



Elektrobit



UDACITY

# Technical Safety Concept Lane Assistance

Document Version: **v1.1**

Template Version 1.1, Released on 2018-07-2



# Document history

[Instructions: Fill in the date, version and description fields. You can fill out the Editor field with your name if you want to do so. Keep track of your editing as if this were a real world project.

For example, if this were your first draft or first submission, you might say version 1.0. If this is a second submission attempt, then you'd add a second line with a new date and version 2.0]

Date	Version	Editor	Description
7/2/2018	V1.1	Aaron li	First submission

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## Purpose of the Technical Safety Concept

[Instructions: Answer what is the purpose of a technical safety concept?]

## Inputs to the Technical Safety Concept

### Functional Safety Requirements

[Instructions: Provide the functional safety requirements derived in the functional safety concept ]

ID	Functional Safety Requirement	ASIL	Fault Tolerant Time Interval	Safe State
Functional Safety Requirement 01-01	LDW shall has a lower limit so that the driver can capture the haptic signal, and not miss the notification.	B	500ms	Driver will notice when the car is off the lane
Functional Safety Requirement 01-02	LDW shall has a upper limit so that the driver can still get control over the steering wheel when the haptic is on.	D	500ms	Driver will get back control when the LDW haptic is off.
Functional Safety Requirement 02-01	LKA shall have a upper limit, so that driver will not lose focus, or abuse the system.	D	500ms	Driver will have a delay in reaction to emergent situations.

# Refined System Architecture from Functional Safety Concept

[Instructions: Provide the refined system architecture from the functional safety concept]

## Functional overview of architecture elements

[Instructions: Provide a description for each functional safety element; what is each element's purpose in the lane assistance item? ]

Element	Description
Camera Sensor	Take in the image from environment; send it to camera sensor ECU
Camera Sensor ECU - Lane Sensing	Take in the image from camera sensor;
Camera Sensor ECU - Torque request generator	process in the information, and send instruction to electronic power steering ECU
Car Display	Take information from car display ECU, display to driver
Car Display ECU - Lane Assistance On/Off Status	Take in the data from camera ECU; send information to lane assistance ECU
Car Display ECU - Lane Assistant Active/Inactive	Take in the data from camera ECU; send information to lane assistance ECU
Car Display ECU - Lane Assistance malfunction warning	Take in the data from camera ECU; send information to lane assistance ECU
Driver Steering Torque Sensor	Sensing the torque generated from motor, and send it to electronic power steering ECU
Electronic Power Steering (EPS) ECU - Driver Steering Torque	Generate the driving steering torque
EPS ECU - Normal Lane Assistance Functionality	Keep the car in lane
EPS ECU - Lane Departure Warning Safety Functionality	Generate warning when the LDW is malfunctioning.
EPS ECU - Lane Keeping Assistant Safety Functionality	Keep the car in lane
EPS ECU - Final Torque	Take information from camera sensor ECU and drive steering torque ECU, compute the right torque to actuator, send it to motor
Motor	Take information from electronic power steering ECU, generate torque

# Technical Safety Concept

## Technical Safety Requirements

[Instructions: Fill in the technical safety requirements for the lane departure warning first functional safety requirement. We have provided the associated functional safety requirement in the first table below. Hint: The technical safety requirements were discussed in the lesson videos. The architecture allocation column should contain element names such as LDW Safety block, Data Transmission Integrity Check, etc. Allocating the technical safety requirements to the "EPS ECU" does not provide enough detail for a technical safety concept.]

### Lane Departure Warning (LDW) Requirements:

Functional Safety Requirement 01-01 with its associated system elements  
(derived in the functional safety concept)

ID	Functional Safety Requirement	Electronic Power Steering ECU	Camera ECU	Car Display ECU
Functional Safety Requirement 01-01	The lane keeping item shall ensure that the lane departure oscillating torque amplitude is below Max_Torque_Amplitude	X		

Technical Safety Requirements related to Functional Safety Requirement 01-01 are:

ID	Technical Safety Requirement	ASIL	Fault Tolerant Time Interval	Architecture Allocation	Safe State
Technical Safety Requirement 01	The LDW safety component shall ensure that the amplitude of the 'LDW_Torque_Request' sent to the 'Final electronic power steering Torque' component is below 'Max_Torque_Amplitude.	C	50ms	EPS ECU	Turn it to 0
Technical Safety Requirement 02	As soon as the LDW function deactivates the LDW feature, the 'LDW Safety' software block shall send a signal to the car display ECU to turn on a warning light.	C	50ms	EPS ECU	Turn it to 0
Technical Safety Requirement 03	As soon as a failure is detected by the LDW function, it shall deactivate the LDW feature and the 'LDW_Torque_Request' shall be set to zero.	C	50ms	EPS ECU	Turn it to 0
Technical Safety Requirement 04	The validity and integrity of the data transmission for 'LDW_Torque_Request' signal shall be ensured.	C	50ms	EPS ECU	Turn it to 0
Technical Safety Requirement 05	Memory test shall be conducted at start up of the EPS ECU to check for any faults in memory.	A	ignition cycle	EPS ECU	Turn it to 0

[Instructions: Fill in the technical safety requirements for the lane departure warning second functional safety requirement. We have provided the associated functional safety requirement in the table below. Hint:. Most of the technical safety requirements will be the same. At least one technical safety requirement will have to be slightly modified

because we are talking about frequency instead of amplitude. These requirements were not given in the lessons]

