# Reflection and Traceability Report on CVT Simulator

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# 1 Changes in Response to Feedback

# 1.1 SRS and Hazard Analysis

The following table corresponds to SRS changes in response to feedback.

Feedback Item	Source	Change Made in Re-	Commit
	of Feed- back	sponse	Refer- ence
D /: 1 D : /		NT 1 1 TO	
Functional Requirements	Peer	No change made, Func-	N/A
do not seem to have mea-	review	tional requirements were	
surable/fit criteria associ-		deemed measurable.	
ated with them Issue #38.			
Acknowledging possible	Peer	Added floating point ac-	b737c9d
floating point errors and	review	curacy consideration to	
specifying a tollerance		NFR1.	
range for error would be			
beneficial Issue #39.			
Adding why specifc sec-	Peer	No change made, deemed	N/A
tion were NA Issue #40.	review	not relevant.	
Traceability matrix not	Peer	Traceability Matrices	f8dc185
clear Issue #41 and Issue	review	fixed to be more clear and	d5080cc
#64.	and TA	complete.	b7db68a
	feedback	_	
Reusability metric not	Peer feed-	No change made as was	N/A
practical Issue #42	back	deemed practical as previ-	·
- "		ous CVT information was	
		available to us.	
Remove unused SRS fold-	Supervisor	Removed used SRS folders	b6e45c2
ers Issue #55.	feedback	from the repository.	

Add References Issue	TA feed-	Added references to SRS	1632c65
#61.	back	where needed.	
Discuss standards Issue	TA feed-	Added standards section.	91148c8
#62.	back		
Missing numerical ratio-	TA feed-	Added rationale for the	b5b0137
nal as why certain num-	back	numbers selected.	
bers were chosen in re-			
quirements Issue #65.			
Missing phase in plane of	TA feed-	Added phase in plan for	43c023e
requirements Issue #66.	back	requirements.	
Add description of sheaves	Supervisor	Added sheave description	e3953cc
Issue #158.	feedback	to improve user under-	
		standing.	

The following table corresponds to Hazard Analysis changes in response to feedback

Feedback Item	Source	Change Made in Re-	Commit
	of Feed-	sponse	Refer-
	back		ence
The failure mode of "in-	Peer	Addressed why one fail-	430fb6d
sufficient frictional forces"	review	ure mode did not have re-	
has no requirement asso-		quirement due to assump-	
ciated with it according		tions made.	
to the FMEA table Issue			
#48.			
Assumptions listed out-	Peer	No change made as dis-	N/A
side Assumptions section	review	cussing some assumptions	
Issue #49.		in the scope section was	
		relevant.	
Security requirements	Peer	No change made as se-	N/A
missing fit criteria Issue	review	curity requirements were	
#50.		deemed practical and at-	
		tainable.	
Table is missing references	Peer	No change made as this	See
for one failure mode Issue	review	was addressed with Issue	430 fb 6 d
#52.		#48.	
Table is missing failure	Peer	Added a section to address	bce0b02
modes and associated	review	why there were no UI se-	
safety requirements for		curity requirements.	
User Interface Component			
Issue #53.			

Should consider cancella-	Peer	No change as not planned	N/A
tion errors under numeri-	review	for this revision of our	
cal stability Issue #54.		product.	
Add traceability to se-	TA feed-	Added traceability to	430fb6d
curity requirements in	back	FMEA table for Security	
FMEA Issue #212.		Requirements.	

# 1.2 Design and Design Documentation

The following table corresponds to the changes to the Module  $\operatorname{Guide}(\operatorname{MG})$  and MIS documents.

Feedback Item	Source	Change Made in Re-	Commit
	of Feed-	sponse	Refer-
	back		ence
MG - Section 6 not val-	Peer	No change made as section	N/A
ueable to the reader Issue	review	6 was deemed valueable.	
#100.			
MG - Link back to SRS to	Peer	Link to SRS was provided.	c947278
reduce duplicate informa-	review		
tion and add traceability			
Issue #101.			
MG - Anticipated changes	Peer	No change made as the	N/A
could be more clear Issue	review	anticipated change's sec-	
#103.		tion was deemed strait for-	
		ward.	
MG - Should the GUI	Peer	No change made as not	N/A
module not make use	review	applicable.	
of initialize module Issue			
#104.			
MG - Missing Add time-	TA feed-	Added details of prior-	a3867bb
line and detail about pri-	back	ity of modules and break-	
ority of modules being im-		down of timeline.	
plemented Issue #222.			
MIS - Some exceptions	Peer	Blank exceptions were re-	5c48147
were left blank. Issue	review	moved.	
#102.			

The following table corresponds to the changes made in the design of the CVT Simulator's design.

