

Optimization for Machine Learning

Stochastic Gradient Methods

Lecturer: Robert M. Gower



Master IASD: AI Systems and Data Science, 2019

Core Info

- **Where:** ENS: 07/11 amphi Langevin, 03/12 U209, 05/12 amphi Langevin.
- **Online:** Teaching materials for these 3 classes:
<https://gowerrobert.github.io/>
- **Google docs with course info:** Can also be found on
<https://gowerrobert.github.io/>

Outline of my three classes

- 07/11/19 Foundations and the empirical risk problem, revision probability, SGD (Stochastic Gradient Descent) for ridge regression
- 03/12/19 (**TODAY**) SGD for convex optimization. Theory, variants including averaging, decreasing stepsizes and momentum.
- 05/12/19 Lab on SGD and variants **BRING LAPTOPS!**

Solving the Finite Sum Training Problem

Recap

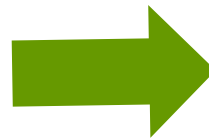
Training Problem

$$\min_{w \in \mathbf{R}^d} \underbrace{\frac{1}{n} \sum_{i=1}^n \ell(h_w(x^i), y^i)}_{L(w) = \text{loss}} + \lambda R(w) =: f(w)$$

$$L(w) = \text{loss}$$

General methods

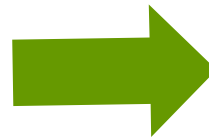
$$\min f(w)$$



- Gradient Descent

Two parts

$$\min L(w) + \lambda R(w)$$



- Proximal gradient (ISTA)
- Fast proximal gradient (FISTA)

Optimization Sum of Terms

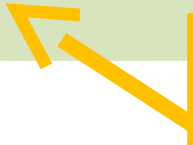
A Datum Function

$$f_i(w) := \ell(h_w(x^i), y^i) + \lambda R(w)$$

$$\begin{aligned} \frac{1}{n} \sum_{i=1}^n \ell(h_w(x^i), y^i) + \lambda R(w) &= \frac{1}{n} \sum_{i=1}^n (\ell(h_w(x^i), y^i) + \lambda R(w)) \\ &= \frac{1}{n} \sum_{i=1}^n f_i(w) \end{aligned}$$

Finite Sum Training Problem

$$\min_{w \in \mathbf{R}^d} \frac{1}{n} \sum_{i=1}^n f_i(w) =: f(w)$$



Can we use this
sum structure?

The Training Problem

Solving the *training problem*:

$$\min_{w \in \mathbf{R}^d} \frac{1}{n} \sum_{i=1}^n f_i(w)$$

Reference method: Gradient descent

$$\nabla \left(\frac{1}{n} \sum_{i=1}^n f_i(w) \right) = \frac{1}{n} \sum_{i=1}^n \nabla f_i(w)$$

Gradient Descent Algorithm

Set $w^0 = 0$, choose $\alpha > 0$.

for $t = 0, 1, 2, \dots, T - 1$

$$w^{t+1} = w^t - \frac{\alpha}{n} \sum_{i=1}^n \nabla f_i(w^t)$$

Output w^T

The Training Problem

Solving the *training problem*:

$$\min_{w \in \mathbf{R}^d} \frac{1}{n} \sum_{i=1}^n f_i(w)$$

Problem with Gradient Descent:

Each iteration requires computing a gradient $\nabla f_i(w)$ for each data point. One gradient for each cat on the internet!

Gradient Descent Algorithm

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for $t = 0, 1, 2, \dots, T$

$$w^{t+1} = w^t - \frac{\alpha}{n} \sum_{i=1}^n \nabla f_i(w^t)$$

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Stochastic Gradient Descent

Is it possible to design a method that uses only the gradient of a **single** data function $f_i(w)$ at each iteration?

Stochastic Gradient Descent

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Unbiased Estimate

Let j be a random index sampled from $\{1, \dots, n\}$ selected uniformly at random. Then

$$\mathbb{E}_j[\nabla f_j(w)] = \frac{1}{n} \sum_{i=1}^n \nabla f_i(w) = \nabla f(w)$$

Stochastic Gradient Descent

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Use $\nabla f_j(w) \approx \nabla f(w)$



Stochastic Gradient Descent

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$$\mathbb{E}_j[\nabla f_j(w)] = \frac{1}{n} \sum_{i=1}^n \nabla f_i(w) = \nabla f(w)$$



Use $\nabla f_j(w) \approx \nabla f(w)$



EXE: Let $\sum_{i=1}^n p_i = 1$ and $j \sim p_j$. Show $\mathbb{E}[\nabla f_j(w)/(np_j)] = \nabla f(w)$

Stochastic Gradient Descent

SGD 0.0 Constant stepsize

Set $w^0 = 0$, choose $\alpha > 0$

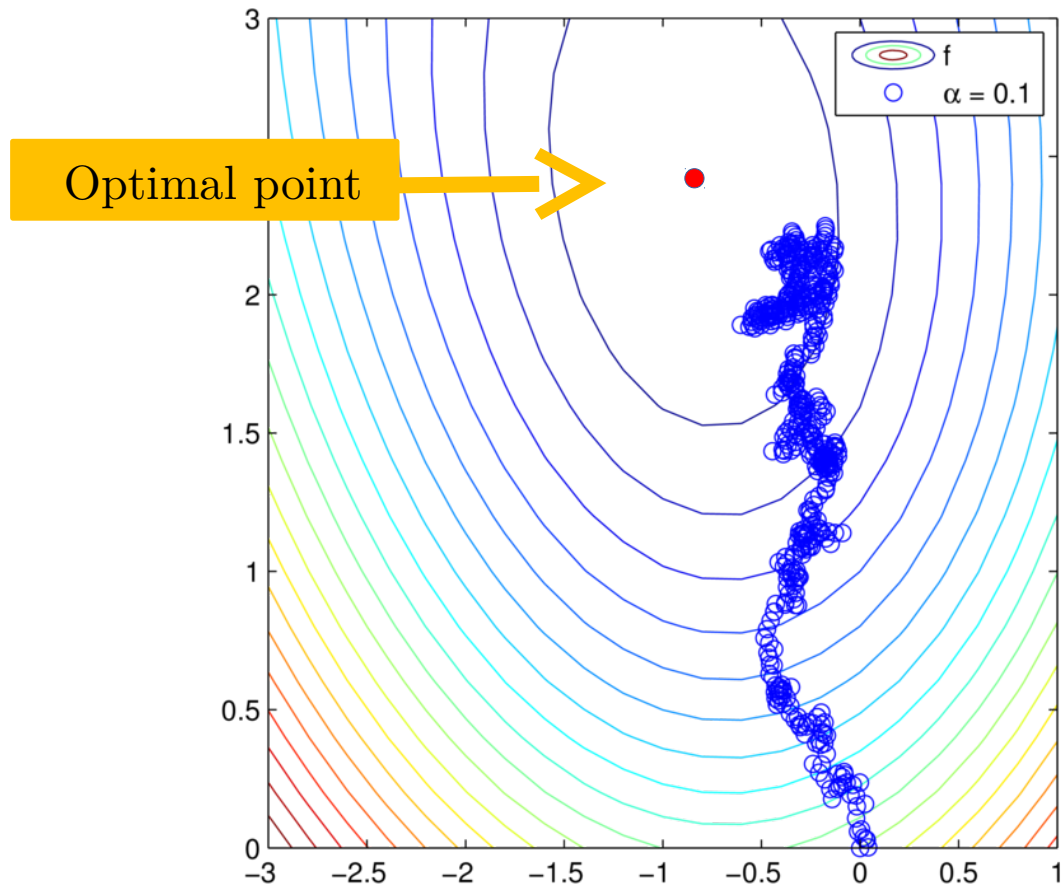
for $t = 0, 1, 2, \dots, T - 1$

 sample $j \in \{1, \dots, n\}$

$$w^{t+1} = w^t - \alpha \nabla f_j(w^t)$$

Output w^T

Stochastic Gradient Descent



Assumptions for Convergence

Strong Convexity

$$f(y) \geq f(w) + \langle \nabla f(w), y - w \rangle + \frac{\lambda}{2} \|y - w\|_2^2, \quad \forall w, y$$



$$y = w^*$$

$$2\langle \nabla f(w), w - w^* \rangle \geq \lambda \|w - w^*\|_2^2$$

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Expected Bounded Stochastic Gradients

$$\mathbb{E}_j[\|\nabla f_j(w^t)\|_2^2] \leq B^2, \text{ for all iterates } w^t \text{ of SGD}$$

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$$\mathbb{E}_j[\|\nabla f_j(w^t)\|_2^2] \leq B^2, \text{ for all iterates } w^t \text{ of SGD}$$

Theorem

If $0 < \alpha \leq \frac{1}{\lambda}$ then the iterates of the SGD 0.0 method satisfy

$$\mathbb{E} [\|w^t - w^*\|_2^2] \leq (1 - \alpha\lambda)^t \|w^0 - w^*\|_2^2 + \frac{\alpha}{\lambda} B^2$$

EXE: Do exercises on convergence of random sequences.

Theorem

If $0 < \alpha \leq \frac{1}{\lambda}$ then the iterates of the SGD 0.0 method satisfy

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Shows that $\alpha \approx \frac{1}{\lambda}$

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Shows that $\alpha \approx \frac{1}{\lambda}$



Shows that $\alpha \approx 0$

EXE: Do exercises on convergence of random sequences.

Proof:

$$\begin{aligned}
\|w^{t+1} - w^*\|_2^2 &= \|w^t - w^* - \alpha \nabla f_j(w^t)\|_2^2 \\
&= \|w^t - w^*\|_2^2 - 2\alpha \langle \nabla f_j(w^t), w^t - w^* \rangle + \alpha^2 \|\nabla f_j(w^t)\|_2^2.
\end{aligned}$$

Taking expectation with respect to j

Unbiased estimator

$$\begin{aligned}
\mathbb{E}_j [\|w^{t+1} - w^*\|_2^2] &= \|w^t - w^*\|_2^2 - 2\alpha \langle \nabla f(w^t), w^t - w^* \rangle + \alpha^2 \mathbb{E}_j [\|\nabla f_j(w^t)\|_2^2] \\
&\leq \|w^t - w^*\|_2^2 - 2\alpha \langle \nabla f(w^t), w^t - w^* \rangle + \alpha^2 B^2
\end{aligned}$$

Strong conv.



$$\leq (1 - \alpha\lambda) \|w^t - w^*\|_2^2 + \alpha^2 B^2$$

Taking total expectation

Bounded
Stoch grad

$$\begin{aligned}
\mathbb{E} [\|w^{t+1} - w^*\|_2^2] &\leq (1 - \alpha\lambda) \mathbb{E} [\|w^t - w^*\|_2^2] + \alpha^2 B^2 \\
&= (1 - \alpha\lambda)^{t+1} \|w^0 - w^*\|_2^2 + \sum_{i=0}^t (1 - \alpha\lambda)^i \alpha^2 B^2
\end{aligned}$$

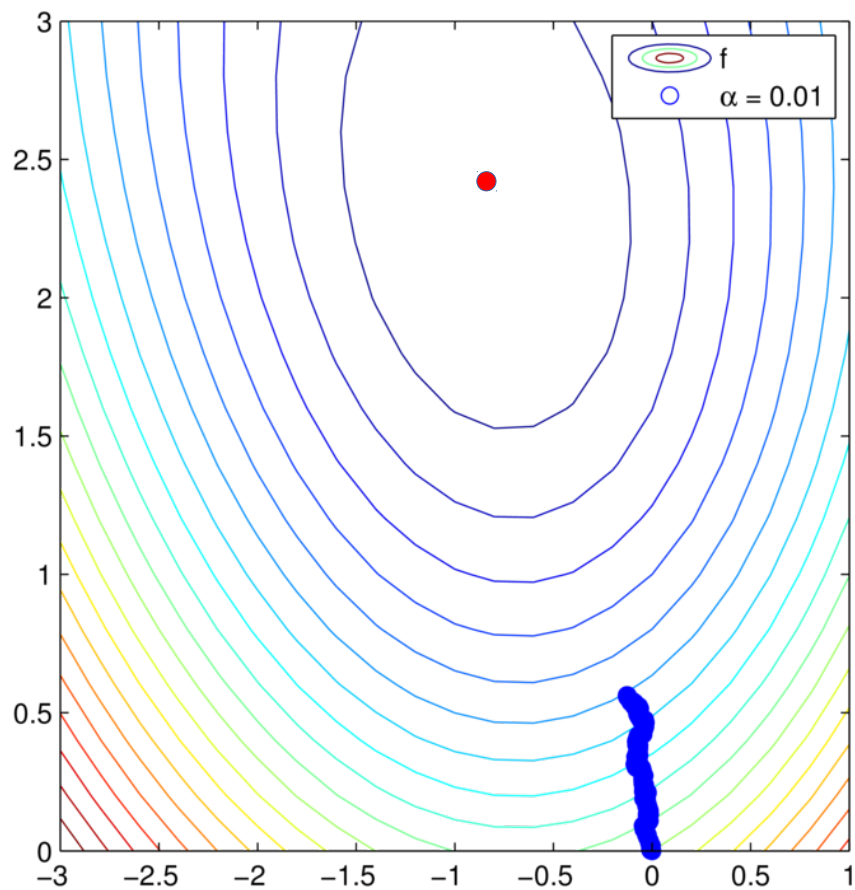
Using the geometric series sum $\sum_{i=0}^t (1 - \alpha\lambda)^i = \frac{1 - (1 - \alpha\lambda)^{t+1}}{\alpha\lambda} \leq \frac{1}{\alpha\lambda}$

$$\mathbb{E} [\|w^{t+1} - w^*\|_2^2] \leq (1 - \alpha\lambda)^{t+1} \|w^0 - w^*\|_2^2 + \frac{\alpha}{\lambda} B^2$$

