

# HW10

#1a) Find:  $\bar{r}_i, \bar{v}_i$  in Earth Inertial coordinates at departure (Ascending Node)

Assume: Circular orbit about Earth, Departure at Ascending node  
 $a = 4R_E, \Omega = 60^\circ, e = 0, \omega = 45^\circ, i = 28.5^\circ, N = 90^\circ$

Circular Orbit  $\therefore r_i = a = 4R_E$

$$\bar{r} = 25512.5452 \text{ [Km]} \quad \hat{r}$$

$$[IR] = \begin{pmatrix} C_n C_\theta - S_n C_i S_\theta & -C_n S_\theta - S_n C_i C_\theta & S_n S_i \\ S_n S_\theta + C_n C_i S_\theta & -S_n S_\theta + C_n C_i C_\theta & -C_n S_i \\ S_i S_\theta & S_i C_\theta & C_i \end{pmatrix}$$

At ascending node:  $\theta = 0^\circ \therefore$  at departure

$$[IR] = \begin{pmatrix} 0.5 & -0.761 & 0.413 \\ 0.866 & 0.439 & -0.238 \\ 0 & 0.477 & 0.8788 \end{pmatrix}$$

$$[\bar{r}_i]_I = [IR] [\bar{r}_i]_R$$

$$= [IR] \begin{bmatrix} r_i \\ 0 \\ 0 \end{bmatrix} = 0.5 r_i \hat{x} + 0.866 r_i \hat{y}$$

$$r_i = 12756.27 \hat{x} + 22094.51 \hat{y} \text{ [Km]}$$

$$\epsilon = \frac{-\mu_0}{2a} = \frac{V_i^2}{2} - \frac{\mu_0}{r_i}, \text{ circular orbit if } r=a$$

$V_i = \sqrt{\frac{\mu_0}{r_i}}$ , circular orbit so  $\vec{V}$  is tangential to path,  $\gamma_i = 0^\circ$

$$\vec{V}_i = V_i \sin(\gamma_i) \hat{r} + V_i \cos(\gamma_i) \hat{\theta} = \sqrt{\frac{\mu_0}{r_i}} \hat{\theta} = 3.952 \text{ [km/s]} \hat{\theta}$$

$$\vec{V}_i = 3.952 \hat{\theta} \text{ [km/s]}$$

$$[\vec{V}_i]_F = [IR] [\vec{V}_i]_R = [IR] \begin{bmatrix} 0 \\ V_i \\ 0 \end{bmatrix} = -0.761 V_i \hat{x} + 0.439 V_i \hat{y} + 0.477 V_i \hat{z}$$

$$\boxed{\vec{V}_i = -3.0083 \hat{x} + 1.7368 \hat{y} + 1.8860 \hat{z} \text{ [km/s]}}$$

#15) Find:  $\vec{r}_2, \vec{v}_2$  in Earth Inertial Frame at arrival

Assume:  $a = 6 R_\oplus, e = 0, \gamma = 60^\circ, \omega = 45^\circ, i = 45^\circ, M = 0, \Theta = 120^\circ$

$$[IR] = \begin{pmatrix} -0.7803 & -0.1268 & 0.6123 \\ -0.1268 & -0.9207 & -0.3535 \\ 0.6123 & 0.3535 & 0.7071 \end{pmatrix}$$

$$r_2 = 6 R_\oplus = a = 38268.82 \text{ [km]} \quad (\text{circular orbit})$$

$$\vec{r}_2 = 38268.82 \hat{r} \text{ [km]}$$

$$[\vec{r}_2]_I = [IR] [\vec{r}_2]_R = -0.7803 r_2 \hat{x} - 0.1268 r_2 \hat{y} + 0.6123 r_2 \hat{z}$$

$$\boxed{\vec{r}_2 = -29862.31 \hat{x} - 4853.50 \hat{y} + 23434.77 \hat{z} \text{ [km]}}$$

