

## Transfer Orbits: Lambert Arcs

Two approaches to mission planning:

- (a) Given the transfer orbit  $\rightarrow$  initial and final positions are specified; relate to the time of flight
- (b) Given the initial (departure) and final (target) points  $\rightarrow$  determine the orbit that passes through the points

**Transfer Orbit Design**  
(special class of boundary value problem)

 **1. Geometrical relationships**

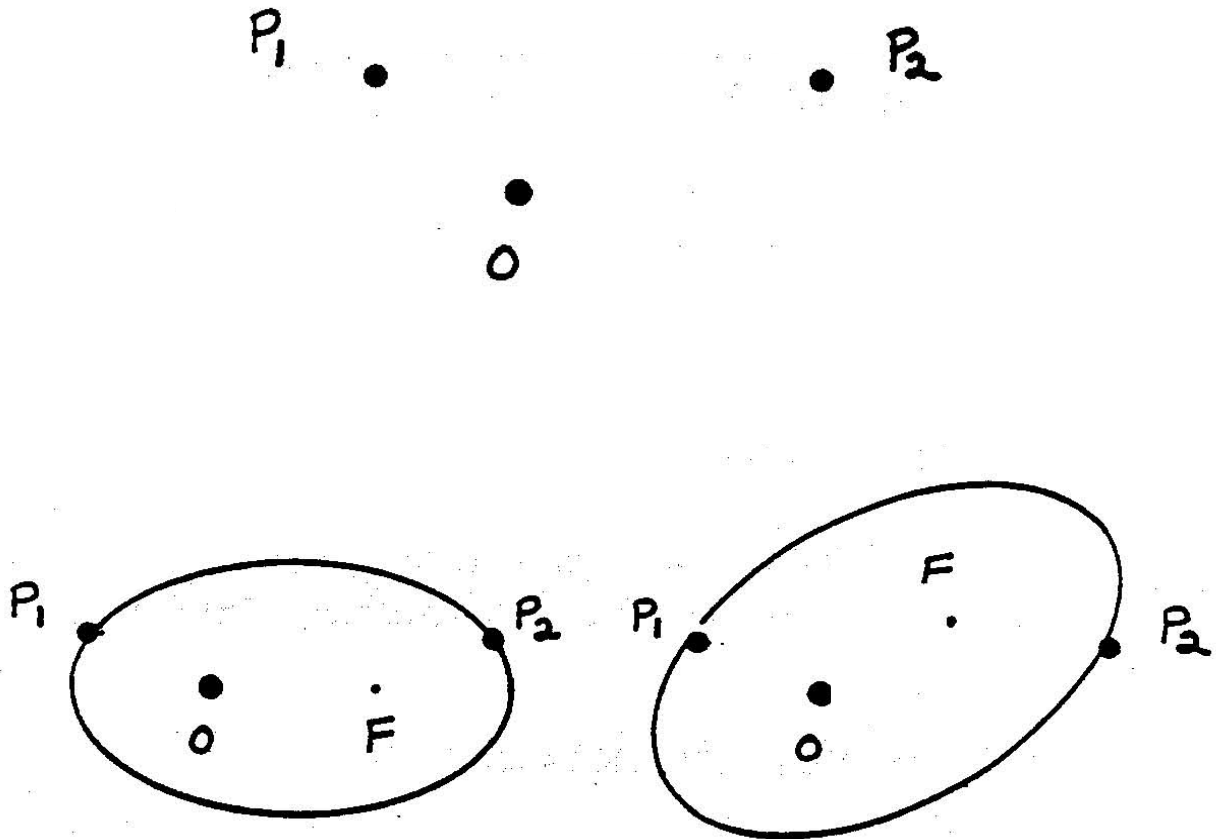
**2. Analytical Relationships**

**3. Lambert's Theorem**

### Geometrical Relationships: Ellipse

Given two fixed points  $P_1, P_2$ ; center of force at point  $O$

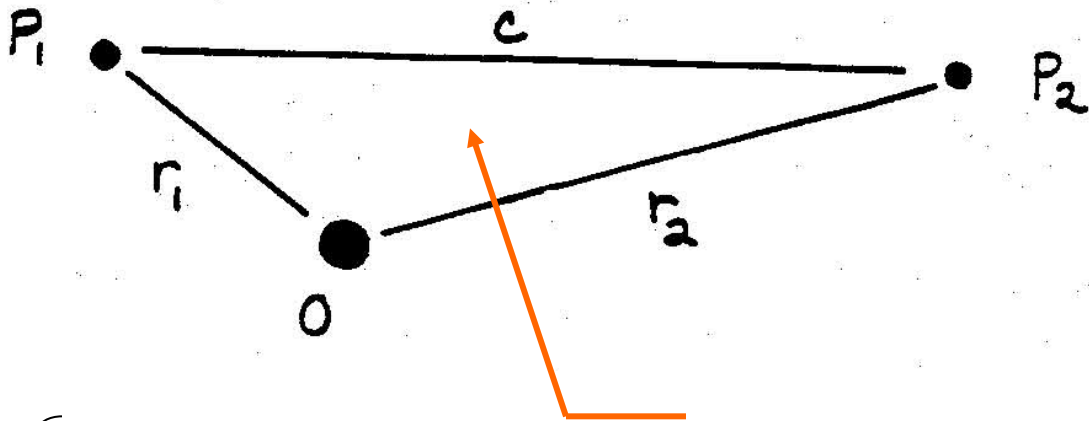
Find: ellipse with focus at point  $O$  that connects  $P_1, P_2$