Feedback Item	Source	Change Made in Re-	Commit
	of Feed-	sponse	Refer-
	back		ence
Add units to the user in-	Supervisor	Units were added beside	54bafd $2$
puts to improve user un-	feedback	inputs.	
derstanding. Issue #153.			
Add ability to upload dxf	Supervisor	No changes as did not	N/A
files for ramp geometry.	feedback	have time to implement.	
Issue #153.			
Check for users enter-	Supervisor	Users are not allowed to	54bafd2
ing negative inputs Issue	feedback	enter negative numbers.	
#154.			
Provide default values	Supervisor	Users are given default	54bafd2
in the input fields Issue	feedback	values allowing them to	
#156.		quickly tune CVT.	
Provide user with load-	Supervisor	Added a loading bar to	f9c304
ing information to im-	feedback	provide the user loading	
prove user feedback Issue		progress.	
#204			

# 1.3 VnV Plan and Report

The following table corresponds to changes regarding the VnV Plan.

Feedback Item	Source	Change Made in Re-	Commit
	of Feed-	sponse	Refer-
	back		ence
Confusion with Validation	Peer	No change made, as one of	N/A
report extra Issue #76.	review	our extras is a Validation	
		report.	
Repetitive information	Peer	No change as was deemed	N/A
that can be listed in your	review	not repetitive.	
development plan Issue			
#77.			
Opportunity for more au-	Peer	No change as not planed	N/A
tomated tests Issue #78.	review	for this revision of the	
		product.	
More granular items in	Peer	No change as not planed	N/A
the SRS verification plan	review	for this revision of the	
checklist Issue #85.		product.	
The checklist format was	Peer	Checklist format was fixed	13e3596
not consistent. Issue #86.	review	so that the format of each	
		checklist was consistent.	

Traceability labels could	Peer	No change made, as test	N/A
be shorter Issue #88.	review	labels were deemed appro-	
		priate.	
Add traceability to tests	TA feed-	Traceability added to the	c50551f
in the tables Issue #214.	back	table.	
Link usabil-	TA feed-	Added link to usabil-	ff2bb8c
ity/understandability	back	ity/understandability sur-	and
in the tests and add		vey and added verifiability	b26ab16.
checklist where applicable		checklist.	
Issue #215.			

The following table corresponds to changes regarding the VnV Report.

Feedback Item	Source	Change Made in Re-	Commit
	of Feed-	sponse	Refer-
	back		ence
Consolidating all your	Peer	No change made, as sym-	N/A
symbols, abbreviations	review	bols are referenced in SRS	
and acronyms into one		already.	
document Issue #201.			
Adding expected result	Peer	No change made, as not	N/A
clarity explaining the re-	review	enough time to imple-	
sults of your testing, Issue		ment.	
#202.			

# 2 Challenge Level and Extras

#### 2.1 Challenge Level

The challenge level of this project is General.

#### 2.2 Extras

#### 2.2.1 Requirements Validation Report

Since our capstone is a simulation of a real-world system there is extra validation that has be done in addition to the VnV Report that was completed earlier this year. In the Requirements Validation Report we will analyze the simulation results vs actual data that was collected from the car using various data analysis techniques.

#### 2.2.2 Usability Report

Users were given the application along with a usability survey that was created with the intention of getting the users to interact with all the core features. We

will review the feedback collected from the users and organize the result into a Usability Report to analyze further.

# 3 Design Iteration (LO11 (PrototypeIterate))

From the initial prototype demo in November and the rev 0 demo in January our project has changed a lot. To more accurately capture the iterations that occurred in our project we will have to split this up into front end and back end.

#### 3.1 Front End

The style and flow of the front end of our capstone remained the same throughout development. We decided to stick to the 3-page system and have users progress through them linearly. The areas that had lots of developmental iterations was the inputs page and results page, these both changed many times due to feedback received from stakeholders and team design decisions. These two pages each had there own specific question that impacted our design choices, on the input page it was "what should the user be able to do" and the results page was "what should the user be able to see".

The input page is where all of our input parameters to the system are stored and the user has the freedom to change any of these parameters to whatever they want. As well the user can upload a set of pre made parameters if they have them saved from an earlier run. Some key design iterations that occurred on this page included:

- Figma Redesign: The team decided a new design was needed after some feedback was received from test users about it being messy and unorganized.
- Drop down options for ramps: After discussing with our stakeholders on the Baja team about how best to handle the ramp inputs for the project it was concluded that instead of a completely free ramp designing option we will instead give them a list of ramps to chose from. The reasoning behind this decision was that a user will never able to input a ramp from scratch on the spot as the ramp design require a mathematical process to be created.
- Saving/Uploading parameters: During our rev 0 demo Dr Smith had some feedback about the user being able to save and upload parameters. We decided to implement that as apart of rev 1 as it allows users to essentially "keep there place" and pick up where they left off from last time.

