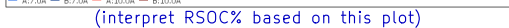
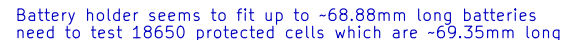


Rev: v0.1.0
Id: 2/23


$$\begin{aligned} 1.658 \leq ILIM \leq 2.063 \\ ILIM(nom) \cong 1.859 \\ 3.9 \leq VIN \leq 14 \end{aligned}$$

R025896
 L301
 I(Lsat)=7A
 L302
 HI1206T500R
 3.5~4.25V
 PWR_FLAG

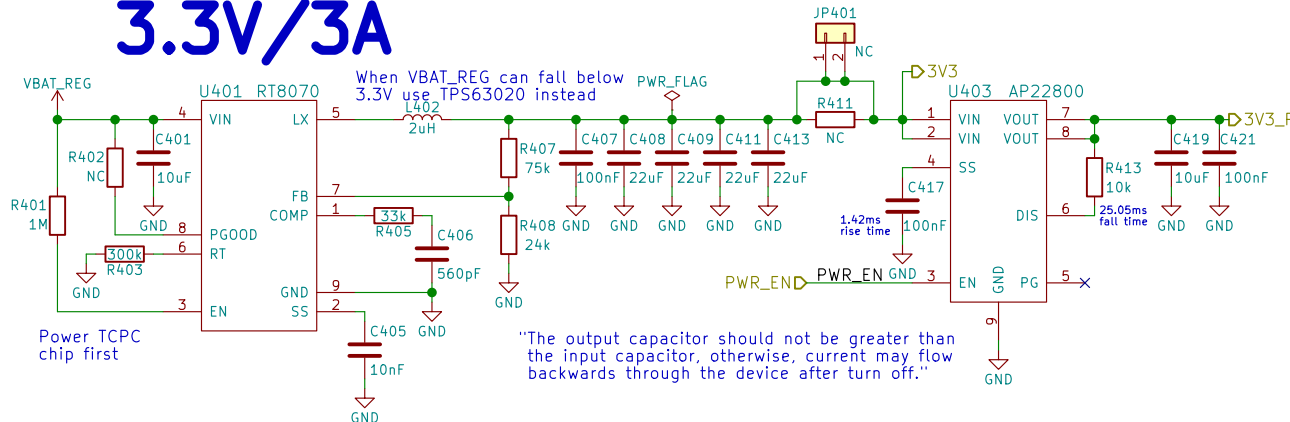


reference design: <http://www.ti.com/lit/ug/sluu2b/sluu2b.pdf>
 may want to include BQ29705 protection as in:
<http://www.ti.com/lit/ug/tiduc1/tiduc1.pdf>
 schematic: <http://www.ti.com/lit/df/tidrp70/tidrp70.pdf>
 (PTC may be good enough)

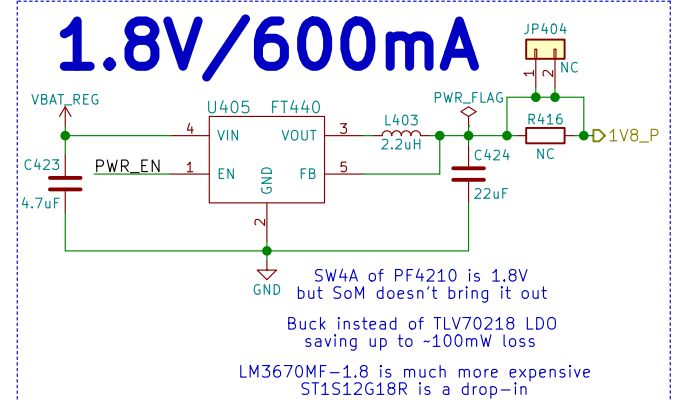
TODO:
Keystone 1042 footprint???

