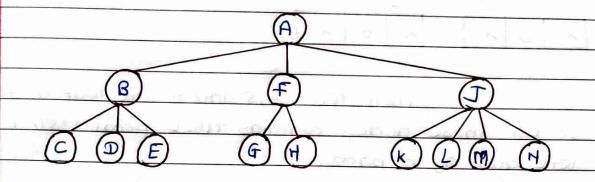


Types of Tree data structure: General Type: - In a general troe, a node can have either o or maximum n number of nades. more is no restrictions imposed on the degree of node (number of nodes that a node can contain) The topmost node in a general tree is known as root hode. The children of parent node are known

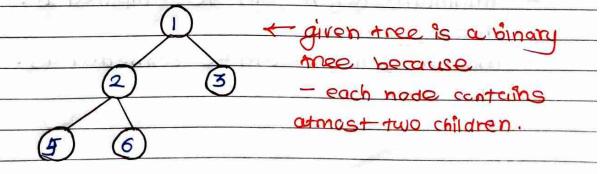


as subtrop.

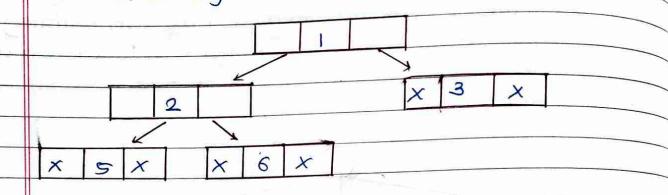
There can be a number of subtrees in general tree. In general trees subtrees are unordered as nodes in subtree cannot be ordered.

Every non-empty tree has a downward edge, and these edges are connected to nodes known as child nodes. The nodes that have some parent are known

2). Binary Tree :- Binary tree means that the node can have marihum two children.



In above thee, node I contains two pointers in above thee node I contains two pointers in left and right pointer pointing to left and right node respectively.



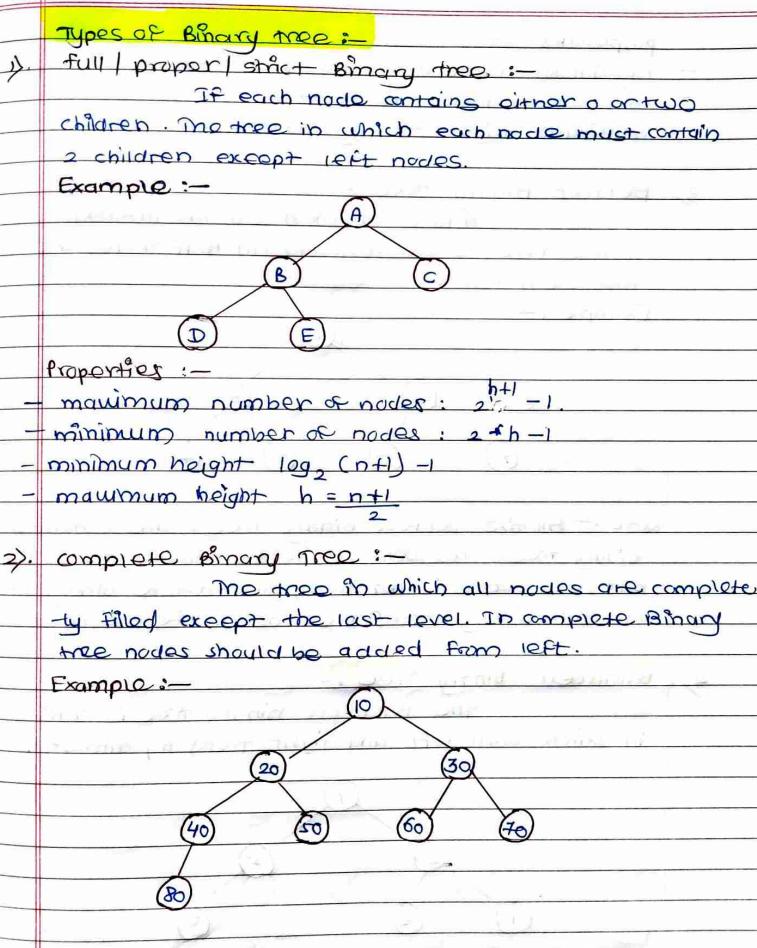
menodes 3,5 and 6 are leaf nodes, so all these nodes contains NULL pointer on both left and right parts.

