

PID Controller

审阅

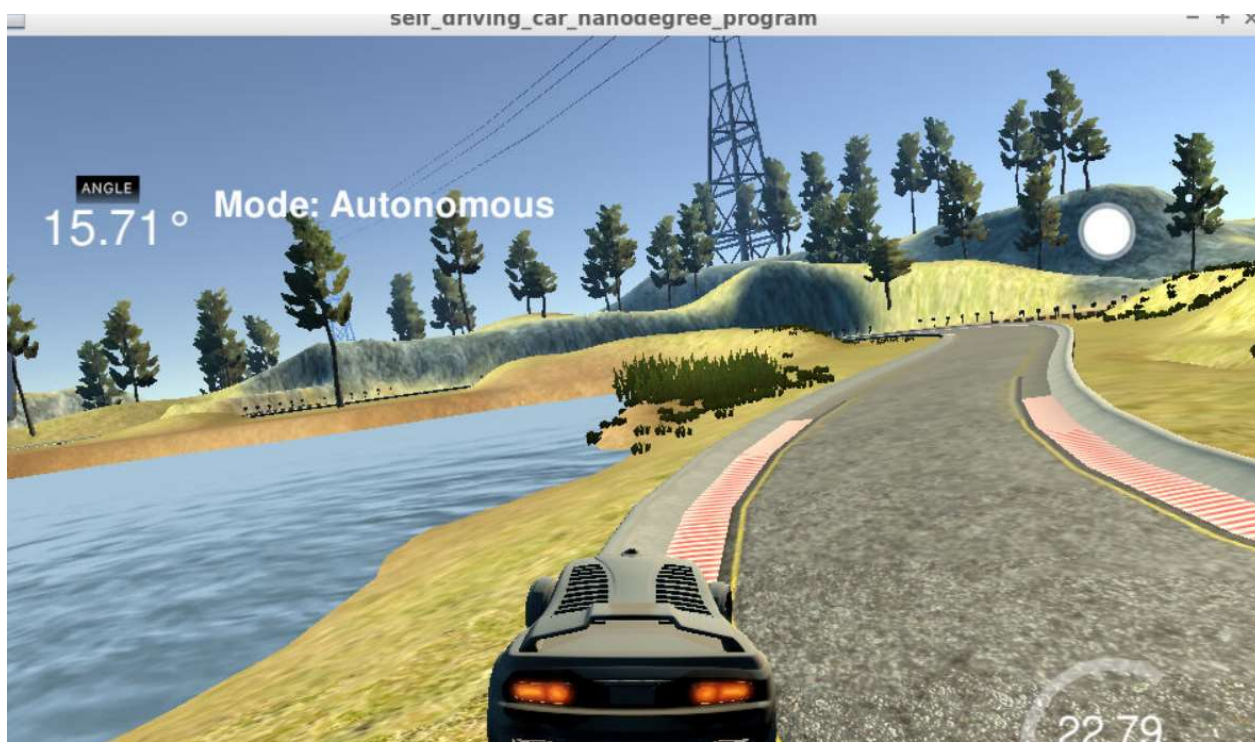
HISTORY

无法审阅

Your project could not be reviewed. Please resubmit after you address the issue noted below by the reviewer.

Dear Student,

Thanks for the submission and ensuring that your code compiles successfully. However, the car is going off the ledges and drivable portion at multiple instances.





Kindly work on fixing the hyperparameters. I would suggest you to first keep base algorithm and find initial set of hyperparameters that work decent on the track. Later you may include twiddle to further fine tune coefficients for better performance.

Good luck!

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