Stochastic Gradient Descent

$\alpha = 0.01$

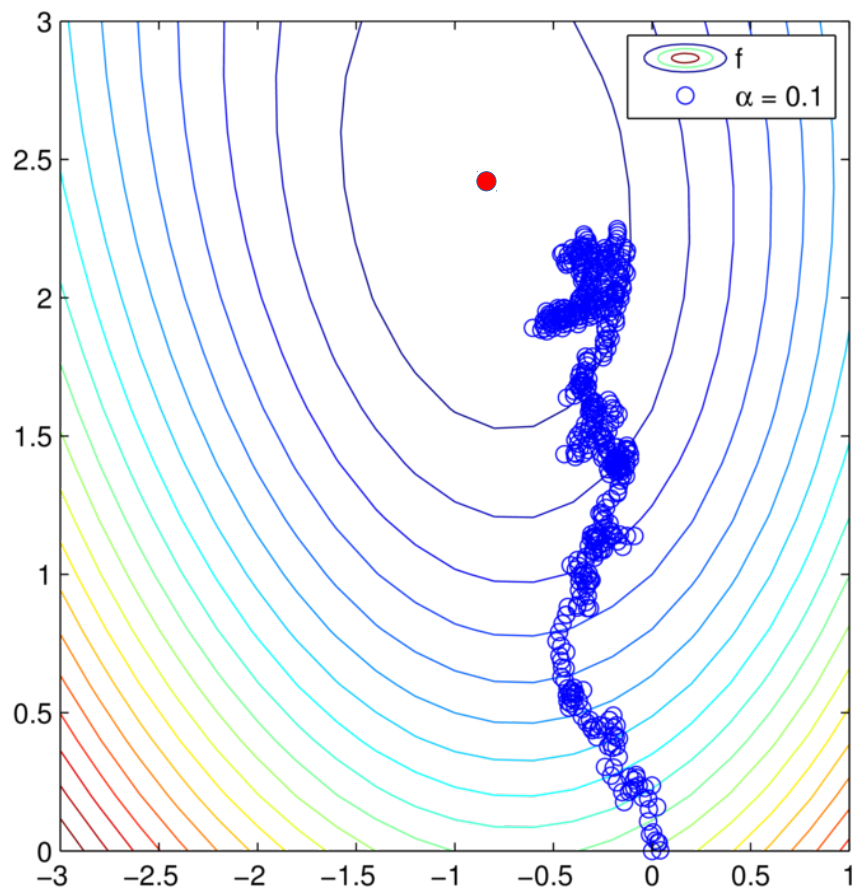
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Stochastic Gradient Descent

$\alpha = 0.1$

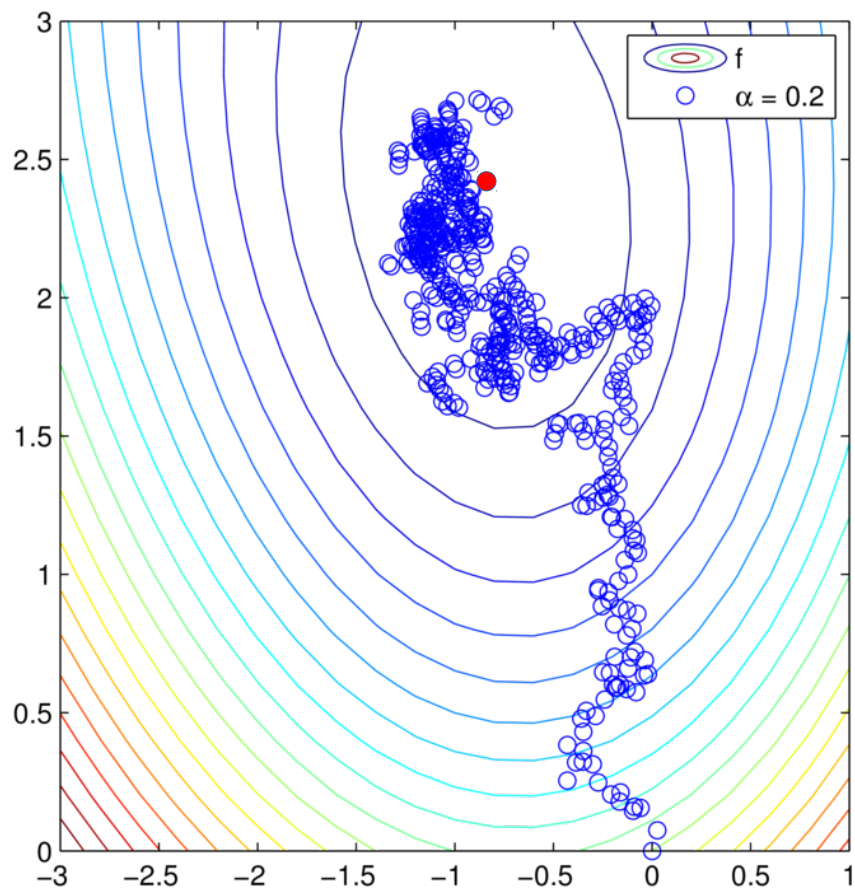
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Stochastic Gradient Descent

$\alpha = 0.2$

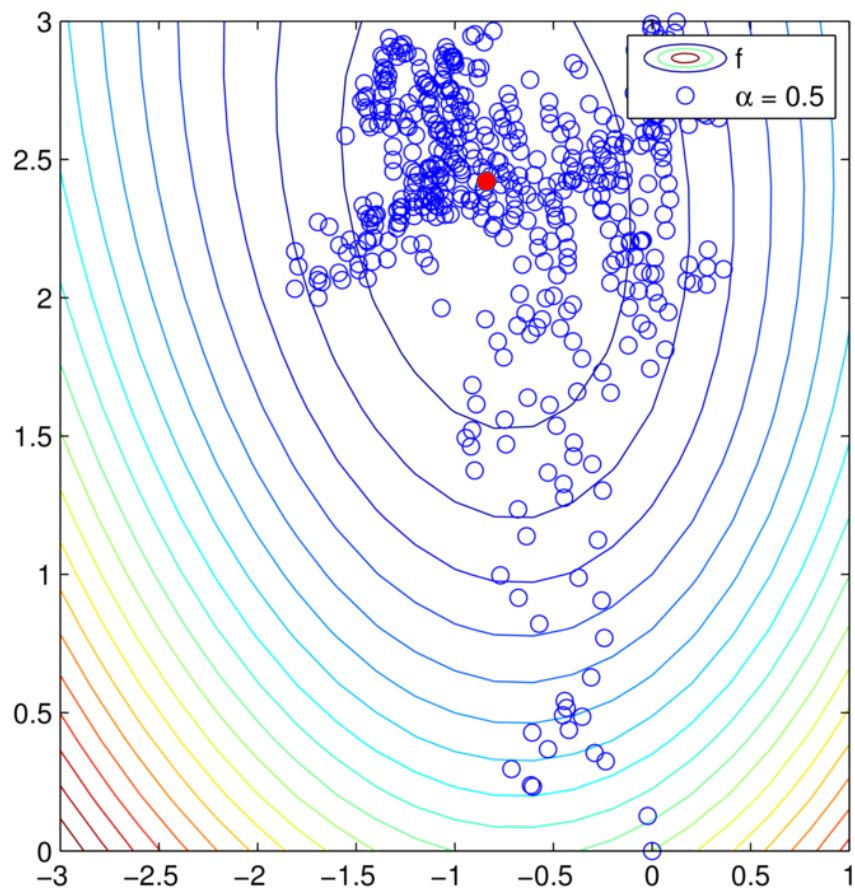
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Stochastic Gradient Descent

$\alpha = 0.5$

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Assumptions for Convergence

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$$y = w^*$$

$$2\langle \nabla f(w), w - w^* \rangle \geq \lambda \|w - w^*\|_2^2$$

Expected Bounded Stochastic Gradients

$$\mathbb{E}_j[\|\nabla f_j(w^t)\|_2^2] \leq B^2, \text{ for all iterates } w^t \text{ of SGD}$$

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EXE:

Let $A \in \mathbb{R}^{n \times d}$, $f_j(w) = (A_j w - b_j)^2$. $\max_w \mathbb{E}_{j \sim \frac{1}{n}} [\|\nabla f_j(w)\|^2] = ?$

EXE:

Let $A \in \mathbb{R}^{n \times d}$, $f_j(w) = (A_{j:}w - b_j)^2$. $\max_w \mathbb{E}_{j \sim \frac{1}{n}} [\|\nabla f_j(w)\|^2] = ?$

Proof: $\max_w \mathbb{E}_{j \sim \frac{1}{n}} [\|\nabla f_j(w)\|^2] = \infty$, indeed since

$$\begin{aligned} \|\nabla f_j(w)\|^2 &= 4\|A_{j:}^\top (A_{j:}w - b_j)\|^2 \\ &= 4\|A_{j:}\|^2 (A_{j:}w - b_j)^2 \\ &= 4(\hat{A}_{j:}w - \hat{b}_j)^2 \quad \text{where } \hat{A}_{j:} := A_{j:}\|A_{j:}\|, \quad \hat{b}_j := b_j\|A_{j:}\| \end{aligned}$$

Taking expectation

$$\mathbb{E}_{j \sim \frac{1}{n}} \|\nabla f_j(w)\|^2 = \frac{1}{n} \sum_{j=1}^n 4(\hat{A}_{j:}w - \hat{b}_j)^2 = \frac{1}{n} \|\hat{A}w - \hat{b}\|^2$$

$$\lim_{w \rightarrow \infty} \|\hat{A}w - \hat{b}\|^2 = \infty$$

Realistic assumptions for Convergence

Strongly quasi-convexity

$$f(w^*) \geq f(w) + \langle \nabla f(w), w^* - w \rangle + \frac{\mu}{2} \|w^* - w\|_2^2, \quad \forall w$$

Each f_i is convex and L_i smooth

$$f_i(y) \leq f_i(w) + \langle \nabla f_i(w), y - w \rangle + \frac{L_i}{2} \|y - w\|_2^2, \quad \forall w$$

$$L_{\max} := \max_{i=1, \dots, n} L_i$$

Definition: Gradient Noise

$$\sigma^2 := \mathbb{E}_j [\|\nabla f_j(w^*)\|_2^2]$$

$$1. \quad f(w) = \frac{1}{2n} \|Aw - y\|_2^2 + \frac{\lambda}{2} \|w\|_2^2 = \frac{1}{n} \sum_{i=1}^n \left(\frac{1}{2} (A_{i:}^\top w - y_i)^2 + \frac{\lambda}{2} \|w\|_2^2 \right)$$

Assumptions for Convergence

EXE: Calculate the L_i 's and L_{\max} for

$$1. \quad f(w) = \frac{1}{2n} \|Aw - y\|_2^2 + \frac{\lambda}{2} \|w\|_2^2$$

HINT: A twice differentiable f_i is L_i -smooth if and only if

$$\nabla^2 f_i(w) \preceq L_i I \quad \Leftrightarrow \quad v^\top \nabla^2 f_i(w) v \leq L_i \|v\|^2, \forall v$$

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$$\nabla^2 f_i(w) = A_{i:} A_{i:}^\top + \lambda \preceq (\|A_{i:}\|_2^2 + \lambda) I = L_i I$$

$$1. \quad f(w) = \frac{1}{2n} \|Aw - y\|_2^2 + \frac{\lambda}{2} \|w\|_2^2 = \frac{1}{n} \sum_{i=1}^n \left(\frac{1}{2} (A_{i:}^\top w - y_i)^2 + \frac{\lambda}{2} \|w\|_2^2 \right)$$

