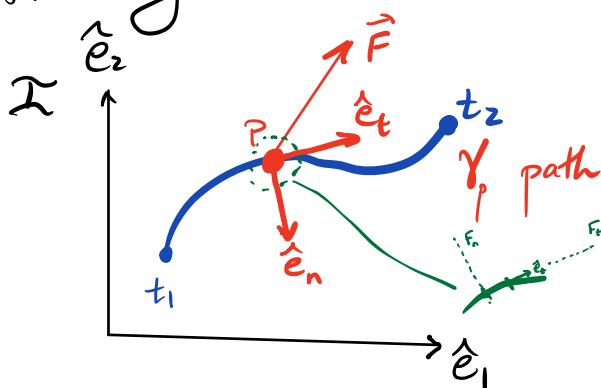


## Ch 5: Energy of a Particle

- "For certain classes of forces, we can solve for the position and/or velocity of a particle without finding the E.O.M. or trajectories"



$$W_p^{(\vec{F})} (\vec{r}_{p/0}; \gamma_p) \triangleq \int_{t_1}^{t_2} \vec{F} \cdot \vec{d}\vec{r}_{p/0}$$

But recall  $\overset{\text{I}}{v}_{p/0} = \frac{d}{dt} \vec{r}_{p/0} \Rightarrow \overset{\text{I}}{d}\vec{r}_{p/0} = \overset{\text{I}}{v}_{p/0} dt$

$$W_p^{(\vec{F})} (\vec{r}_{p/0}; \gamma_p) = \int_{t_1}^{t_2} \vec{F} \cdot \overset{\text{I}}{v}_{p/0} dt$$

Alternate expression

Or we could consider a path frame,

$$W_p^{(\vec{F})}(\vec{r}_{P/0}; \gamma_p) = \int_{\gamma_p} \vec{F} \cdot \hat{\mathbf{e}}_t \, ds$$

Alternate expression

Note that in a path frame

$$\vec{F} = F_t \hat{\mathbf{e}}_t + F_n \hat{\mathbf{e}}_n$$

Then we see  $\vec{F} \cdot \hat{\mathbf{e}}_t$  term ignores  $F_n$  contributions

key idea: Only the tangential component of the force does work on P. Normal component does no work.

Notes:

- ① Work depends on the path
- ② Even though work is a scalar quantity, it is frame dependent.
  - We will only be calculating work in an inertial frame.
- ③ Not all forces on a particle do work
- ④

We can also examine the total work on P

$$W_p^{(\text{tot})}(\vec{r}_{p/0}; \gamma_p) \text{ total work} \longleftrightarrow \vec{F}_p = m_p \vec{a}_{p/0}$$

$$\begin{aligned} W_p^{(\text{tot})}(\vec{r}_{p/0}; \gamma_p) &= \int_{\gamma_p} m_p \vec{a}_{p/0} \cdot \vec{d}\vec{r}_{p/0} \\ &= \int_{\gamma_p} m_p \cancel{\frac{\vec{d}}{dt}} (\vec{v}_{p/0}) \cdot \vec{d}\vec{r}_{p/0} \quad \cancel{\vec{d}\vec{r}_{p/0} = \vec{v}_{p/0} dt} \\ &= \int_{\gamma_p} m_p \vec{d}(\vec{v}_{p/0}) \cdot \vec{v}_{p/0} \end{aligned}$$

Tricky Product rule manipulation,

$$\vec{d}(\vec{v}_{p/0} \cdot \vec{v}_{p/0}) = \vec{d}\vec{v}_{p/0} \cdot \vec{v}_{p/0} + \vec{v}_{p/0} \cdot \vec{d}\vec{v}_{p/0} = 2(\vec{d}\vec{v}_{p/0} \cdot \vec{v}_{p/0})$$

Plugging in,

$$= \frac{1}{2} \int_{\gamma_p} m_p \vec{d}(\vec{v}_{p/0} \cdot \vec{v}_{p/0}) = \frac{1}{2} \int_{\gamma_p} m_p \vec{d}(||\vec{v}_{p/0}||^2)$$

*Recall*  $||\vec{v}_{p/0}|| = \sqrt{\vec{v}_{p/0} \cdot \vec{v}_{p/0}}$

$$W_p^{(\text{tot})}(\vec{r}_{p/0}; \gamma_p) = \frac{1}{2} m_p ||\vec{v}_{p/0}(t_2)||^2 - \frac{1}{2} m_p ||\vec{v}_{p/0}(t_1)||^2$$

Dfn: The Kinetic energy of particle P is given by

$$T_{P/0} \triangleq \frac{1}{2} m_p \left\| \overset{\text{Inertial}}{\vec{v}_{P/0}} \right\|^2$$

Remember that  
you have to  
use an inertial  
velocity here.

