

MA 527

Lecture Notes (section 7.9)

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7.9. Vector spaces.

(V, \oplus, \odot) : a vector space.

$$(Ex) \quad P_2 = \{ p(x) : p(x) = a_2x^2 + a_1x + a_0, \\ a_2, a_1, a_0 \in \mathbb{R} \}$$

$$p(x) = a_2x^2 + a_1x + a_0, \quad g(x) = b_2x^2 + b_1x + b_0 \in P_2$$

$$p(x) \oplus g(x) = (a_2 + b_2)x^2 + (a_1 + b_1)x + a_0 + b_0 \in P_2.$$

$$\beta \in \mathbb{R}$$

$$\beta \odot p(x) = \beta a_2x^2 + \beta a_1x + \beta a_0 \in P_2$$

Q: (P_2, \oplus, \odot) : a vector space?

$$(1) \quad p(x) + q(x) \stackrel{?}{=} q(x) + p(x)$$

$$\begin{aligned} (\text{Proof}) \quad p(x) + q(x) &= (a_2 + b_2)x^2 + (a_1 + b_1)x + a_0 + b_0 \\ &= (b_2 + a_2)x^2 + (b_1 + a_1)x + (b_0 + a_0) \\ &= q(x) + p(x). \end{aligned}$$

(2)

$$(3) \quad 0 = ? : \quad p(x) + ? = p(x).$$

$$0 = 0 \cdot x^2 + 0 \cdot x + 0 \in P_2 : \text{the identity.}$$

(4) $\text{HIP}(u)$: the inverse of $p(u)$.

(5) $\underline{k(p(x) + q(u)) \stackrel{?}{=} kp(x) + kq(u)}$

(8) $\textcircled{L} = k(p(x) + q(u)) = k((a_2 + b_2)x^2 + (a_1 + b_1)x + a_0 + b_0)$
 $= (ka_2 + kb_2)x^2 + (ka_1 + kb_1)x + (ka_0 + kb_0)$

\textcircled{R} **RHS.**
 $= kp(u) + kq(u)$

Same.

$$= ka_2x^2 + ka_1x + ka_0 + kb_2x^2 + kb_1x + kb_0$$
$$= (ka_2 + kb_2)x^2 + (ka_1 + kb_1)x + ka_0 + kb_0$$

(Ex) $(\mathbb{R}^2, +, \cdot)$: a vector space

Q: what if we define different operations?

$$\oplus: [a \ b] \oplus [c \ d] = [a+c+1, \ b+d]$$

$$\odot: \alpha \in \mathbb{R}: \alpha \odot [a \ b] = [\alpha a, \alpha b].$$

$0 = ?$ the identity of \oplus :

$$[a, b] \oplus \underset{[x, y]}{?} = [a, b]$$

$$\textcircled{L} [a+x+1, b+y] = [a, b] \textcircled{R}$$

$y=0; \quad \cancel{a}+x+1 = \cancel{a} : x=-1.$
 $0 = [-1, 0].$

(5) distribution.

$$k=2: \text{ check } 2([a, b] \oplus [c, d]) \\ \stackrel{?}{=} \underline{2[a, b] \oplus 2[c, d]}. \textcircled{R}$$

$$\textcircled{L}: 2([a+c, b+d]) = [2a+2c+\underline{2}, 2b+2d]$$

$$\textcircled{R} = [2a, 2b] \oplus [2c, 2d] \\ = [2a+2c+\underline{1}, 2b+2d].$$

(Dot product & Inner product)

Def $a = [a_1, \dots, a_n]$, $b = [b_1, \dots, b_n]$ in \mathbb{R}^n

$$a \cdot b = a_1 b_1 + a_2 b_2 + \dots + a_n b_n = a b^T$$

(Properties)

$$(1) (\alpha a + \beta b) \cdot c = \alpha a \cdot c + \beta b \cdot c$$

$$(2) a \cdot b = b \cdot a$$

$$(3) a \cdot a = |a|^2 \geq 0$$

$$\text{If } \underline{a \cdot a = 0}, \quad a = 0$$

$$(4) \quad a \cdot b = |a| |b| \cos \theta$$

$$(5) \quad \cos \theta = \frac{a \cdot b}{|a| |b|} : \quad \theta = \cos^{-1} \left(\frac{a \cdot b}{|a| |b|} \right).$$

Def (Inner product).

$V = (V, \oplus, \odot)$: a vector space

$(\cdot, \cdot) : V \times V \rightarrow \mathbb{R}$ is called an inner product

if (1) for any $\alpha \in \mathbb{R}$, $a, b, c \in V$

$$(\alpha a + \beta b, c) = \alpha (a, c) + \beta (b, c)$$

Linear property.

$$(2) \quad (a, b) = (b, a)$$

(3) For any $a \in V$, $(a, a) \geq 0$

If $(a, a) = 0$, $a = 0$: the identity.