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$$L_{\max} = \max_{i=1, \dots, n} (\|A_{i:}\|_2^2 + \lambda) = \max_{i=1, \dots, n} \|A_{i:}\|_2^2 + \lambda$$

Assumptions for Convergence

EXE: Calculate the L_i 's and L_{\max} for

$$2. \quad f(w) = \frac{1}{n} \sum_{i=1}^n \ln(1 + e^{-y_i \langle w, a_i \rangle}) + \frac{\lambda}{2} \|w\|_2^2$$

Assumptions for Convergence

EXE: Calculate the L_i 's and L_{\max} for

$$2. \quad f(w) = \frac{1}{n} \sum_{i=1}^n \ln(1 + e^{-y_i \langle w, a_i \rangle}) + \frac{\lambda}{2} \|w\|_2^2$$

$$2. \quad f_i(w) = \ln(1 + e^{-y_i \langle w, a_i \rangle}) + \frac{\lambda}{2} \|w\|_2^2,$$

Assumptions for Convergence

EXE: Calculate the L_i 's and L_{\max} for

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$$2. \quad f_i(w) = \ln(1 + e^{-y_i \langle w, a_i \rangle}) + \frac{\lambda}{2} \|w\|_2^2,$$

$$\nabla f_i(w) = \frac{-y_i a_i e^{-y_i \langle w, a_i \rangle}}{1 + e^{-y_i \langle w, a_i \rangle}} + \lambda w$$

$$\begin{aligned} \nabla^2 f_i(w) &= a_i a_i^\top \left(\frac{(1 + e^{-y_i \langle w, a_i \rangle}) e^{-y_i \langle w, a_i \rangle}}{(1 + e^{-y_i \langle w, a_i \rangle})^2} - \frac{e^{-2y_i \langle w, a_i \rangle}}{(1 + e^{-y_i \langle w, a_i \rangle})^2} \right) + \lambda I \\ &= a_i a_i^\top \frac{e^{-y_i \langle w, a_i \rangle}}{(1 + e^{-y_i \langle w, a_i \rangle})^2} + \lambda I \quad \preceq \quad \left(\frac{\|a_i\|_2^2}{4} + \lambda \right) I = L_i I \end{aligned}$$

Relationship between smoothness constants 41

EXE: Let f be differentiable and convex. Show that $f(w)$ is L -smooth with

$$L = \max_{w \in \mathbb{R}^d} \lambda_{\max}(\nabla^2 f(w))$$

Thus $f_i(w)$ is L_i -smooth with $L_i = \max_{w \in \mathbb{R}^d} \lambda_{\max}(\nabla^2 f_i(w))$ show that

$$L \leq \frac{1}{n} \sum_{i=1}^n L_i \leq L_{\max} := \max_{i=1, \dots, n} L_i$$

Relationship between smoothness constants 42

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$$L \leq \frac{1}{n} \sum_{i=1}^n L_i \leq L_{\max} := \max_{i=1, \dots, n} L_i$$

Proof: From the Hessian definition of smoothness

$$\nabla^2 f(w) \preceq \lambda_{\max}(\nabla^2 f(w))I \preceq \max_{w \in \mathbb{R}^d} \lambda_{\max}(\nabla^2 f(w))I$$

Furthermore

$$\lambda_{\max}(\nabla^2 f(w)) = \lambda_{\max} \left(\frac{1}{n} \sum_{i=1}^n \nabla^2 f_i(w) \right) \leq \frac{1}{n} \sum_{i=1}^n \lambda_{\max}(\nabla^2 f_i(w)) \leq \frac{1}{n} \sum_{i=1}^n L_i$$

The final result now follows by taking the max over w , then max over i

Theorem.

Let f be μ -strongly quasi-convex and f_i be L_i -smooth.

If $0 < \alpha \leq \frac{1}{2L_{\max}}$ then the iterates of the SGD 0.0 satisfy

$$\mathbb{E} [\|w^t - w^*\|_2^2] \leq (1 - \alpha\mu)^t \|w^0 - w^*\|_2^2 + \frac{2\alpha}{\mu} \sigma^2$$

EXE: The steps of the proof are given in the SGD_proof exercise list for homework!

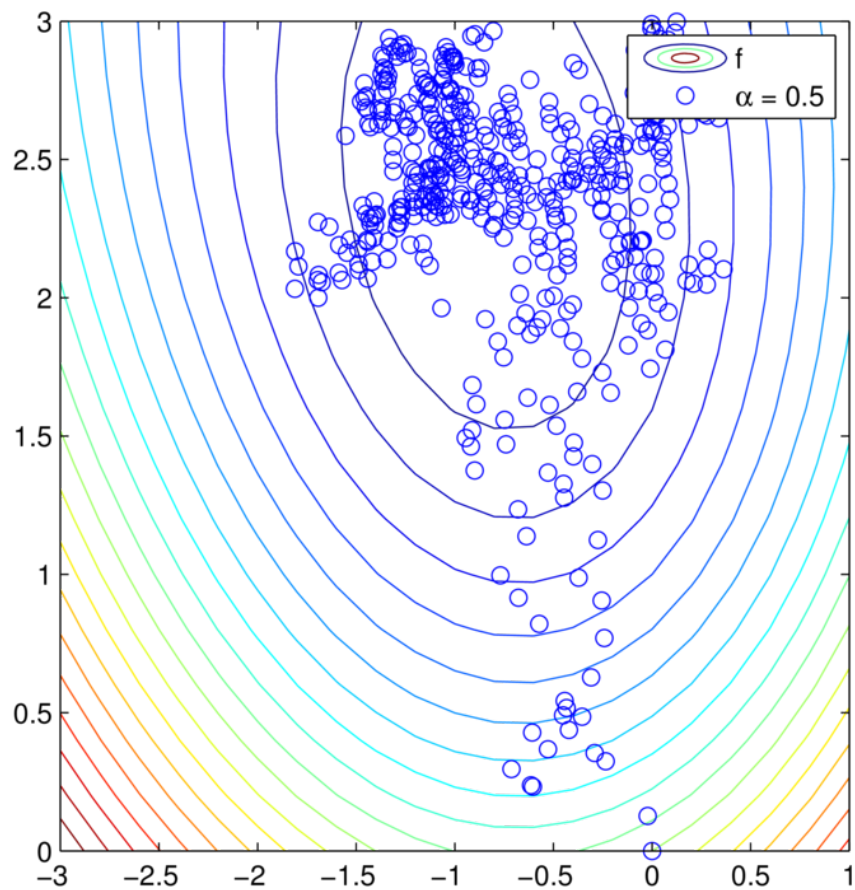


RMG, N. Loizou, X. Qian, A. Sailanbayev, E. Shulgin, P. Richtarik (2019) ICML 2019
SGD: General Analysis and Improved Rates.

Stochastic Gradient Descent

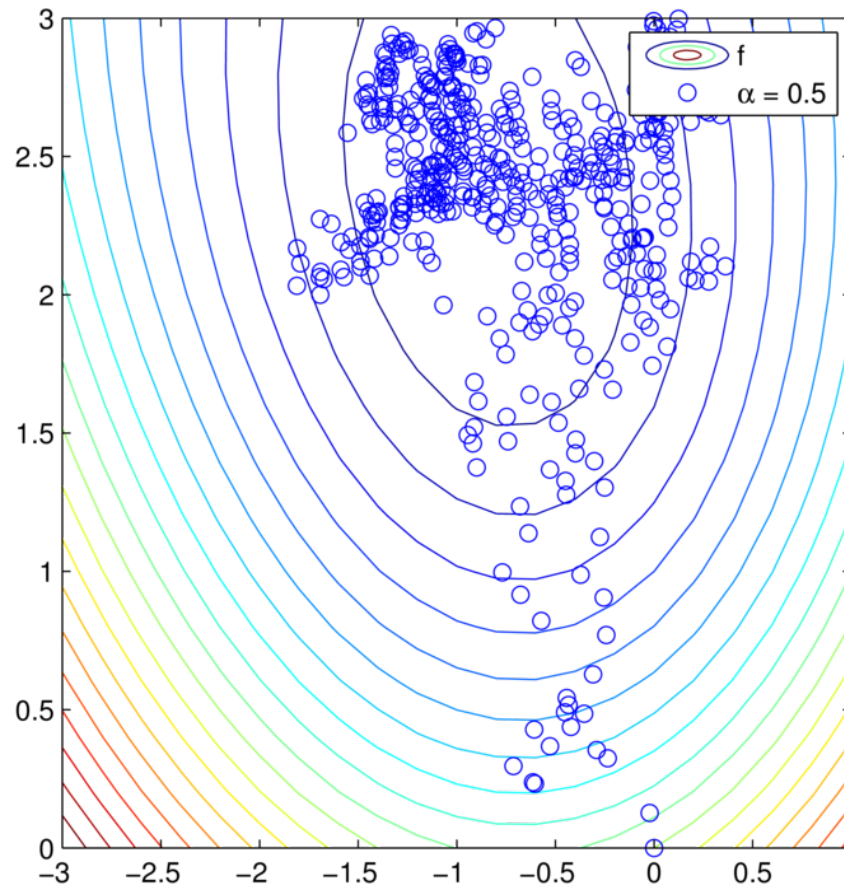
$\alpha = 0.5$

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Stochastic Gradient Descent

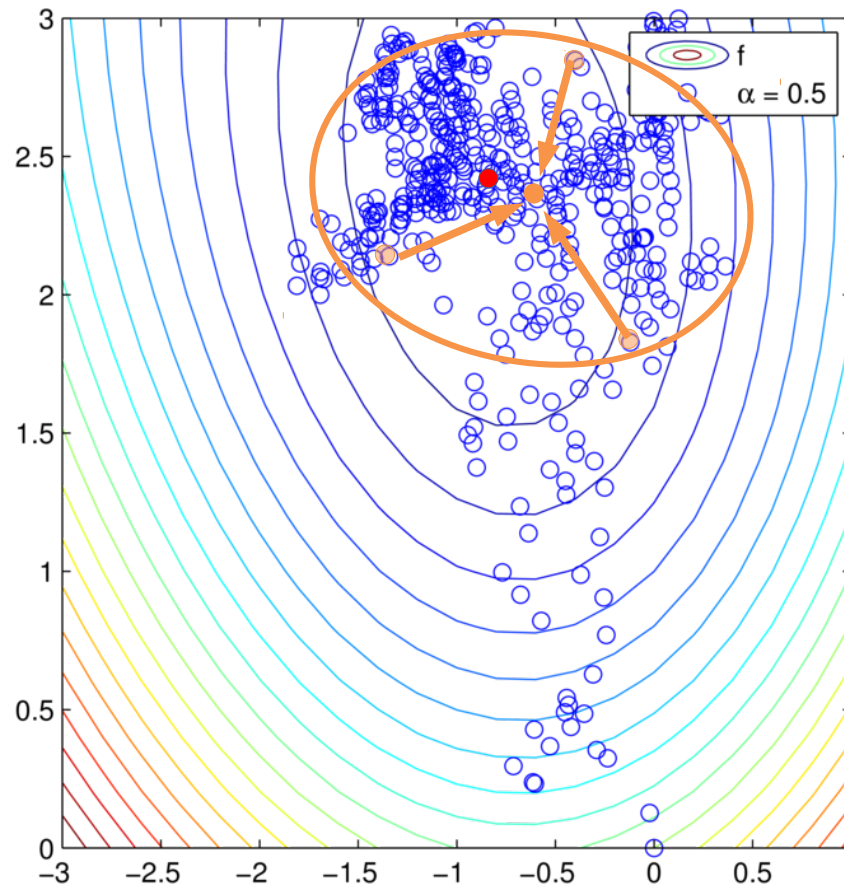
$\alpha = 0.5$



1) Start with big steps and end with smaller steps

Stochastic Gradient Descent

$\alpha = 0.5$



1) Start with big steps and end with smaller steps

2) Try averaging the points

SGD 1.0: Decreasing stepsize


Set $w^0 = 0$

Choose $\alpha_t > 0$, $\alpha_t \rightarrow 0$, $\sum_{t=0}^{\infty} \alpha_t = \infty$
for $t = 0, 1, 2, \dots, T - 1$

