_magneto['time_nano'])/100000000).astype
v1_magneto
```

```
Out[ ]:
```

| | timestamp | time_nano | x_magneto | y_magneto | z_magneto | time_centiseconds |
|---------------|------------------------|----------------|-------------------|-----------|------------|-------------------|
| 0 | 14/05/2016 10:54:33 | 11537628641797 | -1.184853e- 07 | 40.994006 | -7.966440 | 115376 |
| 1 | 14/05/2016 10:54:33 | 11537648266397 | -6.832270e- 07 | 41.030238 | -8.112972 | 115376 |
| 2 | 14/05/2016 10:54:33 | 11537667890997 | -1.365388e- 07 | 40.863243 | -7.899277 | 115376 |
| 3 | 14/05/2016 10:54:33 | 11537667890997 | -6.260234e- 08 | 40.862746 | -7.901860 | 115376 |
| 4 | 14/05/2016 10:54:33 | 11537687485076 | -9.552314e- 07 | 40.778226 | -8.027510 | 115376 |
| ... | ... | ... | ... | ... | ... | ... |
| 128951 | 14/05/2016 11:15:42 | 12806689529792 | -1.117587e- 08 | 15.251873 | -10.477536 | 128066 |
| 128952 | 14/05/2016 11:15:42 | 12806709337514 | -1.117587e- 08 | 15.045683 | -10.811708 | 128067 |
| 128953 | 14/05/2016 11:15:42 | 12806709337514 | -4.228204e- 07 | 15.057556 | -10.795168 | 128067 |
| 128954 | 14/05/2016 11:15:42 | 12806728840032 | -4.479662e- 07 | 15.153189 | -10.435536 | 128067 |
| 128955 | 14/05/2016 11:15:42 | 12806728840032 | 2.672896e- 07 | 15.156427 | -10.430830 | 128067 |

128956 rows × 6 columns

```
In [ ]: v1_lin_acc['time_centiseconds'] = (np.array(v1_lin_acc['time_nano'])/100000000).astype
v1_lin_acc
```

```
Out[ ]:
```

| | timestamp | time_nano | x_lin_acc | y_lin_acc | z_lin_acc | time_centiseconds |
|----------|---------------------|----------------|-----------|-----------|-----------|-------------------|
| 0 | 14/05/2016 10:54:33 | 11537640270059 | -0.161602 | 0.120174 | -0.209893 | 115376 |
| 1 | 14/05/2016 10:54:33 | 11537650128140 | -0.122628 | 0.315638 | -0.380996 | 115376 |

| | timestamp | time_nano | x_lin_acc | y_lin_acc | z_lin_acc | time_centiseconds |
|--------------|---------------------|----------------|-----------|-----------|-----------|-------------------|
| 2 | 14/05/2016 10:54:33 | 11537659894659 | -0.178777 | 0.330181 | -0.360696 | 115376 |
| 3 | 14/05/2016 10:54:33 | 11537679549779 | 0.016043 | 0.038759 | -0.278204 | 115376 |
| 4 | 14/05/2016 10:54:33 | 11537699204899 | 0.141716 | -0.162492 | -0.049796 | 115376 |
| ... | ... | ... | ... | ... | ... | ... |
| 64640 | 14/05/2016 11:15:42 | 12806642253734 | -0.462898 | -0.330468 | -0.780452 | 128066 |
| 64641 | 14/05/2016 11:15:42 | 12806661878334 | 0.274546 | 0.864909 | 0.532109 | 128066 |
| 64642 | 14/05/2016 11:15:42 | 12806681472414 | 0.711429 | 0.930382 | 1.186323 | 128066 |
| 64643 | 14/05/2016 11:15:42 | 12806701066493 | 0.674247 | -0.342384 | 0.097795 | 128067 |
| 64644 | 14/05/2016 11:15:42 | 12806720843694 | 0.203667 | -1.021377 | -0.435942 | 128067 |

64645 rows × 6 columns

```
In [ ]: v1_acc['time_centiseconds'] = (np.array(v1_acc['time_nano'])/100000000).astype(int)
v1_acc
```

| | timestamp | time_nano | x_acc | y_acc | z_acc | time_centiseconds |
|--------------|---------------------|----------------|-----------|-----------|-----------|-------------------|
| 0 | 14/05/2016 10:54:33 | 11537640270059 | -0.161602 | 0.120174 | 9.596758 | 115376 |
| 1 | 14/05/2016 10:54:33 | 11537650128140 | -0.122628 | 0.315638 | 9.425655 | 115376 |
| 2 | 14/05/2016 10:54:33 | 11537659894659 | -0.178777 | 0.330180 | 9.445955 | 115376 |
| 3 | 14/05/2016 10:54:33 | 11537679549779 | 0.016043 | 0.038759 | 9.528445 | 115376 |
| 4 | 14/05/2016 10:54:33 | 11537699204899 | 0.141716 | -0.162492 | 9.756854 | 115376 |
| ... | ... | ... | ... | ... | ... | ... |
| 64640 | 14/05/2016 11:15:42 | 12806642253734 | -0.462898 | -0.330468 | 9.026200 | 128066 |
| 64641 | 14/05/2016 11:15:42 | 12806661878334 | 0.274546 | 0.864909 | 10.338760 | 128066 |
| 64642 | 14/05/2016 11:15:42 | 12806681472414 | 0.711429 | 0.930382 | 10.992975 | 128066 |
| 64643 | 14/05/2016 11:15:42 | 12806701066493 | 0.674247 | -0.342384 | 9.904447 | 128067 |
| 64644 | 14/05/2016 11:15:42 | 12806720843694 | 0.203667 | -1.021377 | 9.370710 | 128067 |

64645 rows × 6 columns

```
In [ ]: v1_gyro['time_centiseconds'] = (np.array(v1_gyro['time_nano'])/100000000).astype(int)
v1_gyro
```

| | timestamp | time_nano | x_gyro | y_gyro | z_gyro | time_centiseconds |
|----------|---------------------|----------------|-----------|-----------|-----------|-------------------|
| 0 | 14/05/2016 10:54:33 | 11537635386799 | -0.070372 | 0.000844 | 0.029619 | 115376 |
| 1 | 14/05/2016 10:54:33 | 11537645580604 | -0.058695 | 0.009130 | 0.024406 | 115376 |
| 2 | 14/05/2016 10:54:33 | 11537667280589 | 0.006625 | -0.002283 | -0.015018 | 115376 |
| 3 | 14/05/2016 10:54:33 | 11537684829803 | 0.064933 | 0.033172 | -0.040503 | 115376 |
| 4 | 14/05/2016 10:54:33 | 11537704912208 | 0.039454 | -0.013078 | -0.007681 | 115377 |

| | timestamp | time_nano | x_gyro | y_gyro | z_gyro | time_centiseconds |
|--------------|---------------------|----------------|-----------|-----------|-----------|-------------------|
| ... | ... | ... | ... | ... | ... | ... |
| 64640 | 14/05/2016 11:15:42 | 12806647564279 | -0.194610 | 0.150351 | -0.012446 | 128066 |
| 64641 | 14/05/2016 11:15:42 | 12806667158359 | -0.167431 | 0.199986 | 0.020079 | 128066 |
| 64642 | 14/05/2016 11:15:42 | 12806686752439 | 0.064197 | 0.053792 | 0.079096 | 128066 |
| 64643 | 14/05/2016 11:15:42 | 12806706438078 | 0.179586 | -0.106454 | 0.048294 | 128067 |
| 64644 | 14/05/2016 11:15:42 | 12806726062678 | 0.067985 | -0.133239 | -0.087171 | 128067 |

64645 rows × 6 columns

```
In [ ]: len(v1_lin_acc['time_centiseconds'].unique())
```

Out[]: 12692

```
In [ ]: v1_lin_acc['time_centiseconds'] = (np.array(v1_lin_acc['time_nano'])/100000000).astype(int)
v1_acc['time_centiseconds'] = (np.array(v1_acc['time_nano'])/100000000).astype(int)
v1_magneto['time_centiseconds'] = (np.array(v1_magneto['time_nano'])/100000000).astype(int)
v1_gyro['time_centiseconds'] = (np.array(v1_gyro['time_nano'])/100000000).astype(int)

v2_lin_acc['time_centiseconds'] = (np.array(v2_lin_acc['time_nano'])/100000000).astype(int)
v2_acc['time_centiseconds'] = (np.array(v2_acc['time_nano'])/100000000).astype(int)
v2_magneto['time_centiseconds'] = (np.array(v2_magneto['time_nano'])/100000000).astype(int)
v2_gyro['time_centiseconds'] = (np.array(v2_gyro['time_nano'])/100000000).astype(int)

v3_lin_acc['time_centiseconds'] = (np.array(v3_lin_acc['time_nano'])/100000000).astype(int)
v3_acc['time_centiseconds'] = (np.array(v3_acc['time_nano'])/100000000).astype(int)
v3_magneto['time_centiseconds'] = (np.array(v3_magneto['time_nano'])/100000000).astype(int)
v3_gyro['time_centiseconds'] = (np.array(v3_gyro['time_nano'])/100000000).astype(int)

v4_lin_acc['time_centiseconds'] = (np.array(v4_lin_acc['time_nano'])/100000000).astype(int)
v4_acc['time_centiseconds'] = (np.array(v4_acc['time_nano'])/100000000).astype(int)
v4_magneto['time_centiseconds'] = (np.array(v4_magneto['time_nano'])/100000000).astype(int)
v4_gyro['time_centiseconds'] = (np.array(v4_gyro['time_nano'])/100000000).astype(int)
```

```
In [ ]: v1_magneto = v1_magneto.groupby('time_centiseconds', as_index=False, sort=False)['x_
v2_magneto = v2_magneto.groupby('time_centiseconds', as_index=False, sort=False)['x_
v3_magneto = v3_magneto.groupby('time_centiseconds', as_index=False, sort=False)['x_
v4_magneto = v4_magneto.groupby('time_centiseconds', as_index=False, sort=False)['x_

v1_gyro = v1_gyro.groupby('time_centiseconds', as_index=False, sort=False)['x_gyro',
v2_gyro = v2_gyro.groupby('time_centiseconds', as_index=False, sort=False)['x_gyro',
v3_gyro = v3_gyro.groupby('time_centiseconds', as_index=False, sort=False)['x_gyro',
v4_gyro = v4_gyro.groupby('time_centiseconds', as_index=False, sort=False)['x_gyro',

v1_acc = v1_acc.groupby('time_centiseconds', as_index=False, sort=False)['x_acc', 'y_
v2_acc = v2_acc.groupby('time_centiseconds', as_index=False, sort=False)['x_acc', 'y_
v3_acc = v3_acc.groupby('time_centiseconds', as_index=False, sort=False)['x_acc', 'y_
v4_acc = v4_acc.groupby('time_centiseconds', as_index=False, sort=False)['x_acc', 'y_

v1_lin_acc = v1_lin_acc.groupby('time_centiseconds', as_index=False, sort=False)['x_
v2_lin_acc = v2_lin_acc.groupby('time_centiseconds', as_index=False, sort=False)['x_
v3_lin_acc = v3_lin_acc.groupby('time_centiseconds', as_index=False, sort=False)['x_
v4_lin_acc = v4_lin_acc.groupby('time_centiseconds', as_index=False, sort=False)['x_
```

```
In [ ]: v1_magneto
```

```
Out[ ]:
```

| | time_centiseconds | x_magneto | y_magneto | z_magneto |
|-------|-------------------|---------------|-----------|------------|
| 0 | 115376 | -2.544296e-07 | 40.885231 | -7.985273 |
| 1 | 115377 | -9.658916e-08 | 40.611182 | -7.537545 |
| 2 | 115378 | -1.441941e-07 | 40.690295 | -7.378162 |
| 3 | 115379 | -1.575346e-07 | 41.221873 | -7.740907 |
| 4 | 115380 | 3.883603e-08 | 41.311051 | -8.667088 |
| ... | ... | ... | ... | ... |
| 12687 | 128063 | 1.620967e-07 | 14.970525 | -10.320365 |
| 12688 | 128064 | -1.456589e-07 | 15.004607 | -10.723637 |
| 12689 | 128065 | 4.847534e-08 | 15.097503 | -10.660156 |
| 12690 | 128066 | -1.252629e-07 | 15.290653 | -10.628135 |
| 12691 | 128067 | -1.536682e-07 | 15.103214 | -10.618311 |

12692 rows × 4 columns

```
In [ ]: len(v1_lin_acc), len(v1_acc), len(v1_gyro),len(v1_magneto),len(v2_lin_acc), len(v2_a
```

```
Out[ ]: (12692,  
12692,  
12692,  
12692,  
4059,  
4059,  
4059,  
4059,  
5892,  
5892,  
5892,  
5892,  
8084,  
8084,  
8084,  
8084)
```

```
In [ ]: v1_lin_acc.set_index('time_centiseconds',inplace=True)  
v1_acc.set_index('time_centiseconds',inplace=True)  
v1_magneto.set_index('time_centiseconds',inplace=True)  
v1_gyro.set_index('time_centiseconds',inplace=True)  
vehicle_1 = pd.concat([v1_lin_acc, v1_acc, v1_magneto, v1_gyro], axis=1, sort=False)  
vehicle_1.rename(columns = {'index':'time_centiseconds'})  
#vehicle_1['time_centiseconds'] = pd.to_datetime(vehicle_1['time_centiseconds'])  
initial_time1 = [vehicle_1['time_centiseconds'][0]]*len(vehicle_1)  
#initial_time1 = pd.to_datetime(initial_time1)  
vehicle_1['Time seconds'] = np.array(vehicle_1['time_centiseconds']-initial_time1)/1  
  
v2_lin_acc.set_index('time_centiseconds',inplace=True)  
v2_acc.set_index('time_centiseconds',inplace=True)  
v2_magneto.set_index('time_centiseconds',inplace=True)  
v2_gyro.set_index('time_centiseconds',inplace=True)  
vehicle_2 = pd.concat([v2_lin_acc, v2_acc, v2_magneto, v2_gyro], axis=1, sort=False)
```

```

vehicle_2.rename(columns = {'index':'time_centiseconds'})
#vehicle_2['time_centiseconds'] = pd.to_datetime(vehicle_1['time_centiseconds'])
initial_time2 = [vehicle_2['time_centiseconds'][0]]*len(vehicle_2)
#initial_time2 = pd.to_datetime(initial_time2)
vehicle_2['Time seconds'] = np.array(vehicle_2['time_centiseconds']-initial_time2)/1

v3_lin_acc.set_index('time_centiseconds',inplace=True)
v3_acc.set_index('time_centiseconds',inplace=True)
v3_magneto.set_index('time_centiseconds',inplace=True)
v3_gyro.set_index('time_centiseconds',inplace=True)
vehicle_3 = pd.concat([v3_lin_acc, v3_acc, v3_magneto, v3_gyro], axis=1, sort=False)
vehicle_3.rename(columns = {'index':'time_centiseconds'})
#vehicle_3['time_centiseconds'] = pd.to_datetime(vehicle_3['time_centiseconds'])
initial_time3 = [vehicle_3['time_centiseconds'][0]]*len(vehicle_3)
#initial_time3 = pd.to_datetime(initial_time3)
vehicle_3['Time seconds'] = np.array(vehicle_3['time_centiseconds']-initial_time3)/1

v4_lin_acc.set_index('time_centiseconds',inplace=True)
v4_acc.set_index('time_centiseconds',inplace=True)
v4_magneto.set_index('time_centiseconds',inplace=True)
v4_gyro.set_index('time_centiseconds',inplace=True)
vehicle_4 = pd.concat([v4_lin_acc, v4_acc, v4_magneto, v4_gyro], axis=1, sort=False)
vehicle_4.rename(columns = {'index':'time_centiseconds'})
#vehicle_4['time_centiseconds'] = pd.to_datetime(vehicle_4['time_centiseconds'])
initial_time4 = [vehicle_4['time_centiseconds'][0]]*len(vehicle_4)
#initial_time4 = pd.to_datetime(initial_time4)
vehicle_4['Time seconds'] = np.array(vehicle_4['time_centiseconds']-initial_time4)/1

```

In []:

```
vehicle_3
```

Out []:

| | time_centiseconds | x_lin_acc | y_lin_acc | z_lin_acc | x_acc | y_acc | z_acc | x_magneto |
|-------------|-------------------|-----------|-----------|-----------|-----------|-----------|----------|---------------|
| 0 | 101969 | -0.057714 | -0.262420 | -0.122779 | -0.057714 | -0.262420 | 9.683872 | 5.634502e-08 |
| 1 | 101970 | -0.084763 | -0.123271 | -0.197237 | -0.084763 | -0.123271 | 9.609414 | 8.915085e-08 |
| 2 | 101971 | -0.045146 | -0.016721 | -0.126474 | -0.045146 | -0.016721 | 9.680177 | -8.381903e-10 |
| 3 | 101972 | 0.030745 | -0.182721 | -0.214915 | 0.030745 | -0.182721 | 9.591736 | 7.235212e-08 |
| 4 | 101973 | 0.055466 | -0.032278 | -0.147409 | 0.055466 | -0.032278 | 9.659242 | -1.245838e-07 |
| ... | ... | ... | ... | ... | ... | ... | ... | ... |
| 5887 | 107856 | 0.012417 | -0.022259 | -0.192566 | 0.012417 | -0.022259 | 9.614084 | -1.864741e-07 |
| 5888 | 107857 | 0.029609 | 0.016640 | -0.142156 | 0.029609 | 0.016640 | 9.664494 | 1.533306e-07 |
| 5889 | 107858 | -0.014249 | 0.119766 | -0.152492 | -0.014249 | 0.119766 | 9.654159 | -1.196982e-07 |
| 5890 | 107859 | 0.078582 | -0.010420 | -0.178355 | 0.078582 | -0.010420 | 9.628296 | -1.957756e-07 |
| 5891 | 107860 | -0.042076 | -0.243651 | -0.293133 | -0.042076 | -0.243651 | 9.513519 | 1.045846e-07 |

5892 rows × 14 columns

In []:

```
#### visualisation ####
###used vehicle 2 data

y_points1 = np.array(vehicle_2['x_lin_acc'][0:400])
y_points2 = np.array(vehicle_2['y_lin_acc'][0:400])
y_points3 = np.array(vehicle_2['z_lin_acc'][0:400])
x_points = np.array(vehicle_2['Time seconds'][0:400])

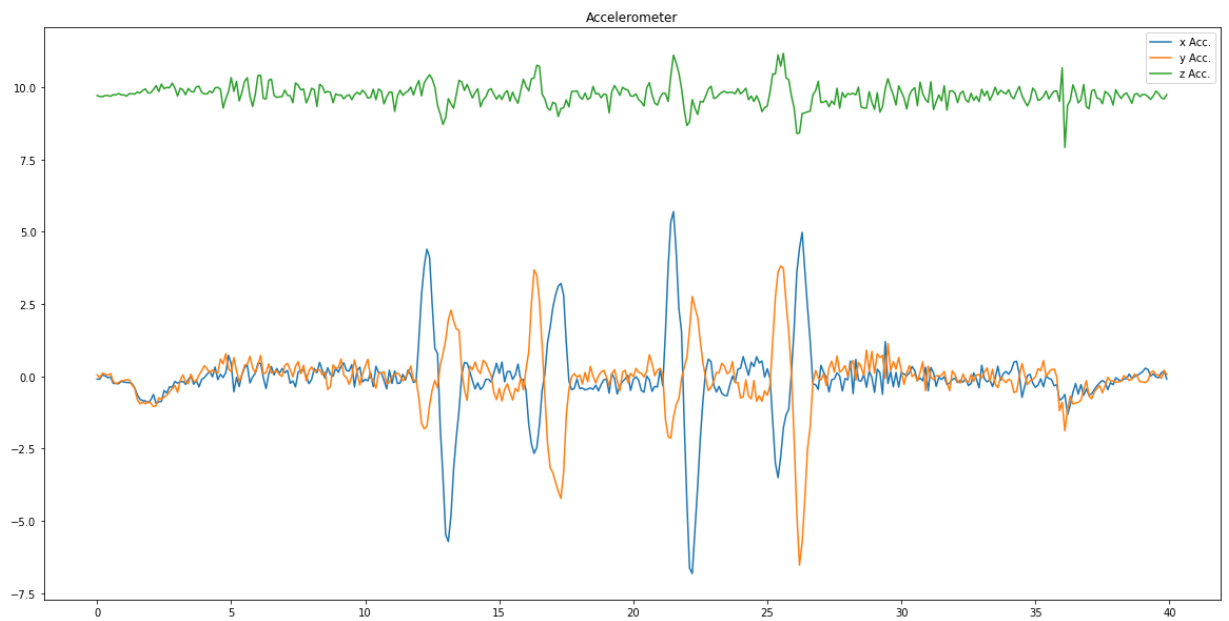
plt.figure(figsize=(20,10))
plt.plot(x_points, y_points1, label="x Linear Acc.")
plt.plot(x_points, y_points2, label="y Linear Acc.")
plt.plot(x_points, y_points3, label="z Linear Acc.")
plt.legend(loc='upper right')
plt.title("Linear Accelerometer ")
plt.show()
```



In []:

```
y_points4 = np.array(vehicle_2['x_acc'][0:400])
y_points5 = np.array(vehicle_2['y_acc'][0:400])
y_points6 = np.array(vehicle_2['z_acc'][0:400])
x_points = np.array(vehicle_2['Time seconds'][0:400])

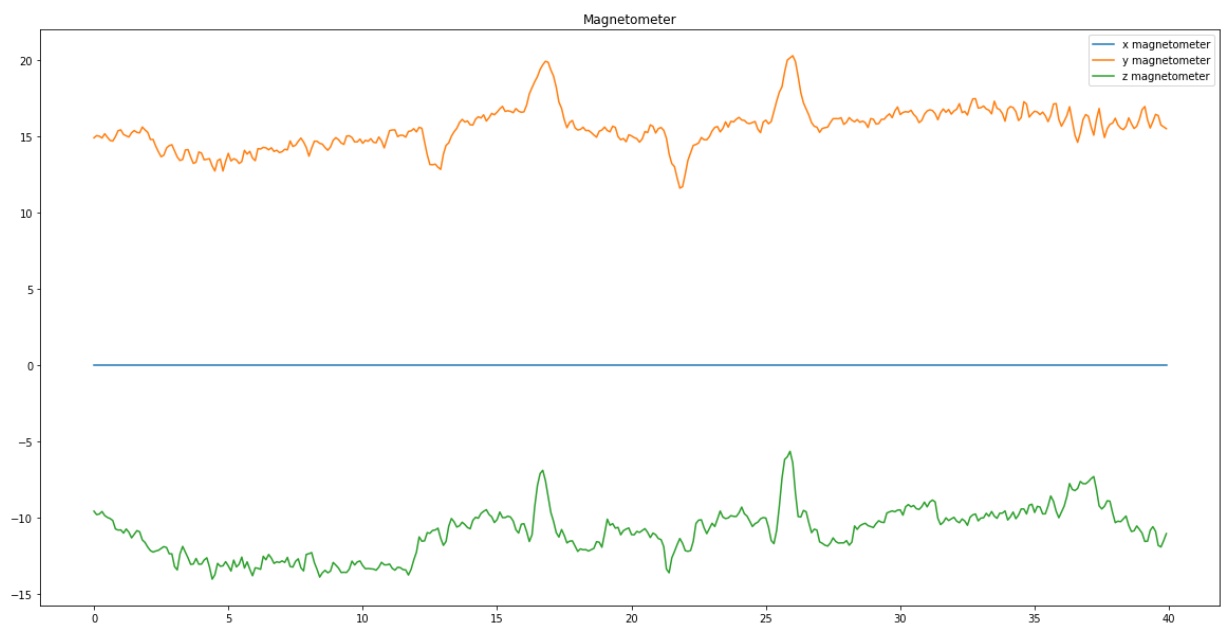
plt.figure(figsize=(20,10))
plt.plot(x_points, y_points4, label="x Acc.")
plt.plot(x_points, y_points5, label="y Acc.")
plt.plot(x_points, y_points6, label="z Acc.")
plt.legend(loc='upper right')
plt.title("Accelerometer")
plt.show()
```

In []:

```
y_points7 = np.array(vehicle_2['x_magneto'][0:400])
y_points8 = np.array(vehicle_2['y_magneto'][0:400])
y_points9 = np.array(vehicle_2['z_magneto'][0:400])
x_points = np.array(vehicle_2['Time seconds'][0:400])

plt.figure(figsize=(20,10))
plt.plot(x_points, y_points7, label="x magnetometer")
plt.plot(x_points, y_points8, label="y magnetometer")
plt.plot(x_points, y_points9, label="z magnetometer")
plt.legend(loc='upper right')
plt.title("Magnetometer")
plt.show()
```

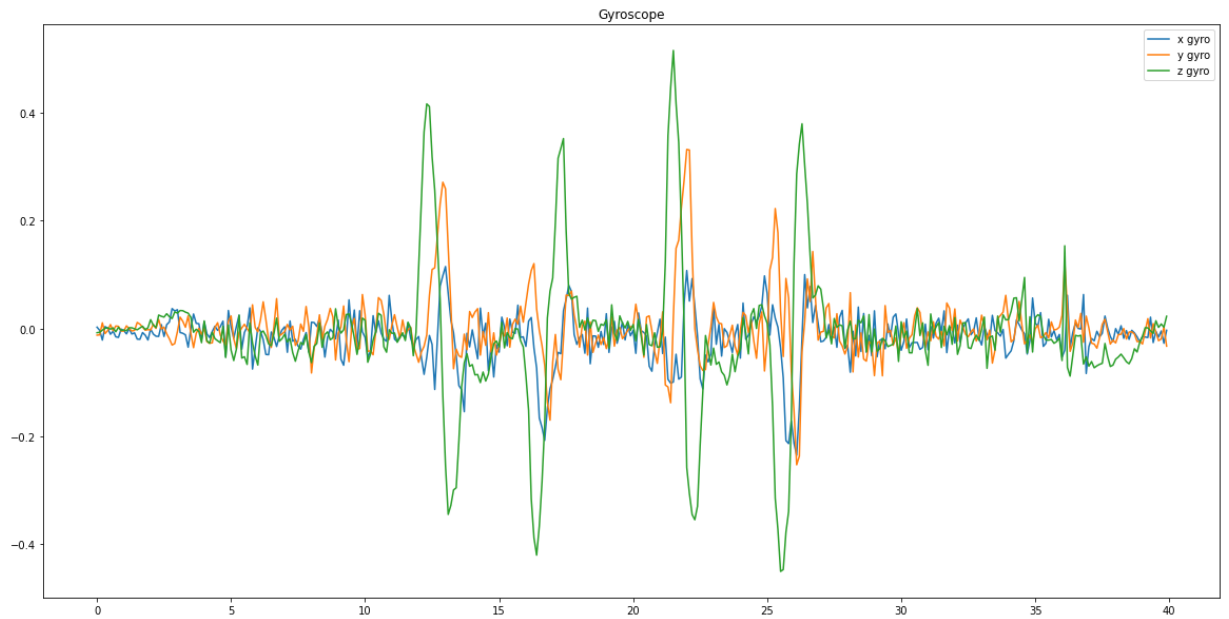


In []:

```
y_points10 = np.array(vehicle_2['x_gyro'][0:400])
y_points11 = np.array(vehicle_2['y_gyro'][0:400])
y_points12 = np.array(vehicle_2['z_gyro'][0:400])
x_points = np.array(vehicle_2['Time seconds'][0:400])

plt.figure(figsize=(20,10))
plt.plot(x_points, y_points10, label="x gyro")
plt.plot(x_points, y_points11, label="y gyro")
plt.plot(x_points, y_points12, label="z gyro")
```

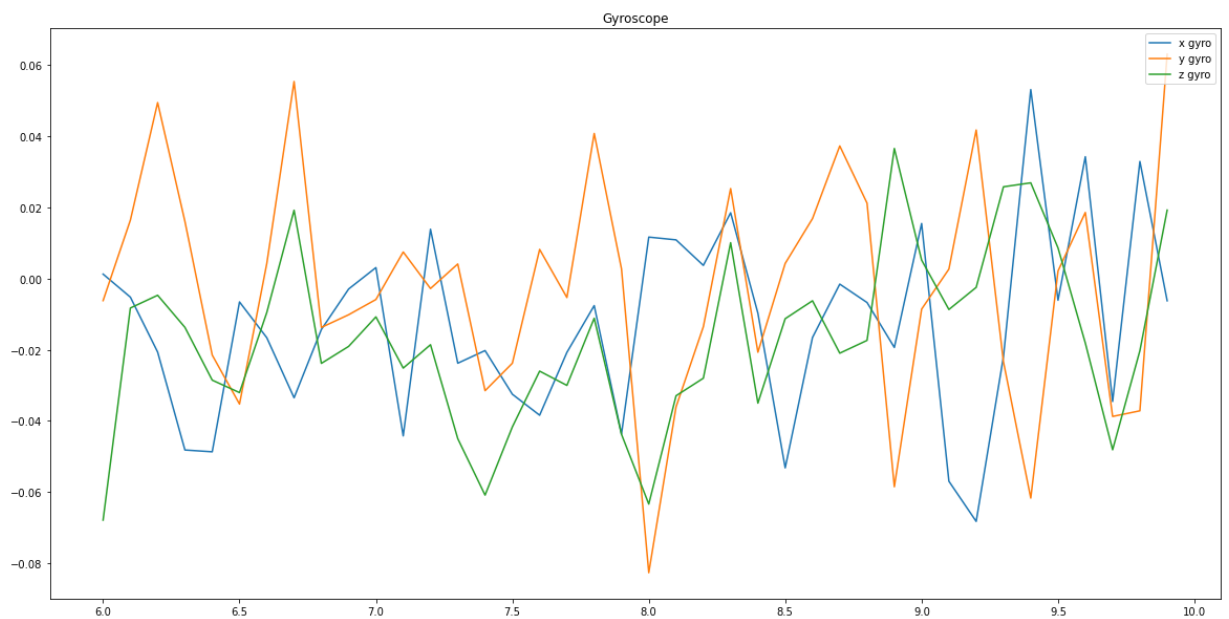
```
plt.legend(loc='upper right')
plt.title("Gyroscope")
plt.show()
```



In []:

```
y_points10 = np.array(vehicle_2['x_gyro'][60:100])
y_points11 = np.array(vehicle_2['y_gyro'][60:100])
y_points12 = np.array(vehicle_2['z_gyro'][60:100])
x_points = np.array(vehicle_2['Time seconds'][60:100])

plt.figure(figsize=(20,10))
plt.plot(x_points, y_points10, label="x gyro")
plt.plot(x_points, y_points11, label="y gyro")
plt.plot(x_points, y_points12, label="z gyro")
plt.legend(loc='upper right')
plt.title("Gyroscope")
plt.show()
```



In []:

```
labels = []
new_vehicle1 = pd.DataFrame()

for i in range(len(vehicle_1)):
    present = False
```

```

    for j in range(len(v1_label)):
        if vehicle_1['Time seconds'][i]<=v1_label['end_time'][j] and vehicle_1['Time
            labels.append(v1_label['event'][j])
            row = vehicle_1.iloc[[i]]
            new_vehicle1 = new_vehicle1.append(row, ignore_index=True)
            present = True
            break
new_vehicle1['event'] = labels

#####
labels = []
new_vehicle2 = pd.DataFrame()

for i in range(len(vehicle_2)):
    present = False
    for j in range(len(v2_label)):
        if vehicle_2['Time seconds'][i]<=v2_label['end_time'][j] and vehicle_2['Time
            labels.append(v2_label['event'][j])
            row = vehicle_2.iloc[[i]]
            new_vehicle2 = new_vehicle2.append(row, ignore_index=True)
            present = True
            break
new_vehicle2['event'] = labels

#####
labels = []
new_vehicle3 = pd.DataFrame()

for i in range(len(vehicle_3)):
    present = False
    for j in range(len(v3_label)):
        if vehicle_3['Time seconds'][i]<=v3_label['end_time'][j] and vehicle_3['Time
            labels.append(v3_label['event'][j])
            row = vehicle_3.iloc[[i]]
            new_vehicle3 = new_vehicle3.append(row, ignore_index=True)
            present = True
            break
new_vehicle3['event'] = labels

#####
labels = []
new_vehicle4 = pd.DataFrame()

for i in range(len(vehicle_4)):
    present = False
    for j in range(len(v4_label)):
        if vehicle_4['Time seconds'][i]<=v4_label['end_time'][j] and vehicle_4['Time
            labels.append(v4_label['event'][j])
            row = vehicle_4.iloc[[i]]
            new_vehicle4 = new_vehicle4.append(row, ignore_index=True)
            present = True
            break
new_vehicle4['event'] = labels

```

In []: labels

Out[]: ['Aggressive left lane change',
'Aggressive left lane change',

[illegible]

[illegible]

[illegible]

[illegible]

[illegible]

[illegible]

[illegible]

[illegible]

[illegible]

[illegible]

```
new_vehicle2
```

| | time_centiseconds | x_lin_acc | y_lin_acc | z_lin_acc | x_acc | y_acc | z_acc | x_magneto |
|---|-------------------|-----------|-----------|-----------|-----------|----------|-----------|---------------|
| 0 | 129093 | -1.653038 | 0.840594 | 0.063234 | -1.653038 | 0.840595 | 9.869885 | -9.164214e-08 |
| 1 | 129094 | -2.341093 | 2.488108 | 0.478537 | -2.341093 | 2.488108 | 10.285188 | 2.058223e-08 |
| 2 | 129095 | -2.667343 | 3.676871 | 0.506474 | -2.667343 | 3.676871 | 10.313124 | 1.687557e-07 |

| | time_centiseconds | x_lin_acc | y_lin_acc | z_lin_acc | x_acc | y_acc | z_acc | x_magneto |
|-----|-------------------|-----------|-----------|-----------|-----------|-----------|-----------|---------------|
| 3 | 129096 | -2.473614 | 3.493380 | 0.942907 | -2.473614 | 3.493380 | 10.749558 | -2.123415e-08 |
| 4 | 129097 | -1.675308 | 2.593474 | 0.907588 | -1.675308 | 2.593474 | 10.714238 | 1.490116e-08 |
| ... | ... | ... | ... | ... | ... | ... | ... | ... |
| 426 | 132930 | -0.024073 | -2.214347 | -0.237045 | -0.024073 | -2.214347 | 9.569605 | 1.549197e-07 |
| 427 | 132931 | 0.142740 | -2.247065 | -0.314202 | 0.142740 | -2.247065 | 9.492449 | 1.036591e-07 |
| 428 | 132932 | -0.331480 | -1.940924 | -0.689715 | -0.331480 | -1.940924 | 9.116937 | -6.466435e-08 |
| 429 | 132933 | -0.423305 | -1.996444 | -0.122956 | -0.423305 | -1.996444 | 9.683695 | 2.318606e-07 |
| 430 | 132934 | -0.290728 | -1.159422 | -0.238115 | -0.290728 | -1.159422 | 9.568535 | -1.138476e-07 |

431 rows × 15 columns

◀ ▶

In []:

```
vehicle_1.iloc[[10]]
```

Out[]:

| | time_centiseconds | x_lin_acc | y_lin_acc | z_lin_acc | x_acc | y_acc | z_acc | x_magneto | y_m |
|----|-------------------|-----------|-----------|-----------|----------|----------|----------|---------------|-----|
| 10 | 115386 | 0.102623 | 0.390929 | -0.174528 | 0.102623 | 0.390929 | 9.632123 | -2.565648e-08 | 4 |

◀ ▶

In []:

```
new_vehicle3
```

Out[]:

[illegible]

| | time_centiseconds | x_lin_acc | y_lin_acc | z_lin_acc | x_acc | y_acc | z_acc | x_magneto |
|------------|-------------------|-----------|-----------|-----------|-----------|----------|-----------|---------------|
| 583 | 107309 | -0.671471 | 1.734737 | -0.922664 | -0.671471 | 1.734737 | 8.883988 | 3.473316e-07 |
| 584 | 107310 | -0.769552 | 1.695303 | -0.709576 | -0.769552 | 1.695303 | 9.097074 | -2.575573e-07 |
| 585 | 107311 | -1.046645 | 1.905795 | -0.360317 | -1.046645 | 1.905795 | 9.446333 | -2.425164e-07 |
| 586 | 107312 | -1.100073 | 2.158354 | -0.152339 | -1.100073 | 2.158355 | 9.654312 | -3.560912e-07 |
| 587 | 107313 | -0.576510 | 1.801576 | 0.592426 | -0.576510 | 1.801576 | 10.399076 | 3.783498e-08 |

588 rows × 15 columns



In []:

```
v3_label
```

Out[]:

| | event | start_time | end_time |
|-----------|----------------------|------------|----------|
| 0 | Agressive right turn | 9.5 | 12.5 |
| 1 | Non aggressive | 19.0 | 23.0 |
| 2 | Agressive right turn | 91.6 | 94.9 |
| 3 | Agressive right turn | 120.9 | 124.1 |
| 4 | Agressive right turn | 135.4 | 139.0 |
| 5 | Non aggressive | 164.0 | 168.0 |
| 6 | Non aggressive | 187.0 | 190.5 |
| 7 | Agressive right turn | 219.4 | 223.9 |
| 8 | Agressive right turn | 232.6 | 236.7 |
| 9 | Non aggressive | 358.0 | 360.5 |
| 10 | Agressive left turn | 412.0 | 416.0 |
| 11 | Agressive left turn | 430.3 | 433.2 |
| 12 | Agressive left turn | 447.4 | 450.7 |
| 13 | Non aggressive | 463.5 | 465.6 |
| 14 | Agressive left turn | 496.1 | 499.2 |
| 15 | Agressive left turn | 508.8 | 512.0 |
| 16 | Agressive left turn | 531.6 | 534.4 |

In []:

```
new_vehicle1['event_shift'] = new_vehicle1['event'].shift(1)
new_vehicle1['is_new_event'] = (new_vehicle1['event']!=new_vehicle1['event_shift'])
new_vehicle1['time_shift'] = new_vehicle1['Time seconds'].shift(1)
new_vehicle1['is_time_gap'] = ((new_vehicle1['Time seconds']-new_vehicle1['time_shift']
new_vehicle1['is_new_event'] = new_vehicle1['is_new_event'] + new_vehicle1['is_time_
new_vehicle1.drop(['is_time_gap','event_shift','time_shift'],axis=1,inplace=True)
```

```

new_vehicle2['event_shift'] = new_vehicle2['event'].shift(1)
new_vehicle2['is_new_event'] = (new_vehicle2['event']!=new_vehicle2['event_shift'])
new_vehicle2['time_shift'] = new_vehicle2['Time seconds'].shift(1)
new_vehicle2['is_time_gap'] = ((new_vehicle2['Time seconds']-new_vehicle2['time_shift'])>0)
new_vehicle2['is_new_event'] = new_vehicle2['is_new_event'] + new_vehicle2['is_time_gap']
new_vehicle2.drop(['is_time_gap','event_shift','time_shift'],axis=1,inplace=True)

new_vehicle3['event_shift'] = new_vehicle3['event'].shift(1)
new_vehicle3['is_new_event'] = (new_vehicle3['event']!=new_vehicle3['event_shift'])
new_vehicle3['time_shift'] = new_vehicle3['Time seconds'].shift(1)
new_vehicle3['is_time_gap'] = ((new_vehicle3['Time seconds']-new_vehicle3['time_shift'])>0)
new_vehicle3['is_new_event'] = new_vehicle3['is_new_event'] + new_vehicle3['is_time_gap']
new_vehicle3.drop(['is_time_gap','event_shift','time_shift'],axis=1,inplace=True)

new_vehicle4['event_shift'] = new_vehicle4['event'].shift(1)
new_vehicle4['is_new_event'] = (new_vehicle4['event']!=new_vehicle4['event_shift'])
new_vehicle4['time_shift'] = new_vehicle4['Time seconds'].shift(1)
new_vehicle4['is_time_gap'] = ((new_vehicle4['Time seconds']-new_vehicle4['time_shift'])>0)
new_vehicle4['is_new_event'] = new_vehicle4['is_new_event'] + new_vehicle4['is_time_gap']
new_vehicle4.drop(['is_time_gap','event_shift','time_shift'],axis=1,inplace=True)

```

```

c:\Users\gg502\AppData\Local\Programs\Python\Python36\lib\site-packages\pandas\core\computation\expressions.py:204: UserWarning: evaluating in Python space because the '+' operator is not supported by numexpr for the bool dtype, use '|' instead
  f"evaluating in Python space because the {repr(op_str)} "
c:\Users\gg502\AppData\Local\Programs\Python\Python36\lib\site-packages\pandas\core\computation\expressions.py:204: UserWarning: evaluating in Python space because the '+' operator is not supported by numexpr for the bool dtype, use '|' instead
  f"evaluating in Python space because the {repr(op_str)} "
c:\Users\gg502\AppData\Local\Programs\Python\Python36\lib\site-packages\pandas\core\computation\expressions.py:204: UserWarning: evaluating in Python space because the '+' operator is not supported by numexpr for the bool dtype, use '|' instead
  f"evaluating in Python space because the {repr(op_str)} "
c:\Users\gg502\AppData\Local\Programs\Python\Python36\lib\site-packages\pandas\core\computation\expressions.py:204: UserWarning: evaluating in Python space because the '+' operator is not supported by numexpr for the bool dtype, use '|' instead
  f"evaluating in Python space because the {repr(op_str)} "

```

```

In [ ]: data = pd.DataFrame
        data = pd.concat([new_vehicle1,new_vehicle2,new_vehicle3,new_vehicle4], ignore_index=True)

```

```

In [ ]: data['is_new_event'].value_counts()

```

```

Out[ ]: False    2174
        True      69
        Name: is_new_event, dtype: int64

```

```

In [ ]: len(data)

```

```

Out[ ]: 2243

```

```

In [ ]: label_summ = data[data['is_new_event']==True]
        idx = [0,1,2,3,4,5,6]
        label_summ = pd.DataFrame(data = label_summ['event'].value_counts())
        label_summ.rename(columns = {'event':'no of sequences'},inplace=True)
        label_summ.rename(columns={'index':'events'},inplace=True)
        label_summ

```


Out[]:

| | no of sequences |
|------------------------------|-----------------|
| Non aggressive | 14 |
| Aggressive acceleration | 12 |
| Agressive braking | 12 |
| Agressive right turn | 11 |
| Agressive left turn | 11 |
| Aggressive right lane change | 5 |
| Aggressive left lane change | 4 |

In []:

```
data
```

Out[]:

| | time_centiseconds | x_lin_acc | y_lin_acc | z_lin_acc | x_acc | y_acc | z_acc | x_magneto |
|------|-------------------|-----------|-----------|-----------|-----------|-----------|----------|---------------|
| 0 | 115396 | 0.132041 | 0.867996 | -0.045091 | 0.132041 | 0.867996 | 9.761559 | -1.259366e-07 |
| 1 | 115397 | 0.171421 | 1.122584 | -0.051169 | 0.171421 | 1.122584 | 9.755482 | 1.040258e-07 |
| 2 | 115398 | 0.153374 | 1.082111 | -0.044352 | 0.153374 | 1.082111 | 9.762299 | 1.226072e-08 |
| 3 | 115399 | 0.127719 | 1.099273 | -0.034528 | 0.127720 | 1.099273 | 9.772121 | 8.466013e-08 |
| 4 | 115400 | 0.141839 | 1.072355 | -0.059415 | 0.141839 | 1.072355 | 9.747235 | -5.626498e-08 |
| ... | ... | ... | ... | ... | ... | ... | ... | ... |
| 2238 | 119877 | 0.393265 | 0.754730 | -0.203305 | 0.393265 | 0.754730 | 9.603346 | 1.142384e-07 |
| 2239 | 119878 | 0.852456 | -0.133665 | -0.558923 | 0.852456 | -0.133665 | 9.247727 | 1.303270e-07 |
| 2240 | 119879 | 1.081358 | -0.811304 | -0.193637 | 1.081358 | -0.811304 | 9.613014 | -2.679146e-07 |
| 2241 | 119880 | -0.966088 | 0.601259 | -0.976800 | -0.966088 | 0.601259 | 8.829851 | -3.210880e-08 |
| 2242 | 119881 | 0.273143 | -0.468067 | 0.111480 | 0.273143 | -0.468067 | 9.918131 | 1.306571e-07 |

2243 rows × 16 columns



In []:

```
fig, ax = plt.subplots(nrows=4, ncols=3, figsize=(30,30))

sns.boxplot(x='event', y='x_lin_acc', data=data, ax=ax[0][0])
sns.boxplot(x='event', y='y_lin_acc', data=data, ax=ax[0][1])
sns.boxplot(x='event', y='z_lin_acc', data=data, ax=ax[0][2])
sns.boxplot(x='event', y='x_acc', data=data, ax=ax[1][0])
sns.boxplot(x='event', y='y_acc', data=data, ax=ax[1][1])
sns.boxplot(x='event', y='z_acc', data=data, ax=ax[1][2])
```

```

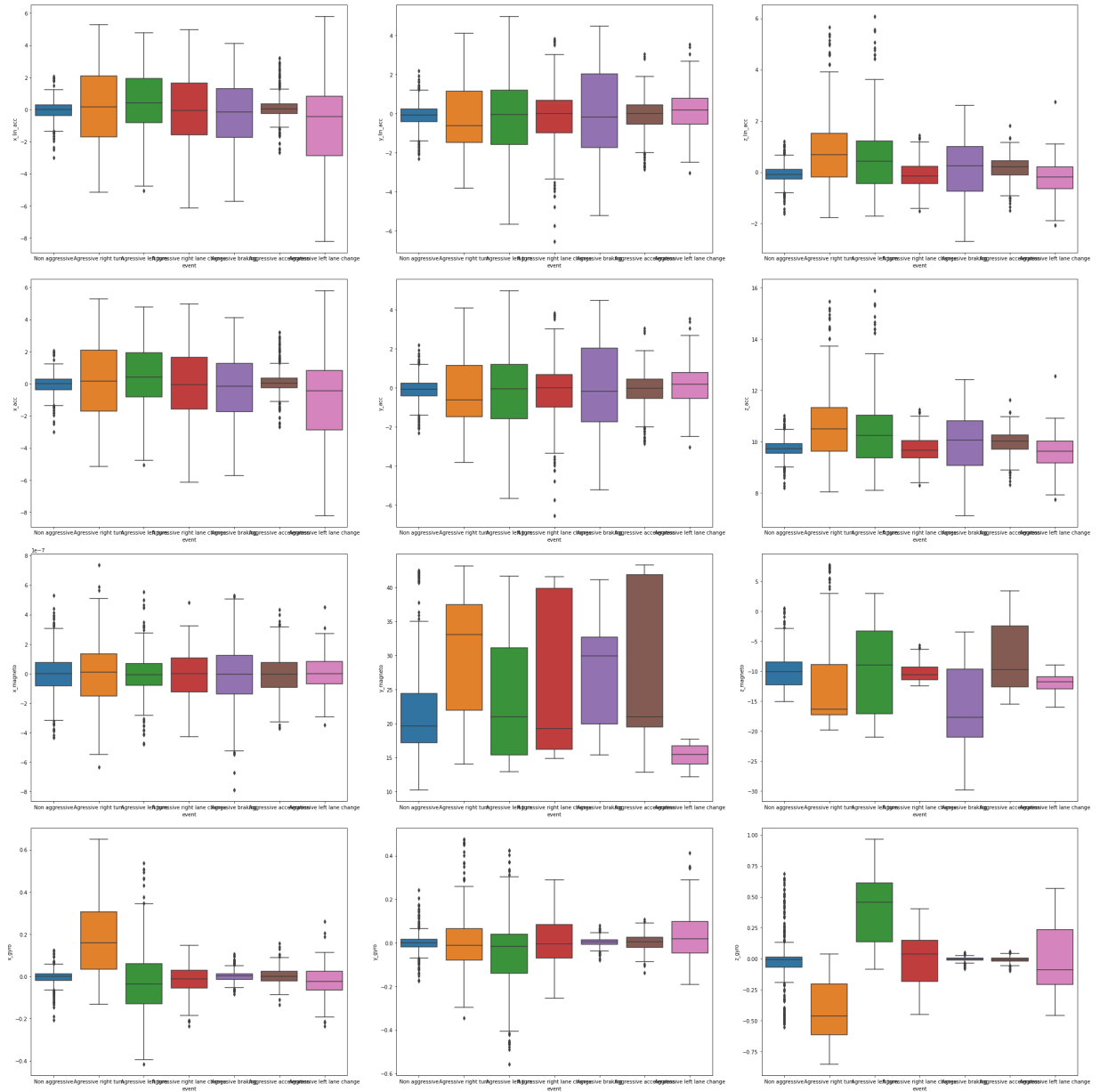
sns.boxplot(x='event', y='x_magneto', data=data, ax=ax[2][0])
sns.boxplot(x='event', y='y_magneto', data=data, ax=ax[2][1])
sns.boxplot(x='event', y='z_magneto', data=data, ax=ax[2][2])
sns.boxplot(x='event', y='x_gyro', data=data, ax=ax[3][0])
sns.boxplot(x='event', y='y_gyro', data=data, ax=ax[3][1])
sns.boxplot(x='event', y='z_gyro', data=data, ax=ax[3][2])

```

```

#plt.setp(ax.get_xticklabels(), rotation=45)
#ax.set_xticklabels(ax.get_xticks(), rotation = 50)
plt.tight_layout()
plt.show()

```



In []:

```

new_sequences = data.loc[data["is_new_event"]==True]
indices = new_sequences.index
seq_no, count = [], 0

for i in range(len(indices)-1):
    seq_len = indices[i+1]-indices[i]
    new_list = [i+1]*seq_len
    seq_no.append(new_list)
    count = i+1

rem_len = len(data)-indices[count]

```

```
seq_no.append([count+1]*rem_len)

flatten_list = list(chain.from_iterable(seq_no))
sequences = np.unique(flatten_list)

data["sequence no."] = flatten_list
```

```
In [ ]: len(flatten_list)
```

```
Out[ ]: 2243
```

```
In [ ]: data
```

```
Out[ ]:
```

| | time_centiseconds | x_lin_acc | y_lin_acc | z_lin_acc | x_acc | y_acc | z_acc | x_magneto |
|-------------|-------------------|-----------|-----------|-----------|-----------|-----------|----------|---------------|
| 0 | 115396 | 0.132041 | 0.867996 | -0.045091 | 0.132041 | 0.867996 | 9.761559 | -1.259366e-07 |
| 1 | 115397 | 0.171421 | 1.122584 | -0.051169 | 0.171421 | 1.122584 | 9.755482 | 1.040258e-07 |
| 2 | 115398 | 0.153374 | 1.082111 | -0.044352 | 0.153374 | 1.082111 | 9.762299 | 1.226072e-08 |
| 3 | 115399 | 0.127719 | 1.099273 | -0.034528 | 0.127720 | 1.099273 | 9.772121 | 8.466013e-08 |
| 4 | 115400 | 0.141839 | 1.072355 | -0.059415 | 0.141839 | 1.072355 | 9.747235 | -5.626498e-08 |
| ... | ... | ... | ... | ... | ... | ... | ... | ... |
| 2238 | 119877 | 0.393265 | 0.754730 | -0.203305 | 0.393265 | 0.754730 | 9.603346 | 1.142384e-07 |
| 2239 | 119878 | 0.852456 | -0.133665 | -0.558923 | 0.852456 | -0.133665 | 9.247727 | 1.303270e-07 |
| 2240 | 119879 | 1.081358 | -0.811304 | -0.193637 | 1.081358 | -0.811304 | 9.613014 | -2.679146e-07 |
| 2241 | 119880 | -0.966088 | 0.601259 | -0.976800 | -0.966088 | 0.601259 | 8.829851 | -3.210880e-08 |
| 2242 | 119881 | 0.273143 | -0.468067 | 0.111480 | 0.273143 | -0.468067 | 9.918131 | 1.306571e-07 |

2243 rows × 17 columns



