

Assignment3 Part1

In [4]:

```
import torch
import torchvision
import torchvision.transforms as transforms
```

In [5]:

```
#Checking CUDA Availability
train_on_gpu = torch.cuda.is_available()

if not train_on_gpu:
    print('CUDA is not available!  Training on CPU...')
else:
    print('CUDA is available!  Training on GPU ...')
```

CUDA is available! Training on GPU ...

In [6]:

```
transform = transforms.Compose(
    [transforms.ToTensor(),
     transforms.Normalize((0.5, 0.5, 0.5), (0.5, 0.5, 0.5))])

trainset = torchvision.datasets.CIFAR10(root='./data', train=True,
                                         download=True, transform=transform)
trainloader = torch.utils.data.DataLoader(trainset, batch_size=4,
                                           shuffle=True, num_workers=2)

testset = torchvision.datasets.CIFAR10(root='./data', train=False,
                                         download=True, transform=transform)
testloader = torch.utils.data.DataLoader(testset, batch_size=4,
                                          shuffle=False, num_workers=2)

classes = ('plane', 'car', 'bird', 'cat',
           'deer', 'dog', 'frog', 'horse', 'ship', 'truck')
```

Files already downloaded and verified

Files already downloaded and verified

In [7]:

```
import matplotlib.pyplot as plt
import numpy as np

# functions to show an image

def imshow(img):
    img = img / 2 + 0.5     # unnormalize
    npimg = img.numpy()
    plt.imshow(np.transpose(npimg, (1, 2, 0)))
    plt.show()

# get some random training images
dataiter = iter(trainloader)
images, labels = dataiter.next()

# show images
imshow(torchvision.utils.make_grid(images))
plt.show()
# print labels
print(' '.join('%5s' % classes[labels[j]] for j in range(4)))
```

<Figure size 640x480 with 1 Axes>

```
truck deer bird truck
```

In [8]:

```
import torch.nn as nn
import torch.nn.functional as F

class Net(nn.Module):
    def __init__(self):
        super(Net, self).__init__()
        self.conv1 = nn.Conv2d(3, 6, 5)
        self.pool = nn.MaxPool2d(2, 2)
        self.conv2 = nn.Conv2d(6, 16, 5)
        self.fc1 = nn.Linear(16 * 5 * 5, 120)
        self.fc2 = nn.Linear(120, 84)
        self.fc3 = nn.Linear(84, 10)

    def forward(self, x):
        x = self.pool(F.relu(self.conv1(x)))
        x = self.pool(F.relu(self.conv2(x)))
        x = x.view(-1, 16 * 5 * 5)
        x = F.relu(self.fc1(x))
        x = F.relu(self.fc2(x))
        x = self.fc3(x)
        return x

net = Net()
print(net)
```

```
Net (
  (conv1): Conv2d(3, 6, kernel_size=(5, 5), stride=(1, 1))
  (pool): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
  (conv2): Conv2d(6, 16, kernel_size=(5, 5), stride=(1, 1))
  (fc1): Linear(in_features=400, out_features=120, bias=True)
  (fc2): Linear(in_features=120, out_features=84, bias=True)
  (fc3): Linear(in_features=84, out_features=10, bias=True)
)
```

In [5]:

```
import torch.optim as optim

criterion = nn.CrossEntropyLoss()
optimizer = optim.SGD(net.parameters(), lr=0.001, momentum=0.9)
```

In [6]:

```
for epoch in range(2): # loop over the dataset multiple times

    running_loss = 0.0
    for i, data in enumerate(trainloader, 0):
        # get the inputs
        inputs, labels = data

        # zero the parameter gradients
        optimizer.zero_grad()

        # forward + backward + optimize
        outputs = net(inputs)
        loss = criterion(outputs, labels)
        loss.backward()
        optimizer.step()

        # print statistics
        running_loss += loss.item()
        if i % 2000 == 1999: # print every 2000 mini-batches
            print('[%d, %5d] loss: %.3f' %
                  (epoch + 1, i + 1, running_loss / 2000))
            running_loss = 0.0
```

```
print('Finished Training')
```

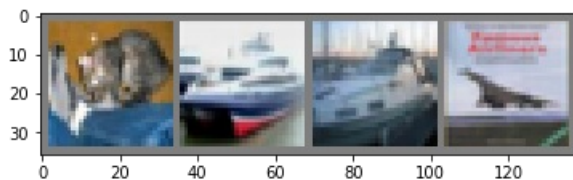
```
[1, 2000] loss: 2.217
[1, 4000] loss: 1.861
[1, 6000] loss: 1.682
[1, 8000] loss: 1.586
[1, 10000] loss: 1.502
[1, 12000] loss: 1.450
[2, 2000] loss: 1.394
[2, 4000] loss: 1.352
[2, 6000] loss: 1.339
[2, 8000] loss: 1.326
[2, 10000] loss: 1.294
[2, 12000] loss: 1.286
Finished Training
```

Test the Network

In [8]:

```
dataiter = iter(testloader)
images, labels = dataiter.next()

# print images
imshow(torchvision.utils.make_grid(images))
print('GroundTruth: ', ' '.join('%5s' % classes[labels[j]] for j in range(4)))
```



GroundTruth: cat ship ship plane

In [9]:

```
_, predicted = torch.max(outputs, 1)
print('Predicted: ', ' '.join('%5s' % classes[predicted[j]]
                                for j in range(4)))
```

Predicted: plane plane plane dog

In [15]:

```
correct = 0
total = 0
confusion_matrix = np.zeros([10,10], int)
with torch.no_grad():
    for data in testloader:
        images, labels = data
        outputs = net(images)
        _, predicted = torch.max(outputs.data, 1)
        total += labels.size(0)
        correct += (predicted == labels).sum().item()
        for i, l in enumerate(labels):
            confusion_matrix[l.item(), predicted[i].item()] += 1

print('Accuracy of the network on the 10000 test images: %d %%' % (
    100 * correct / total))
```

Accuracy of the network on the 10000 test images: 52 %

In [11]:

```

class_correct = list(0. for i in range(10))
class_total = list(0. for i in range(10))
with torch.no_grad():
    for data in testloader:
        images, labels = data
        outputs = net(images)
        _, predicted = torch.max(outputs, 1)
        c = (predicted == labels).squeeze()
        for i in range(4):
            label = labels[i]
            class_correct[label] += c[i].item()
            class_total[label] += 1

for i in range(10):
    print('Accuracy of %5s : %2d %%' % (
        classes[i], 100 * class_correct[i] / class_total[i]))