If  $F$  is not specified →

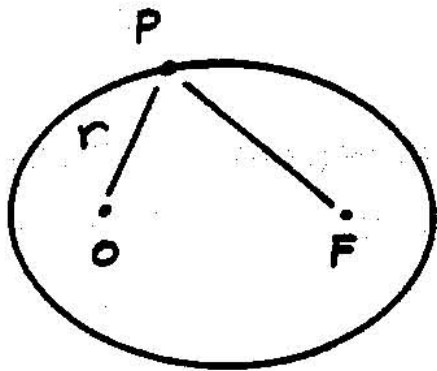
Thus, find the locus of all possible  $F$  locations

Pick one of the  $F$  sites and the ellipse is determined



$$\text{Let } \begin{cases} OP_1 = r_1 \\ OP_2 = r_2 \\ P_1P_2 = c \end{cases}$$

Since  $P_1$  and  $P_2$  must both lie on the same ellipse,  $F$  must be selected such that



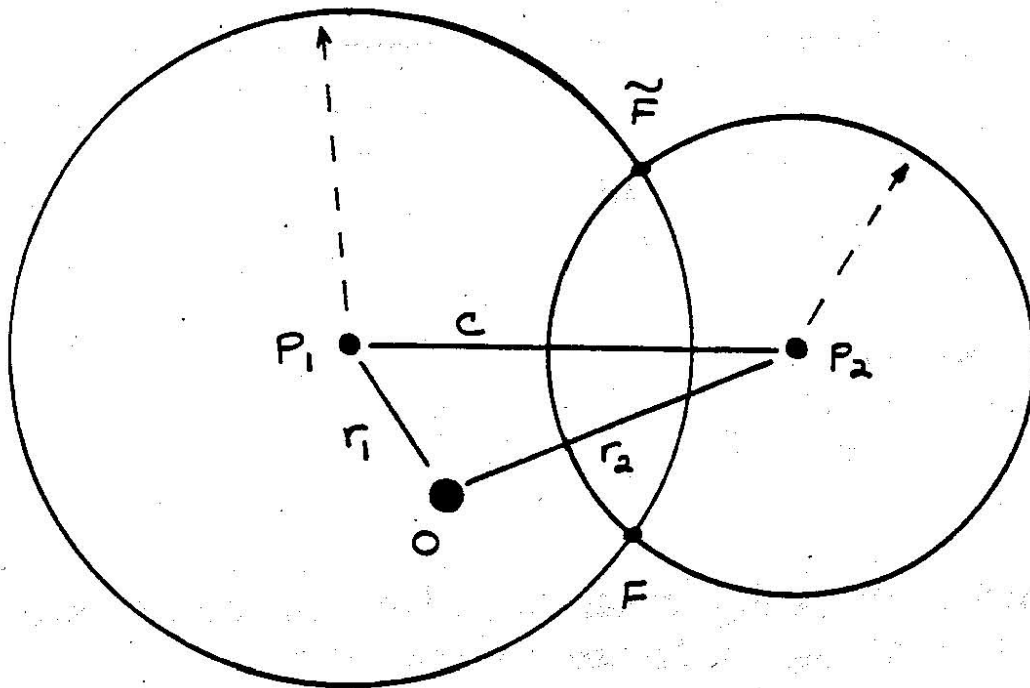
$$\overbrace{OP_1 + P_1F} = 2a = \overbrace{OP_2 + P_2F}$$

(always true for an ellipse)

OR

For ellipse with major axis  $2a$ , point  $F$  determined as the intersection of two circles centered at  $P_1$  and  $P_2$  with radii  $2a - r_1$  and  $2a - r_2$

$$\left. \begin{aligned} P_1 F &= 2a - r_1 \\ P_2 F &= 2a - r_2 \end{aligned} \right\}$$