sample $j \in \{1, \dots, n\}$

$$w^{t+1} = w^t - \alpha_t \nabla f_j(w^t)$$

Output w^T



Shrinking
Stepsize

SGD shrinking stepsize

48

SGD 1.0: Decreasing stepsize


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Shrinking
Stepsize

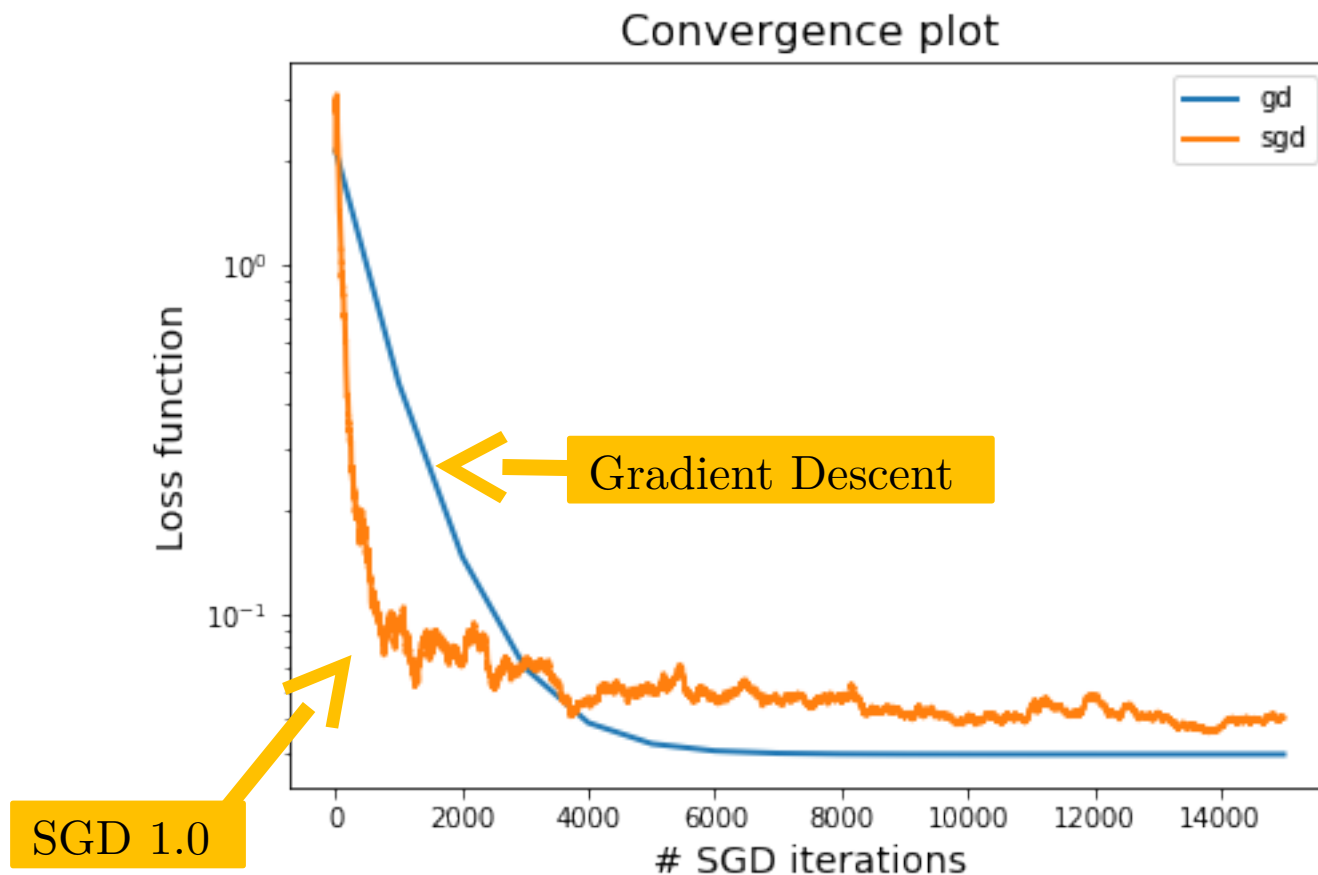
How should we
sample j ?

How fast $\alpha_t \rightarrow 0$?

Does this converge?

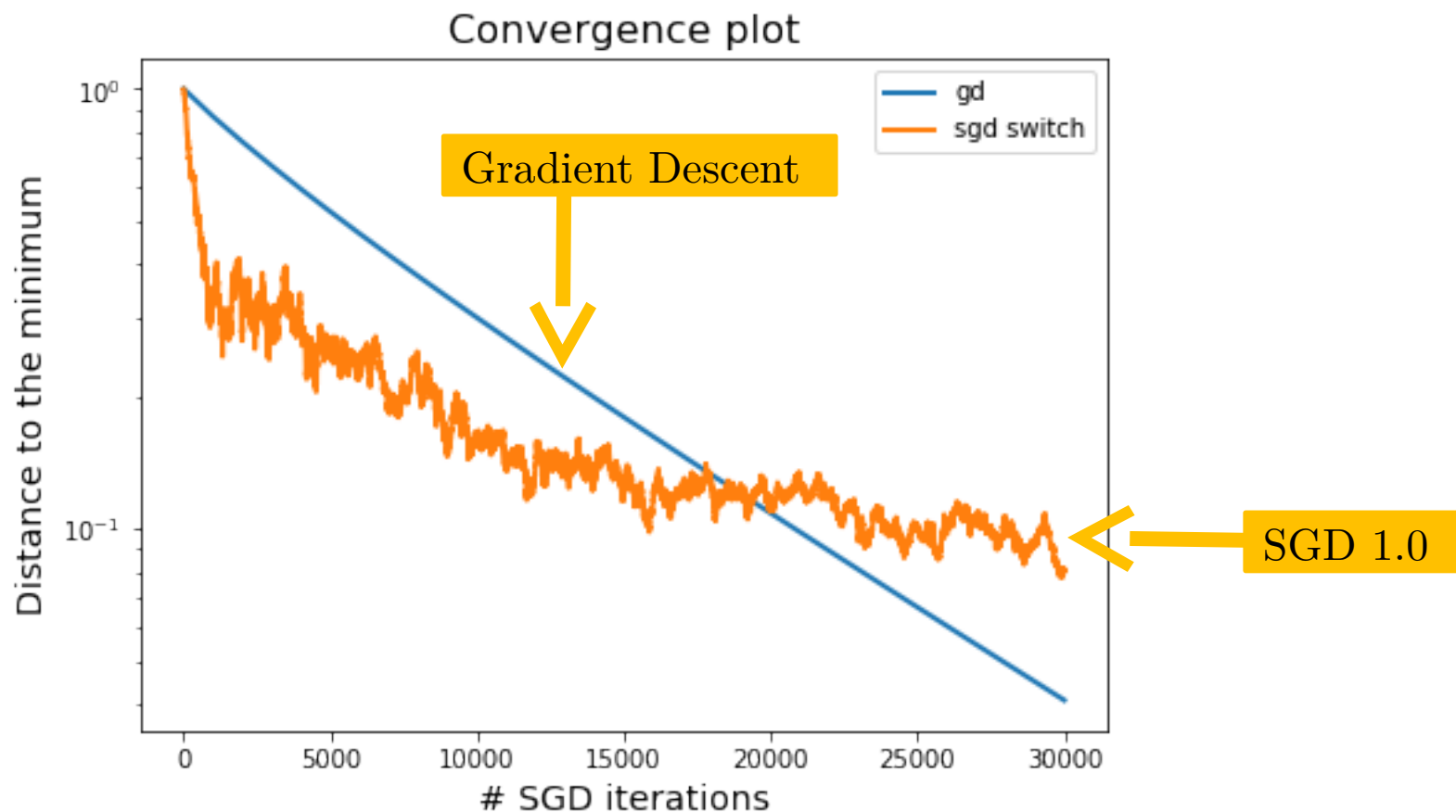
SGD with shrinking stepsize


Compared with Gradient Descent



SGD with shrinking stepsize

Compared with Gradient Descent




$$L_{\max} := \max_{i=1,\dots,n} L_i$$


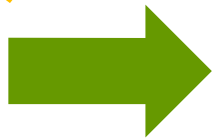
Theorem for shrinking stepsizes

Let f be μ -strongly quasi-convex and f_i be L_i -smooth.
Let $\mathcal{K} := L_{\max}/\mu$ and let

$$\alpha^t = \begin{cases} \frac{1}{2L_{\max}} & \text{for } t \leq 4\lceil\mathcal{K}\rceil \\ \frac{2t+1}{(t+1)^2\mu} & \text{for } t > 4\lceil\mathcal{K}\rceil. \end{cases}$$

If $t \geq 4\lceil\mathcal{K}\rceil$, then SGD 1.0 satisfies

$$\mathbb{E}\|w^t - w^*\|^2 \leq \frac{\sigma^2}{\mu^2} \frac{8}{t} + \frac{16}{e^2} \frac{\lceil\mathcal{K}\rceil^2}{t^2} \|w^0 - w^*\|^2$$


$$O\left(\frac{1}{t}\right)$$


$$\text{Iteration complexity } O\left(\frac{1}{\epsilon}\right)$$

$$L_{\max} := \max_{i=1,\dots,n} L_i$$

Theorem for shrinking stepsizes

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If $t \geq 4\lceil\mathcal{K}\rceil$, then SGD 1.0 satisfies

$$\alpha^t = O(1/(t+1))$$

$$\mathbb{E}\|w^t - w^*\|^2 \leq \frac{\sigma^2}{\mu^2} \frac{8}{t} + \frac{16}{e^2} \frac{\lceil\mathcal{K}\rceil^2}{t^2} \|w^0 - w^*\|^2$$

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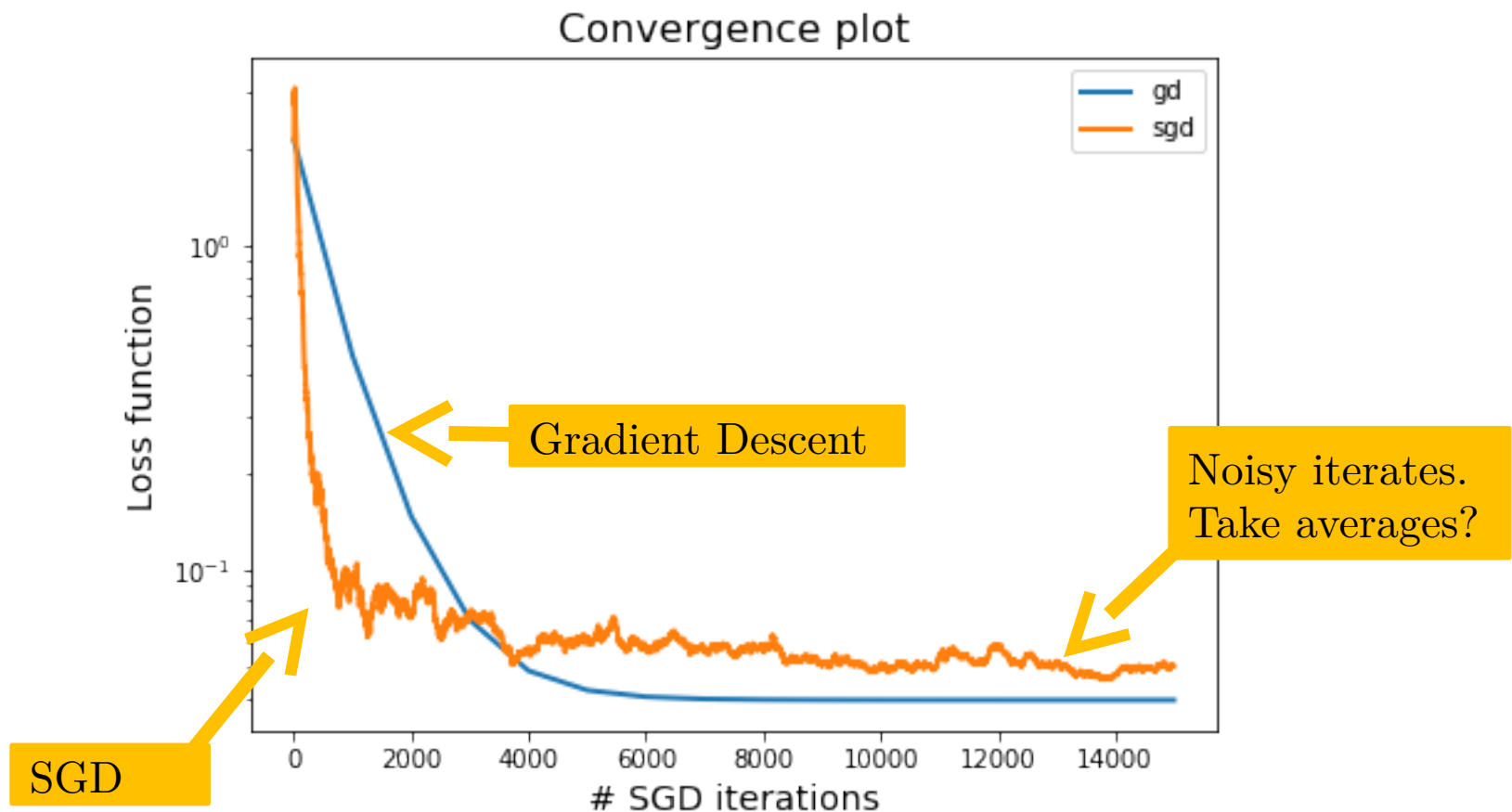
$$O\left(\frac{1}{t}\right)$$



$$\text{Iteration complexity } O\left(\frac{1}{\epsilon}\right)$$

In practice often $\alpha^t = C/(t+1)$ where C is tuned

Stochastic Gradient Descent Compared with Gradient Descent



SGD with (late start) averaging

SGDA 1.1

Set $w^0 = 0$

Choose $\alpha_t > 0$, $\alpha_t \rightarrow 0$, $\sum_{t=0}^{\infty} \alpha_t = \infty$

Choose averaging start $s_0 \in \mathbb{N}$

for $t = 0, 1, 2, \dots, T - 1$

 sample $j \in \{1, \dots, n\}$

$$w^{t+1} = w^t - \alpha_t \nabla f_j(w^t)$$

 if $t > s_0$

$$\bar{w} = \frac{1}{t - s_0} \sum_{i=s_0}^t w^i$$

 else: $\bar{w} = w$

Output \bar{w}



B. T. Polyak and A. B. Juditsky, SIAM Journal on Control and Optimization (1992)

Acceleration of stochastic approximation by averaging

SGD with (late start) averaging

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else: $\bar{w} = w$

Output \bar{w}

This is not efficient. How to make this efficient?

