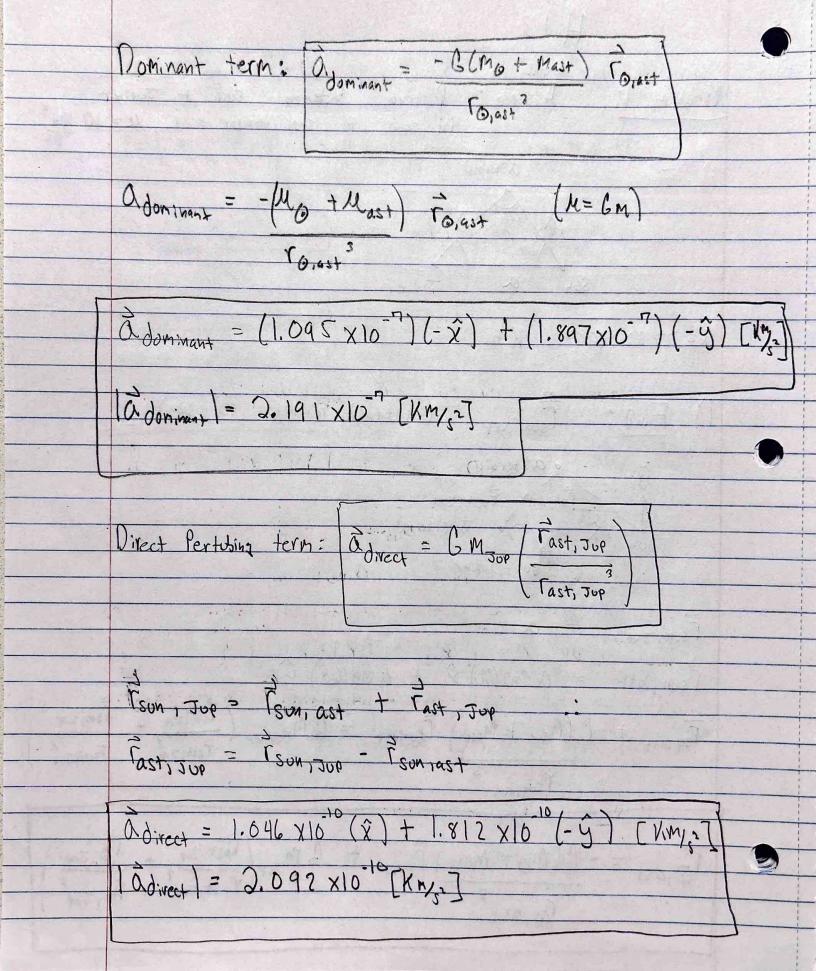
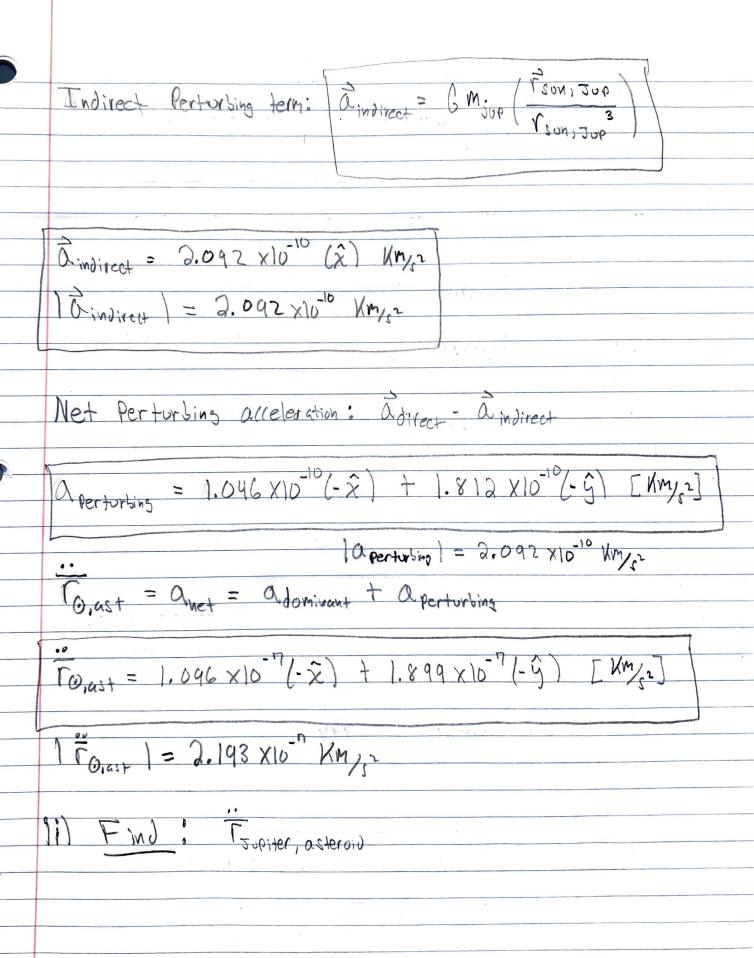
HU3

