

# **ECE 602: LUMPED LINEAR SYSTEMS**

Professor Stan Žak

Minimal Realizations of Transfer Function  
Matrices

# Minimal Realizations of Transfer Function Matrices

- A transfer function  $G(s)$  is realizable if there exists a quadruple of constant matrices  $(A, B, C, D)$  such that  $G(s) = C(sI_n - A)^{-1}B + D$ . We call such a quadruple  $(A, B, C, D)$  a realization of  $G(s)$

## Definition

The dimension of a realization is the size of the matrix  $A$ , that is, if  $A$  is an  $n$ -by- $n$  matrix then we say that the dimension of the corresponding realization is  $n$

- Objective:** Find a **minimal** state-space realization a transfer function matrix of a linear lumped system either discrete or continuous time-invariant multi-input multi-output (MIMO) system

# Realizations of a transfer function matrix of a multi-input multi-output (MIMO) system

- Different methods may yield realizations of different dimensions
- A proper rational transfer function matrix has infinitely many realizations of different dimensions
- A realization with the smallest possible dimension is called a minimal realization
- Necessary and sufficient conditions for a realization to be minimal was given by Kalman in 1963

# Necessary and Sufficient Condition for a Realization to be Minimal

## Theorem

*A realization  $(\mathbf{A}, \mathbf{B}, \mathbf{C}, \mathbf{D})$  of a given transfer function matrix  $\mathbf{G}(s)$  is minimal if and only if the pair  $(\mathbf{A}, \mathbf{B})$  is reachable and the pair  $(\mathbf{A}, \mathbf{C})$  is observable*

# Can always lower the dimension of a realization if it is not reachable/observable!

- If a realization  $(\mathbf{A}, \mathbf{B}, \mathbf{C}, \mathbf{D})$  is non-reachable, separate the reachable part from the non-reachable one
- That is, construct a similarity transformation  $\mathbf{z} = \mathbf{T}\mathbf{x}$  such that

$$\tilde{\mathbf{A}} = \mathbf{T}\mathbf{A}\mathbf{T}^{-1} = \left[ \begin{array}{c|c} \mathbf{A}_1 & \mathbf{A}_2 \\ \hline \mathbf{O} & \mathbf{A}_4 \end{array} \right], \quad \tilde{\mathbf{B}} = \mathbf{T}\mathbf{B} = \left[ \begin{array}{c} \mathbf{B}_1 \\ \hline \mathbf{O} \end{array} \right],$$

where the pair  $(\mathbf{A}_1, \mathbf{B}_1)$  is reachable  $\mathbf{A}_1 \in \mathbb{R}^{r \times r}$ ,  $\mathbf{B}_1 \in \mathbb{R}^{r \times m}$

- The matrix  $\mathbf{C}$  becomes

$$\tilde{\mathbf{C}} = \mathbf{C}\mathbf{T}^{-1} = \left[ \mathbf{C}_1 \mid \mathbf{C}_2 \right],$$

where  $\mathbf{C}_1 \in \mathbb{R}^{p \times r}$ , and  $\tilde{\mathbf{D}} = \mathbf{D}$

# Lowering the dimension of a realization

- The transfer functions of  $(\mathbf{A}, \mathbf{B}, \mathbf{C}, \mathbf{D})$  and  $(\tilde{\mathbf{A}}, \tilde{\mathbf{B}}, \tilde{\mathbf{C}}, \mathbf{D})$  are the same because the transfer function is invariant under similarity transformations
- We have

$$\begin{aligned} G(s) &= \mathbf{C} (s\mathbf{I}_n - \mathbf{A})^{-1} \mathbf{B} + \mathbf{D} \\ &= \tilde{\mathbf{C}} (s\mathbf{I}_n - \tilde{\mathbf{A}})^{-1} \tilde{\mathbf{B}} + \mathbf{D} \\ &= \left[ \begin{array}{c|c} \mathbf{C}_1 & \mathbf{C}_2 \end{array} \right] \left[ \begin{array}{c|c} s\mathbf{I}_r - \mathbf{A}_1 & -\mathbf{A}_2 \\ \hline \mathbf{O} & s\mathbf{I}_{n-r} - \mathbf{A}_4 \end{array} \right]^{-1} \left[ \begin{array}{c} \mathbf{B}_1 \\ \hline \mathbf{O} \end{array} \right] + \mathbf{D} \\ &= \mathbf{C}_1 [s\mathbf{I}_r - \mathbf{A}_1]^{-1} \mathbf{B}_1 + \mathbf{D} \end{aligned}$$

