

Cycle-GAN

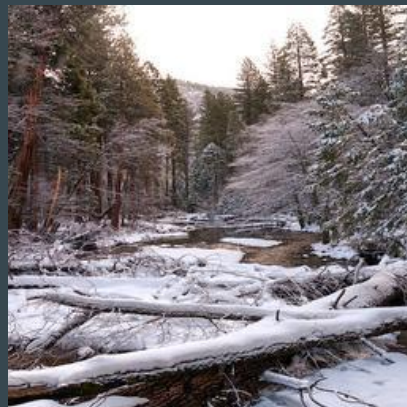


github.com/gvsakashb/cyc-gan

Akash

Contents

- Re-implementation
- Changes and tweaks
- Metrics and output
- Status update
- Deliverables



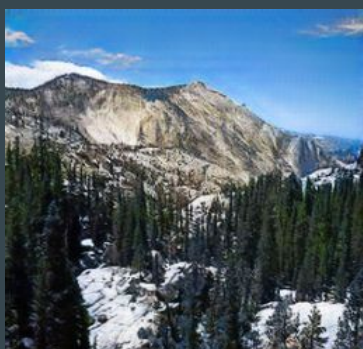
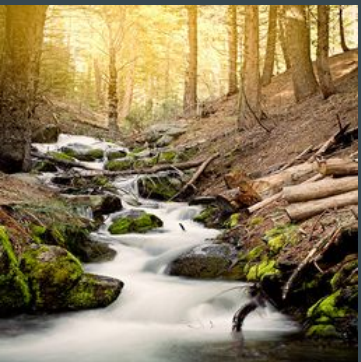
Re-implementation & extensibility

1. Achieved images comparable to best results and reconstructions.
 - a. Improvements in *horse2zebra* and *yosemite* images generated after changes in util, options directory for helper files.
 - i. Reconstruction errors and results have also been generated for the report.
2. Comparison of various models (parameter tuning) and the images,
 - a. Best metrics for content_loss, --netG, normalization, etc. have been illustrated.
3. Tabulated the losses for D, G and developed new models with resized convolutions.
 - a. Initial changes to train_options.py file and data directory's codebase.
 - b. A separate implementation from scratch, mainly to assess and study the architecture..

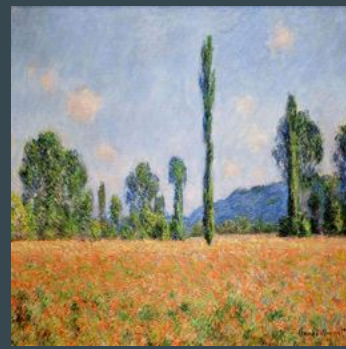


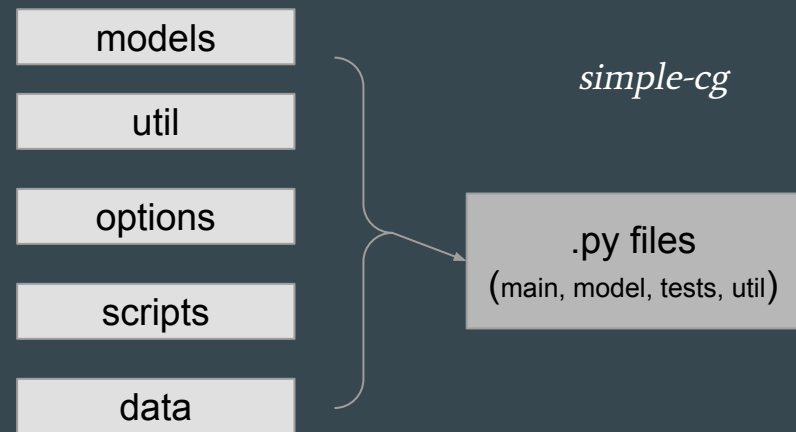
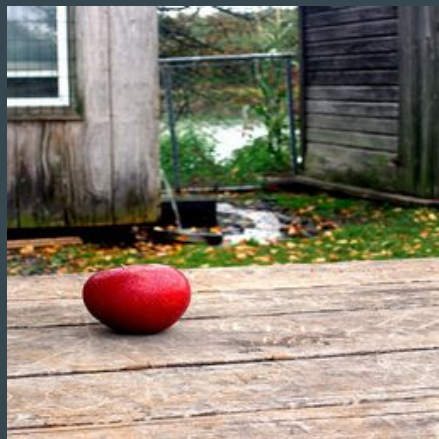
Best results

Monet2Photo

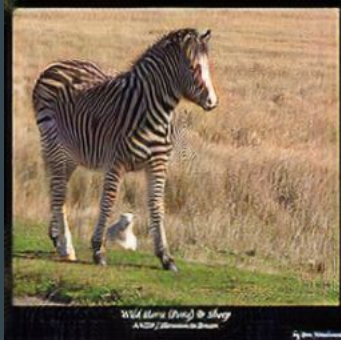


Summer2Winter_Yosemite





Tweaks



- The original repo has been explored by modifying various parameters in each iteration of the datasets.
- A new directory ([simple-cg](#)) has been developed with trained models and submitted.
- Improvements observed include clarity, dehazing and reducing noise.
- Developed a separate model to log and save the adversarial losses and the analysis for various runs changing the lr-policy & --netG parameters.