```

```

Accuracy of plane : 71 %
Accuracy of  car : 57 %
Accuracy of  bird : 37 %
Accuracy of  cat : 41 %
Accuracy of  deer : 60 %
Accuracy of  dog : 37 %
Accuracy of  frog : 75 %
Accuracy of horse : 53 %
Accuracy of  ship : 33 %
Accuracy of truck : 52 %

```

Confusion Matrix

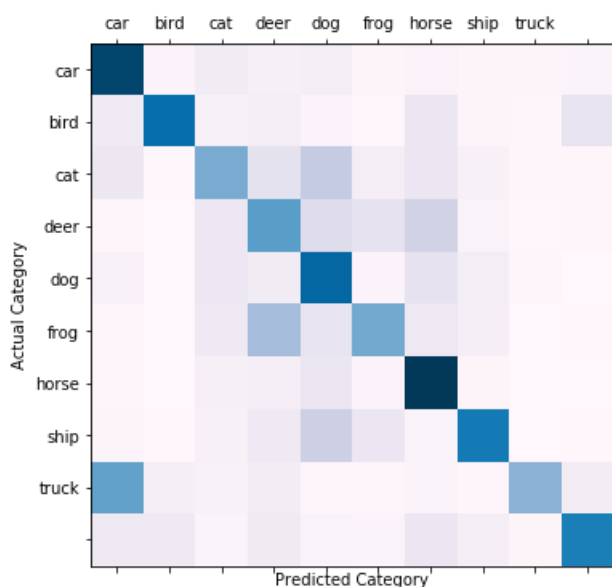
In [41]:

```

import matplotlib.ticker as ticker

fig, ax = plt.subplots(1,1,figsize=(8,6))
cax=ax.matshow(confusion_matrix,cmap=plt.get_cmap('PuBu'))
#fig.colorbar(cax)
plt.ylabel('Actual Category')
plt.yticks(range(10), classes)
plt.xlabel('Predicted Category')
plt.xticks(range(10), classes)
ax.xaxis.set_major_locator(ticker.MultipleLocator(1))
ax.yaxis.set_major_locator(ticker.MultipleLocator(1))
plt.show()

```



In [29]:

```

print('actual/pred'.ljust(16), end='')
for i,c in enumerate(classes):
    print(c.ljust(10), end=' ')

```

actual/pred	plane	car	bird	cat	deer	dog	frog	horse	ship
truck plane 22	717	19	69	43	58	12	26	17	17
0.022	0.717	0.019	0.069	0.043	0.058	0.012	0.026	0.017	0.009
car 111	74	576	39	58	19	4	95	16	8
0.111	0.074	0.576	0.039	0.058	0.019	0.004	0.095	0.016	0.004
bird 8	89	3	370	116	215	54	100	37	8
0.008	0.089	0.003	0.37	0.116	0.215	0.054	0.1	0.037	0.003
cat 11	9	2	92	419	138	114	185	27	3
0.011	0.009	0.002	0.092	0.419	0.138	0.114	0.185	0.027	0.001
deer 1	33	2	94	66	605	19	113	58	9
0.001	0.033	0.002	0.094	0.066	0.605	0.019	0.113	0.058	0.001
dog 4	7	2	78	285	112	378	85	48	1
0.004	0.007	0.002	0.078	0.285	0.112	0.378	0.085	0.048	0.001
frog 2	9	1	46	56	98	18	758	12	0
0.002	0.009	0.001	0.046	0.056	0.098	0.018	0.758	0.012	0.001
horse 3	14	4	37	78	198	99	29	537	1
0.003	0.014	0.004	0.037	0.078	0.198	0.099	0.029	0.537	0.001
ship 60	406	48	33	64	11	10	23	9	336
0.06	0.406	0.048	0.033	0.064	0.011	0.01	0.023	0.009	0.001
truck 525	83	82	22	75	27	22	96	54	14
0.525	0.083	0.082	0.022	0.075	0.027	0.022	0.096	0.054	0.001

Assignment3 Part2

In [1]:

```
import torch
import torchvision
import torchvision.transforms as transforms
```

In [2]:

```
#Checking CUDA Availability
train_on_gpu = torch.cuda.is_available()

if not train_on_gpu:
    print('CUDA is not available!  Training on CPU...')
else:
    print('CUDA is available!  Training on GPU ...')
```

CUDA is available! Training on GPU ...

In [3]:

```
transform = transforms.Compose(
    [transforms.ToTensor(),
     transforms.Normalize((0.5, 0.5, 0.5), (0.5, 0.5, 0.5))])

trainset = torchvision.datasets.CIFAR10(root='./data', train=True,
                                         download=True, transform=transform)
trainloader = torch.utils.data.DataLoader(trainset, batch_size=4,
                                           shuffle=True, num_workers=2)

testset = torchvision.datasets.CIFAR10(root='./data', train=False,
                                         download=True, transform=transform)
testloader = torch.utils.data.DataLoader(testset, batch_size=4,
                                          shuffle=False, num_workers=2)

classes = ('plane', 'car', 'bird', 'cat',
           'deer', 'dog', 'frog', 'horse', 'ship', 'truck')
```

Files already downloaded and verified
Files already downloaded and verified

In [4]:

```
import matplotlib.pyplot as plt
import numpy as np

# functions to show an image

def imshow(img):
    img = img / 2 + 0.5     # unnormalize
    npimg = img.numpy()
    plt.imshow(np.transpose(npimg, (1, 2, 0)))
    plt.show()

# get some random training images
dataiter = iter(trainloader)
images, labels = dataiter.next()

# show images
imshow(torchvision.utils.make_grid(images))
plt.show()
# print labels
print(' '.join('%5s' % classes[labels[j]] for j in range(4)))
```

<Figure size 640x480 with 1 Axes>

plane plane deer truck

Selecting mask size of 3x3

In [8]:

```
import torch.nn as nn
import torch.nn.functional as F

class Net(nn.Module):
    def __init__(self):
        super(Net, self).__init__()
        #3 Convolutional layers
        self.conv1 = nn.Conv2d(3, 6, 3)
        self.pool = nn.MaxPool2d(2, 2)
        self.conv2 = nn.Conv2d(6, 16, 3)
        self.fc1 = nn.Linear(16 * 6 * 6, 120)
        self.fc2 = nn.Linear(120, 84)
        self.fc3 = nn.Linear(84, 10)
        #Add dropout if data is overfitting
        #self.dropout=nn.Dropout(.15)

    def forward(self, x):
        x = self.pool(F.relu(self.conv1(x)))
        x = self.pool(F.relu(self.conv2(x)))
        #x = self.pool(F.relu(self.conv3(x)))
        x = x.view(-1, 16 * 6 * 6)
        x = F.relu(self.fc1(x))
        x = self.fc2(x)
        return x

net = Net()
print(net)
#if train_on_gpu:
# net.cuda()
```

```
Net(
  (conv1): Conv2d(3, 6, kernel_size=(3, 3), stride=(1, 1))
  (pool): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
  (conv2): Conv2d(6, 16, kernel_size=(3, 3), stride=(1, 1))
  (fc1): Linear(in_features=576, out_features=120, bias=True)
  (fc2): Linear(in_features=120, out_features=84, bias=True)
  (fc3): Linear(in_features=84, out_features=10, bias=True)
)
```

