

Your maxon drive

consists of:

Planetary Gearhead GP 32 HP Ø32 mm, 4.0 - 8.0 Nm, Metal Version, High Power

Part number 326669

EC-4pole 30 Ø30 mm, brushless, 200 Watt

Part number 305013

Encoder ENC 16 EASY, 1000 pulses

Part number 499360

ESCON 50/5, 4-Q Servocontroller for DC/EC motors, 5/15 A, 10 - 50 VDC

Part number 409510

Your Contact

maxon motor worldwide

http://www.maxongroup.us:80/maxon/view/content/contact_page

E-Mail: info@maxongroup.com

Internet: http://www.maxongroup.us:80

retail price:

0-4 Pieces \$1,630.01 5-19 Pieces \$1,373.51 20-49 Pieces \$1,169.52 from 50 Pieces On Request

Terms and conditions

Planetary Gearhead GP 32 HP Ø32 mm, 4.0 - 8.0 Nm, Metal Version, High Power Part number 326669



General	inform	ation
General	Intorn	ation

Gearhead type	GP
Outer diameter	32 mm
Version	High Power

Gearhead Data

Reduction	123 : 1
Absolute reduction	6877/56
Max. motor shaft diameter	3 mm
Number of stages	3
Max. continuous torque	8 Nm
Max. intermittent torque	12 Nm
Direction of rotation, drive to output	=
Max. efficiency	70 %
Average backlash no load	1°
Mass inertia	0.7 gcm ²
Gearhead length (L1)	54.8 mm
Max. transmittable power (continuous)	54 W
Max. transmittable power (intermittent)	82 W

Technical Data

Radial play	max. 0.14 mm, 10 mm from flange
Axial play	max. 0.4 mm
Max. radial load	200 N, 10 mm from flange
Max. axial load (dynamic)	120 N
Max. force for press fits	120 N
Max. continuous input speed	8000 rpm
Max. intermittent input speed	8000 rpm
Recommended temperature range	-40+100 °C
Number of autoclave cycles	0

Product

Weight 210 g

EC-4pole 30 Ø30 mm, brushless, 200 Watt

Part number 305013



Values at nominal voltage	9
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Nominal voltage	!	24 V
No load speed		16700 rpm
No load current		723 mA
Nominal speed		16100 rpm
Nominal torque	(max. continuous torque)	95.6 mNm
Nominal current	(max. continuous current)	7.61 A
Stall torque		3240 mNm
Stall current		236 A
Max. efficiency		90 %
Nominal current Stall torque Stall current		7.61 A 3240 mNm 236 A

Characteristics

Terminal resistance	\mid 0.102 $_{\Omega}$
Terminal inductance	0.0163 mH
Torque constant	13.7 mNm/A
Speed constant	697 rpm/V
Speed / torque gradient	5.17 rpm/mNm
Mechanical time constant	1.8 ms
Rotor inertia	33.3 gcm ²

Thermal data

Thermal resistance housing-ambient	7.4 K/W
Thermal resistance winding-housing	0.209 K/W
Thermal time constant winding	2.11 s
Thermal time constant motor	1180 s
Ambient temperature	-20+100 °C
Max. winding temperature	+155 °C

Mechanical data

Bearing type	ball bearings
Max. speed	25000 rpm
Axial play	0 mm, at radial load < 4 N
	0.14 mm, at radial load > 4 N
Max. axial load (dynamic)	5.5 N
Max. force for press fits (static)	73 N
(static, shaft supported)	1300 N
Max. radial load	25 N. 5 mm from flange

Other specifications

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Number o	of pole pairs	2
	of phases	3
Number of	of autoclave cycles	0

Product

Weight	300 g

Encoder ENC 16 EASY, 1000 pulses

Part number 499360



General	intorm	ation.

