Case Study

Use the Kronecker product to convert the "matrix-matrix" equation,

$$AXB = C$$

into the "matrix-vector" equation, where X is the unknown matrix variable.

- Assume that the matrices A, B, C, and X are square and of the same size. Formulate the necessary and sufficient condition for the existence of the unique solution to AXB=C

in terms of the eigenvalues of A and B.

• Does the equation,

$$egin{bmatrix} 0 & 1 \ 0 & 1 \end{bmatrix} egin{bmatrix} x_{11} & x_{12} \ x_{21} & x_{22} \end{bmatrix} egin{bmatrix} -2 & 0 \ -3 & 1 \end{bmatrix} = egin{bmatrix} -4 & 2 \ -4 & 2 \end{bmatrix},$$

have a solution? If yes, find a solution, if not then explain why not.

Please take a moment to work through this problem on your own. When you are ready, scroll down the page to view the solution.

Explanation:

ullet We use the Kronecker product to represent the equation AXB=C in the form

$$\left(B^{ op}\otimes A
ight)\mathrm{vec}(X)=\mathrm{vec}(C),$$

where $\operatorname{vec}(\cdot)$ is the stacking operator, that is, the vectorizing operator. There exists a unique solution to the above equation if and only if the square matrix $B^{\top}\otimes A$ is invertible. This matrix is invertible if and only if all its eigenvalues are non-zero. The eigenvalues of the matrix $B^{\top}\otimes A$ are the products of the eigenvalues of A and B. In summary, a necessary and sufficient condition for the matrix equation AXB=C to have a unique solution is that none of the eigenvalues of the matrices A and B are equal zero.

• We represent AXB=C in the form,

$$\left(egin{bmatrix} -2 & -3 \ 0 & 1 \end{bmatrix} \otimes egin{bmatrix} 0 & 1 \ 0 & 1 \end{bmatrix}
ight) \operatorname{vec} \left(egin{bmatrix} x_{11} & x_{12} \ x_{21} & x_{22} \end{bmatrix}
ight) = \operatorname{vec} \left(egin{bmatrix} -4 & 2 \ -4 & 2 \end{bmatrix}
ight).$$

Performing the required operations, we obtain

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$$egin{bmatrix} 0 & -2 & 0 & -3 \ 0 & -2 & 0 & -3 \ 0 & 0 & 0 & 1 \ 0 & 0 & 0 & 1 \end{bmatrix} egin{bmatrix} x_{11} \ x_{21} \ x_{12} \ x_{22} \end{bmatrix} = egin{bmatrix} -4 \ -4 \ 2 \ 2 \end{bmatrix}.$$

There are multiple solutions to the above system of equations. One of the solutions is

$$X = \begin{bmatrix} 0 & 0 \\ -1 & 2 \end{bmatrix}$$



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