In [9]:

```
import torch.optim as optim

criterion = nn.CrossEntropyLoss()
optimizer = optim.SGD(net.parameters(), lr=0.001, momentum=0.9)
```

In [10]:

```
for epoch in range(2): # loop over the dataset multiple times

    running_loss = 0.0
    net.train()
    for i, data in enumerate(trainloader, 0):
        # get the inputs
        inputs, labels = data

        # zero the parameter gradients
        optimizer.zero_grad()

        # forward + backward + optimize
        outputs = net(inputs)
        loss = criterion(outputs, labels)
```

```

        loss.backward()
        optimizer.step()

        # print statistics
        running_loss += loss.item()
        if i % 2000 == 1999:    # print every 2000 mini-batches
            print('[%d, %5d] loss: %.3f' %
                  (epoch + 1, i + 1, running_loss / 2000))
            running_loss = 0.0

print('Finished Training')

```

```

[1, 2000] loss: 2.253
[1, 4000] loss: 1.806
[1, 6000] loss: 1.612
[1, 8000] loss: 1.497
[1, 10000] loss: 1.451
[1, 12000] loss: 1.408
[2, 2000] loss: 1.326
[2, 4000] loss: 1.287
[2, 6000] loss: 1.282
[2, 8000] loss: 1.230
[2, 10000] loss: 1.226
[2, 12000] loss: 1.231
Finished Training

```

Test the Network

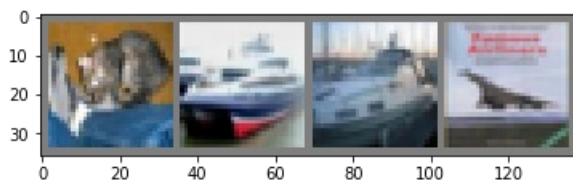
In [11]:

```

dataiter = iter(testloader)
images, labels = dataiter.next()

# print images
imshow(torchvision.utils.make_grid(images))
print('GroundTruth: ', ' '.join('%5s' % classes[labels[j]] for j in range(4)))

```



GroundTruth: cat ship ship plane

In [12]:

```

_, predicted = torch.max(outputs, 1)

print('Predicted: ', ' '.join('%5s' % classes[predicted[j]]
                              for j in range(4)))

```

Predicted: ship deer ship deer

In [13]:

```

correct = 0
total = 0
confusion_matrix = np.zeros([10,10], int)
with torch.no_grad():
    for data in testloader:
        images, labels = data
        outputs = net(images)
        _, predicted = torch.max(outputs.data, 1)
        total += labels.size(0)
        correct += (predicted == labels).sum().item()
    for i, l in enumerate(labels):
        confusion_matrix[l.item(), predicted[i].item()] += 1

```



```
print('Accuracy of the network on the 10000 test images: %d %%' % (
    100 * correct / total))
```

Accuracy of the network on the 10000 test images: 57 %

In [1]:

##Increase in accuracy by 5% by changing the mask size

In [14]:

```
class_correct = list(0. for i in range(10))
class_total = list(0. for i in range(10))
with torch.no_grad():
    for data in testloader:
        images, labels = data
        outputs = net(images)
        _, predicted = torch.max(outputs, 1)
        c = (predicted == labels).squeeze()
        for i in range(4):
            label = labels[i]
            class_correct[label] += c[i].item()
            class_total[label] += 1

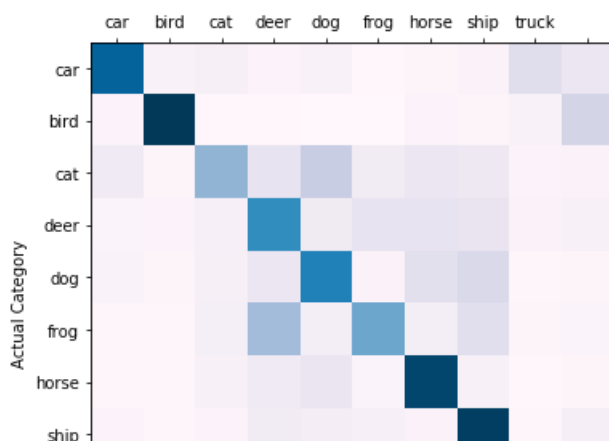
for i in range(10):
    print('Accuracy of %5s : %2d %%' % (
        classes[i], 100 * class_correct[i] / class_total[i]))
```

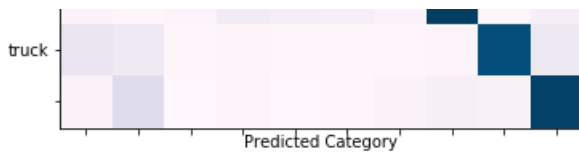
Accuracy of plane	: 60 %
Accuracy of car	: 73 %
Accuracy of bird	: 31 %
Accuracy of cat	: 46 %
Accuracy of deer	: 49 %
Accuracy of dog	: 37 %
Accuracy of frog	: 69 %
Accuracy of horse	: 71 %
Accuracy of ship	: 66 %
Accuracy of truck	: 70 %

In [15]:

```
import matplotlib.ticker as ticker

fig, ax = plt.subplots(1,1,figsize=(8,6))
cax=ax.matshow(confusion_matrix,cmap=plt.get_cmap('PuBu'))
#fig.colorbar(cax)
plt.ylabel('Actual Category')
plt.yticks(range(10), classes)
plt.xlabel('Predicted Category')
plt.xticks(range(10), classes)
ax.xaxis.set_major_locator(ticker.MultipleLocator(1))
ax.yaxis.set_major_locator(ticker.MultipleLocator(1))
plt.show()
```