# Constructing a minimal realization from a given realization

- The quadruple  $(\mathbf{A}_1, \mathbf{B}_1, \mathbf{C}_1, \mathbf{D})$  is a realization of  $\mathbf{G}(s)$  of lower dimension than the realization  $(\mathbf{A}, \mathbf{B}, \mathbf{C}, \mathbf{D})$
- Proceed to check if the pair  $(\mathbf{A}_1, \mathbf{C}_1)$  is observable or not
- If it is, then  $(\mathbf{A}_1, \mathbf{B}_1, \mathbf{C}_1, \mathbf{D})$  is a minimal realization of  $\mathbf{G}(s)$
- If, on the other hand, the pair  $(\mathbf{A}_1, \mathbf{C}_1)$  is not observable, extract from the pair  $(\mathbf{A}_1, \mathbf{C}_1)$  an observable part
- This observable part along with corresponding input sub-matrix and the matrix  $\mathbf{D}$  form a minimal realization of  $\mathbf{G}(s)$

## Example

- Can obtain a minimal realization of a given transfer function matrix using MATLAB's function `ss`
- Construct a minimal realization of the transfer function matrix

$$\mathbf{G}(s) = \begin{bmatrix} \frac{1}{s(s+2)} & \frac{2s-1}{s(s+2)} & \frac{s-1}{s(s+2)} \\ -\frac{1}{s+2} & \frac{1-s}{s^2+3s+2} & \frac{1}{s^2+3s+2} \end{bmatrix}.$$

- Represent the tf as

```
G=[tf([1],[1 2 0]) tf([2 -1],[1 2 0]) tf([1 -1],[1 2 0]);...  
   tf([-1],[1 2]) tf([-1 1],[1 3 2]) tf([1],[1 3 2])]
```

- Then type in

```
sys = ss(G,'min')
```



# Minimal realization

$$\begin{aligned} \mathbf{A} &= \begin{bmatrix} -0.2586 & -0.3622 & 0.1951 & -0.4402 \\ -0.3806 & -1.675 & 0.6493 & 0.3853 \\ -1.046 & 0.519 & -1.267 & 0.6196 \\ 1.082 & 0.1781 & 1.258 & -1.799 \end{bmatrix} \\ \mathbf{B} &= \begin{bmatrix} 0.4118 & -0.3924 & -0.4021 \\ 0.612 & 0.434 & -0.08897 \\ -0.5916 & -1.032 & -0.2202 \\ -0.395 & 1.429 & 0.9121 \end{bmatrix} \\ \mathbf{C} &= \begin{bmatrix} -0.4876 & -0.6661 & -1.355 & 0.4892 \\ -0.8541 & -1.105 & 0.2379 & -0.4269 \end{bmatrix} \\ \mathbf{D} &= \mathbf{O} \end{aligned}$$

# Minimal realization

- Can check, using, for example, MATLAB's functions `ctrb` and `obsv` that the pair  $(\mathbf{A}, \mathbf{B})$  is reachable and the pair  $(\mathbf{A}, \mathbf{C})$  is observable
- Thus the above quadruple is indeed a minimal realization of the given transfer function matrix  $\mathbf{G}(s)$ .

# Minimal realizations of the given $G(s)$ are equivalent

- There are infinitely many different minimal realizations of a given transfer function matrix
- They are related via a similarity transformation
- That is, minimal realizations of a given transfer function matrix are equivalent
- Indeed, suppose we have two different minimal realizations  $(\mathbf{A}_1, \mathbf{B}_1, \mathbf{C}_1, \mathbf{D}_1)$  and  $(\mathbf{A}_2, \mathbf{B}_2, \mathbf{C}_2, \mathbf{D}_2)$  of a given proper transfer function matrix  $\mathbf{G}(s)$
- Then

$$\mathbf{G}(s) = \mathbf{C}_1(s\mathbf{I}_n - \mathbf{A}_1)^{-1}\mathbf{B}_1 + \mathbf{D}_1 = \mathbf{C}_2(s\mathbf{I}_n - \mathbf{A}_2)^{-1}\mathbf{B}_2 + \mathbf{D}_2$$

