

Guillaume de Chambrier

Avenue de la Gare 3 – 1020 Renens – Switzerland • Born 29.06.1987

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🌐 <http://lasa.epfl.ch/people/member.php?SCIPER=213946.com> • Swiss and British

Profile

With several independent projects, I am an expert in developing and applying machine learning techniques to robot systems and I possess meticulous strong analytical skills.

Education

PhD in Manufacturing Systems & Robotics **cole polytechnique f d rale de Lausanne, Switzerland**

- Thesis: Learning Search Strategies from Human Demonstrations *2012 - 31.08.2016*
supervisor: Prof. Aude Billard

First class Master of Informatics with Honours Informatics **University of Edinburgh, UK**

- Thesis: Building and Controlling a Hexapod Robot *2006 - 2011*
supervisor: Dr. Michael Herrmann

Erasmus Exchange, Bachelor **Universit t des Saarlandes, Germany**
2008 - 2009

Experience

Teaching Assistant **cole polytechnique f d rale de Lausanne**

- Course: Applied Machine Learning (MSc) *2013-2016*
- Course: Advanced Machine Learning (MSc)

European Project **cole polytechnique f d rale de Lausanne**

- Flexible Skill and Intuitive Robot Tasking *2012-2013*

Supervision **cole polytechnique f d rale de Lausanne**

- Akshara Rai (Msc student) *2013*

Technical Skills

Programming: C/C++, Python, Java, MATLAB

Expertise: Robotics, Reinforcement Learning, Non-parametric Bayesian inference, Machine learning & Computer Vision

Languages

French, English (first language)

Awards and Certification

2010: Google Prize: Best Phase 1 Project in Master of Informatics Programme

Publication

Oral Presentations

de Chambrier G,et al: (Oct. 2013). Learning from Failed Demonstrations in Unreliable Systems. IEEE-RAS International Conference on Humanoid Robots, Atlanta, US.

de Chambrier G,et al: (Dec. 2013). Learning search behaviour from humans. IEEE-Robotics and Biomimetics (ROBIO), Shenzhen, CN.

de Chambrier G,et al: (Jun. 2014). Learning search policies from humans in a partially observable context. Journal of Robotics and Biomimetics. 1:8

de Chambrier G,et al: (2016). Learning Peg-in-Hole policies given no visual information. Journal of Robotics and Autonomous Systems (RAS) (*under review*)

de Chambrier G,et al: (2016). Measurement Likelihood Memory for Bayesian State Estimation for search scenarios. Journal: Frontiers in Artificial Intelligence(*under review*)