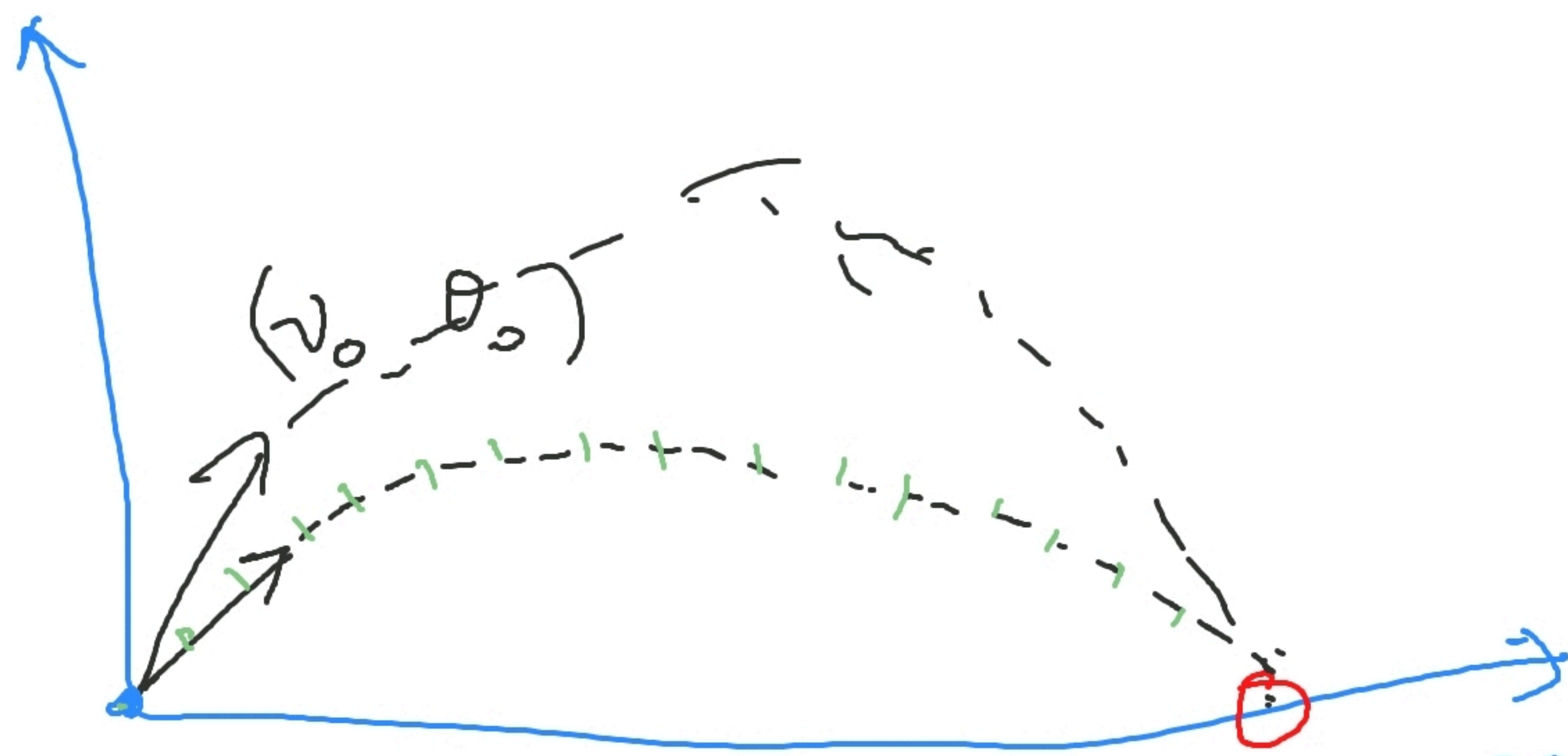


# Shooting method



Two-point BVP

$t$

$$t \in [t_1, t_2]$$

$$B_{1,j}(t_1, \vec{y}) = 0 \quad j = 1, \dots, n_1$$

$$B_{2,k}(t_2, \vec{y}) = 0 \quad k = 1, \dots, n_2$$

$\Rightarrow$  Evolve in  $t$ . (steps in time)

[For IVP  $\vec{y}_0 = (x_0, y_0, v_x^0, v_y^0)$ ]

IVP  $\rightarrow$  specify,  $\vec{y}(t=t_1)$ .