In [16]:

```
print('actual/pred'.ljust(16), end='')
for i,c in enumerate(classes):
    print(c.ljust(10), end='')
print()
for i,r in enumerate(confusion_matrix):
    print(classes[i].ljust(16), end='')
    for idx, p in enumerate(r):
        print(str(p).ljust(10), end='')
    print()

    r = r/np.sum(r)
    print(''.ljust(16), end='')
    for idx, p in enumerate(r):
        print(str(p).ljust(10), end='')
    print()
```

actual/pred	plane	car	bird	cat	deer	dog	frog	horse	ship
truck plane 93	600	32	46	19	32	4	18	26	130
0.093	0.6	0.032	0.046	0.019	0.032	0.004	0.018	0.026	0.1
car 170	20	730	5	6	1	2	19	16	31
0.17	0.02	0.73	0.005	0.006	0.001	0.002	0.019	0.016	0.0
bird 26	72	15	312	109	200	64	97	86	19
0.026	0.072	0.015	0.312	0.109	0.2	0.064	0.097	0.086	0.0
cat 37	21	19	41	465	74	108	109	102	24
0.037	0.021	0.019	0.041	0.465	0.074	0.108	0.109	0.102	0.0
deer 13	28	14	44	96	498	26	121	151	9
0.013	0.028	0.014	0.044	0.096	0.498	0.026	0.121	0.151	0.0
dog 21	12	7	51	278	57	375	56	127	16
0.021	0.012	0.007	0.051	0.278	0.057	0.375	0.056	0.127	0.0
frog 17	7	12	36	71	99	21	692	39	6
0.017	0.007	0.012	0.036	0.071	0.099	0.021	0.692	0.039	0.0
horse 47	19	8	19	64	55	43	26	712	7
0.047	0.019	0.008	0.019	0.064	0.055	0.043	0.026	0.712	0.0
ship 87	99	77	10	13	9	9	10	17	669
0.087	0.099	0.077	0.01	0.013	0.009	0.009	0.01	0.017	0.0
truck 701	24	136	6	19	4	7	25	46	32
0.701	0.024	0.136	0.006	0.019	0.004	0.007	0.025	0.046	0.0

Assignment3 Question3

In [1]:

```
import torch
import torchvision
import torchvision.transforms as transforms
```

In [2]:

```
#Checking CUDA Availability
train_on_gpu = torch.cuda.is_available()

if not train_on_gpu:
    print('CUDA is not available!  Training on CPU...')
else:
    print('CUDA is available!  Training on GPU ...')
```

CUDA is available! Training on GPU ...

In [3]:

```
transform = transforms.Compose(
    [transforms.ToTensor(),
     transforms.Normalize((0.5, 0.5, 0.5), (0.5, 0.5, 0.5))])

trainset = torchvision.datasets.CIFAR10(root='./data', train=True,
                                         download=True, transform=transform)
trainloader = torch.utils.data.DataLoader(trainset, batch_size=4,
                                           shuffle=True, num_workers=2)

testset = torchvision.datasets.CIFAR10(root='./data', train=False,
                                         download=True, transform=transform)
testloader = torch.utils.data.DataLoader(testset, batch_size=4,
                                          shuffle=False, num_workers=2)

classes = ('plane', 'car', 'bird', 'cat',
           'deer', 'dog', 'frog', 'horse', 'ship', 'truck')
```

Files already downloaded and verified

Files already downloaded and verified

In [4]:

```
import matplotlib.pyplot as plt
import numpy as np

# functions to show an image

def imshow(img):
    img = img / 2 + 0.5     # unnormalize
    npimg = img.numpy()
    plt.imshow(np.transpose(npimg, (1, 2, 0)))
    plt.show()

# get some random training images
dataiter = iter(trainloader)
images, labels = dataiter.next()

# show images
imshow(torchvision.utils.make_grid(images))
plt.show()
# print labels
print(' '.join('%5s' % classes[labels[j]] for j in range(4)))
```

<Figure size 640x480 with 1 Axes>

```
deer  bird   cat  ship
```

Increasing no. of filters in conv1

In [11]:

```
import torch.nn as nn
import torch.nn.functional as F

class Net(nn.Module):
    def __init__(self):
        super(Net, self).__init__()
        #3 Convolutional layers changing no of filters to 12 from 6 for conv1
        self.conv1 = nn.Conv2d(3, 12, 3)
        self.pool = nn.MaxPool2d(2, 2)
        self.conv2 = nn.Conv2d(12, 16, 3)
        self.fc1 = nn.Linear(16 * 6 * 6, 120)
        self.fc2 = nn.Linear(120, 84)
        self.fc3 = nn.Linear(84, 10)
        #Add dropout if data is overfitting
        #self.dropout=nn.Dropout(.15)

    def forward(self, x):
        x = self.pool(F.relu(self.conv1(x)))
        x = self.pool(F.relu(self.conv2(x)))
        #x = self.pool(F.relu(self.conv3(x)))
        x = x.view(-1, 16 * 6 * 6)
        x = F.relu(self.fc1(x))
        x = self.fc2(x)
        return x

net = Net()
print(net)
#if train_on_gpu:
#     net.cuda()
```

```
Net(
  (conv1): Conv2d(3, 12, kernel_size=(3, 3), stride=(1, 1))
  (pool): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
  (conv2): Conv2d(12, 16, kernel_size=(3, 3), stride=(1, 1))
  (fc1): Linear(in_features=576, out_features=120, bias=True)
  (fc2): Linear(in_features=120, out_features=84, bias=True)
  (fc3): Linear(in_features=84, out_features=10, bias=True)
)
```

In [12]:

```
import torch.optim as optim

criterion = nn.CrossEntropyLoss()
optimizer = optim.SGD(net.parameters(), lr=0.001, momentum=0.9)
```

In [13]:

```
for epoch in range(2): # loop over the dataset multiple times

    running_loss = 0.0
    net.train()
    for i, data in enumerate(trainloader, 0):
        # get the inputs
        inputs, labels = data

        # zero the parameter gradients
        optimizer.zero_grad()

        # forward + backward + optimize
        outputs = net(inputs)
        loss = criterion(outputs, labels)
```

```

        loss.backward()
        optimizer.step()

        # print statistics
        running_loss += loss.item()
        if i % 2000 == 1999:    # print every 2000 mini-batches
            print('[%d, %5d] loss: %.3f' %
                  (epoch + 1, i + 1, running_loss / 2000))
            running_loss = 0.0

print('Finished Training')

```

```

[1, 2000] loss: 2.225
[1, 4000] loss: 1.751
[1, 6000] loss: 1.603
[1, 8000] loss: 1.516
[1, 10000] loss: 1.423
[1, 12000] loss: 1.400
[2, 2000] loss: 1.303
[2, 4000] loss: 1.282
[2, 6000] loss: 1.256
[2, 8000] loss: 1.216
[2, 10000] loss: 1.168
[2, 12000] loss: 1.166
Finished Training