Id: 3/23

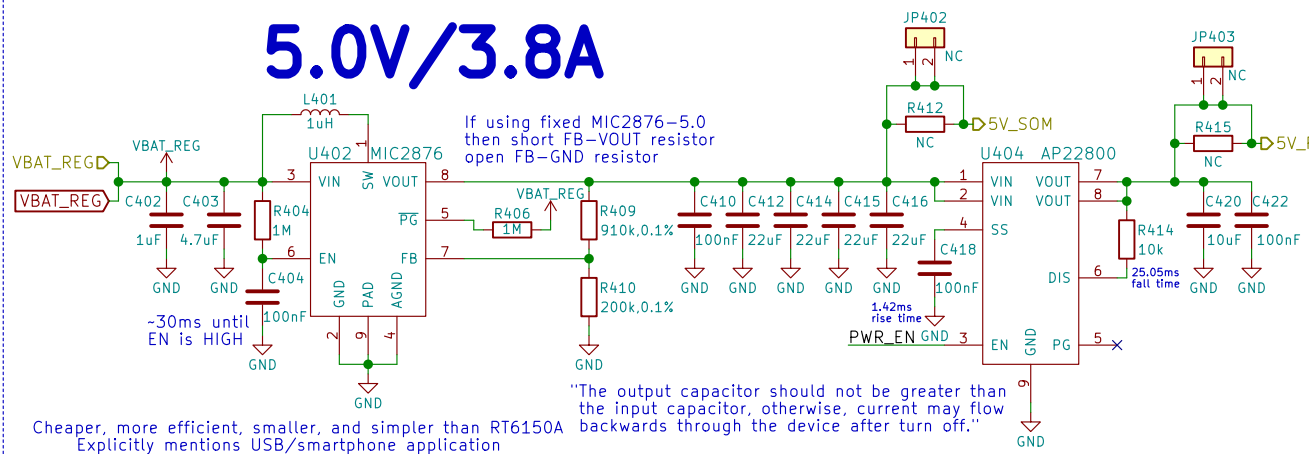
3.3V/3A



1.8V/600mA

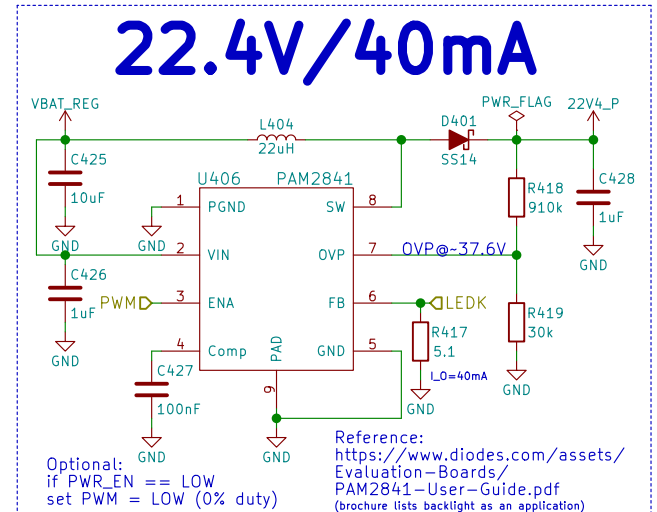


5.0V/3.8A



TODO:
add parallel 100nF bulk caps!
& spread all over the power plane

22.4V/40mA



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Purism SPC

Sheet: /Power/
File: power.sch

Title: Power

Size: A4
KiCad E.D.A. kicad 4.0.7

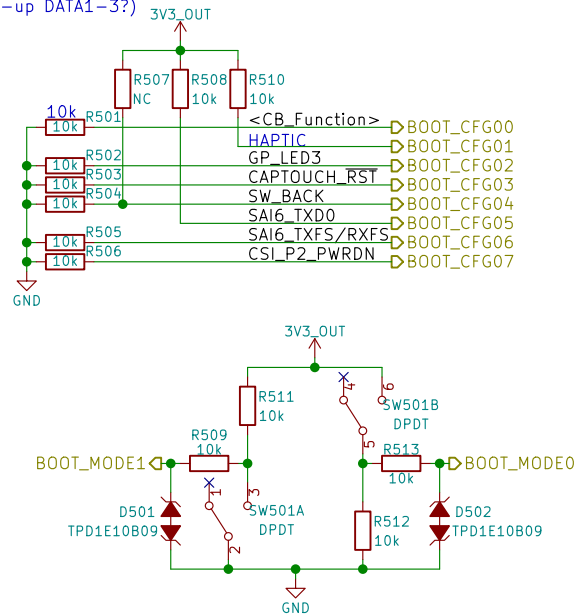
Date: 2018-05-23

Rev: v0.1.0

Id: 4/23

BOOT_CFG04: 0 - 1-bit SD bus
1 - 4-bit SD bus (pull-up DATA1-3?)

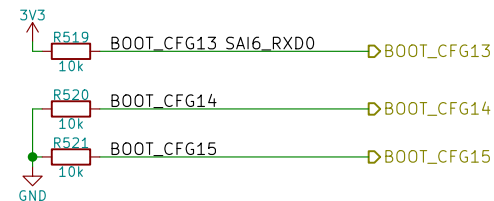
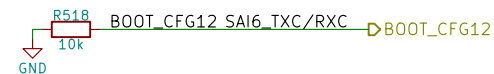
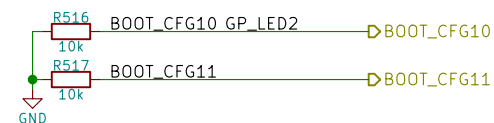
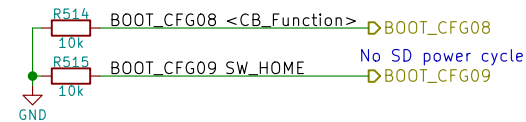
BOOT_CFG05: 1 - 8-bit eMMC bus
0 - 1-bit eMMC bus



2->1: eMMC 2->3: USB (Serial Downloader)	
BOOT_MODE[1:0]	Boot Type
00	Boot From Fuses
01	Serial Downloader
10	Internal Boot
11	Reserved

Only eMMC

BOOT_CFG[14:12]		Boot device			
001		SD/eSD			
010		MMC/eMMC			
011		NAND			
Fuse	Config	Definition	GPIO ¹	Shipped value	Settings
BOOT_CFG[11:10]	OEM	USDHC port selection	Yes	00	00 - USDHC-1 01 - USDHC-2 10 - USDHC-3 else - reserved