BVP  $\vec{y} = (x, y, v_x, v_y)$

$$x(t_1) = x_0, y(t_1) = y_0$$

$$= 0 \quad = 0$$

Guess  $(v_x^0, v_y^0)$

$$x(t_2) = 100m, y(t_2) = 0$$

$$4 \text{ IVPs} = N$$

$$N=4 \left[ \frac{dx}{dt}, \frac{dy}{dt}, \frac{dv_x}{dt}, \frac{dv_y}{dt} \right]$$

$$\left[ \begin{array}{l} n_1 \text{ BCs at } t_1 \\ n_2 = N - n_1 \text{ BCs at } t_2 \end{array} \right]$$



HW4 pendulum  
 $L = 1.5\text{m}$ ,  $g = 9.80\text{m/s}^2$

$$\vec{y} = \begin{pmatrix} \theta \\ \omega \end{pmatrix}$$

$$\frac{d\theta}{dt} = \omega, \big|_{t=t_1} = 0 \quad \leftarrow \text{launch from rest}$$

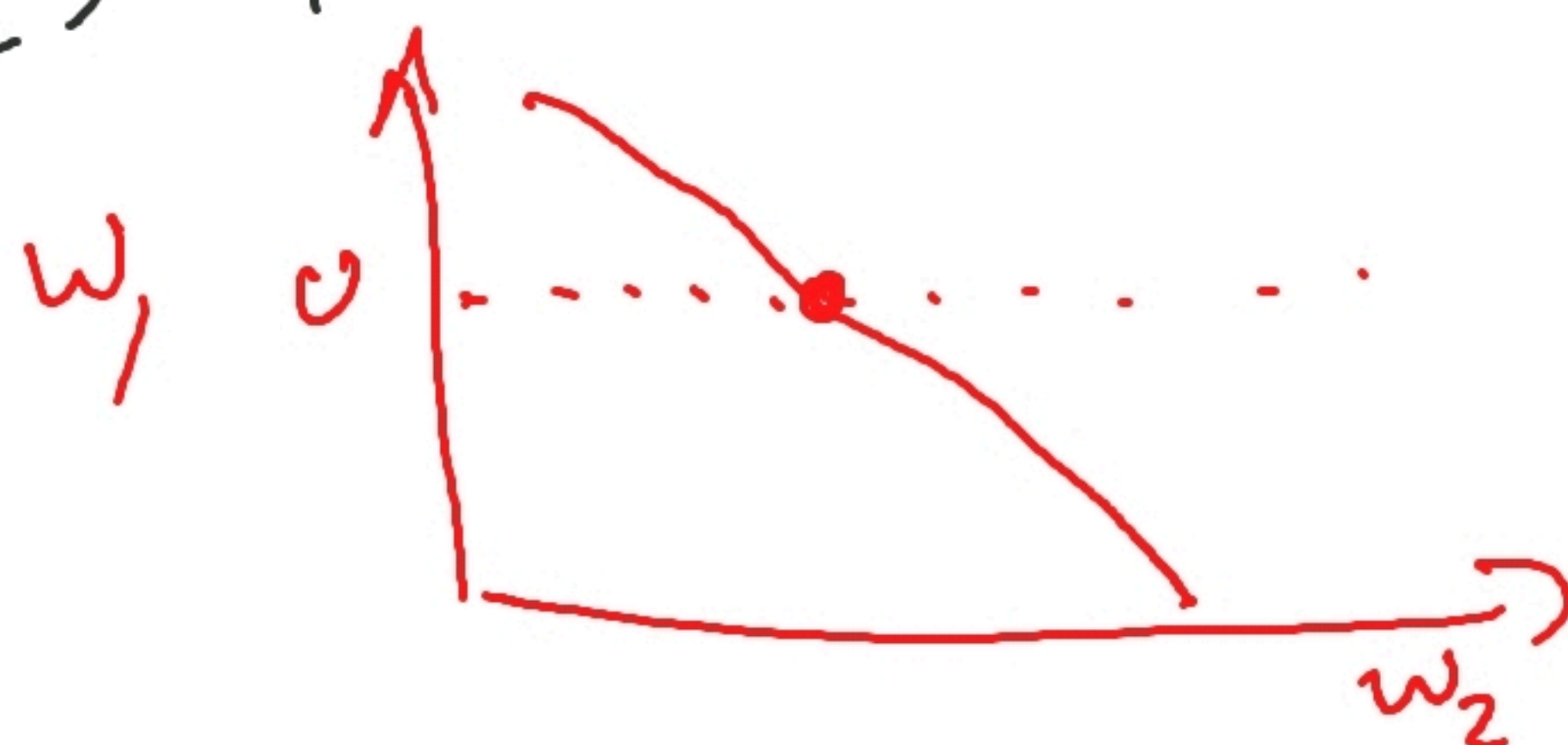
$$\theta_2(t=t_2=T/4)=0 \text{ with } T=2.5\text{s}$$