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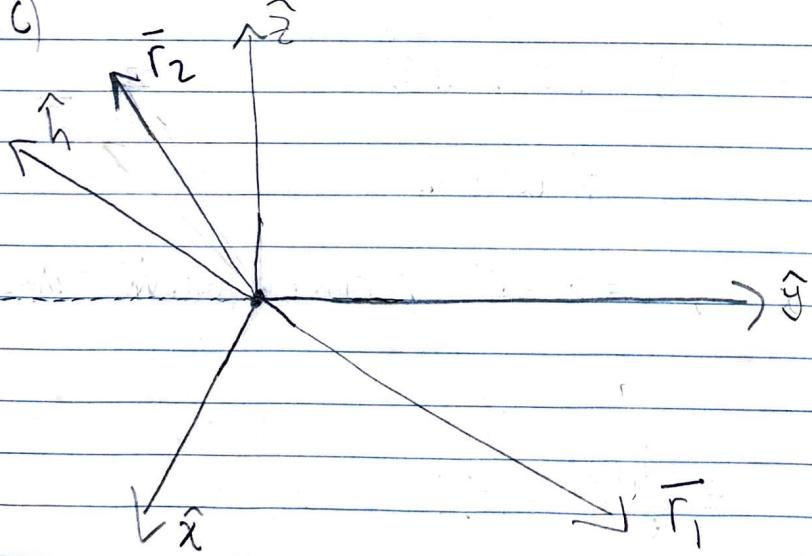
$$V_2 = \sqrt{\frac{\mu_{\oplus}}{r_2}} = 3.227 \text{ km/s}$$

Circular orbit,  $\gamma_2 = 0 \therefore \vec{V}_2 = 3.227 \hat{\theta} [\text{km/s}]$

$$[\vec{v}_2]_{\vec{r}} = [IR] [\vec{v}_2]_r = -0.1268 V_2 \hat{x} - 0.9267 V_2 \hat{y} + 0.3535 V_2 \hat{z}$$

$$\boxed{\vec{V}_2 = -0.4093 \hat{x} - 2.9910 \hat{y} - 1.1410 \hat{z} [\text{km/s}]}$$

#10)



#1c-ii)

$$\hat{h} = \frac{\bar{r}_1 \times \bar{r}_2}{|\bar{r}_1 \times \bar{r}_2|} \quad (\bar{r}_1 \text{ & } \bar{r}_2 \text{ are in same transfer arc plane, } \therefore \hat{h} \text{ is } \perp \text{ to plane of transfer})$$

$$\bar{r}_1 \times \bar{r}_2 = \begin{pmatrix} \hat{x} \\ \hat{y} \\ \hat{z} \end{pmatrix} \begin{pmatrix} 12756.27 \\ 22094.51 \\ 0 \end{pmatrix} - 4853.50 \begin{pmatrix} -29862.31 \\ 28934.77 \\ 0 \end{pmatrix}$$

$$= 51777474.64 \hat{x} - 298940203.81 \hat{y} + 597880607.63 \hat{z}$$

$$|\bar{r}_1 \times \bar{r}_2| = 845530863.99$$

$$\hat{h} = 0.612 \hat{x} - 0.3535 \hat{y} + 0.7071 \hat{z}$$

$$\hat{h} = \sin i \hat{x} - \cos i \hat{y} + \cos i \hat{z}$$

$$\cos(i) = 0.7071, \quad i = \pm 45^\circ, \quad \text{choose positive value}$$

$$i = 45^\circ$$

$$\tan(\theta) = \frac{0.612}{0.3535} \Rightarrow \frac{\sin i}{\cos i} \Rightarrow i = 60^\circ$$

Both 0.612 & 0.3535 are positive  $\therefore \theta$  in Quadrant I

$$\theta = 60^\circ$$

$$\hat{\theta}_1 = \hat{h} \times \hat{r}_1$$

$$\hat{\theta}_2 = \hat{h} \times \hat{r}_2$$

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$$\hat{r}_1 = \frac{r_1}{|r_1|} = 0.5 \hat{x} + 0.866 \hat{y}$$

$$\hat{r}_2 = \frac{r_2}{|r_2|} = -0.7803 \hat{x} - 0.1268 \hat{y} + 0.6124 \hat{z}$$

$$\hat{\theta}_1 = \begin{pmatrix} \hat{x} & \hat{y} & \hat{z} \\ 0.612 & -0.3535 & 0.7071 \\ 0.5 & 0.866 & 0 \end{pmatrix} = -0.612 \hat{x} + 0.3535 \hat{y} + 0.7071 \hat{z}$$