	Problem 1: Assome: Distance between son & Jupiter
1	is equal to semi-major axis, le= 10 km3
	(i) asteroid
1	
t	a/60'a
t	60 60
+	
+	Soy a Jupiter
1	
	a= 778279959 Km
	20
l	[Caseroid relative to son)
t	Lind: (askroid relative to son)
H	a as ternic)
-	g as teroid
	Compast Fast, Jue
	Topiter
	Sin
	Yson, Jopiler
	$\int_{S} \int_{S} \int_{S$
_	Tsom Jupiter = a x
	$\Gamma_{\text{sun,ast}} = \alpha \cos(60) \hat{x} + \alpha \sin(60) \hat{y}$
	= 1 / (m. + m) = (m / Tast, Jup = 15m, Jup)
	Con
	1304,45t Tast, July 1504, July 15
	Υ. 3
	rson, ast
_	
_	
-	(O) ast = - 6 (Mo + Mast) Point + 6 M JUP (Tast, JUP) - 10, JUP)
-	10,0st 10,700
_	·(•) 1 (1.2)





adject = 2.191 x10 /my27 Induct term: 6 mg 1 July 6 Dinduced = 2.191 × 10-7 (-2) [Xm/2] [] judicet = 2.19/X/0 [Km/2] Net Perturbing Acceleration: adjrect - aindirect A Perturbing = 1.095 × 10 - (x) + 1.897 × 10 - (-9) [Km/sz] | a perturbins | = 2.191 ×10-7 [xm/sz] Total net acceleration: Forast = adminant + aperturbius Genest = 1.0965 × 10-7(x) + 1.899 × 10-7(-9) [Km/2] [FJURIST] = 2.193 X10 7 Km/2

For the asteroid relative to the son formulation, the dominant acceleration is the largest. For the asteroid relative to Jopiter formulation, the direct effect on the asteroid due to the son is as equally large as the indirect effect on Jopiter due to the son. For this formulation, the dominant effect is ~ 1000 times smaller than in the asteroid relative to the son formulation.

