

November 1, 2017

Outline

Introduction

Tutorial

Expression graph

Expression operators

New models

Transformer

Summary

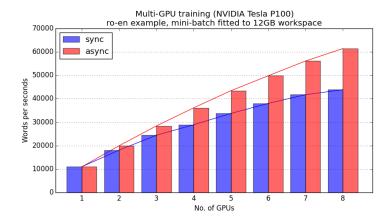
Marian NMT

History:

- ► Rapid development started after MTM 2016
- ► A C++ implementation of a reverse-mode automatic differentiation

Overview

- ► Pure C++ implementation
- ► Up to 15x faster translation
- ► Up to 2x faster training
- ► Multi-GPU training (sync/async) and translation
- Different types of deep and multi-source models



Features

- ► GPU and LSTM cells
- ► Deep and multi-source models: nematus, s2s, transformer, Im, ...
- ► Encoder types: bidirectional, uni-bidirectional, alternating
- Layer normalization
- Moving average of parameters
- Decaying learning rate
- ► Fitting mini-batches
- Residual connections
- ► Tied embeddings
- ► Different attention mechanisms
- ▶ ..

Marian vs. Amun

$amunmt \rightarrow marian-nmt$:

- AmuNMT: amun (CPU and GPU decoding for Nematus models)
- Marian: marian (GPU training), marian-decoder (translation), marian-scorer (rescoring), marian-server (web-socket server)

More information

- ▶ https://marian-nmt.github.io
- ► https://github.com/marian-nmt/marian-dev
- ▶ https:

//groups.google.com/forum/#!forum/marian-nmt

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To follow the slides:

► Download the presentation:

```
https:
```

//marian-nmt.github.io/materials/marian-nov-17.pdf

► Browse the code:

https://github.com/marian-nmt/marian-dev

► See MTM 2017 tutorial:

https://marian-nmt.github.io/examples/mtm2017/code/

Expression Graph

https://github.com/marian-nmt/marian-dev/tree/master/src/examples/iris/iris.cpp

Expression graph

- ► Dynamic graphs (like DyNet, PyTorch)
- ► A reverse-mode automatic differentiation
- ► File: src/graph/expression_graph.h

```
auto graph = New<ExpressionGraph>();
```

Building an expression graph

```
// define the input layer
    auto x = graph->constant({N, NUM_FEATURES},
3
                              init=inits::from_vector(inputData));
4
    // define the hidden layer
5
    auto W1 = graph->param("W1", {NUM_FEATURES, 5}, init=inits::uniform());
6
    auto b1 = graph->param("b1", {1, 5}, init=inits::zeros);
    auto h = tanh(affine(x, W1, b1));
9
    // define the output layer
10
    auto W2 = graph->param("W2", {5, NUM_LABELS}, init=inits::uniform());
11
    auto b2 = graph->param("b2", {1, NUM_LABELS}, init=inits::zeros);
12
    auto o = affine(h, W2. b2):
13
```

Building an expression graph

For training

```
// add the cross entropy
auto y = graph->constant({N}, init=inits::from_vector(outputData));
auto cost = mean(cross_entropy(o, y), axis = 0);

// alternatively
// auto cost = -mean(sum(logsoftmax(o) * y, axis=1), axis=0)
```

For decoding

```
// add the softmax layer
auto pred = logsoftmax(o);
```

Nodes

```
Expr constant(Shape shape, Args...);
Expr param(std::string name, Shape shape, Args...);
Expr ones(Args...);
Expr zeros(Args...);
Expr dropout(float prob, Shape shape);
...
```

Expression operators

- **▶** +, -, *, /
- ▶ sum, mean, sqrt, log, exp, logit
- ▶ relu, tanh, swish
- ▶ dot, transpose, concatenate, reshape, flatten
- ▶ rows, cols, select
- ▶ affine, softmax, cross_entropy
- **>** ...