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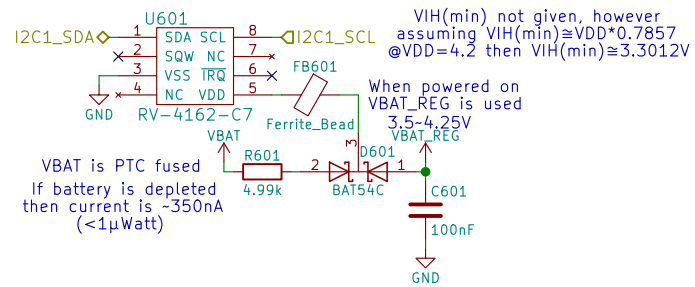
Purism SPC

Sheet: /Boot Config/
File: boot.sch

Title: Boot Configuration

Size: A4 Date: 2018-05-23
KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0
Id: 5/23



GNU GPLv3
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Purism SPC

Sheet: /RTC/
File: rtc.sch

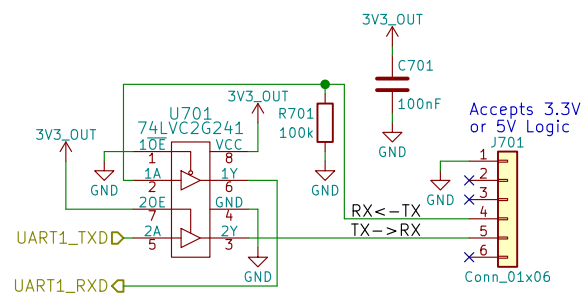
Title: RTC

Size: A4 Date: 2018-05-23

KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0

Id: 6/23



GNU GPLv3
Copyright 2018

Purism SPC

Sheet: /UART Debug/
File: uart.sch

Title: UART Debug

Size: A4 Date: 2018-05-23

KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0

Id: 7/23

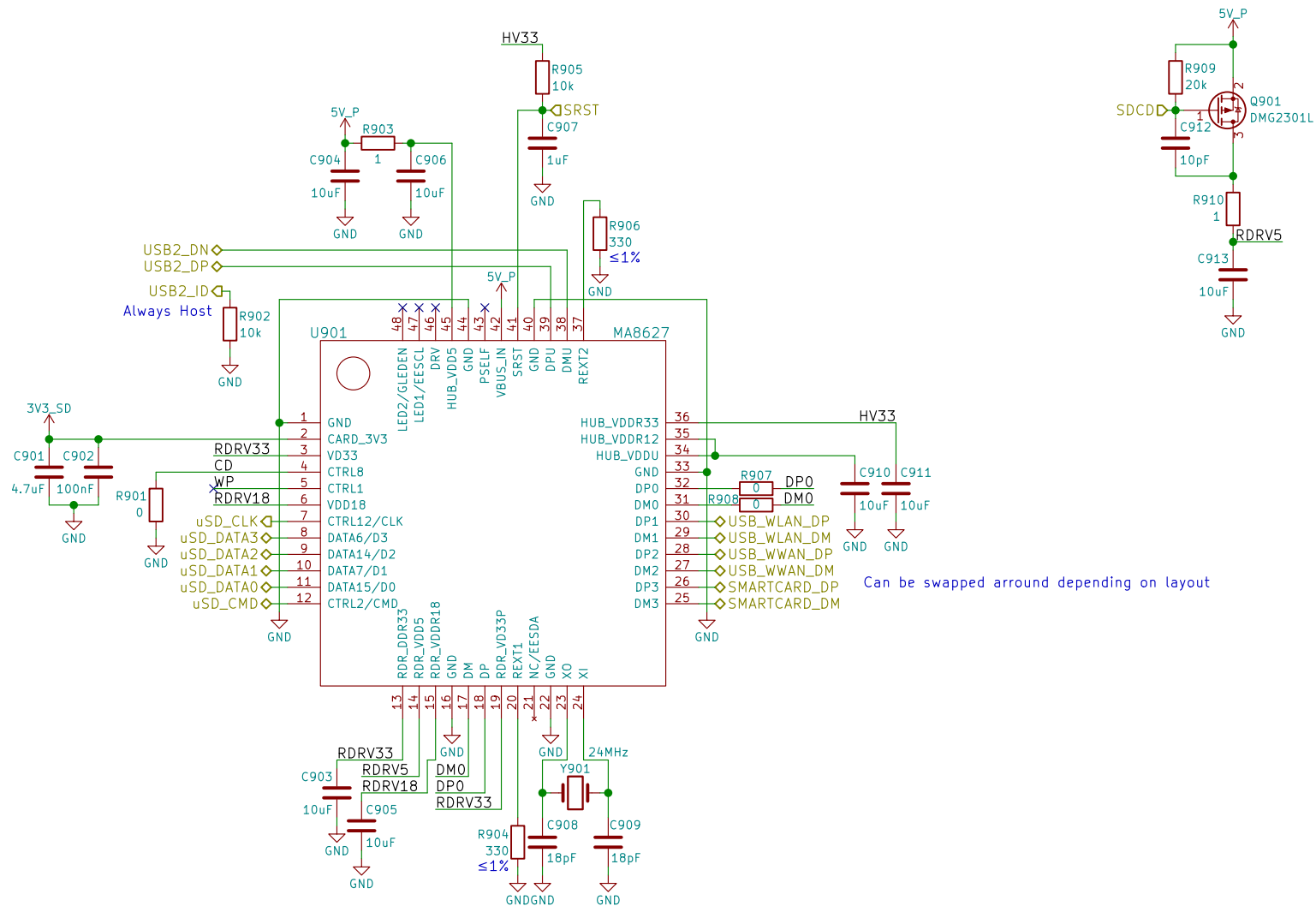


GNU GPLv3
Copyright 2018
Purism SPC
Sheet: /JTAG/
File: jtag.sch

Title: JTAG

Size: A4 Date: 2018-05-23
KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0
Id: 8/23



