

# Module Guide for CVT Simulator

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# 1 Revision History

Date	Version	Notes
Date 1	1.0	Notes
Date 2	1.1	Notes

## 2 Reference Material

This section records information for easy reference.

### 2.1 Abbreviations and Acronyms

symbol	description
AC	Anticipated Change
DAG	Directed Acyclic Graph
M	Module
MG	Module Guide
OS	Operating System
R	Requirement
SC	Scientific Computing
SRS	Software Requirements Specification
CVT Simulator	Explanation of program name
UC	Unlikely Change
<a href="#">[etc. —SS]</a>	<a href="#">[... —SS]</a>

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### 3 Introduction

Decomposing a system into modules is a commonly accepted approach to developing software. A module is a work assignment for a programmer or programming team (Parnas et al., 1984). We advocate a decomposition based on the principle of information hiding (Parnas, 1972). This principle supports design for change, because the “secrets” that each module hides represent likely future changes. Design for change is valuable in SC, where modifications are frequent, especially during initial development as the solution space is explored.

Our design follows the rules laid out by Parnas et al. (1984), as follows:

- System details that are likely to change independently should be the secrets of separate modules.
- Each data structure is implemented in only one module.
- Any other program that requires information stored in a module’s data structures must obtain it by calling access programs belonging to that module.

After completing the first stage of the design, the Software Requirements Specification (SRS), the Module Guide (MG) is developed (Parnas et al., 1984). The MG specifies the modular structure of the system and is intended to allow both designers and maintainers to easily identify the parts of the software. The potential readers of this document are as follows:

- New project members: This document can be a guide for a new project member to easily understand the overall structure and quickly find the relevant modules they are searching for.
- Maintainers: The hierarchical structure of the module guide improves the maintainers’ understanding when they need to make changes to the system. It is important for a maintainer to update the relevant sections of the document after changes have been made.
- Designers: Once the module guide has been written, it can be used to check for consistency, feasibility, and flexibility. Designers can verify the system in various ways, such as consistency among modules, feasibility of the decomposition, and flexibility of the design.

The rest of the document is organized as follows. Section 4 lists the anticipated and unlikely changes of the software requirements. Section 5 summarizes the module decomposition that was constructed according to the likely changes. Section 6 specifies the connections between the software requirements and the modules. Section 7 gives a detailed description of the modules. Section 8 includes two traceability matrices. One checks the completeness of the design against the requirements provided in the SRS. The other shows the relation between anticipated changes and the modules. Section 9 describes the use relation between modules.

## 4 Anticipated and Unlikely Changes

This section lists possible changes to the system. According to the likeliness of the change, the possible changes are classified into two categories. Anticipated changes are listed in Section 4.1, and unlikely changes are listed in Section 4.2.

### 4.1 Anticipated Changes

Anticipated changes are the source of the information that is to be hidden inside the modules. Ideally, changing one of the anticipated changes will only require changing the one module that hides the associated decision. The approach adapted here is called design for change.

**AC1:** The specific hardware on which the software is running.

**AC2:** The format and structure of the initial input data.

**AC3:** The engine simulator implementation could be updated or replaced as new models or technologies become available.

**AC4:** External forces considered in the simulation could vary, depending on changes in design parameters or environmental considerations.

**AC5:** The CVT simulator implementation is likely change during the validation and verification (VnV) process.

**AC6:** The visualizations used and their implementation could be updated to improve the user experience or to accommodate new features.

**AC7:** Constants used in the software could be updated based on changes to the car's physical design.

**AC8:** Input parameters for the system could change to include more parameters based on new requirements or to improve the accuracy of the simulation.

### 4.2 Unlikely Changes

The module design should be as general as possible. However, a general system is more complex. Sometimes this complexity is not necessary. Fixing some design decisions at the system architecture stage can simplify the software design. If these decision should later need to be changed, then many parts of the design will potentially need to be modified. Hence, it is not intended that these decisions will be changed.

**UC1:** Input/Output devices (Input: File and/or Keyboard, Output: File, Memory, and/or Screen).

**UC2:** Constraint parameters in our model/system will remain fixed and will not change.

**UC3:** The simulation will always be an acceleration run, i.e the car will always start from rest and accelerate.

## 5 Module Hierarchy

This section provides an overview of the module design. Modules are summarized in a hierarchy decomposed by secrets in Table 1. The modules listed below, which are leaves in the hierarchy tree, are the modules that will actually be implemented.

**M1:** Hardware-Hiding Module

**M2:** Engine Simulator Module

**M3:** External Forces Module

**M4:** CVT Simulation Module

**M5:** Input Module

**M6:** ODE Solver Module

**M7:** Main Module

**M8:** Playback Module

**M9:** Visualizer Module

**M10:** Constants Module

**M11:** GUI Module

**M12:** File Output Module

**M13:** Communication Module

**M14:** Controller Module

## 6 Connection Between Requirements and Design

The design of the system is intended to satisfy the requirements developed in the SRS. In this stage, the system is decomposed into modules. The connection between requirements and modules is listed in Table 2.

[The intention of this section is to document decisions that are made “between” the requirements and the design. To satisfy some requirements, design decisions need to be made. Rather than make these decisions implicit, they are explicitly recorded here. For instance, if a program has security requirements, a specific design decision may be made to satisfy those requirements with a password. —SS]



Level 1	Level 2
Hardware-Hiding Module	
	Engine Simulator Module
	External Forces Module
	CVT Simulation Module
Behaviour-Hiding Module	Input Module
	ODE Solver Module
	Main Module
	Playback Module
	Visualizer Module
	Constants Module
	GUI Module
Software Decision Module	File Output Module
	Communication Module
	Controller Module

Table 1: Module Hierarchy

## 7 Module Decomposition

Modules are decomposed according to the principle of “information hiding” proposed by [Parnas et al. \(1984\)](#). The *Secrets* field in a module decomposition is a brief statement of the design decision hidden by the module. The *Services* field specifies *what* the module will do without documenting *how* to do it. For each module, a suggestion for the implementing software is given under the *Implemented By* title. If the entry is *OS*, this means that the module is provided by the operating system or by standard programming language libraries. *CVT Simulator* means the module will be implemented by the CVT Simulator software.