```

Test the Network

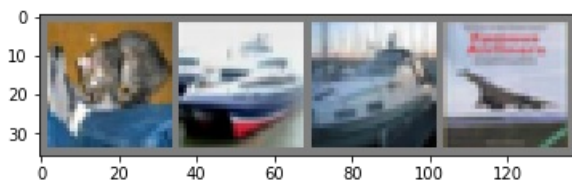
In [14]:

```

dataiter = iter(testloader)
images, labels = dataiter.next()

# print images
imshow(torchvision.utils.make_grid(images))
print('GroundTruth: ', ' '.join('%5s' % classes[labels[j]] for j in range(4)))

```



GroundTruth: cat ship ship plane

In [15]:

```

_, predicted = torch.max(outputs, 1)

print('Predicted: ', ' '.join('%5s' % classes[predicted[j]]
                              for j in range(4)))

```

Predicted: ship ship dog car

In [16]:

```

correct = 0
total = 0
confusion_matrix = np.zeros([10,10], int)
with torch.no_grad():
    for data in testloader:
        images, labels = data
        outputs = net(images)
        _, predicted = torch.max(outputs.data, 1)
        total += labels.size(0)
        correct += (predicted == labels).sum().item()
    for i, l in enumerate(labels):
        confusion_matrix[l.item(), predicted[i].item()] += 1

```

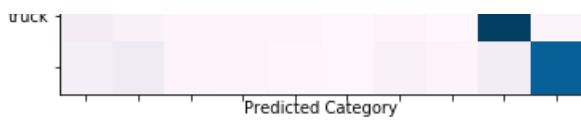
Accuracy of the network on the 10000 test images: 60 %

In [17]:

Accuracy of plane	: 61 %
Accuracy of car	: 64 %
Accuracy of bird	: 39 %
Accuracy of cat	: 37 %
Accuracy of deer	: 60 %
Accuracy of dog	: 45 %
Accuracy of frog	: 82 %
Accuracy of horse	: 59 %
Accuracy of ship	: 80 %
Accuracy of truck	: 68 %

```
import matplotlib.ticker as ticker
```

A confusion matrix for the CIFAR-10 dataset. The x-axis represents the predicted categories and the y-axis represents the actual categories. The categories are: car, bird, cat, deer, dog, frog, horse, ship, and truck. The diagonal elements, representing correct classifications, are the darkest blue. Other cells show the frequency of misclassifications, with varying shades of blue and purple indicating different levels of error.



In [19]:

```
print('actual/pred'.ljust(16), end='')
for i,c in enumerate(classes):
    print(c.ljust(10), end='')
print()
for i,r in enumerate(confusion_matrix):
    print(classes[i].ljust(16), end='')
    for idx, p in enumerate(r):
        print(str(p).ljust(10), end='')
    print()

r = r/np.sum(r)
print(''.ljust(16), end='')
for idx, p in enumerate(r):
    print(str(p).ljust(10), end='')
print()
```

actual/pred	plane	car	bird	cat	deer	dog	frog	horse	ship
truck plane 34	613	13	70	27	25	6	23	7	182
0.034	0.613	0.013	0.07	0.027	0.025	0.006	0.023	0.007	0.1
car 152	51	645	20	8	8	4	42	4	66
0.152	0.051	0.645	0.02	0.008	0.008	0.004	0.042	0.004	0.0
bird 13	62	4	399	70	202	54	141	21	34
0.013	0.062	0.004	0.399	0.07	0.202	0.054	0.141	0.021	0.0
cat 25	22	5	68	374	137	151	169	20	29
0.025	0.022	0.005	0.068	0.374	0.137	0.151	0.169	0.02	0.0
deer 3	16	3	67	50	607	25	150	52	27
0.003	0.016	0.003	0.067	0.05	0.607	0.025	0.15	0.052	0.0
dog 20	15	1	84	181	81	459	105	37	17
0.02	0.015	0.001	0.084	0.181	0.081	0.459	0.105	0.037	0.0
frog 7	5	3	33	54	47	11	823	7	10
0.007	0.005	0.003	0.033	0.054	0.047	0.011	0.823	0.007	0.0
horse 32	17	3	56	44	130	75	41	591	11
0.032	0.017	0.003	0.056	0.044	0.13	0.075	0.041	0.591	0.0
ship 24	66	36	16	19	15	3	17	3	801
0.024	0.066	0.036	0.016	0.019	0.015	0.003	0.017	0.003	0.8
truck 689	56	82	14	21	13	6	34	14	71
0.689	0.056	0.082	0.014	0.021	0.013	0.006	0.034	0.014	0.0

Assignment3 Question4 Part1 with test subset of 100 images

In [55]:

```
import torch
import torchvision
import torchvision.transforms as transforms
```

In [56]:

```
#Checking CUDA Availability
train_on_gpu = torch.cuda.is_available()

if not train_on_gpu:
    print('CUDA is not available! Training on CPU...')
else:
    print('CUDA is available! Training on GPU ...')
```

CUDA is available! Training on GPU ...

In [57]:

```
transform = transforms.Compose([
    transforms.RandomHorizontalFlip(), # randomly flip
    transforms.RandomRotation(10),
    transforms.ToTensor(),
    transforms.Normalize((0.5, 0.5, 0.5), (0.5, 0.5, 0.5))
])

trainset = torchvision.datasets.CIFAR10(root='./data', train=True,
                                         download=True, transform=transform)
trainloader = torch.utils.data.DataLoader(trainset, batch_size=4,
                                           shuffle=True, num_workers=2)

testset = torchvision.datasets.CIFAR10(root='./data', train=False,
                                         download=True, transform=transform)
testloader = torch.utils.data.DataLoader(testset, batch_size=4,
                                          shuffle=False, num_workers=2)

classes = ('plane', 'car', 'bird', 'cat',
           'deer', 'dog', 'frog', 'horse', 'ship', 'truck')
```