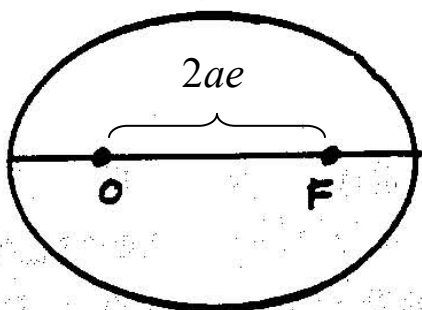


For a given “ $a$ ” two possible intersection points



Closest to  $O$   $\longrightarrow$

Given “ $a$ ”  $\longrightarrow$  distance between foci  $O$  and  $F = 2ae$



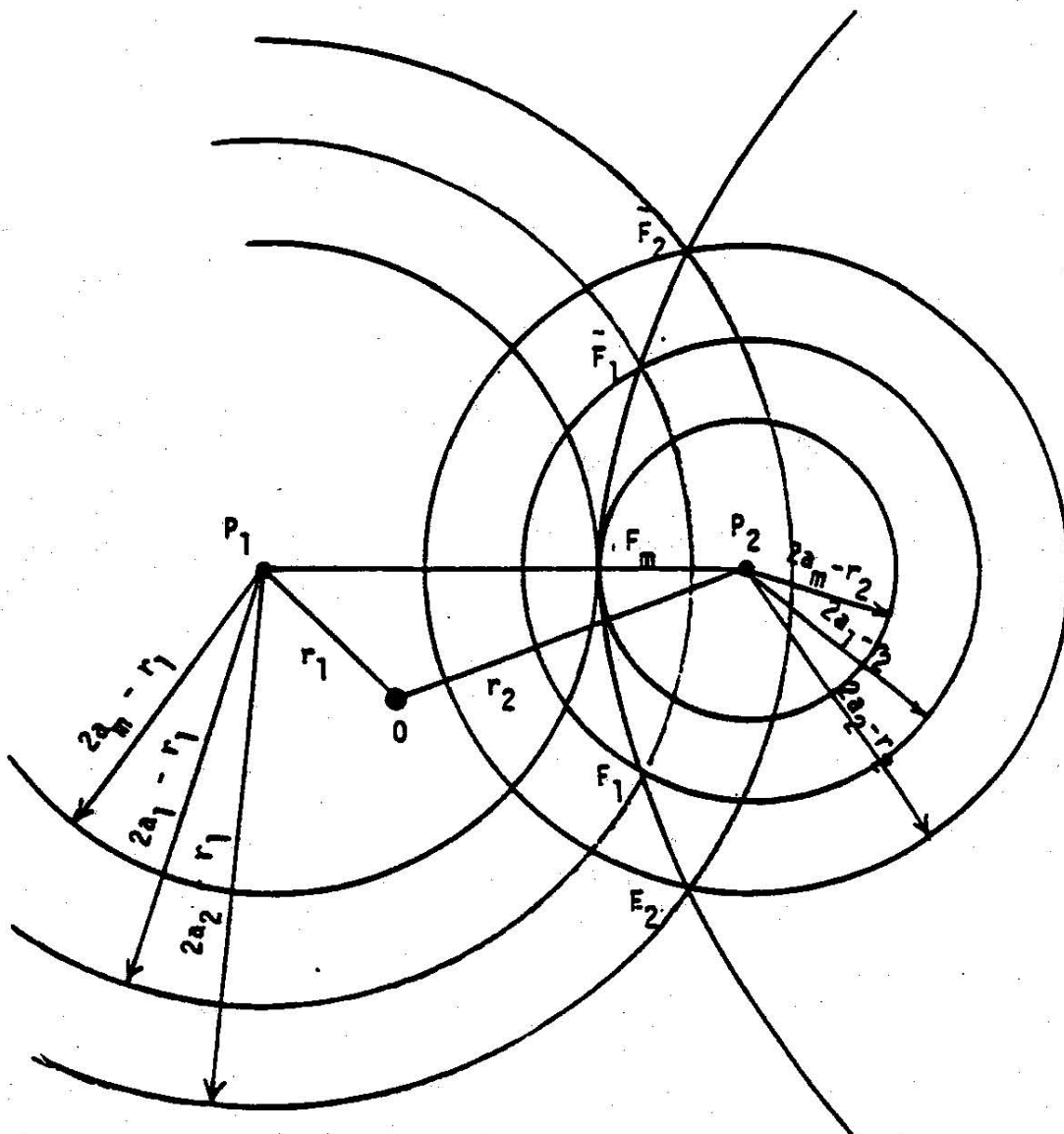
$\therefore \tilde{F}$  associated with

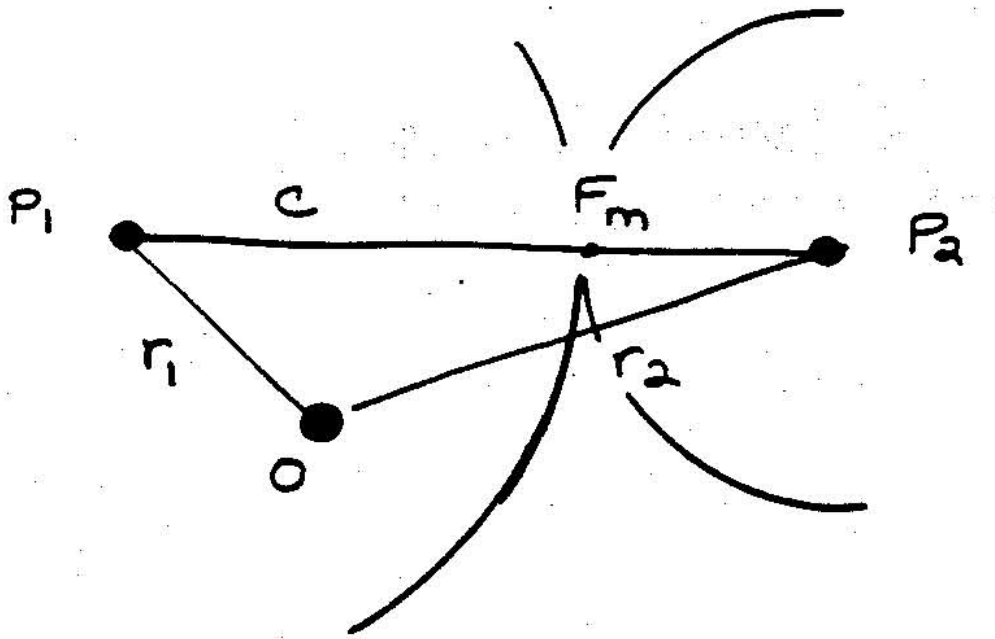
Choose 3 different values of “ $a$ ”



Note: there is a smallest value of “ $a$ ” ( $a_m$ ) below which there is no ellipse that connects  $P_1$  and  $P_2$  because the circles do not intersect

$a = a_m \Rightarrow$





$$(2a_m - r_1) + (2a_m - r_2) = c$$

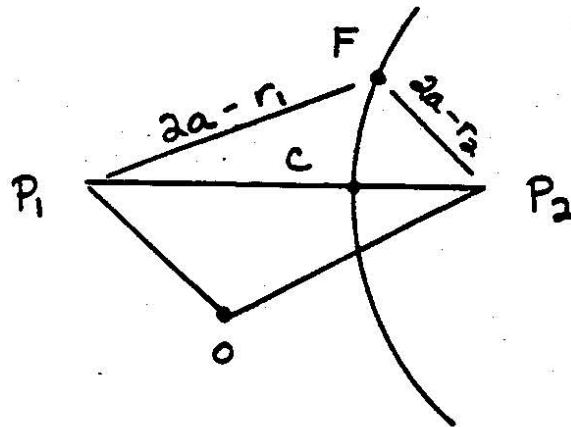
$$4a_m = r_1 + r_2 + c \quad \text{OR}$$

→  $F_m$  defines minimum energy elliptic path from  $P_1$  to  $P_2$

$$\left( \mathcal{E} = -\frac{\mu}{2a_m} \quad \text{when } a_m \text{ small as possible, } \mathcal{E} \text{ is min} \right)$$

Note: choosing different values of “ $a$ ”, produces pairs of vacant foci ( $F, \tilde{F}$ )

Sketch curve through all vacant foci  $F$ 's  
What does curve look like?



