

Gennaro Raiola

Curriculum Vitae

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📄 <https://github.com/graiola>

Fields of interest

Robotics, computer science, motion planning, human-robot interaction, controls, DevOps.

Profession

- 09/2019- *Post-Doc* @ NASA Jet Propulsion Laboratory (NASA-JPL), Pasadena (CA),
current United States 🌐 [www](http://www.nasa.gov)
- 09/2017- *Post-Doc* @ Istituto Italiano di Tecnologia (IIT), Genoa, Italy 🌐 [www](http://www.iit.it) –
06/2019 Development and maintenance of robot real-time control frameworks and
communication systems with EtherCAT. Software architecture development
with the integration of control modules in current frameworks to make the
robots capable of executing tasks in complex environments. Open source
code adaptation, ROS and ROS packages integration on the robots. De-
vOps processes: create and maintain fully automated CI/CD pipelines for
code testing and deployment using GitLab-CI, apt servers and Docker con-
tainers. Development of software for safety to protect robot hardware and
operators. Development and integration of GUI to interact with the robot.
Cooperation with external work groups (mainly Moog, Vodafone and Inail)
in the development of robot software. Development and maintenance of
electronics and software for the new robot HyQReal with a focus on sensors
integration and calibration. Research and development of a novel whole-
body locomotion framework for quadrupedal robots using inverse dynamics
and tasks optimization.
- 03/2017- *Post-Doc* @ Robotics and Mechatronics group, University of Twente, En-
schede, The Netherlands. 🌐 [www](http://www.utwente.nl) - Development of a Safety and Energy
07/2017 aware impedance controller for the KUKA LWR 4+. Supervision of students
in the laboratories.
- 01/2016- *Ph.D. student in Robotics* @ CEA-List (French Alternative Energies and
12/2016 Atomic Energy Commission - Laboratory for Integration of Systems and Tech-
nology), Gif-sur-Yvette, France. 🌐 [www](http://www.cea.fr) - Transferring research results from
the PhD to a Startup at CEA-List (ISybot). Development of a force con-
troller to generate virtual guides through kinesthetic teaching. Integration of
the controller in the software framework of the startup's collaborative robot.

- 05/2013-12/2013 *Research Engineer in Motion Control of Humanoid Robots* @ PAL Robotics S.L., Barcelona, Spain. 🌐 [www](#) - Development, testing and design of ROS-Control and ROS-Controllers to implement a Hardware Abstraction Layer for different kinds of robots (humanoids, manipulators and mobile robots). Implementation through ROS-Control of an inverse kinematics solver with task optimization for REEM-H and REEM-C robots.
- 09/2012-02/2013 *Internship* @ ENSTA-ParisTech and UPMC-ISIR, Paris, France. 🌐 [www](#) - Development of a library in Matlab and C++ to generate Motion Primitives and perform Skills Optimization for humanoid robots (MEKA, NAO, ICub and Pepper). Maintenance of MEKA robot libraries.

Education










- 2014-2016 *Ph.D. student in Robotics* @ Université Paris-Saclay, Palaiseau, France. 🌐 [www](#).
- 2009-2012 *Master's Degree (M.Sc) with honor in Automation and Control Engineering* given by the University of Naples "Federico II", Naples, Italy.
- 2006-2009 *Bachelor's Degree (B.Sc) in Computer Engineering* given by the University of Naples "Federico II", Naples, Italy.

Technical skills

- Proficient in the following programming languages: C, C++ and Matlab
- Competent with Python and Bash scripting.
- Competent with Qt, Eigen, ROS and Boost libraries.
- Excellent knowledge of GIT.
- Excellent knowledge of CMake and Makefile for managing the build process of software and Doxygen for code documentation.
- Competent with Docker and Virtual Machines deployment for testing and development.
- Deep knowledge of Linux-based operating systems (Ubuntu, Kali, Debian).
- Experienced with real time operating systems (RTAI Linux, Xenomai Linux, RT-PREEMPT) and Kernel configuration.

Selected open-source software projects


- "ros-control" 🔄
Ros packages to make controllers generic to all robots.
- "Stack-of-Task" 🔄🎯
Integration of the stack of tasks inverse kinematics solver on the REEM-H and REEM-C robots at PAL Robotics.

