Transitions between patterned states in vegetation models for semiarid ecosystems

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A feature common to many models of vegetation pattern formation in semiarid ecosystems is a sequence of qualitatively different patterned states, "gaps \rightarrow labyrinth \rightarrow spots," that occurs as a parameter representing precipitation decreases. We explore the robustness of this "standard" sequence in the generic setting of a bifurcation problem on a hexagonal lattice, as well as in a particular reaction-diffusion model for vegetation pattern formation. Specifically, we consider a degeneracy of the bifurcation equations that creates a small bubble in parameter space in which stable small-amplitude patterned states may exist near two Turing bifurcations. Pattern transitions between these bifurcation points can then be analyzed in a weakly nonlinear framework. We find that a number of transition scenarios besides the standard sequence are generically possible, which calls into question the reliability of any particular pattern or sequence as a precursor to vegetation collapse. Additionally, we find that clues to the robustness of the standard sequence lie in the nonlinear details of a particular model.

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I. INTRODUCTION

Regular patterns in vegetation are among the most visually captivating and intriguing features of aerial images. These patterns appear ubiquitously in semiarid ecosystems, where water is a limiting resource for vegetation growth. Examples include the regular stripe patterns that form on gradual slopes and the spot, gap, and labyrinth patterns that form on flat terrain [1] (see Fig. 1). Flat terrain patterns are observed to be long-lived steady states and are thought to be self-organized phenomena that result from a symmetry-breaking instability in the underlying ecosystem dynamics [2–5]. This view has informed efforts over the last two decades to model vegetation pattern formation mathematically.

A number of models have been proposed to explain vegetation patterns in semiarid ecosystems (see [1] for a review of work done prior to 2009). In particular, many deterministic partial differential equation (PDE) systems model vegetation patterns as self-organized phenomena that emerge due to positive feedbacks at short spatial ranges and competitive effects at long ranges [2,4–7]. Short-range feedbacks are due, in part, to nutrient and water related facilitation, while long-range effects result from competition for limited resources [8]. Typically, nonlinear terms in these models capture the local interactions between water and vegetation, while advective and diffusive terms describe spatial transport. Patterns emerge in many of these systems at a finite critical wavelength through a Turing instability [9]. In this paper, we focus on PDE models that exhibit this mechanism for pattern formation.

As the mean precipitation level of a system slowly diminishes, patterns may appear in vegetated ecosystems and then undergo a sequence of transitions between qualitatively different states before collapsing to a sparsely vegetated or barren state. Since a number of vegetation pattern models [5–7,10] feature a common "standard" sequence of patterns as precipitation decreases,

gaps
$$\rightarrow$$
 labyrinth \rightarrow spots, (1)

it has been proposed that these characteristic patterns may serve as early indicators of a semiarid ecosystem's imminent shift to desert [11,12]. We will examine this proposition closely, first in the general setting of a degenerate equivariant bifurcation problem, and then in the model by von Hardenberg *et al.* as an example [5].

Previous bifurcation studies by LeJeune *et al.* [6], Dijkstra [13], and Kealey and Wollkind [14] have analyzed two-dimensional (2D) patterned states in vegetation models. One common approach likens spot, gap, and stripe patterns observed in nature to idealized patterns on a 2D hexagonal lattice. In particular, LeJeune *et al.* [6] introduced a simple model featuring a patterned state between two Turing bifurcations. A bifurcation problem on a 2D hexagonal lattice was formulated and the coefficients of the amplitude evolution equations were computed in closed form. Considering a parameter set for which transitions between patterned states occurred entirely at small amplitude, an analog of the sequence (1) was observed.

Here, we introduce a framework for generic PDE systems in which pattern transitions between two Turing bifurcations can be analyzed at small amplitude. We formulate a finitedimensional bifurcation problem on a 2D hexagonal lattice in the vicinity of a degenerate Turing bifurcation. This degeneracy is characterized by the growth rate critical Fourier mode perturbation to a spatially uniform state that varies with the control parameter as depicted in Fig. 2. One can bring this degeneracy about by tuning a system so that two Turing bifurcations collapse to a single point in parameter space. In addition, we enforce a degeneracy that captures stable solutions to the amplitude equations. We then unfold these degeneracies so that two Turing bifurcations emerge at close proximity in parameter space and patterned states can be analyzed at small amplitude. By exploring the space of stable patterned solutions under this unfolding, we identify scenarios for the transition between small-amplitude patterned states that may occur as a control parameter varies monotonically. We apply this framework to the model by von Hardenberg et al. [5], treating precipitation as a control parameter and performing weakly nonlinear analyses and numerical simulations near a degenerate Turing point.