Equations for circles  $\begin{cases} P_1F = 2a - r_1 \\ P_2F = 2a - r_2 \end{cases}$

Subtract equations

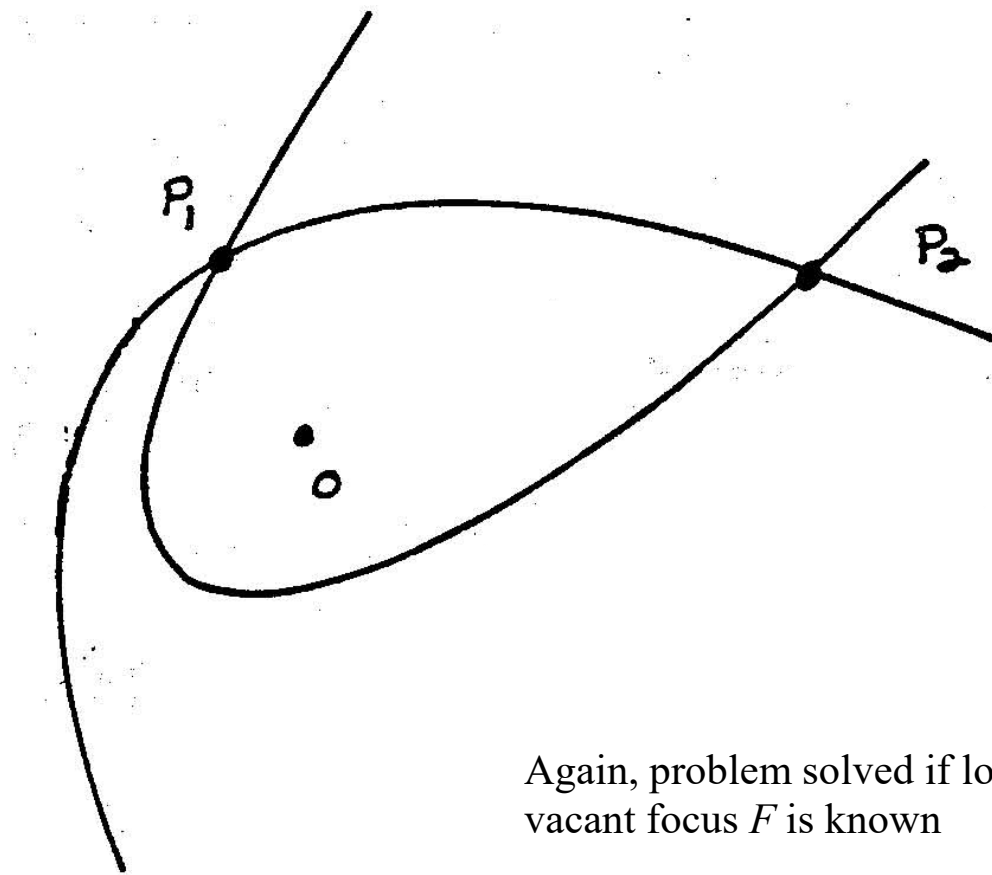
→ Equation of a hyperbola:  $F$  is point on hyperbola  
 $P_1, P_2$  are foci  
 constant on right side:  $2|a_F|$



Given two fixed points  $P_1, P_2$ ; center of force at point  $O$   
Find: hyperbola with focus at point  $O$  that connects  $P_1, P_2$







Again, problem solved if location of vacant focus  $F$  is known

Since  $P_1$  and  $P_2$  must both lie on the same hyperbola,  $F$  must be selected such that

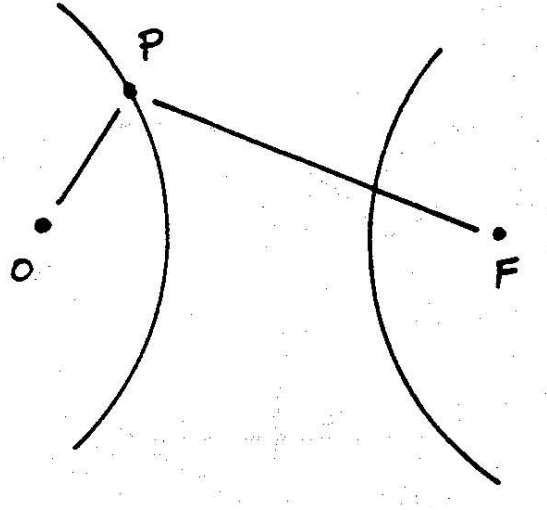
$$P_1F - \overbrace{OP_1} = 2|a| = P_2F - \overbrace{OP_2}$$

