

WMMSIM: A Weak-Memory Model Simulator

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Abstract

We present WMMSIM, a solver-aided DSL to simulate weak memory models. A weak memory model can be defined in terms of acceptable violations of a) program order, and b) atomicity of writes (stores) in shared-memory concurrent program that is otherwise sequentially consistent [Lamport 1979]. WMMSIM relies on this observation to describe a memory model constructively as a non-deterministic function that takes a shared memory concurrent program, and non-deterministically re-orders instructions in the program. WMMSIM then symbolically interprets the resultant program to determine if any unexpected behaviours are possible under the memory model. If such behaviour is possible, WMMSIM outputs an execution of the shared memory program which reproduces unexpected behaviour. We believe that WMMSIM approach can be extended to a full-fledged framework that greatly aids concurrent programmers in understanding and tailoring their programs for new memory models that are constantly being developed.

1. Introduction

Recent years have witnessed the proliferation of multi-core and many-core architectures into general-purpose computing domain. Concurrent programming over these systems is complex even under programming models offering strong semantic guarantees (eg: sequential consistency [Lamport 1979]). However, sequential consistency (SC) is an expensive affair as both compilers and underlying hardware have to forego a range of optimizations to satisfy the requirements of SC [Adve and Boehm]. Instead, existing hardware and programming models provide weaker consistency guarantees by default [Adve and Gharachorloo], strengthening them only on demand. Such weaker models take an unsuspecting programmer by surprise by inducing new hard-to-understand behaviours into otherwise correct programs [Adve and Boehm]. In this paper, we describe a solver-aided DSL [?] that is intended to be used in two different ways: Firstly, it can be used by programmers to a) abstractly describe their shared-memory concurrent programs as list of lists of STOREs and LOADs, and b) define the set of outputs (A) that they intuitively expect the program to produce. Secondly, the DSL can be used by compiler writers (aware of

hardware architectures) to describe the semantic guarantees offered by their language (call is L) as a non-deterministic function in the DSL. The function takes a shared-memory concurrent program in L and outputs a symbolic program that captures the entire space of behaviours possible under the reorderings of memory operations allowed by L's memory model. The DSL then checks if user's understanding of the program's behaviour (A) matches with the reality (as dictated by L's memory model). If there is a mismatch, the DSL shows the concrete set of valid reorderings that the compiler can perform to exhibit the behaviour that programmer did not expect. Furthermore, we are working on an extension to the DSL that will also suggest the placement of FENCE instructions at appropriate locations to constrain reorderings so that reality matches with user's expectations. WMMSIM is primarily intended to be a workbench to understand the implications low-level hardware optimizations (eg: non-coherent caches, store buffers etc) on high-level shared-memory programs.

The rest of the paper is organized as follows. The following section gives an overview of weak memory models, and programming implications of weak consistency guarantees. Section 3 gives a brief introduction to Rosette [Torlak and Bodik 2014] and the paradigm of solver-aided programming pioneered by Rosette. Section 4 describes the design of WMMSIM and demonstrates its utility with help of examples. Section 5 talks about future work and concludes.

2. Weak Memory Models

The memory model, or memory consistency model, of a shared memory multi-processor provides a formal specification of how the memory system will appear to the programmer. Such an artifact is essential to bridge the gap between the behaviour expected by the programmer and the actual behaviour supported by the system. Effectively, consistency model places restrictions on the values that can be returned by a read operation. In a sequential program, a read always returns the value of the last write to the same memory location. Consequently, memory models are simple in the absence of concurrency. On the other hand, in concurrent programs, it is not always obvious what the last write operation is. For example, consider the code snippet in Fig. 1, which shows two threads sharing variables X and Y . What values

Initially $x = y = 0$. Assume $r1$ and $r2$ are register variables.