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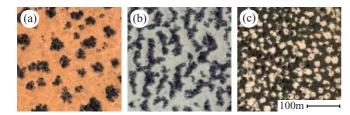


FIG. 1. (Color online) Aerial images of flat terrain vegetation patterns. (a) Spot patterns in Sudan (+11.582 465, +27.913 875), (b) tiger bush labyrinth patterns in Niger (+13.076 354, +2.202 780), and (c) gap patterns in Senegal (+15.206 133, -14.894417). Images © Google, DigitalGlobe.

This paper extends the analysis by LeJeune *et al.* [6] to a general framework for PDE systems with patterned states arising from Turing instabilities, which allows us to explore pattern transition scenarios outside of the constraints imposed by a particular model. Using this framework, we find that an analog of sequence (1) is only one of many possible scenarios. Alternative scenarios include transitions that exclude labyrinth patterns altogether, as well as scenarios involving only spot or only gap patterns. The existence of these alternatives calls into question the utility of sequence (1) as a leading indicator of transition to desert, as any of these other sequences may arise depending on system details.

Additionally, this framework offers a method for identifying which characteristics of particular models are robust, and which are specific to model parameters. By computing amplitude equation coefficients as functions of the model parameters, one can make general statements about the restrictions a model imposes on pattern transitions that occur as a control parameter varies. In the case of the von Hardenberg et al. model, the amplitude equation coefficients reveal that no small-amplitude solutions are stable near Turing points for the parameter set considered by the authors of [5,15], but that a small-amplitude analog of (1) occurs for other distinguished parameter sets. Interestingly, we find that for other parameter sets this model can also exhibit a scenario involving only spot patterns, but that this behavior appears restricted to a small interval of the parameter we vary. Overall, our analysis offers some evidence that sequence (1) is relatively robust in the model by von Hardenberg et al. [5].

This paper is structured as follows. Section II reviews the model by von Hardenberg *et al.* [5] to motivate our analysis. Section III summarizes the formulation of a bifurcation

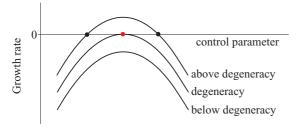


FIG. 2. (Color online) Growth rate of the critical Fourier mode perturbing a spatially uniform equilibrium, plotted as a function of the control parameter. The points denote Turing bifurcations.

problem on a hexagonal lattice and presents the degeneracies that form the basis of our analysis. Section IV explores the parameter space of our perturbed degenerate bifurcation problem to identify transition scenarios in the interesting cases where solutions are stable at small amplitude. Section V returns to the model by von Hardenberg *et al.* [5] to identify pattern transitions near Turing bifurcation points. The results of numerical simulations are also presented. Section VI then concludes with a discussion of our results in the context of the current and future work.

II. MOTIVATING EXAMPLE

To motivate the framework for our subsequent analysis, we briefly review the model by von Hardenberg *et al.* [5] as an example. A detailed description of model terms, scaling, and behavior is given in [15]. In nondimensional form, the model is

$$n_t = f(n, w) + \nabla^2 n, \quad w_t = g(n, w) + \delta \nabla^2 (w - \beta n),$$
 (2) with

$$f(n,w) = \left(\frac{\gamma w}{1+\sigma w} - v\right) n - n^2,$$

$$g(n,w) = p - (1-\rho n)w - w^2 n.$$
(3)

The variable n(x,y,t) represents vegetation density and w(x,y,t) represents ground water density. The nonlinear functions (3) capture the effects of facilitation and competition. Spatial terms model the diffusive spread of vegetation and the transport of water, with cross-diffusion accounting for suction by plant roots in the latter. A parameter representing precipitation, p, imposes resource scarcity. Additionally, γ , σ , ν , ρ , and β are $\mathcal{O}(1)$ positive parameters and δ , which characterizes the diffusivity of water relative to that of vegetation, is usually taken to be a large, positive parameter. One set of default parameter values examined by the authors of [5,15] is given in the caption of Fig. 3.