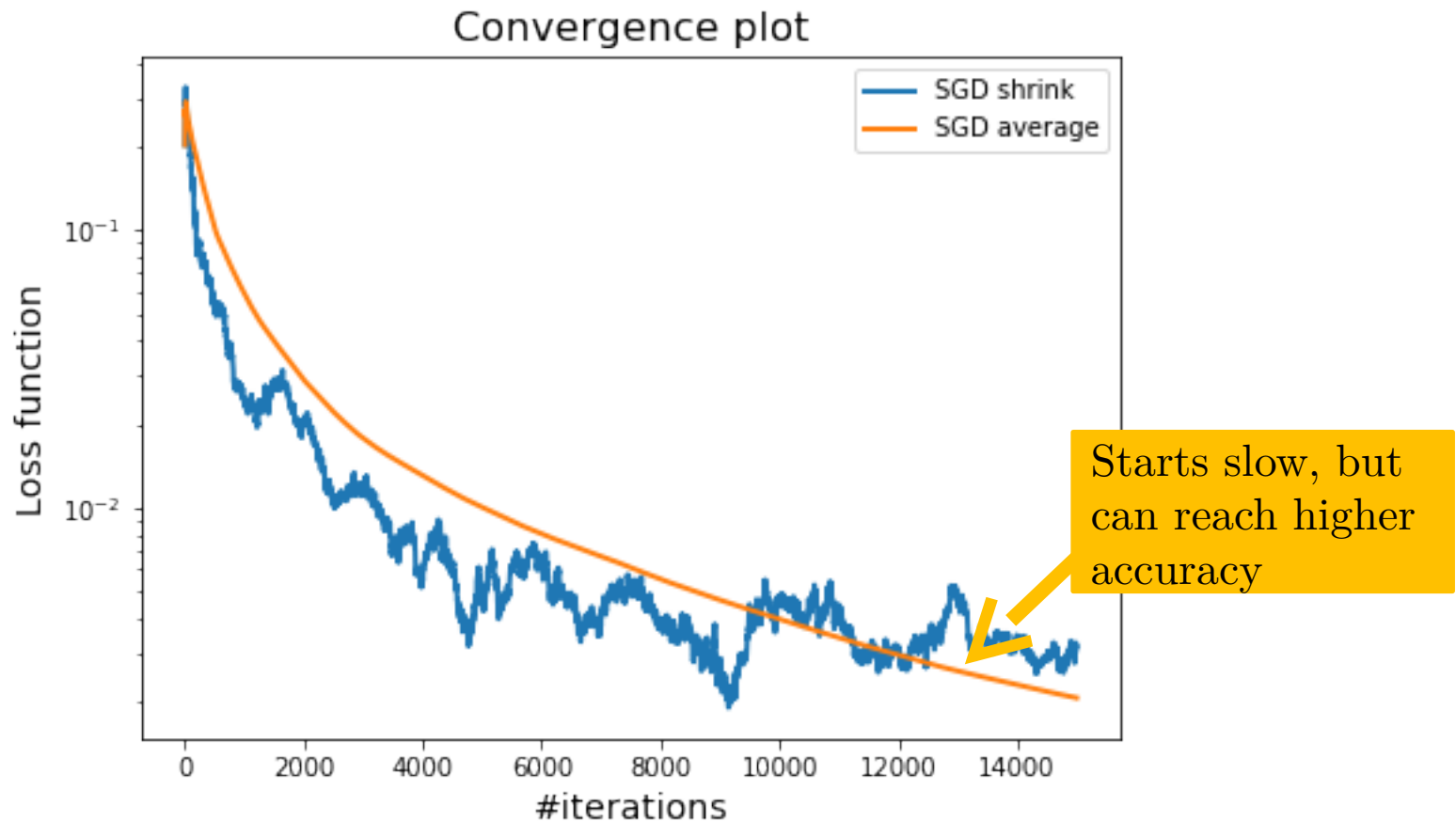


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Acceleration of stochastic approximation by averaging

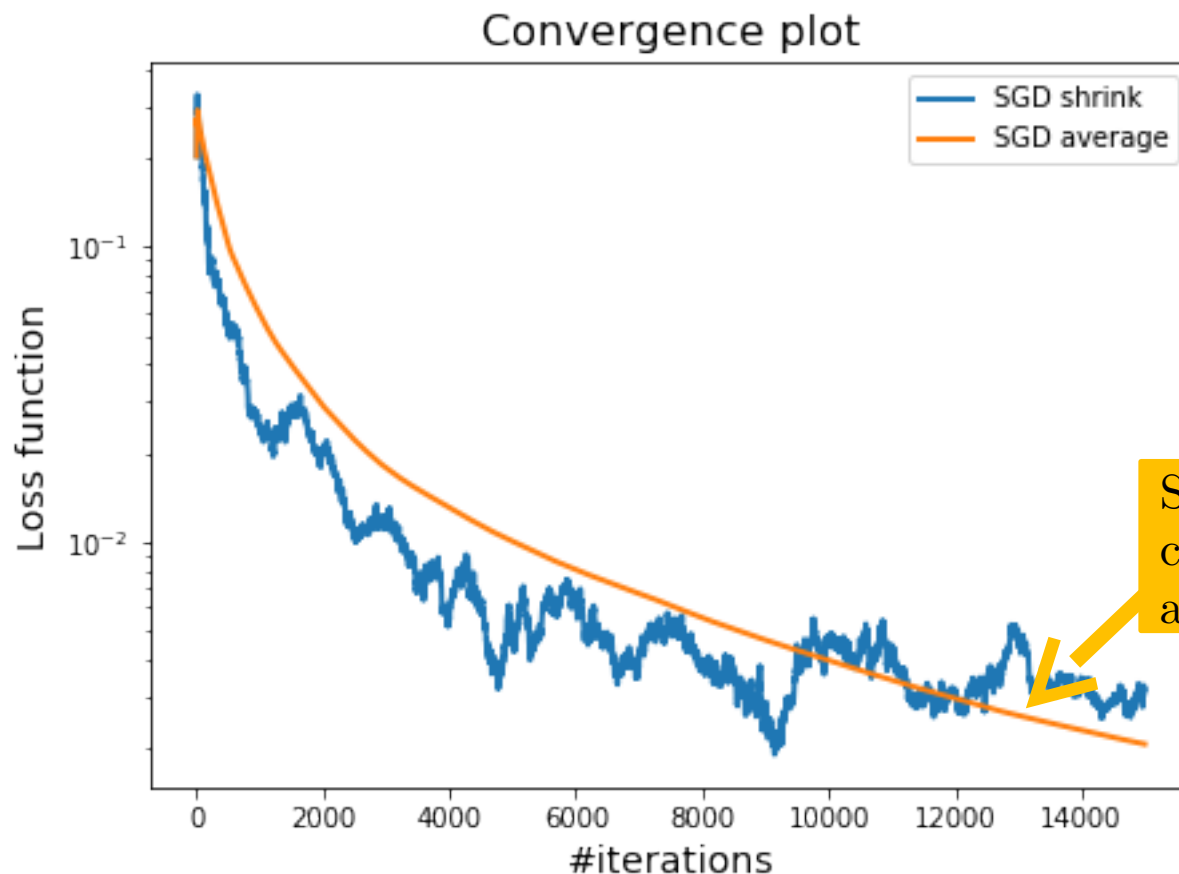
Stochastic Gradient Descent

With and without averaging



Stochastic Gradient Descent

With and without averaging

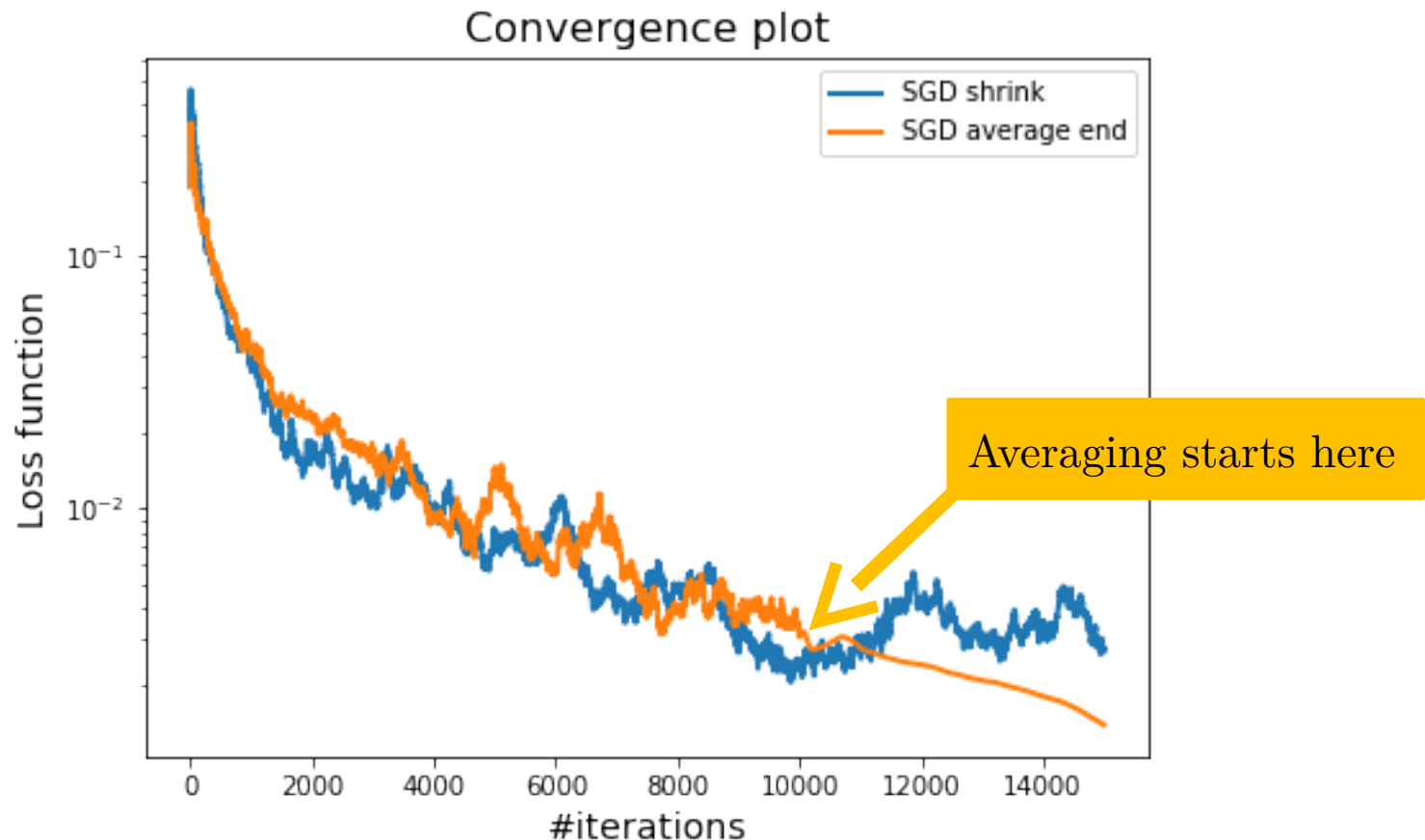


Starts slow, but
can reach higher
accuracy

Only use
averaging
towards the end?

