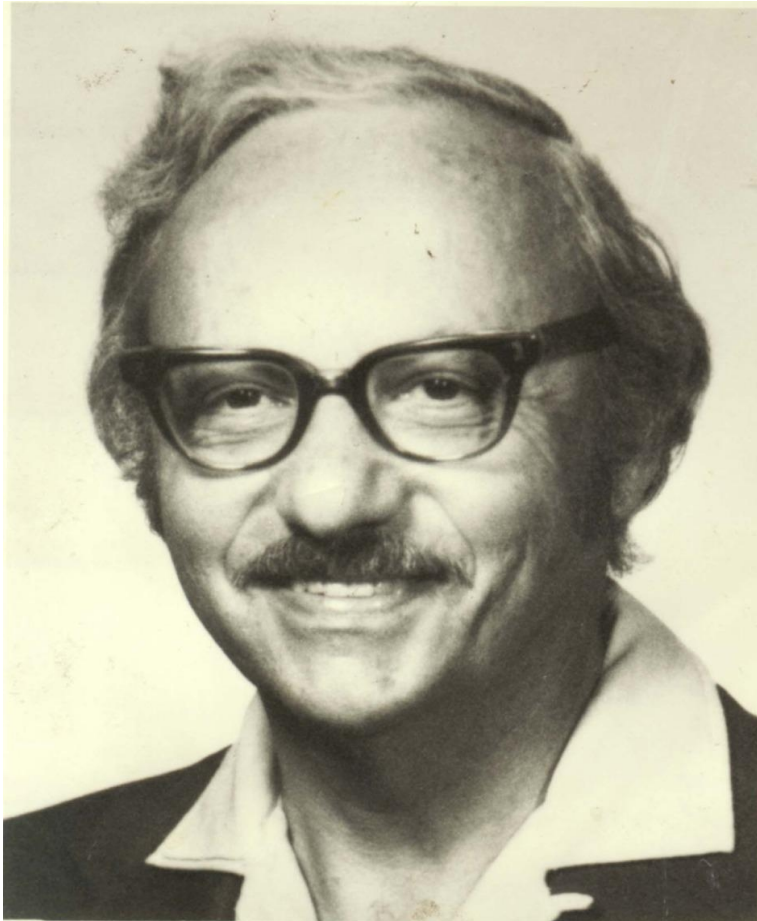


MDI210 : Linear Programming

Robert M. Gower

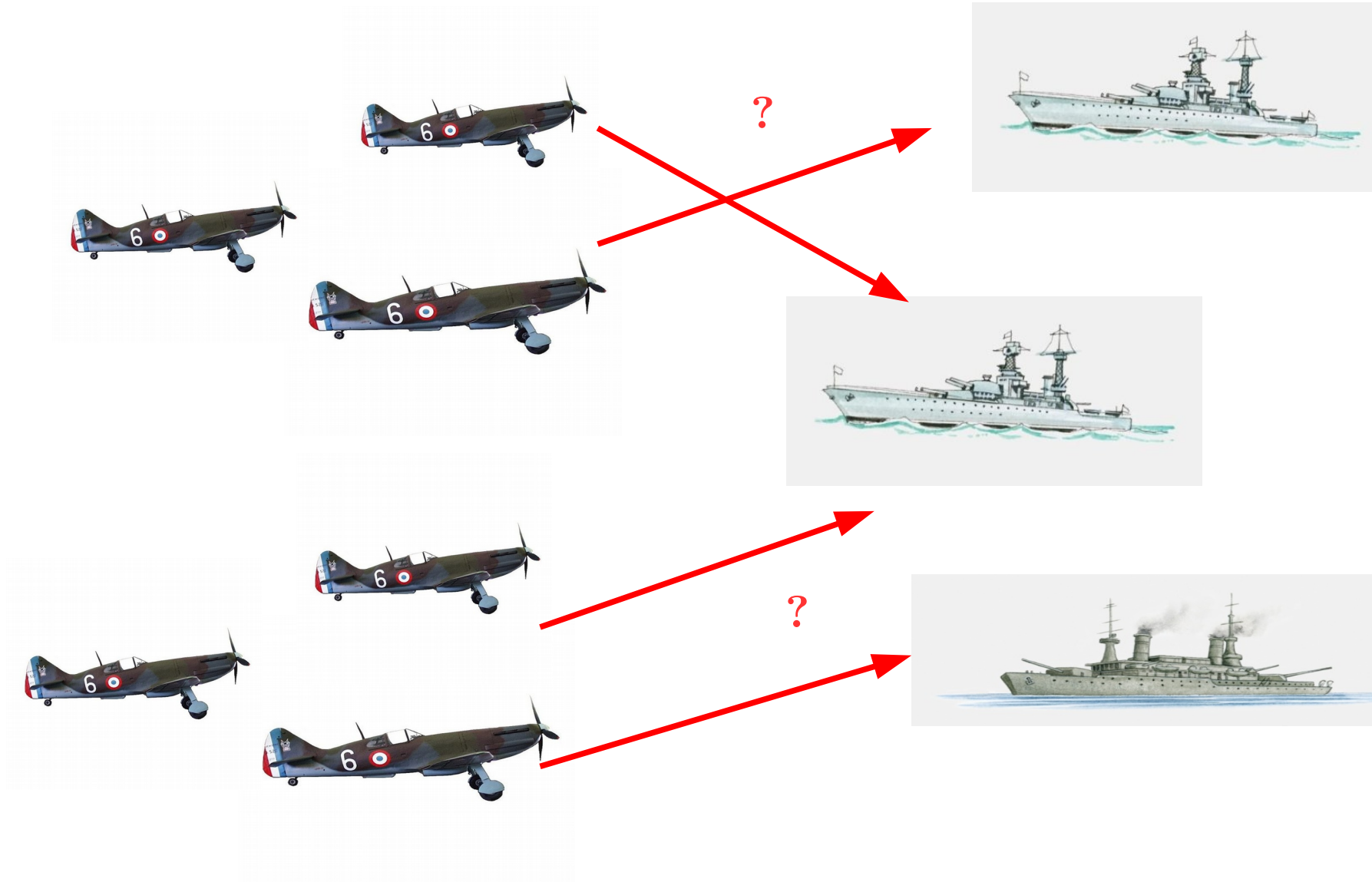


Linear Programming History (1939)