The spatially uniform equilibria (n^*, w^*) of (2) solve $f(n^*, w^*) = g(n^*, w^*) = 0$. One such equilibrium, corresponding to a nonvegetated "desert" state, is given by $(n^*, w^*) = (0, p)$. The desert state is linearly stable for p < p p_0 , and undergoes a transcritical bifurcation at $p = p_0$ to a uniform "vegetated" equilibrium, for which $n^* > 0$. The bifurcation diagram depicting these spatially uniform states and their stability as a function of p is plotted in Fig. 3. Turing bifurcations on the uniform vegetated equilibrium produce patterned states at the points $p = p_1, p_2$. One can determine these points by linearizing (2) about the uniform vegetated equilibrium and examining the growth rate of Fourier mode perturbations $(n - n^*), (w - w^*) \sim e^{iqx}$, for arbitrary perturbing wave number q. From this, one obtains a stability boundary for the spatially uniform state in the p-qplane, which in this case forms a closed bubble that is plotted in Fig. 4. The Turing points p_1 and p_2 are the left and right endpoints of this stability bubble, and they are each associated with a preferred critical wave number $q_1, q_2 > 0$.

Numerical simulations of (2) yield asymptotic states that follow sequence (1) for decreasing values of p (see Fig. 3). It is natural to liken these solutions to regular patterns on

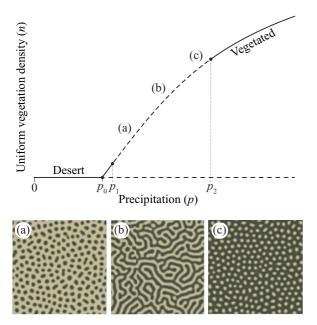


FIG. 3. (Color online) Bifurcation diagram depicting the spatially uniform states of (2) with numerical solutions, using the default parameter set $\gamma = \sigma = 1.6$, $\nu = 0.2$, $\rho = 1.5$, $\beta = 3$, and $\delta = 100$ [5,15]. The desert state loses stability to a vegetated state at $p = p_0 \approx 0.157$. The vegetated equilibrium is unstable to perturbations $n, w \sim e^{iqx}$ in the dashed region $p_1 , where <math>p_1 \approx 0.169$ and $p_2 \approx 0.413$ are the Turing points. Numerical simulations use precipitation values (a) p = 0.20, (b) p = 0.30, and (c) p = 0.40, with higher vegetation density plotted in darker shading.

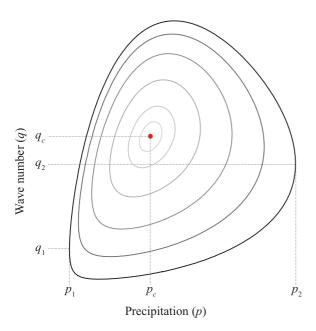


FIG. 4. (Color online) Linear stability boundary of uniform vegetated states of (2) plotted in the p-q plane, where q is the perturbing wave number. The boundary forms a closed bubble whose left and right endpoints are the Turing points p_1 and p_2 , which have corresponding critical wave numbers q_1 and q_2 . As the diffusion coefficient δ is decreased, the stability bubble collapses to a degenerate Turing point, (p_c, q_c) .

a 2D hexagonal lattice [6,14]. A uniform vegetated state that develops dry gaps resembles a "down-hexagons" pattern (H^-) , a labyrinthine intermediate state resembles a distorted stripes pattern (S), and a state of isolated vegetation spots resembles "up-hexagons" (H^+) . Some aspects of pattern existence and stability can be assessed at small amplitude in the weakly nonlinear regime surrounding a Turing bifurcation point, which we explore further for this model in Sec. V.

III. FORMULATING THE BIFURCATION PROBLEM

Near a Turing point ($p_{\rm crit}$, $q_{\rm crit}$), the behavior of a solution to a pattern-forming system is characterized by the modes of a Fourier expansion corresponding to wave number $q_{\rm crit}$. Some aspects of pattern formation can be analyzed through the time-varying amplitudes of these critical modes. The form of the amplitude equations for Fourier modes on a 2D hexagonal lattice can be derived through a standard calculation, described, for instance, in [16–18]. Here, we summarize the key points and results of this derivation, and then formulate the degeneracies that allow us to analyze the transitions between patterned states at small amplitude.

