

2.4.3

$$A = \begin{pmatrix} 1 & 2 & 0 & 1 \\ 0 & 1 & 1 & 0 \\ 1 & 2 & 0 & 1 \end{pmatrix}$$

$$\xrightarrow{E_{31}(-1)} \begin{pmatrix} 1 & 2 & 0 & 1 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$C(A): \text{Basis} = \text{Span} \left\{ \begin{pmatrix} 1 \\ 0 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \\ 1 \\ 2 \end{pmatrix} \right\}$$

$$\text{Dim} = \text{rank} = 2$$

$$\begin{aligned} x_1 + 2x_2 + x_4 &= 0 \\ x_2 + x_3 &= 0 \end{aligned}$$

π_{pivot}

$$x_2 = -x_3$$

$$x_1 = 2x_3 - x_4$$

Preferred solution: $x_3 = 1, x_4 = 0$ & $x_3 = 0, x_4 = 1$

$$N(A): \text{Basis} = \text{Span} \left\{ \begin{pmatrix} 2 \\ -1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \\ 0 \\ 1 \end{pmatrix} \right\}$$

$$\text{Dim} = n - r = 4 - 2 = 2$$

$$A^T = \begin{pmatrix} 1 & 0 & 1 \\ 2 & 1 & 2 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix} \quad E_{41}(-1) = \begin{pmatrix} 1 & 0 & 1 \\ 2 & 1 & 2 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad E_{21}(-2) \rightarrow \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\xrightarrow{E_{32}(-1)} \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

2.4.3

$$C(A^T): \text{Basis} = \text{Span} \left\{ \begin{pmatrix} 1 \\ 2 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} \right\}$$

$$\text{Dim} = \text{rank} = 2$$

← Pivot
 $X_1 + X_3 = 0$

$X_2 = 0$
 ↑ Pivot

Preferred solution: $X_3 = 1 \therefore$

$$N(A^T): \text{Basis} = \text{Span} \left\{ \begin{pmatrix} -1 \\ 0 \\ 1 \\ 0 \end{pmatrix} \right\}$$

$$\text{Dim} = m - r = 3 - 2 = 1$$

$$U = \begin{pmatrix} 1 & 2 & 0 & 1 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \quad (\text{Already in row echelon form})$$

$$C(U): \text{Basis} = \text{Span} \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \\ 0 \\ 0 \end{pmatrix} \right\}$$

$$\text{Dim} = \text{rank} = 2$$

$$C(A^T) = C(U^T) \quad \&$$

$$N(A) = N(U)$$

Have same dimension & basis as U is the row echelon form of A .

2.4.3

$$U^T = \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix} \xrightarrow{E_{41}(-1)} \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \end{pmatrix} \xrightarrow{E_{21}(-2)} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\xrightarrow{E_{32}(-1)} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$x_1 = 0$$

$$x_2 = 0$$

x_3 is free, set to 1 for preferred sol.

$$N(U^T): \text{Basis} = \text{Span} \left\{ \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\}$$

$$\dim = m - r = 3 - 2 = 1$$

2.4.7

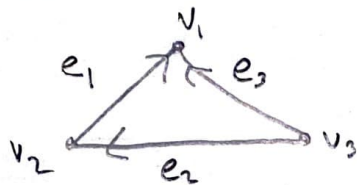
Because the row space must be orthogonal to the nullspace.

2.4.8

$$A_{m \times n} X_{n \times 1} = 0_{n \times 1}$$

The rank is \boxed{n} as the solution $\vec{X} = \vec{0}$ can only occur if $\text{rank}(A)$ equals n , as the columns of A are linearly independent.

2.5.1



$$-x_2 + x_1 = e_1$$

$$-x_3 + x_1 = e_3$$

$$-x_3 + x_2 = e_2$$

$$A = \begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 1 & 0 & -1 \end{pmatrix}$$

$$Ax = 0$$

$$\xrightarrow{E_{31}(-1)} \left(\begin{array}{ccc|c} 1 & -1 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 1 & -1 & 0 \end{array} \right) \xrightarrow{E_{32}(-1)} \left(\begin{array}{ccc|c} 1 & -1 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right)$$