$$\hat{\theta}_2 = \begin{pmatrix} \hat{x} & \hat{y} & \hat{z} \\ 0.612 & -0.3535 & 0.7071 \\ 0 & 0 & 0 \end{pmatrix} = -0.1268 \hat{x} - 0.92677 \hat{y} - 0.3535 \hat{z}$$

$$\hat{z}_1 = \sin \theta_1 \hat{r}_1 + \sin \theta_2 \hat{\theta}_1 + \cos \theta_1 \hat{i}$$

$$\hat{z}_1 = 0.0 \hat{r}_1 + 0.7071 \hat{\theta}_1 + 0.7071 \hat{i}$$

$$\tan \theta_1 = \frac{\sin(i) \sin(\theta_1)}{\sin(i) \cos(\theta_1)} = \frac{0}{0.7071} \Rightarrow \theta_1 = 0, 180$$

0.7071 is positive  $\therefore \theta_1$  is in Quad 1

$$\underline{\theta_1 = 0}$$

$$\tan \theta_2 = \frac{\sin(i) \sin(\theta_2)}{\sin(i) \cos(\theta_2)} = \frac{0.6124}{-0.3535} \Rightarrow \theta_2 = 120, 300$$

0.6124 is positive & -0.3535 is negative  $\therefore \theta_2$  is in Quad 2.

$$\underline{\theta_2 = 120}$$

$$TA = \theta_2 - \theta_1 \quad (\text{Transfer angle})$$

$$TA = 120^\circ$$

$$\text{IC-iii)} \quad P = 5 R_\oplus = 31890.68 \text{ [km]}$$

$$h = \sqrt{\mu_p}$$

$$h = 112745.91 \text{ [Km}^2/\text{s}]$$

$$\bar{r}_2 = \underbrace{\left[ 1 - \frac{r_2}{P} (1 - \cos(\Delta\phi)) \right]}_f \bar{r}_1 + \underbrace{\frac{r_2 r_1}{\mu_p} \sin(\Delta\phi)}_g \bar{v}_1$$

$$\bar{v}_1 = \frac{\bar{r}_2 - f \bar{r}_1}{g}$$

$$f = \left[ 1 - \frac{6R_\oplus}{5R_\oplus} (1 - \cos(120^\circ)) \right] = -0.8$$

$$g = 7499.44 \text{ [s}^2]$$

$$\bar{v}_1 = -2.621 \hat{x} + 1.7097 \hat{y} + 3.1248 \hat{z} \text{ [Km/s]}$$

$$\epsilon = \frac{-\mu}{2a} = \frac{v_1^2}{2} \cdot \frac{\mu}{r_1}$$

$$V_1 = 4.422 \text{ Km/s}$$

$$\epsilon = -5.844 \text{ Km}^2/\text{s}^2$$

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$$a = \frac{-\mu}{2e}$$

$$a = 34100.93 \text{ [Km]}$$

$$P = a(1 - e^2)$$

$$e = \sqrt{1 - \frac{P}{a}}$$

$$e = 0.2546$$

$$r_1 = \frac{P}{1 - e \cos(\theta_1)} \Rightarrow \theta_1^* = \pm \cos^{-1} \left( \frac{1}{e} \left( \frac{P}{r_1} - 1 \right) \right)$$

$$\theta_1^* = \pm 10.89^\circ \quad \bar{r}_1 \cdot \bar{v}_1 = 4339.59 > 0 \quad \therefore \theta_1^* > 0 \\ \therefore \text{ascending}$$

$$\theta_1^* = 10.89^\circ$$

$$h = r_1 v_1 \cos(\gamma_1) \Rightarrow \gamma_1 = \cos^{-1} \left( \frac{h}{r_1 v_1} \right), \text{ ascension so } \gamma_1 > 0$$

$$\gamma_1 = 2.204^\circ$$

$$\bar{v}_2 = \dot{F} \bar{r}_1 + \dot{g} \bar{v}_1$$

$$\dot{F} = \frac{\bar{r}_1 \cdot \bar{v}_1}{P r_1} [1 - \cos(\Delta\theta)] - \frac{1}{r_1} \sqrt{\frac{\mu}{P}} \sin(\Delta\theta) = -1.12 \times 10^{-4} \text{ [Vs]}$$