We consider the evolution of critical Fourier modes on a hexagonal lattice perturbing the uniform state

$$z_1 e^{i\mathbf{q}_1 \cdot \mathbf{x}} + z_2 e^{i\mathbf{q}_2 \cdot \mathbf{x}} + z_3 e^{i\mathbf{q}_3 \cdot \mathbf{x}} + \text{c.c.} + \cdots$$
 (4)

The wave vectors $\mathbf{q_1}$, $\mathbf{q_2}$, and $\mathbf{q_3}$ are chosen such that

$$\mathbf{q_1} = q_{\text{crit}}(1,0), \quad \mathbf{q_2} = q_{\text{crit}}(-1/2,\sqrt{3}/2), \quad \mathbf{q_3} = -(\mathbf{q_1} + \mathbf{q_2}).$$
(5)

These vectors lie on the critical circle $|\mathbf{q}| = q_{\text{crit}}$ and z_1 , z_2 , and z_3 (as well as their complex conjugates) are the complex amplitudes of the corresponding critical modes. Near p_{crit} , all other complex Fourier modes associated with the hexagonal lattice are linearly damped.

The form of the equations describing the evolution of the critical mode amplitudes near a Turing point can be determined using an equivariant bifurcation theory approach [16]. To cubic order, these equations are

$$\dot{z}_1 = \mu z_1 + a \bar{z}_2 \bar{z}_3 - (b|z_1|^2 + c(|z_2|^2 + |z_3|^2)) z_1,
\dot{z}_2 = \mu z_2 + a \bar{z}_1 \bar{z}_3 - (b|z_2|^2 + c(|z_1|^2 + |z_3|^2)) z_2,
\dot{z}_3 = \mu z_3 + a \bar{z}_1 \bar{z}_2 - (b|z_3|^2 + c(|z_1|^2 + |z_2|^2)) z_3.$$
(6)

The coefficients μ , a, b, and c are real-valued and are determined by the specific terms and parameter values of a system in a neighborhood of a Turing point. These equations describe the branching and relative linear stability of stripes and hexagons solutions. Specifically, the relative stability of a solution to lattice perturbations is governed by the eigenvalues of the linearization of (6) about that solution. The solutions and their eigenvalues are listed in Table I. From these eigenvalues, one may determine the conditions for the stability of a solution. For example, a necessary condition for the stability of stripes is b > 0, which ensures that the eigenvalue $-2bx_s^2$ is negative. Eigenvalues are often repeated (indicated by $\times 2$ in Table I) due to the spatial symmetries of a solution, and zero eigenvalues reflect the neutral stability of solutions to translation.

TABLE I. Branching equations for solutions on a hexagonal lattice, and eigenvalues of linearizations of (6), together with their multiplicities. $\mathbf{z} = (z_1, z_2, z_3)$ and $x_s, x_h, x_1, x_2 > 0$.

| Solution and branching equation | Eigenvalues |
|--|----------------------------------|
| Stripes (S) | $-2bx_{s}^{2},0$ |
| $\mathbf{z} = (x_s, 0, 0)$ | $(b-c)x_s^2 + ax_s (\times 2)$ |
| $0 = \mu x_s - b x_s^3$ | $(b-c)x_s^2-ax_s$ (×2) |
| Up-hexagons (H^+) | $-3ax_h$, 0 (×2) |
| $\mathbf{z} = (x_h, x_h, x_h)$ | $ax_h - 2(b+2c)x_h^2$ |
| $0 = \mu x_h + ax_h^2 - (b + 2c)x_h^3$ | $-2ax_h - 2(b-c)x_h^2(\times 2)$ |
| Down-hexagons (H^-) | $3ax_h$, 0 (×2) |
| $\mathbf{z} = -(x_h, x_h, x_h)$ | $-ax_h - 2(b+2c)x_h^2$ |
| $0 = \mu x_h - ax_h^2 - (b + 2c)x_h^3$ | $2ax_h - 2(b-c)x_h^2 (\times 2)$ |
| Mixed-modes (MM) | Always unstable |
| $\mathbf{z} = (x_1, x_2, x_2)$ | |
| $0 = \mu x_1 + ax_2^2 - (bx_1^2 + 2cx_2^2)x_1$ | |
| $0 = \mu x_2 + ax_1x_2 - (b+c)x_2^3 - cx_1^3$ | |

We now introduce a distinguished control parameter λ . The coefficients in (6) are generally functions of this parameter, i.e., $\mu=\mu(\lambda)$, and so on, which we constrain to vary with λ in the following way. First, we force the bifurcation problem to occur in the vicinity of a degenerate Turing point at $\lambda=0$ (without loss of generality), which corresponds to μ varying quadratically in λ to leading order [i.e., $\mu(\lambda)=\mu''(0)\lambda^2/2+\cdots$, where $\mu''(0)<0$]. Unfolding the degenerate point results in the expansion