Files already downloaded and verified
Files already downloaded and verified

In [58]:

```
import matplotlib.pyplot as plt
import numpy as np

# functions to show an image

def imshow(img):
    img = img / 2 + 0.5 # unnormalize
    npimg = img.numpy()
    plt.imshow(np.transpose(npimg, (1, 2, 0)))
    plt.show()

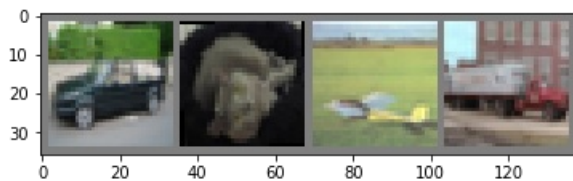
# get some random training images
dataiter = iter(trainloader)
images, labels = dataiter.next()

# show images
imshow(torchvision.utils.make_grid(images))
plt.show()

# print labels
print(' '.join('%5s' % classes[labels[j]] for j in range(4)))
```



```
print(' '.join('%5s' % classes[labels[j]] for j in range(4)))
```



car cat plane truck

In [59]:

```
import torch.nn as nn
import torch.nn.functional as F

class Net(nn.Module):
    def __init__(self):
        super(Net, self).__init__()
        #3 Convolutional layers
        self.conv1 = nn.Conv2d(3, 16, 3, padding=1)
        self.conv2 = nn.Conv2d(16, 32, 3, padding=1)
        self.conv3 = nn.Conv2d(32, 64, 3, padding=1)
        #Max Pooling Layer
        self.pool = nn.MaxPool2d(2, 2)
        #Fully Connected Linear Layer
        self.fc1 = nn.Linear(64 * 4 * 4, 800)
        self.fc2 = nn.Linear(800, 400)
        self.fc3=nn.Linear(400,10)
        self.dropout = nn.Dropout(0.20)
        #Add dropout if data is overfitting
        #self.dropout=nn.Dropout(.15)

    def forward(self, x):
        x = self.pool(F.relu(self.conv1(x)))
        x = self.pool(F.relu(self.conv2(x)))
        x = self.pool(F.relu(self.conv3(x)))
        x = x.view(-1, 64 * 4 * 4)
        x = F.relu(self.fc1(x))
        x = self.dropout(x)
        x = F.relu(self.fc2(x))
        x = self.dropout(x)
        x = self.fc3(x)
        return x

net = Net()
#if train_on_gpu:
#    net.cuda()
```

In [60]:

```
import torch.optim as optim

criterion = nn.CrossEntropyLoss()
optimizer = optim.SGD(net.parameters(), lr=0.001, momentum=0.9)
```

In [61]:

```
for epoch in range(2): # loop over the dataset multiple times

    running_loss = 0.0
    net.train()
    for i, data in enumerate(trainloader, 0):
        # get the inputs
        inputs, labels = data

        # zero the parameter gradients
        optimizer.zero_grad()

        # forward + backward + optimize
        outputs = net(inputs)
```

```

loss = criterion(outputs, labels)
loss.backward()
optimizer.step()

# print statistics
running_loss += loss.item()
if i % 2000 == 1999:    # print every 2000 mini-batches
    print('[%d, %5d] loss: %.3f' %
          (epoch + 1, i + 1, running_loss / 2000))
    running_loss = 0.0

print('Finished Training')

```

```

[1, 2000] loss: 2.252
[1, 4000] loss: 1.963
[1, 6000] loss: 1.734
[1, 8000] loss: 1.602
[1, 10000] loss: 1.508
[1, 12000] loss: 1.451
[2, 2000] loss: 1.356
[2, 4000] loss: 1.328
[2, 6000] loss: 1.255
[2, 8000] loss: 1.249
[2, 10000] loss: 1.184
[2, 12000] loss: 1.180
Finished Training

```

Test the Network

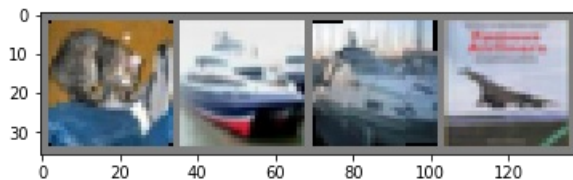
In [62]:

```

dataiter = iter(testloader)
images, labels = dataiter.next()

# print images
imshow(torchvision.utils.make_grid(images))
print('GroundTruth: ', ' '.join('%5s' % classes[labels[j]] for j in range(4)))

```



GroundTruth: cat ship ship plane

In [63]:

```

_, predicted = torch.max(outputs, 1)
print('Predicted: ', ' '.join('%5s' % classes[predicted[j]]
                              for j in range(4)))

```

Predicted: frog dog truck horse

In [64]:

```

from torch.utils.data.sampler import SubsetRandomSampler
num_test=len(testset)
indices = list(range(num_test))
np.random.shuffle(indices)
split = int(np.floor(.01 * num_test))
test_idx, subset_idx = indices[split:], indices[:split]

print(len(subset_idx), "Test subset created")

#test_sampler = SubsetRandomSampler(test_idx)
subset_sampler = SubsetRandomSampler(subset_idx)

```

```
#trainloader = torch.utils.data.DataLoader(trainset, batch_size=4,
                                           # sampler=train_sampler, num_workers=2)

subsetloader = torch.utils.data.DataLoader(testset, batch_size=4,
                                           sampler=subset_sampler, num_workers=2)
```

100 Test subset created

In [65]:

```
correct = 0
total = 0

confusion_matrix = np.zeros([10,10], int)

with torch.no_grad():
    for data in subsetloader:
        images, labels = data
        outputs = net(images)
        _, predicted = torch.max(outputs.data, 1)
        labels=labels
        #print(len(labels))
        total += labels.size(0)
        correct += (predicted == labels).sum().item()
        for i, l in enumerate(labels):
            confusion_matrix[l.item(), predicted[i].item()] += 1

#print(correct, total)
print('Accuracy of the network on the 100 test images: %d %%' % (
    100 * correct / total))
```

Accuracy of the network on the 100 test images: 60 %

In [66]:

```
class_correct = list(0. for i in range(10))
class_total = list(0. for i in range(10))
with torch.no_grad():
    for data in subsetloader:
        images, labels = data
        outputs = net(images)
        _, predicted = torch.max(outputs, 1)
        c = (predicted == labels).squeeze()
        for i in range(4):
            label = labels[i]
            class_correct[label] += c[i].item()
            class_total[label] += 1

for i in range(10):
    print('Accuracy of %5s : %2d %%' % (
        classes[i], 100 * class_correct[i] / class_total[i]))
```