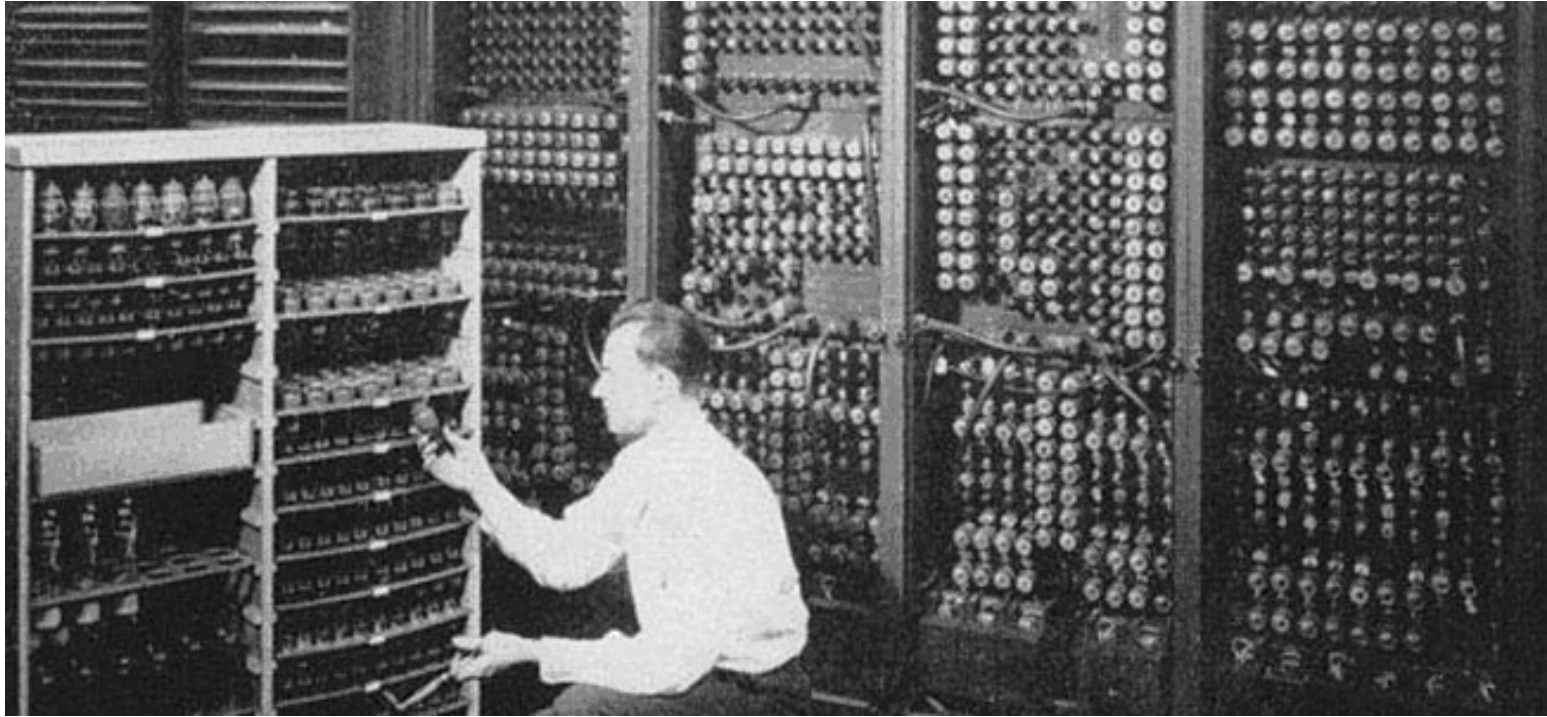


- 1947: George Dantzig, advising U.S. Air Force, invents Simplex.
- Assignment 70 people to 70 jobs (more possibilities than particles).

Linear Programming History (1941)



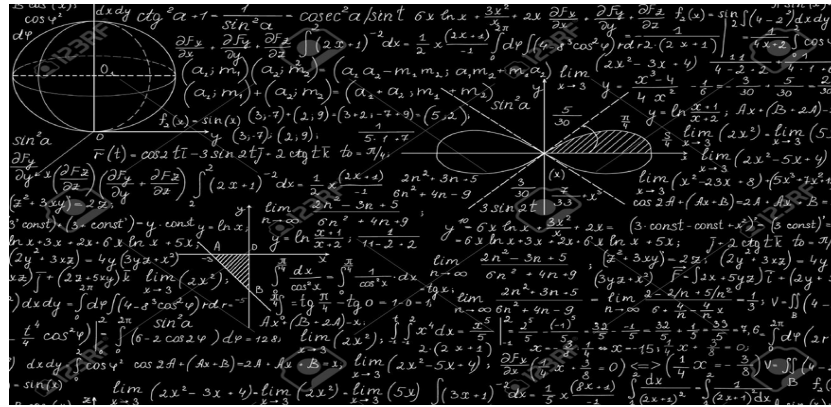
Army Builds Killing Machine (1949)



1949 SCOOP: Scientific Computation Of Optimal Programs

Mathematical Programming: Math used to figure out Flight and logistic programs/schedules

Dantzig the Urban Legend



Dantzig, George B. "On the Non-Existence of Tests of 'Student's' Hypothesis Having Power Functions Independent of Sigma." *Annals of Mathematical Statistics*. No. 11; 1940 (pp. 186-192).

