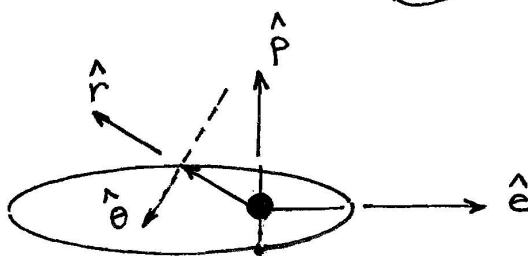
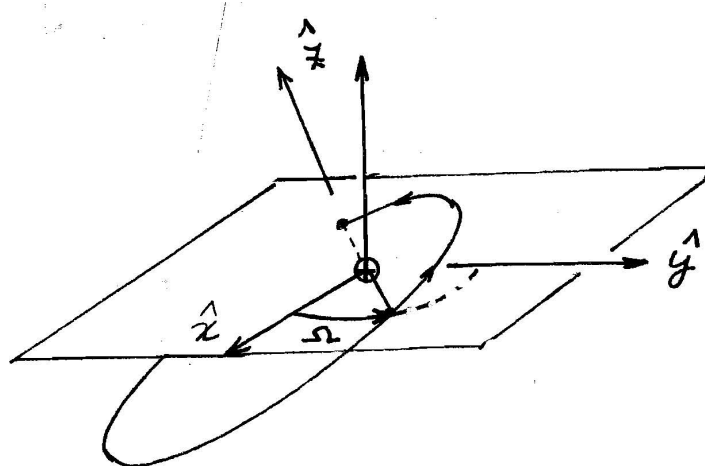
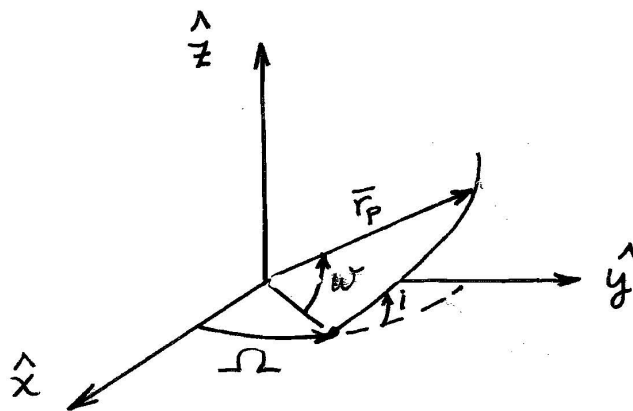


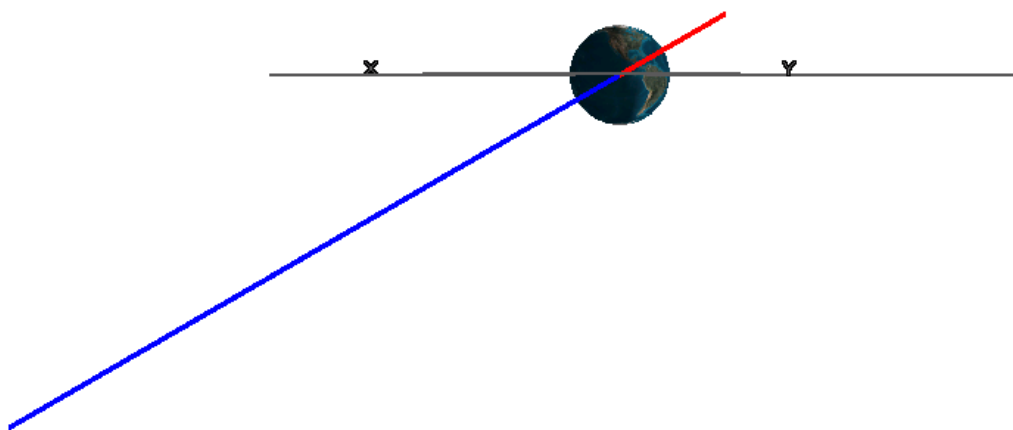
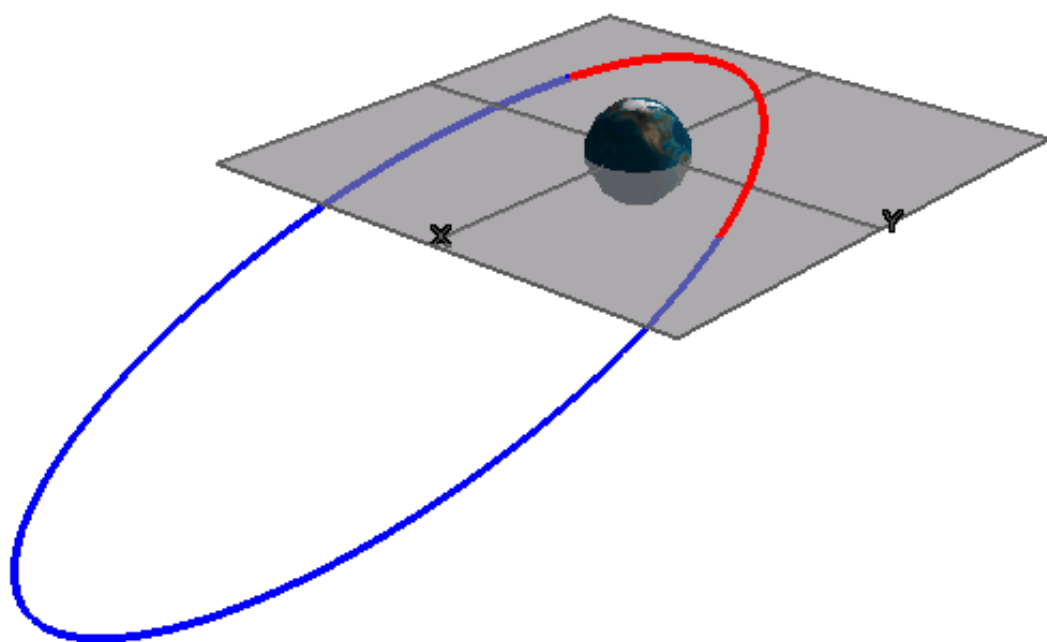
3D Example