Only the leaf modules in the hierarchy have to be implemented. If a dash (–) is shown, this means that the module is not a leaf and will not have to be implemented.

### 7.1 Hardware Hiding Modules (M1)

**Secrets:** The data structure and algorithm used to implement the virtual hardware.

**Services:** Serves as a virtual hardware used by the rest of the system. This module provides the interface between the hardware and the software. So, the system can use it to display outputs or to accept inputs.

**Implemented By:** OS

## 7.2 Behaviour-Hiding Module

**Secrets:** The contents of the required behaviours.

**Services:** Includes programs that provide externally visible behaviour of the system as specified in the software requirements specification (SRS) documents. This module serves as a communication layer between the hardware-hiding module and the software decision module. The programs in this module will need to change if there are changes in the SRS.

**Implemented By:** –

### 7.2.1 Input Format Module (M5)

**Secrets:** The format and structure of the input data.

**Services:** Converts the input data into the data structure used by the input parameters module.

**Implemented By:** [Your Program Name Here]

**Type of Module:** [Record, Library, Abstract Object, or Abstract Data Type] [Information to include for leaf modules in the decomposition by secrets tree.]

### 7.2.2 Engine Simulator Module (M2)

**Secrets:**

**Services:**

**Implemented By:**

**Type of Module:**

### 7.2.3 External Forces Module (M3)

**Secrets:**

**Services:**

**Implemented By:**

**Type of Module:**

#### 7.2.4 CVT Simulation Module (M4)

Secrets:

Services:

Implemented By:

Type of Module:

#### 7.2.5 ODE Solver Module (M6)

Secrets:

Services:

Implemented By:

Type of Module:

#### 7.2.6 Main Module (M7)

Secrets:

Services:

Implemented By:

Type of Module:

#### 7.2.7 Playback Module (M8)

Secrets:

Services:

Implemented By:

Type of Module:

#### 7.2.8 Visualizer Module (M9)

Secrets:

Services:

Implemented By:

Type of Module:

#### 7.2.9 Constants Module (M10)

Secrets:

Services:

Implemented By:

Type of Module:

### 7.3 Software Decision Module

**Secrets:** The design decision based on mathematical theorems, physical facts, or programming considerations. The secrets of this module are *not* described in the SRS.

**Services:** Includes data structure and algorithms used in the system that do not provide direct interaction with the user.

Implemented By: –

#### 7.3.1 GUI Module (M11)

Secrets:

Services:

Implemented By:

Type of Module:

#### 7.3.2 File Output Module (M12)

Secrets:

Services:

Implemented By:

Type of Module:

#### 7.3.3 Communication Module (M13)

Secrets:

Services:

Implemented By:

Type of Module:

### 7.3.4 Controller Module (M14)

Secrets:

Services:

Implemented By:

Type of Module:

## 8 Traceability Matrix

This section shows two traceability matrices: between the modules and the requirements and between the modules and the anticipated changes.

Req.	Modules
R1	M4, M6, M10
R2	M3, M10
R3	M3, M10
R4	M3, M10
R5	M4, M10
R6	M4, M10
R7	M4, M10
R8	M4, M10
R9	M2, M10
R10	M11, M5
R11	M11, M5
R12	M11, M14, M5
R13	M9, M8
R14	M9, M8
R15	M9, M8
R16	M1
R17	M1

Table 2: Trace Between Requirements and Modules

AC	Modules
AC1	M1
AC2AC8	M5
AC3	M2
AC4	M3
AC5	M4
AC6	M9
AC7	M10

Table 3: Trace Between Anticipated Changes and Modules

## 9 Use Hierarchy Between Modules

In this section, the uses hierarchy between modules is provided. Parnas (1978) said of two programs A and B that A *uses* B if correct execution of B may be necessary for A to complete the task described in its specification. That is, A *uses* B if there exist situations in which the correct functioning of A depends upon the availability of a correct implementation of B. Figure 1 illustrates the use relation between the modules. It can be seen that the graph is a directed acyclic graph (DAG). Each level of the hierarchy offers a testable and usable subset of the system, and modules in the higher level of the hierarchy are essentially simpler because they use modules from the lower levels.

[The uses relation is not a data flow diagram. In the code there will often be an import statement in module A when it directly uses module B. Module B provides the services that module A needs. The code for module A needs to be able to see these services (hence the import statement). Since the uses relation is transitive, there is a use relation without an import, but the arrows in the diagram typically correspond to the presence of import statement. —SS]

[If module A uses module B, the arrow is directed from A to B. —SS]

Figure 1: Use hierarchy among modules

## 10 User Interfaces

[Design of user interface for software and hardware. Attach an appendix if needed. Drawings, Sketches, Figma —SS]

## 11 Design of Communication Protocols

[If appropriate —SS]

## 12 Timeline

[Schedule of tasks and who is responsible —SS]

[You can point to GitHub if this information is included there —SS]

## References

David L. Parnas. On the criteria to be used in decomposing systems into modules. *Comm. ACM*, 15(2):1053–1058, December 1972.

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D.L. Parnas, P.C. Clement, and D. M. Weiss. The modular structure of complex systems. In *International Conference on Software Engineering*, pages 408–419, 1984.