Counts per turn	1000
Number of channels	3
Line Driver	RS422
Max. length of encoder housing	8.5 mm
Max. electrical speed	90000 rpm
Max. mechanical speed	30000 rpm

Technical Data

Su	ipply voltage Vcc	5.0V ± 10.0%
Ou	utput signal	Incremental
Dr	iver used logic	Differential, EIA RS 422
Ou	utput current per channel	-2020 mA
Sig	gnal rise time	20 ns
Me	easurement condition for signal rise time	CL=25pF, RL=1kOhm
Sig	gnal fall time	20 ns
Me	easurement condition for signal fall time	CL=25pF, RL=1kOhm
Mi	n. state duration	125 ns
Dir	rection of rotation	A before B CW
Inc	dex position	A low & B low
Inc	dex synchronized to AB	Yes
Ту	pical current draw at standstill	22 mA
Ma	ax. moment of inertia of code wheel	0.1 gcm ²
Op	perating temperature	-40+100 °C
Or	rientation of encoder output to motor flange	0 °

Product

Weight 9 g

ESCON 50/5, 4-Q Servocontroller for DC/EC motors, 5/15 A, 10 - 50 VDC

Part number 409510



Product		
	Weight	204 g
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Motor		
	DC motors up to	250 W
	EC motors up to	250 W
Sensor		
	Without sensor (DC motors)	Yes
	DC tacho	Yes
	Digital incremental encoder (2-channel, single-ended)	Yes
	Digital incremental encoder (2-channel, differential)	Yes
	Digital incremental encoder (3-channel, differential)	Yes
	Digital Hall sensors (EC Motors)	Yes
Operating I	modes	
	Current controller	Yes
	Speed controller (open loop)	Yes
	Speed controller (closed loop)	Yes
Electrical d	ata	
	Operating voltage Vcc (min.)	10 V
	Operating voltage Vcc (max.)	50 V
	Max. output voltage (factor * Vcc)	0.98
	Max. output current Imax	15 A
	Max. time of peak output current Imax	20 s
	Continuous output current Icont	5 A
	PWM clock frequency of power stage	53.6 kHz
	Sampling rate PI current controller	53.6 kHz
	Sampling rate PI speed controller	5.36 kHz
	Max. efficiency	95 %
	Max. speed (DC)	150000 rpm
	Max. speed (EC; 1 pole pair) block commutation	150000 rpm
	Built-in motor choke per phase	30 µH
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Inputs		
	Hall sensor signals	H1, H2, H3
	Encoder signals	A, A, B, B\
	Max. encoder input frequency	1 MHz
	Digital inputs	2
	Functionality of digital inputs	Enable, enable CW, enable CCW, enable
	, , ,	CW+CCW, enable + direction of rotation,
		stop, PWM set value, RC Servo set value,
		fixed set value
	Analog inputs	2
	Resolution, range, circuit	12-bit, -10+10V, differential
	Functionality of analog inputs	Set value, current limit, offset, speed ramp
	Potentiometers	2
	Functionality of the potentiometers	set value, current limit, offset, speed ramp, gain, IxR factor
		gan, <i>p.</i>
Outputs		
Cutputs		

	Digital outputs	2
	Functionality of digital outputs	ready, speed comparator, current
		comparator, commutation frequency
	Analog outputs	2
	Resolution, range	12-bit, -4+4V
	Functionality of analog outputs	current monitor, speed monitor,
		temperature, fixed value
Voltage ou	utputs	
	Hall sensor supply voltage	+5 VDC, max. 30 mA
	Encoder supply voltage	+5 VDC, max. 70 mA
	Auxiliary output voltage	+5 VDC, max. 10 mA
	riamar, surpar isitage	10 120, max 10 mm
Interface		
	USB 2.0 (full speed)	Yes
Display		
	Status indicator "Ready"	green LED
	Status indicator "Error"	red LED
Protective	functions	
	Protective functions	current limit, overcurrent, excess temperature, undervoltage, overvoltage, voltage transients, short-circuits in the motor cable
Ambient c	onditions	
	Temperature – Operation (min.)	-30 °C
	Temperature – Operation (min.)	45 °C
	Temperature – Operation (max.) Temperature – Extended Range	+45+85°C, Derating: -0.125 A/°C
	Temperature – Storage (min.)	-40 °C
	Temperature – Storage (max.)	85 °C
	Humidity (non-condensing) (min.)	5 %
	Humidity (non-condensing) (max.)	90 %
Mechanica	al data	
WECHAIIC	ai uata	
	Weight	204 g
	Dimension (length)	115 mm
	Dimension (width)	75.5 mm
	Dimension (height)	24 mm
	Mounting	Flange for M4 screws
Software		
	Installation program	ESCON Setup
	Graphical User Interface	ESCON Studio
	Operating system	Windows 10, 8, 7, Windows XP SP3
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