

## Contents

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```
clear
clc
```

## Problem 1

---

```
disp('--Problem 1 -----')
disp(' ')

T      = [1 0 -2 -1;...
          0 1 2 0; ...
          0 0 1 1;...
          0 0 0 1];
Tinv   = inv(T)
```

```
--Problem 1 -----
```

```
Tinv =

    1     0     2    -1
     0     1    -2     2
     0     0     1    -1
     0     0     0     1
```

## Problem 2

---

### Social Network A-----

---

```
Aa      = [1/4 1/4 1/4 1/4;...
           1/3 1/3 1/3 0;
           1/4 1/4 1/4 1/4;
           1/3 0 1/3 1/3];

% Eigenvalues
lambda_a = eig(Aa);

disp('--Problem 2a -----')
disp(' ')

% Check Algebraic and Geometric Multiplicities
AlgMult_a = GetAlgebraicMultiplicity(lambda_a);
```

```

GeoMult    = GetGeometricMultiplicity(lambda_a, Aa);
[Ta,Ja]    = CheckDiagonalizable(AlgMulta, GeoMulta, lambda_a, Aa)

% left evecs are rows of T^-1
Tainv      = inv(Ta)

```

## Social Network B-----

```

Ab          = [1/3 1/3 0 1/3;...
              1/3 1/3 1/3 0;
              0 1/3 1/3 1/3;
              1/3 0 1/3 1/3];

% Eigenvalues
lambda_b    = eig(Ab);

disp('--Problem 2b -----')
disp(' ')

% Check Algebraic and Geometric Multiplicities
AlgMultb    = GetAlgebraicMultiplicity(lambda_b);
GeoMultb    = GetGeometricMultiplicity(lambda_b, Ab);
[Tb,Jb]     = CheckDiagonalizable(AlgMultb, GeoMultb, lambda_b, Ab)

% left evecs are rows of T^-1
Tbinv       = inv(Tb)

```

## Social Network C-----

```

Ac          = [1/3 1/3 0 1/3;...
              1/3 1/3 1/3 0;
              0 1/2 1/2 0;
              1/2 0 0 1/2];

% Eigenvalues
lambda_c    = eig(Ac);

disp('--Problem 2c -----')
disp(' ')

% Check Algebraic and Geometric Multiplicities
AlgMultc    = GetAlgebraicMultiplicity(lambda_c);
GeoMultc    = GetGeometricMultiplicity(lambda_c, Ac);
[Tc,Jc]     = CheckDiagonalizable(AlgMultc, GeoMultc, lambda_c, Ac)

% left evecs are rows of T^-1
Tcinv       = inv(Tc)

```

## Social Network D-----

```

Ad          = [1/2 0 0 1/2;...
              0 1/2 1/2 0;
              0 1/2 1/2 0;
              1/2 0 0 1/2];

% Eigenvalues
lambda_d    = eig(Ad);

disp('--Problem 2d -----')
disp(' ')

```

```

% Check Algebraic and Geometric Multiplicities
AlgMultd = GetAlgebraicMultiplicity(lambda_d);
GeoMultd = GetGeometricMultiplicity(lambda_d, Ad);
[Td,Jd] = CheckDiagonalizable(AlgMultd, GeoMultd, lambda_d, Ad)

% left evecs are rows of T^-1
Tdinv = inv(Td)

```

---

--Problem 2a -----

```

Eigenvalue of -0.1667 has Alg Mult of 1
Eigenvalue of -0.0000 has Alg Mult of 1
Eigenvalue of 0.3333 has Alg Mult of 1
Eigenvalue of 1.0000 has Alg Mult of 1
Matrix is diagonalizable

```

Ta =

```

0.5000    0.4243   -0.7071    0.0000
0.5000   -0.5657   -0.0000   -0.7071
0.5000    0.4243    0.7071   -0.0000
0.5000   -0.5657   -0.0000    0.7071

```

Ja =

```

1.0000     0     0     0
0   -0.1667     0     0
0     0  -0.0000     0
0     0     0    0.3333

```

Tainv =

```

0.5714    0.4286    0.5714    0.4286
0.5051   -0.5051    0.5051   -0.5051
-0.7071    0.0000    0.7071    0.0000
-0.0000   -0.7071    0.0000    0.7071

```

--Problem 2b -----

```

Eigenvalue of -0.3333 has Alg Mult of 1
Eigenvalue of 0.3333 has Alg Mult of 2
Eigenvalue of 1.0000 has Alg Mult of 1
Matrix is diagonalizable

```

Tb =