$$\mu(\lambda) = \mu_0 + \mu_1 \lambda + \mu_2 \lambda^2 + \cdots, \tag{7}$$

where μ_0 and μ_1 are small parameters and $\mu_2 < 0$. This unfolding corresponds to a small parameter perturbation to a Turing degeneracy, and two Turing points may emerge as real solutions to $\mu(\lambda) = 0$. An illustration of the Turing instability growth rate, which is proportional to μ , is shown near a Turing degeneracy in Fig. 2. Second, if the quadratic coefficient $a \neq 0$, it can be shown that all solutions to (6) bifurcate unstably [16]. Hence, to capture stable solutions of (6), it is standard to consider (6) near a = 0. We therefore unfold a as

$$a(\lambda) = a_0 + a_1 \lambda + \cdots, \tag{8}$$

where a_0 is another small parameter. Last, we do not consider the variation of b or c with λ , which is reasonable if we avoid degeneracies involving those coefficients.

Through a rescaling of time and amplitudes and ignoring higher order terms, we can write unfoldings of the degenerate linear and quadratic coefficients of (6) as

$$\mu(\lambda) = \mu_0 + \mu_1 \lambda - \lambda^2, \quad a(\lambda) = a_0 + \operatorname{sgn}(a_1)\lambda, \quad (9)$$

where μ_0 , μ_1 , and a_0 are small parameters. Equations (6) with coefficients (9) now show transitions between pattern solutions that can occur entirely at small amplitude.

IV. PATTERN TRANSITIONS NEAR TURING DEGENERACY

For fixed values of the coefficients b and c, the eigenvalues in Table I specify regions in the a- μ plane where solutions

TABLE II. Regions of stability for stripes and hexagon solutions to (6) in the a- μ plane for cases (i) 0 < b < c, (ii) -c < b < 0, and (iii) -b/2 < c < b. Regions are bounded by the curves given in (10). H^+ is stable when a > 0, and H^- is stable when a < 0.

| | Case (i) | Case (ii) | Case (iii) |
|----------------------|-------------------|-------------------|-------------|
| Stripes (S) | $\mu > S_1$ | | |
| Hexagons $(H^{+/-})$ | $H_1 < \mu < H_2$ | $H_1 < \mu < H_2$ | $\mu > H_1$ |

to (6) are stable, and the coefficients (9) describe paths through these regions that are parameterized by the control parameter λ . A path through the stability region of a solution corresponds to the existence of a stable solution for an interval of the control parameter. Exiting a region through a stability boundary represents a solution losing stability and points to a transition between patterned states. In the following, we outline our procedure for identifying small-amplitude pattern transition scenarios.

By requiring the nonidentically zero eigenvalues in Table I to be negative, stability regions in the a- μ plane for solutions to (6) divide consideration into three distinct cases: (i) 0 < b < c, (ii) -c < b < 0, and (iii) -b/2 < c < b. Together, these make up all cases in which stable solutions to (6) exist. Notably, case (i) is the only case in which small-amplitude stripes are stable.

Table II lists stability regions for each case, which are bounded by the curves

$$H_1: \mu = -a^2/4(b+2c),$$

 $H_2: \mu = a^2(2b+c)/(b-c)^2,$ (10)
 $S_1: \mu = a^2b/(b-c)^2.$

 H_1 is derived from the existence condition for hexagons, and H_2 and S_1 come from necessary conditions for the stability of hexagons and stripes, respectively. These stability regions are plotted in Fig. 5, and the bounding curves are labeled I–VI and distinguish between the regions of stability on either side of the line a = 0.

Varying the control parameter λ in the coefficients (9) leads to parabolic paths in the a- μ plane. Depending on the sign of a_1 and the small parameters μ_0 , μ_1 , and a_0 , these parabolic paths cut through the regions of pattern stability in Table II. Some example paths through these regions are sketched in Fig. 5. We observe that example path (a) crosses through boundaries I–VI. This means varying λ along this path leads (6) sequentially through the regions of stability for H^- , S, and H^+ solutions. A bifurcation diagram corresponding to this path is sketched in Fig. 6, from which we infer the transition sequence " $H^- \rightarrow S \rightarrow H^+$ " (i.e., "gaps \rightarrow labyrinth \rightarrow spots") occurs as λ varies.