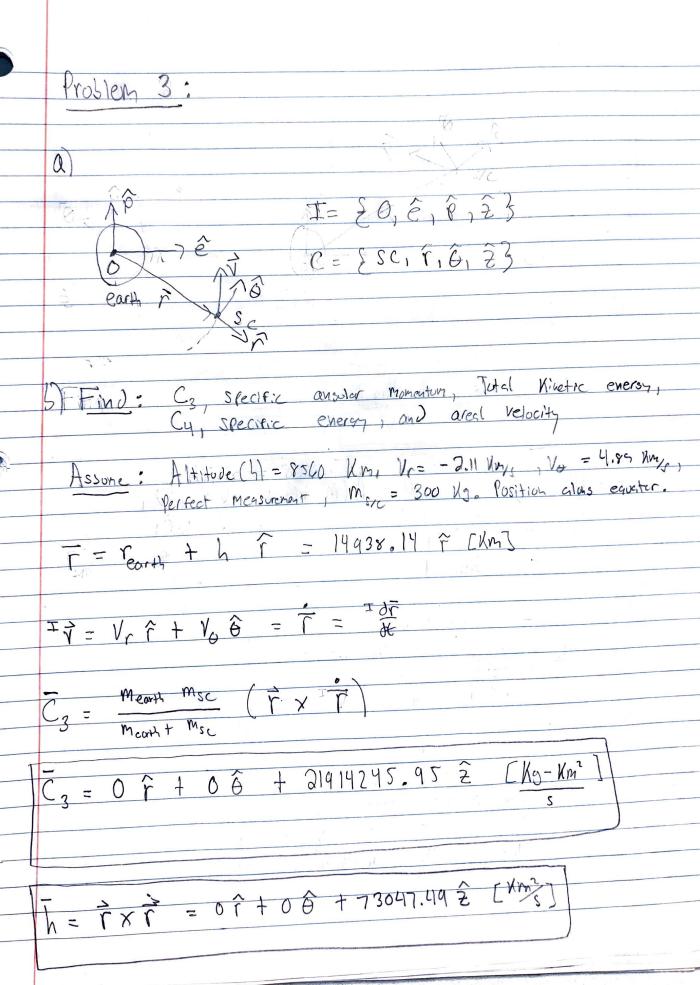
111

The net perturbins acceleration in the asteroid relative to Son care is ~ 1000 smaller than in the asteroid relative to Jopiter case. For both formulations the Son has the largest impact.

The total Net acceleration on the asteroid has the same magnitude in both cases, but apposite & directions. This makes sense because the only thins changing is the reference point of view.

Both formulations are correct or provide the same net acceleration as the Sodies are equally distanced. If they weren't, the various formulations could be used to sain more insist.

From these results, it is reasonable to model the asteroid motion as a two-body problem between the sun of the asteroid. This is because the gravitational effect of the sun is ~1000 times stronger than Jupiters.



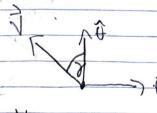
$$E = \frac{\sqrt{2} \cdot \mu}{2} \quad \mathcal{L} = G(M_1 + M_2), \quad V = \frac{1}{7}$$

$$V = \frac{1}{7}$$

$$\dot{A} = \frac{h}{2} = \frac{1\overline{h}1}{2}$$

$$P = \frac{h^2}{M} = 13386.68$$
 Km

$$e = \frac{\dot{r} \times \dot{h}}{h} - \dot{r}$$
 $\hat{r} = \frac{\bar{r}}{r}$, $e = |\dot{e}|$



1V/ cos (x) = V6

$$\theta^* = c\omega^{-1}\left(\frac{\rho}{e}\right)$$

7=17



V= Vrî + Voê = V, cos(+*)ê - V6 sm(+*)ê + V, sin(+*)ê + V, cos(+*)ê V = -4.175 ê - 3.306 p [Km/s] e) Vc=Vk VC= 5.166 KM/s V = 5.326 Km/s = V Ta Vc = 7,305 Km/s :: The relative velocity

this is an elliptical orbit

Nerified by oce 2 The relative velocity is less than Ta Vc :

```
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```

Problem 1- i) - Acceleration of asteroid relative to Sun

