1、公式推导

注目:
$$f_{\theta}(x_{i}) = \frac{1}{1+e^{-\theta^{T}X_{i}}}$$
 $1-f_{\theta}(x_{i}) = \frac{e^{-\theta^{T}X_{i}}}{1+e^{-\theta^{T}X_{i}}}$
 $M(L(\theta)) = \frac{\pi}{i^{N-1}} \left(y_{i} * h_{i} f_{\theta}(x_{i}) + (1-y_{i}) h_{i} (1-f_{\theta}(x_{i})) \right)$
 $= \frac{\pi}{i^{N-1}} \left(y_{i} * h_{i} f_{\theta}(x_{i}) + h_{i} (1-f_{\theta}(x_{i})) + h_{i} (1-f_{\theta}(x_{i})) \right)$
 $= \frac{\pi}{i^{N-1}} \left(y_{i} * h_{i} \frac{f_{\theta}(x_{i})}{10+f_{\theta}(x_{i})} + h_{i} \frac{(1-f_{\theta}(x_{i}))}{1+e^{-\theta^{T}X_{i}}} \frac{e^{-\theta^{T}X_{i}}}{e^{-\theta^{T}X_{i}}} \right)$
 $= \frac{\pi}{i^{N-1}} \left(y_{i} * h_{i} f_{\theta}(x_{i}) + h_{i} \frac{e^{-\theta^{T}X_{i}}}{1+e^{-\theta^{T}X_{i}}} \frac{e^{-\theta^{T}X_{i}}}{e^{-\theta^{T}X_{i}}} \right)$
 $= \frac{\pi}{i^{N-1}} \left(y_{i} * h_{i} f_{\theta}(x_{i}) + h_{i} f_{\theta}(x_{i}) + h_{i} f_{\theta}(x_{i}) \right)$
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 $= \frac{\pi}{i^{N-1}} \left(y_{i} * h_{i} f_{\theta}(x_{i}) + h_{i} f_{\theta}(x_{i}) \right)$
 $= \frac{\pi}{i^{N-1$

2、上机实验

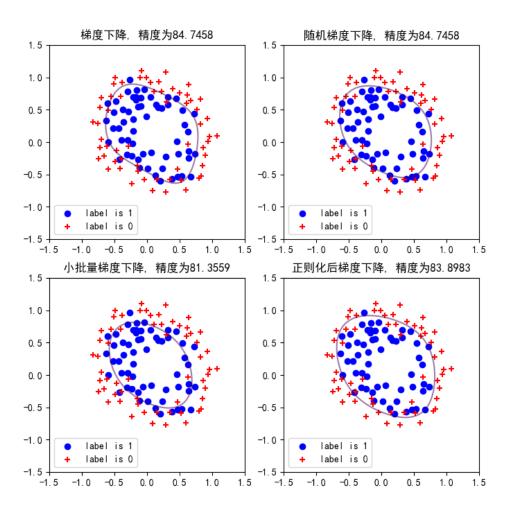
(1)从文件中读取数据,直接转换为四阶多项式,以四阶多项式作为决策边界。

```
def read_data(string):
       infile = open(string, 'r')
       data, l_x, l_y = [], [], []
       for line in infile:
          words = line.split(',') # 以逗号分开
          x1 = float(words[0])
          x2 = float(words[1])
          y1 = int(words[2][0:1])
          l_x.append([1, x1, x2, x1 * x2, x1 ** 2, x2 ** 2,
                    x1 * x2 ** 2, x2 * x1 ** 2, x1 ** 3, x2 ** 3,
                    x1 * x2 ** 3, x1 ** 2 * x2 ** 2, x1 ** 3 * x2, x1 ** 4, x2 ** 4])
          l_y.append([y1])
          data.append([x1, x2, y1])
       infile.close()
       l_x = np.array(l_x)
       l_y = np.array(l_y)
       data = np.array(data)
       return data, l_x, l_y
     (2) 梯度下降,在θ或者损失函数下降很小时提前终止
    def gradient_ascent(X, y, eta=0.1, n_iterations=5000):
        theta = np.random.randn(15, 1)
        for iteration in range(n_iterations):
            f = sigmoid(np.dot(X, theta))
            gradients = np.dot(X.T, (y - f))
            theta_old = np.array([i for i in theta])
            theta += eta * gradients
            if 0.01 < cost(theta_old, X, y) - cost(theta, X, y) < 0.01:
               return theta
            if 0.01 < np.dot((theta - theta_old).T, (theta - theta_old)) < 0.01:</pre>
               return theta
        return theta
     (3) 随机梯度下降, 随机选择一个样本进行迭代, 每轮迭代之后降低学习
率,减小振荡
    def stochastic_gradient_ascent(X, y):
        theta = np.random.randn(15, 1)
        for epoch in range(100):
             for i in range(len(y)):
                 random_index = np.random.randint(len(y))
                 xi = X[random_index:random_index + 1, :]
                 yi = y[random_index:random_index + 1]
                 f = sigmoid(np.dot(xi, theta))
                 gradients = np.dot(xi.T, (yi - f))
                 eta = 1 / (np.sqrt(epoch + 1)) # 不断降低学习率
                 theta += eta * gradients
        return theta
```

