

BLG 561 E FALL 2021  
Deep Learning

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3 components of an general ML algorithm : DL is a sub-class

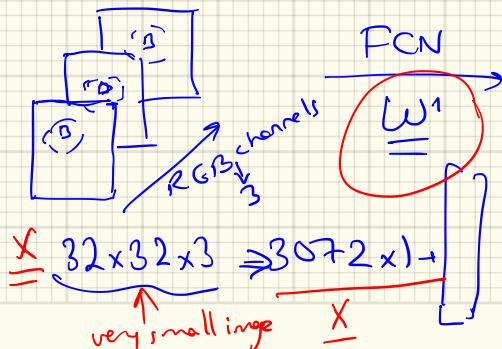
- 1) Hypothesis function:
- 2) Loss function:
- 3) Optimization : optime loss fn.

## Today: CONVOLUTIONAL NEURAL NETWORKS (CNNs)

\* Only the hypothesis functions change, <sup>i.e.</sup> the (1)st component ONLY

Then you can pick (2) & (3) freely according to your task.

Now Say, you have large (spatial) data , let's use a FCN / Fully Connected hypothesis



$$\underline{a}^1 = \text{activation} \quad \underline{a}^1 = \underline{W}^1 \underline{X}$$

$\underline{a}^1 = 28 \times 28 \times 6 = 4074 \times 1$  (1st layer)

$\underline{W}^1 : 3072 \times 4074$   
 $\approx 14 \text{ Million!}$  parameters.

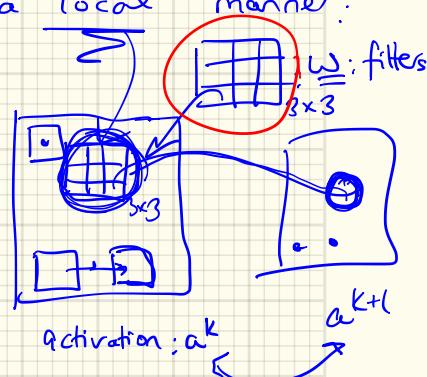
e.g. if we had  
 $256 \times 256 \times 3$   
 $\approx 600 \text{K dimensions}$

→ FCNs would need a huge # parameters !!

⇒ CNNs can handle large spatial data : Q: How?

They restrict the weights in 2 ways: (in contrast to FCNs)

- 1) Activations between layers occur in a "local" manner.  
(sparsity):
- 2) Parameter sharing: All activations share the same weight.



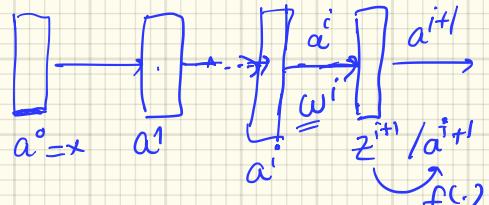
① 1st component:  
New hypothesis function for CNNs :

$$z^{i+1} = \underline{w^i} * a^i + b^i$$

$$a^{i+1} = f(z^{i+1}) = f(w^i * a^i + b^i)$$

\* convolution operation

$f$ : ReLU or other nonlinearity



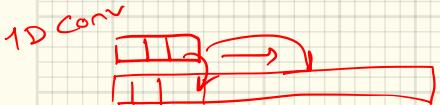
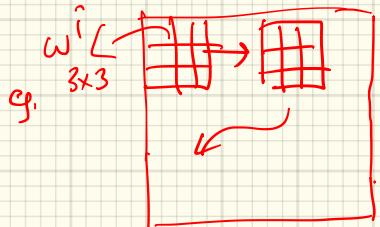
Compare

CNN

convolution

$$z^{i+1} = \underline{w^i} * \underline{a^i} + \underline{b^i}$$

$$a^{i+1} = f(\underline{w^i * a^i + b^i}) = f(z^{i+1})$$



FCN

matrix. vector multiplication

$$\begin{aligned} z^{i+1} &= \underline{w^i} \cdot \underline{z^i} + \underline{b^i} \\ a^{i+1} &= f(z^{i+1}) \end{aligned}$$

- (1) locality (sparsity)
- (2) shared connections

Note :  
maxpool  
other  
components  
can be  
added

For illustration:

$$\rightarrow 1\text{-D CNN. } a^{i+1} = f(w^i * a^i + b^i)$$

Say  $w^i = (w_1, w_2, w_3)$ : 1D filter

Input:  $a^i \xrightarrow[6 \times 1]{} \boxed{1 \quad 1 \quad 1 \quad 1 \quad 1 \quad 1}$

$w^i$  filter:  $\begin{matrix} \boxed{w_1 \quad w_2 \quad w_3} \\ \boxed{w_1 \quad w_2 \quad w_3} \\ \boxed{w_1 \quad w_2 \quad w_3} \\ \boxed{w_1 \quad w_2 \quad w_3} \end{matrix} \xrightarrow[4 \text{ possible "valid" shifts}]{} \dots$

Recall: FC layer  
 $a^{i+1} = f(w^i \cdot a^i + b^i)$   
Write convolution to a matrix operator

$$w^i = \begin{bmatrix} w_1 & w_2 & w_3 & 0 & 0 & 0 \\ 0 & w_1 & w_2 & w_3 & 0 & 0 \\ 0 & 0 & w_1 & w_2 & w_3 & 0 \\ 0 & 0 & 0 & w_1 & w_2 & w_3 \end{bmatrix}_{4 \times 6}$$

CNN:  $a^{i+1} = f(w^i \cdot a^i + b^i)$

What happens at backprop?