$$\dot{g} = 1 - \frac{r_1}{P} (1 - \cos(\Delta\theta)) = -0.2$$

$$\bar{v}_2 = -0.9046 \hat{x} - 2.8167 \hat{y} - 0.6250 \hat{z} \text{ [Km/s]}$$

$$\theta_2^* = \cos^{-1}\left(\frac{1}{e}\left(\frac{p}{a} - 1\right)\right) = \pm 130.9$$

$$r_2 \cdot v_2 = 26037 > 0 \quad \therefore \quad \theta_2^* > 0, \text{ ascending}$$

$$\boxed{\theta_2^* = 130.9^\circ}$$

$$h = r_2 v_2 \cos(\gamma_2) \quad \gamma_2 > 0, \text{ ascension}$$

$$\gamma_2 = \cos^{-1}\left(\frac{h}{r_2 v_2}\right)$$

$$\boxed{\gamma_2 = 13.0^\circ}$$

$$\tan\left(\frac{\theta^*}{2}\right) = \sqrt{\frac{1+e}{1-e}} \tan\left(\frac{\epsilon}{2}\right) \Rightarrow$$

$$E = 2 \tan^{-1}\left(\frac{\tan(\theta^*)}{\sqrt{\frac{1+e}{1-e}}}\right)$$

$$E_1 = 0.1467 \text{ [rad]}$$

$$E_2 = 2.0715 \text{ [rad]}$$

$$M_1 = E_1 - e \sin(E_1) = 0.1095$$

$$M_2 = E_2 - e \sin(E_2) = 1.8482$$

$$M_1 = n(t_1 - t_p) \Rightarrow t_1 = \frac{M_1}{n} + t_p$$

$$M_2 = n(t_2 - t_p) \Rightarrow t_2 = \frac{M_2}{n} + t_p$$

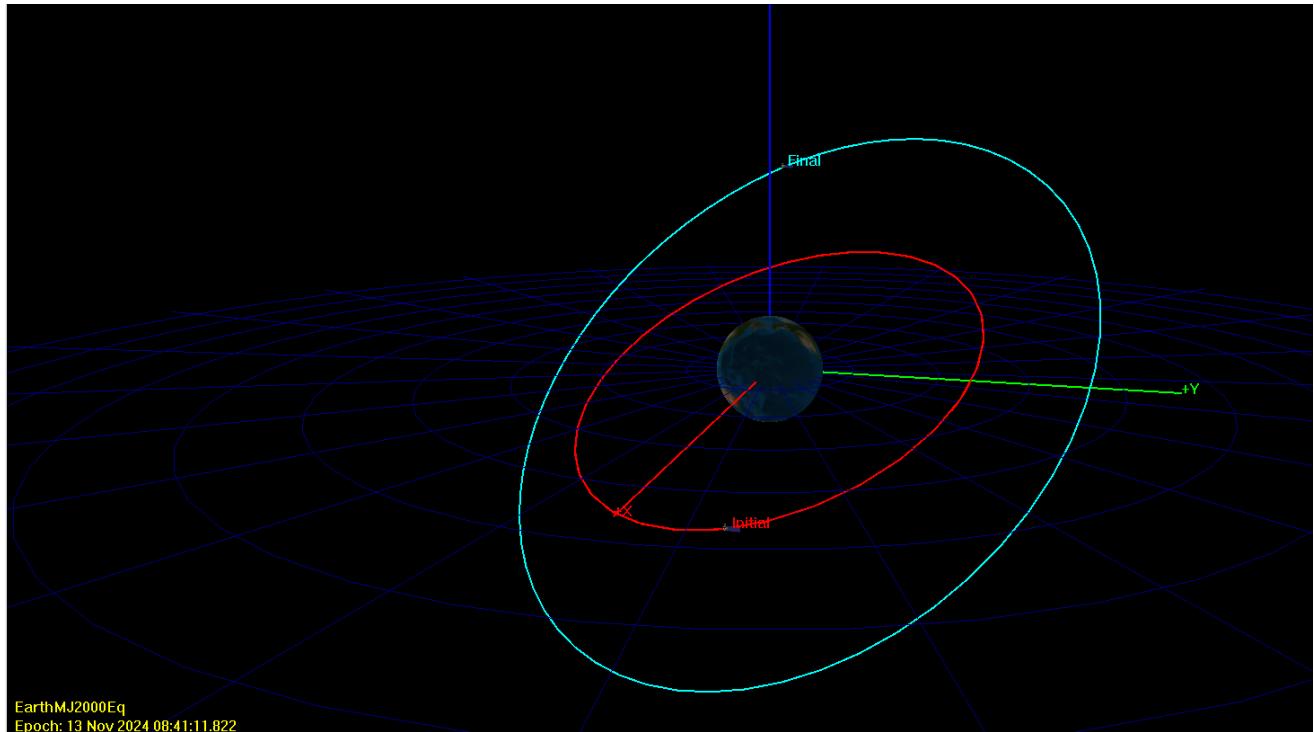
$$t_2 - t_1 = \frac{1}{n}(M_2 - M_1) = T.O.F.$$