(4) 小批量梯度下降,每次选择 mb_size 个样本,事先按顺序分配好迭代的小样本,然后进行 100 轮迭代。

```
def mini_batch_gradient_ascent(X, y, mb_size=10, eta=0.1):
    theta = np.random.randn(15, 1)
    m = len(y)
    nums = (m - 1) // mb_size
    index_list = np.arange(nums)
    index_list = index_list * mb_size
    for epoch in range(100):
         for index in index_list:
             xi = X[index:index + mb_size + 1, :]
             yi = y[index:index + mb_size + 1]
             f = sigmoid(np.dot(xi, theta))
             gradients = np.dot(xi.T, (yi - f))
             theta += eta * gradients
         # 处理最后可能不到mb_size大小的数组
         d = m - nums * mb_size
         index = index_list[-1] + mb_size
         xi = X[index:index + d + 1, :]
         yi = y[index:index + d + 1]
         f = sigmoid(np.dot(xi, theta))
         gradients = np.dot(xi.T, (yi - f))
         theta += eta * gradients
    return theta
(5) 正则化,对θ进行惩罚,减小过拟合,以梯度下降为例
def reg_gradient(X, y, eta=0.1, n_iterations=10000, learning_rate=0.1):
   theta = np.random.randn(15, 1)
   for iteration in range(n_iterations):
      f = sigmoid(np.dot(X, theta))
      gradients = np.dot(X.T, (y - f))
      theta_old = np.array([i for i in theta])
      theta = theta * (1 - eta * learning_rate) + eta * gradients
       if 0.01 < reg_cost(theta_old, X, y) - reg_cost(theta, X, y) < 0.01:</pre>
          return theta
       if 0.01 < np.dot((theta - theta_old).T, (theta - theta_old)) < 0.01:</pre>
          return theta
   return theta
```

(6) 梯度下降,随机梯度下降, 小批量梯度下降和正则化梯度下降进行比较,可以发现都可以得到较好的结果。加入正则化后梯度下降的 θ 值更小一点,决策 边界 更光滑些, 较好的减小了过拟合的现象。



梯度下降后的得到的 θ 值为:

随机梯度下降后的得到的 θ 值为:

```
[ 4.18732136  2.52144889  4.25928263  -6.03602321  -6.85404428  -7.17677913  -0.69428872  -1.66590994  1.18860034  -1.57376916  -2.00956159  -2.19906501  1.1130972  -6.16796198  -4.46086954]
```

小批量梯度下降后的得到的 θ 值为:

```
[ 3.05340103 2.02688606 3.52050902 -5.90566788 -7.87894932 -6.39295466 -0.88827487 -1.98658334 0.56767954 0.31943746 -1.51214073 -3.08040269 -0.19991322 -4.84840199 -5.22576131] 
对梯度下降正则化后的得到的θ值为:
```

(5)对正则化惩罚因子的比较,可以发现在惩罚因子比较好时,得到的结果比较好,但是在惩罚因子过大时,会找不到决策边界。