Then, we get

$$W_p^{(\text{tot})}(\vec{r}_{P/0}; \gamma_p) = T_{P/0}(t_2) - T_{P/0}(t_1)$$

Or,

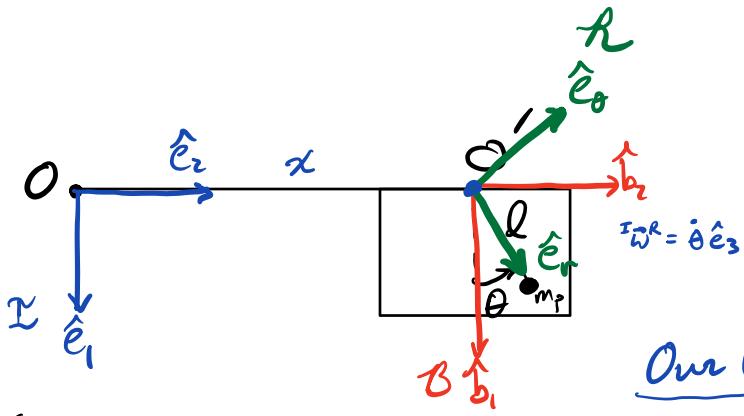
$$T_{P/0}(t_2) = T_{P/0}(t_1) + W_p^{(\text{tot})}(\vec{r}_{P/0}; \gamma_p)$$

Work-Energy Formula #1 of 3

Conservation?

The kinetic energy is conserved if the total work done on P is zero.

Ex 5.2 (Similar to 4.6 in K&P) But the box travels with constant velocity here.  
 Find the kinetic energy  $T_{P/0}$



Our Guess:

$$\frac{1}{2}m_p\dot{x}^2 + \frac{1}{2}m_p l\dot{\theta}^2$$

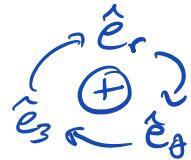
Kinematics

$$\vec{r}_{P/0} = \vec{r}_{P/0'} + \vec{r}_{0/0} = l\hat{e}_r + x\hat{e}_2$$

$${}^I\vec{v}_{P/0} = l \underbrace{\frac{d}{dt}\hat{e}_r}_{\text{unit}} + \dot{x}\hat{e}_2$$

$$\hookrightarrow {}^I\vec{\omega}^R \times \hat{e}_r = (\underbrace{{}^I\vec{\omega}^B}_{\text{unit}} + \underbrace{{}^B\vec{\omega}^R}_{\text{unit}}) = \dot{\theta}\hat{e}_3 \times \hat{e}_r = \dot{\theta}\hat{e}_\theta \\ = 0 \quad \dot{\theta}\hat{e}_3$$

$${}^I\vec{v}_{P/0} = l\dot{\theta}\hat{e}_\theta + \dot{x}\hat{e}_2$$



We want  $T_{P/0}$ , but we need to be careful, because  $\hat{e}_\theta$  and  $\hat{e}_2$  are not perpendicular, so we can't just take the square root of the sum of squares.

$$\|{}^I\vec{v}_{P/0}\| \neq \sqrt{(\dot{x})^2 + (\dot{\theta}l)^2}$$

$$\|\overset{I}{V}_{P_0}\| = \sqrt{\overset{I}{V}_{P_0} \cdot \overset{I}{V}_{P_0}}$$