```
In [ ]: ## partitioning data into 0.5 seconds windows

time_wd, seq_part_no = [], []

for seq in sequences:
    seq_df = data[data["sequence no."]==seq].reset_index(drop=True)
    min_time = seq_df["time_centiseconds"][0]
    min_time_lis = [min_time]*len(seq_df)

    time_diff = (seq_df["time_centiseconds"]-min_time_lis)
```

```

wd_no = np.floor_divide(time_diff,5)+1
wd_tostr = wd_no.apply(str)
seq_str = [str(seq)]*len(seq_df)
_str = ["_"]*len(seq_df)
part_no = list(i+j for i,j in zip(seq_str , _str))
part_no = list(i+j for i,j in zip(part_no , wd_tostr))

time_wd.append(wd_no)
seq_part_no.append(part_no)

time_wd = list(chain.from_iterable(time_wd))
seq_part_no = list(chain.from_iterable(seq_part_no))

data["partition no"] = time_wd
data["Partition label"] = seq_part_no

```

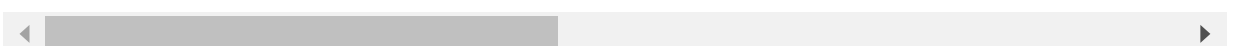
In []:

```
data
```

Out []:

| | time_centiseconds | x_lin_acc | y_lin_acc | z_lin_acc | x_acc | y_acc | z_acc | x_magneto |
|-------------|-------------------|-----------|-----------|-----------|-----------|-----------|----------|---------------|
| 0 | 115396 | 0.132041 | 0.867996 | -0.045091 | 0.132041 | 0.867996 | 9.761559 | -1.259366e-07 |
| 1 | 115397 | 0.171421 | 1.122584 | -0.051169 | 0.171421 | 1.122584 | 9.755482 | 1.040258e-07 |
| 2 | 115398 | 0.153374 | 1.082111 | -0.044352 | 0.153374 | 1.082111 | 9.762299 | 1.226072e-08 |
| 3 | 115399 | 0.127719 | 1.099273 | -0.034528 | 0.127720 | 1.099273 | 9.772121 | 8.466013e-08 |
| 4 | 115400 | 0.141839 | 1.072355 | -0.059415 | 0.141839 | 1.072355 | 9.747235 | -5.626498e-08 |
| ... | ... | ... | ... | ... | ... | ... | ... | ... |
| 2238 | 119877 | 0.393265 | 0.754730 | -0.203305 | 0.393265 | 0.754730 | 9.603346 | 1.142384e-07 |
| 2239 | 119878 | 0.852456 | -0.133665 | -0.558923 | 0.852456 | -0.133665 | 9.247727 | 1.303270e-07 |
| 2240 | 119879 | 1.081358 | -0.811304 | -0.193637 | 1.081358 | -0.811304 | 9.613014 | -2.679146e-07 |
| 2241 | 119880 | -0.966088 | 0.601259 | -0.976800 | -0.966088 | 0.601259 | 8.829851 | -3.210880e-08 |
| 2242 | 119881 | 0.273143 | -0.468067 | 0.111480 | 0.273143 | -0.468067 | 9.918131 | 1.306571e-07 |

2243 rows × 9 columns



In []:

```
len(data['Partition label'].unique())
```

Out []: 483

In []:

```
label_dfs = [y for x,y in data.groupby(data['Partition label'])]
label = []
```

```

label_class = []
features = []
time_data = []

for label_df in label_dfs:
    label_df = label_df.reset_index(drop=True)

    label.append(label_df["Partition label"][0])
    label_class.append(label_df["event"][0])

    x_linacc_min = min(label_df["x_lin_acc"])
    y_linacc_min = min(label_df["y_lin_acc"])
    z_linacc_min = min(label_df["z_lin_acc"])

    x_linacc_max = max(label_df["x_lin_acc"])
    y_linacc_max = max(label_df["y_lin_acc"])
    z_linacc_max = max(label_df["z_lin_acc"])

    x_linacc_avg = np.mean(label_df["x_lin_acc"])
    y_linacc_avg = np.mean(label_df["y_lin_acc"])
    z_linacc_avg = np.mean(label_df["z_lin_acc"])

    x_linacc_std = np.std(label_df["x_lin_acc"])
    y_linacc_std = np.std(label_df["y_lin_acc"])
    z_linacc_std = np.std(label_df["z_lin_acc"])

    x_acc_min = min(label_df["x_acc"])
    y_acc_min = min(label_df["y_acc"])
    z_acc_min = min(label_df["z_acc"])

    x_acc_max = max(label_df["x_acc"])
    y_acc_max = max(label_df["y_acc"])
    z_acc_max = max(label_df["z_acc"])

    x_acc_avg = np.mean(label_df["x_acc"])
    y_acc_avg = np.mean(label_df["y_acc"])
    z_acc_avg = np.mean(label_df["z_acc"])

    x_acc_std = np.std(label_df["x_acc"])
    y_acc_std = np.std(label_df["y_acc"])
    z_acc_std = np.std(label_df["z_acc"])

    x_magneto_min = min(label_df["x_magneto"])
    y_magneto_min = min(label_df["y_magneto"])
    z_magneto_min = min(label_df["z_magneto"])

    x_magneto_max = max(label_df["x_magneto"])
    y_magneto_max = max(label_df["y_magneto"])
    z_magneto_max = max(label_df["z_magneto"])

    x_magneto_avg = np.mean(label_df["x_magneto"])
    y_magneto_avg = np.mean(label_df["y_magneto"])
    z_magneto_avg = np.mean(label_df["z_magneto"])

    x_magneto_std = np.std(label_df["x_magneto"])
    y_magneto_std = np.std(label_df["y_magneto"])
    z_magneto_std = np.std(label_df["z_magneto"])

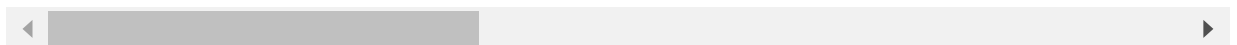
    x_gyro_min = min(label_df["x_gyro"])
    y_gyro_min = min(label_df["y_gyro"])
    z_gyro_min = min(label_df["z_gyro"])

    x_gyro_max = max(label_df["x_gyro"])
    y_gyro_max = max(label_df["y_gyro"])

```


| | x_linacc_min | y_linacc_min | z_linacc_min | x_linacc_max | y_linacc_max | z_linacc_max | x_linacc_avg |
|------------|--------------|--------------|--------------|--------------|--------------|--------------|--------------|
| 478 | 0.194214 | -2.915153 | -0.072153 | 1.176256 | -0.660332 | 4.659564 | 0.594686 |
| 479 | -1.315942 | -2.204906 | 0.789823 | 0.950823 | -1.220241 | 1.861554 | -0.544849 |
| 480 | -3.341690 | -0.820263 | -1.051386 | -1.489183 | 2.555306 | 1.007381 | -2.614278 |
| 481 | -3.181725 | 1.390165 | -1.027327 | -1.672604 | 2.677557 | -0.183479 | -2.205725 |
| 482 | -1.432755 | 1.653576 | -0.335926 | -1.432755 | 1.653576 | -0.335926 | -1.432755 |

483 rows × 49 columns



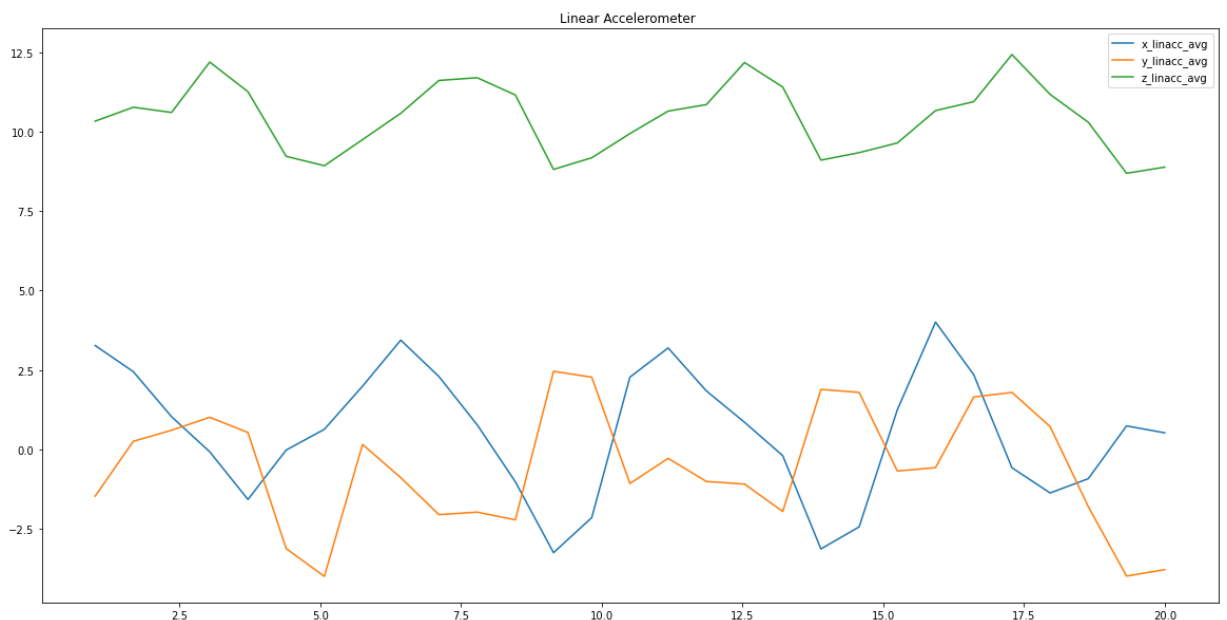
In []:

```

y_points1 = np.array(df['x_acc_avg'][1:30])
y_points2 = np.array(df['y_acc_avg'][1:30])
y_points3 = np.array(df['z_acc_avg'][1:30])
x_points = np.linspace(1,20,29)

plt.figure(figsize=(20,10))
plt.plot(x_points, y_points1, label="x_linacc_avg")
plt.plot(x_points, y_points2, label="y_linacc_avg")
plt.plot(x_points, y_points3, label="z_linacc_avg")
plt.legend(loc='upper right')
plt.title("Linear Accelerometer ")
plt.show()

```



In []:

```
df['event'][1:30]
```

```

Out[ ]: 1    Agressive left turn
        2    Agressive left turn
        3    Agressive left turn
        4    Agressive left turn
        5    Agressive left turn
        6    Agressive left turn
        7    Agressive left turn

```

```

8    Agressive right turn
9    Agressive right turn
10   Agressive right turn
11   Agressive right turn
12   Agressive right turn
13   Agressive right turn
14   Agressive right turn
15   Agressive right turn
16   Agressive right turn
17   Agressive right turn
18   Agressive right turn
19   Agressive right turn
20   Agressive right turn
21   Agressive right turn
22   Agressive left turn
23   Agressive left turn
24   Agressive left turn
25   Agressive left turn
26   Agressive left turn
27   Agressive left turn
28   Agressive left turn
29   Agressive left turn
Name: event, dtype: object

```

```

In [ ]: cols_scale = ["x_linacc_min", "y_linacc_min", "z_linacc_min", "x_linacc_max", "y_lin
            "x_acc_min", "y_acc_min", "z_acc_min", "x_acc_max", "y_acc_max", "z_
            "x_magneto_min", "y_magneto_min", "z_magneto_min", "x_magneto_max",
            "x_gyro_min", "y_gyro_min", "z_gyro_min", "x_gyro_max", "y_gyro_max"
        ]

```

```

scaler = MinMaxScaler()
df[cols_scale] = scaler.fit_transform(df[cols_scale])

```

```

In [ ]: label_encoder = LabelEncoder()
df["class"] = label_encoder.fit_transform(df["event"])

```

```

In [ ]: df

```

```

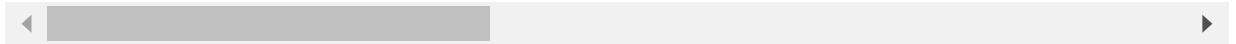
Out[ ]:

```

| | x_linacc_min | y_linacc_min | z_linacc_min | x_linacc_max | y_linacc_max | z_linacc_max | x_linacc_avg |
|-----|--------------|--------------|--------------|--------------|--------------|--------------|--------------|
| 0 | 0.697794 | 0.546702 | 0.448173 | 0.580582 | 0.487860 | 0.160141 | 0.648999 |
| 1 | 0.897954 | 0.450035 | 0.591370 | 0.771061 | 0.342637 | 0.300238 | 0.920619 |
| 2 | 0.839684 | 0.552765 | 0.715714 | 0.718727 | 0.544079 | 0.318640 | 0.832000 |
| 3 | 0.683258 | 0.675419 | 0.421322 | 0.597437 | 0.559184 | 0.440064 | 0.679611 |
| 4 | 0.621592 | 0.662326 | 0.807452 | 0.459019 | 0.641442 | 0.767596 | 0.560855 |
| ... | ... | ... | ... | ... | ... | ... | ... |
| 478 | 0.696192 | 0.353821 | 0.549253 | 0.515359 | 0.385740 | 0.801351 | 0.633074 |
| 479 | 0.570994 | 0.423358 | 0.730079 | 0.491745 | 0.324633 | 0.409810 | 0.510652 |

| | x_linacc_min | y_linacc_min | z_linacc_min | x_linacc_max | y_linacc_max | z_linacc_max | x_linacc_avg |
|------------|--------------|--------------|--------------|--------------|--------------|--------------|--------------|
| 480 | 0.403050 | 0.558922 | 0.343829 | 0.236161 | 0.736690 | 0.290280 | 0.288329 |
| 481 | 0.416312 | 0.775335 | 0.348877 | 0.216948 | 0.750033 | 0.123637 | 0.332221 |
| 482 | 0.561310 | 0.801124 | 0.493919 | 0.242071 | 0.638277 | 0.102304 | 0.415262 |

483 rows × 50 columns



```
In [ ]: X = df.drop(['event', 'class'], axis=1)
        Y = df['class']
        x_train, x_test, y_train, y_test = train_test_split(X, Y, test_size=0.2, stratify=df
```

```
In [ ]: y_train.value_counts()
```

```
Out[ ]: 6    90
        0    75
        5    68
        4    67
        3    51
        2    20
        1    15
        Name: class, dtype: int64
```

```
In [ ]: y_test.value_counts()
```

```
Out[ ]: 6    22
        0    19
        5    17
        4    17
        3    13
        2     5
        1     4
        Name: class, dtype: int64
```

```
In [ ]: over_sampler = RandomOverSampler(random_state=42)
        X_train, Y_train = over_sampler.fit_resample(x_train, y_train)
```

```
In [ ]: Y_train.value_counts()
```

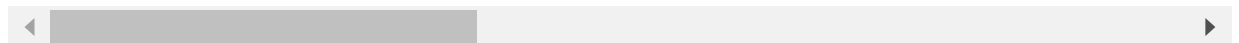
```
Out[ ]: 6    90
        5    90
        4    90
        3    90
        2    90
        1    90
        0    90
        Name: class, dtype: int64
```

```
In [ ]: X_train
```

```
Out[ ]: x_linacc_min y_linacc_min z_linacc_min x_linacc_max y_linacc_max z_linacc_max x_linacc_avg
```

| | x_linacc_min | y_linacc_min | z_linacc_min | x_linacc_max | y_linacc_max | z_linacc_max | x_linacc_avg |
|------------|--------------|--------------|--------------|--------------|--------------|--------------|--------------|
| 0 | 0.674155 | 0.430854 | 0.571117 | 0.662502 | 0.407645 | 0.793664 | 0.687773 |
| 1 | 0.747232 | 0.524273 | 0.698709 | 0.641927 | 0.554332 | 0.607313 | 0.736250 |
| 2 | 0.616106 | 0.579775 | 0.532495 | 0.406725 | 0.469788 | 0.233945 | 0.550526 |
| 3 | 0.340214 | 0.715768 | 0.400069 | 0.070293 | 0.628103 | 0.157923 | 0.202534 |
| 4 | 0.637887 | 0.580290 | 0.226857 | 0.461024 | 0.557530 | 0.287488 | 0.562707 |
| ... | ... | ... | ... | ... | ... | ... | ... |
| 625 | 0.674155 | 0.430854 | 0.571117 | 0.662502 | 0.407645 | 0.793664 | 0.687773 |
| 626 | 0.542585 | 0.502784 | 0.811512 | 0.265664 | 0.410735 | 0.521112 | 0.416184 |
| 627 | 0.643004 | 0.526702 | 0.764935 | 0.485639 | 0.488245 | 0.492473 | 0.596764 |
| 628 | 0.347746 | 0.540109 | 0.236229 | 0.188574 | 0.863443 | 0.292491 | 0.232118 |
| 629 | 0.416606 | 0.711201 | 0.271586 | 0.162163 | 0.806648 | 0.187518 | 0.286230 |

630 rows × 48 columns



ANN

In []:

```
ann = keras.Sequential([
    keras.layers.Dense(28, input_shape = (48,), activation = 'relu'),
    keras.layers.BatchNormalization(),
    keras.layers.Dense(40, activation='relu'),
    keras.layers.BatchNormalization(),
    keras.layers.Dense(30, activation='relu'),
    keras.layers.Dense(20, activation='relu'),
    keras.layers.Dense(10, activation='relu'),
    keras.layers.BatchNormalization(),
    keras.layers.Dense(7, activation='softmax')
])

ann.compile(
    optimizer = 'adam',
    loss = 'sparse_categorical_crossentropy',
    metrics = ['accuracy']
)
#tf.keras.optimizers.RMSprop()

ann.fit(X_train, Y_train, epochs = 300, validation_split=0.1, batch_size=16)
```

Epoch 1/300

36/36 [=====] - 2s 14ms/step - loss: 1.9451 - accuracy: 0.2099 - val_loss: 1.9344 - val_accuracy: 0.0476

Epoch 2/300

36/36 [=====] - 0s 4ms/step - loss: 1.6368 - accuracy: 0.3704 - val_loss: 1.9598 - val_accuracy: 0.0000e+00

Epoch 3/300

36/36 [=====] - 0s 3ms/step - loss: 1.4889 - accuracy: 0.4674 - val_loss: 1.9888 - val_accuracy: 0.0159

Epoch 4/300

36/36 [=====] - 0s 3ms/step - loss: 1.4514 - accuracy: 0.4515 - val_loss: 1.9838 - val_accuracy: 0.0159

Epoch 5/300

36/36 [=====] - 0s 3ms/step - loss: 1.2966 - accuracy: 0.52

91 - val_loss: 1.9274 - val_accuracy: 0.0317
Epoch 6/300
36/36 [=====] - 0s 3ms/step - loss: 1.2107 - accuracy: 0.58
73 - val_loss: 1.9113 - val_accuracy: 0.0794
Epoch 7/300
36/36 [=====] - 0s 3ms/step - loss: 1.1657 - accuracy: 0.62
43 - val_loss: 1.8744 - val_accuracy: 0.2222
Epoch 8/300
36/36 [=====] - 0s 4ms/step - loss: 1.0861 - accuracy: 0.63
14 - val_loss: 1.7144 - val_accuracy: 0.3810
Epoch 9/300
36/36 [=====] - 0s 4ms/step - loss: 1.0064 - accuracy: 0.68
96 - val_loss: 1.5800 - val_accuracy: 0.4286
Epoch 10/300
36/36 [=====] - 0s 4ms/step - loss: 0.9582 - accuracy: 0.69
14 - val_loss: 1.3212 - val_accuracy: 0.5238
Epoch 11/300
36/36 [=====] - 0s 4ms/step - loss: 0.9355 - accuracy: 0.69
49 - val_loss: 1.2143 - val_accuracy: 0.5714
Epoch 12/300
36/36 [=====] - 0s 5ms/step - loss: 0.8889 - accuracy: 0.71
78 - val_loss: 1.1123 - val_accuracy: 0.6190
Epoch 13/300
36/36 [=====] - 0s 4ms/step - loss: 0.8456 - accuracy: 0.69
49 - val_loss: 0.9130 - val_accuracy: 0.6984
Epoch 14/300
36/36 [=====] - 0s 3ms/step - loss: 0.7877 - accuracy: 0.74
60 - val_loss: 0.9114 - val_accuracy: 0.7302
Epoch 15/300
36/36 [=====] - 0s 3ms/step - loss: 0.7789 - accuracy: 0.76
19 - val_loss: 0.7073 - val_accuracy: 0.7778
Epoch 16/300
36/36 [=====] - 0s 3ms/step - loss: 0.7571 - accuracy: 0.76
54 - val_loss: 0.6611 - val_accuracy: 0.7778
Epoch 17/300
36/36 [=====] - 0s 3ms/step - loss: 0.7358 - accuracy: 0.76
01 - val_loss: 0.4986 - val_accuracy: 0.8254
Epoch 18/300
36/36 [=====] - 0s 4ms/step - loss: 0.7554 - accuracy: 0.76
19 - val_loss: 0.4655 - val_accuracy: 0.8889
Epoch 19/300
36/36 [=====] - 0s 3ms/step - loss: 0.7243 - accuracy: 0.75
66 - val_loss: 0.4481 - val_accuracy: 0.8571
Epoch 20/300
36/36 [=====] - 0s 4ms/step - loss: 0.6693 - accuracy: 0.77
25 - val_loss: 0.3750 - val_accuracy: 0.8889
Epoch 21/300
36/36 [=====] - 0s 3ms/step - loss: 0.6616 - accuracy: 0.78
66 - val_loss: 0.3960 - val_accuracy: 0.9206
Epoch 22/300
36/36 [=====] - 0s 4ms/step - loss: 0.6048 - accuracy: 0.79
72 - val_loss: 0.2595 - val_accuracy: 0.9206
Epoch 23/300
36/36 [=====] - 0s 3ms/step - loss: 0.5623 - accuracy: 0.81
31 - val_loss: 0.3439 - val_accuracy: 0.9048
Epoch 24/300
36/36 [=====] - 0s 3ms/step - loss: 0.6297 - accuracy: 0.77
60 - val_loss: 0.3470 - val_accuracy: 0.8889
Epoch 25/300
36/36 [=====] - 0s 3ms/step - loss: 0.5935 - accuracy: 0.79
89 - val_loss: 0.2596 - val_accuracy: 0.9365
Epoch 26/300
36/36 [=====] - 0s 3ms/step - loss: 0.5447 - accuracy: 0.83
60 - val_loss: 0.2710 - val_accuracy: 0.9365
Epoch 27/300
36/36 [=====] - 0s 3ms/step - loss: 0.5349 - accuracy: 0.83
07 - val_loss: 0.2107 - val_accuracy: 0.9524
Epoch 28/300
36/36 [=====] - 0s 3ms/step - loss: 0.5658 - accuracy: 0.79

89 - val_loss: 0.2229 - val_accuracy: 0.9365
Epoch 29/300
36/36 [=====] - 0s 4ms/step - loss: 0.5694 - accuracy: 0.81
31 - val_loss: 0.2592 - val_accuracy: 0.9365
Epoch 30/300
36/36 [=====] - 0s 3ms/step - loss: 0.4840 - accuracy: 0.84
13 - val_loss: 0.2247 - val_accuracy: 0.9048
Epoch 31/300
36/36 [=====] - 0s 3ms/step - loss: 0.5505 - accuracy: 0.81
13 - val_loss: 0.2597 - val_accuracy: 0.9206
Epoch 32/300
36/36 [=====] - 0s 3ms/step - loss: 0.4588 - accuracy: 0.85
19 - val_loss: 0.1843 - val_accuracy: 0.9206
Epoch 33/300
36/36 [=====] - 0s 3ms/step - loss: 0.4806 - accuracy: 0.83
07 - val_loss: 0.1524 - val_accuracy: 0.9524
Epoch 34/300
36/36 [=====] - 0s 3ms/step - loss: 0.4792 - accuracy: 0.85
71 - val_loss: 0.1473 - val_accuracy: 0.9683
Epoch 35/300
36/36 [=====] - 0s 4ms/step - loss: 0.5155 - accuracy: 0.83
95 - val_loss: 0.1289 - val_accuracy: 0.9524
Epoch 36/300
36/36 [=====] - 0s 4ms/step - loss: 0.5413 - accuracy: 0.82
01 - val_loss: 0.0865 - val_accuracy: 0.9841
Epoch 37/300
36/36 [=====] - 0s 3ms/step - loss: 0.4984 - accuracy: 0.82
19 - val_loss: 0.1586 - val_accuracy: 0.9683
Epoch 38/300
36/36 [=====] - 0s 3ms/step - loss: 0.4208 - accuracy: 0.85
36 - val_loss: 0.1200 - val_accuracy: 0.9841
Epoch 39/300
36/36 [=====] - 0s 3ms/step - loss: 0.4719 - accuracy: 0.84
83 - val_loss: 0.1081 - val_accuracy: 0.9683
Epoch 40/300
36/36 [=====] - 0s 3ms/step - loss: 0.4179 - accuracy: 0.86
95 - val_loss: 0.1062 - val_accuracy: 1.0000
Epoch 41/300
36/36 [=====] - 0s 4ms/step - loss: 0.4978 - accuracy: 0.82
19 - val_loss: 0.1588 - val_accuracy: 0.9524
Epoch 42/300
36/36 [=====] - 0s 3ms/step - loss: 0.4534 - accuracy: 0.84
66 - val_loss: 0.1316 - val_accuracy: 0.9524
Epoch 43/300
36/36 [=====] - 0s 3ms/step - loss: 0.3998 - accuracy: 0.87
48 - val_loss: 0.1188 - val_accuracy: 0.9683
Epoch 44/300
36/36 [=====] - 0s 3ms/step - loss: 0.3870 - accuracy: 0.87
30 - val_loss: 0.1400 - val_accuracy: 0.9524
Epoch 45/300
36/36 [=====] - 0s 3ms/step - loss: 0.4025 - accuracy: 0.85
36 - val_loss: 0.2226 - val_accuracy: 0.9365
Epoch 46/300
36/36 [=====] - 0s 3ms/step - loss: 0.4012 - accuracy: 0.85
89 - val_loss: 0.1069 - val_accuracy: 0.9683
Epoch 47/300
36/36 [=====] - 0s 5ms/step - loss: 0.3924 - accuracy: 0.86
60 - val_loss: 0.0959 - val_accuracy: 0.9683
Epoch 48/300
36/36 [=====] - 0s 3ms/step - loss: 0.3553 - accuracy: 0.88
18 - val_loss: 0.0728 - val_accuracy: 1.0000
Epoch 49/300
36/36 [=====] - 0s 3ms/step - loss: 0.4120 - accuracy: 0.86
24 - val_loss: 0.1196 - val_accuracy: 0.9524
Epoch 50/300
36/36 [=====] - 0s 3ms/step - loss: 0.3630 - accuracy: 0.87
48 - val_loss: 0.0448 - val_accuracy: 1.0000
Epoch 51/300
36/36 [=====] - 0s 3ms/step - loss: 0.3615 - accuracy: 0.88

71 - val_loss: 0.0916 - val_accuracy: 0.9841
Epoch 52/300
36/36 [=====] - 0s 3ms/step - loss: 0.4328 - accuracy: 0.84
48 - val_loss: 0.3589 - val_accuracy: 0.8730
Epoch 53/300
36/36 [=====] - 0s 4ms/step - loss: 0.3671 - accuracy: 0.87
48 - val_loss: 0.0578 - val_accuracy: 0.9841
Epoch 54/300
36/36 [=====] - 0s 4ms/step - loss: 0.3520 - accuracy: 0.87
48 - val_loss: 0.0512 - val_accuracy: 1.0000
Epoch 55/300
36/36 [=====] - 0s 4ms/step - loss: 0.3239 - accuracy: 0.89
42 - val_loss: 0.1281 - val_accuracy: 0.9683
Epoch 56/300
36/36 [=====] - 0s 5ms/step - loss: 0.3490 - accuracy: 0.88
89 - val_loss: 0.0660 - val_accuracy: 0.9841
Epoch 57/300
36/36 [=====] - 0s 4ms/step - loss: 0.3222 - accuracy: 0.88
54 - val_loss: 0.1130 - val_accuracy: 0.9841
Epoch 58/300
36/36 [=====] - 0s 4ms/step - loss: 0.4283 - accuracy: 0.87
48 - val_loss: 0.0411 - val_accuracy: 1.0000
Epoch 59/300
36/36 [=====] - 0s 3ms/step - loss: 0.3935 - accuracy: 0.86
24 - val_loss: 0.0521 - val_accuracy: 1.0000
Epoch 60/300
36/36 [=====] - 0s 3ms/step - loss: 0.3242 - accuracy: 0.88
54 - val_loss: 0.0547 - val_accuracy: 1.0000
Epoch 61/300
36/36 [=====] - 0s 4ms/step - loss: 0.3332 - accuracy: 0.89
59 - val_loss: 0.0798 - val_accuracy: 1.0000
Epoch 62/300
36/36 [=====] - 0s 4ms/step - loss: 0.3798 - accuracy: 0.86
42 - val_loss: 0.0786 - val_accuracy: 0.9683
Epoch 63/300
36/36 [=====] - 0s 5ms/step - loss: 0.3335 - accuracy: 0.88
54 - val_loss: 0.0604 - val_accuracy: 0.9841
Epoch 64/300
36/36 [=====] - 0s 4ms/step - loss: 0.3037 - accuracy: 0.89
59 - val_loss: 0.0292 - val_accuracy: 1.0000
Epoch 65/300
36/36 [=====] - 0s 3ms/step - loss: 0.2940 - accuracy: 0.90
12 - val_loss: 0.0523 - val_accuracy: 0.9841
Epoch 66/300
36/36 [=====] - 0s 3ms/step - loss: 0.2860 - accuracy: 0.90
48 - val_loss: 0.0267 - val_accuracy: 1.0000
Epoch 67/300
36/36 [=====] - 0s 3ms/step - loss: 0.3377 - accuracy: 0.86
77 - val_loss: 0.0372 - val_accuracy: 1.0000
Epoch 68/300
36/36 [=====] - 0s 3ms/step - loss: 0.2856 - accuracy: 0.89
07 - val_loss: 0.0793 - val_accuracy: 1.0000
Epoch 69/300
36/36 [=====] - 0s 3ms/step - loss: 0.3202 - accuracy: 0.89
42 - val_loss: 0.0505 - val_accuracy: 0.9841
Epoch 70/300
36/36 [=====] - 0s 3ms/step - loss: 0.2933 - accuracy: 0.89
07 - val_loss: 0.0294 - val_accuracy: 1.0000
Epoch 71/300
36/36 [=====] - 0s 3ms/step - loss: 0.2356 - accuracy: 0.92
06 - val_loss: 0.0232 - val_accuracy: 1.0000
Epoch 72/300
36/36 [=====] - 0s 3ms/step - loss: 0.3085 - accuracy: 0.89
42 - val_loss: 0.0256 - val_accuracy: 1.0000
Epoch 73/300
36/36 [=====] - 0s 3ms/step - loss: 0.2990 - accuracy: 0.90
48 - val_loss: 0.0497 - val_accuracy: 1.0000
Epoch 74/300
36/36 [=====] - 0s 3ms/step - loss: 0.3242 - accuracy: 0.88

01 - val_loss: 0.0311 - val_accuracy: 1.0000
Epoch 75/300
36/36 [=====] - 0s 3ms/step - loss: 0.3220 - accuracy: 0.88
36 - val_loss: 0.0465 - val_accuracy: 1.0000
Epoch 76/300
36/36 [=====] - 0s 3ms/step - loss: 0.2834 - accuracy: 0.91
01 - val_loss: 0.1403 - val_accuracy: 0.9365
Epoch 77/300
36/36 [=====] - 0s 3ms/step - loss: 0.2659 - accuracy: 0.91
01 - val_loss: 0.0269 - val_accuracy: 1.0000
Epoch 78/300
36/36 [=====] - 0s 4ms/step - loss: 0.2719 - accuracy: 0.91
71 - val_loss: 0.0495 - val_accuracy: 1.0000
Epoch 79/300
36/36 [=====] - 0s 3ms/step - loss: 0.3364 - accuracy: 0.89
95 - val_loss: 0.1156 - val_accuracy: 0.9841
Epoch 80/300
36/36 [=====] - 0s 3ms/step - loss: 0.2979 - accuracy: 0.90
65 - val_loss: 0.0897 - val_accuracy: 0.9683
Epoch 81/300
36/36 [=====] - 0s 3ms/step - loss: 0.2782 - accuracy: 0.90
12 - val_loss: 0.0448 - val_accuracy: 1.0000
Epoch 82/300
36/36 [=====] - 0s 3ms/step - loss: 0.2448 - accuracy: 0.91
18 - val_loss: 0.0224 - val_accuracy: 1.0000
Epoch 83/300
36/36 [=====] - 0s 3ms/step - loss: 0.2202 - accuracy: 0.92
95 - val_loss: 0.0216 - val_accuracy: 1.0000
Epoch 84/300
36/36 [=====] - 0s 3ms/step - loss: 0.2833 - accuracy: 0.91
18 - val_loss: 0.0339 - val_accuracy: 1.0000
Epoch 85/300
36/36 [=====] - 0s 3ms/step - loss: 0.2970 - accuracy: 0.88
18 - val_loss: 0.0183 - val_accuracy: 1.0000
Epoch 86/300
36/36 [=====] - 0s 3ms/step - loss: 0.2559 - accuracy: 0.91
01 - val_loss: 0.0151 - val_accuracy: 1.0000
Epoch 87/300
36/36 [=====] - 0s 3ms/step - loss: 0.2812 - accuracy: 0.90
30 - val_loss: 0.0274 - val_accuracy: 1.0000
Epoch 88/300
36/36 [=====] - 0s 3ms/step - loss: 0.2620 - accuracy: 0.91
53 - val_loss: 0.0277 - val_accuracy: 1.0000
Epoch 89/300
36/36 [=====] - 0s 3ms/step - loss: 0.2302 - accuracy: 0.91
36 - val_loss: 0.0152 - val_accuracy: 1.0000
Epoch 90/300
36/36 [=====] - 0s 4ms/step - loss: 0.2121 - accuracy: 0.92
95 - val_loss: 0.0677 - val_accuracy: 0.9841
Epoch 91/300
36/36 [=====] - 0s 4ms/step - loss: 0.2919 - accuracy: 0.89
77 - val_loss: 0.0185 - val_accuracy: 1.0000
Epoch 92/300
36/36 [=====] - 0s 3ms/step - loss: 0.2940 - accuracy: 0.90
48 - val_loss: 0.0395 - val_accuracy: 0.9841
Epoch 93/300
36/36 [=====] - 0s 3ms/step - loss: 0.2593 - accuracy: 0.92
06 - val_loss: 0.0254 - val_accuracy: 1.0000
Epoch 94/300
36/36 [=====] - 0s 3ms/step - loss: 0.2471 - accuracy: 0.89
77 - val_loss: 0.0111 - val_accuracy: 1.0000
Epoch 95/300
36/36 [=====] - 0s 5ms/step - loss: 0.2206 - accuracy: 0.93
30 - val_loss: 0.0290 - val_accuracy: 1.0000
Epoch 96/300
36/36 [=====] - 0s 3ms/step - loss: 0.2244 - accuracy: 0.92
95 - val_loss: 0.0132 - val_accuracy: 1.0000
Epoch 97/300
36/36 [=====] - 0s 3ms/step - loss: 0.2499 - accuracy: 0.91

36 - val_loss: 0.0454 - val_accuracy: 1.0000
Epoch 98/300
36/36 [=====] - 0s 3ms/step - loss: 0.2055 - accuracy: 0.93
47 - val_loss: 0.0471 - val_accuracy: 1.0000
Epoch 99/300
36/36 [=====] - 0s 3ms/step - loss: 0.2559 - accuracy: 0.91
53 - val_loss: 0.0102 - val_accuracy: 1.0000
Epoch 100/300
36/36 [=====] - 0s 4ms/step - loss: 0.2759 - accuracy: 0.90
30 - val_loss: 0.0358 - val_accuracy: 1.0000
Epoch 101/300
36/36 [=====] - 0s 3ms/step - loss: 0.2325 - accuracy: 0.91
53 - val_loss: 0.0360 - val_accuracy: 1.0000
Epoch 102/300
36/36 [=====] - 0s 4ms/step - loss: 0.2704 - accuracy: 0.89
77 - val_loss: 0.0317 - val_accuracy: 0.9841
Epoch 103/300
36/36 [=====] - 0s 6ms/step - loss: 0.2098 - accuracy: 0.91
89 - val_loss: 0.0197 - val_accuracy: 1.0000
Epoch 104/300
36/36 [=====] - 0s 4ms/step - loss: 0.2685 - accuracy: 0.90
65 - val_loss: 0.0979 - val_accuracy: 0.9683
Epoch 105/300
36/36 [=====] - 0s 3ms/step - loss: 0.2127 - accuracy: 0.92
42 - val_loss: 0.0102 - val_accuracy: 1.0000
Epoch 106/300
36/36 [=====] - 0s 3ms/step - loss: 0.2771 - accuracy: 0.89
07 - val_loss: 0.0448 - val_accuracy: 0.9841
Epoch 107/300
36/36 [=====] - 0s 4ms/step - loss: 0.2151 - accuracy: 0.92
24 - val_loss: 0.0818 - val_accuracy: 0.9683
Epoch 108/300
36/36 [=====] - 0s 3ms/step - loss: 0.2295 - accuracy: 0.92
06 - val_loss: 0.0633 - val_accuracy: 0.9683
Epoch 109/300
36/36 [=====] - 0s 3ms/step - loss: 0.3053 - accuracy: 0.89
42 - val_loss: 0.0180 - val_accuracy: 1.0000
Epoch 110/300
36/36 [=====] - 0s 3ms/step - loss: 0.2513 - accuracy: 0.91
71 - val_loss: 0.0195 - val_accuracy: 1.0000
Epoch 111/300
36/36 [=====] - 0s 4ms/step - loss: 0.2386 - accuracy: 0.91
71 - val_loss: 0.0446 - val_accuracy: 0.9683
Epoch 112/300
36/36 [=====] - 0s 4ms/step - loss: 0.2400 - accuracy: 0.90
48 - val_loss: 0.0244 - val_accuracy: 1.0000
Epoch 113/300
36/36 [=====] - 0s 4ms/step - loss: 0.2379 - accuracy: 0.92
77 - val_loss: 0.0243 - val_accuracy: 1.0000
Epoch 114/300
36/36 [=====] - 0s 4ms/step - loss: 0.2275 - accuracy: 0.92
06 - val_loss: 0.0174 - val_accuracy: 1.0000
Epoch 115/300
36/36 [=====] - 0s 4ms/step - loss: 0.2064 - accuracy: 0.92
59 - val_loss: 0.0373 - val_accuracy: 1.0000
Epoch 116/300
36/36 [=====] - 0s 3ms/step - loss: 0.2823 - accuracy: 0.91
36 - val_loss: 0.0469 - val_accuracy: 1.0000
Epoch 117/300
36/36 [=====] - 0s 3ms/step - loss: 0.2121 - accuracy: 0.91
18 - val_loss: 0.0218 - val_accuracy: 1.0000
Epoch 118/300
36/36 [=====] - 0s 4ms/step - loss: 0.1797 - accuracy: 0.94
00 - val_loss: 0.0216 - val_accuracy: 1.0000
Epoch 119/300
36/36 [=====] - 0s 3ms/step - loss: 0.2282 - accuracy: 0.91
71 - val_loss: 0.0538 - val_accuracy: 0.9683
Epoch 120/300
36/36 [=====] - 0s 4ms/step - loss: 0.2079 - accuracy: 0.92

06 - val_loss: 0.0211 - val_accuracy: 1.0000
Epoch 121/300
36/36 [=====] - ETA: 0s - loss: 0.2618 - accuracy: 0.92 - 0
s 3ms/step - loss: 0.2733 - accuracy: 0.9153 - val_loss: 0.0144 - val_accuracy: 1.00
00
Epoch 122/300
36/36 [=====] - 0s 4ms/step - loss: 0.1857 - accuracy: 0.94
89 - val_loss: 0.0110 - val_accuracy: 1.0000
Epoch 123/300
36/36 [=====] - 0s 4ms/step - loss: 0.2231 - accuracy: 0.92
59 - val_loss: 0.0202 - val_accuracy: 1.0000
Epoch 124/300
36/36 [=====] - 0s 4ms/step - loss: 0.1855 - accuracy: 0.94
18 - val_loss: 0.0605 - val_accuracy: 0.9683
Epoch 125/300
36/36 [=====] - 0s 3ms/step - loss: 0.1694 - accuracy: 0.94
89 - val_loss: 0.0091 - val_accuracy: 1.0000
Epoch 126/300
36/36 [=====] - 0s 3ms/step - loss: 0.1930 - accuracy: 0.91
89 - val_loss: 0.0093 - val_accuracy: 1.0000
Epoch 127/300
36/36 [=====] - 0s 4ms/step - loss: 0.1801 - accuracy: 0.94
53 - val_loss: 0.0197 - val_accuracy: 1.0000
Epoch 128/300
36/36 [=====] - 0s 4ms/step - loss: 0.2115 - accuracy: 0.92
77 - val_loss: 0.0540 - val_accuracy: 1.0000
Epoch 129/300
36/36 [=====] - 0s 3ms/step - loss: 0.1898 - accuracy: 0.93
30 - val_loss: 0.0336 - val_accuracy: 1.0000
Epoch 130/300
36/36 [=====] - 0s 3ms/step - loss: 0.2089 - accuracy: 0.91
89 - val_loss: 0.0334 - val_accuracy: 1.0000
Epoch 131/300
36/36 [=====] - 0s 3ms/step - loss: 0.1647 - accuracy: 0.94
18 - val_loss: 0.0123 - val_accuracy: 1.0000
Epoch 132/300
36/36 [=====] - 0s 4ms/step - loss: 0.1998 - accuracy: 0.92
95 - val_loss: 0.0277 - val_accuracy: 1.0000
Epoch 133/300
36/36 [=====] - 0s 3ms/step - loss: 0.1613 - accuracy: 0.94
53 - val_loss: 0.0165 - val_accuracy: 1.0000
Epoch 134/300
36/36 [=====] - 0s 3ms/step - loss: 0.1776 - accuracy: 0.93
12 - val_loss: 0.0299 - val_accuracy: 1.0000
Epoch 135/300
36/36 [=====] - 0s 3ms/step - loss: 0.1929 - accuracy: 0.93
65 - val_loss: 0.0506 - val_accuracy: 0.9841
Epoch 136/300
36/36 [=====] - 0s 4ms/step - loss: 0.1824 - accuracy: 0.93
30 - val_loss: 0.0100 - val_accuracy: 1.0000
Epoch 137/300
36/36 [=====] - 0s 4ms/step - loss: 0.1811 - accuracy: 0.93
83 - val_loss: 0.0228 - val_accuracy: 1.0000
Epoch 138/300
36/36 [=====] - 0s 4ms/step - loss: 0.1637 - accuracy: 0.95