Dantzig, George B. and Abraham Wald. "On the Fundamental Lemma of Neyman and Pearson." *Annals of Mathematical Statistics*. No. 22; 1951 (pp. 87-93).

Optimization and Numerical Analysis: Linear Programming

Robert Gower



September 17, 2019

Table of Contents

Simple 2D problem

The Fundamental Theorem

Notation

Simplex Algorithm

- Degeneracy

- Finding an initial feasible dictionary

Duality

The Problem: Linear Programming

$$\begin{aligned} \max_x z &\stackrel{\text{def}}{=} c^\top x \\ \text{subject to } Ax &\leq b, \\ x &\geq 0, \end{aligned}$$

where $c, x \in \mathbb{R}^n$, $A \in \mathbb{R}^{m \times n}$, and $b \in \mathbb{R}^m$. Equivalently

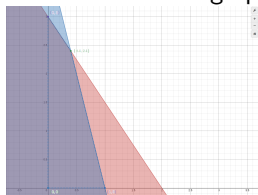
$$\begin{aligned} \max_x z &\stackrel{\text{def}}{=} \sum_{j=1}^n c_j x_j \\ \text{subject to } \sum_{j=1}^n a_{ij} x_j &\leq b_i, \quad \text{for } i = 1, \dots, m. \\ x &\geq 0. \end{aligned}$$

First example Simplex

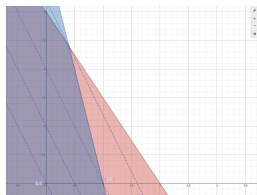
The problem

$$\begin{aligned} \max \quad & 4x_1 + 2x_2 \\ & 3x_1 + 2x_2 \leq 600 \\ & 4x_1 + 1x_2 \leq 400 \\ & x_1 \geq 0, x_2 \geq 0. \end{aligned}$$

We can solve this graphically:



With level sets \Rightarrow



How to do this systematically?

First example Simplex

The problem

$$\begin{aligned}
 \max \quad & 4x_1 + 2x_2 \\
 & 3x_1 + 2x_2 \leq 600 \\
 & 4x_1 + 1x_2 \leq 400 \\
 & x_1 \geq 0, x_2 \geq 0.
 \end{aligned}$$

Can be transformed into

$$\begin{aligned}
 \max \quad & 4x_1 + 2x_2 \\
 x_3 = 600 \quad & - 3x_1 - 2x_2 \\
 x_4 = 400 \quad & - 4x_1 - x_2,
 \end{aligned}$$

where x_3 and x_4 are *slack variables*. This is known as the *dictionary* format and is often written as:

$$\begin{array}{rclcl}
 x_3 & = & 600 & - & 3x_1 & - & 2x_2 \\
 x_4 & = & 400 & - & 4x_1 & - & x_2 \\
 \hline
 z & = & & & 4x_1 & + & 2x_2
 \end{array}$$

First example Simplex

The *dictionary* format

$$\begin{array}{rclclcl} x_3 & = & 600 & - & 3x_1 & - & 2x_2 \\ x_4 & = & 400 & - & 4x_1 & - & x_2 \\ \hline z & = & & & 4x_1 & + & 2x_2 \end{array}$$

admits obvious solution

$$(x_1^*, x_2^*, x_3^*, x_4^*) = (0, 0, 600, 400).$$

The objective z will improve if $x_1 > 0$. Increasing x_1 as much as possible

$$x_3 \geq 0 \Rightarrow 600 - 3x_1 \geq 0 \Rightarrow x_1 \leq 200,$$

$$x_4 \geq 0 \Rightarrow 400 - 4x_1 \geq 0 \Rightarrow x_1 \leq 100.$$

Thus $x_1 \leq 100$ to guarantee $x_4 \geq 0$. This means x_4 will **leave the basis** and x_1 will **enter the basis**. Using row operations $r_3 \leftarrow r_3 + r_2$ and $r_1 \leftarrow r_1 - \frac{3}{4}r_2$ to isolate x_1 on row2.

$$\begin{array}{rclclcl} x_3 & = & 300 & + & \frac{3}{4}x_4 & - & \frac{5}{4}x_2 \\ x_1 & = & 100 & - & \frac{x_4}{4} & - & \frac{x_2}{4} \\ \hline z & = & 400 & - & x_4 & + & x_2 \end{array}$$

First example Simplex

From

$$\begin{array}{rclclcl}
 x_3 & = & 300 & + & \frac{3}{4}x_4 & - & \frac{5}{4}x_2 \\
 x_1 & = & 100 & - & \frac{x_4}{4} & - & \frac{x_2}{4} \\
 \hline
 z & = & 400 & - & x_4 & + & x_2
 \end{array}$$

Now we are at the vertex $(x_1^*, x_2^*) = (100, 0)$. Next we see that increasing x_2 increases the objective value but

$$\begin{aligned}
 x_3 \geq 0 &\Rightarrow 300 - \frac{5}{4}x_2 \geq 0 \Rightarrow 240 \geq x_2, \\
 x_1 \geq 0 &\Rightarrow 100 - \frac{x_2}{4} \geq 0 \Rightarrow 400 \geq x_2.
 \end{aligned}$$

Increase x_2 upto 240 while respecting the positivity constraints of x_3 . Thus x_3 will *leave* the basis and x_2 will *enter* the basis. Performing a row elimination again via $r_3 \leftarrow r_3 + \frac{4}{5}r_1$ and $r_2 \leftarrow r_2 - \frac{1}{5}r_1$, we have that

