#### CS M146 - Week 4

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#### Overview

- Exercises in class
- HW2 Q4
- Numpy tutorial
- HW2 Q5

#### Exercise in class

- Let  $\sigma(z) = \frac{1}{1 + \exp(-z)}$ , show  $\sigma(-z) = 1 \sigma(z)$
- What is the gradient (respect to  $\theta$ ) of

$$-\sum_{i=1}^{m} y_i \log \sigma(\boldsymbol{\theta}^T x) + (1 - y_i) \log(1 - \sigma(\boldsymbol{\theta}^T x))$$
 (1)

• we have  $\sigma'(z) = \sigma(z)(1 - \sigma(z))$  (proved in class)

•

$$\frac{\partial h_{\theta}(\mathbf{x})}{\partial \theta_{k}} = \frac{\partial \sigma(\boldsymbol{\theta}^{T} \mathbf{x})}{\partial \theta_{k}} = \frac{\partial \sigma(\boldsymbol{\theta}^{T} \mathbf{x})}{\partial (\boldsymbol{\theta}^{T} \mathbf{x})} \frac{\partial (\boldsymbol{\theta}^{T} \mathbf{x})}{\partial \theta_{k}}$$

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#### Exercise in Class

LMS regression can be solved analytically. Given a dataset  $D = (x_1, y_1), (x_2, y_2), \dots, (x_m, y_m)$ , define matrix X and vector Y as follows:

$$X = \left[\mathbf{x}_{1}, \mathbf{x}_{2}, \cdots, \mathbf{x}_{m}\right]_{d \times m}, Y = \begin{bmatrix} y_{1} \\ y_{2} \\ \vdots \\ y_{m} \end{bmatrix}_{m \times 1}$$
(2)

Show that the optimization problem

$$J(\mathbf{w}) = \frac{1}{2} \sum_{i=1}^{m} (y_i - \mathbf{w}^T \mathbf{x}_i)^2$$

is equivalent to

$$\min_{\mathbf{w}} (X^T \mathbf{w} - \mathbf{y})^T (X^T \mathbf{w} - \mathbf{y})$$

This can be solved analytically. Show that the solution w\* is

$$\mathbf{w}^* = (XX^T)^{-1}X\mathbf{y}$$

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#### Exercise in Class

$$f(\mathbf{w}) = (X^T \mathbf{w} - \mathbf{y})^T (X^T \mathbf{w} - \mathbf{y})$$

$$= [(X^T \mathbf{w})^T - \mathbf{y}^T] (X^T \mathbf{w} - \mathbf{y})$$

$$= [\mathbf{w}^T X - \mathbf{y}^T] (X^T \mathbf{w} - \mathbf{y})$$

$$= \mathbf{w}^T X X^T \mathbf{w} - \mathbf{y}^T X^T \mathbf{w} - \mathbf{w}^T X \mathbf{y} + \mathbf{y}^T Y$$

$$\stackrel{1}{=} \mathbf{w}^T X X^T \mathbf{w} - 2 \mathbf{y}^T X^T \mathbf{w} + \mathbf{y}^T \mathbf{y}$$
(3)

1 holds because  $([\mathbf{v}^T X^T \mathbf{w}]_{1 \times 1})^T = [\mathbf{v}^T X^T \mathbf{w}]_{1 \times 1} = \mathbf{w}^T X \mathbf{v}$ .

$$\nabla_{\mathbf{w}} f(\mathbf{w}) = 2XX^{T} \mathbf{w} - 2X \mathbf{y} = 0$$
$$\mathbf{w} = (XX^{T})^{-1} X \mathbf{y}$$
 (4)

This is slightly different from the formula in homework. You can match the formula in homework by taking  $X' = X^T$ .

