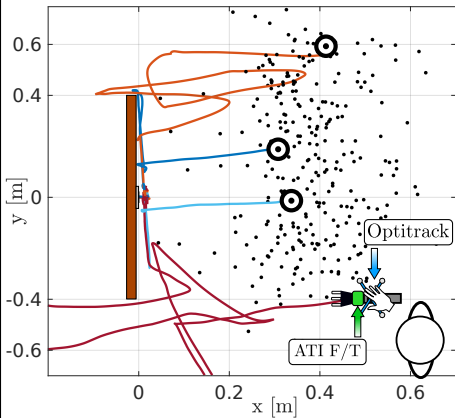
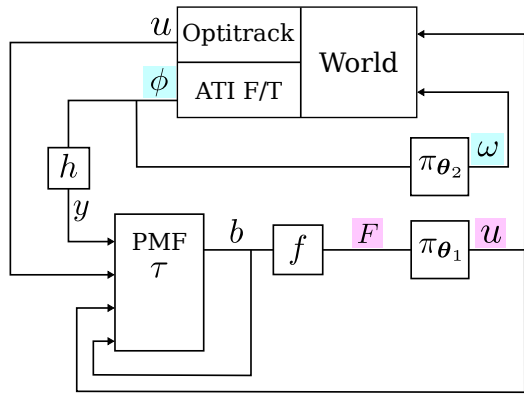


Demonstrations



Environment-control

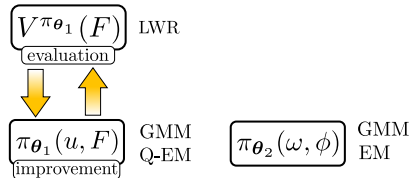


Data-learning-control

Data collection



Learning



Control

$$u = \mathbb{E}_{\alpha} \{ \pi_{\theta_1}(u|F) \}$$

$$\omega \sim \mathbb{E} \{ \pi_{\theta_2}(\omega|\phi) \}$$