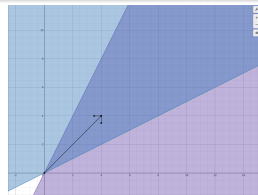
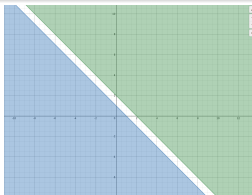
$$\begin{array}{rclclcl}
 x_2 & = & 240 & + & \frac{3}{5}x_4 & - & \frac{4}{5}x_3 \\
 x_1 & = & 40 & - & \frac{2}{5}x_4 & - & \frac{1}{5}x_3 \\
 \hline
 z & = & 640 & - & \frac{2}{5}x_4 & - & \frac{4}{5}x_3
 \end{array}$$

Now $(x_1^*, x_2^*) = (40, 240)$. Increasing x_4 or x_3 will decrease z . THE END

Theorem (Fundamental Theorem of Linear Programming)

Let $P = \{x \mid Ax = b, x \geq 0\}$ then either

- ① $P = \{\emptyset\}$
- ② $P \neq \{\emptyset\}$ and there exists a vertex v of P such that $v \in \arg \min_{x \in P} c^\top x$
- ③ There exists $x, d \in \mathbb{R}^n$ such that $x + td \in P$ for all $t \geq 0$ and $\lim_{t \rightarrow \infty} c^\top (x + td) = \infty$.



Problem Notation

We will now formalize the definitions we introduced in the examples.

- ▶ There are n variables and m constraints
- ▶ The linear objective function $z = \sum_{j=1}^n c_j x_j$
- ▶ The m inequality constraints in standard form

$$\sum_{j=1}^n a_{ij} x_j \leq b_i, \text{ for } i \in \{1, \dots, m\}.$$

- ▶ The n positivity constraints $x_j \geq 0$, for $j \in \{1, \dots, n\}$.
- ▶ x_i^* denotes the value of i th variable.
- ▶ We call $(x_1^*, \dots, x_n^*) \in \mathbb{R}^n$ a feasible solution if it satisfies the inequality and positivity constraints.

Dictionary Notation

- ▶ The slack variables $(x_{n+1}, \dots, x_{n+m}) \in \mathbb{R}^m$ (*variables d'écart*)
- ▶ The initial dictionary

$$\begin{array}{rcl} x_{n+1} & = & b_1 - \sum_{j=1}^n a_{1j}x_j \\ \vdots & & \\ x_{n+i} & = & b_i - \sum_{j=1}^n a_{ij}x_j \\ \vdots & & \\ x_{n+m} & = & b_m - \sum_{j=1}^n a_{mj}x_j \\ \hline z & = & \sum_{j=1}^n c_jx_j \end{array}$$

- ▶ Valid dictionary if m of the variables (x_1, \dots, x_{n+m}) can be expressed as function of the remaining n variables.
- ▶ The m variables on the left-hand side are the **basic variable** (*variable de base*). The n variables on the right-hand side are the **non-basic** (*variable hors-base*).

Dictionary Notation

After row elimination operations we have a new basis.

- ▶ **Basic variable set** $I \subset \{1, \dots, n + m\}$ and **non-basic set** $J = \{1, \dots, n + m\} \setminus I$ with $|I| = m$ and $|J| = n$
- ▶ **Current objective value** $z^* = \sum_{j=1}^n c_j x_j^*$.
- ▶ For each basis set I there is a corresponding dictionary

$$\frac{\begin{array}{l} x_i = b'_i - \sum_{j \in J} a'_{ij} x_j, \text{ for } i \in I \\ z = z^* + \sum_{j \in J} c'_j x_j, \end{array}}{}$$

where $a'_{ij}, b'_i, z^* \in \mathbb{R}$ are coefficients resulting from the row operations. For this to be a feasible dictionary we require that $b'_i \geq 0$.

- ▶ **A basic solution:** $x_i^* = b'_i$ for $i \in I$ and $x_j^* = 0$ for $j \in J$.

Variable entering/leaving the basis

- ▶ If $j_0 \in J$ with $c'_{j_0} > 0$ then increasing x_{j_0} will improve the objective since

$$z = z^* + \sum_{j \in J} c'_j x_j.$$

Variable entering/leaving the basis

- ▶ If $j_0 \in J$ with $c'_{j_0} > 0$ then increasing x_{j_0} will improve the objective since

$$z = z^* + \sum_{j \in J} c'_j x_j.$$

- ▶ How much can we increase x_{j_0} ? Until there is a $x_i = 0$ since

$$x_i^* = b'_i - a'_{ij_0} x_{j_0}^* \geq 0$$

Variable entering/leaving the basis

- ▶ If $j_0 \in J$ with $c'_{j_0} > 0$ then increasing x_{j_0} will improve the objective since

$$z = z^* + \sum_{j \in J} c'_j x_j.$$

- ▶ How much can we increase x_{j_0} ? Until there is a $x_i = 0$ since

$$x_i^* = b'_i - a'_{ij_0} x_{j_0}^* \geq 0 \quad \Rightarrow \quad a'_{ij_0} x_{j_0}^* \leq b'_i, \quad \forall i \in I.$$

Variable entering/leaving the basis

- ▶ If $j_0 \in J$ with $c'_{j_0} > 0$ then increasing x_{j_0} will improve the objective since

$$z = z^* + \sum_{j \in J} c'_j x_j.$$

- ▶ How much can we increase x_{j_0} ? Until there is a $x_i = 0$ since

$$x_i^* = b'_i - a'_{ij_0} x_{j_0}^* \geq 0 \quad \Rightarrow \quad a'_{ij_0} x_{j_0}^* \leq b'_i, \quad \forall i \in I.$$

- ▶ If $a'_{ij_0} \leq 0$, then increasing $x_{j_0}^*$ will increase x_i^*

Variable entering/leaving the basis

- ▶ If $j_0 \in J$ with $c'_{j_0} > 0$ then increasing x_{j_0} will improve the objective since

$$z = z^* + \sum_{j \in J} c'_j x_j.$$

- ▶ How much can we increase x_{j_0} ? Until there is a $x_i = 0$ since

$$x_i^* = b'_i - a'_{ij_0} x_{j_0}^* \geq 0 \quad \Rightarrow \quad a'_{ij_0} x_{j_0}^* \leq b'_i, \quad \forall i \in I.$$

