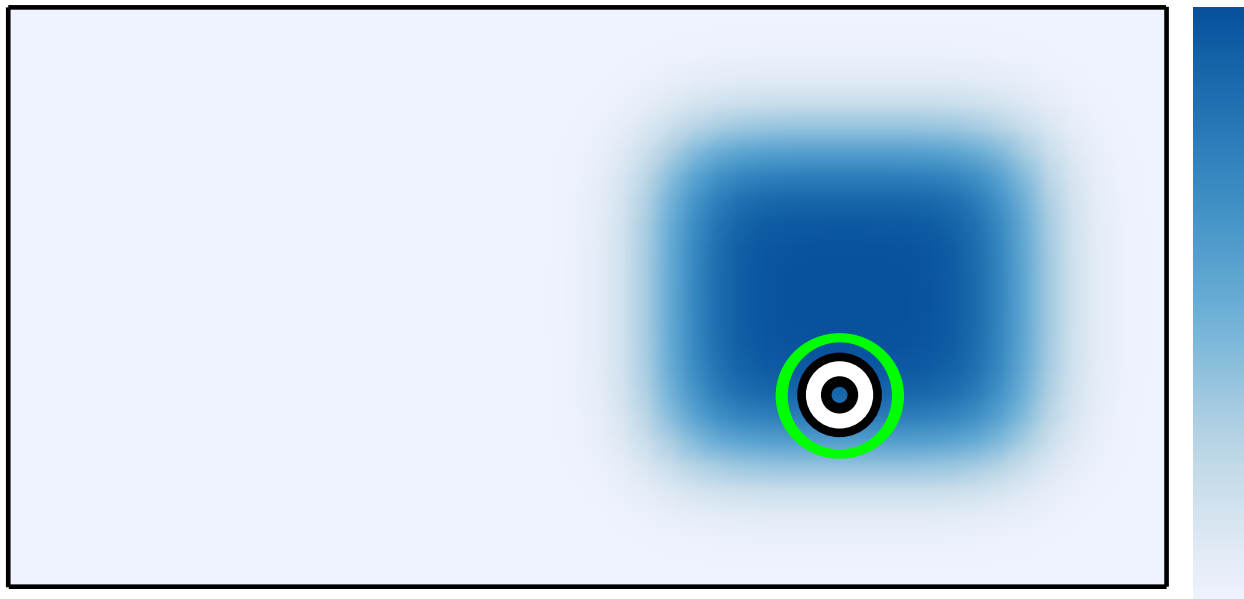
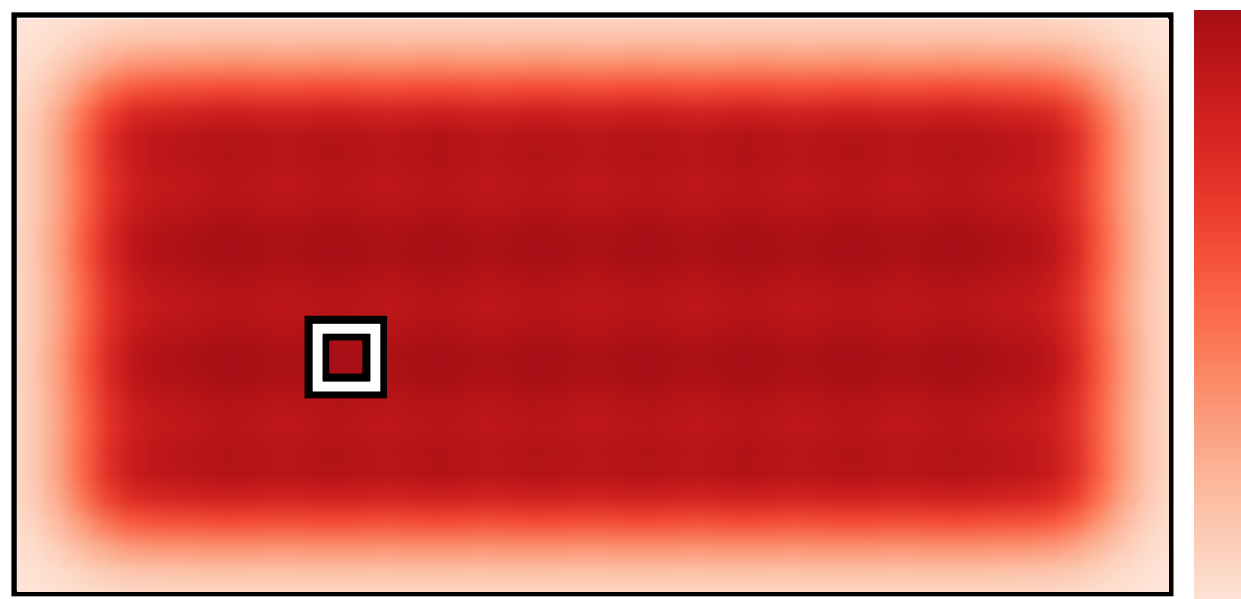


