



For my robot:

`paper_size_x = 32 * 25.4`

`paper_size_y = 40 * 25.4`

`image_size_x = 28 * 25.4`

`image_size_y = 36 * 25.4`

`paper_top_to_origin = 285mm`

This gives me a 50.8mm (2 inch) border

All coordinates in millimeters.