Free

✓

$$x_1 - x_2 = 0$$

$$x_2 - x_3 = 0$$

↑ Pivot

Preferred solution let $x_3 = 1 \therefore x_2 = 1$ & $x_1 = 1$

$$\vec{x} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \quad N(A) = \text{span} \left\{ \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right\}$$

$$A^T y = 0$$

$$A^T = \begin{pmatrix} 1 & 0 & 1 \\ -1 & 1 & 0 \\ 0 & -1 & -1 \end{pmatrix} \xrightarrow{E_{32}(1)} \begin{pmatrix} 1 & 0 & 1 \\ -1 & 1 & 0 \\ -1 & 0 & -1 \end{pmatrix}$$

$$\xrightarrow{E_{31}(1)} \begin{pmatrix} 1 & 0 & 1 \\ -1 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \xrightarrow{E_{21}(1)} \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

2.5.1

Pivot $\rightarrow y_1 + y_3 = 0$

$y_2 + y_3 = 0$

\uparrow
Pivot

\uparrow
Free

Preferred solution, $y_3 = 1 \quad \therefore y_2 = y_1 = -1$

$$y = \begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix}$$

$$N(A^T) = \text{span} \left\{ \begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix} \right\}$$

2.5.2

$$A = \begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 1 & 0 & -1 \end{pmatrix}$$

$$Ax = b$$

P P F

$$\begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 1 & 0 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}$$

$$C(A) = \text{Span}\left\{ \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} \right\}$$

← From 2.5.1
 x_1 & x_2 are pivots,
 x_3 is free

$$= x_1 \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + x_2 \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}$$

$$x_1 - x_2 = b_1$$

$$x_2 = b_2$$

$$x_1 = b_3$$

$$\therefore b_3 - b_2 = b_1 \Rightarrow \boxed{b_1 + b_2 - b_3 = 0}$$

$$x_1 - x_2 = b_1$$

$$x_2 - x_3 = b_2$$

$$x_1 - x_3 = b_3 \Rightarrow x_1 = b_3 + x_3$$

$$b_1 = b_3 + x_3 - x_2 \Rightarrow x_2 = b_3 - b_1 + x_3$$

$$b_3 - b_1 + \cancel{x_3} - \cancel{x_3} = b_2 \Rightarrow b_3 - b_1 = b_2$$

2.5.2

\therefore

$$b_1 + b_2 - b_3 = 0$$

The sum of potential differences around is zero

2.5.3

$$A^T = \begin{pmatrix} 1 & 0 & 1 \\ -1 & 1 & 0 \\ 0 & -1 & -1 \end{pmatrix}$$

$$A = \begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 1 & 0 & -1 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{pmatrix}$$

$$C(A^T) = \text{span} \left\{ \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} \right\}$$

$$y_1 \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix} + y_2 \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} = \begin{pmatrix} f_1 \\ f_2 \\ f_3 \end{pmatrix}$$

$$y_1 = f_1$$

$$y_2 - y_1 = f_2$$

$$-y_2 = f_3$$

$$\therefore -f_3 - f_1 = f_2 \Rightarrow \boxed{f_1 + f_2 + f_3 = 0}$$

$$A^T y = F$$

$$\begin{pmatrix} 1 & 0 & 1 \\ -1 & 1 & 0 \\ 0 & -1 & -1 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} = \begin{pmatrix} f_1 \\ f_2 \\ f_3 \end{pmatrix}$$

$$y_1 + y_3 = f_1$$

$$y_2 - y_1 = f_2$$

$$-y_3 - y_2 = f_3 \Rightarrow y_3 = -f_3 - y_2$$

$$y_1 - f_3 - y_2 = f_1 \Rightarrow y_1 = f_1 + f_3 + y_2$$

2.5.3

$$\cancel{y_2} - f_1 - f_3 - \cancel{y_2} = f_2$$

$$-f_1 - f_3 = f_2 \Rightarrow f_1 + f_2 + f_3 = 0$$

The sum of the current into a node is zero.

2.6a1

Rotation of 90° :
$$\begin{pmatrix} \cos(90) & -\sin(90) \\ \sin(90) & \cos(90) \end{pmatrix} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

Projection onto x axis:
$$\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} = \boxed{\begin{pmatrix} 0 & -1 \\ 0 & 0 \end{pmatrix}}$$

↑ Rotate by 90°
Then project to x

Projection onto y:
$$\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} = \boxed{\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}}$$

↑ project to x then y

2.607

Basis: $1, t, t^2, t^3$

$$\frac{d^2}{dt^2}(1) = 0$$

$$\frac{d^2}{dt^2}(t) = 0$$

$$\frac{d^2}{dt^2}(t^2) = 2$$

$$\frac{d^2}{dt^2}(t^3) = 6t$$

$$A = \begin{pmatrix} 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 6 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \begin{matrix} 1 \\ t \\ t^2 \\ t^3 \end{matrix}$$

$$C(A) = \text{Span} \left\{ \begin{pmatrix} 2 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 6 \\ 0 \\ 0 \end{pmatrix} \right\}$$

x_1 & x_2 are free, x_3 & x_4 are pivots

$$2x_3 = 0$$

$$6x_4 = 0$$

Preferred solutions: $x_1=1, x_2=0$ & $x_1=0, x_2=1$ \therefore

$$N(A) = \text{Span} \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} \right\}$$

2.6.7

The nullspace shows that taking $\frac{d}{dt}$ on a 1st or
Zero order polynomial gives zero.

