

PID Controller

审阅

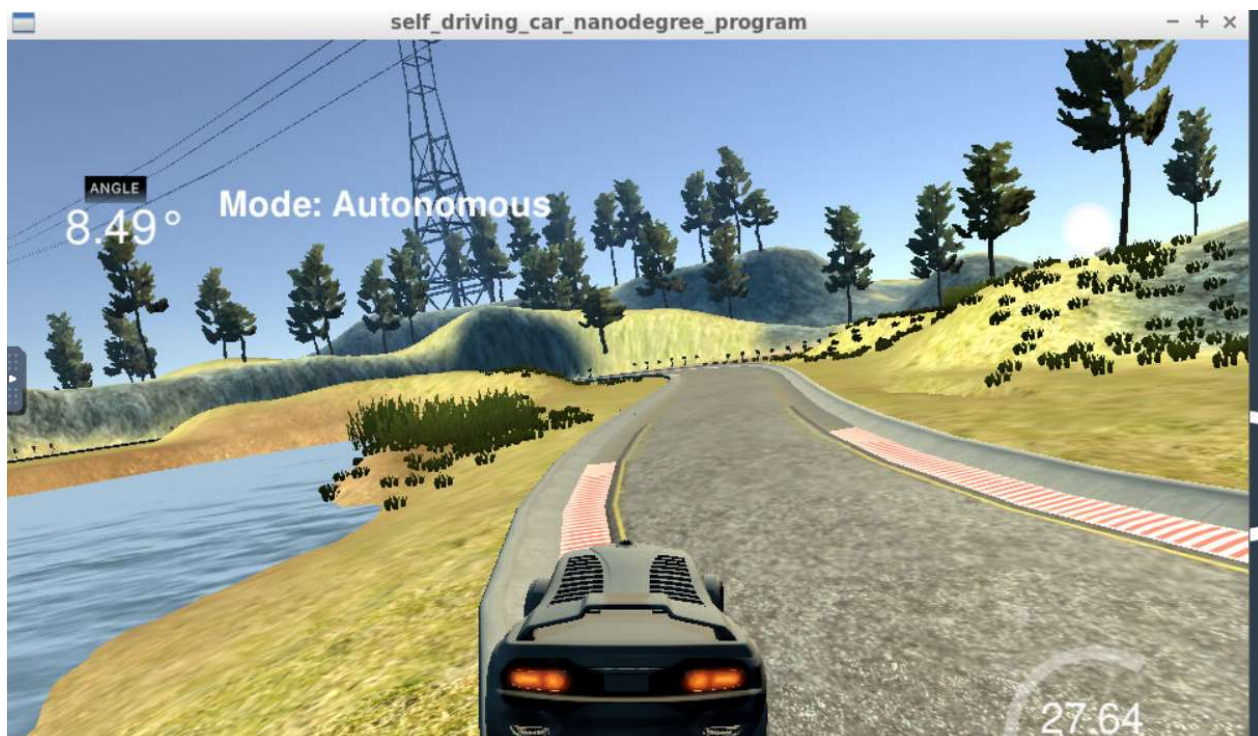
HISTORY

无法审阅

Your project could not be reviewed. Please resubmit after you address the issue noted below by the reviewer.

Dear Student,

Thanks for the submission again and I am sorry however the car is still not staying on the track. It goes off over ledges at different instances.





As a previous suggestion, request you to stabilize car performance using base algorithm first and see how it goes.

Good luck!

 [重新提交](#)

 [下载项目文档](#)

了解 [修改和重新提交项目的最佳做法](#).

[返回](#) PATH