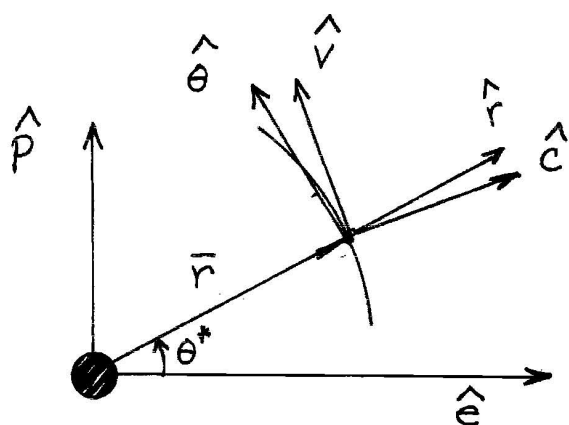
Assume s/c moving in orbit about the Earth

$$\left. \begin{aligned} a &= 8 R_{\oplus} \\ e &= .7 \\ i &= 30^{\circ} \\ \Omega &= 60^{\circ} \\ \omega &= 90^{\circ} \end{aligned} \right\} \text{ wrt "Earth centered Mean J2000 coordinates"}$$



maneuver @ $\theta^* = 90^{\circ}$



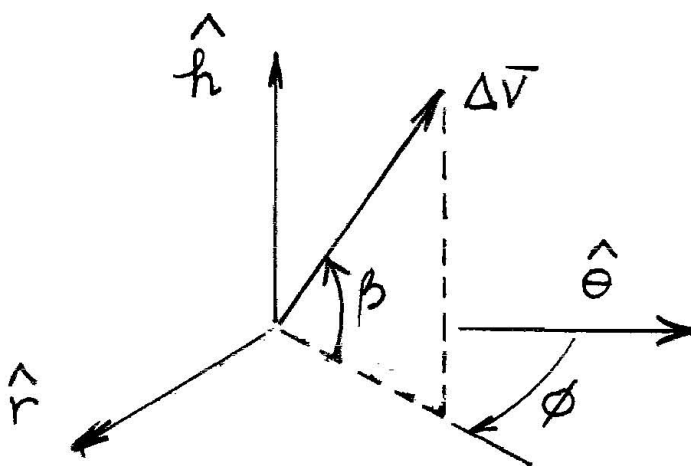


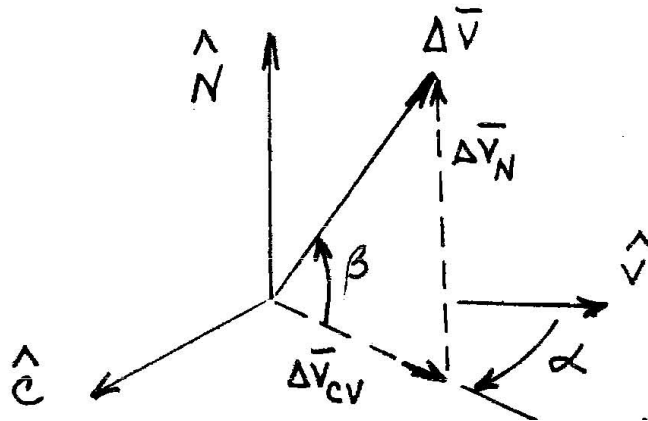
VNB coordinate frame
(useful for describing Δv 's and
maneuvers)

\hat{V} parallel to velocity; tangent to path

\hat{N} normal; out-of-plane

\hat{B} bi-normal to curve; in plane of motion

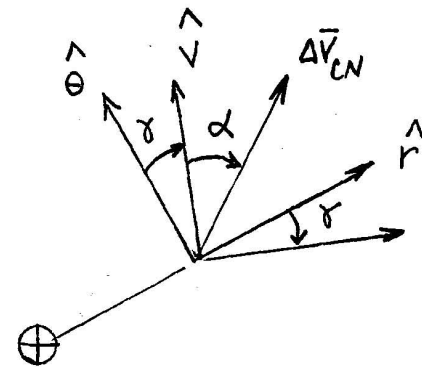




Assume a maneuver such that:

$$\Delta v = 2 \text{ km/s} \quad \alpha = 0^\circ \quad \beta = 150^\circ$$

$$\Delta \bar{v} = -1.732 \hat{V} + 1.0 \hat{N} \text{ km/s}$$



	\hat{r}	$\hat{\theta}$	\hat{h}
\hat{x}	$c_\Omega c_\theta - s_\Omega c_i s_\theta$	$-c_\Omega s_\theta - s_\Omega c_i c_\theta$	$s_\Omega s_i$
\hat{y}	$s_\Omega c_\theta + c_\Omega c_i s_\theta$	$-s_\Omega s_\theta + c_\Omega c_i c_\theta$	$-c_\Omega s_i$
\hat{z}	$s_i s_\theta$	$s_i c_\theta$	c_i

$$\begin{array}{l}
 i = 30^\circ \\
 \Omega = 60^\circ \\