- ▶ If $a'_{ij_0} \leq 0$, then increasing $x_{j_0}^*$ will increase x_i^*
- ▶ If $a'_{ij_0} > 0$, then $x_{j_0}^* \leq b'_i / a'_{ij_0}$

Variable entering/leaving the basis

- ▶ If $j_0 \in J$ with $c'_{j_0} > 0$ then increasing x_{j_0} will improve the objective since

$$z = z^* + \sum_{j \in J} c'_j x_j.$$

- ▶ How much can we increase x_{j_0} ? Until there is a $x_i = 0$ since

$$x_i^* = b'_i - a'_{ij_0} x_{j_0}^* \geq 0 \quad \Rightarrow \quad a'_{ij_0} x_{j_0}^* \leq b'_i, \quad \forall i \in I.$$

- ▶ If $a'_{ij_0} \leq 0$, then increasing $x_{j_0}^*$ will increase x_i^*
- ▶ If $a'_{ij_0} > 0$, then $x_{j_0}^* \leq b'_i / a'_{ij_0}$
- ▶ Thus

$$x_{j_0}^* = \min_{i \in I, a'_{ij_0} > 0} \frac{b'_i}{a'_{ij_0}}$$

Variable entering/leaving the basis

- ▶ If $j_0 \in J$ with $c'_{j_0} > 0$ then increasing x_{j_0} will improve the objective since

$$z = z^* + \sum_{j \in J} c'_j x_j.$$

- ▶ How much can we increase x_{j_0} ? Until there is a $x_i = 0$ since

$$x_i^* = b'_i - a'_{ij_0} x_{j_0}^* \geq 0 \quad \Rightarrow \quad a'_{ij_0} x_{j_0}^* \leq b'_i, \quad \forall i \in I.$$

- ▶ If $a'_{ij_0} \leq 0$, then increasing $x_{j_0}^*$ will increase x_i^*
- ▶ If $a'_{ij} > 0$, then $x_{j_0}^* \leq b'_i / a'_{ij_0}$
- ▶ Thus

$$x_{j_0}^* = \min_{i \in I, a'_{ij_0} > 0} \frac{b'_i}{a'_{ij_0}}$$

- ▶ In this case, which $x_i^* = 0$ (which i leaves the basis?)

A Step of the Simplex Method

Input: $I = \{n+1, \dots, n+m\}$, $J = \{1, \dots, n\}$, $a'_{ij} \in \mathbb{R}$, $b'_i \geq 0$, $c'_i \in \mathbb{R}$.

A Step of the Simplex Method

Input: $I = \{n+1, \dots, n+m\}$, $J = \{1, \dots, n\}$, $a'_{ij} \in \mathbb{R}$, $b'_i \geq 0$, $c'_i \in \mathbb{R}$.

if $c'_i \leq 0$ for all $i \in J$ **then**
 STOP; # Optimal point found.

A Step of the Simplex Method

Input: $I = \{n+1, \dots, n+m\}$, $J = \{1, \dots, n\}$, $a'_{ij} \in \mathbb{R}$, $b'_i \geq 0$, $c'_i \in \mathbb{R}$.

if $c'_i \leq 0$ for all $i \in J$ **then**

STOP; # Optimal point found.

Choose a variable j_0 to **enter the basis** from the set $j_0 \in \{j \in J : c'_j > 0\}$.

if $a'_{ij_0} \leq 0$ for all $i \in I$ **then**

STOP; # The problem is unbounded.

A Step of the Simplex Method

Input: $I = \{n+1, \dots, n+m\}$, $J = \{1, \dots, n\}$, $a'_{ij} \in \mathbb{R}$, $b'_i \geq 0$, $c'_i \in \mathbb{R}$.

if $c'_i \leq 0$ for all $i \in J$ **then**

STOP; # Optimal point found.

Choose a variable j_0 to **enter the basis** from the set $j_0 \in \{j \in J : c'_j > 0\}$.

if $a'_{ij_0} \leq 0$ for all $i \in I$ **then**

STOP; # The problem is unbounded.

Choose a variable i_0 to **leave the basis** from the set $i_0 \in \arg \min_{i \in I, a'_{ij_0} > 0} \left\{ \frac{b'_i}{a'_{ij_0}} \right\}$.

A Step of the Simplex Method

Input: $I = \{n+1, \dots, n+m\}$, $J = \{1, \dots, n\}$, $a'_{ij} \in \mathbb{R}$, $b'_i \geq 0$, $c'_i \in \mathbb{R}$.

if $c'_i \leq 0$ for all $i \in J$ **then**

STOP; # Optimal point found.

Choose a variable j_0 to **enter the basis** from the set $j_0 \in \{j \in J : c'_j > 0\}$.

if $a'_{ij_0} \leq 0$ for all $i \in I$ **then**

STOP; # The problem is unbounded.

Choose a variable i_0 to **leave the basis** from the set $i_0 \in \arg \min_{i \in I, a'_{ij_0} > 0} \left\{ \frac{b'_i}{a'_{ij_0}} \right\}$.

$I \leftarrow (I \setminus \{i_0\})$ and $J \leftarrow J \cup \{i_0\}$ \triangleright Move i_0 from basic to non-basic

for $i \in I$ **do**

$a'_{i:} \leftarrow a'_{i:} - \frac{a'_{ij_0}}{a'_{i_0j_0}} a'_{i_0:}$ \triangleright Row elimination on pivot (i_0, j_0) .

A Step of the Simplex Method

Input: $I = \{n+1, \dots, n+m\}$, $J = \{1, \dots, n\}$, $a'_{ij} \in \mathbb{R}$, $b'_i \geq 0$, $c'_i \in \mathbb{R}$.

if $c'_i \leq 0$ for all $i \in J$ **then**

STOP; # Optimal point found.