Stochastic Gradient Descent

Averaging the last few iterates



Comparison GD and SGD for strongly convex

61

	SGD	GD
Iteration complexity	$O\left(\frac{1}{\epsilon}\right)$	$O\left(\log\left(\frac{1}{\epsilon}\right)\right)$

Comparison GD and SGD for strongly convex

	SGD	GD
Iteration complexity	$O\left(\frac{1}{\epsilon}\right)$	$O\left(\log\left(\frac{1}{\epsilon}\right)\right)$
Cost of an iteration	$O(1)$	$O(n)$

Comparison GD and SGD for strongly convex

63

	SGD	GD
Iteration complexity	$O\left(\frac{1}{\epsilon}\right)$	$O\left(\log\left(\frac{1}{\epsilon}\right)\right)$
Cost of an iteration	$O(1)$	$O(n)$
Total complexity*	$O\left(\frac{1}{\epsilon}\right)$	$O\left(n \log\left(\frac{1}{\epsilon}\right)\right)$

Comparison GD and SGD for strongly convex

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*Total complexity = (Iteration complexity) \times (Cost of an iteration)

Comparison GD and SGD for strongly convex

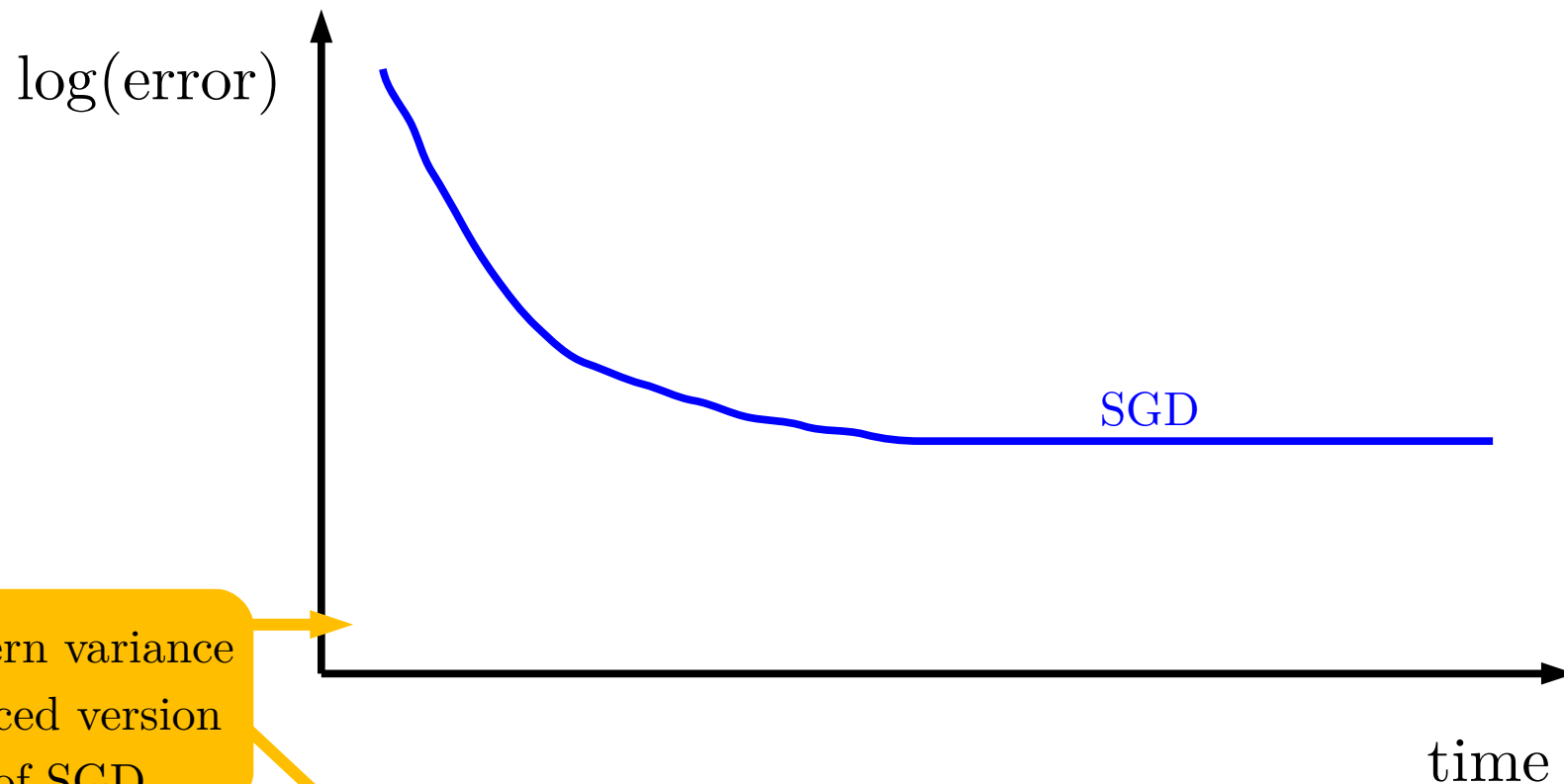
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What happens if ϵ is small?

What happens if n is big?

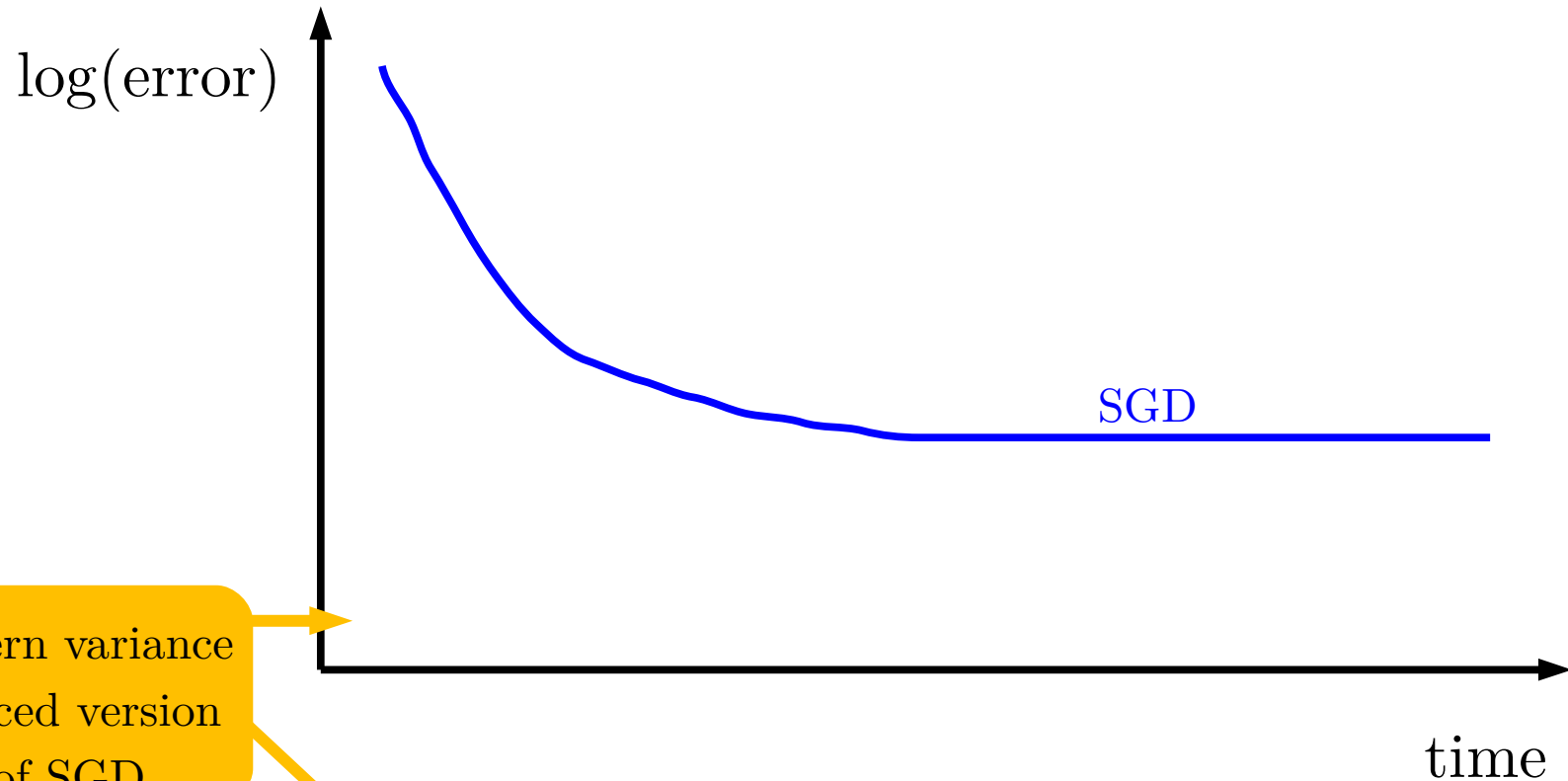
*Total complexity = (Iteration complexity) \times (Cost of an iteration)

Comparison SGD vs GD



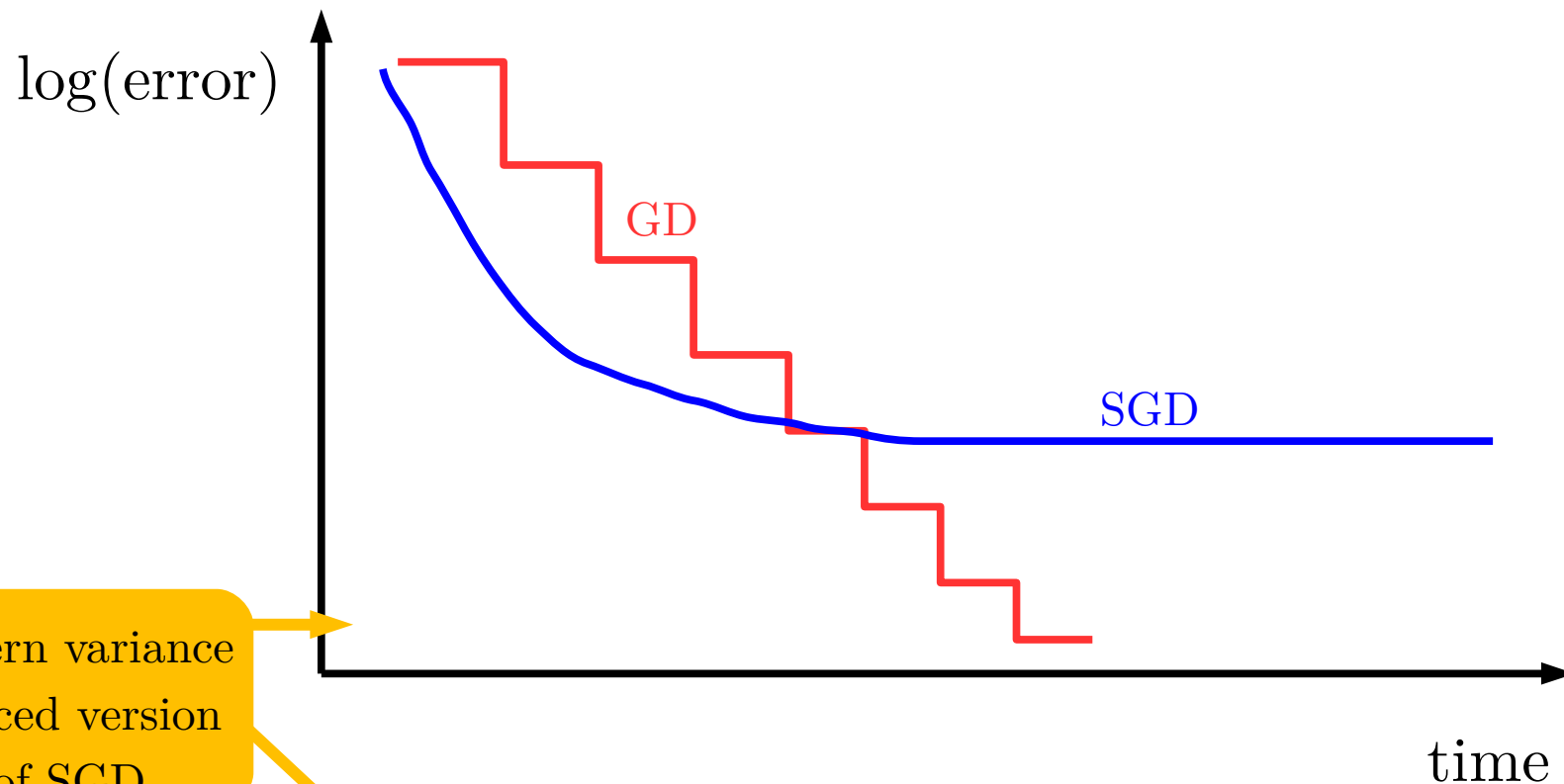
M. Schmidt, N. Le Roux, F. Bach (2016)
Mathematical Programming
Minimizing Finite Sums with the Stochastic Average Gradient.