2.6.8

Basis: $(1, t, t^2, t^3, t^4)$

$$(2+3t)(1) = 2 + 3t$$

$$(2+3t)(t) = 2t + 3t^2$$

$$(2+3t)(t^2) = 2t^2 + 3t^3$$

$$(2+3t)(t^3) = 2t^3 + 3t^4$$

$$A = \begin{pmatrix} 2 & 0 & 0 & 0 & 0 \\ 3 & 2 & 0 & 0 & 0 \\ 0 & 3 & 2 & 0 & 0 \\ 0 & 0 & 3 & 2 & 0 \\ 0 & 0 & 0 & 3 & 2 \end{pmatrix}$$

$$\begin{matrix} 1 \\ t \\ t^2 \\ t^3 \\ t^4 \end{matrix}$$

2.6.18

$$p(x) = a_0 + a_1x + a_2x^2 + a_3x^3$$

$$\int_0^1 a_0 + a_1x + a_2x^2 + a_3x^3 dx = 0$$

$$= a_0x + \frac{a_1x^2}{2} + \frac{a_2x^3}{3} + \frac{a_3x^4}{4} \Big|_0^1$$

$$= a_0 + \frac{a_1}{2} + \frac{a_2}{3} + \frac{a_3}{4} = 0$$

$$\text{IF } a_0 = a_1 = a_2 = a_3 = 0 \quad \therefore \int_0^1 p(x) dx = 0$$

\therefore Zero vector is in subspace.

$$\text{Let } a_0 = 1, a_1 = -2, a_2 = 3, a_3 = -4$$

$$\therefore \int_0^1 p(x) dx = 0 = 1 + (-1) + 1 + (-1) = 0 \quad \checkmark$$

$$c \int_0^1 p(x) dx = c[0] = 0 \quad \checkmark$$

$$\int_0^1 c p(x) dx = (c)(1)x + (c)(-2)\frac{x^2}{2} + \frac{3cx^3}{3} + \frac{(-4)c x^4}{4} \Big|_0^1 = 0$$
$$c - c + c - c = 0 \quad \checkmark$$

Closed under multiplication.

$$\int_0^1 p_1(x) dx + \int_0^1 p_2(x) dx = \int_0^1 p_1(x) + p_2(x) dx$$

$$\text{Let } b_0 = 1, b_1 = -4, b_2 = 6, b_3 = -4$$

2.6.18

$$a_0 + \frac{a_1}{2} + \frac{a_2}{3} + \frac{a_3}{4} = 0 = \int_0^1 p_1(x) dx$$

$$b_0 + \frac{b_1}{2} + \frac{b_2}{3} + \frac{b_3}{4} = 0 = 1 - 2 + 2 - 1 = 0 = \int_0^1 p_2(x) dx$$

$$0 + 0 = 0 \checkmark = \int_0^1 p_1(x) dx + \int_0^1 p_2(x) dx$$

$$\int (a_0 + b_0) + (a_1 + b_1)x + (a_2 + b_2)x^2 + (a_3 + b_3)x^3 dx$$

$$= (a_0 + b_0)x + \frac{(a_1 + b_1)x^2}{2} + \frac{(a_2 + b_2)x^3}{3} + \frac{(a_3 + b_3)x^4}{4} \Big|_0^1$$

$$= a_0 + b_0 + \frac{a_1 + b_1}{2} + \frac{a_2 + b_2}{3} + \frac{a_3 + b_3}{4}$$

$$= (1+1) + \frac{(-2+4)}{2} + \frac{(3+6)}{3} + \frac{(-4+4)}{4}$$

$$= 2 + 3 + 3 + -2 = 0 \checkmark = \int_0^1 p_1 + p_2 dx$$

Therefore, closed under addition.

S is closed under addition & multiplication, while including the zero vector. Therefore S is a subspace.

Basu:

$$\begin{pmatrix} 1 \\ -2 \\ 3 \\ -4 \end{pmatrix}$$

e
 e^2
 e^3