```

0.5000    0.3627    0.6070    0.5000
-0.5000   -0.6070    0.3627    0.5000
0.5000   -0.3627   -0.6070    0.5000
-0.5000    0.6070   -0.3627    0.5000

```

Jb =

```

-0.3333     0     0     0
0    0.3333     0     0

```

0	0	0.3333	0
0	0	0	1.0000

T<sub>binv</sub> =

0.5000	-0.5000	0.5000	-0.5000
0.3627	-0.6070	-0.3627	0.6070
0.6070	0.3627	-0.6070	-0.3627
0.5000	0.5000	0.5000	0.5000

--Problem 2c -----

Eigenvalue of -0.2287 has Alg Mult of 1  
 Eigenvalue of 0.1667 has Alg Mult of 1  
 Eigenvalue of 0.7287 has Alg Mult of 1  
 Eigenvalue of 1.0000 has Alg Mult of 1  
 Matrix is diagonalizable

T<sub>c</sub> =

0.5831	-0.3922	0.5000	0.2941
-0.5831	-0.3922	0.5000	-0.2941
0.4001	0.5883	0.5000	-0.6430
-0.4001	0.5883	0.5000	0.6430

J<sub>c</sub> =

-0.2287	0	0	0
0	0.1667	0	0
0	0	1.0000	0
0	0	0	0.7287

T<sub>cinv</sub> =

0.6527	-0.6527	0.2986	-0.2986
-0.5099	-0.5099	0.5099	0.5099
0.6000	0.6000	0.4000	0.4000
0.4061	-0.4061	-0.5918	0.5918

--Problem 2d -----

Eigenvalue of 0.0000 has Alg Mult of 2  
 Eigenvalue of 1.0000 has Alg Mult of 2  
 Matrix is diagonalizable

T<sub>d</sub> =

0	0.7071	0.7071	0
-0.7071	0	0	0.7071
0.7071	0	0	0.7071
0	-0.7071	0.7071	0

J<sub>d</sub> =

0	0	0	0
0	0	0	0
0	0	1	0

0    0    0    1

Tdinv =

0	-0.7071	0.7071	0
0.7071	0	0	-0.7071
0.7071	0	0	0.7071
0	0.7071	0.7071	0

### Problem 3

---

```
disp('--Problem 3 -----')
disp(' ')

% Eigenvectors - from hand written
V1 = [-1; 0; 1]*1/sqrt(2);
V2 = [1;-1;1]*1/sqrt(3);
V3 = [1;1;1]*1/sqrt(3);

T = [V1,V2,V3];
Tinv= inv(T)
```

### Functions

---

```
% Function to find Alg Mult of each Eigenvalue
function am = GetAlgebraicMultiplicity(evals)
    % Initialize
    lam_uni = uniquetol(evals,1e-8); % unique evals
    am      = zeros(size(lam_uni));

    % Check to see how many times each eigenvalue repeats
    for i = 1:length(am)
        ind = find(abs(lam_uni(i) - evals) <= 1e-8);
        am(i) = length(ind);
        fprintf('Eigenvalue of %.4f has Alg Mult of %i \n',lam_uni(i), am(i))
    end
end

% Function to find Geo Mult of each Eigenvalue
function gm = GetGeometricMultiplicity(evals, A)
    % Initialize
    lam_uni = uniquetol(evals,1e-8); % unique evals
    gm      = zeros(size(lam_uni));

    % Check dimension of null space of lamda*I - A
    for i = 1:length(gm)
        gm(i) = size(null(lam_uni(i)*eye(size(A)) - A),2);
    end
end

function [T,J] = CheckDiagonalizable(AlgMult, GeoMult, lambda, A)
    % Check if Matrix is diagonalizable (n distinct evals or AlgMult = GeoMult)
    if (AlgMult == GeoMult)
        disp('Matrix is diagonalizable')
        [T,J] = eig(A);
    elseif ((length(uniquetol(lambda)) == length(lambda)) == 1)
```

```
        disp('Matrix is diagonalizable')
        [T,J] = eig(A);
    else
        disp('Matrix is not diagonalizable')
        [T,J] = jordan(A);
    end
end
```

---

--Problem 3 -----

Tinv =

-0.7071	0.0000	0.7071
0.4330	-0.8660	0.4330
0.4330	0.8660	0.4330