The results page is where the user gets to view the simulation results and also where they can export parameters, graphs and data. This page is based around a playback component where the user can stop and start the simulation. Some key design iterations that occurred on this page included:

- Adding the seekbar: After presenting our rev 0 version of the project the team identified a missing aspect of our "playback" system was having a seek bar. It was put on the list of important features to add for the rev 1 demo as it ties together the whole idea of having playback control over the simulation, without it seemed we were just starting and stopping something with no identifiers of where we were in the simulation.
- Displaying graphs: After discussing the rev 0 demonstration of the project with our stakeholders on the Baja team and discussing what the most important information is from a run on the simulation. It was determined that instead of just having the option to export the data and analyze it elsewhere we should let them view important graphs while still on the application. The idea is to remove the wasted time of taking the data and creating the same graphs manually elsewhere. Therefore, for rev 1 we added the option to view graphs on the results page and it was an important part of our live demonstration.
- Downloading parameters: As mentioned earlier in the inputs page section Dr Smith provided us with the feedback of being able to download parameters. Originally, we had the download parameters option on the inputs page but after some usability testing it was determined that didn't make sense to the user. Therefore, we moved it to the results page because the feedback was that you wouldn't know if you wanted to download that set of parameters until you saw the results of the simulation.
- Changing CVT material: : In our rev 0 demo the CVT object we have on the results page was the default material in unity and it did not look good. After doing some UI review the team decided that we needed to dig more into unity to figure out how to change this material because originally we were not able to change it. It was then changed to the color it is now which fits much better with the rest of the application.

#### 3.2 Back End

The backend saw several important design iterations driven by the need for more accurate results that better matched real data and improved overall code clarity. Some key design iterations that occurred on the backend include:

• **Updated Engine Dynamics**: Previously, the engine's angular velocity was simulated as a separate system with its own inertia, causing it to accelerate on its own due to missing forces. Recognizing discrepancies

with real-world behavior and the benefits of the no-slip assumption, we unified the engine and car into one system—effectively connected like a timing belt rather than a rubber one—to improve accuracy.

- Improved Ramp Representation: Initially, the math for the circular portion of the ramp was faulty, leading to incorrect simulation outputs when compared with real data. We rewrote the equations and their derivatives to yield a far more accurate ramp representation which resulted in our results aligning much more closely with real data.
- Modular Graphing System: We separated out the graphing functionality to make it more modular. This change was driven by the decision to add a graphing feature on the front end for real-time data visualization. Now, the graphing module simply reads the output file and leverages established math modules, which simplifies the frontend code and enhances maintainability.
- Added Progress Printing: Given that the simulation frequently takes a while to run, progress printing was implemented to provide real-time feedback. This not only aids developers during debugging but also gives the frontend user clear indicators of how far along the simulation is, improving the overall user experience.
- Decoupled FE output conversions: Conversion calculations for output data have been moved from the frontend to the backend. This decoupling was done to improve the readability and maintainability of the frontend code, ensuring that the frontend focuses solely on user interaction while the backend handles all computational tasks.
- Revisited and verified Math: Various mathematical computations were re-evaluated because earlier inaccuracies resulted in outcomes that did not align with real data. This thorough review helped us identify and correct errors, leading to more reliable simulation results.
- Incorperated frictional forces: Frictional forces, once thought to have minimal impact, were added to introduce necessary dampening. Without these forces, the system exhibited oscillations that deviated from observed physical behavior, so their inclusion ensures that the simulation more accurately reflects real-world dynamics.

# 4 Design Decisions (LO12)

#### 4.1 Limitations

The key limitation in this project was our understanding of the CVT system and how it functions. Even now with our simulation successfully producing results that accurately depict how the system should be functioning our key limitation is still our lack of knowledge of the CVT system. Essentially the

CVT system is a black box and there is so much math and physics that goes into it that fully understanding how each aspect works and how it impacts the overall performance is really challenging. Over the course of this capstone we have learned so much about the system and the "whys" of certain tuning parameters impact performance in a certain way. However, there is still so much more to learn about the system and that is why it is our biggest limitation. Basically, as our project has progressed, we gained more and more knowledge about how the CVT functions and as a result the simulation became more accurate. We have been reducing the limitation over time, but it remains the biggest obstacle to achieving a "perfect" simulation. So, when talking about limitations I would label this as the most important/significant one when it comes to our capstone.

#### 4.2 Assumptions

We made a lot of simplifying assumptions when doing this project to ensure we could capture the mathematics behind the CVT system. The two assumptions that affected our final design the most are:

- No Belt Slippage: As a result of assuming the belt does not slip the system overpredicts torque transfer and grip reliability.
- No friction on noncritical components: This resulted inaccuracies through various resistive/ dampening forces when shifting.