```
% Semi-major axis of Jupiters orbit
                 = 778279959;
                                              % [km]
a
% Gravitational Parameters: mu = G*m [km^3/s^2]
                = 132712440017.99;
mu sun
mu_asteroid
                = 10;
mu_jupiter
                = 126712767.8578;
% Define 2-D position vectors [x-y] plane
% Assume equilateral triangle of 60 deg
r sun jupiter = [a;0];
                                              % [km]
r_{sun_asteroid} = [a*cosd(60); a*sind(60)]; % [km]
% Dominant acceleration of asteroid wrt sun [km/s^2]
a_sa_dominant
                    = -(mu_sun + mu_asteroid)*r_sun_asteroid...
                   /(norm(r sun asteroid)^3)
a sa dominant = 2 \times 1
     -1.0954938498391e-07
    -1.89745100730055e-07
% Magnitude of dominant acceleration of asteroid wrt sun
a_sa_dominant_mag = norm(a_sa_dominant)
a sa dominant mag =
      2.1909876996782e-07
% Position vector from asteroid to Jupiter [km]
r asteroid_jupiter = r_sun_jupiter - r_sun_asteroid;
% Direct perturbing acceleration due to Jupiter on asteroid wrt sun [km/s^2]
a_sa_direct
                       = mu_jupiter*r_asteroid_jupiter/(norm(r_asteroid_jupiter)^3)
a_sa_direct = 2×1
       1.045968696341e-10
    -1.81167092518919e-10
% Magnitude of direct perturbing acceleration on asteroid wrt sun
                        = norm(a_sa_direct)
a_sa_direct_mag
a sa direct mag =
       2.091937392682e-10
% Indirect perturbing acceleration due to Jupiter on asteroid wrt sun [km/s^2]
                         = mu jupiter*r sun jupiter/(norm(r sun jupiter)^3)
a_sa_indirect
a sa indirect = 2 \times 1
       2.091937392682e-10
```

```
% Net perturbing acceleration on asteroid wrt sun
                            = a sa direct - a sa indirect
 a sa pertubing
 a sa pertubing = 2 \times 1
       -1.045968696341e-10
      -1.81167092518919e-10
 % Magnitude of perturbing acceleration on asteroid wrt sun
 a sa pertubing mag
                             = norm(a sa pertubing)
 a_sa_pertubing_mag =
        2.091937392682e-10
 % Net acceleration of asteroid wrt sun
                             = a_sa_dominant + a_sa_pertubing
 a_sa_net
 a sa net = 2 \times 1
      -1.09653981853544e-07
      -1.89926267822574e-07
 % Magnitude of net acceleration of asteroid wrt sun
                              = norm(a_sa_net)
 a_sa_net_mag
 a_sa_net_mag =
      2.19307963707088e-07
Problem 1- ii) - Acceleration of asteroid relative to Jupiter
 % Relevant position vectors
 r asteroid sun
                           = -r_sun_asteroid;
 r jupiter sun
                           = -r sun jupiter;
 r_jupiter_asteroid
                           = -r_asteroid_jupiter;
 % Dominant acceleration of asteroid wrt Jupiter [km/s^2]
                           = -(mu_jupiter + mu_asteroid)*r_jupiter_asteroid...
 a_ja_dominant
                              /(norm(r jupiter asteroid)^3)
 a ja dominant = 2 \times 1
      1.04596877888743e-10
      -1.81167106816381e-10
 % Magnitude of dominant acceleration of asteroid wrt Jupiter
 a_ja_dominant_mag
                           = norm(a ja dominant)
 a ja dominant mag =
       2.09193755777486e-10
 % Direct perturbing acceleration due to sun on asteroid wrt Jupiter [km/s^2]
                           = mu_sun*r_asteroid_sun/(norm(r_asteroid_sun)^3)
 a_ja_direct
 a_ja_direct = 2×1
      -1.09549384975655e-07
      -1.89745100715758e-07
 % Magnitude of direct perturbing acceleration on asteroid wrt Jupiter
                          = norm(a ja direct)
 a ja direct mag
```

```
% Indirect perturbing acceleration due to sun on asteroid wrt Jupiter [km/s^2]
a_ja_indirect
                          = mu sun*r jupiter sun/(norm(r jupiter sun)^3)
a ja indirect = 2 \times 1
    -2.19098769951311e-07
% Net perturbing acceleration on asteroid wrt Jupiter
                           = a_ja_direct - a_ja_indirect
a ja pertubing
a_ja_pertubing = 2×1
     1.09549384975655e-07
    -1.89745100715758e-07
% Magnitude of perturbing acceleration on asteroid wrt Jupiter
a ja pertubing mag
                            = norm(a_ja_pertubing)
a ja_pertubing_mag =
     2.19098769951311e-07
% Net acceleration of asteroid wrt Jupiter
                            = a_ja_dominant + a_ja_pertubing
a_ja_net
a ja net = 2 \times 1
     1.09653981853544e-07
    -1.89926267822574e-07
% Magnitude of net acceleration of asteroid wrt Jupiter
a_ja_net_mag
                             = norm(a_ja_net)
a_ja_net_mag =
     2.19307963707088e-07
```

Problem 3b)