- Hence, we have to have

$$\mathbf{D}_1 = \mathbf{D}_2$$

# Minimal realizations of the given $G(s)$ are equivalent—Contd

- We have

$$C_1(sI_n - A_1)^{-1}B_1 = C_2(sI_n - A_2)^{-1}B_2$$

- Taking the inverse Laplace transform of both sides yields

$$C_1 e^{A_1 t} B_1 = C_2 e^{A_2 t} B_2$$

- Taking into account that

$$e^{A t} = I + tA + \frac{t^2}{2!}A^2 + \dots = \sum_{k=0}^{\infty} \frac{t^k}{k!} A^k$$

we obtain

$$\sum_{k=0}^{\infty} \frac{t^k}{k!} C_1 A_1^k B_1 = \sum_{k=0}^{\infty} \frac{t^k}{k!} C_2 A_2^k B_2$$

# Markov's parameters

- We obtain

$$\sum_{k=0}^{\infty} \frac{t^k}{k!} \mathbf{C}_1 \mathbf{A}_1^k \mathbf{B}_1 = \sum_{k=0}^{\infty} \frac{t^k}{k!} \mathbf{C}_2 \mathbf{A}_2^k \mathbf{B}_2$$

- That is,

$$\mathbf{C}_1 \mathbf{A}_1^k \mathbf{B}_1 = \mathbf{C}_2 \mathbf{A}_2^k \mathbf{B}_2, \quad k = 0, 1, 2, \dots$$

- The matrices  $\mathbf{C}_i \mathbf{A}_i^k \mathbf{B}_i$  are called **Markov parameters**
- Thus Markov parameters of different realizations of a given transfer function matrix are equal

# Constructing a similarity transformation linking two different minimal realizations of the same tf

- Using Markov parameters, we obtain

$$\begin{bmatrix} C_1 \\ C_1 A_1 \\ \vdots \\ C_1 A_1^{n-1} \end{bmatrix} \begin{bmatrix} B_1 & \cdots & A_1^{n-1} B_1 \end{bmatrix} = \begin{bmatrix} C_2 \\ C_2 A_2 \\ \vdots \\ C_2 A_2^{n-1} \end{bmatrix} \begin{bmatrix} B_2 & \cdots & A_2^{n-1} B_2 \end{bmatrix}$$

- Let

$$\mathcal{U}_i = \begin{bmatrix} B_i & A_i B_i & \cdots & A_i^{n-1} B_i \end{bmatrix}, \quad i = 1, 2$$

and

$$\mathcal{V}_i = \begin{bmatrix} C_i \\ C_i A_i \\ \vdots \\ C_i A_i^{n-1} \end{bmatrix}, \quad i = 1, 2.$$

# Constructing a similarity transformation linking two different minimal realizations

- Then

$$\mathbf{v}_1 \mathbf{u}_1 = \mathbf{v}_2 \mathbf{u}_2$$

Pre-multiplying both sides by  $\mathbf{v}_1^\top$  gives

$$\mathbf{v}_1^\top \mathbf{v}_1 \mathbf{u}_1 = \mathbf{v}_1^\top \mathbf{v}_2 \mathbf{u}_2$$

- Both realizations are minimal, therefore their controllability and observability matrices have full ranks, that is,

$$\text{rank } \mathbf{u}_i = \text{rank } \mathbf{v}_i = n, \quad i = 1, 2$$

# Similarity transformation

- The  $n \times n$  matrix

$$\mathbf{v}_1^\top \mathbf{v}_1$$

is invertible

- Pre-multiply both sides of  $\mathbf{v}_1^\top \mathbf{v}_1 \mathbf{u}_1 = \mathbf{v}_1^\top \mathbf{v}_2 \mathbf{u}_2$  by

$$[\mathbf{v}_1^\top \mathbf{v}_1]^{-1}$$

- We obtain

$$\mathbf{u}_1 = [\mathbf{v}_1^\top \mathbf{v}_1]^{-1} \mathbf{v}_1^\top \mathbf{v}_2 \mathbf{u}_2$$

- Let

$$\mathbf{T}_1 = [\mathbf{v}_1^\top \mathbf{v}_1]^{-1} \mathbf{v}_1^\top \mathbf{v}_2$$

