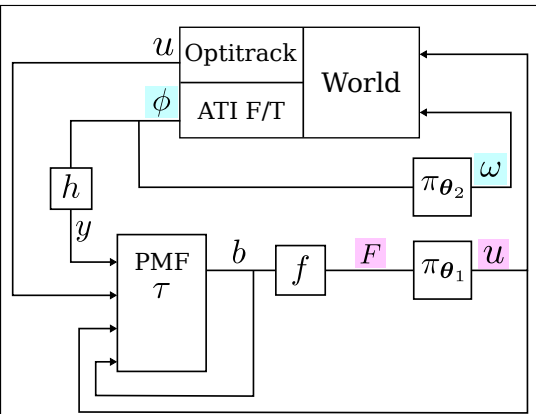
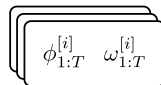
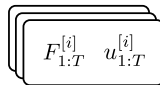


# Environment-control

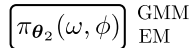
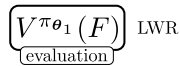


# Data-learning-control

## Data collection



## Learning



## Control

$$u = \mathbb{E}_{\alpha} \{ \pi_{\theta_1}(u|F) \}$$

$$\omega \sim \mathbb{E} \{ \pi_{\theta_2}(\omega|\phi) \}$$