CS5016: Computational Methods and Applications Eigen and Singular Value Decomposition

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Eigenvectors and Eigenvalues

A non-zero vector $\mathbf{v} \in \mathbb{R}^n$ is an Eigenvector of an $n \times n$ matrix \mathbf{A} is it satisfies

$$\mathbf{A}\mathbf{v} = \lambda \mathbf{v}$$

for some $\lambda\in\mathbb{R}$ (eigenvalue). Linear transformation only scale these vectors — a notion of fundamental directions

$$AV = A \begin{bmatrix} \mathbf{v}_1 & \mathbf{v}_2 & \cdots & \mathbf{v}_n \end{bmatrix} = \begin{bmatrix} \mathbf{v}_1 & \mathbf{v}_2 & \cdots & \mathbf{v}_n \end{bmatrix} \begin{bmatrix} \lambda_1 & 0 & \cdots & 0 \\ 0 & \lambda_2 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & \cdots & \lambda_n \end{bmatrix} = VD$$

To learn more, visit:

https://en.wikipedia.org/wiki/Eigenvalues_and_eigenvectors

A very good video on Eigenvalues and Eigenvectors https://www.youtube.com/watch?v=PFDu9oVAE-g

How are the Eigenvalues and Eigenvectors of A^{100} related to those of A?

Power Method

Let us order the Eigen values of **A** as follows

$$|\lambda_1| > |\lambda_2| \ge |\lambda_3| \ge \cdots \ge |\lambda_n|$$

Let us start with some non-zero vector $\mathbf{b}_0 \in \mathbb{R}$ and create a sequence of vectors using the following iteration

$$oldsymbol{b}_{k+1} = rac{oldsymbol{A}oldsymbol{b}_k}{\|oldsymbol{A}oldsymbol{b}_k\|_2}$$

where $\|\cdot\|$ is the L^2 norm. It is also known as the *Euclidean norm*. Then,

$$\mathbf{b}_k \xrightarrow{k \to \infty} \mathbf{v}_1 \quad \text{and} \quad \frac{\mathbf{b}_k^T \mathbf{A} \mathbf{b}_k}{\mathbf{b}_k^T \mathbf{b}_k} \xrightarrow{k \to \infty} \lambda_1$$

where v_1 is the Eigenvector corresponding to Eigenvalue λ_1 .

Why does it work?

$$\boldsymbol{b}_{k} = \frac{\boldsymbol{A}\boldsymbol{b}_{k-1}}{\|\boldsymbol{A}\boldsymbol{b}_{k-1}\|_{2}} = \frac{\boldsymbol{A}^{2}\boldsymbol{b}_{k-2}}{\|\boldsymbol{A}^{2}\boldsymbol{b}_{k-2}\|_{2}} = \dots = \frac{\boldsymbol{z}_{k}}{\|\boldsymbol{z}_{k}\|_{2}}$$
(1)

where $\mathbf{z}_k = \mathbf{A}^k \mathbf{b}_0$. Consequently, we have

$$\frac{\boldsymbol{b}_{k}^{T}\boldsymbol{A}\boldsymbol{b}_{k}}{\boldsymbol{b}_{k}^{T}\boldsymbol{b}_{k}} = \frac{\boldsymbol{z}_{k}^{T}\boldsymbol{A}\boldsymbol{z}_{k}}{\boldsymbol{z}_{k}^{T}\boldsymbol{z}_{k}}$$
(2)

Since Eigen vectors form a basis, we have $\mathbf{b}_0 = \sum_{i=1}^n c_i \mathbf{v}_i$. Thus

$$\mathbf{z}_{k} = \mathbf{A}^{k} \mathbf{b}_{0} = \sum_{i=1}^{n} c_{i} \lambda_{i}^{k} \mathbf{v}_{i} = \lambda_{1}^{k} \left(c_{1} \mathbf{v}_{1} + \sum_{i=2}^{n} c_{i} \left(\frac{\lambda_{i}}{\lambda_{1}} \right)^{k} \mathbf{v}_{i} \right)$$
(3)

Plug in (3) in (2) and (1) and complete the proof.

What would happen if $\boldsymbol{b}_0^T \boldsymbol{v}_1 = 0$?

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Simultaneous orthogonalization¹

Can we simultaneously run power iteration on different initial point? Let

$$extbf{\emph{B}}_0 = egin{bmatrix} extbf{\emph{b}}_0^{(1)} & extbf{\emph{b}}_0^{(2)} & \dots & extbf{\emph{b}}_0^{(n)} \end{bmatrix} \in \mathbb{R}^{n imes n}$$

Then, we can produce a new set of n vectors by performing the operation AB_0 . How will A^kB_0 look like? Will orthogonalizing the vectors AB_0 help?