```
% Radius of Earth [km]
r earth
            = 6378.1363;
altitude
            = 8560;
                                 % [km]
% Position vector from Earth CG to spacecraft (polar coordinates)
r_earth_sc = [r_earth + altitude;0;0];
% Inertial velocity of spacecraft relative to earth (polar coordinates)
v_earth_sc = [-2.11;4.89;0];
                                 % [km/s]
                                 % Spacecraft mass [kg]
m_sc
            = 300;
% Gravitational constant km<sup>3</sup>/kg-s<sup>2</sup>
            = 6.6743e-11*(1/1000)^3;
            = 398600.4415/G;
                                 % Earth mass
m earth
% Total system angular momentum
C3
            = (m_earth*m_sc)*cross(r_earth_sc,v_earth_sc)...
              /(m_earth + m_sc) % [kg-km^2/s]
```

```
C3 = 3 \times 1
                        0
             21914245.9521
 % Specific angular momentum
 h_vec
               = cross(r_earth_sc,v_earth_sc) % [km^2/s]
 h_{vec} = 3 \times 1
                        0
                         a
              73047.486507
 % Total system kinetic energy
                = 1/2*(m_earth*m_sc)*dot(v_earth_sc,v_earth_sc)...
                 /(m_earth + m_sc) \% [kg-km^2/s^2]
 T =
                   4254.63
 % Gravitional potential
 U
                 = G*m_earth*m_sc/norm(r_earth_sc);
 % Total energy
 C4
                 = T - U
                                     % [kg-km<sup>2</sup>/s<sup>2</sup>]
 C4 =
          -3750.39352157545
 % Magnitude of angular momentum
                 = norm(h_vec);
 h
 % Gravitional parmeter
                 = G*(m_earth + m_sc);
 % Specific energy
 Ε
                 = norm(v_earth_sc)^2/2 - mu/norm(r_earth_sc)
 E =
          -12.5013117385848
 % Areal velocity
 Adot
                   = h/2 \% [km^2/s]
 Adot =
             36523.7432535
Problem 3d)
 % Semi-latus rectum
                   = h^2/mu % [km]
 р
 p =
           13386.6768057515
```

= cross(v_earth_sc,h_vec)/mu -...

% Eccentricity vector

e_vec

```
r earth sc/norm(r earth sc);
% Eccentricity
                  = norm(e vec)
e
e =
        0.400383443095008
% Semi-major axis
                   = p/(1 - e^2) \% [km]
sma
sma =
        15942.3446849075
% Orbital Period
period
                    = 2*pi*sqrt(sma^3/mu)/3600 % [hours]
period =
        5.56463613853122
% Flight path angle
                    = acosd(v_earth_sc(2)/norm(v_earth_sc))
gamma
gamma =
        23.3398520112336
% True anomaly
                    = acosd((p/norm(r_earth_sc) - 1)/e) % [deg]
theta_star
theta star =
         105.03439032896
% Rotation matrix from Inertial p & e frame to polar frame
                    = [cosd(theta_star), sind(theta_star), 0;...
DCM_C_I
                        -sind(theta_star), cosd(theta_star), 0;...
                        0, 0, 1];
% Position vector in semi-latus rectum and eccentricity unit vectors
r_earth_sc_ep
                     = DCM_C_I'*r_earth_sc
r_earth_sc_ep = 3 \times 1
        -3874.93419372084
        14426.8084173774
% Velocity vector in semi-latus rectum and eccentricity unit vectors
                      = DCM_C_I'*v_earth_sc
v_earth_sc_ep
v_earth_sc_ep = 3 \times 1
        -4.17528537426884
        -3.30623532789436
```

Problem 3e)

```
% Circular velocity
Vc = sqrt(mu/norm(r_earth_sc_ep))
```

Vc =

5.16559887511456

% Magnitude of relative velocity
v_mag = norm(v_earth_sc_ep)

v_mag =

5.32580510345619