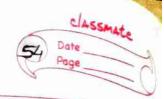
Properties of Binary tree :-

- At each level of is the manumum number of nodes is 2.
- The height of tree is longest puth from rout node to leaf node. In general, maximum number of nodes possible at height is (2°+21+2²+...2")

  The minimum number of nodes possible at heighth
  - is equal to hel.
  - If number of nodes is minimum, then height of thee would be maximum.
- minimum height can be amputed as:

  h = leg\_(n+1)-1
- modiming height can be computed as:



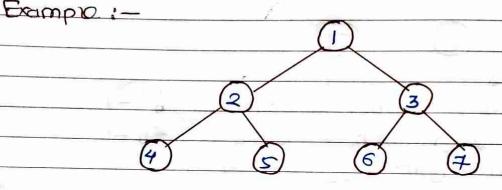


properties:

model  $\Rightarrow 2^{h+1}-1$ .

minimum number of nodes  $\Rightarrow 2^{h}$ minimum number of nodes  $\Rightarrow 2^{h}$ minimum number of nodes  $\Rightarrow 2^{h}$ minimum neight  $\Rightarrow \log_{2}(n+1)-1$ .

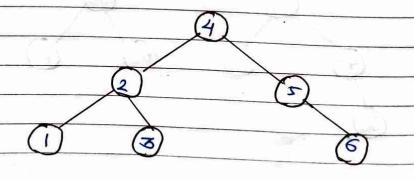
Atree in which all the internal nades have 2 children, and all heaf nodes are at the same level.



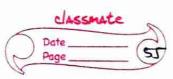
both in All the perfect Binary troos are amplete both any trees as well as the full Binary trees as But, vice versa is not true, all complete binary trees and full binary trees are the perfect Binary trees

Balanced Bingry Tree:

The balanced binary tree is a tree
in which both left and right trees by almost.



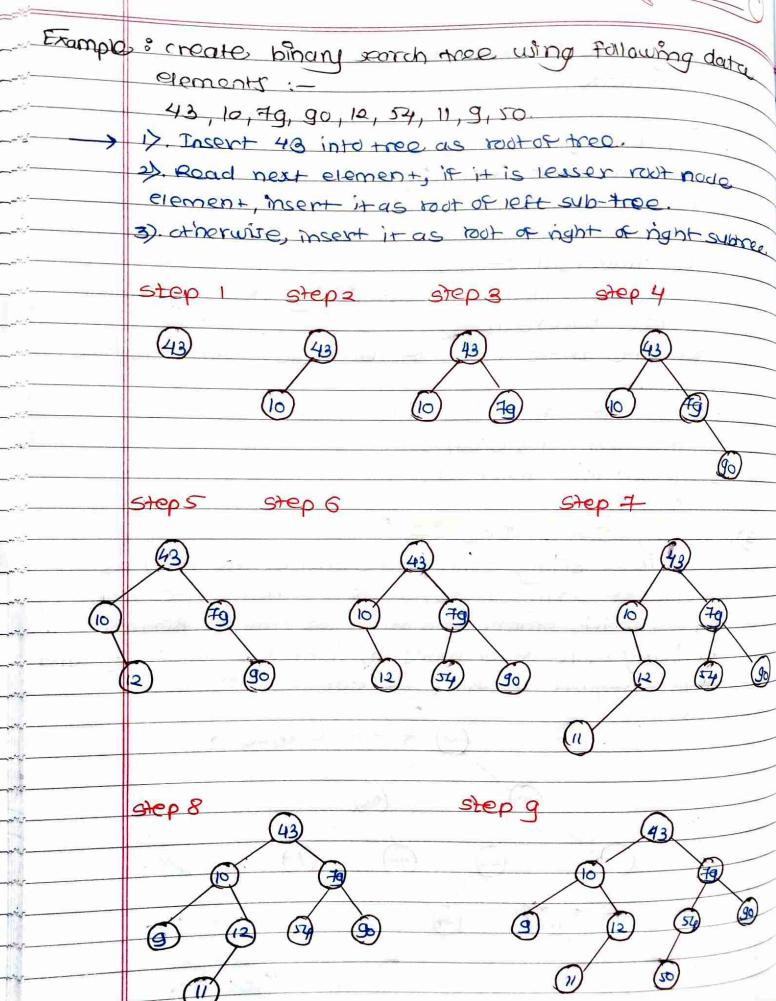
above tree is balance: diff bet left subtree frights. I is accomp

