

ECE 602: LUMPED LINEAR SYSTEMS

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Time-Invariant and Time-Varying Systems,
Causal and Non-Causal Systems

Time-Invariant vs. Time-Varying Systems

Continuous-time systems \mathcal{N} are

- **time-invariant** if for all $u \in \mathcal{U}$ and all $\tau \in \mathcal{I}$, $\tau \geq 0$

$$y(\cdot) = \mathcal{N}(u(\cdot)) \quad \Rightarrow \quad y(\cdot - \tau) = \mathcal{N}(u(\cdot - \tau))$$

- **time-varying** if otherwise

Similar definitions for discrete-time systems

Examples

❶ $y(t) = [u(t)]^2$

❷ $y(t) = t^2 u(t)$

❸ $y(t) = \int_{t-1}^{t+2} u(s) ds$

❹ $y(t) = u(t) - u(t-1)$

❺ $y(t) = \begin{cases} t & \text{if } |u(t)| \leq 1 \\ 0 & \text{if } |u(t)| > 1 \end{cases}$

❻ $y[k] = \begin{cases} 3u[k-1] & \text{if } k = 0, 1, \dots, \\ 0 & \text{if } k = -1, -2, \dots \end{cases}$

Causal vs. Non-Causal Systems

Continuous-time systems \mathcal{N} are

- **causal** if for all $t_0 \in \mathcal{I}$, $y(t_0)$ only depends on past input, $u(t)$ for $t \leq t_0$. Or more precisely,

$$\begin{cases} y_1 = \mathcal{N}(u_1), y_2 = \mathcal{N}(u_2) \\ u_1(t) = u_2(t), t \leq t_0 \end{cases} \Rightarrow y_1(t_0) = y_2(t_0)$$

- **non-causal** if otherwise

Similar definitions for discrete-time systems

Examples

$$\textcircled{1} \quad y(t) = [u(t)]^2$$

$$\textcircled{2} \quad y(t) = t^2 u(t)$$

$$\textcircled{3} \quad y(t) = \int_{t-1}^{t+2} u(s) \, ds$$

$$\textcircled{4} \quad y(t) = u(t) - u(t-1)$$

$$\textcircled{5} \quad y(t) = \begin{cases} t & \text{if } |u(t)| \leq 1 \\ 0 & \text{if } |u(t)| > 1 \end{cases}$$

$$\textcircled{6} \quad y[k] = \begin{cases} 3u[k-1] & \text{if } k = 0, 1, \dots, \\ 0 & \text{if } k = -1, -2, \dots \end{cases}$$