

6.1.3

$$\begin{pmatrix} a & b \\ b & c \end{pmatrix} = A$$

$$|A-\lambda I| = \lambda^2 - (a+c)\lambda + ac - b^2 = 0$$

$$\lambda_1, \lambda_2 = ac - b^2$$

$$a > 0$$

$$ac > b^2$$

$$\therefore (\lambda_1)(\lambda_2) > 0$$

$$\lambda_{1,2} = (a+c) \pm \sqrt{(a+c)^2 - (4)(ac-b^2)}$$

$$\frac{\lambda_1 + \lambda_2}{2} = \frac{a+c}{2}$$

$$\lambda_1 + \lambda_2 = a + c$$

$$\frac{\lambda_1 + \lambda_2}{2} = a > 0 \quad \therefore c > 0$$

$$\therefore \lambda_1 \text{ & } \lambda_2 > 0$$

6.1.4

$$a) F = -1 + 4(e^x - x) - 5x \sin y + 6y^2$$

$$\frac{\partial F}{\partial x} = 4e^x - 4 - 5 \sin y \Big|_{x=0, y=0} = 4 - 4 - 5 \sin(0) = 0$$

$$\frac{\partial F}{\partial y} = -5x \cos y + 12y \Big|_{x=0, y=0} = 0$$

$$\frac{\partial^2 F}{\partial x^2} = 4e^x \Big|_{x=0, y=0} = 4$$

$$\frac{\partial^2 F}{\partial x \partial y} = -5 \cos y \Big|_{x=0, y=0} = -5$$

$$\frac{\partial^2 F}{\partial y^2} = 5x \sin y + 12 \Big|_{x=0, y=0} = 12$$

$$A = \begin{pmatrix} 4 & -5 \\ -5 & 12 \end{pmatrix}$$

$$|A - \lambda I| = \lambda^2 - 16\lambda + 23 = 0$$

$$\lambda_{1,2} = \frac{16 \pm \sqrt{16^2 - (4)(23)}}{2}$$

$$\lambda_1 = \frac{16 + \sqrt{164}}{2}, \quad \lambda_2 = \frac{16 - \sqrt{164}}{2}$$

6.1.4

$$\lambda_1 = 14.4631$$

$$\lambda_2 = 1.5969$$

$$\lambda_1 \text{ & } \lambda_2 > 0 \therefore$$

Hessian is  
Positive definite, minimum  
at  $x=y=0$

b)  $F = (x^2 - 2x) \cos y$

$$\frac{\partial F}{\partial x} = (2x - 2) \cos y \Big| = 0$$

$$x=1, y=\pi$$

$$\frac{\partial F}{\partial y} = -(x^2 - 2x) \sin y \Big| = 0$$

$$x=1, y=\pi$$

$$\frac{\partial^2 F}{\partial x^2} = -2 \cos y \Big| = -2$$

$$x=1, y=\pi$$

$$\frac{\partial^2 F}{\partial y^2} = - (x^2 - 2x) \cos y \Big| = - (1 - 2)(-1) = -1$$

$$x=1, y=\pi$$

$$A = \begin{pmatrix} -2 & 0 \\ 0 & -1 \end{pmatrix}$$

6.1.4

$$|A - \lambda I| = \lambda^2 + 3\lambda + 2 = 0 = (\lambda+2)(\lambda+1) = 0$$

$$\lambda_1 = -2, \lambda_2 = -1$$

$$\lambda_1, \lambda_2 < 0$$

$\therefore$  Hessian is negative definite, maximum at  
 $x=1, y=\pi.$

6.1.12

$$F = x^2y^2 - 2x - 2y$$

$$\frac{\partial F}{\partial x} = 2xy^2 - 2 \Big|_{x=1, y=1} = 2 - 2 = 0$$

$$\frac{\partial F}{\partial y} = 2x^2y - 2 \Big|_{x=1, y=1} = 2 - 2 = 0$$

$$\frac{\partial^2 F}{\partial y^2} \Big|_{x=1, y=1} = \frac{\partial F}{\partial x} \Big|_{x=1, y=1} = 0 \quad (1, 1) \text{ is } \underline{\text{stationary point.}}$$

$$\frac{\partial^2 F}{\partial x^2} = 2y^2 \Big|_{(1,1)} = 2$$

$$\frac{\partial^2 F}{\partial x \partial y} = 4xy \Big|_{(1,1)} = 4$$

$$\frac{\partial^2 F}{\partial y^2} = 2x^2 \Big|_{(1,1)} = 2$$

$$A = \begin{pmatrix} 2 & 4 \\ 4 & 2 \end{pmatrix}$$

$$|A - \lambda I| = \lambda^2 - 4\lambda - 12 = 0$$

$$(\lambda - 6)(\lambda + 2) = 0$$

6.1.12

$$\lambda_1 = 6, \lambda_2 = -2 \therefore$$

Hessian is indefinite, (1,1) is a saddle point  
& not a minimum.