Choose a variable j_0 to **enter the basis** from the set $j_0 \in \{j \in J : c'_j > 0\}$.

if $a'_{ij_0} \leq 0$ for all $i \in I$ **then**

STOP; # The problem is unbounded.

Choose a variable i_0 to **leave the basis** from the set $i_0 \in \arg \min_{i \in I, a'_{ij_0} > 0} \left\{ \frac{b'_i}{a'_{ij_0}} \right\}$.

$I \leftarrow (I \setminus \{i_0\})$ and $J \leftarrow J \cup \{i_0\}$ \triangleright Move i_0 from basic to non-basic

for $i \in I$ **do**

$a'_{i:} \leftarrow a'_{i:} - \frac{a'_{ij_0}}{a'_{i_0j_0}} a'_{i_0:}$ \triangleright Row elimination on pivot (i_0, j_0) .

$a'_{i_0:} \leftarrow \frac{1}{a'_{i_0j_0}} a'_{i_0:}$ and $a'_{i_0j_0} \leftarrow \frac{1}{a'_{i_0j_0}}$ \triangleright Normalize the coefficient of $a'_{i_0j_0}$

A Step of the Simplex Method

Input: $I = \{n+1, \dots, n+m\}$, $J = \{1, \dots, n\}$, $a'_{ij} \in \mathbb{R}$, $b'_i \geq 0$, $c'_i \in \mathbb{R}$.

if $c'_i \leq 0$ for all $i \in J$ **then**

STOP; # Optimal point found.

Choose a variable j_0 to **enter the basis** from the set $j_0 \in \{j \in J : c'_j > 0\}$.

if $a'_{ij_0} \leq 0$ for all $i \in I$ **then**

STOP; # The problem is unbounded.

Choose a variable i_0 to **leave the basis** from the set $i_0 \in \arg \min_{i \in I, a'_{ij_0} > 0} \left\{ \frac{b'_i}{a'_{ij_0}} \right\}$.

$I \leftarrow (I \setminus \{i_0\})$ and $J \leftarrow J \cup \{i_0\}$ ▷ Move i_0 from basic to non-basic

for $i \in I$ **do**

$$a'_{i:} \leftarrow a'_{i:} - \frac{a'_{ij_0}}{a'_{i_0j_0}} a'_{i_0:}$$

▷ Row elimination on pivot (i_0, j_0) .

$$a'_{i_0:} \leftarrow \frac{1}{a'_{i_0j_0}} a'_{i_0:} \quad \text{and} \quad a'_{i_0j_0} \leftarrow \frac{1}{a'_{i_0j_0}}$$

▷ Normalize the coefficient of $a'_{i_0j_0}$

$$c' \leftarrow c' - \frac{c'_{j_0}}{a'_{i_0j_0}} a'_{i_0:}$$

▷ Update the cost coefficients.

A Step of the Simplex Method

Input: $I = \{n + 1, \dots, n + m\}$, $J = \{1, \dots, n\}$, $a'_{ij} \in \mathbb{R}$, $b'_i \geq 0$, $c'_i \in \mathbb{R}$.

if $c'_i \leq 0$ for all $i \in J$ **then**

STOP; # Optimal point found.

Choose a variable j_0 to **enter the basis** from the set $j_0 \in \{j \in J : c'_j > 0\}$.

if $a'_{ij_0} \leq 0$ for all $i \in I$ **then**

STOP; # The problem is unbounded.

Choose a variable i_0 to **leave the basis** from the set $i_0 \in \arg \min_{i \in I, a'_{ij_0} > 0} \left\{ \frac{b'_i}{a'_{ij_0}} \right\}$.

$I \leftarrow (I \setminus \{i_0\})$ and $J \leftarrow J \cup \{i_0\}$ \triangleright Move i_0 from basic to non-basic

for $i \in I$ **do**

$a'_{i:} \leftarrow a'_{i:} - \frac{a'_{ij_0}}{a'_{i_0j_0}} a'_{i_0:}$ \triangleright Row elimination on pivot (i_0, j_0) .

$a'_{i_0:} \leftarrow \frac{1}{a'_{i_0j_0}} a'_{i_0:}$ and $a'_{i_0j_0} \leftarrow \frac{1}{a'_{i_0j_0}}$ \triangleright Normalize the coefficient of $a'_{i_0j_0}$

$c' \leftarrow c' - \frac{c'_{j_0}}{a'_{i_0j_0}} a'_{i_0:}$ \triangleright Update the cost coefficients.

$I \leftarrow I \cup \{j_0\}$ and $J \leftarrow (J \setminus \{j_0\})$ \triangleright Move j_0 from non-basic to basic

How to choose who enters the basis?

$$j_0 \in \{j \in J : c'_j > 0\}$$

- ① The mad hatter rule: Choose the first one you see costs: $O(1)$
- ② Dantzig's 1st rule: $j_0 = \arg \max_{j \in J} c_j$ cost: $O(n)$
- ③ Dantzig's 2nd rule: Choose j_0 that maximizes the increase in z .

$$j_0 = \arg \max_{j \in J} \left\{ c_j \min_{i \in I, a_{ij} > 0} \left\{ \frac{b_i}{a_{ij}} \right\} \right\} \quad \text{costs : } O(n)$$

Effective, but computationally expensive. costs: $O(nm)$

- ④ Bland's rule: Choose the smallest indices j_0 and i_0 . That is, choose

$$j_0 = \arg \min \{j \in J : c_j > 0\} \quad \text{costs : } O(n)$$

$$i_0 = \min \left\{ \arg \min_{i \in I, a_{ij_0} > 0} \left\{ \frac{b_i}{a_{ij_0}} \right\} \right\}.$$

Degeneracy

If any of the basic variables are zero, then we say that the solution is degenerate.