It follows from this example that for each case, each distinct boundary crossing sequence is linked to a pattern transition sequence. Distinct boundary crossings and inferred transitions for all three cases are listed in Table III. "Symmetric" sequences occur where boundaries are crossed on one side of the line a=0 only [e.g., case (i) sequence "I,I"], while "asymmetric" sequences occur where boundaries are crossed on both sides of the μ axis [e.g., case (i) sequence "I,II,III,IV,V,VI"]. Path (a) in Fig. 5 results in an asymmetric

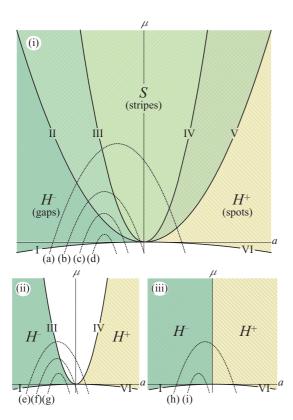


FIG. 5. (Color online) Stability regions in the $a-\mu$ plane for S and $H^{+/-}$ solutions to (6) for cases (i) 0 < b < c, (ii) -c < b < 0, and (iii) -b/2 < c < b, with sample paths (a)–(i) formed by varying λ in (9) (discussed in the text). The boundaries H_1 , H_2 , and S_1 given in (10) are labeled I–VI and distinguish between boundaries on either side of a=0. Cross hatching denotes regions of bistability between S and $H^{+/-}$ solutions. Region colors reflect a vegetation health gradient, where dark green reflects gap vegetation and yellow reflects less healthy spot vegetation.

sequence, while paths (b)–(d) result in symmetric sequences. Only one asymmetric sequence, corresponding to a transition involving both H^+ and H^- solutions, exists for each case.

One type of scenario not explicitly described above occurs when a parabolic path crosses through a region of hexagon stability without crossing the line $\mu = 0$. Since Turing

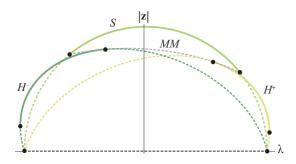


FIG. 6. (Color online) Schematic bifurcation diagram corresponding to path (a) in Fig. 5, taking $sgn(a_1) = 1$. The Euclidean norm of $\mathbf{z} = (z_1, z_2, z_3)$ is plotted, with stable solutions as solid lines and unstable solutions as dashed lines. Bifurcation points are indicated by dots.

TABLE III. Distinct boundary crossing sequences and inferred transition scenarios for cases (i) 0 < b < c, (ii) -c < b < 0, and (iii) -b/2 < c < b, with example paths from Fig. 5 indicated. Dashes in case (ii) indicate that no intermediate state is stable at small amplitude. "Symmetric" sequences occurring for a > 0 (e.g., VI,VI) are omitted.

| | Ex. Sequence | Transition scenario |
|------------|-----------------------|-----------------------------------|
| Case (i) | | |
| | (a) I–VI | $H^- 	o S 	o H^+$ |
| | (b) I,II,III,III,II,I | $H^- 	o S 	o H^-$ |
| | (c) I,II,II,I | H^- (w/ S bistability) |
| | (d) I,I | H^{-} |
| Case (ii) | | |
| | (e) I,III,IV,VI | $H^- ightarrow - ightarrow H^+$ |
| | (f) I,III,III,I | $H^- ightarrow - ightarrow H^-$ |
| | (g) I,I | H^- |
| Case (iii) | | |
| | (h) I,VI | $H^-	o H^+$ |
| | (i) I,I | H^- |

bifurcations occur when $\mu=0$, such a scenario can be interpreted as a small-amplitude hexagon states that occurs without Turing bifurcations. These states coexist with spatially uniform states that are stable to Fourier mode perturbations, and thus may only be accessed through a finite amplitude perturbation. Transition scenarios for such patterned states must necessarily involve only one type of hexagon solution.

This analysis shows that a number of transition scenarios between patterned states, beyond the standard "gaps \rightarrow labyrinth \rightarrow spots," are possible. Many of these scenarios correspond to "symmetric" sequences and therefore only involve one type of hexagon's solution [e.g., case (i) sequence "I,II,III,III,II,I"]. This demonstrates that it is possible for pattern transitions to occur without the appearance of spots, for instance, as in paths (b)–(d) in Fig. 5. The occurrence of spots as precursors to pattern collapse may therefore be sensitive to the specific parameters of a system.

V. PATTERN TRANSITIONS IN THE MODEL BY VON HARDENBERG ET AL.

In this section, we analyze patterned states in the model (2) by von Hardenberg *et al.* [5]. Note that we only consider the dependence of pattern transition scenarios on the diffusion parameter δ as an illustration, but that one could just as well consider the dependence on other parameters. We obtain the coefficients of the amplitude equations (6) following the results of Judd and Silber [19], who derived these coefficients perturbatively for general two-component reaction-diffusion systems with diagonal diffusion. Equation (2) is transformed into this problem by diagonalizing the diffusion matrix.