Finding two matrices $extbf{\emph{Q}}_1$ (orthogonal) and $extbf{\emph{R}}_1$ (upper triangular) such that

$$AB_0 = Q_1R_1$$

Choose $\boldsymbol{B}_0 = \boldsymbol{Q}_0 = \boldsymbol{I}$ and proceed as follows

$$\mathbf{A}\mathbf{Q}_0=\mathbf{Q}_1\mathbf{R}_1$$

$$\pmb{A} \pmb{Q}_1 = \pmb{Q}_2 \pmb{R}_2$$

$$\mathbf{A}\mathbf{Q}_2 = \mathbf{Q}_3\mathbf{R}_3$$

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http://madrury.github.io/jekyll/update/statistics/2017/10/04/

If convergence occurs

We have the steady state equation

$$\mathbf{AQ} = \mathbf{QR} \Rightarrow \mathbf{A} \text{ and } \mathbf{R}$$
 are similar

Similar matrices have same eigenvalues. What about their eigenvectors?

Eigenvalues of triangular matrices lie on their diagonal.

If R is a diagonal matrix, then the columns of Q are the eigenvectors of A.

Not possible to improve convergence and rate of convergence.

The unshifted QR algorithm (John Francis, 1961)

Matrices \hat{Q}_i (orthogonal) and \hat{R}_i (upper triangular)

$$egin{aligned} m{A} &= ilde{m{A}}_1 = ilde{m{Q}}_1 ilde{m{R}}_1 \ & ilde{m{R}}_1 ilde{m{Q}}_1 = ilde{m{A}}_2 = ilde{m{Q}}_2 ilde{m{R}}_2 \ & ilde{m{R}}_2 ilde{m{Q}}_2 = ilde{m{A}}_3 = ilde{m{Q}}_3 ilde{m{R}}_3 \ &dots \ &dots \ & ilde{m{R}}_k ilde{m{Q}}_k = ilde{m{A}}_{k+1} = ilde{m{Q}}_{k+1} ilde{m{R}}_{k+1} \end{aligned}$$

Note that

$$ilde{m{A}}_k = ilde{m{R}}_k ilde{m{Q}}_k = ilde{m{Q}}_k^ op ilde{m{Q}}_k ilde{m{R}}_k ilde{m{Q}}_k = ilde{m{Q}}_k^ op ilde{m{A}}_{k-1} ilde{m{Q}}_k = \prod_{i=1}^k ilde{m{Q}}_{k+1-i}^ op m{A} \prod_{i=1}^k ilde{m{Q}}_i$$

Matrices $\hat{\mathbf{A}}_k$ (for any $k \geq 1$) and \mathbf{A} are similar and share the same eigenvalues.

Does convergence occurs?

Let

$$P_k = \prod_{i=1}^k \tilde{Q}_k$$
 — an orthogonal matrix

Then,

$$\tilde{\mathbf{A}}_k = \mathbf{P}_k^T \mathbf{A} \mathbf{P}_k = \mathbf{P}_k^T \mathbf{V} \mathbf{D} \mathbf{V}^{-1} \mathbf{P}_k = \mathbf{P}_k^T \hat{\mathbf{Q}} \hat{\mathbf{R}} \mathbf{D} \hat{\mathbf{R}}^{-1} \hat{\mathbf{Q}}^{-1} \mathbf{P}_k$$

Since V is invertible, it can be written as the product of an orthogonal matrix \hat{Q} and upper triangular matrix \hat{R}

$$\lim_{k\to\infty} \boldsymbol{P}_k = \hat{\boldsymbol{Q}} \quad \Rightarrow \quad \lim_{k\to\infty} \tilde{\boldsymbol{A}}_k = \hat{\boldsymbol{R}} \boldsymbol{D} \hat{\boldsymbol{R}}^{-1} \quad \text{an upper triangular matrix}$$

Eigenvalues of ${\it A}$ would lie on the diagonal of limiting matrix ${\it \tilde{A}}_{\infty}.$

Does convergence occurs?