$$\frac{d\theta}{dt}$$

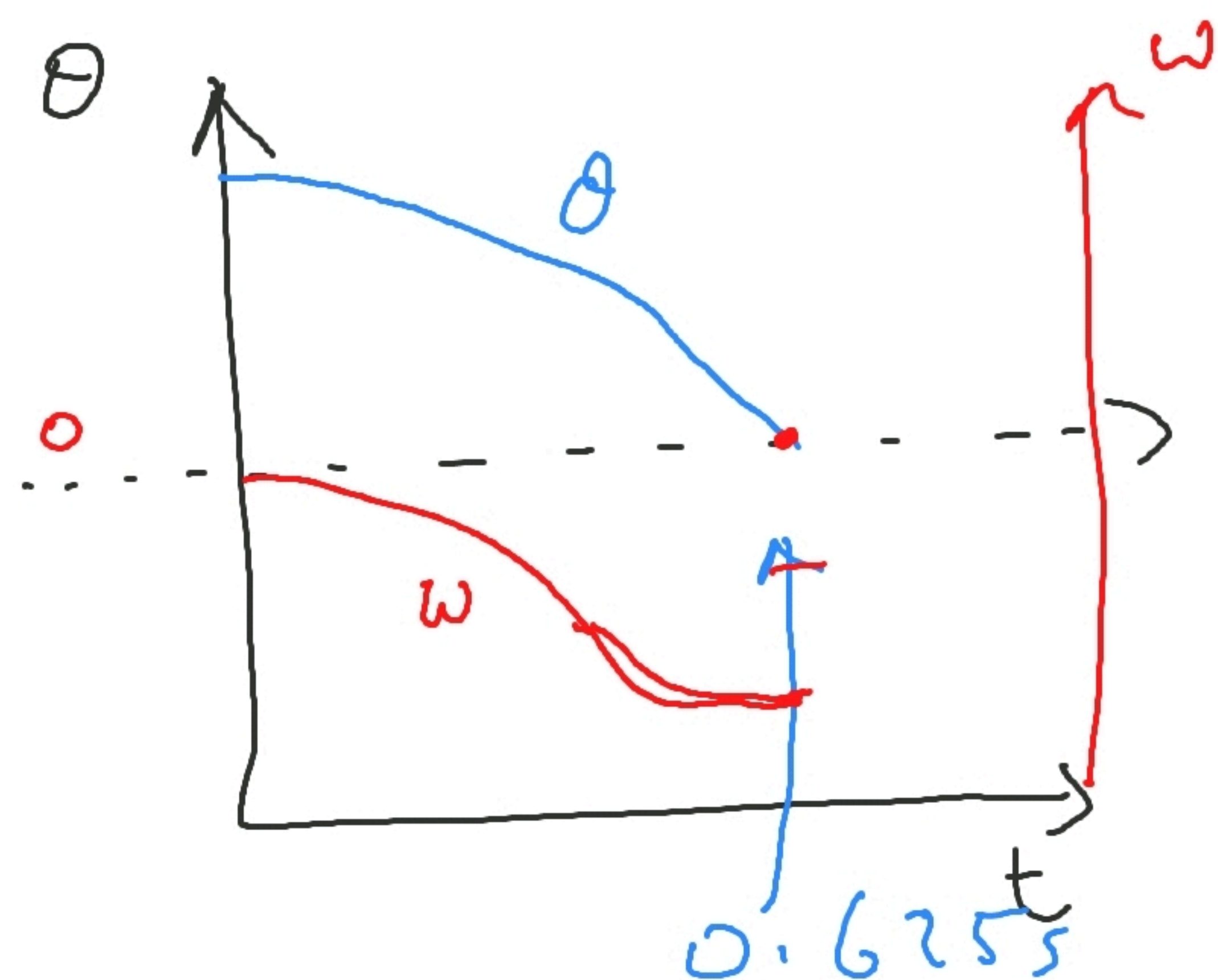
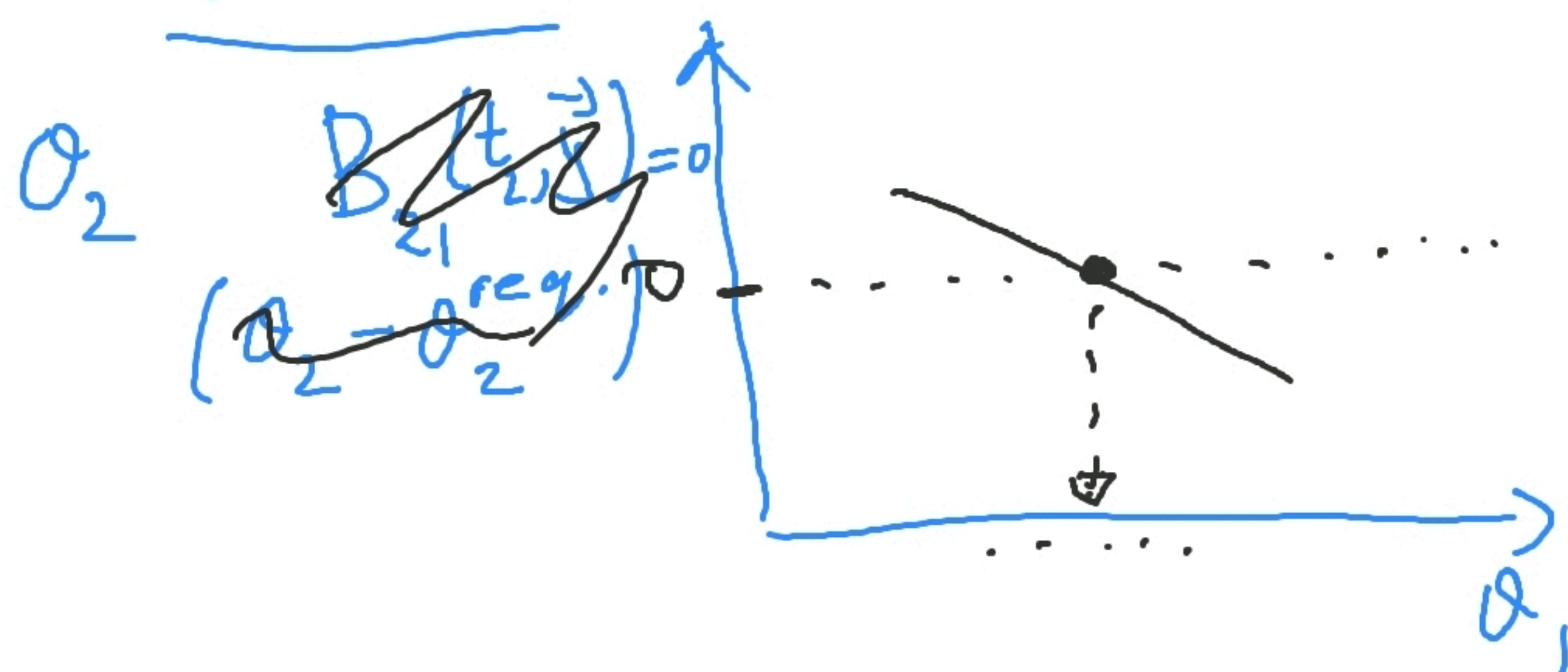
$$\frac{d\omega}{dt}$$