06 - val_loss: 0.0125 - val_accuracy: 1.0000
Epoch 139/300
36/36 [=====] - 0s 3ms/step - loss: 0.1701 - accuracy: 0.94
53 - val_loss: 0.0117 - val_accuracy: 1.0000
Epoch 140/300
36/36 [=====] - 0s 3ms/step - loss: 0.1292 - accuracy: 0.94
71 - val_loss: 0.0252 - val_accuracy: 1.0000
Epoch 141/300
36/36 [=====] - 0s 4ms/step - loss: 0.1804 - accuracy: 0.94
36 - val_loss: 0.0160 - val_accuracy: 1.0000
Epoch 142/300
36/36 [=====] - 0s 3ms/step - loss: 0.1723 - accuracy: 0.94
71 - val_loss: 0.0392 - val_accuracy: 1.0000
Epoch 143/300

36/36 [=====] - 0s 3ms/step - loss: 0.2404 - accuracy: 0.91
53 - val_loss: 0.0048 - val_accuracy: 1.0000
Epoch 144/300
36/36 [=====] - 0s 3ms/step - loss: 0.1894 - accuracy: 0.93
30 - val_loss: 0.0016 - val_accuracy: 1.0000
Epoch 145/300
36/36 [=====] - 0s 3ms/step - loss: 0.1332 - accuracy: 0.95
59 - val_loss: 0.0032 - val_accuracy: 1.0000
Epoch 146/300
36/36 [=====] - 0s 3ms/step - loss: 0.1543 - accuracy: 0.95
77 - val_loss: 0.0141 - val_accuracy: 1.0000
Epoch 147/300
36/36 [=====] - 0s 4ms/step - loss: 0.1829 - accuracy: 0.94
00 - val_loss: 0.0571 - val_accuracy: 0.9683
Epoch 148/300
36/36 [=====] - 0s 3ms/step - loss: 0.1762 - accuracy: 0.94
71 - val_loss: 0.0504 - val_accuracy: 0.9841
Epoch 149/300
36/36 [=====] - 0s 3ms/step - loss: 0.1570 - accuracy: 0.94
89 - val_loss: 0.0125 - val_accuracy: 1.0000
Epoch 150/300
36/36 [=====] - 0s 3ms/step - loss: 0.2068 - accuracy: 0.92
77 - val_loss: 0.0036 - val_accuracy: 1.0000
Epoch 151/300
36/36 [=====] - 0s 4ms/step - loss: 0.2077 - accuracy: 0.92
06 - val_loss: 0.0151 - val_accuracy: 1.0000
Epoch 152/300
36/36 [=====] - 0s 4ms/step - loss: 0.1642 - accuracy: 0.94
36 - val_loss: 0.0226 - val_accuracy: 1.0000
Epoch 153/300
36/36 [=====] - 0s 5ms/step - loss: 0.1761 - accuracy: 0.92
24 - val_loss: 0.0094 - val_accuracy: 1.0000
Epoch 154/300
36/36 [=====] - 0s 4ms/step - loss: 0.1463 - accuracy: 0.94
71 - val_loss: 0.0209 - val_accuracy: 0.9841
Epoch 155/300
36/36 [=====] - 0s 3ms/step - loss: 0.2063 - accuracy: 0.94
00 - val_loss: 0.0029 - val_accuracy: 1.0000
Epoch 156/300
36/36 [=====] - 0s 4ms/step - loss: 0.2108 - accuracy: 0.91
89 - val_loss: 0.0108 - val_accuracy: 1.0000
Epoch 157/300
36/36 [=====] - 0s 3ms/step - loss: 0.1601 - accuracy: 0.94
36 - val_loss: 0.0029 - val_accuracy: 1.0000
Epoch 158/300
36/36 [=====] - 0s 3ms/step - loss: 0.1521 - accuracy: 0.95
06 - val_loss: 0.0039 - val_accuracy: 1.0000
Epoch 159/300
36/36 [=====] - 0s 3ms/step - loss: 0.1881 - accuracy: 0.93
12 - val_loss: 0.0152 - val_accuracy: 1.0000
Epoch 160/300
36/36 [=====] - 0s 3ms/step - loss: 0.1785 - accuracy: 0.94
18 - val_loss: 0.0097 - val_accuracy: 1.0000
Epoch 161/300
36/36 [=====] - 0s 4ms/step - loss: 0.2322 - accuracy: 0.92
77 - val_loss: 0.0737 - val_accuracy: 0.9683
Epoch 162/300
36/36 [=====] - 0s 5ms/step - loss: 0.1779 - accuracy: 0.93
83 - val_loss: 0.0195 - val_accuracy: 0.9841
Epoch 163/300
36/36 [=====] - 0s 3ms/step - loss: 0.1660 - accuracy: 0.94
18 - val_loss: 0.0082 - val_accuracy: 1.0000
Epoch 164/300
36/36 [=====] - 0s 3ms/step - loss: 0.1688 - accuracy: 0.94
18 - val_loss: 0.0847 - val_accuracy: 0.9683
Epoch 165/300
36/36 [=====] - 0s 5ms/step - loss: 0.1705 - accuracy: 0.93
65 - val_loss: 0.0457 - val_accuracy: 0.9683
Epoch 166/300

36/36 [=====] - 0s 5ms/step - loss: 0.1580 - accuracy: 0.95
77 - val_loss: 0.0084 - val_accuracy: 1.0000
Epoch 167/300
36/36 [=====] - 0s 4ms/step - loss: 0.1711 - accuracy: 0.94
53 - val_loss: 0.0192 - val_accuracy: 1.0000
Epoch 168/300
36/36 [=====] - 0s 3ms/step - loss: 0.1581 - accuracy: 0.94
00 - val_loss: 0.0032 - val_accuracy: 1.0000
Epoch 169/300
36/36 [=====] - 0s 3ms/step - loss: 0.1506 - accuracy: 0.95
94 - val_loss: 0.0056 - val_accuracy: 1.0000
Epoch 170/300
36/36 [=====] - 0s 3ms/step - loss: 0.2315 - accuracy: 0.92
24 - val_loss: 0.0246 - val_accuracy: 1.0000
Epoch 171/300
36/36 [=====] - ETA: 0s - loss: 0.2503 - accuracy: 0.91 - 0
s 3ms/step - loss: 0.2550 - accuracy: 0.9171 - val_loss: 0.0032 - val_accuracy: 1.00
00
Epoch 172/300
36/36 [=====] - 0s 4ms/step - loss: 0.2134 - accuracy: 0.92
77 - val_loss: 0.0062 - val_accuracy: 1.0000
Epoch 173/300
36/36 [=====] - 0s 3ms/step - loss: 0.1438 - accuracy: 0.94
89 - val_loss: 0.0247 - val_accuracy: 1.0000
Epoch 174/300
36/36 [=====] - 0s 3ms/step - loss: 0.1325 - accuracy: 0.95
06 - val_loss: 0.0184 - val_accuracy: 0.9841
Epoch 175/300
36/36 [=====] - 0s 3ms/step - loss: 0.1724 - accuracy: 0.93
30 - val_loss: 0.0063 - val_accuracy: 1.0000
Epoch 176/300
36/36 [=====] - 0s 4ms/step - loss: 0.1642 - accuracy: 0.94
36 - val_loss: 0.0285 - val_accuracy: 1.0000
Epoch 177/300
36/36 [=====] - 0s 3ms/step - loss: 0.1673 - accuracy: 0.93
12 - val_loss: 0.0254 - val_accuracy: 1.0000
Epoch 178/300
36/36 [=====] - 0s 3ms/step - loss: 0.1929 - accuracy: 0.93
12 - val_loss: 0.0063 - val_accuracy: 1.0000
Epoch 179/300
36/36 [=====] - 0s 4ms/step - loss: 0.1590 - accuracy: 0.95
24 - val_loss: 0.0050 - val_accuracy: 1.0000
Epoch 180/300
36/36 [=====] - 0s 4ms/step - loss: 0.1819 - accuracy: 0.94
00 - val_loss: 0.0206 - val_accuracy: 1.0000
Epoch 181/300
36/36 [=====] - 0s 3ms/step - loss: 0.1732 - accuracy: 0.94
00 - val_loss: 0.0484 - val_accuracy: 0.9841
Epoch 182/300
36/36 [=====] - 0s 4ms/step - loss: 0.1603 - accuracy: 0.94
71 - val_loss: 0.0087 - val_accuracy: 1.0000
Epoch 183/300
36/36 [=====] - 0s 4ms/step - loss: 0.1485 - accuracy: 0.95
77 - val_loss: 0.0088 - val_accuracy: 1.0000
Epoch 184/300
36/36 [=====] - 0s 4ms/step - loss: 0.1898 - accuracy: 0.92
59 - val_loss: 0.0091 - val_accuracy: 1.0000
Epoch 185/300
36/36 [=====] - 0s 3ms/step - loss: 0.1265 - accuracy: 0.95
06 - val_loss: 0.0080 - val_accuracy: 1.0000
Epoch 186/300
36/36 [=====] - 0s 3ms/step - loss: 0.1570 - accuracy: 0.93
83 - val_loss: 0.0044 - val_accuracy: 1.0000
Epoch 187/300
36/36 [=====] - 0s 3ms/step - loss: 0.1307 - accuracy: 0.95
59 - val_loss: 0.0429 - val_accuracy: 0.9841
Epoch 188/300
36/36 [=====] - 0s 3ms/step - loss: 0.1509 - accuracy: 0.94
71 - val_loss: 0.0546 - val_accuracy: 0.9683

Epoch 189/300
36/36 [=====] - 0s 5ms/step - loss: 0.1345 - accuracy: 0.94
89 - val_loss: 0.0052 - val_accuracy: 1.0000
Epoch 190/300
36/36 [=====] - 0s 4ms/step - loss: 0.1741 - accuracy: 0.95
24 - val_loss: 0.0152 - val_accuracy: 1.0000
Epoch 191/300
36/36 [=====] - 0s 3ms/step - loss: 0.1951 - accuracy: 0.94
18 - val_loss: 0.0048 - val_accuracy: 1.0000
Epoch 192/300
36/36 [=====] - 0s 4ms/step - loss: 0.1905 - accuracy: 0.93
12 - val_loss: 0.0381 - val_accuracy: 0.9683
Epoch 193/300
36/36 [=====] - 0s 4ms/step - loss: 0.1765 - accuracy: 0.94
53 - val_loss: 0.0030 - val_accuracy: 1.0000
Epoch 194/300
36/36 [=====] - 0s 4ms/step - loss: 0.1701 - accuracy: 0.94
53 - val_loss: 0.0063 - val_accuracy: 1.0000
Epoch 195/300
36/36 [=====] - 0s 5ms/step - loss: 0.1566 - accuracy: 0.94
00 - val_loss: 0.0134 - val_accuracy: 1.0000
Epoch 196/300
36/36 [=====] - 0s 4ms/step - loss: 0.1435 - accuracy: 0.95
77 - val_loss: 0.0083 - val_accuracy: 1.0000
Epoch 197/300
36/36 [=====] - 0s 5ms/step - loss: 0.1773 - accuracy: 0.92
77 - val_loss: 0.0097 - val_accuracy: 1.0000
Epoch 198/300
36/36 [=====] - 0s 6ms/step - loss: 0.1475 - accuracy: 0.95
59 - val_loss: 0.0104 - val_accuracy: 1.0000
Epoch 199/300
36/36 [=====] - 0s 4ms/step - loss: 0.1490 - accuracy: 0.95
41 - val_loss: 0.0121 - val_accuracy: 1.0000
Epoch 200/300
36/36 [=====] - 0s 4ms/step - loss: 0.1564 - accuracy: 0.94
53 - val_loss: 0.0188 - val_accuracy: 1.0000
Epoch 201/300
36/36 [=====] - 0s 4ms/step - loss: 0.1280 - accuracy: 0.95
41 - val_loss: 0.0035 - val_accuracy: 1.0000
Epoch 202/300
36/36 [=====] - 0s 4ms/step - loss: 0.1231 - accuracy: 0.95
59 - val_loss: 0.0018 - val_accuracy: 1.0000
Epoch 203/300
36/36 [=====] - 0s 5ms/step - loss: 0.1339 - accuracy: 0.95
24 - val_loss: 0.0279 - val_accuracy: 1.0000
Epoch 204/300
36/36 [=====] - 0s 4ms/step - loss: 0.1245 - accuracy: 0.95
24 - val_loss: 0.0020 - val_accuracy: 1.0000
Epoch 205/300
36/36 [=====] - 0s 4ms/step - loss: 0.1217 - accuracy: 0.96
12 - val_loss: 0.0036 - val_accuracy: 1.0000
Epoch 206/300
36/36 [=====] - 0s 5ms/step - loss: 0.1339 - accuracy: 0.95
77 - val_loss: 0.0358 - val_accuracy: 1.0000
Epoch 207/300
36/36 [=====] - 0s 4ms/step - loss: 0.2131 - accuracy: 0.92
24 - val_loss: 0.0096 - val_accuracy: 1.0000
Epoch 208/300
36/36 [=====] - 0s 5ms/step - loss: 0.1544 - accuracy: 0.95
94 - val_loss: 0.0071 - val_accuracy: 1.0000
Epoch 209/300
36/36 [=====] - 0s 6ms/step - loss: 0.2349 - accuracy: 0.91
71 - val_loss: 0.0060 - val_accuracy: 1.0000
Epoch 210/300
36/36 [=====] - 0s 5ms/step - loss: 0.1508 - accuracy: 0.95
24 - val_loss: 0.0316 - val_accuracy: 0.9841
Epoch 211/300
36/36 [=====] - 0s 4ms/step - loss: 0.2485 - accuracy: 0.91
01 - val_loss: 0.0148 - val_accuracy: 1.0000

Epoch 212/300
36/36 [=====] - 0s 4ms/step - loss: 0.2420 - accuracy: 0.90
65 - val_loss: 0.0137 - val_accuracy: 1.0000
Epoch 213/300
36/36 [=====] - 0s 4ms/step - loss: 0.2366 - accuracy: 0.92
24 - val_loss: 0.0246 - val_accuracy: 1.0000
Epoch 214/300
36/36 [=====] - 0s 5ms/step - loss: 0.1547 - accuracy: 0.95
41 - val_loss: 0.0066 - val_accuracy: 1.0000
Epoch 215/300
36/36 [=====] - 0s 5ms/step - loss: 0.1221 - accuracy: 0.95
41 - val_loss: 0.0054 - val_accuracy: 1.0000
Epoch 216/300
36/36 [=====] - 0s 5ms/step - loss: 0.1882 - accuracy: 0.92
95 - val_loss: 0.0951 - val_accuracy: 0.9683
Epoch 217/300
36/36 [=====] - 0s 4ms/step - loss: 0.1802 - accuracy: 0.95
06 - val_loss: 0.0101 - val_accuracy: 1.0000
Epoch 218/300
36/36 [=====] - 0s 4ms/step - loss: 0.1216 - accuracy: 0.95
41 - val_loss: 0.0135 - val_accuracy: 1.0000
Epoch 219/300
36/36 [=====] - 0s 3ms/step - loss: 0.1513 - accuracy: 0.95
41 - val_loss: 0.0096 - val_accuracy: 1.0000
Epoch 220/300
36/36 [=====] - 0s 5ms/step - loss: 0.1643 - accuracy: 0.94
53 - val_loss: 0.0404 - val_accuracy: 0.9683
Epoch 221/300
36/36 [=====] - 0s 4ms/step - loss: 0.1584 - accuracy: 0.94
18 - val_loss: 0.0053 - val_accuracy: 1.0000
Epoch 222/300
36/36 [=====] - 0s 3ms/step - loss: 0.1434 - accuracy: 0.94
71 - val_loss: 0.0066 - val_accuracy: 1.0000
Epoch 223/300
36/36 [=====] - 0s 3ms/step - loss: 0.1312 - accuracy: 0.95
77 - val_loss: 0.0056 - val_accuracy: 1.0000
Epoch 224/300
36/36 [=====] - 0s 3ms/step - loss: 0.1800 - accuracy: 0.94
53 - val_loss: 0.0052 - val_accuracy: 1.0000
Epoch 225/300
36/36 [=====] - 0s 3ms/step - loss: 0.1104 - accuracy: 0.96
65 - val_loss: 0.0016 - val_accuracy: 1.0000
Epoch 226/300
36/36 [=====] - 0s 3ms/step - loss: 0.1426 - accuracy: 0.96
12 - val_loss: 0.0020 - val_accuracy: 1.0000
Epoch 227/300
36/36 [=====] - 0s 4ms/step - loss: 0.1253 - accuracy: 0.95
94 - val_loss: 0.0054 - val_accuracy: 1.0000
Epoch 228/300
36/36 [=====] - 0s 3ms/step - loss: 0.1485 - accuracy: 0.95
77 - val_loss: 0.0393 - val_accuracy: 0.9683
Epoch 229/300
36/36 [=====] - 0s 4ms/step - loss: 0.1493 - accuracy: 0.94
36 - val_loss: 0.0133 - val_accuracy: 1.0000
Epoch 230/300
36/36 [=====] - 0s 4ms/step - loss: 0.1395 - accuracy: 0.95
06 - val_loss: 0.0135 - val_accuracy: 1.0000
Epoch 231/300
36/36 [=====] - 0s 4ms/step - loss: 0.2110 - accuracy: 0.94
18 - val_loss: 0.0203 - val_accuracy: 1.0000
Epoch 232/300
36/36 [=====] - 0s 4ms/step - loss: 0.1764 - accuracy: 0.93
12 - val_loss: 0.0077 - val_accuracy: 1.0000
Epoch 233/300
36/36 [=====] - 0s 4ms/step - loss: 0.1379 - accuracy: 0.96
30 - val_loss: 0.0082 - val_accuracy: 1.0000
Epoch 234/300
36/36 [=====] - 0s 5ms/step - loss: 0.1673 - accuracy: 0.93
30 - val_loss: 0.0015 - val_accuracy: 1.0000

Epoch 235/300
36/36 [=====] - 0s 4ms/step - loss: 0.1010 - accuracy: 0.95
94 - val_loss: 9.8755e-04 - val_accuracy: 1.0000
Epoch 236/300
36/36 [=====] - 0s 5ms/step - loss: 0.0900 - accuracy: 0.96
83 - val_loss: 0.0025 - val_accuracy: 1.0000
Epoch 237/300
36/36 [=====] - 0s 4ms/step - loss: 0.1362 - accuracy: 0.95
24 - val_loss: 0.0056 - val_accuracy: 1.0000
Epoch 238/300
36/36 [=====] - 0s 4ms/step - loss: 0.1260 - accuracy: 0.95
24 - val_loss: 0.0186 - val_accuracy: 1.0000
Epoch 239/300
36/36 [=====] - 0s 4ms/step - loss: 0.1117 - accuracy: 0.95
94 - val_loss: 0.0049 - val_accuracy: 1.0000
Epoch 240/300
36/36 [=====] - 0s 4ms/step - loss: 0.1377 - accuracy: 0.95
24 - val_loss: 0.0014 - val_accuracy: 1.0000
Epoch 241/300
36/36 [=====] - 0s 4ms/step - loss: 0.1562 - accuracy: 0.94
36 - val_loss: 0.0067 - val_accuracy: 1.0000
Epoch 242/300
36/36 [=====] - 0s 4ms/step - loss: 0.1201 - accuracy: 0.95
94 - val_loss: 0.0049 - val_accuracy: 1.0000
Epoch 243/300
36/36 [=====] - 0s 3ms/step - loss: 0.1792 - accuracy: 0.93
30 - val_loss: 0.0019 - val_accuracy: 1.0000
Epoch 244/300
36/36 [=====] - 0s 3ms/step - loss: 0.1212 - accuracy: 0.95
24 - val_loss: 0.0028 - val_accuracy: 1.0000
Epoch 245/300
36/36 [=====] - 0s 4ms/step - loss: 0.1272 - accuracy: 0.95
59 - val_loss: 0.0051 - val_accuracy: 1.0000
Epoch 246/300
36/36 [=====] - 0s 4ms/step - loss: 0.0967 - accuracy: 0.97
00 - val_loss: 8.7818e-04 - val_accuracy: 1.0000
Epoch 247/300
36/36 [=====] - 0s 3ms/step - loss: 0.1198 - accuracy: 0.95
77 - val_loss: 0.0014 - val_accuracy: 1.0000
Epoch 248/300
36/36 [=====] - 0s 3ms/step - loss: 0.1179 - accuracy: 0.95
94 - val_loss: 0.0184 - val_accuracy: 0.9841
Epoch 249/300
36/36 [=====] - 0s 3ms/step - loss: 0.1072 - accuracy: 0.95
59 - val_loss: 0.0032 - val_accuracy: 1.0000
Epoch 250/300
36/36 [=====] - 0s 3ms/step - loss: 0.1164 - accuracy: 0.95
59 - val_loss: 0.0013 - val_accuracy: 1.0000
Epoch 251/300
36/36 [=====] - 0s 3ms/step - loss: 0.1716 - accuracy: 0.94
53 - val_loss: 0.0018 - val_accuracy: 1.0000
Epoch 252/300
36/36 [=====] - 0s 3ms/step - loss: 0.1220 - accuracy: 0.96
12 - val_loss: 0.0034 - val_accuracy: 1.0000
Epoch 253/300
36/36 [=====] - 0s 3ms/step - loss: 0.1410 - accuracy: 0.95
24 - val_loss: 0.0026 - val_accuracy: 1.0000
Epoch 254/300
36/36 [=====] - 0s 3ms/step - loss: 0.1151 - accuracy: 0.95
41 - val_loss: 0.0021 - val_accuracy: 1.0000
Epoch 255/300
36/36 [=====] - 0s 4ms/step - loss: 0.1520 - accuracy: 0.94
18 - val_loss: 0.0035 - val_accuracy: 1.0000
Epoch 256/300
36/36 [=====] - 0s 5ms/step - loss: 0.1199 - accuracy: 0.95
06 - val_loss: 3.6406e-04 - val_accuracy: 1.0000
Epoch 257/300
36/36 [=====] - 0s 3ms/step - loss: 0.1323 - accuracy: 0.95
77 - val_loss: 0.0018 - val_accuracy: 1.0000

Epoch 258/300
36/36 [=====] - 0s 3ms/step - loss: 0.1253 - accuracy: 0.94
89 - val_loss: 0.0013 - val_accuracy: 1.0000
Epoch 259/300
36/36 [=====] - 0s 3ms/step - loss: 0.1090 - accuracy: 0.97
18 - val_loss: 0.0031 - val_accuracy: 1.0000
Epoch 260/300
36/36 [=====] - 0s 3ms/step - loss: 0.1883 - accuracy: 0.93
65 - val_loss: 0.0036 - val_accuracy: 1.0000
Epoch 261/300
36/36 [=====] - 0s 3ms/step - loss: 0.1557 - accuracy: 0.95
41 - val_loss: 0.0043 - val_accuracy: 1.0000
Epoch 262/300
36/36 [=====] - 0s 3ms/step - loss: 0.1088 - accuracy: 0.95
41 - val_loss: 0.0027 - val_accuracy: 1.0000
Epoch 263/300
36/36 [=====] - 0s 3ms/step - loss: 0.1522 - accuracy: 0.94
89 - val_loss: 0.0049 - val_accuracy: 1.0000
Epoch 264/300
36/36 [=====] - 0s 4ms/step - loss: 0.0932 - accuracy: 0.97
53 - val_loss: 0.0081 - val_accuracy: 1.0000
Epoch 265/300
36/36 [=====] - 0s 4ms/step - loss: 0.1003 - accuracy: 0.97
18 - val_loss: 0.0111 - val_accuracy: 1.0000
Epoch 266/300
36/36 [=====] - 0s 3ms/step - loss: 0.1460 - accuracy: 0.95
06 - val_loss: 0.0071 - val_accuracy: 1.0000
Epoch 267/300
36/36 [=====] - 0s 3ms/step - loss: 0.1226 - accuracy: 0.95
77 - val_loss: 0.0038 - val_accuracy: 1.0000
Epoch 268/300
36/36 [=====] - 0s 3ms/step - loss: 0.1572 - accuracy: 0.93
83 - val_loss: 0.0290 - val_accuracy: 1.0000
Epoch 269/300
36/36 [=====] - 0s 3ms/step - loss: 0.1318 - accuracy: 0.95
77 - val_loss: 0.0069 - val_accuracy: 1.0000
Epoch 270/300
36/36 [=====] - 0s 3ms/step - loss: 0.1417 - accuracy: 0.95
06 - val_loss: 0.0200 - val_accuracy: 0.9841
Epoch 271/300
36/36 [=====] - 0s 3ms/step - loss: 0.1000 - accuracy: 0.96
65 - val_loss: 0.0046 - val_accuracy: 1.0000
Epoch 272/300
36/36 [=====] - 0s 3ms/step - loss: 0.1314 - accuracy: 0.95
77 - val_loss: 0.0094 - val_accuracy: 1.0000
Epoch 273/300
36/36 [=====] - 0s 3ms/step - loss: 0.1089 - accuracy: 0.96
12 - val_loss: 0.0040 - val_accuracy: 1.0000
Epoch 274/300
36/36 [=====] - 0s 3ms/step - loss: 0.0856 - accuracy: 0.97
00 - val_loss: 0.0049 - val_accuracy: 1.0000
Epoch 275/300
36/36 [=====] - ETA: 0s - loss: 0.0829 - accuracy: 0.97 - 0
s 3ms/step - loss: 0.1067 - accuracy: 0.9630 - val_loss: 0.0026 - val_accuracy: 1.00
00
Epoch 276/300
36/36 [=====] - 0s 4ms/step - loss: 0.1126 - accuracy: 0.96
30 - val_loss: 0.0154 - val_accuracy: 0.9841
Epoch 277/300
36/36 [=====] - 0s 4ms/step - loss: 0.0852 - accuracy: 0.96
65 - val_loss: 0.0017 - val_accuracy: 1.0000
Epoch 278/300
36/36 [=====] - 0s 3ms/step - loss: 0.1386 - accuracy: 0.95
06 - val_loss: 0.0071 - val_accuracy: 1.0000
Epoch 279/300
36/36 [=====] - 0s 3ms/step - loss: 0.1275 - accuracy: 0.95
41 - val_loss: 0.0019 - val_accuracy: 1.0000
Epoch 280/300
36/36 [=====] - 0s 3ms/step - loss: 0.1504 - accuracy: 0.95