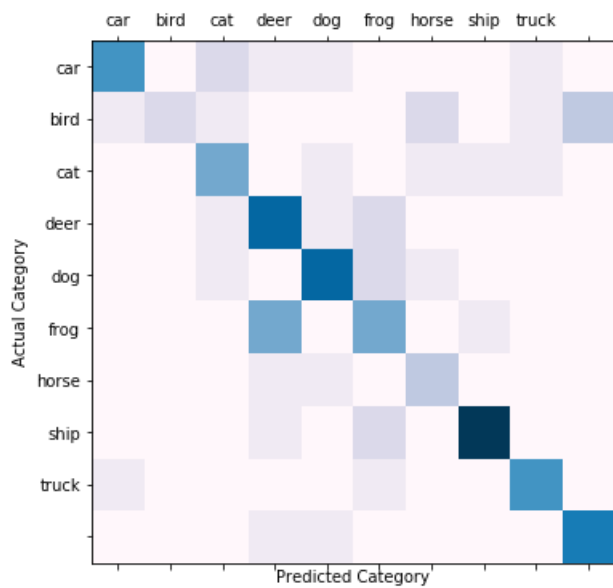
```
Accuracy of plane : 63 %
Accuracy of  car : 20 %
Accuracy of  bird : 33 %
Accuracy of  cat : 50 %
Accuracy of  deer : 58 %
Accuracy of  dog : 45 %
Accuracy of  frog : 80 %
Accuracy of horse : 53 %
Accuracy of  ship : 87 %
Accuracy of truck : 55 %
```

In [67]:

```
import matplotlib.ticker as ticker

fig, ax = plt.subplots(1,1,figsize=(8,6))
cax=ax.matshow(confusion_matrix,cmap=plt.get_cmap('PuBu'))
#fig.colorbar(cax)
```

```
plt.ylabel('Actual Category')
plt.yticks(range(10), classes)
plt.xlabel('Predicted Category')
plt.xticks(range(10), classes)
ax.xaxis.set_major_locator(ticker.MultipleLocator(1))
ax.yaxis.set_major_locator(ticker.MultipleLocator(1))
plt.show()
```



Assignment3 Question4 Part2 with flip and additional conv layer

In [37]:

```
import torch
import torchvision
import torchvision.transforms as transforms
```

In [38]:

```
#Checking CUDA Availability
train_on_gpu = torch.cuda.is_available()

if not train_on_gpu:
    print('CUDA is not available! Training on CPU...')
else:
    print('CUDA is available! Training on GPU ...')
```

CUDA is available! Training on GPU ...

In [63]:

```
#Adding random flipping & rotation
```

In [39]:

```
transform = transforms.Compose([
    transforms.RandomHorizontalFlip(), # randomly flip
    transforms.RandomRotation(10),
    transforms.ToTensor(),
    transforms.Normalize((0.5, 0.5, 0.5), (0.5, 0.5, 0.5))
])

trainset = torchvision.datasets.CIFAR10(root='./data', train=True,
                                         download=True, transform=transform)
trainloader = torch.utils.data.DataLoader(trainset, batch_size=4,
                                           shuffle=True, num_workers=2)

testset = torchvision.datasets.CIFAR10(root='./data', train=False,
                                         download=True, transform=transform)
testloader = torch.utils.data.DataLoader(testset, batch_size=4,
                                          shuffle=False, num_workers=2)

classes = ('plane', 'car', 'bird', 'cat',
           'deer', 'dog', 'frog', 'horse', 'ship', 'truck')
```

Files already downloaded and verified
Files already downloaded and verified

In [40]:

```
import matplotlib.pyplot as plt
import numpy as np

# functions to show an image

def imshow(img):
    img = img / 2 + 0.5 # unnormalize
    npimg = img.numpy()
    plt.imshow(np.transpose(npimg, (1, 2, 0)))
    plt.show()

# get some random training images
dataiter = iter(trainloader)
images, labels = dataiter.next()
```

```
# show images
imshow(torchvision.utils.make_grid(images))
plt.show()
# print labels
print(' '.join('%5s' % classes[labels[j]] for j in range(4)))
```



horse dog plane truck

In []:

```
#Network achitecture is modified with increasing the depth and adding 3 convolutional layers and  
#3 fully connected layers along with dropout
```

In [54]:

```
import torch.nn as nn
import torch.nn.functional as F

class Net(nn.Module):
    def __init__(self):
        super(Net, self).__init__()
        #3 Convolutional layers
        self.conv1 = nn.Conv2d(3, 16, 3, padding=1)
        self.conv2 = nn.Conv2d(16, 32, 3, padding=1)
        self.conv3 = nn.Conv2d(32, 64, 3, padding=1)
        #Max Pooling Layer
        self.pool = nn.MaxPool2d(2, 2)
        #Fully Connected Linear Layer
        self.fc1 = nn.Linear(64 * 4 * 4, 800)
        self.fc2 = nn.Linear(800, 400)
        self.fc3=nn.Linear(400,10)
        self.dropout = nn.Dropout(0.25)
        #Add dropout if data is overfitting
        #self.dropout=nn.Dropout(.15)

    def forward(self, x):
        x = self.pool(F.relu(self.conv1(x)))
        x = self.pool(F.relu(self.conv2(x)))
        x = self.pool(F.relu(self.conv3(x)))
        x = x.view(-1, 64 * 4 * 4)
        x = F.relu(self.fc1(x))
        x = self.dropout(x)
        x = F.relu(self.fc2(x))
        x = self.dropout(x)
        x = self.fc3(x)
        return x

net = Net()
#if train_on_gpu:
#     net.cuda()
```

In [55]:

```
import torch.optim as optim

criterion = nn.CrossEntropyLoss()
optimizer = optim.SGD(net.parameters(), lr=0.001, momentum=0.9)
```

In [56]:

```
for epoch in range(5): # loop over the dataset multiple times
```

```

running_loss = 0.0
net.train()
for i, data in enumerate(trainloader, 0):
    # get the inputs
    inputs, labels = data

    # zero the parameter gradients
    optimizer.zero_grad()

    # forward + backward + optimize
    outputs = net(inputs)
    loss = criterion(outputs, labels)
    loss.backward()
    optimizer.step()

    # print statistics
    running_loss += loss.item()
    if i % 2000 == 1999:    # print every 2000 mini-batches
        print('[%d, %5d] loss: %.3f' %
              (epoch + 1, i + 1, running_loss / 2000))
        running_loss = 0.0

print('Finished Training')