$$n = \sqrt{\frac{m}{a^3}} = 1.0026 \times 10^{-4} [\text{ks}]$$

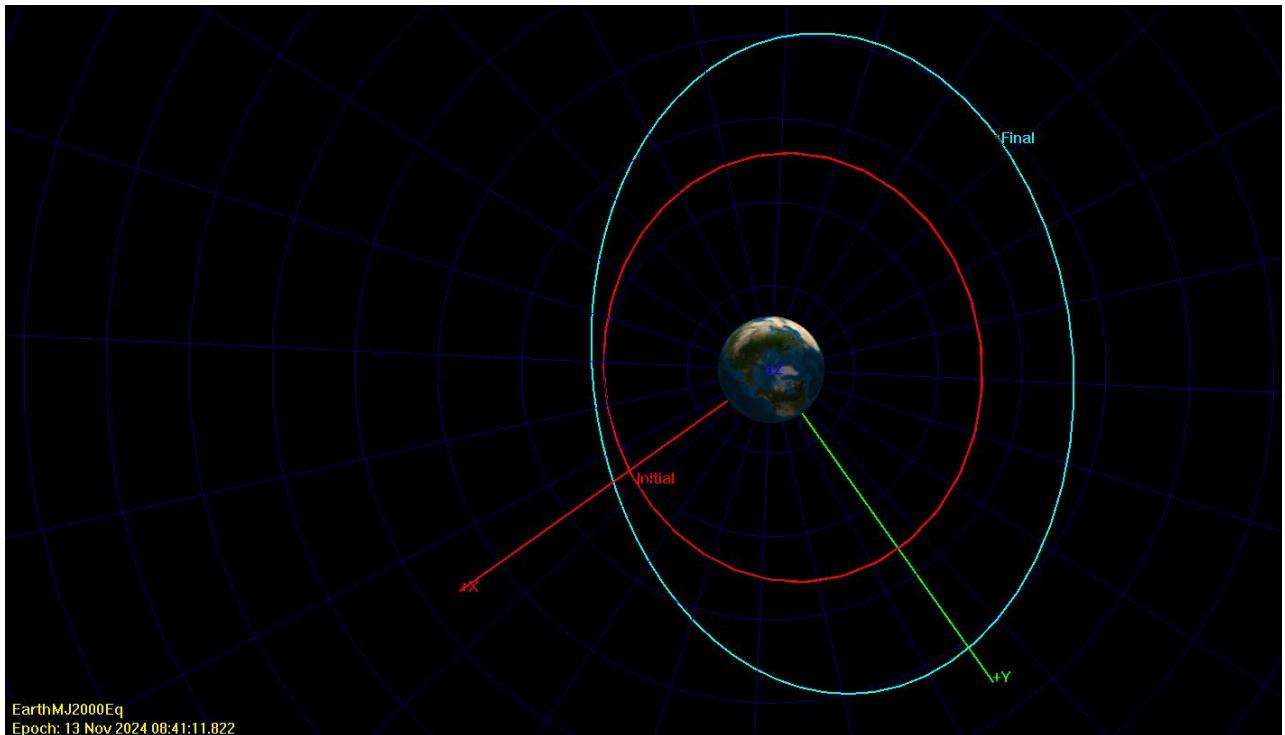
$$\text{TOF} = \frac{1}{1.0026 \times 10^{-4}} (1.848 - 0.1095) = 17342.26 [\text{s}]$$