 \theta = \omega + \theta^* = 180^\circ
 \end{array}
 \quad \longrightarrow \quad
 \begin{array}{c|ccc}
 & \hat{r} & \hat{\theta} & \hat{h} \\
 \hline
 \hat{x} & -.5 & .75 & .433 \\
 \hat{y} & -.866 & -.433 & -.25 \\
 \hat{z} & 0 & -.5 & .866
 \end{array}$$

$$\bar{r} = 26022.80 \hat{r} \text{ km}$$

$$\bar{r} = -13011.40 \hat{x} - 22536.40 \hat{y} \text{ km/s} \quad \longleftarrow$$

$$v = 4.777328 \text{ km/s} \quad \gamma = 34.992^\circ$$

$$\begin{aligned}
 \bar{v} &= 2.739616 \hat{r} + 3.91374 \hat{\theta} \text{ km/s} \\
 &= (-1.36981 \hat{x} - 2.37258 \hat{y} \text{ km/s}) \\
 &\quad + (2.93573 \hat{x} - 1.69465 \hat{y} - 1.95687 \hat{z} \text{ km/s})
 \end{aligned}$$

$$\bar{v} = 1.56550 \hat{x} - 4.06728 \hat{y} - 1.95687 \hat{z} \text{ km/s}$$

$$\Delta \bar{v} \quad \longleftarrow \text{ also in inertial coordinates}$$

$$\Delta \bar{v} = -.134551 \hat{x} + 1.22457 \hat{y} + 1.57548 \hat{z} \text{ km/s}$$

$$\bar{v}_{new} = \bar{v}_{old} + \Delta \bar{v}$$

$$\bar{v}_{new} =$$

$$\bar{r}_{new} = \bar{r}_{old}$$

Characteristics of new orbit?

$$\hat{h}_{new} =$$

$$\hat{h} = \sin \Omega \sin i \hat{x} - \cos \Omega \sin i \hat{y} + \cos i \hat{z}$$

\longleftarrow from where?

