# CS5016: Computational Methods and Applications Ordinary Differential Equations

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#### What is an ODE?

An equation involving one or more derivatives of an unknown function.

If all derivatives are taken with respect to a single independent variable we get an **ordinary differential equation**.

The differential equation (ordinary or partial) has order p if p is the maximum order of differentiation in the equation.

A simple order 1 ODE

$$\frac{d(x(t))}{dt} = -x(t)$$

Verify that the function  $x(t) = e^{-t}$  satisfies the above ODE.

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### An example: prey predator dynamics

The Lotka–Volterra equations<sup>1</sup>, also known as the predator–prey equations, are a pair of first-order nonlinear differential equations, frequently used to describe the dynamics of biological systems in which two species interact, one as a predator and the other as prey. The populations change through time according to the pair of equations:

$$\frac{d(x(t))}{dt} = \alpha x(t) - \beta x(t)y(t) \qquad \frac{d(y(t))}{dt} = \delta x(t)y(t) - \gamma y(t)$$

x(t) and y(t) denotes number of prey and predators at time t, respectively.

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#### Order reduction

An ODE of order p > 1 can always be reduced to a system of p equations of order 1.

Consider the following order 3 ODE

$$\frac{d(x(t))}{dt} + x(t)\frac{d^2(x(t))}{dt^2} + 3x(t)^2\frac{d^3(x(t))}{dt^3} = 4x(t)^3$$

The above ODE is equivalent to the following system of order 1 ODEs. Verify!!!

$$u(t) + x(t)v(t) + 3x(t)^{2} \frac{d(v(t))}{dt} - 4x(t)^{3} = 0$$
$$u(t) - \frac{d(x(t))}{dt} = 0$$
$$v(t) - \frac{d(u(t))}{dt} = 0$$

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## The Cauchy problem

An ordinary differential equation in general admits an infinite number of solutions.

For e.g.,  $\frac{d(x(t))}{dt} = -x(t)$  admits the solution  $x(t) = Ce^{-t}$ , where C an arbitrary constant.

If we impose the condition x(0) = 2, we get a unique solution  $x(t) = 2e^{-t}$ .

#### Cauchy problem

Find  $x: I \to \mathbb{R}$  such that

$$x^{'}(t) = f(t, x(t)) \quad \forall t \in I \quad \text{and} \quad x(t_0) = x_0$$

where I is an interval of  $\mathbb{R}$ .

If certain conditions are met, the *Cauchy problem* has a unique solution. What are these conditions?

## Explicit and implicit solution

The ODE  $\frac{d(x(t))}{dt} = -x(t)$  has an explicit solution  $x(t) = Ce^{-t}$ , i.e., x can be written as a function of t.

Consider the following ODE

$$\frac{d(x(t))}{dt} = \frac{(x(t)-t)}{(x(t)+t)}$$

Show that the following satisfies the above ODE

$$\frac{1}{2}\ln(t^2 + x(t)^2) + \tan^{-1}\frac{x(t)}{t} = C$$

x(t) and t are related according to the above law. However, it is not possible to write x(t) as a function of t.

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#### Euler methods

Subdivide integration interval  $I = [t_0, T]$ , with  $T < \infty$ , into  $N_h$  intervals of length  $h = (T - t_0)/N_h$ ; h is called the **discretization step**.

At each  $t_n, n \in \{0, 1, \dots, N_h - 1\}$  we seek the unknown value  $x_n$  that approximates  $x(t_n)$ . The set of values  $\{x_n\}_{n=0}^{N_h - 1}$  is our numerical solution.

#### Forward Euler method

$$x_{n+1} = x_n + hf(t_n, x_n) \quad \forall n \in \{0, 1, \dots, N_h - 1\}$$

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$$x_{n+1} = x_n + hf(t_{n+1}, x_{n+1}) \quad \forall n \in \{0, 1, \dots, N_h - 1\}$$

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#### Euler methods

Consider the ODE

$$\frac{d(x(t))}{dt} = -x(t)^4$$

Forward Euler method gives

$$x_{n+1} = x_n - h \cdot x_n^4$$

#### An explicit expression

Backward Euler method gives

$$x_{n+1} = x_n - h \cdot x_{n+1}^4$$

i.e.,  $x_{n+1}$  should be a real root of the polynomial

$$y^4 - \frac{y}{h} - \frac{x_n}{h} = 0$$

#### An implicit expression

Implicit methods enjoy better stability properties than explicit ones.

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## Stability on unbounded intervals

Consider the following

$$x^{'}(t) = \lambda x(t) \quad \forall t \in (0, \infty) \quad \text{and} \quad x(0) = 1$$

It is easy to check that  $x(t) = e^{\lambda t}$  is the exact solution. Note that if  $\lambda < 0$ , then  $\lim_{t\to\infty} x(t) = 0$ .

**Forward Euler** method with  $x_0 = 1$  gives

$$x_{n+1} = x_n(1 + \lambda h) = (1 + \lambda h)^n \quad \forall n \ge 0$$

 $\lim_{n\to\infty} x_n = 0$  only if  $h \in (0,2/|\lambda|)$ 

**Backward Euler** method with  $x_0 = 1$  gives

$$x_{n+1} = x_n/(1-\lambda h) = 1/(1-\lambda h)^n \quad \forall n \ge 0$$

$$\lim_{n\to\infty} x_n = 0$$
 for all  $h > 0$ 

## Systems of ODEs

Consider the following system of first-order ODEs with unknowns  $x_1(t), \dots, x_m(t)$ 

$$x_{1}^{'}(t) = f_{1}(t, x_{1}(t), \dots, x_{m}(t))$$
 $\vdots$ 
 $x_{m}^{'}(t) = f_{m}(t, x_{1}(t), \dots, x_{m}(t))$ 

where  $t \in (t_0, T]$  with initial conditions  $x_{1,0}, \dots x_{m,0}$ .

Let us write the above system of ODEs as

$$\mathbf{x}'(t) = \mathbf{F}(t, \mathbf{x}(t))$$

Now, we can apply any of the methods used to solve the Cauchy problem.

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## Higher order methods

More sophisticated schemes, such as **Runge-Kutta** methods, can achieve better accuracy.

The SciPy module scipy.integrate offers methods to solve ODEs. To know more visit https://docs.scipy.org/doc/scipy/reference/tutorial/integrate.html

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## Thank You