$$\boxed{\text{TOF} = 4.82 [\text{hours}]}$$

**Problem 1a & 1b)**



*Figure 1: Problem 1a and 1b*



*Figure 2: Problem 1a and*

	Initial	Final
X [km]	12756.2726	-29862.30988
Y [km]	22094.51226	-4853.49961
Z [km]	0	23434.76917
Vx [km/s]	-3.008299911	-0.409313734
Vy [km/s]	1.736842764	-2.991034821
Vz [km/s]	1.886057356	-1.141041319

The values obtained from GMAT are listed in the table above. These results match the handwritten results, confirming their accuracy. In the figures on the previous pages, the red line is the orbit from problem 1a, and the blue line is the orbit from problem 1b.

#### Problem 1d)

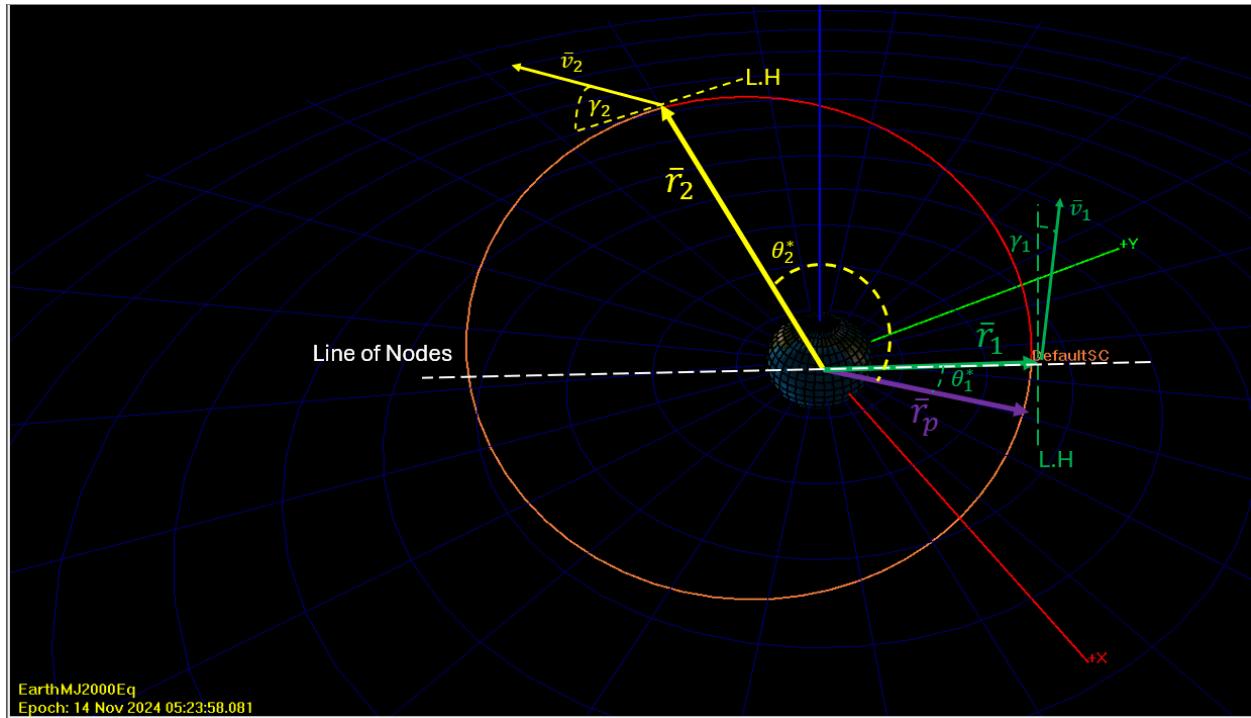


Figure 3: Problem 1d

The transfer ellipse is plotted in the figure above. The transfer arc is denoted by the red line, while the orange line comprises the rest of the transfer ellipse. Based off the orbit, it can be determined that the transfer type is a **1A** because the transfer angle is  $< 180$  (transfer angle is 120) and the vacant focus is outside the chord and arc.