Metrics

$$Identity\ loss\ (optional): \lambda (|G_A(B) - B| + \lambda_B B + |G_B(A) - A|)$$

Also, in contrast to the basic model (70x70 PatchGAN), we usually tune `n_layers` in the discriminator for in the options directory.

- Here, we eliminate that compelxity by just modifying the code in `model.py` and `trainpy` accordingly for our models as needed.
-

```
In [10]: !python main.py --training True --norm 'batch'

Epoch: ( 49) ( 22/ 30) | Generator Loss:6.125e+00 | Discriminator Loss:3.31e-01
Epoch: ( 49) ( 23/ 30) | Generator Loss:6.91e+00 | Discriminator Loss:6.18e-01
Epoch: ( 49) ( 24/ 30) | Generator Loss:6.31e+00 | Discriminator Loss:5.11e-01
Epoch: ( 49) ( 25/ 30) | Generator Loss:5.88e+00 | Discriminator Loss:4.32e-01
Epoch: ( 49) ( 26/ 30) | Generator Loss:5.56e+00 | Discriminator Loss:3.21e-01
Epoch: ( 49) ( 27/ 30) | Generator Loss:5.43e+00 | Discriminator Loss:3.29e-01
Epoch: ( 49) ( 28/ 30) | Generator Loss:8.67e+00 | Discriminator Loss:2.70e-01
Epoch: ( 49) ( 29/ 30) | Generator Loss:9.99e+00 | Discriminator Loss:4.74e-01
Epoch: ( 49) ( 30/ 30) | Generator Loss:5.23e+00 | Discriminator Loss:4.88e-01
Epoch: ( 49) ( 30/ 30) | Generator Loss:7.73e+00 | Discriminator Loss:3.01e-01
learning rate = 0.0005000
Epoch: ( 50) ( 1/ 30) | Generator Loss:7.01e+00 | Discriminator Loss:4.59e-01
Epoch: ( 50) ( 2/ 30) | Generator Loss:6.48e+00 | Discriminator Loss:5.37e-01
Epoch: ( 50) ( 3/ 30) | Generator Loss:6.30e+00 | Discriminator Loss:4.42e-01
Epoch: ( 50) ( 4/ 30) | Generator Loss:6.05e+00 | Discriminator Loss:3.03e-01
Epoch: ( 50) ( 5/ 30) | Generator Loss:5.92e+00 | Discriminator Loss:1.36e-01
Epoch: ( 50) ( 6/ 30) | Generator Loss:5.48e+00 | Discriminator Loss:2.33e-01
Epoch: ( 50) ( 7/ 30) | Generator Loss:6.35e+00 | Discriminator Loss:2.95e-01
Epoch: ( 50) ( 8/ 30) | Generator Loss:6.93e+00 | Discriminator Loss:4.42e-01
Epoch: ( 50) ( 9/ 30) | Generator Loss:5.64e+00 | Discriminator Loss:4.63e-01
```

<u>Task</u>	<u>dataset</u>	<u>metric</u>	<u>value</u>
Img-to-img translation	<i>ukiyo</i> e	Class IoU score	0.1012
Img-to-img translation	<i>monet-photo</i>	Quality	0.408
Img-to-img translation	<i>horse-zebra</i>	Per-pixel accuracy /ablation study score	0.52
Img-to-img translation	<i>horse-zebra</i>	Per-class accuracy	0.17





Re-implementation results ^

From newer
implementation:



Reconstruction (results)

Status :

1. Successful implementations and models for h2z, monet, ukiyoe and seasonal datasets have been done.
2. A simpler version of cycle-gan model, with easier access to parameter tuning has been developed and trained.
 - a. Two approaches with better latency, to compare batch vs instance norm.
3. Comparative analysis of loss of G & D against each epoch in training has been tabulated.
4. Improved latency with changes to train & model.py files.

Issues:

- Setup and latency of the nvidia-docker image for the official docker file, resorted to AWS and then deploying to Docker.
- Object transfiguration and some errors in hue and tint of images (especially Ukiyo-e)

Deliverables:

- Repository with both versions
 - Re-implementation & simple-cg directories
 - Trained notebooks and code
 - Deep Learning AMI
 - Ready to deploy / trained models for each dataset (h2z, monet, seasonal & art styles)
 - Simple-cg implementation and tabulated metrics(losses)
 - Access key for AMI and readme for opening the EC2 instance
 - Final report & documentation, results
-
- *Additional: Working on scaling AMI upon Docker image* (with accompanying file)*