Convert to all one basis,

$$\begin{aligned}\overset{I}{V}_{P_0} &= l\dot{\theta}(-\sin\theta \hat{b}_1 + \cos\theta \hat{b}_2) + \dot{x} \hat{b}_2 \\ &= -l\dot{\theta} \sin\theta \hat{b}_1 + (l\dot{\theta} \cos\theta + \dot{x}) \hat{b}_2\end{aligned}$$

$$\begin{aligned}T_{P_0} &= \frac{m_p}{2} \|\overset{I}{V}_{P_0}\|^2 = \frac{1}{2} m_p \overset{I}{V}_{P_0} \cdot \overset{I}{V}_{P_0} \\ &= \frac{1}{2} m_p [(-l\dot{\theta} \sin\theta)^2 + (l\dot{\theta} \cos\theta + \dot{x})^2] \\ &= \frac{1}{2} m_p [l^2 \dot{\theta}^2 + \dot{x}^2 + \underbrace{2l\dot{\theta} \cos\theta}_{\text{Cross terms}}]\end{aligned}$$

Cross terms that involve the motion of frames B and R

What if  $\dot{x}$  is constant?

We could also calculate  $T_{P'_0}$

$$T_{P'_0} = \frac{m_p}{2} \|\overset{I}{V}_{P'_0}\|^2 = m_p l^2 \dot{\theta}^2 \quad \text{Compare to other expression}$$

$\Rightarrow$  The answers are different in differing inertial frames.

Also note:  $T_{P_0} \neq T_{P'_0} + T_{O_0}$  Kinetic energies don't add this way

(Recall kinetic energy is a quadratic function of velocity)

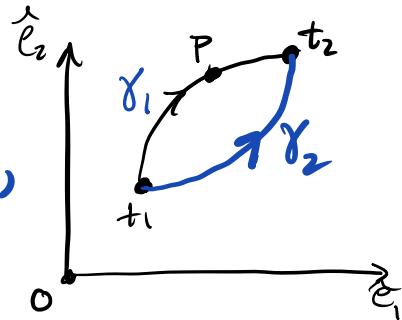
## An important class of forces

Dfn: A conservative force is one in which the work performed only depends on the end points of the path.

Let  $\vec{F}$  be a conservative force,

$$W_p^{(\vec{F})}(\vec{r}_{p_0}; \gamma_p) = W_p^{(\vec{F})}(t_1, t_2)$$

Simplifying notation since work only depends on the end points here.



$$W_p^{(\vec{F})}(t_1, t_2) = \int_{t_1}^{t_2} \vec{F} \cdot d\vec{r}_{p_0} = - \int_{t_2}^{t_1} \vec{F} \cdot d\vec{r}_{p_0} = - W_p^{(\vec{F})}(t_2, t_1)$$

Further, we could consider a closed circuit

$$\oint \vec{F} \cdot d\vec{r}_{p_0} = \int_{t_1}^{t_2} \vec{F} \cdot d\vec{r}_{p_0} + \int_{t_2}^{t_1} \vec{F} \cdot d\vec{r}_{p_0}$$

$$\underbrace{W_p^{(\vec{F})}(t_1, t_2)}_{W_p^{(\vec{F})}(t_2, t_1)} = -W_p^{(\vec{F})}(t_1, t_2)$$

$$\Rightarrow \oint \vec{F} \cdot d\vec{r}_{p_0} = 0 \quad \text{if } \vec{F} \text{ is conservative}$$

We will make use of the nice properties of conservative forces, and to begin doing this, we will divide forces into two groups:

$$\vec{F}^{(c)} \quad \text{conservative forces}$$

$$\vec{F}^{(nc)} \quad \text{nonconservative forces}$$

Then work can be divided up as well:

$$W_p^{(\text{tot})}(\vec{r}_{p/0}, \gamma_p) = W_p^{(c)}(t_1, t_2) + W_p^{(nc)}(\vec{r}_{p/0}; \gamma_p)$$

Dfn: Let the potential energy associated with a conservative force  $\vec{F}$  be

$$U_{p/0}^{(\vec{F})}(\vec{r}_{p/0}) \triangleq - \int \vec{F} \cdot d\vec{r}_{p/0}$$

↑  
recall conservative  $\vec{F}$

Indefinite integral results in constant of integration. Potential energy is therefore arbitrary up to an additive constant.