always true for hyperbola

OR

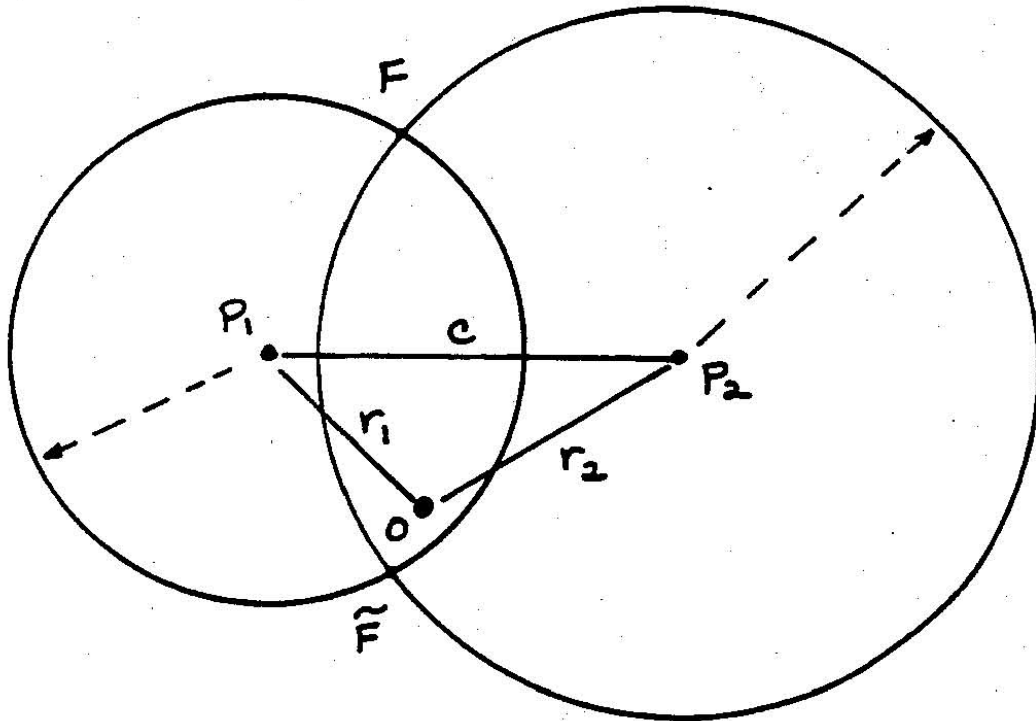
$$P_1F = 2|a| + r_1$$

$$P_2F = 2|a| + r_2$$



For hyperbola, with major axis  $2|a|$ , point  $F$  determined as the intersection of two circles centered at  $P_1$  and  $P_2$  with radii  $2|a| + r_1$  and  $2|a| + r_2$

$$\left. \begin{aligned} P_1 F &= 2|a| + r_1 \\ P_2 F &= 2|a| + r_2 \end{aligned} \right\}$$