Comparison SGD vs GD



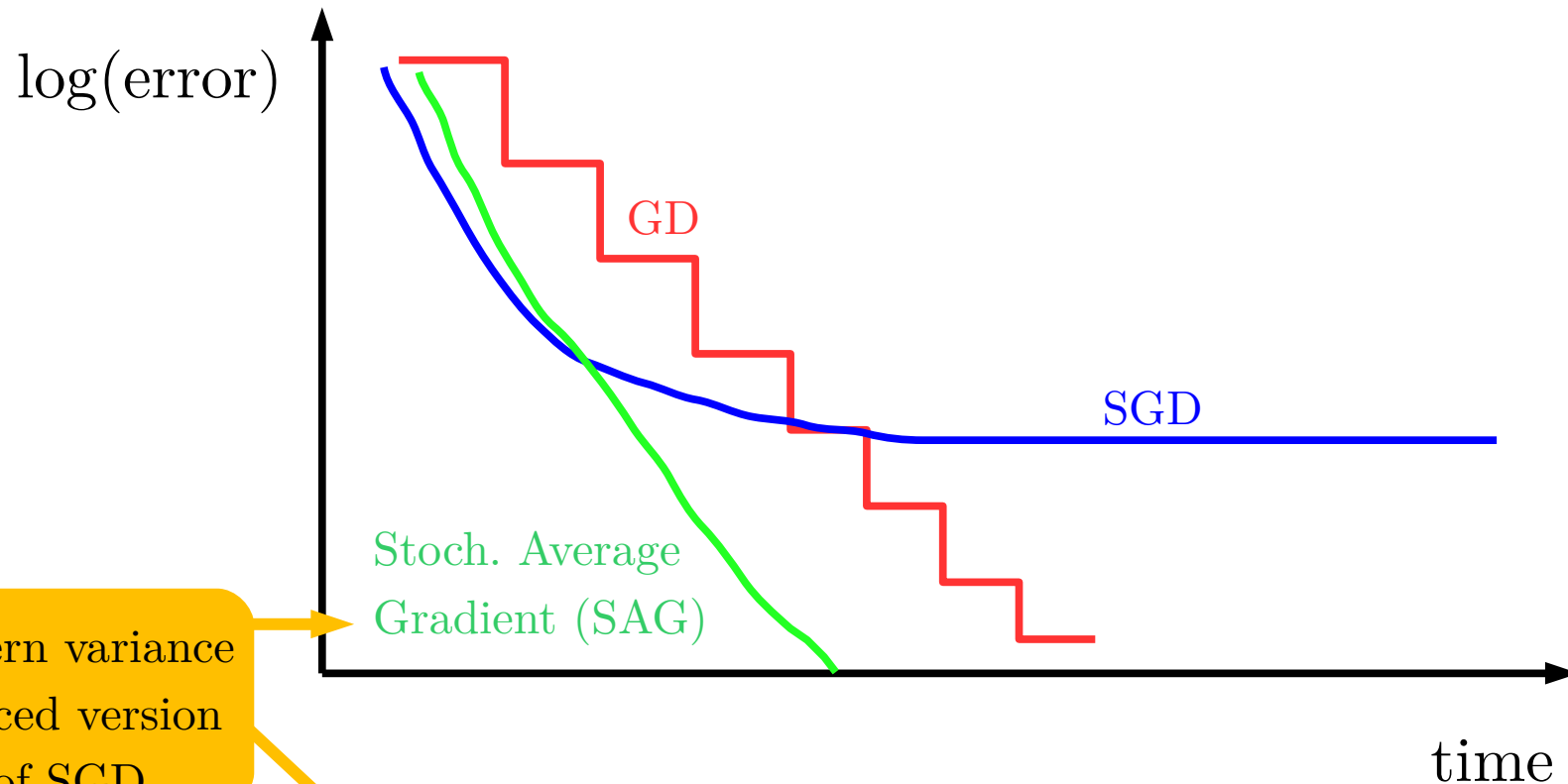
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Mathematical Programming
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Comparison SGD vs GD



Stoch. Average
Gradient (SAG)

SGD

GD

time

Modern variance
reduced version
of SGD



M. Schmidt, N. Le Roux, F. Bach (2016)
Mathematical Programming
**Minimizing Finite Sums with the Stochastic Average
Gradient.**

20 min tea time break?

Practical SGD for Sparse Data

Lazy SGD updates for Sparse Data

Finite Sum Training Problem

L2 regularizer +
linear hypothesis

$$\min_{w \in \mathbf{R}^d} \frac{1}{n} \sum_{i=1}^n \ell(\langle w, x^i \rangle, y^i) + \frac{\lambda}{2} \|w\|_2^2$$

Assume each data point x^i is s -sparse, how many operations does each SGD step cost?

Lazy SGD updates for Sparse Data

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Assume each data point x^i is s -sparse, how many operations does each SGD step cost?

$$\begin{aligned} w^{t+1} &= w^t - \alpha_t (\ell'(\langle w^t, x^i \rangle, y^i) x^i + \lambda w^t) \\ &= (1 - \lambda \alpha_t) w^t - \alpha_t \ell'(\langle w^t, x^i \rangle, y^i) x^i \end{aligned}$$

Lazy SGD updates for Sparse Data

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L2 regularizer +
linear hypothesis

$$\min_{w \in \mathbf{R}^d} \frac{1}{n} \sum_{i=1}^n \ell(\langle w, x^i \rangle, y^i) + \frac{\lambda}{2} \|w\|_2^2$$

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Rescaling
 $O(d)$

+



Addition sparse
vector $O(s)$

=

$O(d)$

Lazy SGD updates for Sparse Data

SGD step

$$w^{t+1} = (1 - \lambda\alpha_t)w^t - \alpha_t\ell'(\langle w^t, x^i \rangle, y^i)x^i$$

EXE: re-write the iterates using $w^t = \beta_t z^t$ where $\beta_t \in \mathbb{R}$, $z^t \in \mathbb{R}^d$

Can you update β_t and z^t so that each iteration is $O(s)$?

Lazy SGD updates for Sparse Data

SGD step

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Can you update β_t and z^t so that each iteration is $O(s)$?

$$\begin{aligned} \beta_{t+1} z^{t+1} &= (1 - \lambda\alpha_t) \beta_t z^t - \alpha_t \ell'(\beta_t \langle z^t, x^i \rangle, y^i) x^i \\ &= (1 - \lambda\alpha_t) \beta_t \left(z^t - \frac{\alpha_t \ell'(\beta_t \langle z^t, x^i \rangle, y^i)}{(1 - \lambda\alpha_t) \beta_t} x^i \right) \end{aligned}$$

Lazy SGD updates for Sparse Data

SGD step

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$$\beta_{t+1} = (1 - \lambda\alpha_t) \beta_t, \quad z^{t+1} = z^t - \frac{\alpha_t \ell'(\beta_t \langle z^t, x^i \rangle, y^i)}{(1 - \lambda\alpha_t) \beta_t} x^i$$

Lazy SGD updates for Sparse Data

SGD step

$$w^{t+1} = (1 - \lambda\alpha_t)w^t - \alpha_t \ell'(\langle w^t, x^i \rangle, y^i) x^i$$

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$O(1)$ scaling +
 $O(s)$ sparse add
 $= O(s)$ update

$$\beta_{t+1} = (1 - \lambda\alpha_t) \beta_t, \quad z^{t+1} = z^t - \frac{\alpha_t \ell'(\beta_t \langle z^t, x^i \rangle, y^i)}{(1 - \lambda\alpha_t) \beta_t} x^i$$

Momentum

Issue with Gradient Descent

Solving the *training problem*: $\min_{w \in \mathbb{R}^d} \frac{1}{n} \sum_{i=1}^n f_i(w) =: f(w)$

Baseline method: Gradient Descent (GD)

$$w^{t+1} = w^t - \gamma \nabla f(w^t)$$

Step size/
Learning rate

Why GD and the the Issues

Local rate of change

$$\Delta(d) := \lim_{s \rightarrow 0^+} \frac{f(x + ds) - f(x)}{s}$$

Max local rate

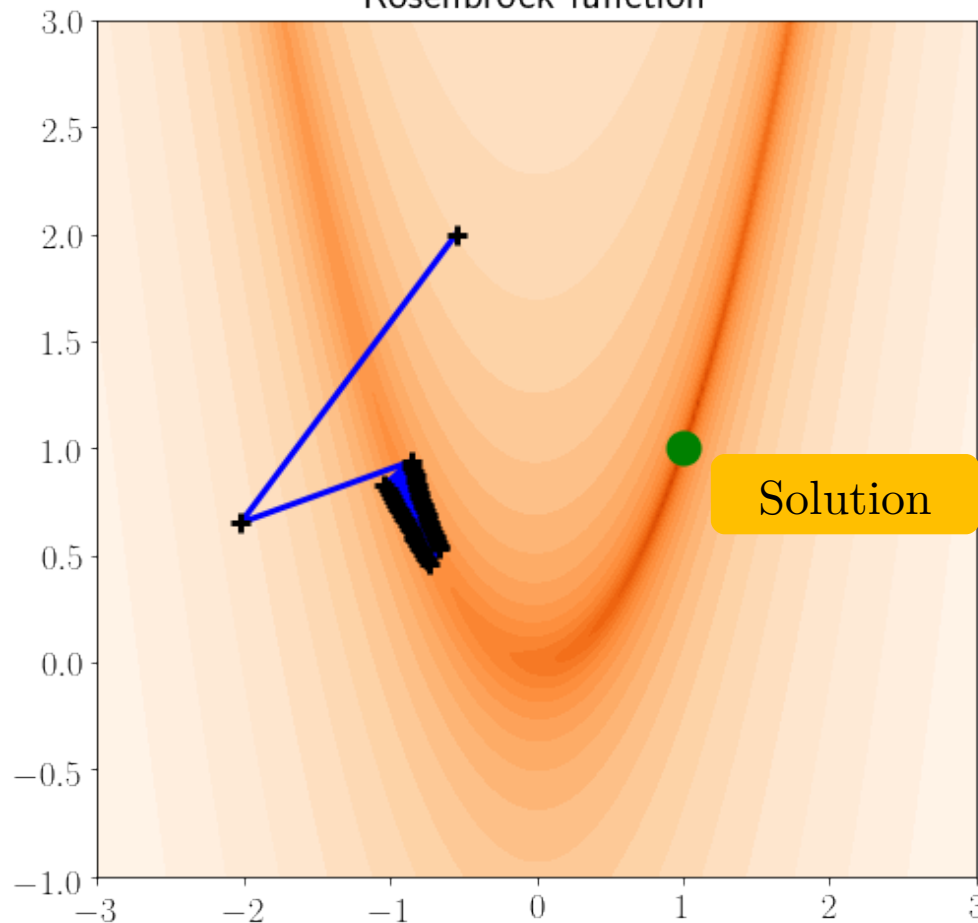
$$\frac{\nabla f(w^t)}{\|\nabla f(w^t)\|} := \max_{w \in \mathbb{R}^d} \Delta(d) \quad \text{subject to} \quad \|d\| = 1$$

GD is the “steepest descent”