Ex / Application

1. Dot product: an inner product.

2. V : the set of square-integrable functions.
on $[a, b]$

$f \in V$ iff $\int_a^b f(x)^2 dx$ is finite.

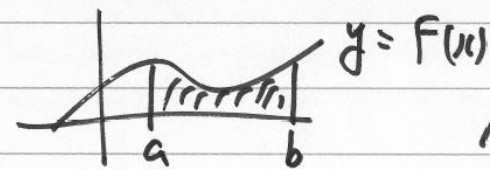
$(f, g) \stackrel{\text{define}}{=} \int_a^b f(x) g(x) dx.$
: an inner product.

(proof) (1) $(\alpha f + \beta g, h) = \alpha (f, h) + \beta (g, h)$
for any $f, g, h \in V$

$$\begin{aligned} (\because \textcircled{L}) &= (\alpha f + \beta g, h) = \int_a^b (\alpha f(x) + \beta g(x)) h(x) dx \\ &= \alpha \int_a^b f(x) h(x) dx + \beta \int_a^b g(x) h(x) dx \\ &= \alpha (f, h) + \beta (g, h) = \textcircled{R} \end{aligned}$$

(2) \checkmark

$$(3) (f, f) = \int_a^b f(x)^2 dx \geq 0$$



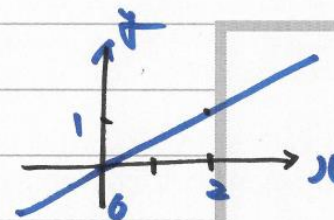
$$\text{Area} = \int_a^b F(x) dx$$

If $(f, f) = 0$, $f(x)^2 = 0$: $\underline{f(x) = 0}$

(Linear transformation).

$$(Ex) \quad y = \underline{f(x) = \frac{1}{2}x}$$

a linear polynomial.



$$1. f(x_1 + x_2) = \frac{1}{2}(x_1 + x_2) = \frac{1}{2}x_1 + \frac{1}{2}x_2 \\ = f(x_1) + f(x_2)$$

$$2. f(\alpha x) = \frac{1}{2}\alpha x = \alpha\left(\frac{1}{2}x\right) = \alpha f(x).$$

Def X, Y : vector spaces

A function $F: X \rightarrow Y$ is called
a linear transformation

if for any $x_1, x_2 \in X$ and $c \in \mathbb{R}$

$$(1) F(x_1 + x_2) = F(x_1) + F(x_2)$$

$$(2) F(c x_1) = c F(x_1).$$

Remark: (1), (2) means

$$\underline{F(\alpha x_1 + \beta x_2) = \alpha F(x_1) + \beta F(x_2)}$$

(Ex) Let $F: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be a function
defined by $\underline{F\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} x_1 - 2x_2 \\ 3x_1 + 4x_2 \end{pmatrix}}.$

$$F\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \underset{\text{"A"}}{\begin{bmatrix} 1 & -2 \\ 3 & 4 \end{bmatrix}} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}.$$

$F(X) = AX$ is a linear transformation

$$\text{(Proof) } 1. F(x_1 + x_2) = A(x_1 + x_2) = Ax_1 + Ax_2 \\ = F(x_1) + F(x_2)$$

$$2. F(cX_1) = A cX_1 = cAX_1 = cF(X_1)$$

Thm If $F: X \rightarrow Y$ is a linear transformation,
then $F(X)$ is represented by a matrix:
 $F(X) = AX$.

$$(Ex) F\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = \begin{bmatrix} 1 & -2 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \therefore F^{-1} = ?$$

$$A^{-1} = \frac{1}{4+6} \begin{bmatrix} 4 & 2 \\ -3 & 1 \end{bmatrix} = \begin{bmatrix} 0.4 & 0.2 \\ -0.3 & 0.1 \end{bmatrix}$$

$$F^{-1}(X) = A^{-1}X$$

Nonlinear transformation?

$$F: \mathbb{R}^2 \rightarrow \mathbb{R}^2: F\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = \begin{pmatrix} x_1^2 + x_2 \\ x_1 x_2 + e^{x_2} \end{pmatrix}$$

(Orthogonality).

(Ex) Find all vectors in \mathbb{R}^2 orthogonal to
 $u = [1, 2]$.

Do they form a vector space? Yes.

Find $v = [v_1, v_2]$ s.t. $u \cdot v = 0$

$$v_1 + 2v_2 = 0 \text{ iff } v_1 = -2v_2$$

$$v_1 = [-2v_2, v_2] = v_2[-2, 1].$$

$$\text{Let } W = \{ v \in \mathbb{R}^2 \mid v \cdot u = 0 \}$$

$$\underline{W = \text{span}\{-2, 1\}} : \text{a subspace of } \mathbb{R}^2.$$