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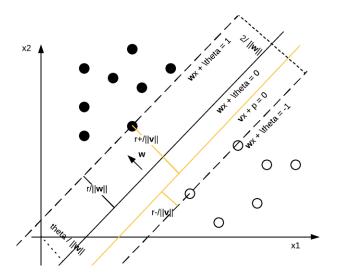
• Linearly Separable  $\Rightarrow \exists$  a linear function with parameter  $(\mathbf{w}, \theta)$ ,

$$\forall (\mathbf{x}_i, y_i) \in D, y_i = \begin{cases} 1 \text{ if } \mathbf{w}^T \mathbf{x}_i + \theta \ge 0\\ -1 \text{ if } \mathbf{w}^T \mathbf{x}_i + \theta < 0 \end{cases}$$
 (5)

The following linear program is used to "find" the linear separator

$$\min_{(\mathbf{w},\theta),\delta} \delta$$
s.t.  $y_i(\mathbf{w}^T \mathbf{x}_i + \theta) \ge 1 - \delta$ , (6)
$$\delta \ge 0, \forall (\mathbf{x}_i, y_i) \in D$$

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#### Linearly Separable

 $\Rightarrow \exists$  a linear function with parameter  $(\mathbf{v}, \rho)$ ,

$$\forall (\mathbf{x}_i, y_i) \in D, y_i = \begin{cases} 1 \text{ if } \mathbf{v}^T \mathbf{x}_i + \rho \ge 0\\ -1 \text{ if } \mathbf{v}^T \mathbf{x}_i + \rho < 0 \end{cases}$$
 (7)

 $\Rightarrow \exists$  a linear function with parameter  $(\mathbf{v}, \rho)$ ,

$$\min_{(x,y)\in D, y=1} (\mathbf{v}^{T} x + p) \ge 0 > \max_{(x,y)\in D, y=-1} (\mathbf{v}^{T} x + p)$$

$$r^{+} \ge 0 > r^{-}$$

$$r^{+}/||\mathbf{v}|| \ge 0 > r^{-}/||\mathbf{v}||$$
(8)

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$$\min_{(\mathbf{w},\theta),\delta} \quad \delta 
\text{s.t.} \quad y_i(\mathbf{w}^T \mathbf{x}_i + \theta) \ge 1 - \delta, 
\delta \ge 0, \forall (\mathbf{x}_i, y_i) \in D$$
(9)

#### Observations

• The distance of a point x to a hyperplane  $\mathbf{w}^T x + \theta$  is

$$r_{x} = (\mathbf{w}^{T}x + \theta)/||\mathbf{w}||$$

- $y_i(\mathbf{w}^T\mathbf{x}_i + \theta) = |r_x|/||\mathbf{w}||$
- If  $\delta^* = 0$ , then there must exist a hyperplane  $(\mathbf{w}^T, \theta)$ , such that  $y_i(\mathbf{w}^T\mathbf{x}_i + \theta) \ge 1 0 = 1$ .
- If there exist a hyperplane  $(\mathbf{w}^T, \theta)$ , such that  $y_i(\mathbf{w}^T\mathbf{x}_i + \theta) \geq 1$ , then  $\delta^* = 0$ .
- Even the linear program reach the minimum value  $\delta^* = 0$ , the optimal hyperplane  $(\mathbf{w}^*, \theta^*)$  is not unique.

# HW2 Q4.a - Entire Logic

- 1) Linearly Separable  $\Rightarrow \exists$  a linear function with parameter  $(\mathbf{v}, \rho)$  that satisfies condition (1).
- 2) Using  $(\mathbf{v}, \rho)$  to show that there is  $(\mathbf{w}, \theta)$  that satisfies

$$y_i(\mathbf{w}^T x_i + \theta) \geq 1$$

3) Trivial to show that

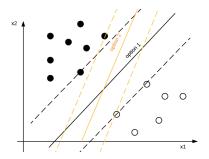
$$y_i(\mathbf{w}^T x_i + \theta) \ge 1 \Leftrightarrow (\mathbf{w}, \theta, \delta^* = 0)$$
 optimized condition 2

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#### HW2 Q4 - Some Additional Interpretation

Statement: Even the linear program reach the minimum value  $\delta^*=0$ , the optimal hyperplane  $(\mathbf{w}^*,\theta^*)$  is not unique. (You can prove question a by simply finding one of them.)

