

# **Urban Scene Cleanliness Classification using Transfer Learning and Explainable Deep learning**

**PREPARED BY**

**GOVINDA SHAW (106439)**

**MEDHANSH AHUJA (105982)**

**COURSE: LEARNING FROM IMAGES (2025-26)**

**UNIVERSITY: BERLINER HOCHSCHULE FÜR TECHNIK**

**PROFESSOR : KRISTIAN HILDEBRAND**

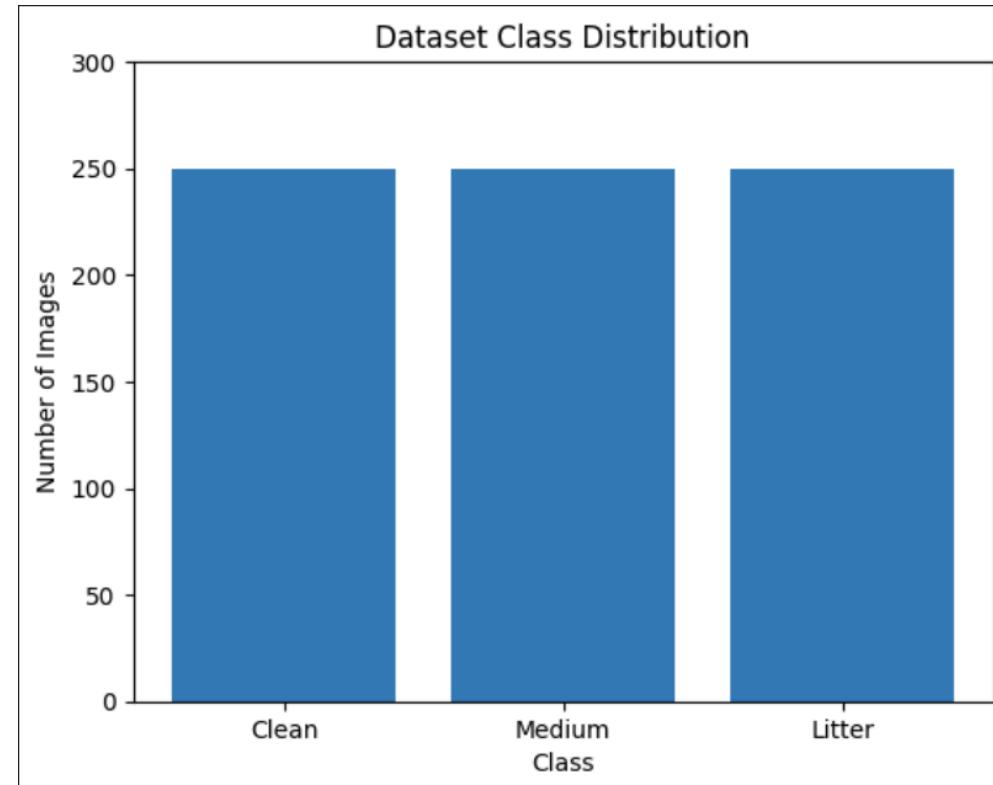
## Problem statement

Urban cleanliness monitoring is important for smart city planning and public health, yet manual inspection is subjective and resource-intensive.

This project investigates whether deep convolutional neural networks can automatically classify street images into Clean, Medium, and Litter categories. We further examine how transfer learning affects classification accuracy and decision stability in real-world urban scenes.

## Dataset overview:

- Original images sourced from Kaggle dataset
- Reorganized into three classes (Clean, Medium, Litter)
- Total Images: 750
- Images per class: 250 each
- Train/Val/Test split: 70% / 15% / 15%