GNU GPLv3
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Purism SPC

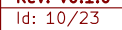
Sheet: /USB Hub + SDIO Bridge/
File: usb_hub_sdio.sch

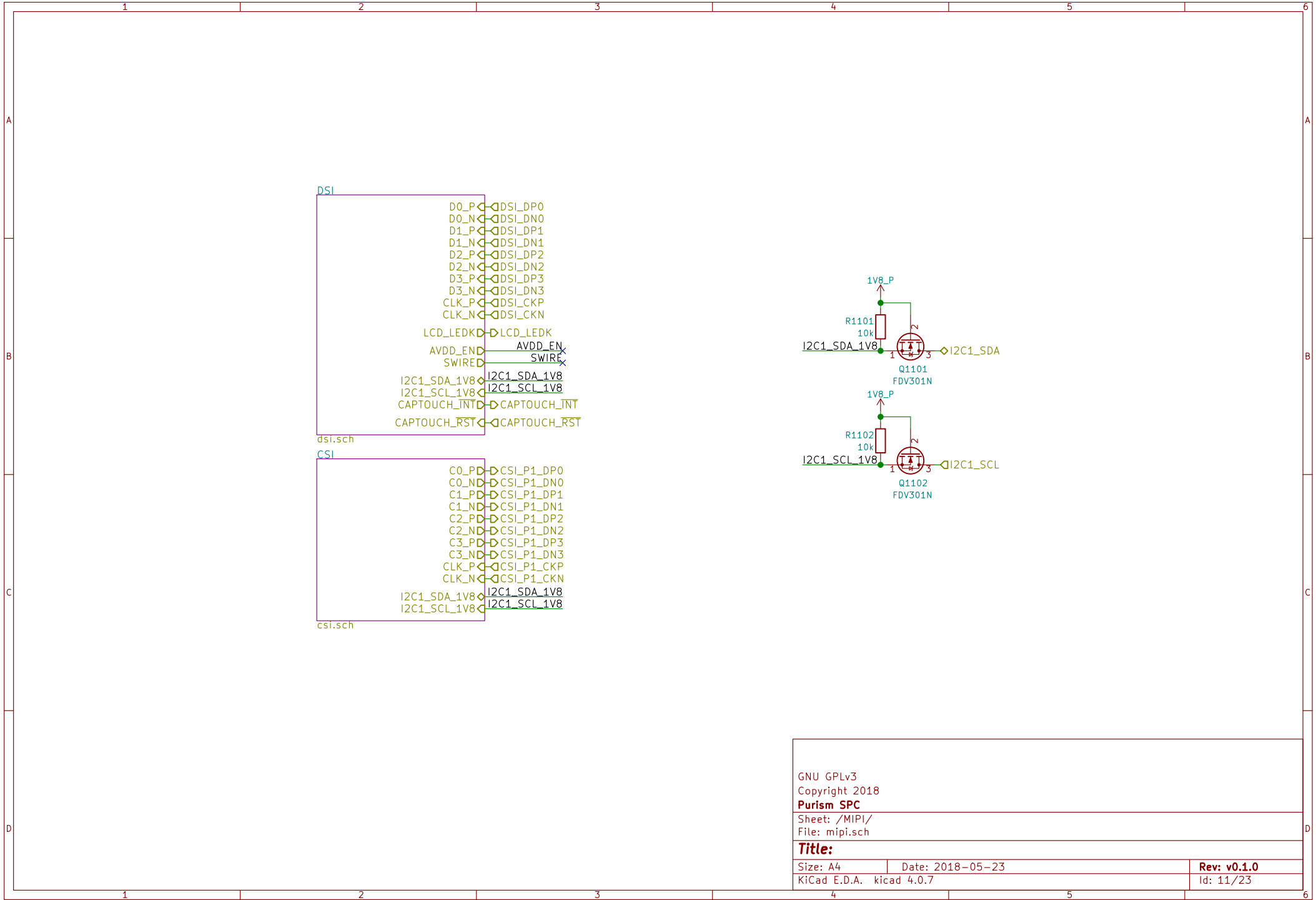
Title:

Size: A4
KiCad E.D.A. kicad 4.0.7

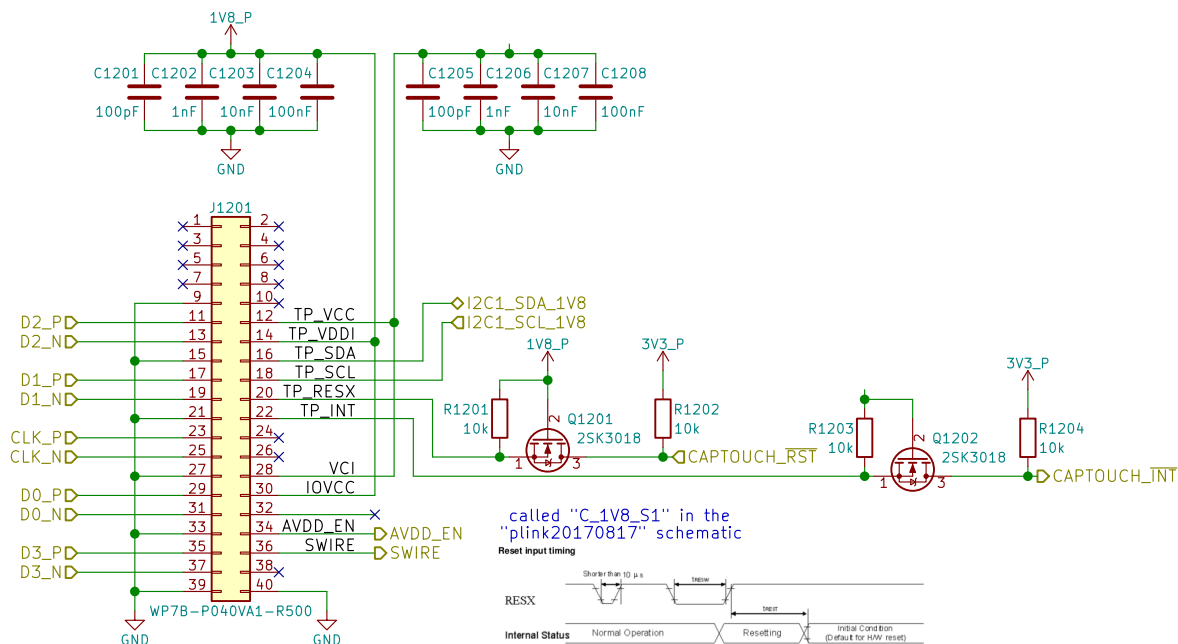
Date: 2018-05-23

Rev: v0.1.0
Id: 9/23





TODO:
ensure power sequence is satisfied
based on the display used



TODO: low power state signal?? → LCD_LEDK

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Sheet: /MIPI/DSI/
File: dsi.sch

Title: MIPI DSI

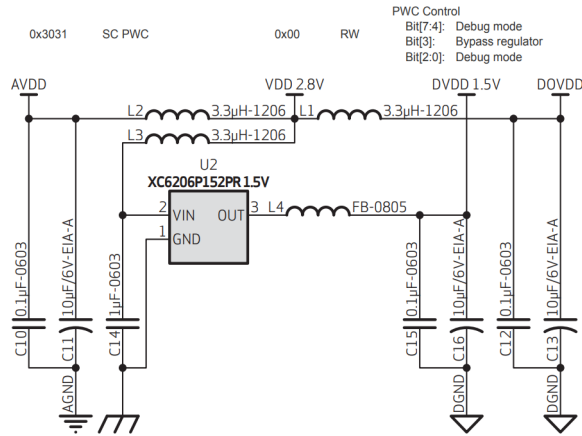
Size: A4 Date: 2018-05-23

KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0

Id: 12/23

Using Internal DVDD 1.5V Regulator:



2.7 POWER UP SEQUENCE

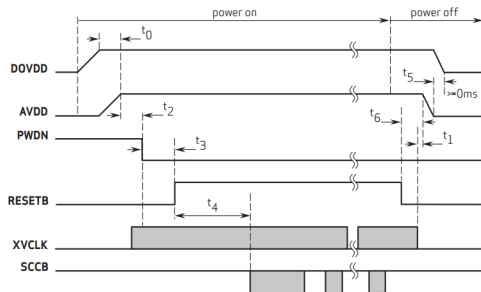
Based on the system power configuration (1.8V or 2.8V for I/O power, using external DVDD or internal DVDD, requiring access to the I2C during power up period or not), the power up sequence will differ. If 1.8V is used for I/O power, using the internal DVDD is preferred. If 2.8V is used for I/O power, due to a high voltage drop at the internal DVDD regulator, there is a potential heat issue. Hence, for a 2.8V power system, OmniVision recommends using an external DVDD source. Due to the higher power down current when using an external DVDD source, OmniVision strongly recommends cutting off all powers, including the external DVDD, when the sensor is not in use in the case of 2.8V I/O and external DVDD.