For the default parameter set $\gamma = \sigma = 1.6$, $\nu = 0.2$, $\rho = 1.5$, $\beta = 3$, and $\delta = 100$, Turing instabilities occur along the spatially uniform vegetated equilibrium at $(p_1,q_1) \approx (0.169,0.106)$ and $(p_2,q_2) \approx (0.414,0.206)$. The coefficients b and c of (6) are negative at both Turing points, which renders unstable small-amplitude stripes and

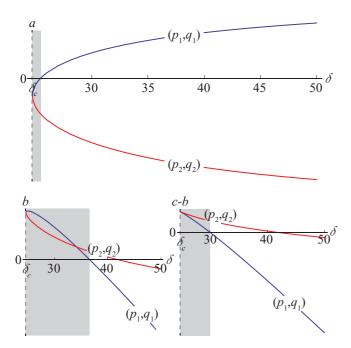


FIG. 7. (Color online) The coefficients a, b and c-b, plotted at Turing points (p_1,q_1) and (p_2,q_2) as functions of the parameter δ (default parameter values used otherwise). Gray-shaded intervals indicate where a < 0, b > 0 and c - b > 0 at both Turing points simultaneously.

hexagons. Weakly nonlinear theory is therefore unable to describe stable patterned solutions to (2) near these points. Numerical simulations, which are shown in Fig. 3, reveal that the "gaps \rightarrow labyrinth \rightarrow spots" sequence occurs at large amplitude as precipitation decreases.

By modifying the value of δ in the default parameter set, we find that (2) is amenable to weakly nonlinear analysis in a neighborhood of $\delta = \delta_c \approx 24.7$ (the two Turing points collapse to a single degenerate point at $\delta = \delta_c$). This is observed through the coefficients b and c of (6). We saw in case (i) of Sec. IV that both small-amplitude stripes and hexagons can be stable when 0 < b < c. Plotting b and c-b evaluated at Turing points (p_1,q_1) and (p_2,q_2) as functions of δ in Fig. 7, we observe that 0 < b < c when $\delta \lesssim 30.0$. Plotting a in a similar way shows that a changes sign between the Turing points when $\delta \gtrsim 25.5$, which permits the asymmetric sequences described in Sec. IV, i.e., sequences that involve both gap and spot patterns. Together, these coefficients indicate that the sequence " $H^- \rightarrow S \rightarrow H^+$ " appears at small amplitude in the interval $\delta \in [25.5, 30.0]$, which parallels what is observed at large amplitude for larger values of δ . A bifurcation diagram depicting this scenario is shown in Fig. 8.

To simulate this sequence numerically, we set $\delta = 27.0$ so that two Turing points emerge at $(p_1,q_1) \approx (0.225,0.214)$ and $(p_2,q_2) \approx (0.292,0.247)$. A numerical solution of (2) at $p \approx p_2$ is evolved using a pseudospectral Runge-Kutta 4 scheme from spatially random initial conditions for n and w drawn uniformly from the interval [0.2,0.4]. After this solution reaches a steady state, the parameter p is decreased in two steps, and the solution is allowed to reach a steady state after each step. These steady states, shown in Fig. 8, closely

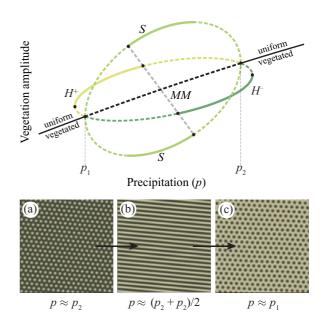


FIG. 8. (Color online) Schematic bifurcation diagram for solutions of (2) with $\delta \in [25.5,30.0]$ and numerical solutions with $\delta = 27.0$ (default parameter values used otherwise). The numerical simulation (a) is evolved to a steady state resembling an H^- solution from spatially noisy initial conditions at $p = 0.292 \approx p_2$. p is then decreased to $0.259 \approx (p_1 + p_2)/2$ and the solution is allowed to settle to the S steady state shown in (b). This procedure is repeated once more at $p = 0.225 \approx p_1$, and the S solution initial condition settles to an H^+ steady state, shown in (c).

resemble H^- , S, and H^+ solutions at $p \approx p_2, (p_1 + p_2)/2$, and $p \approx p_1$, respectively, which is consistent with the picture suggested by the analysis.