```

```

[1, 2000] loss: 2.283
[1, 4000] loss: 1.991
[1, 6000] loss: 1.742
[1, 8000] loss: 1.601
[1, 10000] loss: 1.524
[1, 12000] loss: 1.454
[2, 2000] loss: 1.381
[2, 4000] loss: 1.338
[2, 6000] loss: 1.292
[2, 8000] loss: 1.250
[2, 10000] loss: 1.199
[2, 12000] loss: 1.192
[3, 2000] loss: 1.122
[3, 4000] loss: 1.093
[3, 6000] loss: 1.098
[3, 8000] loss: 1.057
[3, 10000] loss: 1.067
[3, 12000] loss: 1.027
[4, 2000] loss: 0.994
[4, 4000] loss: 0.980
[4, 6000] loss: 0.960
[4, 8000] loss: 0.945
[4, 10000] loss: 0.946
[4, 12000] loss: 0.936
[5, 2000] loss: 0.901
[5, 4000] loss: 0.879
[5, 6000] loss: 0.881
[5, 8000] loss: 0.876
[5, 10000] loss: 0.889
[5, 12000] loss: 0.866

```

Finished Training

Test the Network

In [57]:

```

dataiter = iter(testloader)
images, labels = dataiter.next()

# print images
imshow(torchvision.utils.make_grid(images))
print('GroundTruth: ', ' '.join('%5s' % classes[labels[j]] for j in range(4)))

```



0 20 40 60 80 100 120

GroundTruth: cat ship ship plane

In [58]:

```
_, predicted = torch.max(outputs, 1)

print('Predicted: ', ' '.join('%5s' % classes[predicted[j]]
                                for j in range(4)))
```

Predicted: frog frog car dog

In [59]:

```
correct = 0
total = 0
confusion_matrix = np.zeros([10,10], int)
with torch.no_grad():
    for data in testloader:
        images, labels = data
        outputs = net(images)
        _, predicted = torch.max(outputs.data, 1)
        total += labels.size(0)
        correct += (predicted == labels).sum().item()
    for i, l in enumerate(labels):
        confusion_matrix[l.item(), predicted[i].item()] += 1

print('Accuracy of the network on the 10000 test images: %d %%' % (
    100 * correct / total))
```

Accuracy of the network on the 10000 test images: 69 %

Accuracy achieved is 69% which is 9% higher than the last best case with smaller subset of test images

In [60]:

```
class_correct = list(0. for i in range(10))
class_total = list(0. for i in range(10))
with torch.no_grad():
    for data in testloader:
        images, labels = data
        outputs = net(images)
        _, predicted = torch.max(outputs, 1)
        c = (predicted == labels).squeeze()
        for i in range(4):
            label = labels[i]
            class_correct[label] += c[i].item()
            class_total[label] += 1

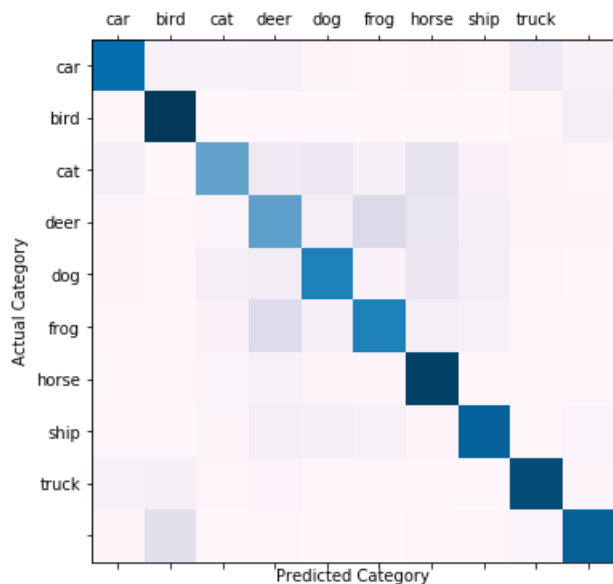
for i in range(10):
    print('Accuracy of %5s : %2d %%' % (
        classes[i], 100 * class_correct[i] / class_total[i]))
```

Accuracy of plane : 65 %
Accuracy of car : 89 %
Accuracy of bird : 47 %
Accuracy of cat : 48 %
Accuracy of deer : 61 %
Accuracy of dog : 60 %
Accuracy of frog : 86 %
Accuracy of horse : 74 %
Accuracy of ship : 81 %
Accuracy of truck : 74 %

In [61]:


```
import matplotlib.ticker as ticker

fig, ax = plt.subplots(1,1,figsize=(8,6))
cax=ax.matshow(confusion_matrix,cmap=plt.get_cmap('PuBu'))
#fig.colorbar(cax)
plt.ylabel('Actual Category')
plt.yticks(range(10), classes)
plt.xlabel('Predicted Category')
plt.xticks(range(10), classes)
ax.xaxis.set_major_locator(ticker.MultipleLocator(1))
ax.yaxis.set_major_locator(ticker.MultipleLocator(1))
plt.show()
```



In [62]:

```
print('actual/pred'.ljust(16), end='')
for i,c in enumerate(classes):
    print(c.ljust(10), end='')
print()
for i,r in enumerate(confusion_matrix):
    print(classes[i].ljust(16), end='')
    for idx, p in enumerate(r):
        print(str(p).ljust(10), end='')
    print()

r = r/np.sum(r)
print(''.ljust(16), end='')
for idx, p in enumerate(r):
    print(str(p).ljust(10), end='')
print()
```

actual/pred	plane	car	bird	cat	deer	dog	frog	horse	shi
truck plane 41	678	47	35	48	21	7	16	9	98
0.041	0.678	0.047	0.035	0.048	0.021	0.007	0.016	0.009	0.0
car 63	12	890	2	7	2	2	7	4	11
0.063	0.012	0.89	0.002	0.007	0.002	0.002	0.007	0.004	0.0
bird 13	65	7	474	96	105	57	132	31	20
0.013	0.065	0.007	0.474	0.096	0.105	0.057	0.132	0.031	0.0
cat 17	16	12	29	482	63	182	128	53	18
0.017	0.016	0.012	0.029	0.482	0.063	0.182	0.128	0.053	0.0
deer 3	18	3	58	77	611	32	114	71	13
0.003	0.018	0.003	0.058	0.077	0.611	0.032	0.114	0.071	0.0

dog 8	9	4	30	168	54	611	62	47	7
0.008 frog 7	0.009	0.004	0.03	0.168	0.054	0.611	0.062	0.047	0.0
0.007 horse 28	7	9	29	38	17	18	857	10	8
0.028 ship 17	0.007	0.009	0.029	0.038	0.017	0.018	0.857	0.01	0.0
0.017 truck 745	9	5	21	67	51	50	18	743	8
0.745	0.009	0.005	0.021	0.067	0.051	0.05	0.018	0.743	0.0
	45	53	9	23	8	9	8	4	824
	0.045	0.053	0.009	0.023	0.008	0.009	0.008	0.004	0.8
	20	147	7	15	4	4	14	15	29
	0.02	0.147	0.007	0.015	0.004	0.004	0.014	0.015	0.0