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Gaussian Mixture model: Bag of words representation

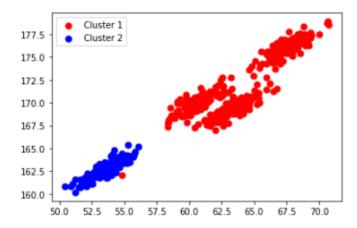
A Gaussian mixture model is a probabilistic model that assumes all the data points are generated from a mixture of a finite number of Gaussian distributions with unknown parameters. It attempts to find a mixture of multi-dimensional Gaussian probability distributions that best model any input dataset allowing the model to learn automatically, i.e. in an unsupervised manner. The bag-of-words model is a way of representing text data when modelling text with machine learning algorithms which can be combined with GMM to get a useful model representation.

Implementation: Bag of words representation

```
import pandas as pd
import numpy as np
import matplotlib.pyplot as plt
import seaborn as sns
from sklearn.mixture import GaussianMixture
from sklearn.cluster import KMeans
 data = pd.read_csv('Clustering_gmm.csv')
data.head()
           Weight
                                Height
  0 67.062924 176.086355
     68.804094 178.388669
60.930863 170.284496
       59.733843 168.691992
  4 65.431230 173.763679
Error =[]
for i in range(1, 11):
    kmeans = KMeans(n_clusters = i).fit(data)
    kmeans.fit(data)
    Error.append(kmeans.inertia_)
import matplotlib.pyplot as plt
plt.plot(range(1, 11), Error)
plt.title('Elbow method')
plt.xlabel('No of clusters')
plt.ylabel('Error')
plt.show()
                                                Elbow method
     25000
     20000
     15000
     10000
       5000
            0
                                                                                8
                                                                                                 10
                                                  No of clusters
gm = GaussianMixture(n_components=2, random_state=0).fit(data)
gm.means
array([[ 63.77281821, 171.71722858],
              [ 53.57474006, 162.74626605]])
y = gm.predict(data)
```

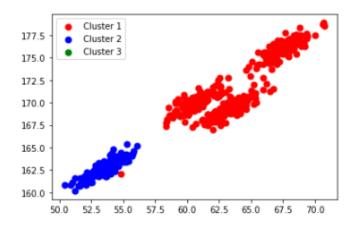
```
x = np.array(data)
plt.scatter(x[y== 0, 0], x[y == 0, 1], s = 50, c = 'red', label = 'Cluster 1')
plt.scatter(x[y == 1, 0], x[y == 1, 1], s = 50, c = 'blue', label = 'Cluster 2')
plt.legend()
```

<matplotlib.legend.Legend at 0x235c6ce3c70>



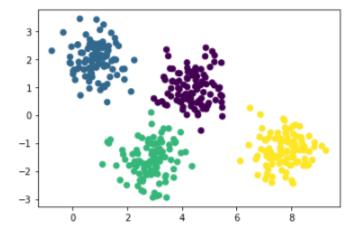
```
gm = GaussianMixture(n_components=2, random_state=0).fit(data)
y1 = gm.predict(data)
x = np.array(data)
plt.scatter(x[y1== 0, 0], x[y1 == 0, 1], s = 50, c = 'red', label = 'Cluster 1')
plt.scatter(x[y1 == 1, 0], x[y1 == 1, 1], s = 50, c = 'blue', label = 'Cluster 2')
plt.scatter(x[y1 == 2, 0], x[y1 == 2, 1], s = 50, c = 'green', label = 'Cluster 3')
plt.legend()
```

<matplotlib.legend.Legend at 0x235c6cf1e20>



: from sklearn.datasets import make_blobs

```
plt.scatter(X[:, 0], X[:, 1], c=y_true, s=40, cmap='viridis')
plt.show()
```



```
from sklearn.mixture import GaussianMixture as GMM
gmm = GMM(n_components=4).fit(X)
labels = gmm.predict(X)
plt.scatter(X[:, 0], X[:, 1], c=labels, s=40, cmap='viridis')
plt.show()
```