Figure 7 also shows that a < 0 at both Turing points when $\delta \in [24.7,25.5]$, resulting in "symmetric" pattern transition sequences that exclude stable H^- (gaps) patterns in this interval. In Fig. 9, we plot a bifurcation diagram of solutions to (2) as functions of p with $\delta = 25.0$, which shows that only H^+ (spot) solutions are stable at small amplitude between the two Turing points. For this value of δ , the two Turing bifurcations occur at $(p_1,q_1) \approx (0.245,0.231)$ at $(p_2,q_2) \approx (0.269,0.243)$. Numerical simulations at $p = p_1, (p_1 + p_2)/2$ and p_2 all yield small amplitude up-hexagon solutions (see Fig. 9). We remark that although this analysis is evidence of an alternative to the standard sequence in the model by von Hardenberg et al., this alternative occurs only in a small interval of δ .

VI. DISCUSSION

To analyze some aspects of the transition between patterned states in PDE vegetation models, we have formulated a bifurcation problem on a 2D hexagonal lattice. Amplitude equations capture dynamics that are dominated by the evolution of critical Fourier mode perturbations to a uniform equilibrium. We enforced degeneracies of the amplitude equation coefficients that enable transitions between patterned states to occur at small amplitude, where they can be investigated analytically. We found that a number of scenarios beyond the standard "gaps \rightarrow labyrinth \rightarrow spots" transition sequence are possible in this generic setting and that the appearance

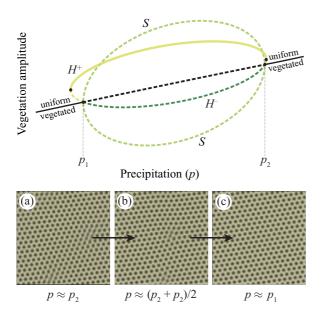


FIG. 9. (Color online) Bifurcation diagram for solutions of (2) and numerical solutions with $\delta=25.0$ (default parameter values used otherwise). The numerical simulation (a) is evolved to a steady state resembling an H^+ solution from spatially noisy initial conditions at $p=0.269\approx p_2$. p is then decreased to $0.257\approx (p_1+p_2)/2$ and the H^+ state remains stable, as shown in (b). This procedure is repeated once more at $p=0.245\approx p_1$, and the H^+ state continues to remain stable, as shown in (c).

of these scenarios is distinguished by the coefficients of the amplitude equations near the degenerate point. Since the bifurcation problem exploits the symmetries present in a number of vegetation pattern models near Turing bifurcation points, one can place these models within the framework we have described. We did this for the model by von Hardenberg et al. [5] and observed the standard sequence as well as a "spots-only" scenario for two near-degenerate parameter sets.

Based on our analysis and observations of patterned states in (2), we speculate that specific assumptions make the standard sequence relatively robust in some PDE models for vegetation pattern formation. This is despite our observation of the "spots-

only" scenario in (2), which we found to occur only for a small interval of the parameter we vary. In Sec. IV, we found that an analog of the standard sequence occurs at small amplitude due in part to the quadratic coefficient of (6) changing sign between the Turing bifurcation points. This weakly nonlinear assessment forms an organizing center for more strongly nonlinear model behavior away from a degeneracy, and we conjecture that the quadratic coefficient changing sign between Turing points serves as a crude signpost for the standard sequence. Our expectation is that if a small-amplitude analog of this sequence is observed near a degeneracy, then the quadratic coefficient will often give a qualitative description of behavior even when no small-amplitude patterned states are stable away from the degeneracy. In this way, our approach suggests a framework for assessing the robustness of the standard sequence under the parameter variations in (2), as well as in other models.

Patterned vegetated states often occur during the process of desertification, and the transition between patterned and desert states is accordingly of great interest. In this paper, we presented a picture of pattern formation and collapse that occurs via two Turing bifurcations, but finite-wavelength Turing instability is not the only mechanism for vegetation collapse observed in models. In a study of the generalized Klausmeier model by van der Stelt et al. [20], a patterned vegetated state collapses directly to desert via long-wavelength, sideband, and Hopf instabilities. Additionally, homoclinic snaking [21,22] has been proposed as a mechanism for the stabilization and motion of localized patterned states that emerge en route to desertification [23]. These approaches, as well as the approach we presented in this paper, can help to form a catalog of scenarios for the transition between vegetated and desert states in semiarid ecosystems, which may provide crucial insight into how semiarid ecosystems will respond to the change in precipitation conditions that will accompany global climate change in the coming decades.

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