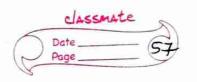


|     | Binary Tree implementation:  |
|-----|--|
|     | struct hode  |
|     |  |
|     | int data;  |
|     | struct node "loft, "right 5  |
|     | 3  |
|     | All a the first of |
|     | Tree Traversal:  |
|     | me process of visiting nodes is called   |
|     | as tree traversal.   |
|     | mere are three types of traversus used to visit a  |
|     | nade:  |
|     | 1). Incider Traversal  |
|     | 2) proorder Travetsal  |
|     | 3) postorder Traversal.  |
|     |  |
| 3>. | Binary Search Tree :-  |
|     | defin: - Binary search tree can be defined as  |
|     | a class of binary trees, in which a nodes are atranged   |
|     | in a specific order. also called as ordered BinaryTreo.  |
| _   | smilarly value or all nodes in right subtree is greater  |
| 1   | than or equal to value of 700t.  |
|     | (30) - Root node.  |
|     | (30) Thoot node.   |
|     |  |
|     | (60)   |
|     |  |
|     | (45) (75)  |
| Ť   |  |
|     | (i <sup>4</sup> ) (2 <sup>4</sup> )  |
|     |  |

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cs)





| operations | on Binani | Sourch | mee | (RST) | <u>}</u> |
|------------|-----------|--------|-----|-------|----------|
| - P        | - 119     |        |     |       |          |

|   | and the professional commence to the control of the |                        |                                   |  |
|---|--|------------------------|-----------------------------------|--|
|   | ex.Ho.   | Operation              | Description                       |  |
|   | 1>.  | searching in           | finding location of some specific |  |
|   | /  | BST                    | element in a Binary secirch Mee.  |  |
|   | 2).  | Insertion in           | Adding a new element to the       |  |
|   | /  | BST                    | binary search tree at appropria   |  |
|   | 4ab j  | (*)                    | BST do not violate.               |  |
|   | 3).  | Peletion in            | Deleting some specific nucle      |  |
|   |  | BST.                   | from a BST, However, tree         |  |
| 1 |  | and a                  | there can be various cases in     |  |
|   |  | A Secretary Laboratory | or children, node have.           |  |
|   |  |                        |                                   |  |

4). ALL Tree :- AVL Thee is invented by GM Adelson
-velsky and FM Landis in 1962. The tree is
named as AVL in honour of its inventors.

All tree is dofined as height balanced binary search tree in which each node is associated with a balance factor which is calculated by subtracting the neight of its R. subtraction its left subtree.

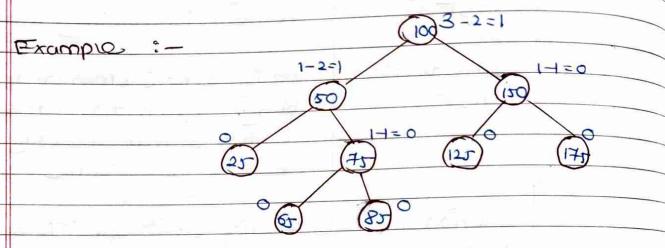
Balance factor (K) = height (left (K)) - height (right (K))

If balance factor of any node is 1, it means that left sub-tree is one level higher than right subtree.



If balance factor of any node is 0, it means that left sub-tree and right sub-tree contain equal height.

IF bulance factor of any node is I, it means that left sub-tree is one level lower than right subtree



Here we see that, balance factor associated with each node is between -1 and +1.

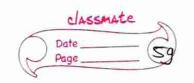
-: It is an example of AVL treo.

comprosity:-

| Algoirthm | Average rase | Worst case |
|-----------|--------------|------------|
| space     | o(n)         | O(n)       |
| search    | 0(log n)     | o(log n)   |
| msert     | 0(10gn)      | 0(10g n)   |
| Delete    | 0 (log n)    | o (log n). |

why AVL Tree P -> AVL tree controls height of binary search tree by not letting it to be skelled me time taken by all operations in BST is o(h).