Issue with Gradient Descent

$$f(x_1, x_2) = 100(x_1 - x_2^2)^2 + (1 - x_2)^2$$

Rosenbrock function



Get's stuck in "flat" valleys



Give momentum to keep going

Adding some Momentum to GD

Heavy Ball Method:

$$w^{t+1} = w^t - \gamma \nabla f(w^t) + \beta(w^t - w^{t-1})$$

Adds “Inertia” to update

Adding some Momentum to GD

Heavy Ball Method:

$$w^{t+1} = w^t - \gamma \nabla f(w^t) + \beta(w^t - w^{t-1})$$



Adds “Inertia” to update

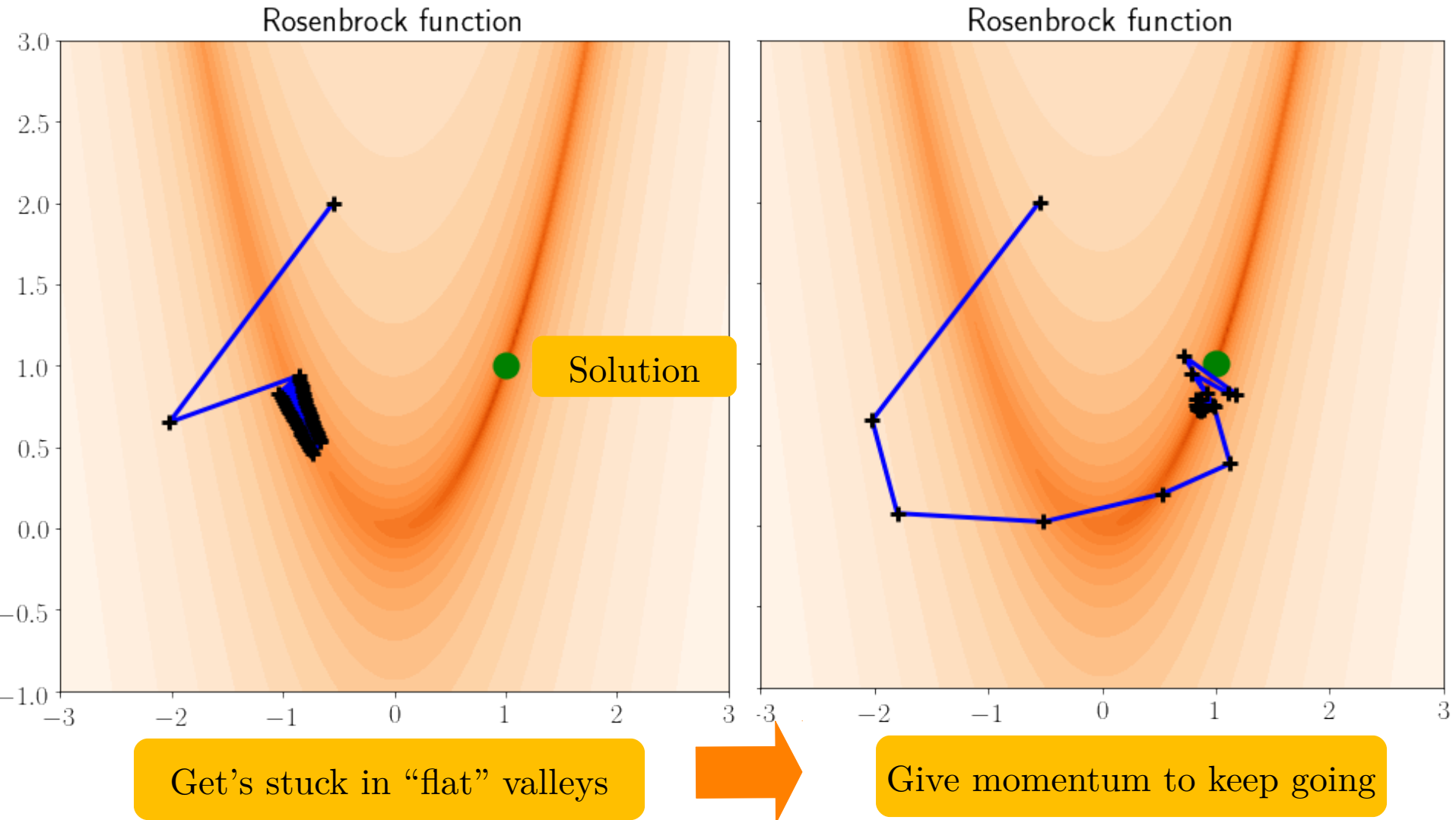
GD with momentum (GDm):

Adds “Momentum”
to update

$$m^t = \beta m^{t-1} + \nabla f(w^t)$$

$$w^{t+1} = w^t - \gamma m^t$$

Issue with Gradient Descent



GDm and Heavy Ball Equivalence

GD with momentum:

$$\begin{aligned}m^t &= \beta m^{t-1} + \nabla f(w^t) \\w^{t+1} &= w^t - \gamma m^t\end{aligned}$$

GDm and Heavy Ball Equivalence

GD with momentum:

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$$\begin{aligned} w^{t+1} &= w^t - \gamma m^t \\ &= w^t - \gamma (\beta m^{t-1} + \nabla f(w^t)) \\ &= w^t - \gamma \nabla f(w^t) - \gamma \beta m^{t-1} \\ &= w^t - \gamma \nabla f(w^t) + \frac{\gamma \beta}{\gamma} (w^t - w^{t-1}) \end{aligned}$$

GDm and Heavy Ball Equivalence

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$$m^{t-1} = -\frac{1}{\gamma} (w^t - w^{t-1})$$

GDm and Heavy Ball Equivalence

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$$m^{t-1} = -\frac{1}{\gamma}(w^t - w^{t-1})$$

$$w^{t+1} = w^t - \gamma \nabla f(w^t) + \beta(w^t - w^{t-1})$$

GDm and Heavy Ball Equivalence

GD with momentum:

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$$m^{t-1} = -\frac{1}{\gamma}(w^t - w^{t-1})$$

Heavy Ball Method:

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Convergence of Gradient Descent with Momentum

96




Polyak 1964

Theorem Let f be μ -strongly convex and L -smooth, that is

stepsize $\mu I \preceq \nabla^2 f(w) \preceq LI, \quad \forall w \in \mathbb{R}^d$

If $\gamma = \frac{4}{(\sqrt{L} + \sqrt{\mu})^2}$ and $\beta = \frac{\sqrt{L} - \sqrt{\mu}}{\sqrt{L} + \sqrt{\mu}}$ then SGDm converges

momentum parameter

 $\|w^t - w^*\| \leq \left(\frac{\sqrt{\kappa} - 1}{\sqrt{\kappa} + 1} \right)^t \|w^0 - w^*\|$

$\kappa := L/\mu$

Convergence of Gradient Descent with Momentum

97



Polyak 1964

Theorem Let f be μ -strongly convex and L -smooth, that is

stepsize $\mu I \preceq \nabla^2 f(w) \preceq LI, \quad \forall w \in \mathbb{R}^d$

If $\gamma = \frac{4}{(\sqrt{L} + \sqrt{\mu})^2}$ and $\beta = \frac{\sqrt{L} - \sqrt{\mu}}{\sqrt{L} + \sqrt{\mu}}$ then SGDm converges

momentum parameter

$\Rightarrow \|w^t - w^*\| \leq \left(\frac{\sqrt{\kappa} - 1}{\sqrt{\kappa} + 1} \right)^t \|w^0 - w^*\|$

$\kappa := L/\mu$

Corollary $t \geq \frac{1}{\sqrt{\kappa} + 1} \log \left(\frac{1}{\epsilon} \right) \Rightarrow \frac{\|w^t - w^*\|}{\|w^0 - w^*\|} \leq \epsilon$

Proof sketch: GDm convergence

Fundamental Theorem of Calculus

$$\int_{s=0}^1 \underbrace{\nabla^2 f(w_s)}_{w_s := w^* + s(w^t - w^*)} ds (w^t - w^*) = \nabla f(w^t) - \nabla f(w^*) = \nabla f(w^t)$$

$$w_s := w^* + s(w^t - w^*)$$

Proof sketch: GDm convergence

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$$w_s := w^* + s(w^t - w^*)$$

$$\begin{aligned} w^{t+1} - w^* &= w^t - w^* - \gamma \nabla f(w^t) + \beta(w^t - w^{t-1}) \quad \boxed{+w^* - w^*} \\ &= \left(I - \gamma \int_{s=0}^1 \nabla^2 f(w^s) \right) (w^t - w^*) + \beta(w^t - w^{t-1}) \\ &= \left((1 + \beta)I - \gamma \int_{s=0}^1 \nabla^2 f(w^s) \right) (w^t - w^*) - \beta(w^{t-1} - w^*) \end{aligned}$$

Proof sketch: GDm convergence

100

Fundamental Theorem of Calculus

$$\int_{s=0}^1 \underbrace{\nabla^2 f(w_s)}_{w_s := w^* + s(w^t - w^*)} ds (w^t - w^*) = \nabla f(w^t) - \nabla f(w^*) = \nabla f(w^t)$$

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Proof sketch: GDm convergence

101

Fundamental Theorem of Calculus

$$\int_{s=0}^1 \underbrace{\nabla^2 f(w_s)}_{w_s := w^* + s(w^t - w^*)} ds (w^t - w^*) = \nabla f(w^t) - \nabla f(w^*) = \nabla f(w^t)$$

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Depends on past. Difficult recurrence

Proof: Convergence of Heavy Ball

$$z^{t+1} = \begin{bmatrix} w^{t+1} - w^* \\ w^t - w^* \end{bmatrix} \in \mathbb{R}^{2d}$$

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Simple recurrence!

$$\|z^{t+1}\| \leq \left\| \begin{bmatrix} A_s & -I\beta \\ I & 0 \end{bmatrix} \right\| \|z^t\|$$

Proof: Convergence of Heavy Ball

$$\|z^{t+1}\| \leq \left\| \begin{bmatrix} A_s & -I\beta \\ I & 0 \end{bmatrix} \right\| \|z^t\|$$

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EXE on Eigenvalues:

If $\gamma = \frac{4}{(\sqrt{L} + \sqrt{\mu})^2}$ and $\beta = \frac{\sqrt{L} - \sqrt{\mu}}{\sqrt{L} + \sqrt{\mu}}$ then

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Adding Momentum to SGD



Rumelhart, Hinton,
Geoffrey, Ronald,
1986, Nature

Stochastic Heavey Ball Method:

$$w^{t+1} = w^t - \gamma \nabla f_{j_t}(w^t) + \beta(w^t - w^{t-1})$$



Adds “Inertia” to update

SGD with momentum (SGDm):

$$m^t = \beta m^{t-1} + \nabla f_{j_t}(w^t)$$

$$w^{t+1} = w^t - \gamma m^t$$

Sampled i.i.d
 $j \in \{1, \dots, n\}$
 $j \sim \frac{1}{n}$

SGDm and Averaging

$$\begin{aligned} m^t &= \beta m^{t-1} + \nabla f_{j_t}(w^t) \\ &= \beta m^{t-2} + \nabla f_{j_t}(w^t) + \beta \nabla f_{j_{t-1}}(w^{t-1}) \\ &= \sum_{i=1}^t \beta^i \nabla f_{j_{t-i}}(w^{t-i}) \end{aligned}$$

SGDm and Averaging

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SGD with momentum (SGDm):

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SGDm and Averaging

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SGD with momentum (SGDm):

$$w^{t+1} = w^t - \gamma \sum_{i=1}^t \beta^i \nabla f_{j_{t-i}}(w^{t-i})$$

Acts like an approximate variance reduction since

SGDm and Averaging

$$\begin{aligned}
 m^t &= \beta m^{t-1} + \nabla f_{j_t}(w^t) \\
 &= \beta m^{t-2} + \nabla f_{j_t}(w^t) + \beta \nabla f_{j_{t-1}}(w^{t-1}) \\
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Acts like an approximate variance reduction since

$$\sum_{i=1}^t \beta^i \nabla f_{j_{t-i}}(w^{t-i}) \approx \sum_{i=1}^n \frac{1}{n} \nabla f_i(w^t) = \nabla f(w^t)$$

Why Machine Learners Like SGD

Why Machine Learners like SGD

Though we solve:

$$\min_{w \in \mathbf{R}^d} \frac{1}{n} \sum_{i=1}^n \ell(h_w(x^i), y^i) + \lambda R(w)$$

We want to solve:

The statistical learning problem:

Minimize the expected loss over an *unknown* expectation

$$\min_{w \in \mathbf{R}^d} \mathbb{E}_{(x,y) \sim \mathcal{D}} [\ell(h_w(x), y)]$$

SGD can solve the
statistical learning problem!

Why Machine Learners like SGD

The statistical learning problem:

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SGD $\infty.0$ for learning

Set $w^0 = 0$, $\alpha > 0$

for $t = 0, 1, 2, \dots, T - 1$

sample $(x, y) \sim \mathcal{D}$

calculate $v_t \in \partial \ell(h_{w^t}(x), y)$

$w^{t+1} = w^t - \alpha v_t$

Output $\bar{w}^T = \frac{1}{T} \sum_{t=1}^T w^t$

Bring laptops for Thursday TD !



RMG, Nicolas Loizou, Xun Qian, Alibek Sailanbayev, Egor Shulgin and Peter Richtárik (2019), ICML
SGD: general analysis and improved rates



RMG, P. Richtarik, F. Bach (2018), preprint online
Stochastic quasi-gradient methods: Variance reduction via Jacobian sketching



N. Gazagnadou, RMG, J. Salmon (2019) , ICML 2019.
Optimal mini-batch and step sizes for SAGA



O. Sebbouh, N. Gazagnadou, S. Jelassi, F. Bach, RMG
Neurips 2019, preprint online. **Towards closing the gap between the theory and practice of SVRG**