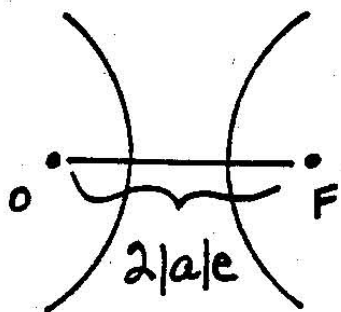


For a given  $|a|$ , two possible intersection points

→ 2 possible hyperbolic paths between  $P_1$  and  $P_2$

$F, \tilde{F}$

Given  $|a|$  → distance between foci  $O$  and  $F = 2|a|e$



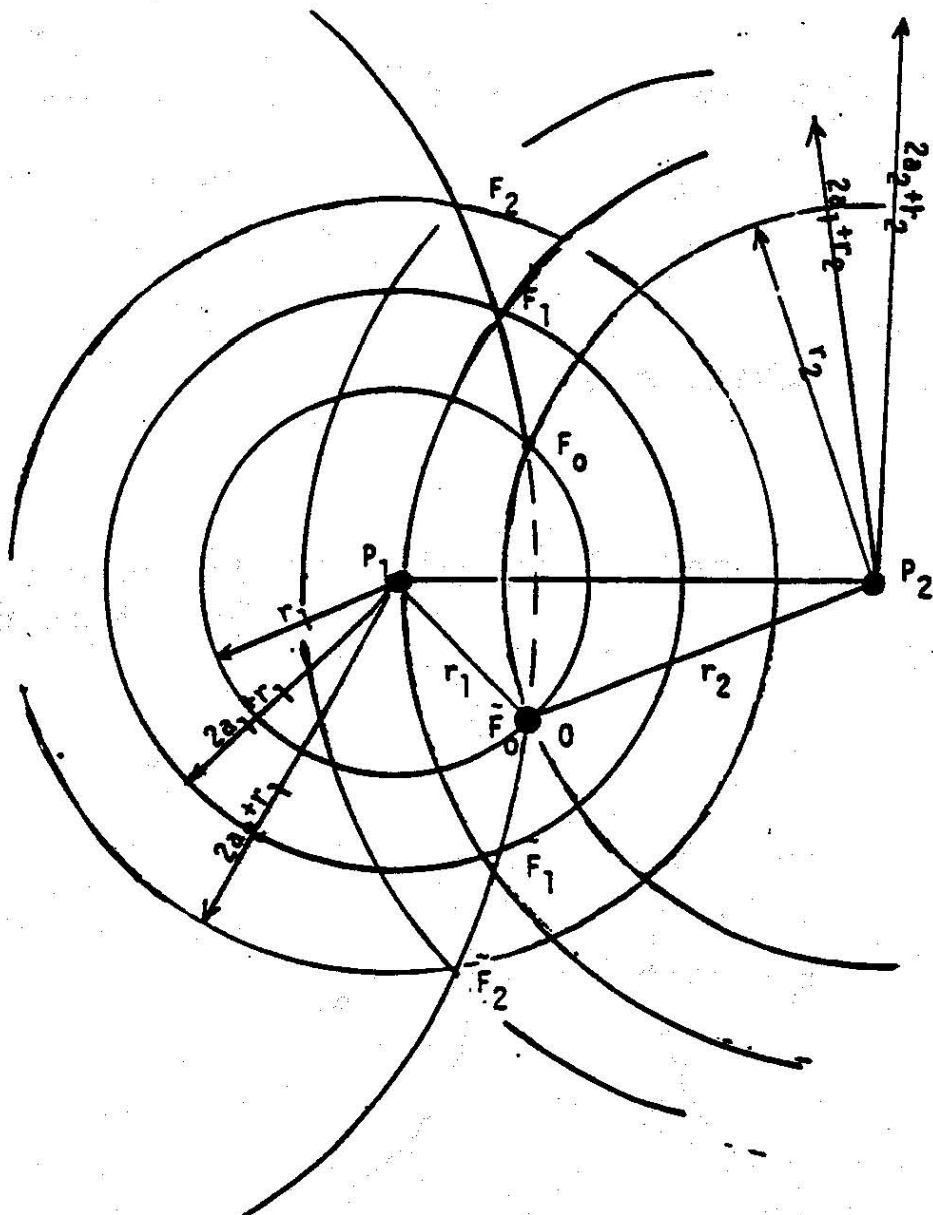
∴  $F$  associated with {

Choose 3 different values of  $|a|$

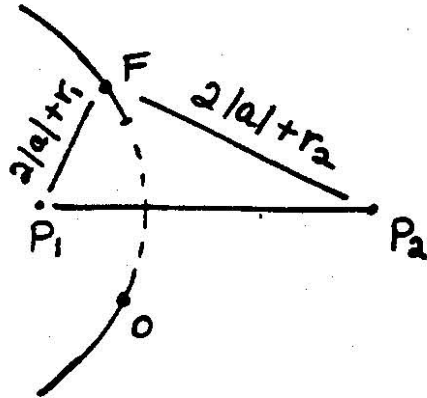
$\Rightarrow$  as  $|a|$  gets smaller, circles shrink

Note: smallest value of  $|a|$  that is possible is

(then circles have radii  $r_1$  and  $r_2$ )  $\Rightarrow$



Note: Now sketch a curve through all vacant  $F$ 's  
What does the curve look like?

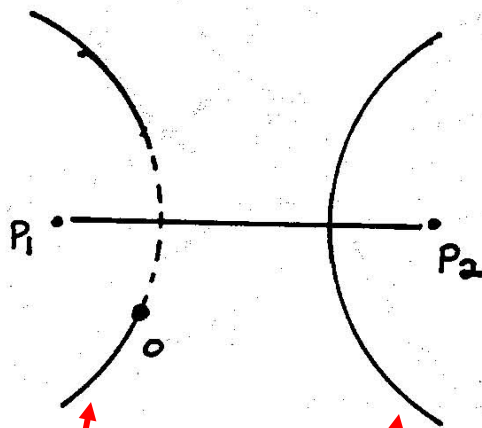


Locus of vacant foci is branch of a hyperbola

Equations for circles  $\begin{cases} P_1F = 2a + r_1 \\ P_2F = 2a + r_2 \end{cases}$

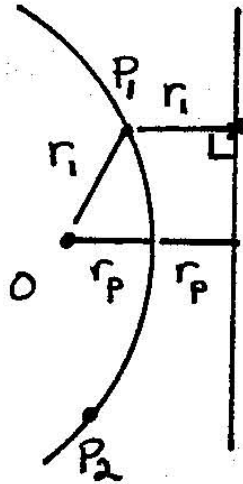
Subtract equations  $P_2F - P_1F = \underbrace{r_2 - r_1}_{\text{unknown is } F \text{ again!}}$

→ Equation of a hyperbola: other branch of **same** hyperbola  
 $P_1, P_2$  are foci  
constant on right side:  $2|a_F|$