Let

$$oldsymbol{U}_k = \prod_{i=1}^k ilde{R}_{k+1-i}$$
 — an upper triangular matrix

Then,

$$\mathbf{A}^k = \mathbf{P}_k \mathbf{U}_k$$
 $\mathbf{A}^k = \mathbf{V} \mathbf{D}^k \mathbf{V}^{-1} = \hat{\mathbf{Q}} \hat{\mathbf{R}} \mathbf{D}^k \mathbf{V}^{-1} = \hat{\mathbf{Q}} \hat{\mathbf{R}} \mathbf{D}^k \mathbf{V}^{-1} \mathbf{D}^{-k} \mathbf{D}^k$

But,

$$[\mathbf{D}^k \mathbf{V}^{-1} \mathbf{D}^{-k}]_{ij} = \left(\frac{\lambda_i}{\lambda_j}\right)^k \mathsf{v}_{ij}^{-1}$$

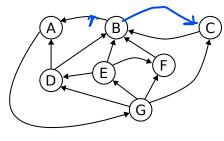
where $v_{ij}^{-1} = [\boldsymbol{V}^{-1}]_{ij}$. If $|\lambda_1| > |\lambda_2| > \cdots > |\lambda_n| > 0$, then $\boldsymbol{D}^k \boldsymbol{V}^{-1} \boldsymbol{D}^{-k}$ tends to an upper triangular matrix. Consequently, $\boldsymbol{P}_k \boldsymbol{U}_k$ tend to the product of an $\tilde{\boldsymbol{Q}}$ (orthogonal) and a triangular matrix.

Performance can be improved by considering the Hessenberg form and using shifts.

PageRank — an application of Eigenvalues

Consider a collection of 7 websites with the following link count matrix

$$\boldsymbol{L} = \begin{bmatrix} 0 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 1 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$



Note that $l_{uv} = 1$ if and only if there is a link from v to u.

How would you rank the above website?

distance from most popular node based on number of incoming nodes

PageRank — an application of Eigenvalues

Let p_u be the rank assigned to node u. Then, we have

$$p_{v} = \sum_{u} l_{uv} \frac{p_{u}}{\sum_{w} l_{uw}} \Rightarrow \boldsymbol{p} = \tilde{\boldsymbol{L}} \boldsymbol{p}$$

For the above example, we have

stochastic matices

$$\tilde{\mathbf{L}} = \begin{bmatrix} 0 & 1/2 & 0 & 1/2 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1/2 & 1/3 & 1 & 0 \\ 0 & 1/2 & 0 & 0 & 0 & 0 & 1/4 \\ 0 & 0 & 0 & 0 & 1/3 & 0 & 1/4 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1/4 \\ 0 & 0 & 0 & 0 & 1/3 & 0 & 1/4 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \quad \boldsymbol{p} = \begin{bmatrix} 0.176 \\ 0.249 \\ 0.191 \\ 0.058 \\ 0.044 \\ 0.058 \\ 0.176 \end{bmatrix}$$

What happens to the rank if the link from B to A is moved to C?

For a deeper understanding, look into the theory of Markov chains.

Singular value decomposition

The singular value decomposition of an $m \times n$ matrix M is²

$$M = U\Sigma V^T$$

U: $m \times m$ orthogonal matrix

 Σ : $m \times n$ rectangular diagonal matrix

 $V: n \times n$ orthogonal matrix

Note that

$$(MM^{T})U = U\Sigma V^{T}V\Sigma^{T}U^{T}U = U(\Sigma\Sigma^{T})$$
$$(M^{T}M)V = V\Sigma^{T}U^{T}U\Sigma V^{T}V = V(\Sigma^{T}\Sigma)$$
$$U^{T}MV = U^{T}U\Sigma V^{T}V = \Sigma$$

Thus

 \boldsymbol{U} and \boldsymbol{V} : collection of eigenvectors of $\boldsymbol{M}\boldsymbol{M}^T$ and $\boldsymbol{M}^T\boldsymbol{M}$ $\boldsymbol{\Sigma}$: square root of non-zero eigenvalues of $\boldsymbol{M}\boldsymbol{M}^T$ or $\boldsymbol{M}^T\boldsymbol{M}$

²https://en.wikipedia.org/wiki/Singular_value_decomposition > > >

Low-rank matrix approximation

Approximating M with another matrix \tilde{M} which has a lower rank.

$$\min_{\tilde{\boldsymbol{M}}} \|\boldsymbol{M} - \tilde{\boldsymbol{M}}\|_{F} \quad \text{such that} \quad rank(\tilde{\boldsymbol{M}}) \leq r$$

where $\|\cdot\|_F = \|\cdot\|_{2,2}$ is the *Frobenius* norm. The solution is

$$\tilde{\mathbf{M}} = \mathbf{U}\tilde{\mathbf{\Sigma}}\mathbf{V}^T$$

where $\tilde{\Sigma}$ contains only the *r*-largest singular values.

The above result is know as the Eckart-Young-Mirsky theorem

Python functions

The NumPy module numpy.linalg offers methods to find Eigen and singular value decomposition. To know more visit https://numpy.org/doc/stable/reference/routines.linalg.html

Thank You