2.7.1 POWER UP WITH INTERNAL DVDD

For powering up with the internal DVDD and I2C access during the power ON period, the following conditions must occur:

1. when DOVDD and AVDD are turned ON, make sure DOVDD becomes stable before AVDD becomes stable
2. PWDN is active high with an asynchronized design (does not need clock)
3. PWDN pin tied to digital ground if it is not controlled.
4. if PWDN pin is controlled as below, for PWDN to go low, power must first become stable (AVDD to PWDN ≥ 5 ms)
5. RESETB is active low with an asynchronized design
6. master clock XVCLK should provide at least 1 ms before host accesses the sensor's registers
7. host can access I2C bus (if shared) during entire period. 20ms after RESETB goes high, host can access the sensor's registers to initialize sensor

figure 2-3 power up timing with internal DVDD



- note $t_0 \geq 0$ ms, delay from DOVDD stable to AVDD stable, it is recommended to power up AVDD shortly after DOVDD has been powered up
- $t_1 \geq 0$ ms, delay from XVCLK off to AVDD off
- $t_2 \geq 5$ ms, delay from AVDD stable to sensor power up stable, PWDN can be pulled low after this point. XVCLK can be turned on after power on
- $t_3 \geq 1$ ms, delay from sensor power up stable to RESETB pull up
- $t_4 \geq 20$ ms, delay from RESETB pull high to SCCB initialization
- $t_5 \geq 0$ ms, delay from AVDD off to DOVDD off
- $t_6 \geq 0$ ms, delay from RESETB pull low to AVDD off

✕D C0_P
✕D C0_N
✕D C1_P
✕D C1_N
✕D C2_P
✕D C2_N
✕D C3_P
✕D C3_N
✕D CLK_P
✕D CLK_N
◇ I2C1_SDA_1V8
◇ I2C1_SCL_1V8

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Purism SPC

Sheet: /MIPI/CSI/
File: csi.sch

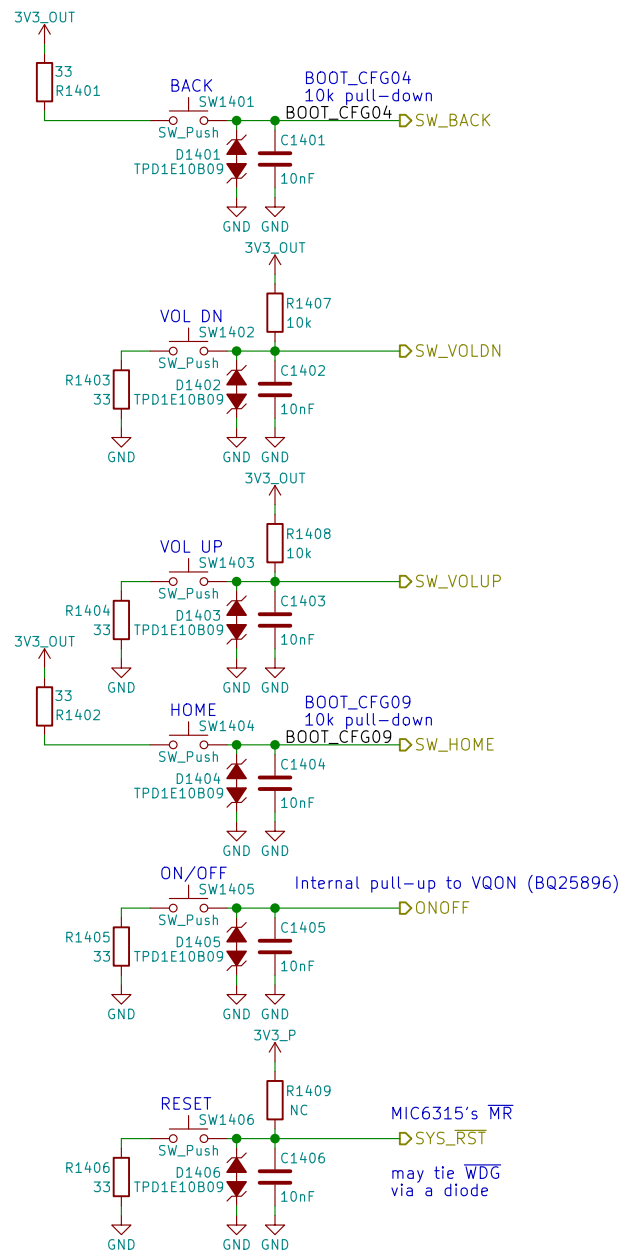
Title:

Size: A4 Date: 2018-05-23

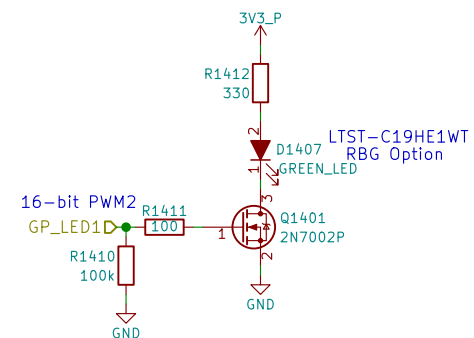
KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0

Id: 13/23



Use PWM2_PWMSAR to set the compare value (duty cycle)
 Use PWM2_PWMCR[15:4] to set the PRESCALER (frequency)
 Use PWM2_PWMPR to set the top of the counter (frequency)



