

Govind Chari

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EDUCATION

UNIV. OF WASHINGTON

PHD IN CONTROLS
Advisor: Behçet Açıkmese
May 2026 | Seattle, WA

CORNELL UNIV.

BS IN MECH
GPA: 4.18 (1/103)
May 2022 | Ithaca, NY

LINKS

LinkedIn:// [govindchari](#)
Github:// [govindchari](#)
Website:// [govindchari.com](#)

COURSEWORK

Convex Optimization
Machine Learning
Reinforcement Learning
Stochastic Controls
Feedback Controls
Nonlinear Controls
Linear Systems
Model-Based Estimation
Numeric Methods
Advanced Astrodynamics
Spaceflight Mechanics

SKILLS

SOFTWARE

C++ • Julia • Python
Matlab • ANSYS •
Solidworks (CSWA Cert)
HSMWorks

HOBBIES

Tennis • Badminton
Stargazing • Hiking
Weightlifting

EXPERIENCE

X, THE MOONSHOT FACTORY | SOFTWARE ENGINEERING INTERN

June 2023 - Sept 2023 | Seattle, WA

- Accepted 12 week internship for the summer of 2023 working on motion-planning and controls for robotics

UNIV. OF WASHINGTON | RESEARCH ASSISTANT

Sept 2022 - Present | Seattle, WA

- Writing high-speed conic optimizer for real-time quadrotor path-planning
- Researching novel first-order optimization algorithms

SPACEX | ASSOCIATE GNC ENGINEER

Jun 2022 - Aug 2022 | Hawthorne, CA

- Ran Monte-Carlo simulations and analysis to assess the impact of altering thruster configuration on Dragon's entry performance
- Prototyped new thrust allocation scheme
- Added state machine branch for debris avoidance maneuvers
- Built verification tool to ensure positive propellant margin in all two fault propulsion cases

SPACEX | PROPULSION ANALYSIS INTERN

Jun 2021 - Aug 2021 | Hawthorne, CA

- Performed nonlinear structural and thermal analysis of Raptor and Merlin engines components using ANSYS and documented results for the responsible engineers

CORNELL SPACE SYSTEMS DESIGN STUDIO | GNC ENGINEER

April 2021 - May 2022 | Ithaca, NY

- Worked on the development of a high fidelity 6DOF simulation for [PAN](#)
- Tuned orbital rendezvous controller and worked on flight software implementation
- Conducted HITL and HOOTL tests to verify performance of orbital rendezvous controller and propulsion system
- Ran simulations to determine if deployment dispersions met our satellite's delta-v budget

PERSONAL PROJECTS

CONVEX SOLVERS | JAN 2022

- Wrote a primal-dual interior point solver for convex quadratic programs in C++ based on Mehrotra's predictor-corrector
- Wrote an Augmented Lagrangian solver for convex quadratic programs in Julia
- Wrote unit tests, set up CI pipeline, and code coverage using Github Actions

G-FOLD IMPLEMENTATION | MARCH 2021-JUNE 2021

- Recreated Acikemese and Blackmore's powered descent algorithm
- Utilized lossless convexification and modified problem to help with feasibility
- Coded algorithm and a 6DOF simulation in C++ to verify robustness to disturbances
- Conducted Monte-Carlo trials to determine landing ellipse of the algorithm

VERTICAL TAKEOFF AND LANDING VEHICLE | APRIL 2020-AUGUST 2020

- Built and coded a vertical takeoff and landing vehicle powered by racing drone motors which utilizes servo driven thrust vectoring fins for attitude control
- Wrote GNC code from scratch using C++ including a Kalman Filter to fuse altimeter and accelerometer readings which reduced variance in altitude readings by 44%
- Designed and printed thrust test stand to accurately model the nonlinear thrust curve of racing drone motors and to measure the effectiveness of the thrust vectoring fins
- Conducted isolated unit tests to validate efficacy of the roll controller