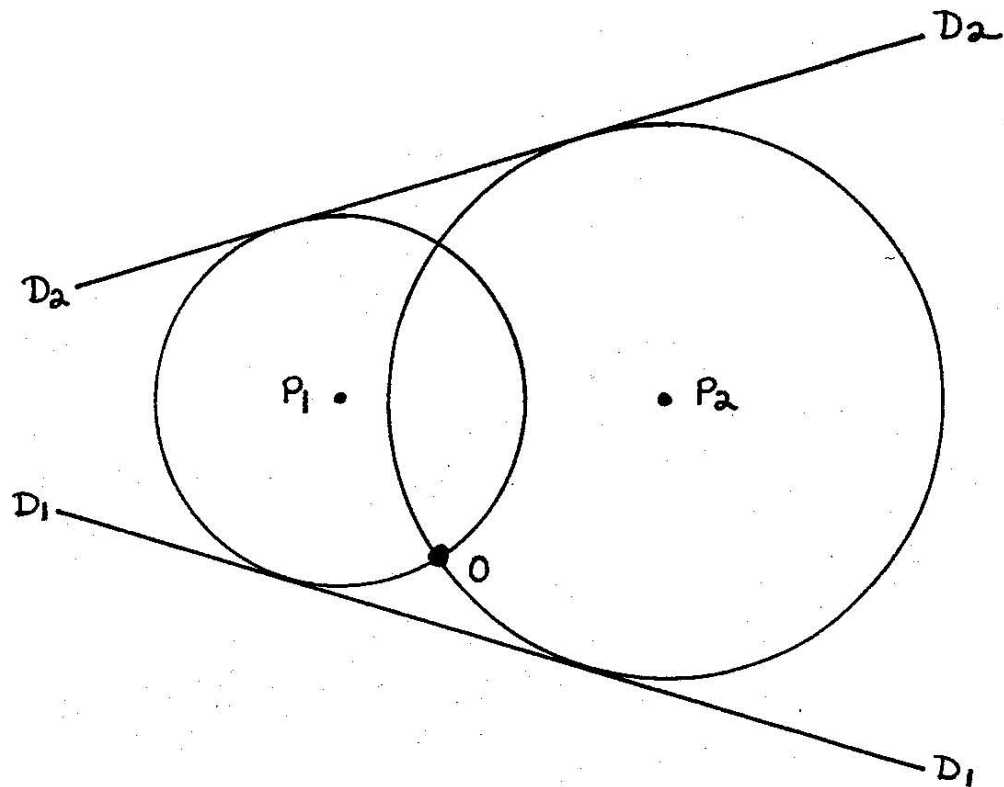
## Geometrical Relationships: Parabola

Only two possible parabolas  $\leftarrow a = \infty$ ;  $F$  at  $\infty$

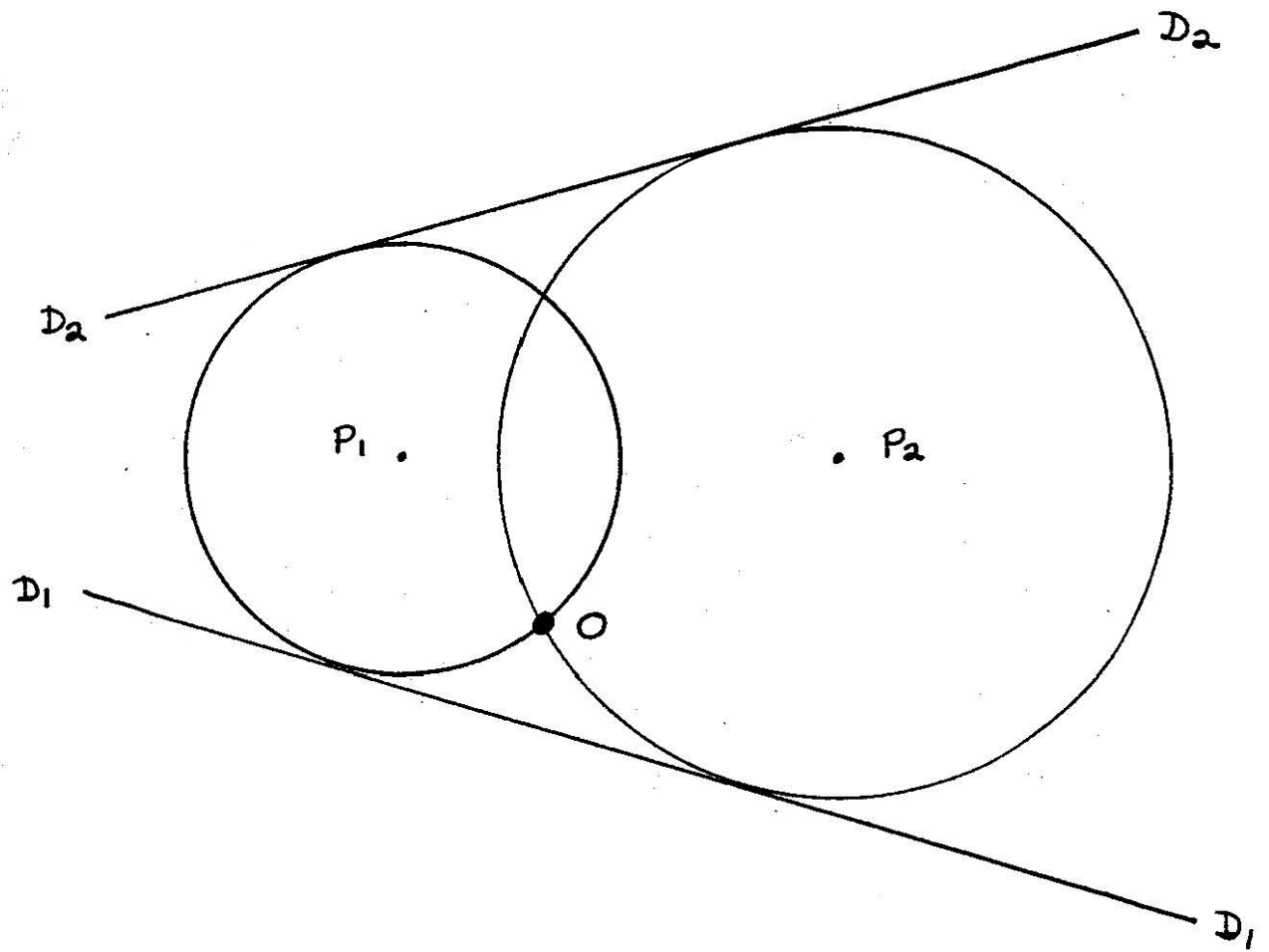


Definition of parabola:

$OP$  = distance to perpendicular  
intersection with directrix



To construct parabolas: requires normals  $N$  and vertices  $V$

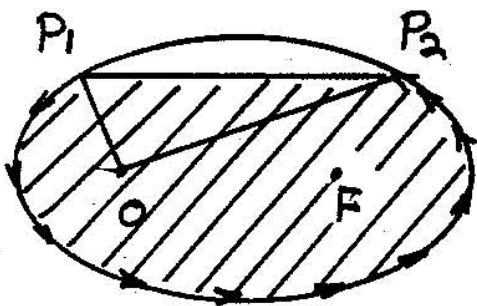
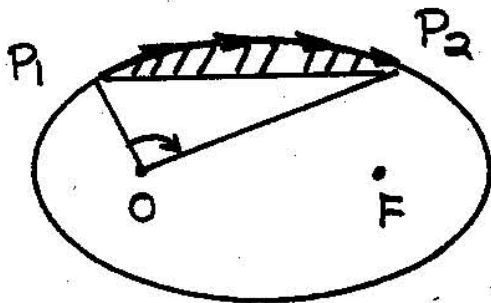