<u>Thread1</u>	<u>Thread2</u>
$x = 1;$	$y = 1;$
$r1 = y$	$r2 = x$

Figure 1. The core of Dekker’s Mutual Exclusion Algorithm

<u>Execution1</u>	<u>Execution2</u>	<u>Execution3</u>
$x = 1;$	$y = 1;$	$x = 1;$
$r1 = y;$	$r2 = x;$	$y = 1;$
$y = 1;$	$x = 1;$	$r1 = y;$
$r2 = x;$	$r1 = y;$	$r2 = x;$
$//r1 == 0$	$//r1 == 1;$	$//r1 == 1$
$//r2 == 1$	$//r2 == 0;$	$//r2 == 1$

Figure 2. Some Sequentially Consistent Executions of the Program in Fig. 1

do register variables $r1$ and $r2$ contain? Since there are no obvious last write operations to variables x and y before their corresponding reads, the question has no obvious answer.

To answer this question, an intuitive extension of the uniprocessor model can be applied to the multiprocessor case. This model is called *sequential consistency* (SC). SC model requires that all memory operations appear to execute one at a time, and operations of a single thread appear to execute in the program order. For example, some sequentially consistent executions of the concurrent program shown in Fig. 1 are shown in Fig. 2. As evident from the figure, $r1$ and $r2$ can assume different values depending on the interleaving of operations between two threads. Nonetheless, there is always one sequential execution of operations from both the threads that explains the values assumed by $r1$ and $r2$.

Sequential Consistency provides simple and intuitive programming model. Unfortunately, it disallows many hardware and compiler optimizations that are possible in uniprocessors by enforcing strict order among shared memory operations. For example, consider *store buffers*, which are commonly used by the memory hardware to mask write latency. When a write is issued by the processor, memory hardware buffers the write in the local store buffer and signals success to the processor, before actually committing the write to the main memory. Since only the writes committed to the main memory are available to rest of the processors, utilizing store buffers results in writes that are considered successful, but are not yet available at rest of the processors. This results in the violation of SC guarantee. For example, in Fig. 1, writes $x=1$ and $y=1$ can be buffered at their respective processors, and therefore may not be available to the other thread. Consequently, it is possible that the reads $r1=y$ and $r2=x$ may read old values of x and y (namely 0). Observe that

this behaviour of both reads returning 0 is not possible under any sequentially consistent execution (see Fig. 2), and may confound a programmer who is unaware of workings of the underlying hardware.

Common compiler optimizations, such as prefetching loads, also violate SC guarantee. In order to support SC memory model, it is therefore necessary to forego a range of compiler and hardware optimizations that are quite fundamental for performance. For this reason, most practical multi-processor memory hardware and compilers do not support SC model. However, in the absence of a memory model, programmers have to painstakingly reason about program correctness in terms of low-level hardware optimizations. To avoid this, a number of relaxed memory consistency models have been proposed. These models describe the effect of low-level optimizations in terms of *relaxations* to the strict SC model. For example, a memory model of the hardware utilizing store buffer optimization might relax the program order the requirement of SC model that in an SC execution operations of a thread must appear in program order. The model might instead allow a write and a subsequent read to not appear in the same order in a valid execution. Under this relaxation, the writes to x and y can be reordered with respect to reads to $r1$ and $r2$, respectively, in Fig. 1 making the following execution possible:

```

r1 = x;
r2 = y;
x = 1;
y = 1;
//r1 == 0
//r2 == 0

```

Similar to the store buffer optimization, more subtle hardware optimizations can also be described in terms of instruction reorderings, which can be more elaborate than the *write-read* reordering shown above.

3. WMMSIM

Relaxed memory models provide an abstract description of the behaviour of a shared memory system in terms of reorderings. However, reasoning about a shared memory concurrent program becomes more complicated in presence of instruction reorderings due to large number of possible interleavings, even for small programs. It is therefore desirable if the reasoning can be performed automatically. WMMSIM is a tool built for this purpose. The primary insight underlying WMMSIM is that a shared memory concurrent program can be transformed to a non-deterministic sequential program capturing all possible interleavings allowed by the memory model. For example, consider the program in Fig. 1. A non-deterministic program that can generate *any* SC execution of the program can be described by the following algorithm:

Data: T_1, T_2 : Two threads as list of instructions
Result: An SC execution represented as a list of instructions

```

1 Exn := [];
2 while  $T_1$  and  $T_2$  not empty do
3   T := oneOf( $T_1, T_2$ );
4   Instr := removeFirst(T);
5   Exn := addAtEnd(Exn, Instr);
6 end
7 if  $T_1$  is empty list then
8   Exn := append(Exn,  $T_2$ )
9 end
10 if  $T_2$  is empty list then
11   Exn := append(Exn,  $T_1$ )
12 end
13 return Exn

```

In the above algorithm, the function `oneOf` non-deterministically selects one of its both arguments (for eg, based on a coin toss). One way to look at the above algorithm is as a *definition* of SC memory model for a shared-memory program of two threads. Alternatively, if we redefined the algorithm for n threads, the algorithm simply serves as a constructive definition of SC. Our main observation is that such constructive definitions can be given for most¹ weak memory models.

Although the above algorithm is constructive (i.e., it can generate any SC execution of the program in Fig. 1), it is only of theoretical interest; it cannot be used to generate an SC execution that satisfies or violates a given property. To realize the practical utility of the algorithm, we replace the construct `oneOf` with `angelicOneOf`, and add an assertion at the end. `angelicOneOf` is a hypothetical construct that non-deterministically selects one of its both arguments *such that* an assertion in the future is satisfied. The assertion could be an assertion on the generated execution. For example, if we are interested in knowing if there exists an SC execution of program in Fig. 1 such that $r1==1$ and $r2==0$ under that execution, we modify the algorithm as following: The semantics of `angelicOneOf` lets us guar-

```

1 Exn := [];
2 while  $T_1$  and  $T_2$  not empty do
3   T := angelicOneOf( $T_1, T_2$ );
4   // ... rest remains same
5 end
6 // ...
7 assert(Exn  $\vdash$   $r1==1 \wedge r2==0$ );
8 return Exn

```

¹ Weak memory models violating write atomicity have more complex constructive definitions. Source code (wmmsim.rkt) has a demo.

antee that any execution generated by the algorithm satisfies the stated assertion. Since the algorithm only generates SC executions, the returned execution is an SC execution satisfying the stated assertion. If there does not exist such an execution, the assertion simply fails. In the similar manner, the behaviour of a shared memory program under any relaxed memory model can be understood.

The aforementioned methodology crucially relies on angelic non-determinism. In order for the method to be practical, `angelicOneOf` construct has to be realized. WMM-SIM realizes it with help of Rosette's [Torlak and Bodik 2014] solver-aided features. Following section elaborates.

4. Rosette Implementation

Rosette [Torlak and Bodik 2014] is a solver-aided symbolic virtual machine. In Rosette, we can express a computation by using symbols for unknown values, make assertions on the computation, and finally solve for unknown symbols such that the assertions are valid. The `angelicOneOf` feature described in the previous section can be implemented with help of binary symbols as following (shown in Haskell):

```

angelicOneOf (x,y) = if (k=0) then x else y
  where k = newBinarySymbol()

```

A binary symbol takes the values of either 0 or 1. Everytime a call to `angelicOneOf` is made, a new binary symbol is created. For a program with n threads, we create integer symbols. The values that these symbols take determines the execution generated by the algorithm.

The assertion on the execution shown on the line 7 of the 2nd algorithm is made by implementing an interpreter for the shared memory language. For the sake of simplicity, we define a very simple language with the following grammar:

i	\in	Integer constants	
r	\in	Register-allocated vars	
x	\in	Memory-allocated vars	
c	$::=$	$STORE\ x\ i \mid LOAD\ x\ r$	Commands
t	$::=$	$c; t \mid \cdot$	Thread
p	$::=$	$t \parallel p \mid \cdot$	Program

The interpreter for the language is implemented trivially. The non-deterministic execution generated by the constructive definition of the memory model is given to the interpreter, which interprets the execution and generates symbolic values for register variables. The symbolic values are then asserted equal to concrete values, which generates concrete bindings for symbols (i.e., resolves symbols). The result is a concrete witness of the program trace possible under the memory model which satisfies the stated assertion.

References

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