Consider the initial dictionary:

$$x_4 = 1 + 0 + 0 - 2x_3$$

$$x_5 = 3 - 2x_1 + 4x_2 - 6x_3$$

$$x_6 = 2 + x_1 - 3x_2 - 4x_3$$

$$z = 0 + 2x_1 - x_2 + 8x_3$$

If x_3 enters then who leaves?

Degeneracy

If any of the basic variables are zero, then we say that the solution is degenerate.

Consider the initial dictionary:

$$x_4 = 1 + 0 + 0 - 2x_3$$

$$x_5 = 3 - 2x_1 + 4x_2 - 6x_3$$

$$x_6 = 2 + x_1 - 3x_2 - 4x_3$$

$$z = 0 + 2x_1 - x_2 + 8x_3$$

If x_3 enters then who leaves? Both x_5 and x_6 are set to zero, so either one. Choosing x_4 and pivoting on a'_{13} we have.

$$x_3 = 0.5 + 0 + 0 - 0.5x_4$$

$$x_5 = 0 - 2x_1 + 4x_2 + 3x_4$$

$$x_6 = 0 + x_1 - 3x_2 + 2x_4$$

$$z = 4 + 2x_1 - x_2 - 4x_4$$

Only x_1 can enter the basis, but it doesn't increase in value :(
[Example in lecture notes.](#)

Bland's rule for degeneracy

Bland's rule

Choose the smallest indices j_0 and i_0 . That is, choose

$$j_0 = \arg \min \{j \in J : c_j > 0\}.$$

$$i_0 = \min \left\{ \arg \min_{i \in I, a_{ij_0} > 0} \left\{ \frac{b_i}{a_{ij_0}} \right\} \right\}.$$

Theorem

If Bland's rule is used on all degenerate dictionaries, then the simplex algorithm will not cycle.

The zero is not always feasible

$$\begin{array}{rcll} \max & x_1 & -x_2 & +x_3 \\ & 2x_1 & -x_2 & +2x_3 \leq 4 \\ & 2x_1 & -3x_2 & +x_3 \leq -5 \\ & -x_1 & +x_2 & -2x_3 \leq -1 \\ & x_1, & x_2, & x_3, \geq 0. \end{array}$$

The point $(x_1^*, x_2^*, x_3^*) = (0, 0, 0)$ is **not feasible**.

The zero is not always feasible

$$\begin{array}{rcll}
 \max & x_1 & -x_2 & +x_3 \\
 & 2x_1 & -x_2 & +2x_3 \leq 4 \\
 & 2x_1 & -3x_2 & +x_3 \leq -5 \\
 & -x_1 & +x_2 & -2x_3 \leq -1 \\
 & x_1, & x_2, & x_3, \geq 0.
 \end{array}$$

The point $(x_1^*, x_2^*, x_3^*) = (0, 0, 0)$ is **not feasible**.

Setup an **auxiliary problem**

$$\begin{array}{rcll}
 \max & -x_0 \\
 & 2x_1 & -x_2 & +2x_3 & -x_0 \leq 4 \\
 & 2x_1 & -3x_2 & +x_3 & -x_0 \leq -5 \\
 & -x_1 & +x_2 & -2x_3 & -x_0 \leq -1 \\
 & x_1, & x_2, & x_3, & x_0 \geq 0.
 \end{array}$$

Setup initial dictionary

Initial phase one dictionary:

$$\begin{array}{rclclcl} x_4 & = & 4 & -2x_1 & +x_2 & -2x_3 & +x_0 \\ x_5 & = & -5 & -2x_1 & +3x_2 & -x_3 & +x_0 \\ x_6 & = & -1 & +x_1 & -x_2 & +2x_3 & +x_0 \\ w & = & & & & & -x_0. \end{array}$$

Pivot on “most infeasible” basis. Thus x_5 leaves the basis and x_0 enters the basis. Gaussian elimination :

$$r_1 \leftarrow r_1 - r_2.$$

$$r_3 \leftarrow r_3 - r_2.$$

$$w \leftarrow w + r_2.$$

Initial phase one dictionary:

$$\begin{array}{rclclcl}
 x_4 & = & 4 & -2x_1 & +x_2 & -2x_3 & +x_0 \\
 x_5 & = & -5 & -2x_1 & +3x_2 & -x_3 & +x_0 \\
 x_6 & = & -1 & +x_1 & -x_2 & +2x_3 & +x_0 \\
 w & = & & & & & -x_0.
 \end{array}$$

Pivot on “most infeasible” basis. Thus x_5 leaves the basis and x_0 enters the basis. Gaussian elimination :

$$r_1 \leftarrow r_1 - r_2.$$

$$r_3 \leftarrow r_3 - r_2.$$

$$w \leftarrow w + r_2.$$

$$\begin{array}{rclclcl}
 x_4 & = & 9 & +0 & -2x_2 & -x_3 & +x_5 \\
 x_0 & = & 5 & 2x_1 & -3x_2 & +x_3 & +x_5 \\
 x_6 & = & 4 & +3x_1 & -4x_2 & +3x_3 & +x_5 \\
 w & = & -5 & -2x_1 & +3x_2 & -x_3 & -x_5.
 \end{array}$$

Now x_2 enters and who leaves?