- "DmpBbo"    
C++ framework for motion primitives and black-box optimization.
- "mekabot" 
Meka robot packages.
- "m3ros-control" 
C++ bridge to integrate the control layer of the Meka robot into a ROS environment.
- "virtual-fixtures"   
Library of virtual guides for co-manipulation.






Publications

Journals

- 2020 **G. Raiola**, E. Mingo Hoffman, M. Focchi, N. Tsagarakis, C. Semini.
"A simple yet effective whole-body locomotion framework for quadruped robots".
Under review at Frontiers in Robotics.
- 2019 R. Orsolino, M. Focchi, S. Caron, **G. Raiola**, V. Barasuol, C. Semini.
"Feasible Region: an Actuation-Aware Extension of the Support Region". 
IEEE Transactions on Robotics.
- 2019 F. Stulp, **G. Raiola**.
"DmpBbo: A versatile Python/C++ library for Function Approximation, Dynamical Movement Primitives, and Black-Box Optimization". 
In *The Journal of Open Source Software*.
- 2018 Susana Sánchez Restrepo, **Gennaro Raiola**, Joris Guerry, Evelyn D'Elia, Xavier Lamy and Daniel Sidobre.
"Towards an Intuitive and Iterative 6D Virtual Guides Programming Framework for Human-Robot Comanipulation".
Robotica.
- 2017 **Gennaro Raiola**, Carlos Cardenas Alberto, Tadele Shiferaw Tadele, Theo De Vries, Stefano Stramigioli.
"Development of a Safety and Energy Aware Impedance Controller for Collaborative Robots". 
In *IEEE Robotics and Automation Letters*.
The contents of this paper were also selected by ICRA'18 Program Committee for presentation at the Conference.
- 2017 S. Chitta, E. Marder-Eppstein, W. Meeussen, V. Pradeep, A. Rodriguez Tsouroukdissian, J. Bohren, D. Coleman, B. Magyar, **G. Raiola**, M. Ludtke and E. Perdomo Fernandez.
"ros_control: A generic and simple control framework for ROS". 
In *The Journal of Open Source Software*.

- 2017 **Gennaro Raiola**, Susana Sanchez Restrepo, Pauline Chevalier, et al.
"Co-manipulation with a Library of Virtual Guiding Fixtures". 
In *Autonomous Robots, Special Issue on Learning for Human-Robot Collaboration*.

Conferences

- 2017 Pauline Chevalier, **Gennaro Raiola**, Brice Isableu, Jean-Claude Martin, Christophe Bazile and Adriana Tapus.
"Do Sensory Preferences of Children with Autism Impact an Imitation Task with a Robot?".
In *Conference on Human-Robot Interaction (HRI)*.
- 2017 Susana Sanchez Restrepo, **Gennaro Raiola**, Pauline Chevalier, Xavier Lamy, and Daniel Sidobre.
"Iterative Virtual Guides Programming for Human-Robot Comanipulation". 
In *IEEE International Conference on Advanced Intelligent Mechatronics (AIM)*.
- 2015 **Gennaro Raiola**, Xavier Lamy, and Freek Stulp.
"Co-manipulation with Multiple Probabilistic Virtual Guides". 
In *International Conference on Intelligent Robots and Systems (IROS)*.
- 2015 **Gennaro Raiola**, Pedro Rodriguez-Ayerbe, Xavier Lamy, Sami Tliba, and Freek Stulp.
"Parallel Guiding Virtual Fixtures: Control and Stability". 
In *IEEE Multi-Conference on Systems and Control (MSC)*.
- 2014 Freek Stulp, Laura Herlant, Antoine Hoarau, and **Gennaro Raiola**.
"Simultaneous On-line Discovery and Improvement of Robotic Skill". 
In *International Conference on Intelligent Robots and Systems (IROS)*.
- 2013 Freek Stulp, **Gennaro Raiola**, Antoine Hoarau, Serena Ivaldi, and Olivier Sigaud.
"Learning Compact Parameterized Skills with a Single Regression". 
In *IEEE-RAS International Conference on Humanoid Robots*.

Languages

italian	native proficiency
english	professional working proficiency
french	limited working proficiency