## Geometrical Relationships: Summary

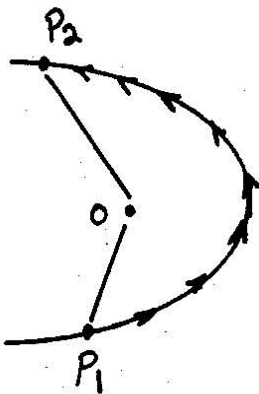
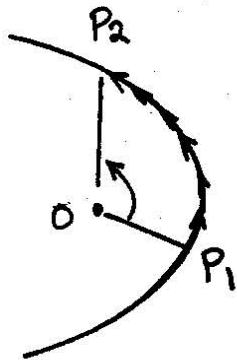
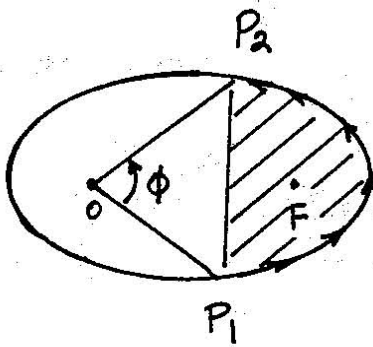
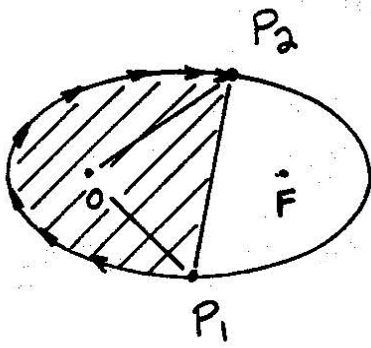
Once  $F$  is selected or otherwise identified, particular conic section is known

Necessary to define a method to categorize or classify transfers

Legend:	A – Ellipse ( $F$ <b>NOT</b> between chord and arc)
	B – Ellipse ( $F$ between chord and arc)
	H – Hyperbola
	1 – Transfer Angle $< 180^\circ$
	2 – Transfer Angle $> 180^\circ$

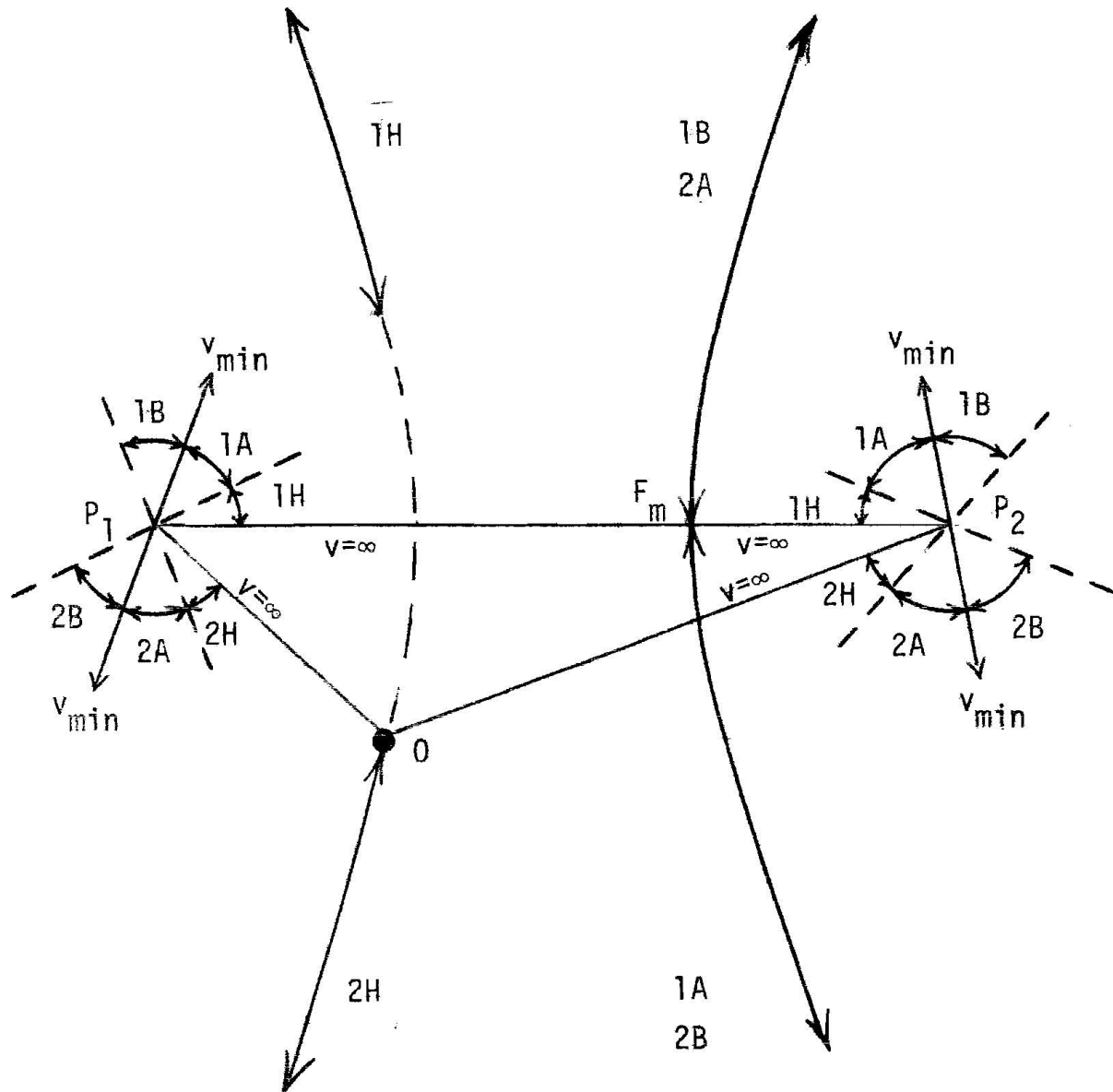






# Various Orbits Between Two Points $P_1, P_2$

Locus of Vacant Focus  $F$



- Legend:
- A - Ellipse (  $F$  not between chord and focus)
  - B - Ellipse (  $F$  between chord and focus)
  - H - Hyperbola
  - 1 - Transfer Angle  $< 180^\circ$
  - 2 - Transfer Angle  $> 180^\circ$

We may suppose  $r_2 \geq r_1$ .