```

06 - val_loss: 0.0019 - val_accuracy: 1.0000
Epoch 281/300
36/36 [=====] - 0s 7ms/step - loss: 0.1188 - accuracy: 0.96
12 - val_loss: 0.0012 - val_accuracy: 1.0000
Epoch 282/300
36/36 [=====] - 0s 3ms/step - loss: 0.1476 - accuracy: 0.95
77 - val_loss: 0.0018 - val_accuracy: 1.0000
Epoch 283/300
36/36 [=====] - 0s 3ms/step - loss: 0.1084 - accuracy: 0.95
59 - val_loss: 0.0032 - val_accuracy: 1.0000
Epoch 284/300
36/36 [=====] - 0s 3ms/step - loss: 0.0959 - accuracy: 0.96
83 - val_loss: 0.0021 - val_accuracy: 1.0000
Epoch 285/300
36/36 [=====] - 0s 3ms/step - loss: 0.1250 - accuracy: 0.95
41 - val_loss: 9.3564e-04 - val_accuracy: 1.0000
Epoch 286/300
36/36 [=====] - 0s 3ms/step - loss: 0.1278 - accuracy: 0.95
59 - val_loss: 6.6924e-04 - val_accuracy: 1.0000
Epoch 287/300
36/36 [=====] - 0s 3ms/step - loss: 0.0911 - accuracy: 0.96
65 - val_loss: 0.0028 - val_accuracy: 1.0000
Epoch 288/300
36/36 [=====] - 0s 4ms/step - loss: 0.0746 - accuracy: 0.98
06 - val_loss: 0.0092 - val_accuracy: 1.0000
Epoch 289/300
36/36 [=====] - 0s 5ms/step - loss: 0.1399 - accuracy: 0.94
89 - val_loss: 0.0035 - val_accuracy: 1.0000
Epoch 290/300
36/36 [=====] - 0s 4ms/step - loss: 0.1051 - accuracy: 0.96
12 - val_loss: 9.3830e-04 - val_accuracy: 1.0000
Epoch 291/300
36/36 [=====] - 0s 3ms/step - loss: 0.1004 - accuracy: 0.97
35 - val_loss: 0.0040 - val_accuracy: 1.0000
Epoch 292/300
36/36 [=====] - 0s 3ms/step - loss: 0.1462 - accuracy: 0.95
41 - val_loss: 0.0013 - val_accuracy: 1.0000
Epoch 293/300
36/36 [=====] - 0s 5ms/step - loss: 0.1382 - accuracy: 0.95
24 - val_loss: 9.4749e-04 - val_accuracy: 1.0000
Epoch 294/300
36/36 [=====] - 0s 4ms/step - loss: 0.0777 - accuracy: 0.97
18 - val_loss: 8.2144e-04 - val_accuracy: 1.0000
Epoch 295/300
36/36 [=====] - 0s 4ms/step - loss: 0.0971 - accuracy: 0.96
65 - val_loss: 0.0017 - val_accuracy: 1.0000
Epoch 296/300
36/36 [=====] - 0s 5ms/step - loss: 0.1374 - accuracy: 0.95
06 - val_loss: 0.0471 - val_accuracy: 0.9841
Epoch 297/300
36/36 [=====] - 0s 5ms/step - loss: 0.1260 - accuracy: 0.96
30 - val_loss: 0.0032 - val_accuracy: 1.0000
Epoch 298/300
36/36 [=====] - 0s 4ms/step - loss: 0.1366 - accuracy: 0.95
06 - val_loss: 0.0072 - val_accuracy: 1.0000
Epoch 299/300
36/36 [=====] - 0s 6ms/step - loss: 0.0835 - accuracy: 0.97
71 - val_loss: 7.3829e-04 - val_accuracy: 1.0000
Epoch 300/300
36/36 [=====] - 0s 6ms/step - loss: 0.1083 - accuracy: 0.95
94 - val_loss: 0.0011 - val_accuracy: 1.0000

```