See file: src/graph/expression_operators.h

Function building a graph

```
1
      Expr build(Ptr<ExpressionGraph> graph,
                 std::vector<float> inputData,
 3
                 std::vector<float> outputData = {},
 4
                 bool train = false) {
 5
        graph->clear();
 6
        // define the input layer
        auto x = graph->constant({N. NUM FEATURES}.
9
                                 init=inits::from_vector(inputData));
10
        // define the hidden layer
11
12
        auto W1 = graph->param("W1", {NUM_FEATURES, 5}, init=inits::uniform());
13
        auto b1 = graph->param("b1", {1, 5}, init=inits::zeros);
14
        auto h = tanh(affine(x, W1, b1));
15
16
        // define the output layer
17
        auto W2 = graph->param("W2", {5, NUM LABELS}, init=inits::uniform());
18
        auto b2 = graph->param("b2", {1, NUM_LABELS}, init=inits::zeros);
19
        auto o = affine(h, W2, b2);
20
21
        if(train) {
22
          auto y = graph->constant({N}, init=inits::from_vector(outputData));
23
          return mean(cross_entropy(o, y), axis = 0);
24
        } else {
25
          return logsoftmax(o);
26
27
```

Training loop

```
2
       auto graph = New < ExpressionGraph > ();
       graph->setDevice(0);
3
4
       graph->reserveWorkspaceMB(128);
5
6
       // choose optimizer and initial learning rate
       auto opt = Optimizer<Adam>(0.005);
8
       for(size_t epoch = 1; epoch <= MAX_EPOCHS; ++epoch) {</pre>
9
         shuffleData(trainX, trainY);
10
11
         // build the classifier
12
         auto cost = build(graph, trainX, trainY, true);
13
14
         // train the network and update weights
15
         graph->forward();
16
         graph->backward();
17
         opt->update(graph);
18
19
         std::cout << "Epoch: " << epoch << " Cost: " << cost->scalar()
20
                    << std::endl:
21
22
23
```

Prediction

```
auto probs = build(graph, testX);
    // debug(probs, "Probs:")
3
4
    // run classifier
     graph->forward();
5
6
    // extract predictions
     std::vector<float> preds(testY.size());
     probs->val()->get(preds);
10
     std::cout << "Accuracy: " << calculateAccuracy(preds, testY)</pre>
11
               << std::endl;
12
```

Complete examples:

- ► Iris: src/examples/iris
- ► MNIST: src/examples/mnist

Expression operators

https://github.com/marian-nmt/marian-dev/tree/master/src/graph/node_operators_unary.h

New activation function

Swish (Ramachandran et al. 2017):

$$f(x) = x \cdot \sigma(x)$$
$$f'(x) = f(x) + \sigma(x)(1 - f(x))$$

Skeleton

```
// src/graph/expression_operators.h
Expr swish(Expr a);

// src/graph/expression_operators.cu
Expr swish(Expr a) {
    return Expression<SwishNodeOp>(a);
}
```

```
// src/graph/node_operators_unary.h
1
    struct SwishNodeOp : public UnaryNodeOp {
      template <typename... Args>
3
      SwishNodeOp(Args... args) : UnaryNodeOp(args...) {}
4
5
      NodeOps forwardOps() { return {/*...*/}; }
6
      NodeOps backwardOps() { return {/*...*/}; }
8
      const std::string type() { return "swish"; }
9
    };
10
```

Forward step

Swish:

$$f(x) = x \cdot \sigma(x)$$

Backward step

Derivative:

$$f'(x) = f(x) + \sigma(x)(1 - f(x))$$

We need:

$$\frac{\partial J}{\partial x} += \frac{\partial J}{\partial f} \cdot f'(x)$$

Alternative way: write a kernel/thrust function

See ReLU or PReLU operators

Sutskever-style model

https://github.com/marian-nmt/marian-dev/tree/tutorial-nov-17/src/models/sutskever.h

MTM2017 tutorial

https://marian-nmt.github.io/examples/mtm2017/code

For lazy people:

```
cd marian-dev
git fetch origin tutorial-nov-17
git checkout tutorial-nov-17
cd build
cmake .. -DCMAKE_BUILD_TYPE=Release
make -j8
```

Encoder

```
// skeleton code for encoder
    class EncoderSutskever : public EncoderBase {
    public:
       EncoderSutskever(Ptr<Options> options) : EncoderBase(options) {}
5
6
      Ptr<EncoderState> build(Ptr<ExpressionGraph> graph,
                                Ptr<data::CorpusBatch> batch) {
8
         return New < EncoderState > (nullptr, nullptr, batch);
       }
10
       void clear() {}
11
    };
12
```