$$\cos i = .989864407 \quad \longrightarrow$$

$$\left. \begin{array}{l} \sin \Omega \sin i = .122989 \\ -\cos \Omega \sin i = -.071008 \end{array} \right\} \quad \left. \begin{array}{l} \Omega = 60^\circ, 120^\circ \\ \Omega = \pm 60^\circ \end{array} \right\}$$

$$|\vec{v}| = 3.206887 \text{ km/s}$$

$$\frac{v^2}{2} - \frac{\mu}{r} = -\frac{\mu}{2a} \quad \longrightarrow$$

$$\vec{r} \bullet \vec{v} = +45476 \text{ km}^2/\text{s} \quad \longrightarrow \quad \text{sign on } \gamma \text{ is positive}$$

$$\underbrace{\quad}_{r \dot{r} = r v \sin \gamma}$$

$$e^2 = \left(\frac{rv^2}{\mu} - 1 \right)^2 \cos^2 \gamma + \sin^2 \gamma$$

$$\longrightarrow$$

$$\tan \theta^* = \frac{\left(\frac{rv^2}{\mu} \right) \sin \gamma \cos \gamma}{\left(\frac{rv^2}{\mu} \right) \cos^2 \gamma - 1}$$

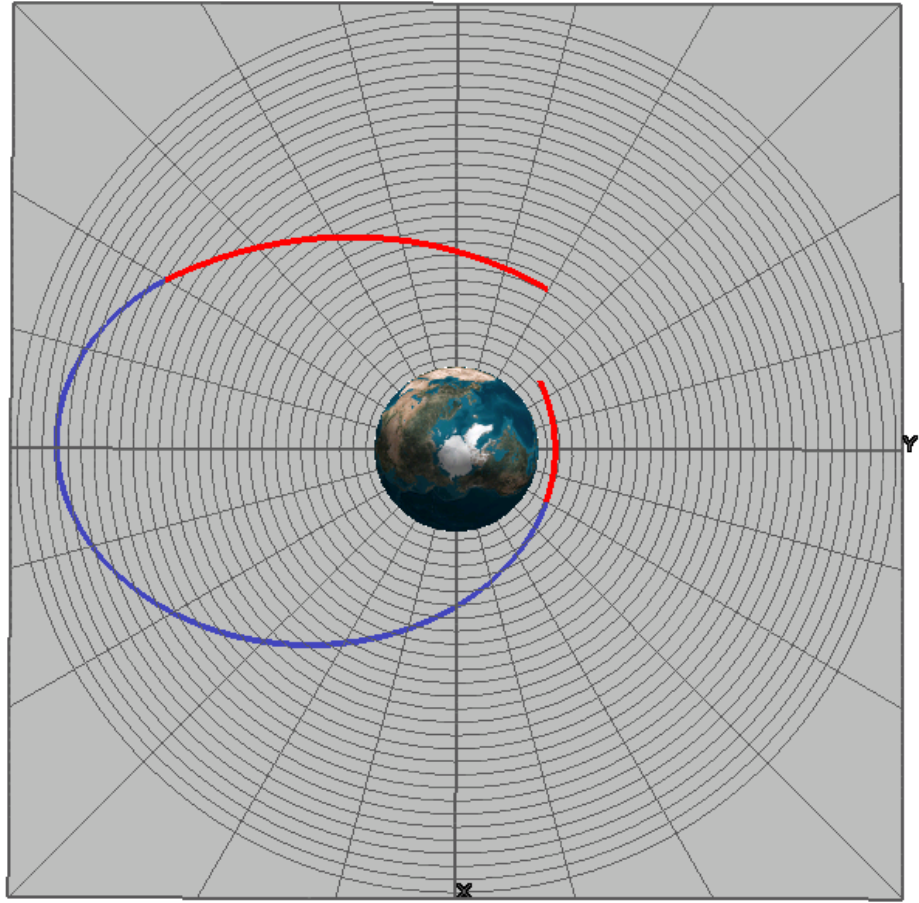
$$\longrightarrow$$

$$\hat{r} \bullet \hat{z} = \sin i \sin \theta = 0 \quad \longrightarrow \quad \theta = 0^\circ, 180^\circ$$

$$\hat{r} \bullet \hat{x} = \cos \Omega \cos \theta - \sin \Omega \cos i \sin \theta$$

$$\omega_{new} = \theta_{new} - \theta_{new}^*$$

$$\longrightarrow$$



000 Axis