# Sample images from each class

## Clean



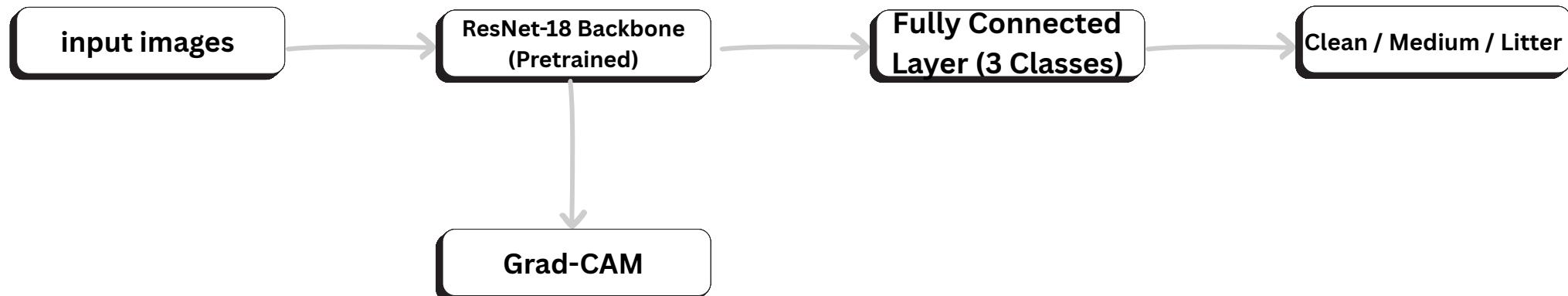
## Medium



## Litter:



# Method overview



## Model Architecture

- ResNet-18 Convolutional Neural Network
- Modified final layer for 3-class classification (Clean, Medium, Litter)

## Training Strategies

- **Transfer Learning:** Pretrained on ImageNet, fine-tuned on urban dataset
- **From Scratch:** Random weight initialization, trained entirely on dataset

## Optimization

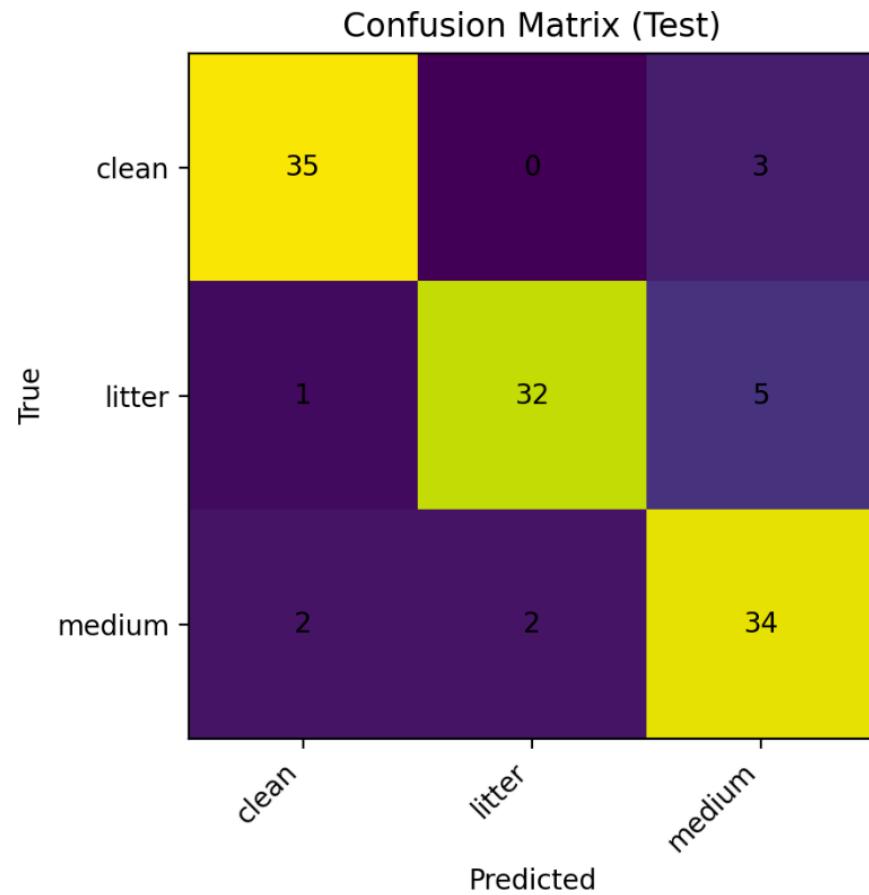
- Loss Function: Cross-Entropy Loss
- Optimizer: Adam
- Learning rate scheduling applied