Decoder

```
// skeleton code for decoder
1
     class DecoderSutskever : public DecoderBase {
     public:
       DecoderSutskever(Ptr<Options> options) : DecoderBase(options) {}
4
5
6
       virtual Ptr<DecoderState> startState(
7
           Ptr < Expression Graph > graph,
8
           Ptr<data::CorpusBatch> batch,
           std::vector<Ptr<EncoderState>>& encStates) {
9
10
         rnn::States startStates:
11
12
         return New<DecoderState>(startStates, nullptr, encStates);
       }
13
14
       virtual Ptr < DecoderState > step (Ptr < ExpressionGraph > graph,
15
                                        Ptr<DecoderState> state) {
16
         rnn::States decoderStates:
17
         return New < DecoderState > (decoderStates,
18
                                    nullptr,
19
                                    state->getEncoderStates());
20
       }
21
22
       void clear() {}
23
     };
24
```

Register the encoder and the decoder

```
#include "models/sutskever.h"
    // ...
4
    Ptr<EncoderBase> EncoderFactory::construct() {
5
       if(options_->get<std::string>("type") == "sutskever")
        return New<EncoderSutskever>(options_);
      // ...
9
    Ptr<DecoderBase> DecoderFactory::construct() {
10
       if(options_->get<std::string>("type") == "sutskever")
11
        return New<DecoderSutskever>(options_);
12
      // ...
13
```

Construct the encoder-decoder model

```
Ptr<ModelBase> by_type(std::string type, Ptr<Options> options) {

if(type == "sutskever") {

return models::encoder_decoder()(options)

.push_back(models::encoder()("type", "sutskever"))

.push_back(models::decoder()("type", "sutskever"))

.construct();

}

// ...
```

Encoder::build

Source embeddings

```
// create source embeddings
int dimVoc = opt<std::vector<int>>("dim-vocabs")[batchIndex_];
auto embeddings = embedding(graph)

("prefix", prefix_ + "_Wemb")
("dimVocab", dimVoc)
("dimEmb", opt<int>("dim-emb"))
.construct();
```

More on embeddings(Ptr<ExpressionGraph>)

Encoder::build

Embedding look-up

```
// select embeddings that occur in the batch
Expr batchEmbeddings, batchMask;
std::tie(batchEmbeddings, batchMask)
= EncoderBase::lookup(embeddings, batch, encoderIndex);
```

Encoder::build

Backward encoder RNN

```
// backward RNN for encoding
    float dropoutRnn = inference_ ? 0 : opt<float>("dropout-rnn");
    auto rnnBw = rnn::rnn(graph)
3
                  ("type", "lstm")
4
                  ("prefix", prefix_)
5
                  ("direction", rnn::dir::backward)
6
                  ("dimInput", opt<int>("dim-emb"))
                  ("dimState", opt<int>("dim-rnn"))
8
                  ("dropout", dropoutRnn)
                  ("layer-normalization", opt<bool>("layer-normalization"))
10
                      .push_back(rnn::cell(graph))
11
                      .construct();
12
13
    auto context = rnnBw->transduce(batchEmbeddings, batchMask);
14
```

Decoder::startState

Setting the start state for decoding

```
virtual Ptr<DecoderState> startState(
    Ptr<ExpressionGraph> graph,
    Ptr<data::CorpusBatch> batch,
    std::vector<Ptr<EncoderState>>& encStates) {
    using namespace keywords;

// use first encoded word as start state
    auto start = marian::step(encStates[0]->getContext(), 0, 2);

rnn::States startStates({{start, start}});
    return New<DecoderState>(startStates, nullptr, encStates);
}
```

Shifted embeddings

```
auto embeddings = state->getTargetEmbeddings();
```

```
// forward RNN for decoder
    float dropoutRnn = inference_ ? 0 : opt<float>("dropout-rnn");
    auto rnn = rnn::rnn(graph)
3
                ("type", "lstm")
4
                ("prefix", prefix_)
5
                ("dimInput", opt<int>("dim-emb"))
6
                ("dimState", opt<int>("dim-rnn"))
7
8
                ("dropout", dropoutRnn)
9
                ("layer-normalization", opt<bool>("layer-normalization"))
                .push_back(rnn::cell(graph))
10
                .construct():
11
12
    // apply RNN to embeddings, initialized with encoder context
13
    // mapped into decoder space
14
     auto decoderContext = rnn->transduce(embeddings, state->getStates());
15
16
    // retrieve the last state per layer. They are required during
17
    // translation in order to continue decoding for the next word
18
    rnn::States decoderStates = rnn->lastCellStates():
19
```