- Then

$$\mathbf{u}_1 = \mathbf{T}_1 \mathbf{u}_2$$



# Minimal realizations are equivalent

- Re-write  $\mathcal{U}_1 = T_1 \mathcal{U}_2$  as

$$\begin{aligned} \begin{bmatrix} B_1 & \cdots & A_1^{n-1} B_1 \end{bmatrix} &= T_1 \begin{bmatrix} B_2 & \cdots & A_2^{n-1} B_2 \end{bmatrix} \\ &= \begin{bmatrix} T_1 B_2 & \cdots & T_1 A_2^{n-1} T_1^{-1} T_1 B_2 \end{bmatrix} \end{aligned}$$

- Recall

$$T_1 A_2^k T_1^{-1} = (T_1 A_2 T_1^{-1})^k$$

- Therefore, the pairs  $(A_1, B_1)$  and  $(A_2, B_2)$  are equivalent
- That is, they are related via the similarity transformation
- In other words,

$$A_1 = T_1 A_2 T_1^{-1} \quad \text{and} \quad B_1 = T_1 B_2$$

- Express the similarity transformation matrix  $T_2$  relating the observability matrices and show that  $T_1 = T_2$

## Example

- Construct a realization of the transfer function

$$G(s) = \frac{4s^3 - 2s^2 + 3s + 1}{s^3 + 3s^2 - 5s + 7}$$

- First, represent  $G(s)$  as

$$G(s) = G(s)_{\text{sp}} + G(\infty) = \frac{-14s^2 + 23s - 27}{s^3 + 3s^2 - 5s + 7} + 4$$

- Using the method we discussed previously

$$\begin{aligned}\dot{\mathbf{x}} &= \mathbf{A}_1 \mathbf{x} + \mathbf{b}_1 u \\ &= \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -7 & 5 & -3 \end{bmatrix} \mathbf{x} + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} u \\ y &= \mathbf{c}_1 \mathbf{x} + d_1 u \\ &= \begin{bmatrix} -27 & 23 & -14 \end{bmatrix} \mathbf{x} + 4u\end{aligned}$$

## Another minimal realization of $G(s)$

- Using the results of the above discussion, we obtain

$$\begin{aligned}\dot{\tilde{\mathbf{x}}} &= \mathbf{A}_2 \tilde{\mathbf{x}} + \mathbf{b}_2 u \\ &= \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -7 & 5 & -3 \end{bmatrix} \tilde{\mathbf{x}} + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} u \\ y &= \mathbf{c}_2 \tilde{\mathbf{x}} + d_2 u \\ &= \begin{bmatrix} -27 & 23 & -14 \end{bmatrix} \mathbf{x} + 4u\end{aligned}$$

- Note that

$$d_1 = d_2 = 4$$

- Construct

$$\mathbf{T}_1 = [\mathbf{v}_1^\top \mathbf{v}_1]^{-1} \mathbf{v}_1^\top \mathbf{v}_2$$

# Verifying the equivalence of the minimal realizations

- Minimal realizations  $(\mathbf{A}_1, \mathbf{b}_1, \mathbf{c}_1, d_1)$  and  $(\mathbf{A}_2, \mathbf{b}_2, \mathbf{c}_2, d_2)$  of  $G(s)$  are equivalent if

$$\mathbf{A}_1 = \mathbf{T}_1 \mathbf{A}_2 \mathbf{T}_1^{-1}, \quad \mathbf{b}_1 = \mathbf{T}_1 \mathbf{b}_2, \quad \mathbf{c}_1 = \mathbf{c}_2 \mathbf{T}_1^{-1}, \quad d_1 = d_2$$

where

$$\mathbf{T}_1 = [\mathbf{v}_1^\top \mathbf{v}_1]^{-1} \mathbf{v}_1^\top \mathbf{v}_2 = \begin{bmatrix} -0.0198 & -0.0555 & -0.0529 \\ -0.0555 & -0.0529 & 0.0201 \\ -0.0529 & 0.0201 & 0.0636 \end{bmatrix}$$

where, in our Example,

$$\mathbf{v}_i = \begin{bmatrix} \mathbf{c}_i \\ \mathbf{c}_i \mathbf{A}_i \\ \mathbf{c}_i \mathbf{A}_i^2 \end{bmatrix} \quad i = 1, 2$$