Functional Safety Requirement 01-2 with its associated system elements  
(derived in the functional safety concept)

ID	Functional Safety Requirement	Electronic Power Steering ECU	Camera ECU	Car Display ECU
Functional Safety Requirement 01-02	The lane keeping item shall ensure that the lane departure oscillating torque frequency is below Max_Torque_Frequency	X		

Technical Safety Requirements related to Functional Safety Requirement 01-02 are:

ID	Technical Safety Requirement	ASIL	Fault Tolerant Time Interval	Architecture Allocation	Safe State
Technical Safety Requirement 01	The LDW safety component shall ensure that the amplitude of the 'LDW_Frequency_Request' sent to the 'Final electronic power steering Torque' component is below 'Max_Frequency_Amplitude.	C	50ms	EPS ECU	Turn it to 0
Technical Safety Requirement 02	As soon as the LDW function deactivates the LDW feature, the 'LDW Safety' software block shall send a signal to the car display ECU to turn on a warning light.	C	50ms	EPS ECU	Turn it to 0
Technical Safety Requirement 03	As soon as a failure is detected by the LDW function, it shall deactivate the LDW feature and the 'LDW_Frequency_Request' shall be set to zero.	C	50ms	EPS ECU	Turn it to 0
Technical Safety Requirement 04	The LDW safety component shall ensure that the amplitude of the 'LDW_Frequency_Request' sent to the 'Final electronic power steering Torque' component is below 'Max_Frequency_Amplitude.	C	50ms	EPS ECU	Turn it to 0

## Lane Departure Warning (LDW) Verification and Validation Acceptance Criteria:

[OPTIONAL: For each technical safety requirement, identify both the verification and validation acceptance criteria. “Validation” asks whether or not you chose the appropriate parameters. “Verification” involves testing to make sure the vehicle behaves as expected when the parameter value is crossed. There is not necessarily one right answer. Look at your verification and validation acceptance criteria from the functional safety concept for inspiration.]

## Lane Keeping Assistance (LKA) Requirements:

[Instructions: Fill in the technical safety requirements for the lane keeping assistance functional safety requirement 02-01. We have provided the associated functional safety requirement in the table below. Hint:. You can reuse the technical safety requirements from functional safety requirement 01-01. But you need to change the language because we are now looking at a different system. The ASIL and Fault Tolerant Time Interval are different as well.]

Functional Safety Requirement 02-1 with its associated system elements  
(derived in the functional safety concept)

ID	Functional Safety Requirement	Electronic Power Steering ECU	Camera ECU	Car Display ECU
Functional Safety Requirement 02-01	The lane keeping item shall ensure that the lane keeping assistance torque is applied for only Max_Duration	X		

Technical Safety Requirements related to Functional Safety Requirement 02-01 are:



ID	Technical Safety Requirement	A S I L	Fault Tolerant Time Interval	Allocation to Architecture	Safe State
Technical Safety Requirement 01	The LDW safety component shall ensure that the time duration sent to the 'Final electronic power steering Torque' component is below 'Max_time_duration'.	C	50ms	EPS ECU	Turn it to 0
Technical Safety Requirement 02	As soon as the LKA function deactivates the LKA feature, the 'LKA Safety' software block shall send a signal to the car display ECU to turn on a warning light.	C	50ms	EPS ECU	Turn it to 0
Technical Safety Requirement 03	As soon as a failure is detected by the LKA function, it shall deactivate the LKA feature and the 'Max_time_duration ' shall be set to zero.	C	50ms	EPS ECU	Turn it to 0
Technical Safety Requirement 04	The validity and integrity of the data transmission for 'Max_time_duration' signal shall be ensured.	C	50ms	EPS ECU	Turn it to 0
Technical Safety Requirement 05	Memory test shall be conducted at start up of the EPS ECU to check for any faults in memory.	A	ignition cycle	EPS ECU	Turn it to 0

#### Lane Keeping Assistance (LKA) Verification and Validation Acceptance Criteria:

[OPTIONAL: For each technical safety requirement, identify both the verification and validation acceptance criteria. “Validation” asks whether or not you chose the appropriate parameters. “Verification” involves testing to make sure the vehicle behaves as expected when the parameter value is crossed. There is not necessarily one right answer. Look at your verification and validation acceptance criteria from the functional safety concept for inspiration.]

## Refinement of the System Architecture

[Instructions: Include the refined system architecture. Hint: The refined system architecture should include the system architecture from the end of the technical safety lesson, including all of the ASIL labels.]

## Allocation of Technical Safety Requirements to Architecture Elements

[Instructions: We already included the allocation as part of the technical requirement tables. Here you can state that for this particular item, all technical safety requirements are allocated to the Electronic Power Steering ECU]

## Warning and Degradation Concept

[Instructions: We've already identified that for any system malfunction, the lane assistance functions will be turned off and the driver will receive a warning light indication. The technical safety requirements have not changed how functionality will be degraded or what the warning will be.

So in this case, the warning and degradation concept is the same for the technical safety requirements as for the functional safety requirements. You can copy the functional safety warning and degradation concept here.

Oftentimes, a technical safety analysis will lead to a more detailed warning and degradation concept. ]