Deep output (2-layers)

```
// construct deep output multi-layer network layer-wise
2
    auto layer1 = mlp::dense(graph)
                   ("prefix", prefix_ + "_ff_logit_l1")
3
                   ("dim", opt<int>("dim-emb"))
4
                   ("activation", mlp::act::tanh);
5
    int dimTrgVoc = opt<std::vector<int>>("dim-vocabs").back();
6
     auto layer2 = mlp::dense(graph)
                   ("prefix", prefix_ + "_ff_logit_12")
8
                   ("dim", dimTrgVoc);
9
10
    // assemble layers into MLP and apply to embeddings, decoder context
11
    // and aligned source context
12
     auto logits = mlp::mlp(graph)
13
                   .push_back(layer1)
14
                   .push_back(layer2)
15
                   ->apply(embeddings, decoderContext);
16
```

Return the decoder state

```
// return unnormalized(!) probabilities
return New<DecoderState>(decoderStates,
logits,
state->getEncoderStates());
```

Recompile:

```
1 cd build
2 make -j
3 cd ..
```

Train:

```
./build/marian \
    --type sutskever \
    -t data/corpus.bpe.ro data/corpus.bpe.en \
    -v data/vocab.ro.yml data/vocab.en.yml \
    -m model/model.npz
```

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Transformer

Transformer (Attention is All You Need, Vaswani et al. 2017)

New in Marian:

- ► Transformer model
- ► New dropouts
- ► Google-style learning rate warm-up
- ► Label smoothing

Experiments

Settings:

- ► WMT2017 en-de training data
- ► Problem-set from the tensor2tensor repo by Google: 36,000 common BPE subwords for both languages

Three modifications:

- ► Highway connections instead of skip-connections
- Averaging parameters
- ► Swish function

Results

System	2013	2014	2015	2016
Edinburgh Deep RNN (Micelli Barone et al. 2017)	_	23.4	26.0	31.0
Transformer 12-layers (Ramachandran et al. 2017)	26.1*	27.8*	29.8*	33.3*

^{*} Measured with multi-bleu.perl, rest with mteval-v13a.pl

Results

System	2013	2014	2015	2016
Edinburgh Deep RNN (Micelli Barone et al. 2017)	_	23.4	26.0	31.0
Transformer 12-layers (Ramachandran et al. 2017)	26.1*	27.8*	29.8*	33.3*
Marian Transformer 6-layers (195,000 it.)	25.4*	26.5	29.5	33.2

^{*} Measured with multi-bleu.perl, rest with mteval-v13a.pl

Results

2013	2014	2015	2016
_	23.4	26.0	31.0
26.1*	27.8*	29.8*	33.3*
25.4*	26.5	29.5	33.2
24.6*	24.5	28.1	32.4
		- 23.4 26.1* 27.8* 25.4* 26.5	— 23.4 26.0 26.1* 27.8* 29.8* 25.4* 26.5 29.5

^{*} Measured with multi-bleu.perl, rest with mteval-v13a.pl

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Future work

- ► Numpy-style shape (finished)
- ► Batched decoding
- ► Facebook conv2conv model
- Moses scorers
- ► Reinforcement learning / Minimum error rate training
- ► CPU version
- **.**...

Any suggestions?

- M. Junczys-Dowmunt, T. Dwojak, and H. Hoang. Is neural machine translation ready for deployment? a case study on 30 translation directions. In *Proceedings of the* 9th International Workshop on Spoken Language Translation (IWSLT), 2016. URL http://workshop2016.iwslt.org/downloads/IWSLT_2016_paper_4.pdf.
- A. V. Miceli Barone, J. Helcl, R. Sennrich, B. Haddow, and A. Birch. Deep architectures for neural machine translation. Association for Computational Linguistics, 2017. URL http://aclweb.org/anthology/W17-4710.
- P. Ramachandran, B. Zoph, and Q. V. Le. Searching for activation functions. arXiv.org, 2017. URL https://arxiv.org/pdf/1710.05941.pdf.
- A. Vaswani, N. Shazeer, N. Parmar, J. Uszkoreit, L. Jones, A. N. Gomez, L. Kaiser, and I. Polosukhin. Attention is all you need. arXiv preprint arXiv:1706.03762, 2017. URL https://arxiv.org/pdf/1706.03762.pdf.