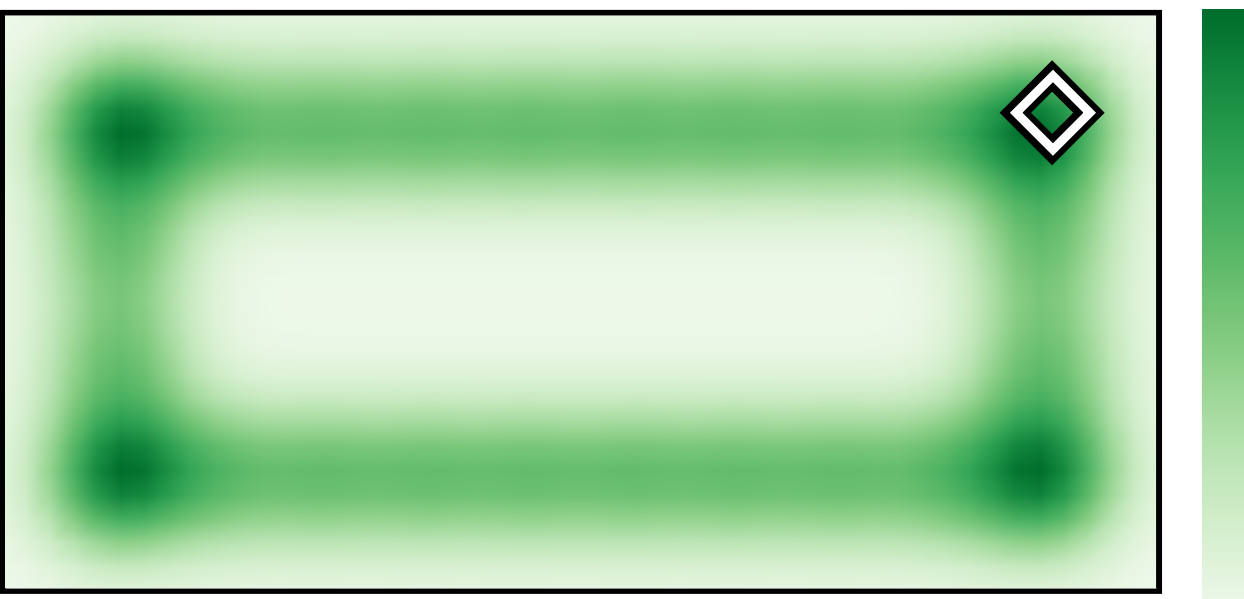
Agent

 $P(A_t)$ 

Object(1)

 $P(O^{(1)})$ 

Object(2)

 $P(O^{(2)})$ 

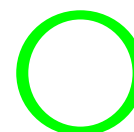
Agents position



Object(1) position



Object(2) position



range of Agents
perception