However it will be extended to O(n) If BST became



skewed (worst case). By limiting this height to log in, AVL tree imposes an upper bound on each operation to be o(logn), where n is number of nodes.

Operations on AVL , ee:-

| ST. NO | operation   | Description.                             |
|--------|---|--|
|        | A STATE OF STREET   | 1 (1 (1 (1 (1 (1 (1 (1 (1 (1 (1 (1 (1 (1 |
| ١٧.    | Insertion   | Insertion is performed in                |
| 7      |   | some way it performed                    |
|        | Salt care a substitute of   | in BST. However, it may                  |
|        | cie no o massino de   | lead to violation in the                 |
| J-C-04 | no also gove na sull  | AVI tree property and                    |
|        | ACT ACT FA  | so tree may need                         |
|        |   | balancing and tree can                   |
|        | the section of the section of   | be balanced by rotation.                 |
| 2).    | pelestion   | polotion is also same                    |
| 7.     | t to the contract of the contr  | uly performed as BST                     |
|        |   | Itan be also disturb                     |
|        | - 1 - 1 - 1 - 1 - 4 - <del>1</del> | balance of theo, so                      |
|        |   | various types of rotations               |
|        | 1 + 0   | are used to rebulance                    |
|        |   | tree.                                    |

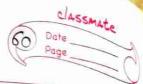
AVL Rotations:

We perform rotations in AVI tree only in case if

Balance factor is other than -1, 0 and 1.

There are Basically four types of rotations which

are as follows:



1). L-1 rotation: - Inserted node is in the left e). R-R rotation: - Inserted node is in the night subtree or right subtree of A. 3). 1-R rotation: - Inserted rade is in right submed or left submed of A. 4). R-L Potentian: - Inserted node is in the left subtree of right subtree of A. 5). B Tree :- B Free is specialized m-way thee that can be widely used for disk quest. A B-tree of order m can have at most m-1 keys and m children. Proporties:-1. Every node in B-Tree contains at most m children 2. Every node in B-Tree except rout node and leaf node contain at least m/2 children. 3. The root nodes must have at least anodes. 4. All leaf nodes must be at the same level. Example: 32 98 90

| 0 | perations | 5- |
|---|-----------|----|
| _ |           |    |

searching :- The Searching in Btree is similar to searching in Binary tree. For example, we search for an item 4g in following B Tree. The process will be:

D. compute item 4g with root node 78. sinco 49×78 hence, more its left sub-tree.

- @ since, 40<49<56, traverse right subtree of 40.
- 3. 49 >45, more to right compare 49.
- (4) match found, return.

searching in B tree depends upon height of the tree. The sourch algunithm takes octagn) time to search any element in B tree.

- Inserting: Insertion are done at leaf node level.
  The following algorithm needs to be followed in
  order to insert an item into B tree.
- (). Traverse B tree in order to find appropriate.

  leaf node at which node can be inserted.
- 2). If leaf node centains less than m-1 keys then ment element in increasing order.
- 3. FISE, if leaf node contains my keys, then following steps:
  - Insert new element in increasing order of
  - split node into two nodes at median.
  - Push median element up to its parent node.
- If parent node also contain m-1 number of keys, then split it too by steps.

## Application of B tree:-

B tree is used to inder data and provides fast access to actual data stored on disks since, the

stored on a disk is a very time consuming process.

containing n key values needs o(n) running time.

6). B + Tree !-

efficient insertion, deletion and search operations.

The leaf nodes of B+ tree are 19nked together in form of the singly linked list tomake search queries more efficient:

Advantages of B+ thee :-

y. Records can be fetched in equal number of disk accesses.

2) Height of thee remains bullanced and less as compute to 8 thee

3) we can access duter Stored in B+ thee sequentially as well as directly.

4) keys are used for indering.

Graph :-

A graph can be defined as group of vertices and edges that are used to connect these vertices.

Defination:

set G(V, E) where VCG) represents set of edges.