Recall for FC: backprop:

Upstream gradient:  $\frac{\partial l}{\partial a^i} = g^i = (w^{i+1})^T \cdot \underbrace{g^{i+1}}_{6 \times 1} \cdot \underbrace{f'(z^{i+1})}_{4 \times 1}$

→ let's transpose

in CNN backprop :

$$W_i^T = \begin{bmatrix} w_1 & 0 & 0 & 0 \\ w_2 & w_1 & 0 & 0 \\ w_3 & w_2 & w_1 & 0 \\ 0 & w_3 & w_2 & w_1 \\ 0 & 0 & w_3 & w_2 \\ 0 & 0 & 0 & w_3 \end{bmatrix}_{6 \times 4}$$

filter is flipped

∴ In CNNs, backprop just flips convolutions.

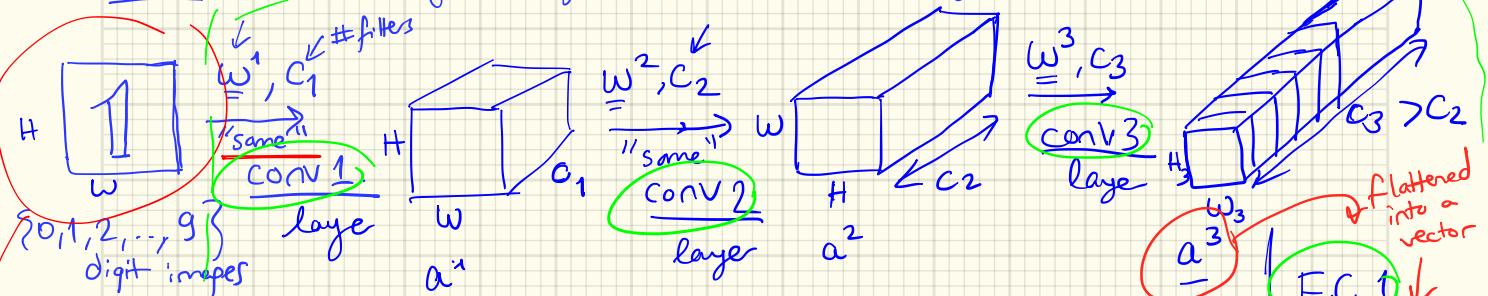
2D Conv: flip vertically & horizontally.

Ex: CNN

mainly

## Encoder Module

for images. Build a CNN for Digit Classification (10 class)



$p(0)$

$p(9)$

$10 \times 1$

$256 \times 1$

$1024 \times 1$

$1024 \times 2048$

$2048 \times 1$

$multi-class$

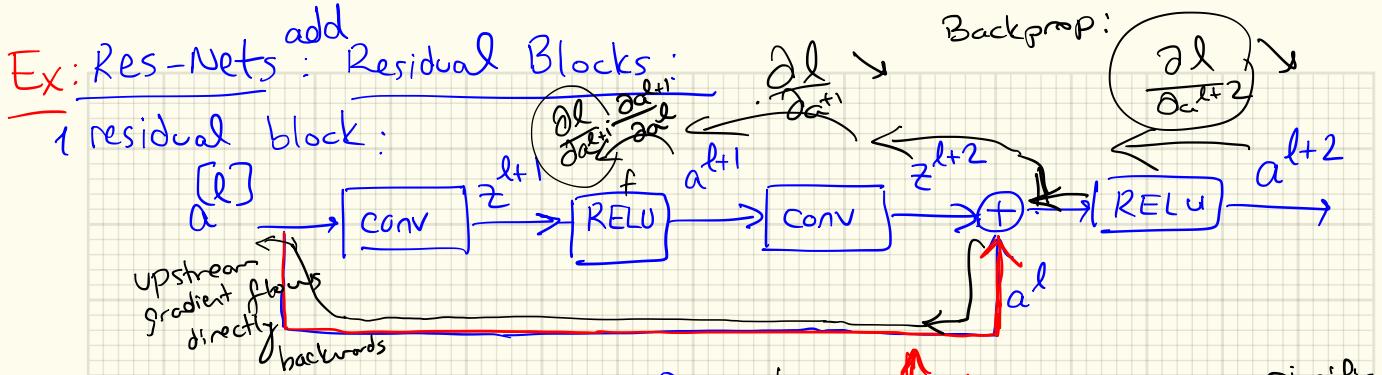
$loss$

① this whole model defines our hypothesis function  $\rightarrow$

② loss fn: cross-entropy, hinge loss

③ pick an optimizer, e.g. Adam.

You have a deep learning CNN classifier.



$$a^{l+1} = f(W^l * a^l + b^l)$$

$$z^{l+2} = W^{l+1} * a^{l+1} + b^{l+1}$$

$$a^{l+2} = f(z^{l+2} + a^l)$$

$\xrightarrow{\text{newly added}}$  in a ResNet Block

$$a^{l+2} = f(W^{l+1} * f(W^l * a^l + b^l) + b^{l+1} + a^l)$$

(ResNet 2015) :  $\approx 150$  layers !! very deep network

Backprop:

$$\frac{\partial l}{\partial a^{l+2}}$$

↑ skip connection : significance

- think of vanishing gradient problem
- ∴ ResNet : its skip connections helped reduce vanishing grad. problem, particularly in deep networks