$$\theta_1, \omega_1 = \text{IVP}$$

$$\theta_2, \omega_1 = \text{BVP}$$



Guess  $\theta_1$





$\mathcal{P}$   
 $T_{1/4}$ ?



2 ODEs

3 ODEs

$$\frac{d\theta}{dt}, \frac{d\omega}{dt}$$

HW4.p2

$$t_1 = 0$$

$$\left. \begin{array}{l} n_1 = 2 \\ n_2 = 1 \end{array} \right\}$$

$T_{1/4}$

$$\tau \equiv \frac{(t - t_1)}{T_{1/4}} = \frac{t}{T_{1/4}}$$

$$\tau \in [0, 1]$$

$$t \in [0, T_{1/4}]$$

$$\left. \begin{array}{l} \frac{d\theta}{dt} = \omega \\ \frac{d\omega}{dt} = -\frac{g}{l} \sin \theta \\ \frac{dT_{1/4}}{dt} = 0 \end{array} \right\} \rightarrow$$

$$\left. \begin{array}{l} \frac{d\theta}{d\tau} = T_{1/4} \omega \\ \frac{d\omega}{d\tau} = -\frac{g}{l} T_{1/4} \sin \theta \\ \frac{dT_{1/4}}{d\tau} = 0 \end{array} \right\}$$

$$\theta(\tau=0) = 60^\circ$$

$$\omega(\tau=0) = 0 \text{ rad/s}$$

$$\theta(\tau=1) = 0$$

$$\vec{y} = (\theta, \omega, \underline{T_{1/4}})$$