## Model Interpretability

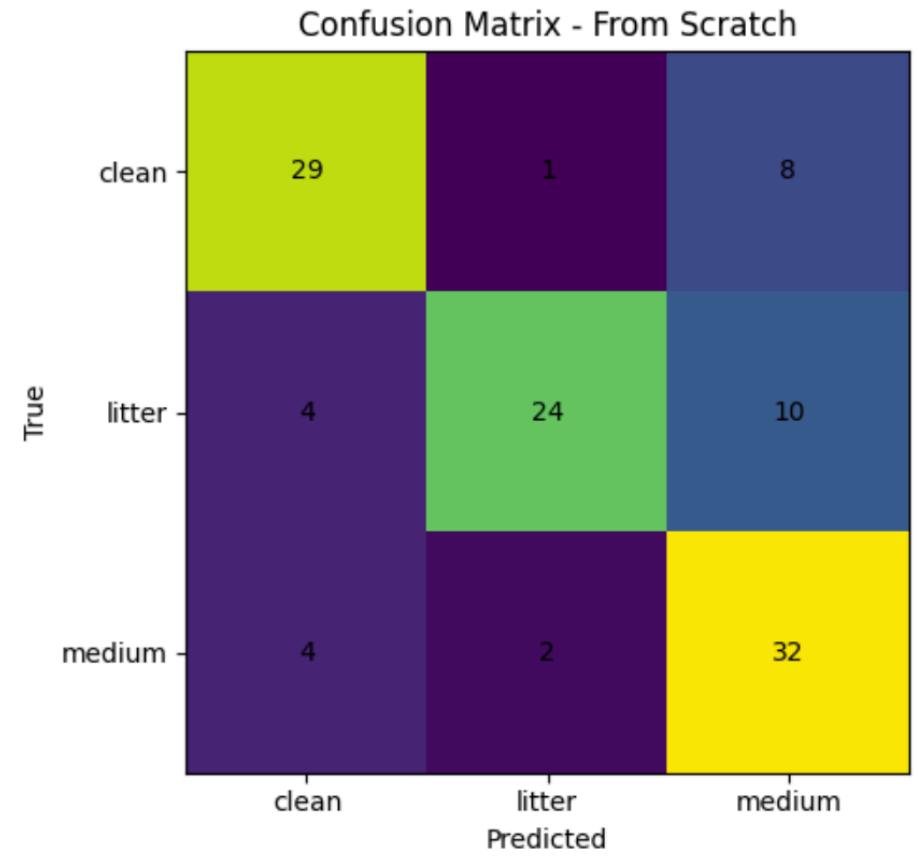
- Grad-CAM used to visualize spatial attention
- Enables analysis of decision behavior and boundary ambiguity

# RESULT

## confusion matrix



Pretrained:  
Stronger diagonal consistency;  
reduced confusion and  
improved class discrimination.



From Scratch:  
Higher confusion across classes, weaker  
boundary separation.

# Metric Comparision

## Pretrained ResNet-18

### Class-wise Performance

Class	Precision	Recall	F1-Score	Support
Clean	0.921	0.921	<b>0.921</b>	38
Litter	0.941	0.842	<b>0.889</b>	38
Medium	0.81	0.895	<b>0.85</b>	38

### Overall Performance

Metric	Value
Accuracy	<b>0.886</b>
Macro Precision	0.891
Macro Recall	0.886
Macro F1-score	<b>0.887</b>

## From-Scratch ResNet-18

### Class-wise Performance

Class	Precisio	Recall	F1-	Support
Clean	0.78	0.76	<b>0.77</b>	38
Litter	0.89	0.63	<b>0.74</b>	38
Medium	0.64	0.84	<b>0.73</b>	38

### Overall Performance

Metric	Value
Accuracy	<b>0.75</b>
Macro Precision	0.77
Macro Recall	0.75
Macro F1-score	<b>0.75</b>

Model	Accuracy	Macro F1
<b>ResNet-18 (Pretrained)</b>	<b>0.886</b>	<b>0.887</b>
ResNet-18 (From Scratch)	0.75	0.75

# Interpretation(Grad-CAM)

It answer: What is the model looking at when making decisions?

Litter-predicted as Litter



Litter-predicted as Medium



Medium-predicted as Litter



Clean-predicted as Medium



## Related work

Residual Networks (He et al., 2016) significantly improved image classification through deep residual learning. Transfer learning from ImageNet has become standard practice for small datasets. However, few urban cleanliness studies evaluate interpretability alongside performance. We address this gap using Grad-CAM analysis.

He, K., Zhang, X., Ren, S., & Sun, J. (2016). Deep Residual Learning for Image Recognition. CVPR.

Selvaraju et al. (2017). Grad-CAM: Visual Explanations from Deep Networks. ICCV.