Going back to look at conservative forces, let  $\vec{F}$  be conservative, then,

$$W_p^{(c)}(t_1, t_2) = \int_{t_1}^{t_2} \vec{F} \cdot d\vec{r}_{p/0} = -U_{p/0}^{(\vec{F})}(t_2) + U_{p/0}^{(\vec{F})}(t_1)$$

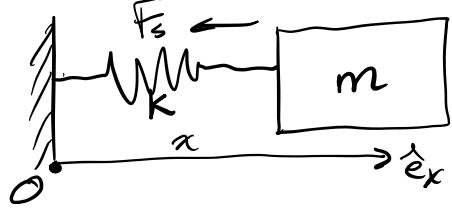
$$U_{p0}^{(\vec{F})}(t_2) = U_{p0}^{(\vec{F})}(t_1) - W_p^{(c)}(t_1, t_2)$$

Work-Energy Formula #2 of 3

Conservation?

$U_{p0}$  is conserved if  $W_p^{(c)}(t_1, t_2) = 0$ .

Ex. mass-spring      Find  $U_{p0}^{(\vec{F}_s)}$



$$\begin{aligned}\vec{r}_{p0} &= x \hat{e}_x \\ \vec{V}_{p0} &= \frac{d\vec{r}_{p0}}{dt} = \dot{x} \hat{e}_x \\ \Rightarrow d\vec{r}_{p0} &= \frac{dx}{dt} dt \hat{e}_x\end{aligned}$$

$$\begin{aligned}U_{p0}^{(\vec{F}_s)} &= - \int \vec{F}_s \cdot d\vec{r}_{p0} = - \int (-kx \hat{e}_x) \cdot dx \hat{e}_x = \int kx dx \\ &= \frac{1}{2} kx^2 + C\end{aligned}$$

where  $C = U_{p0}(0)$

Ex. Gravitational force. Find  $U_{P/0}^{(\vec{F}_G)}$

$$\vec{F}_G = -\frac{G m_o m_p}{r^2} \hat{e}_r$$

kinematics:

$$\vec{r}_{P/0} = r \hat{e}_r$$

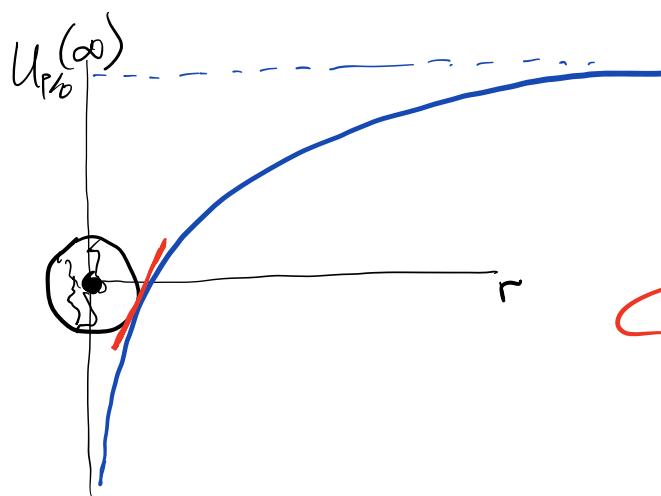
$${}^I\vec{V}_{P/0} = \dot{r} \hat{e}_r + r \dot{\theta} \hat{e}_\theta \Rightarrow {}^I d\vec{r}_{P/0} = dr \hat{e}_r + r d\theta \hat{e}_\theta$$

$$U_{P/0}^{(\vec{F}_G)} = - \int \vec{F}_G \cdot {}^I d\vec{r}_{P/0}$$

$$U_{P/0}^{(\vec{F}_G)} = - \int -\frac{G m_o m_p}{r^2} \hat{e}_r \cdot (dr \hat{e}_r + r d\theta \hat{e}_\theta)$$

$$= \int \frac{G m_o m_p}{r^2} dr = -\frac{G m_o m_p}{r} + C$$

Note: the integration contributes a minus sign here
  
 $\underbrace{U_{P/0}(\infty)}$



$$\begin{aligned} \vec{F}_G &= -\nabla U_{P/0}^{(\vec{F}_G)} \\ &= -\frac{G m_o m_p}{r^2} \hat{e}_r \end{aligned}$$

Near earth's surface,  
 $r = (R_e + h) \approx R_e$  since  $R_e \gg h$ .

$$\frac{G m_o}{R_e^2} \approx 9.8 \frac{m}{s^2}$$