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Purism SPC

Sheet: /Buttons & LED/
 File: buttons_led.sch

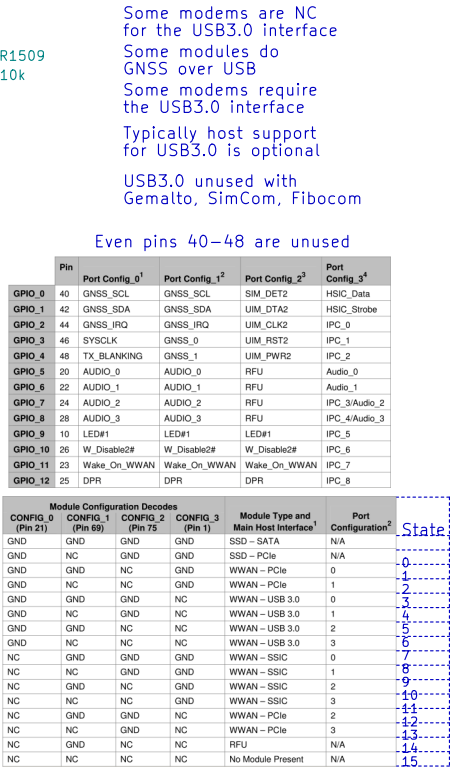
Title: Buttons & LED

Size: A4 Date: 2018-05-23

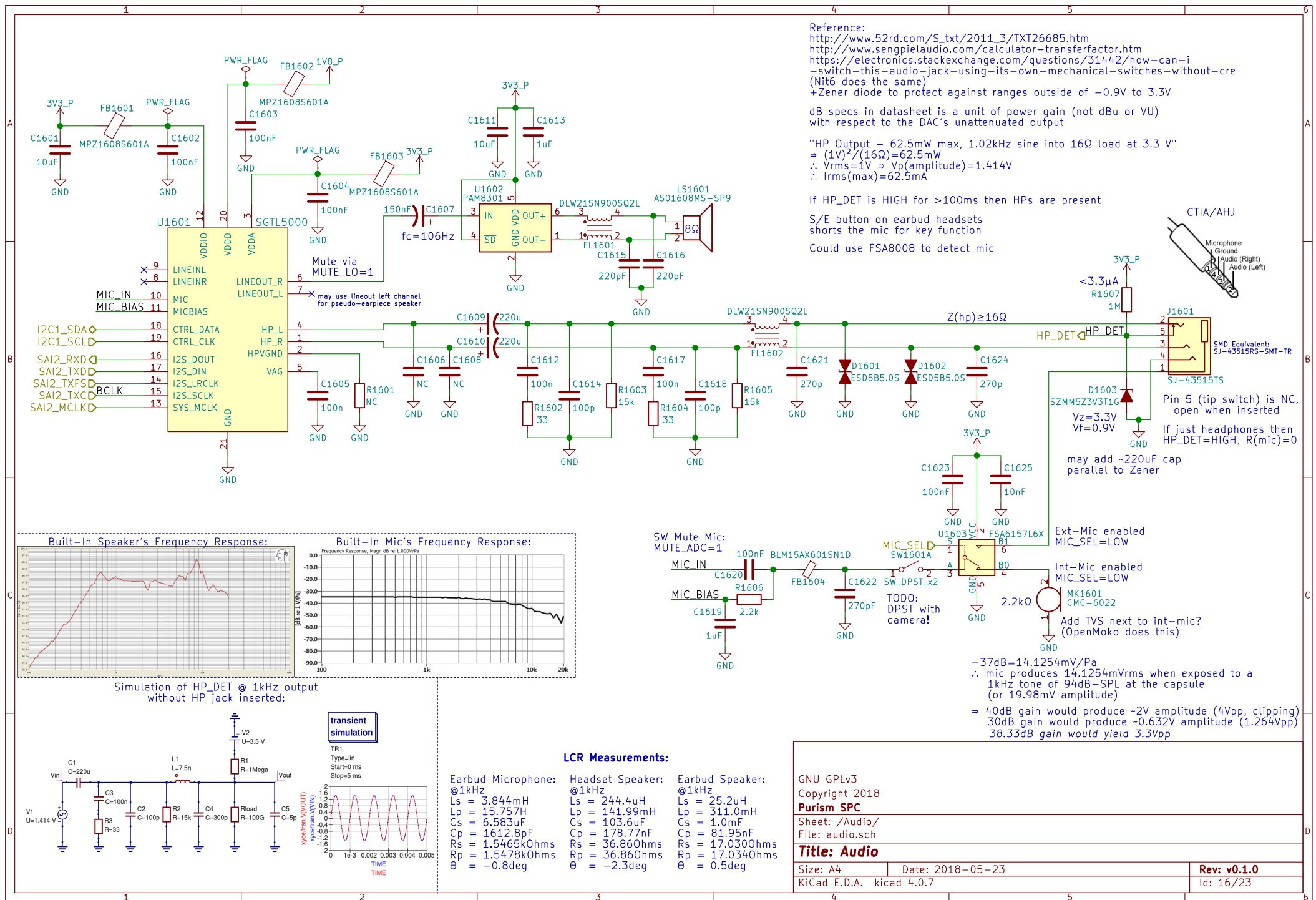
KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0

Id: 14/23



Rev: v0.1.0
Id: 15/23



[illegible]

Id: 17/23

RS9116 NC:
RTS, CTS, BT_HOST_WAKE

RS9116 datasheet says
no WIFI_WAKE
but the schematic has it

RedPine RS9116 MB0
Requires 5V on
Pin 54 for USB!