The other assumptions that were made very mode simple in concept, these two are the ones that have the most impacts on the actual results of our CVT simulation results as they fundamentally changed how we designed the backend architecture. However attempting to incorporate these assumptions from the beginning would have made the project significantly more complicated and we don't believe we would have achieved the same success if we had tried that.

# 5 Economic Considerations (LO23)

There is a market for our CVT Simulator, for instance the market would be the hundreds of Baja teams all over North America. Each team uses a CVT in their car and I would guess that they would be interested in having a way to simulate it for the same reasons why our team was interested in it. However, I don't think this project would succeed as a product that we would market and sell to other teams and the reason for that is the math. The math of the simulation is specifically based around how McMaster Bajas CVT is designed, and it was built off all the knowledge we have of how our CVT functions. If you were to give it to another team, they would have to change a bunch of math to make it align with there specific system before it started being of use to them. Therefore, I can see our capstone being more of an open-source project where other teams would have access to the codebase to be able to tailor the project to

there needs. To go about attracting users to this project the approach I would first send it to the Baja SAE discord server which has thousands of members from across North America and let people know about our project. It would for sure get some people interested in looking at it. However, before that we would first have to rewrite the backend to abstract out the specific parts where the math is solely based on our CVT to make it easier for others to change it to there's. That would be a complicated undertaking but would have to been done if this was an actual goal for the project. Therefore, this capstone has the potential future to be an open source project where other Baja teams can come use the software to improve there teams CVT tuning but there would be a large barrier of entry because the domain and technical knowledge needed to interact with the codebase.

# 6 Reflection on Project Management (LO24)

# 6.1 How Does Your Project Management Compare to Your Development Plan

The team meeting plan in the development plan was an in person meeting every Monday (during our tutorial time) and then an online meeting every Friday. As the semester progressed, and we went got busy we stopped following this plan and began meeting on a need be basis.

Our communication plan was followed, and it became one of our strong points as a team, we communicated frequently and about everything. Our discord server has all our PR's, resources, notes and Todo's.

The team member roles were followed closely:

- Grace is the primary note taker at meetings and project manager
- Travis is the issue manager and was the front-end lead
- Kai is the primary reviewer for code and was the backend lead.
- Cam is the product owner and oversees meetings.

For different stretches of the project when we got busy the roles changed a bit but overall, this was the structure we followed.

The workflow plan was followed. For branches main was only updated when deliverables were due, develop was the primary branch we were interacting with and bigger features that took a while were kept on separate branches to be worked on. We added all of the various issues labels and used them throughout the project for better organization. We utilized CI/CD to run our test suites and to lint/check our backend code on each commit.

The technology was as expected:

• Backend: python

• Front-end: Unity/Csharp

• Github

• VSCode

#### 6.2 What Went Well?

#### **Processes:**

- Git hub standards (PR's and reviewing) were all really well done
- Communication was the highlight of our team, utilized our discord server to its fullest extent.
- Issue creation before development cycles, we issues out all the tickets needed for each cycle making it very easy to pick up work

#### Technologies:

- Python was a great choice for backend
- Testing, linting, formatting tools all are really easy to use in python

#### 6.3 What Went Wrong?

#### **Processes:**

- Issue tracking during development was difficult, frequently had to go back and back update and link issues to PR's.
- Making issues when new issues/bugs came up, we defaulted to just fixing them as fast as possible.

#### Technologies:

- Using Unity for the front end was probably not a good choice in hindsight, the learning curve to use it effectively was much higher than we expected. Probably would have been better to make it a web application so that we would have been more familiar with the languages.
- Testing was difficult in unity because of the nature of our modules and how Unity works.

#### 6.4 What Would you Do Differently Next Time?

- Do a lot more research into technologies before starting the project so we are sure we are using the right tech for the project.
- Having stricter GitHub regulations, reviewing, issue tracking, branch naming, etc.
- - Not having lapses in development due to getting busy with other courses, because we found that it really derails the project development.

### 7 Reflection on Capstone

#### 7.1 Which Courses Were Relevant

Courses that were relevant to this capstone project include:

- SFWRENG 4X03 Scientific computation
- SFWRENG 3A04 Software Development
- ENG 3PX3, 2PX3, 1P13
- Calc 1, Calc 2
- Physics 1D03 and 1E03
- SFWRENG 3XB3

#### 7.2 Knowledge/Skills Outside of Courses

Knowledge that had to be acquired outside of courses include:

- Unity and Csharp, we had to learn how to use Unity and Csharp to build the front end of our project.
- GitHub, we had to learn how to use GitHub effectively and how to use the issue tracking system as well as properly using CI/CD
- Python best practises, we were familiar with python but we had to learn how to use it in a more professional way.
- Physics and math of the CVT, we had to learn how a CVT works and how to simulate it.