```
Out[ ]: <keras.callbacks.History at 0x20d3e9b1588>
```

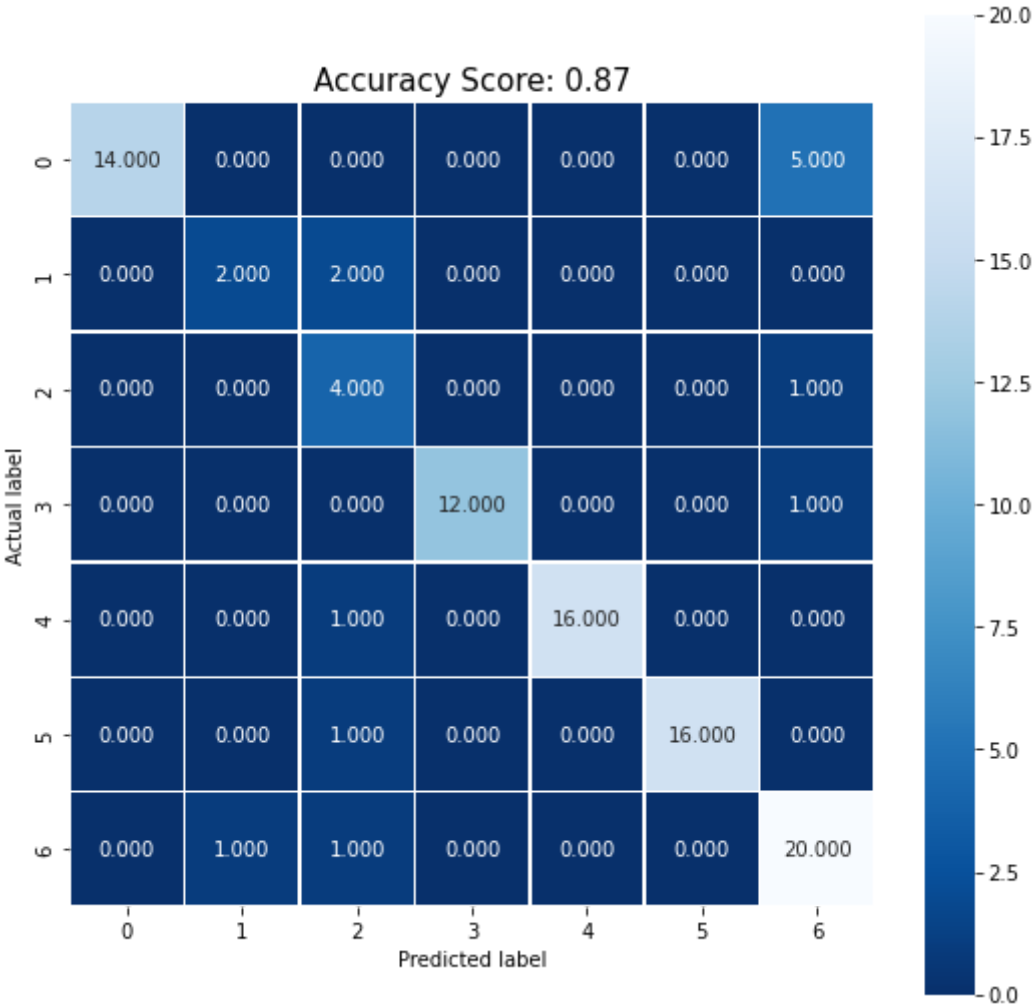
```

In [ ]: y_pred_ann = [np.argmax(i) for i in ann.predict(x_test)]
        score_ann = accuracy_score(y_test, y_pred_ann)
        score_ann

```

Out[]: 0.865979381443299

```
In [ ]: cf_ann = confusion_matrix(y_test, y_pred_ann)
plt.figure(figsize=(9,9))
sns.heatmap(cf_ann, annot=True, fmt=".3f", linewidths=.5, square = True, cmap = 'Blu
plt.ylabel('Actual label');
plt.xlabel('Predicted label');
all_sample_title = 'Accuracy Score: {0}'.format(round(score_ann,2))
plt.title(all_sample_title, size = 15);
```



```
In [ ]: print(classification_report(y_test,y_pred_ann))
```

| | precision | recall | f1-score | support |
|--------------|-----------|--------|----------|---------|
| 0 | 1.00 | 0.74 | 0.85 | 19 |
| 1 | 0.67 | 0.50 | 0.57 | 4 |
| 2 | 0.44 | 0.80 | 0.57 | 5 |
| 3 | 1.00 | 0.92 | 0.96 | 13 |
| 4 | 1.00 | 0.94 | 0.97 | 17 |
| 5 | 1.00 | 0.94 | 0.97 | 17 |
| 6 | 0.74 | 0.91 | 0.82 | 22 |
| accuracy | | | 0.87 | 97 |
| macro avg | 0.84 | 0.82 | 0.82 | 97 |
| weighted avg | 0.90 | 0.87 | 0.87 | 97 |

SVM

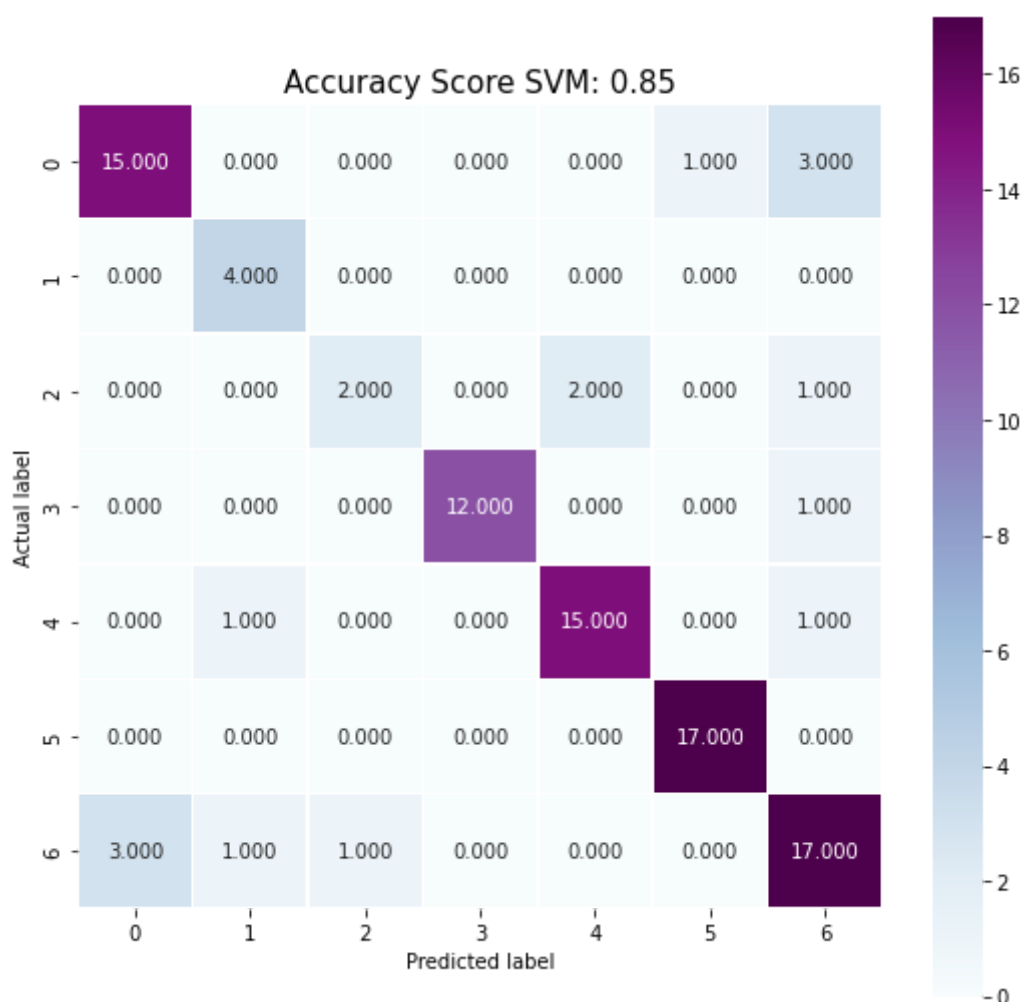

```
In [ ]: classifier_svm = SVC(kernel = 'rbf', C=2.5, gamma=1.4, random_state = 0)
classifier_svm.fit(X_train, Y_train)
```

```
Out[ ]: SVC(C=2.5, gamma=1.4, random_state=0)
```

```
In [ ]: y_pred_svm = classifier_svm.predict(x_test)
cf_svm = confusion_matrix(y_test, y_pred_svm)
score_svm = accuracy_score(y_test, y_pred_svm)
score_svm
```

```
Out[ ]: 0.845360824742268
```

```
In [ ]: plt.figure(figsize=(9,9))
sns.heatmap(cf_svm, annot=True, fmt=".3f", linewidths=.5, square = True, cmap = 'BuP
plt.ylabel('Actual label');
plt.xlabel('Predicted label');
all_sample_title = 'Accuracy Score SVM: {0}'.format(round(score_svm,2))
plt.title(all_sample_title, size = 15);
```



```
In [ ]: print(classification_report(y_test,y_pred_svm))
```

| | precision | recall | f1-score | support |
|---|-----------|--------|----------|---------|
| 0 | 0.83 | 0.79 | 0.81 | 19 |
| 1 | 0.67 | 1.00 | 0.80 | 4 |
| 2 | 0.67 | 0.40 | 0.50 | 5 |
| 3 | 1.00 | 0.92 | 0.96 | 13 |
| 4 | 0.88 | 0.88 | 0.88 | 17 |

| | | | | | |
|--------------|---|------|------|------|----|
| | 5 | 0.94 | 1.00 | 0.97 | 17 |
| | 6 | 0.74 | 0.77 | 0.76 | 22 |
| accuracy | | | | 0.85 | 97 |
| macro avg | | 0.82 | 0.82 | 0.81 | 97 |
| weighted avg | | 0.85 | 0.85 | 0.84 | 97 |

RF

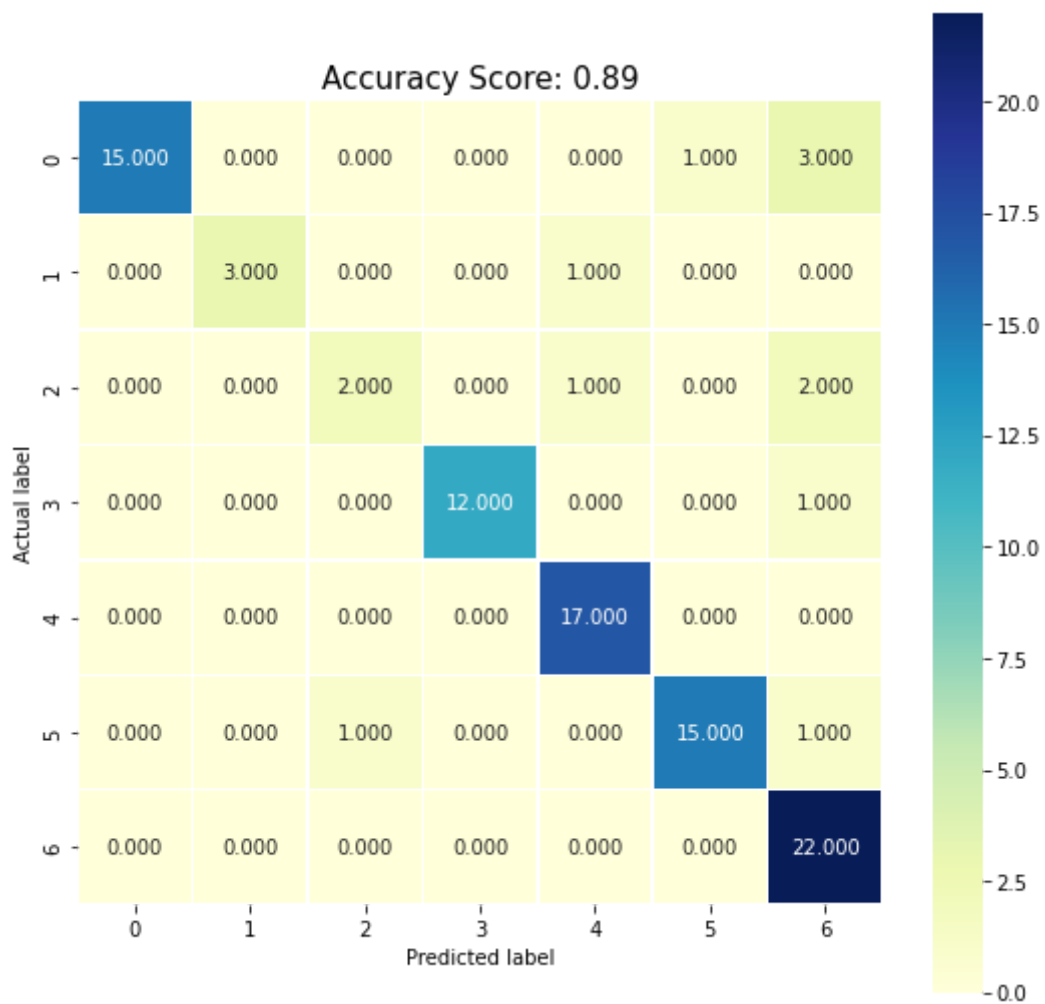
```
In [ ]: rf = RandomForestClassifier(n_estimators = 300, criterion = 'gini', max_depth=10, r
rf.fit(X_train, Y_train)
```

```
Out[ ]: RandomForestClassifier(max_depth=10, n_estimators=300, random_state=42)
```

```
In [ ]: y_pred_rf = rf.predict(x_test)
#y_pred_rf = [int(i) for i in y_pred_rf]
cf_rf = confusion_matrix(y_test, y_pred_rf)
score_rf = accuracy_score(y_test, y_pred_rf)
score_rf = round(score_rf,2)
score_rf
```

```
Out[ ]: 0.89
```

```
In [ ]: cf_rf = confusion_matrix(y_test, y_pred_rf)
plt.figure(figsize=(9,9))
sns.heatmap(cf_rf, annot=True, fmt=".3f", linewidths=.5, square = True, cmap = 'YlGn
plt.ylabel('Actual label');
plt.xlabel('Predicted label');
all_sample_title = 'Accuracy Score: {0}'.format(score_rf)
plt.title(all_sample_title, size = 15);
```



In []:

```
print(classification_report(y_test,y_pred_rf))
```

| | precision | recall | f1-score | support |
|--------------|-----------|--------|----------|---------|
| 0 | 1.00 | 0.79 | 0.88 | 19 |
| 1 | 1.00 | 0.75 | 0.86 | 4 |
| 2 | 0.67 | 0.40 | 0.50 | 5 |
| 3 | 1.00 | 0.92 | 0.96 | 13 |
| 4 | 0.89 | 1.00 | 0.94 | 17 |
| 5 | 0.94 | 0.88 | 0.91 | 17 |
| 6 | 0.76 | 1.00 | 0.86 | 22 |
| accuracy | | | 0.89 | 97 |
| macro avg | 0.89 | 0.82 | 0.85 | 97 |
| weighted avg | 0.90 | 0.89 | 0.88 | 97 |