AAE 666

HOMEWORK FOUR

Exercise 1 Determine whether or not the following function is positive definite.

$$V(x) = x_1^4 - x_1^2 x_2 + x_2^2$$

Exercise 2 Show that the following system is AS about zero

$$\dot{x} = -(1 + \sin x)x$$

Exercise 3 By appropriate choice of Lyapunov function, show that the origin is an asymptotically stable equilibrium state for

$$\dot{x}_1 = x_2
 \dot{x}_2 = -x_1 + x_1^3 - x_2$$

Exercise 4 (Stabilization of the Duffing system.) Consider the Duffing system with a scalar control input u(t):

$$\dot{x}_1 = x_2
\dot{x}_2 = x_1 - x_1^3 + u$$

Obtain a linear controller of the form

$$u = -k_1 x_1 - k_2 x_2$$

which results in a closed loop system which is GAS about the origin. Numerically simulate the open loop system (u = 0) and the closed loop system for several initial conditions.

Exercise 5 Determine whether or not the following function is radially unbounded.

$$V(x) = x_1 - x_1^3 + x_1^4 - x_2^2 + x_2^4$$

Exercise 6 (Forced Duffing's equation with damping.) Show that all solutions of the system

$$\dot{x}_1 = x_2$$

 $\dot{x}_2 = x_1 - x_1^3 - cx_2 + 1$ $c > 0$

are bounded.

Hint: Consider

$$V(x) = \frac{1}{2}\lambda c^2 x_1^2 + \lambda c x_1 x_2 + \frac{1}{2}x_2^2 - \frac{1}{2}x_1^2 + \frac{1}{4}x_1^4$$

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where $0 < \lambda < 1$. Letting

$$P = \frac{1}{2} \left[\begin{array}{cc} \lambda c^2 & \lambda c \\ \lambda c & 1 \end{array} \right]$$

note that P > 0 and

$$V(x) = x^{T} P x - \frac{1}{2} x_{1}^{2} + \frac{1}{4} x_{1}^{4}$$
$$\geq x^{T} P x - \frac{1}{4}$$

Exercise 7 Show that all solutions of

$$\dot{x} = \cos x - x^3 + 100$$

are bounded.

Exercise 8 Show that all solutions of

$$\dot{x}_1 = x_2
 \dot{x}_2 = \cos x_1 - x_1^3 + 100$$

are bounded.

Exercise 9 Show that the following system is GES about zero

$$\dot{x} = -(2 + \sin x)x$$

Give a rate of convergence.

Exercise 10 Show that the following system is GES about 1.

$$\dot{x} = -(2 + \sin x)(x - 1)$$

Give a rate of convergence.

Exercise 11 Show that the following system is GES about the zero state.

$$\dot{x}_1 = -x_1 + (I_2 - I_3)x_2x_3
\dot{x}_2 = -2x_2 + (I_3 - I_1)x_1x_3
\dot{x}_3 = -3x_3 + (I_1 - I_2)x_1x_2$$

where I_2, I_2, I_3 are arbitrary constants. Give a rate of convergence.