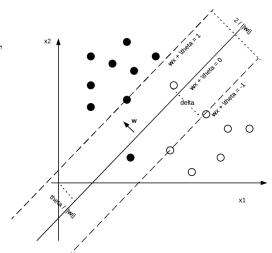
Why? Because in many cases, there are more than one linear functions that can "perfectly" separate the data. And for each linear function  $(\mathbf{v}_k, \rho_k)$ , we can find a corresponding  $(\mathbf{w}_k, \theta_k)$  that satisfies condition (2).



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# HW2 Q4 - linearly inseparable case

$$\min_{(\mathbf{w},\theta),\delta} \delta$$
s.t.  $y_i(\mathbf{w}^T \mathbf{x}_i + \theta) \ge 1 - \delta$ ,  $\delta \ge 0$ ,  $\forall (\mathbf{x}_i, y_i) \in D$  (10)



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# NumPy\_Tutorial

```
• import numpy
  import numpy as np
  from numpy import *
```

• NumPy's arrays are more compact than Python lists.

```
b = np.array([6, 7, 8])
b_ = [6,7,8]
```

• Attributes: shape, size, type, etc.

```
>>> np.array([1, 2, 3]).shape
(3,)
>>> np.array([[1, 2, 3]]).shape
(1, 3)
>>> np.array([[1], [2], [3]]).shape
(3, 1)
```

## $\mathsf{NumPy}_{\scriptscriptstyle{-}}\mathsf{Tutorial}$

```
• >>> np.zeros((3,4))
  array([[ 0., 0., 0., 0.],
         [0., 0., 0., 0.],
         [0., 0., 0., 0.]
>>> a = np.array([[3,1,5],
          [1,0,8],[2,1,4]])
  >>> for i in a:
  ... print i
  [3 1 5]
  [1 0 8]
  [2 \ 1 \ 4]
\bullet >>> ones_ = np.ones((3,1))
  >>> np.c_[ones_,a]
  array([[ 1., 3., 1., 5.],
         [1., 1., 0., 8.],
         [1., 2., 1., 4.]])
  >>> np.column_stack((ones_,a))
```

```
>>> A = np.array([[1,1],[0,1]])
>>> B = np.array([[2,0],[3,4]])
>>> A+B
array([[3, 1],
      [3.511)
>>> A-B
array([[-1, 1],
     [-3, -3]])
>>> B**2
array([[ 4, 0],
      [ 9, 16]])
>>> A*B # elementwise product
array([[2, 0],
      [0, 4]])
>>> np.dot(A,B) # matrix product
array([[5, 4],
      [3, 4]])
>>> 2*A
array([[2, 2],
      [0, 2]])
```

Given N training instances, it is always possible to obtain a perfect fit (a fit in which all the data points are exactly predicted) by setting the degree of the regression to N-1.

A polynomial of degree n is of the form  $p_{n-1}(x) = a_{n-1}x^{n-1} + a_1x + a_0$ . To study the existence and uniqueness of such a polynomial consider the system of linear equations:

$$\begin{cases}
a_{n-1}x_1^{n-1} + a_1x_1 + a_0 = y_1 \\
& \cdots \\
a_{n-1}x_n^{n-1} + a_1x_n + a_0 = y_n
\end{cases}$$
(11)

We write the system as

$$\begin{pmatrix} x_1^{n-1} & x_1^{n-2} & \cdots & x_1 & 1 \\ & & \cdots & & \\ x_n^{n-1} & x_n^{n-2} & \cdots & x_n & 1 \end{pmatrix} \begin{pmatrix} a_{n-1} \\ \cdots \\ a_0 \end{pmatrix} = \begin{pmatrix} y_1 \\ \cdots \\ y_n \end{pmatrix}$$
(12)

There are n unknowns with n equations. This results in an unique answer.

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# The End