Initial phase one dictionary:

$$\begin{array}{rclclcl}
 x_4 & = & 4 & -2x_1 & +x_2 & -2x_3 & +x_0 \\
 x_5 & = & -5 & -2x_1 & +3x_2 & -x_3 & +x_0 \\
 x_6 & = & -1 & +x_1 & -x_2 & +2x_3 & +x_0 \\
 w & = & & & & & -x_0.
 \end{array}$$

Pivot on “most infeasible” basis. Thus x_5 leaves the basis and x_0 enters the basis. Gaussian elimination :

$$r_1 \leftarrow r_1 - r_2.$$

$$r_3 \leftarrow r_3 - r_2.$$

$$w \leftarrow w + r_2.$$

$$\begin{array}{rclclcl}
 x_4 & = & 9 & +0 & -2x_2 & -x_3 & +x_5 \\
 x_0 & = & 5 & 2x_1 & -3x_2 & +x_3 & +x_5 \\
 x_6 & = & 4 & +3x_1 & -4x_2 & +3x_3 & +x_5 \\
 w & = & -5 & -2x_1 & +3x_2 & -x_3 & -x_5.
 \end{array}$$

Now x_2 enters and who leaves? x_6 leaves the basis

Upper Bounds Using Duality

The LP in standard form

$$\begin{aligned} \max_x z &\stackrel{\text{def}}{=} c^\top x \\ \text{subject to } Ax &\leq b, \\ x &\geq 0, \end{aligned} \tag{LP}$$

We want to find $w \in \mathbb{R}$ so that $z = c^\top x \leq w$ for all $x \in \mathbb{R}^n$.

Combine rows of constraints?

Look for $y \geq 0 \in \mathbb{R}^m$ so that $y^\top A \approx c^\top$, consequently

$$c^\top x \approx (y^\top A)x \leq y^\top b = w.$$

Precisely, let $y \geq 0 \in \mathbb{R}^m$ be such that $y^\top A \geq c^\top$ or equivalently $A^\top y \geq c$. Then

$$c^\top x \leq (y^\top A)x \leq y^\top b.$$

Can we make this upper bound as **tight as possible**? Yes, by minimizing $y^\top b$. That is, we need to the *dual* linear program.

Dual definition

The LP in standard form

$$\begin{aligned} \max_x z &\stackrel{\text{def}}{=} c^\top x \\ \text{subject to } Ax &\leq b, \\ x &\geq 0, \end{aligned} \tag{LP}$$

The dual LP:

$$\begin{aligned} \max_y w &\stackrel{\text{def}}{=} y^\top b \\ \text{subject to } A^\top y &\geq c, \\ y &\geq 0. \end{aligned} \tag{DP}$$

Lemma (Weak Duality)

If $x \in \mathbb{R}^n$ is a feasible point for (LP) and $y \in \mathbb{R}^m$ is a feasible point for (DP) then

$$c^\top x \leq y^\top Ax \leq y^\top b. \tag{1}$$

Weak Duality

Lemma (Weak Duality)

If $x \in \mathbb{R}^n$ is a feasible point for (LP) and $y \in \mathbb{R}^m$ is a feasible point for (DP) then

$$c^\top x \leq y^\top Ax \leq y^\top b. \quad (2)$$

Consequently

- ▶ *If (LP) has an unbounded solution, that is $c^\top x \rightarrow \infty$, then there exists no feasible point y for (DP)*
- ▶ *If (DP) has an unbounded solution, that is $y^\top b \rightarrow -\infty$, then there exists no feasible point x for (LP)*
- ▶ *If x and y are primal and dual feasible, respectively, and $c^\top x = y^\top b$, then x and y are the primal and dual optimal points, respectively.*

Strong Duality

Theorem (Strong Duality)

If (LP) or (DP) is feasible, then $z^ = w^*$. Moreover, if c^* is the cost vector of the optimal dictionary of the primal problem (LP), that is, if*

$$z = z^* + \sum_{i=1}^{n+m} c_i^* x_i, \quad (3)$$

then $y_i^ = -c_{n+i}^*$ for $i = 1, \dots, m$.*

First $c_i^* \leq 0$ for $i = 1, \dots, m+n$ because dictionary is optimal.
Consequently $y_i^* = -c_{n+i}^* \geq 0$ for $i = 1, \dots, m$.

Strong duality: Proof I

By the definition of the slack variables we have that

$$x_{n+i} = b_i - \sum_{j=1}^n a_{ij}x_j, \quad \text{for } i = 1, \dots, m. \quad (4)$$

Consequently, setting $y_i^* = -c_{n+i}^*$, we have that

$$\begin{aligned} z &\stackrel{(3)}{=} z^* + \sum_{j=1}^n c_j^* x_j + \sum_{i=n+1}^{n+m} c_i^* x_i \\ &\stackrel{(4)}{=} z^* + \sum_{j=1}^n c_j^* x_j - \sum_{i=1}^m y_i^* (b_i - \sum_{j=1}^n a_{ij}x_j) \\ &= z^* - \sum_{i=1}^m y_i^* b_i + \sum_{j=1}^n \left(c_j^* + \sum_{i=1}^m y_i^* a_{ij} \right) x_j \\ &= \sum_{j=1}^n c_j x_j, \quad \forall x_1, \dots, x_n. \end{aligned} \quad (5)$$

Last line followed by definition $z = \sum_{j=1}^n c_j x_j$. Since the above holds for all $x \in \mathbb{R}^n$, we can match the coefficients.

Strong duality: Proof II

Matching coefficients on x_j 's we have

$$z^* = \sum_{i=1}^m y_i^* b_i \quad (6)$$

$$c_j = c_j^* + \sum_{i=1}^m y_i^* a_{ij}, \quad \text{for } j = 1, \dots, n. \quad (7)$$

Since $c_j^* \leq 0$ for $j = 1, \dots, n$, the above is equivalent to

$$z^* = \sum_{i=1}^m y_i^* b_i \quad (8)$$

$$\sum_{i=1}^m y_i^* a_{ij} \leq c_j, \quad \text{for } j = 1, \dots, n. \quad (9)$$

The inequalities (9) prove that y_i^* 's satisfies the constraints in (DP), and thus is feasible. The equality (8) shows that $z^* = \sum_{i=1}^m y_i^* b_i = w$, a consequently by weak duality the y_i^* 's are dual optimal. \square



G.,R & P Richtárik, Randomized Iterative Methods for Linear Systems arXiv:1506.03296