6.1.17

$$(AB)^T = B^T A^T$$

$$(X^T A^T) = (A X)^T$$

$$\therefore X^T A^T A X = (A X)^T (A X)$$

$$\|X\|^2 = X^T X$$

$$\therefore \|A X\|^2 = (A X)^T (A X)$$

If  $A^T A$  is positive definite, then

$$\|A X\|^2 \geq 0 \text{ unless } X=0$$

$$\text{then } \|A \vec{0}\|^2 = 0$$

Q2.2

$$A = \begin{pmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{pmatrix}$$

$$\det(A_1) = 2 > 0$$

$$\det(A_2) = 4 - 1 = 3 > 0$$

$$\det(A_3) = 2 \begin{vmatrix} 2 & -1 \\ -1 & 2 \end{vmatrix} - (-1) \begin{vmatrix} -1 & -1 \\ -1 & 2 \end{vmatrix} + (-1) \begin{vmatrix} -1 & 2 \\ -1 & -1 \end{vmatrix}$$

$$= (2)(3) + (-2 - 1) - (1 + 2) = 0$$

$\therefore A$  isn't positive definite

$$B = \begin{pmatrix} 2 & -1 & -1 \\ -1 & 2 & 1 \\ -1 & 1 & 2 \end{pmatrix}$$

$$\det(B_1) = 2 > 0$$

$$\det(B_2) = 4 - 1 = 3 > 0$$

$$\det(B_3) = 2 \begin{vmatrix} 2 & -1 \\ 1 & 2 \end{vmatrix} - (-1) \begin{vmatrix} -1 & 1 \\ -1 & 2 \end{vmatrix} + (-1) \begin{vmatrix} -1 & 2 \\ -1 & 1 \end{vmatrix}$$

$$= (2)(3) + (-2 + 1) - (-1 + 2)$$

$$= 4 > 0$$

$B$  is positive definite.

6.2.2

$$C^2 = \begin{pmatrix} 0 & 1 & 2 \\ 1 & 0 & 1 \\ 2 & 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 & 2 \\ 1 & 0 & 1 \\ 2 & 1 & 0 \end{pmatrix} = \begin{pmatrix} 5 & 2 & 1 \\ 2 & 2 & 2 \\ 1 & 2 & 5 \end{pmatrix}$$

$$\det(C_1^2) = 5$$

$$\det(C_2^2) = 10 - 4 = 6$$

$$\begin{aligned}\det(C_3^2) &= (5)(6) - 2 \begin{vmatrix} 2 & 2 \\ 2 & 5 \end{vmatrix} + \begin{vmatrix} 2 & 2 \\ 1 & 2 \end{vmatrix} \\ &= 30 - (2)(8) + 2 = 16\end{aligned}$$

C is positive definite.

6.2.7

Because entries of  $\lambda$  are positive & R is symmetric.

$$A = \begin{pmatrix} 10 & 6 \\ 6 & 10 \end{pmatrix}$$

$$|A - \lambda I| = \lambda^2 - 20\lambda + 64 = 0$$

$$(\lambda - 16)(\lambda - 4) = 0$$

$$\lambda_1 = 16, \lambda_2 = 4$$

$$\Lambda = \begin{pmatrix} 16 & 0 \\ 0 & 4 \end{pmatrix}$$

$$(A - \lambda_1 I) x_1 = 0$$

$$\begin{pmatrix} -6 & 6 \\ 6 & -6 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0 \Rightarrow x_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$(A - \lambda_2 I) x_2 = 0$$

$$\begin{pmatrix} 6 & 6 \\ 6 & 6 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0 \Rightarrow x_2 = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

$$q_1 = \frac{x_1}{\|x_1\|} = \begin{pmatrix} y_{r1} \\ y_{s1} \end{pmatrix}$$

$$b_2 = x_2 - (q_1^T x_2) q_1 = \begin{pmatrix} -1 \\ 1 \end{pmatrix} - \left[ \begin{pmatrix} y_{r1} & y_{s1} \end{pmatrix} \begin{pmatrix} -1 \\ 1 \end{pmatrix} \right] \begin{pmatrix} y_{r1} \\ y_{s1} \end{pmatrix}$$

