

System Verification and Validation Plan for CVT Simulator

Team #17, Baja Dynamics

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Revision History

Date		Version	Notes
October 11th, 2024	0		First version of VnV extra report
April 1st, 2025	1		Added real-world data into VnV extra

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1 Symbols, Abbreviations, and Acronyms

acronym	definition
CVT	Continuous Variable Transmission
GPS	Global Positioning System
IMU	Inertial Measurement Unit
VnV	Verification and Validation

Table 1: Verification and Validation Acronyms

2 General Information

2.1 Summary

This document will go into detail on the real-world data validation performed for the CVT Simulator. As per Dr. Smith's instructions, it will be completed prior to the course's end. This document currently serves as a placeholder for the final VnV extra report.

3 Functional Tests Evaluation

3.1 Simulation Model

3.1.1 Position

- Car go fast... still! Explained by poor modelling of air resistance and other resistive forces such as rolling resistance, frictions, etc - At the end you can see error decreases a bit. Perhaps the final force of air resistance was estimated too high, but the other forces were estimated too low, giving a slightly different final value, so final speed was too high. - Also note the poor tests mentioned later about no max velocity

Car position over time

3.1.2 Velocity

- Car go fast, shocker! Ignored many resistive forces, no slipping so early on its most noticeable.

Car velocity over time

3.1.3 Acceleration

Not available (no data gotten from IMU)

3.1.4 Shift

- We see generally a flat shift in both, which is great! - Both also have a low ratio, although slight differences, they definitely both exist well

- Low ratio is somewhat different in calculations (causes: Wrong geometry, precision in machined parts, assumption of slip) - Through the shift, we see some curve. A subtle change in ramps could cause this, or a poor understanding of the springs in our system. Potential in the real CVT system for spring to bind as it compresses,

bringing unknown forces - Don't see max shift much, this is due to poor data collection tests - Limits on the length of track we have access to mean we don't see our top end of the speeds our vehicle can achieve.

1 and 2 (What is 1?)

4 Trace to Requirements or Modules