$$b_2 = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

$$q_2 = \frac{b_2}{\|b_2\|} = \begin{pmatrix} -y_{r2} \\ y_{s2} \end{pmatrix}$$

↳ Makes sense as  
e-vec of symmetric real matrix  
are orthogonal

6.2.7

$$Q = \begin{pmatrix} \gamma_{F_2} & -\gamma_{F_2} \\ \gamma_{F_2} & \gamma_{F_2} \end{pmatrix}$$

$$Q^T = \begin{pmatrix} \gamma_{F_2} & \gamma_{F_2} \\ -\gamma_{F_2} & \gamma_{F_2} \end{pmatrix}$$

$$\Gamma = \begin{pmatrix} 4 & 0 \\ 0 & 2 \end{pmatrix}$$

$$R = Q \Gamma Q^T = \begin{pmatrix} \gamma_{F_2} & -\gamma_{F_2} \\ \gamma_{F_2} & \gamma_{F_2} \end{pmatrix} \begin{pmatrix} 4 & 0 \\ 0 & 2 \end{pmatrix} \quad Q^T$$

$$R = \begin{pmatrix} 4\gamma_{F_2} & -3\gamma_{F_2} \\ 4\gamma_{F_2} & 3\gamma_{F_2} \end{pmatrix} \begin{pmatrix} \gamma_{F_2} & \gamma_{F_2} \\ -\gamma_{F_2} & \gamma_{F_2} \end{pmatrix}$$

$$R = \boxed{\begin{pmatrix} 3 & 1 \\ 1 & 3 \end{pmatrix}}$$

$$R^2 = \begin{pmatrix} 3 & 1 \\ 1 & 3 \end{pmatrix} \begin{pmatrix} 3 & 1 \\ 1 & 3 \end{pmatrix} = \begin{pmatrix} 10 & 6 \\ 6 & 10 \end{pmatrix} \quad \checkmark$$

$$A = \begin{pmatrix} 10 & -6 \\ -6 & 10 \end{pmatrix}$$

$$|A - \lambda I| = \lambda^2 - 20\lambda + 64 = 0$$

$$\lambda_1 = 16, \quad \lambda_2 = 4$$

6.2.7

$$(A - \lambda_1 I) \mathbf{x} = 0$$

$$\begin{pmatrix} 6 & -6 \\ -6 & 6 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0 \Rightarrow \begin{pmatrix} -1 \\ 1 \end{pmatrix} = x_1$$

$$(A - \lambda_2 I) \mathbf{x}_2 = 0$$

$$\begin{pmatrix} 6 & -6 \\ -6 & 6 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 \\ 1 \end{pmatrix} = x_2$$

$$q_1 = \frac{x_1}{\|x_1\|} = \begin{pmatrix} \sqrt{2}/2 \\ \sqrt{2}/2 \end{pmatrix}$$

$$q_2 = \frac{x_2}{\|x_2\|} = \begin{pmatrix} \sqrt{2}/2 \\ \sqrt{2}/2 \end{pmatrix}$$

$$Q = \begin{pmatrix} \sqrt{2}/2 & \sqrt{2}/2 \\ \sqrt{2}/2 & \sqrt{2}/2 \end{pmatrix}$$

$$\sqrt{\Lambda} = \begin{pmatrix} 4 & 0 \\ 0 & 2 \end{pmatrix} = \begin{pmatrix} \sqrt{16} & 0 \\ 0 & \sqrt{4} \end{pmatrix}$$

$$R = Q \sqrt{\Lambda} Q^{-1} = \begin{pmatrix} \sqrt{2}/2 & \sqrt{2}/2 \\ \sqrt{2}/2 & \sqrt{2}/2 \end{pmatrix} \begin{pmatrix} 4 & 0 \\ 0 & 2 \end{pmatrix} \begin{pmatrix} \sqrt{2}/2 & \sqrt{2}/2 \\ \sqrt{2}/2 & \sqrt{2}/2 \end{pmatrix}$$

$$= \begin{pmatrix} -\sqrt{2}/2 & \sqrt{2}/2 \\ \sqrt{2}/2 & \sqrt{2}/2 \end{pmatrix} \begin{pmatrix} \sqrt{2}/2 & \sqrt{2}/2 \\ \sqrt{2}/2 & \sqrt{2}/2 \end{pmatrix}$$

6.2.7

$$R = \begin{pmatrix} 3 & -1 \\ -1 & 3 \end{pmatrix}$$

$$R^2 = \begin{pmatrix} 3 & -1 \\ -1 & 3 \end{pmatrix} \begin{pmatrix} 3 & -1 \\ -1 & 3 \end{pmatrix} = \begin{pmatrix} 10 & -6 \\ -6 & 10 \end{pmatrix} \checkmark$$

6.2.10

$$A = \begin{pmatrix} 1 & 0 \\ 0 & 4 \end{pmatrix}$$

$$|A - \lambda I| = 0 = \lambda^2 - 5\lambda + 4$$

$$\lambda_1 = 4, \lambda_2 = 1$$

$$(A - \lambda_1 I) x_1 = 0$$

$$\begin{pmatrix} -3 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0 \Rightarrow x_1 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

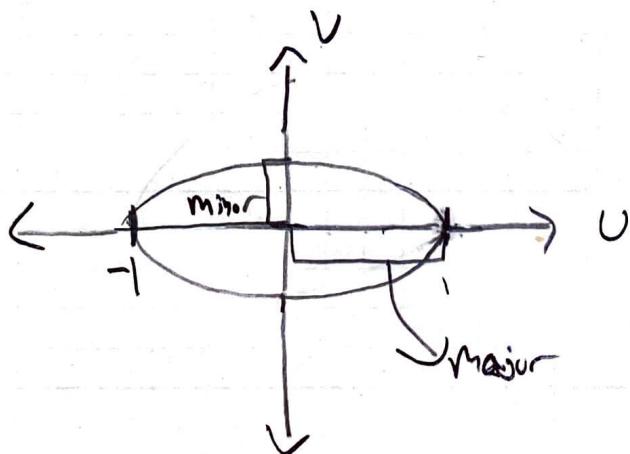
$$(A - \lambda_2 I) x_2 = 0$$

$$\begin{pmatrix} 0 & 0 \\ 0 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0 \Rightarrow x_2 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\lambda_1 = 4, x_1 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\lambda_2 = 1, x_2 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$\begin{pmatrix} 1 \\ 0 \end{pmatrix} \leftarrow$  Major axis as  
 $\lambda_2$  is smallest



6.2.14

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 5 & 4 \\ 3 & 4 & 9 \end{pmatrix}$$

$$\xrightarrow{E_{21}(-2)} \begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & -2 \\ 3 & 4 & 9 \end{pmatrix} \xrightarrow{E_{31}(-3)} \begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & -2 \\ 0 & -2 & 0 \end{pmatrix}$$

$$\xrightarrow{E_{32}(2)} \begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & -2 \\ 0 & 0 & -4 \end{pmatrix}$$

$A^T = A$ , 1 Negative Pivot, 2 Positive pivots,  $\therefore$

1 Negative  $\lambda$  & 2 Positive  $\lambda$ . Therefore

A is indefinite

$$B = \begin{pmatrix} 1 & 2 & 0 & 0 \\ 2 & 6 & -2 & 0 \\ 0 & -2 & 5 & -2 \\ 0 & 0 & -2 & 3 \end{pmatrix}$$

$$\xrightarrow{E_{21}(-2)} \begin{pmatrix} 1 & 2 & 0 & 0 \\ 0 & 2 & -2 & 0 \\ 0 & -2 & 5 & -2 \\ 0 & 0 & -2 & 3 \end{pmatrix} \xrightarrow{E_{32}(1)} \begin{pmatrix} 1 & 2 & 0 & 0 \\ 0 & 2 & -2 & 0 \\ 0 & 0 & 3 & -2 \\ 0 & 0 & -2 & 3 \end{pmatrix}$$

$$\xrightarrow{E_{43}\left(\frac{2}{3}\right)} \begin{pmatrix} 1 & 2 & 0 & 0 \\ 0 & 2 & -2 & 0 \\ 0 & 0 & 3 & -2 \\ 0 & 0 & 0 & \frac{5}{3} \end{pmatrix}$$

6.2.14

$B = B^T$ , all pivots are  $> 0 \therefore$  all  $\lambda > 0$

$B$  is positive definite

$C = -B$ , therefore all pivots  $< 0$  & all  $\lambda < 0$

$C$  is negative definite

$$D = A^{-1} \quad A^{-1} = \frac{C^T}{\det(A)}$$

$$\begin{aligned}\det(A) &= \begin{vmatrix} 5 & 4 \\ 4 & 9 \end{vmatrix} = 2 \begin{vmatrix} 2 & 4 \\ 3 & 9 \end{vmatrix} + 3 \begin{vmatrix} 2 & 5 \\ 3 & 4 \end{vmatrix} \\ &= 45 - 16 - 2(18 - 12) + 3(8 - 15) \\ &= 45 - 16 - 12 - 21 = -4\end{aligned}$$

$$C_{11} = \begin{vmatrix} 5 & 4 \\ 4 & 9 \end{vmatrix} \quad C_{12} = -\begin{vmatrix} 2 & 4 \\ 3 & 9 \end{vmatrix} \quad C_{13} = \begin{vmatrix} 2 & 5 \\ 3 & 4 \end{vmatrix}$$

$$C_{21} = -\begin{vmatrix} 2 & 3 \\ 4 & 9 \end{vmatrix} \quad C_{22} = \begin{vmatrix} 1 & 3 \\ 3 & 9 \end{vmatrix} \quad C_{23} = -\begin{vmatrix} 1 & 2 \\ 3 & 4 \end{vmatrix}$$

$$C_{31} = \begin{vmatrix} 2 & 3 \\ 5 & 4 \end{vmatrix} \quad C_{32} = -\begin{vmatrix} 1 & 3 \\ 2 & 4 \end{vmatrix} \quad C_{33} = \begin{vmatrix} 1 & 2 \\ 2 & 5 \end{vmatrix}$$

$$C = \begin{pmatrix} 29 & -6 & -7 \\ -6 & 0 & 2 \\ -7 & 2 & 1 \end{pmatrix} \quad C^T = C$$

6.2.14

$$D = F^{-1} = \begin{pmatrix} -\frac{9}{4} & \frac{6}{4} & \frac{3}{4} \\ \frac{6}{4} & 0 & -\frac{1}{2} \\ \frac{3}{4} & -\frac{1}{2} & -\frac{1}{4} \end{pmatrix}$$

$$\xrightarrow{E_2 \left( \frac{6}{24} \right)} \begin{pmatrix} -\frac{9}{4} & \frac{6}{4} & \frac{3}{4} \\ 0 & \frac{36}{116} & -\frac{16}{116} \\ \frac{3}{4} & -\frac{1}{2} & -\frac{1}{4} \end{pmatrix} \quad \frac{42}{116} \cdot \frac{5}{16}$$

$D = D^T$ , First and second pivots have different signs,  $\therefore$  at least one  $\lambda < 0$  & one  $\lambda > 0$ .

D is indefinite

6.2.23

- a) All eigenvalues are greater than 0, therefore an inverse must exist.
- b) Projection Matrices all have  $\det = 0$  except for  $I$ .
- c) The eigenvalues of a diagonal matrix are the diagonal entries.
- d) The even powers of negative definite matrices can give a positive determinate.

6.2.24

$$A = \begin{pmatrix} s & -4 & -4 \\ -4 & s & -4 \\ -4 & -4 & s \end{pmatrix}$$

$$\det(A_1) = s > 0$$

$$\det(A_2) = s^2 - 16 > 0 \quad s^2 > 16$$

$$\det(A_3) = s(s^2 - 16) + 4 \begin{vmatrix} -4 & -4 \\ -4 & s \end{vmatrix} - 4 \begin{vmatrix} -4 & s \\ -4 & -4 \end{vmatrix} > 0$$

$$s^3 - 16s + 4(-4s - 16) - 4(16 + 4s) = 0$$

$$= s^3 - 16s - 16s - 64 - 64 - 16s = 0$$

$$= s^3 - 48s - 128 > 0$$

$$= \underbrace{(s+4)^2}_{\text{Always positive}} \underbrace{(s-8)}_{s>8} > 0$$

$$s > 8$$

$$B = \begin{pmatrix} t & 3 & 0 \\ 3 & t & 4 \\ 0 & 4 & t \end{pmatrix}$$

$$\det(B_1) = t > 0$$

6.2.24

$$\det(B_2) = t^2 - 16 > 0 \quad t^2 > 16$$

$$\det(B_3) = t(t^2 - 16) - 3 \begin{vmatrix} 3 & 4 \\ 0 & t \end{vmatrix} > 0$$

$$= t^3 - 16t - 96 > 0$$

$$= t(t^2 - 25) > 0$$

$$\therefore t^2 > 25 \Rightarrow t = \pm 5$$

$t = -5 \neq 0$     $t = -5$  isn't a solution

$$\boxed{t > 5}$$