USB_WLAN_DP
USB_WLAN_DN

Module: Table 23
Socket: Table 46

3V3_P

JP1801
1 NC
2 NC

M2_PCM_CLK

M2_PCM_SYNC

M2_PCM_IN

M2_PCM_OUT

SoC's IN/OUT

BT_HOST_WAKE

BT_UART_RXD

SoC's RX
Module's TX

SoC's TX
Module's RX

BT_UART_TXD

BT_UART_RTS

BT_UART_CTS

i.MX8M in DCE mode (POR state)
has CTS output, RTS input

RS9116 SUSCLK
is a GPIO (unused)
SUSCLK

W_DISABLE2

W_DISABLE1

M2_I2C_SDA

M2_I2C_SCL

M2_Key_E

GND

GND

GND

GND

GND

GND

GND

GND

GND

GND

GND

GND

GND

GND

GND

GND

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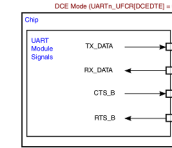
GND

GND

GND

6.2 M.2 Signal Directions

UARTn_UFCR[DCEDTE]=0 on POR



TX output
RX input
CTS output
RTS input

→ TX→RX
RX→TX
CTS→CTS
RTS→RTS

Note:
Dual 2-input AND much more
available and cheaper than NOR

TODO:
Pin 54 on RS9116 is USB_VBUS Sink!!!

BT_DISABLE

WIFI_DISABLE

SW1801
WWAN_HKS

Open = ON
Closed = OFF

RS9116 is an I2C master
=its SCL is an output
(ok bc only device on I2C2)

M2_I2C_SDA

M2_I2C_SCL

I2C2_SDA

I2C2_SCL

Q1801
FDV301N

Q1802
FDV301N

Q1801
FDV301N

Q1802
FDV301N

Q1801
FDV301N

Q1802
FDV301N

Q1801
FDV301N

Q1802
FDV301N

Q1801
FDV301N

Q1802
FDV301N

Q1801
FDV301N

Q1802
FDV301N

Q1801
FDV301N

Q1802
FDV301N

Q1801
FDV301N

Q1802
FDV301N

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FDV301N

Q1801
FDV301N

Q1802
FDV301N

Q1801
FDV301N

Q1802
FDV301N

Q1801
FDV301N

Q1802
FDV301N

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Purism SPC

Sheet: /WLAN+BT M.2/

File: wifi_bt_m2.sch

Title: WLAN+BT M.2

Size: A4 Date: 2018-05-23

KiCad E.D.A. kicad 4.0.7

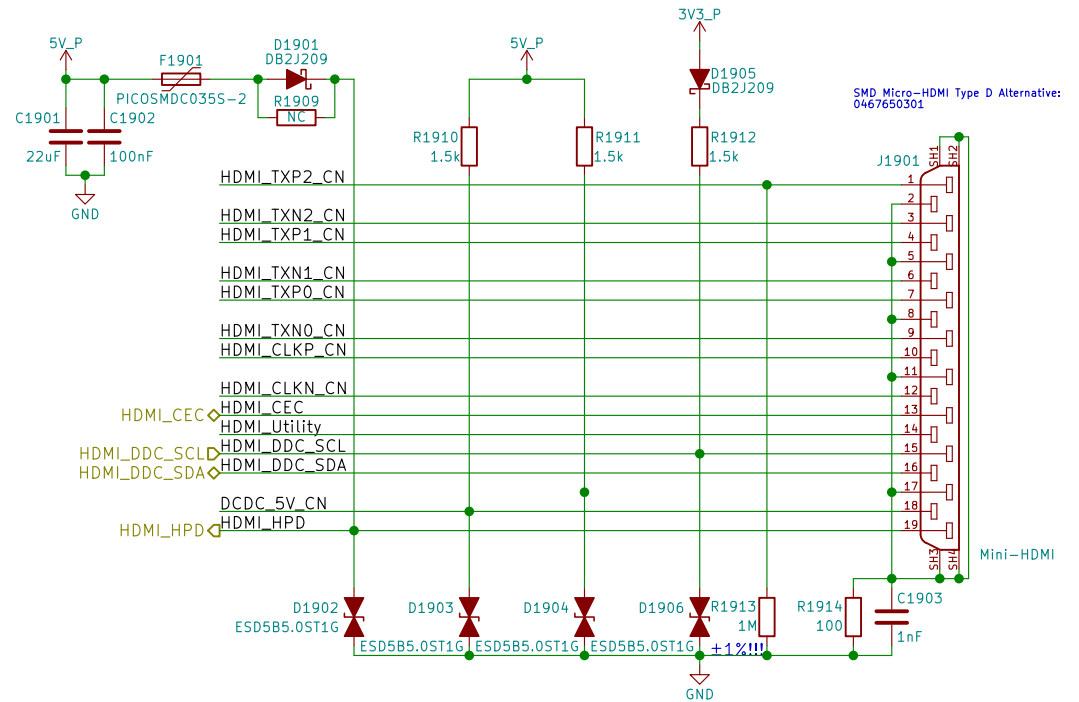
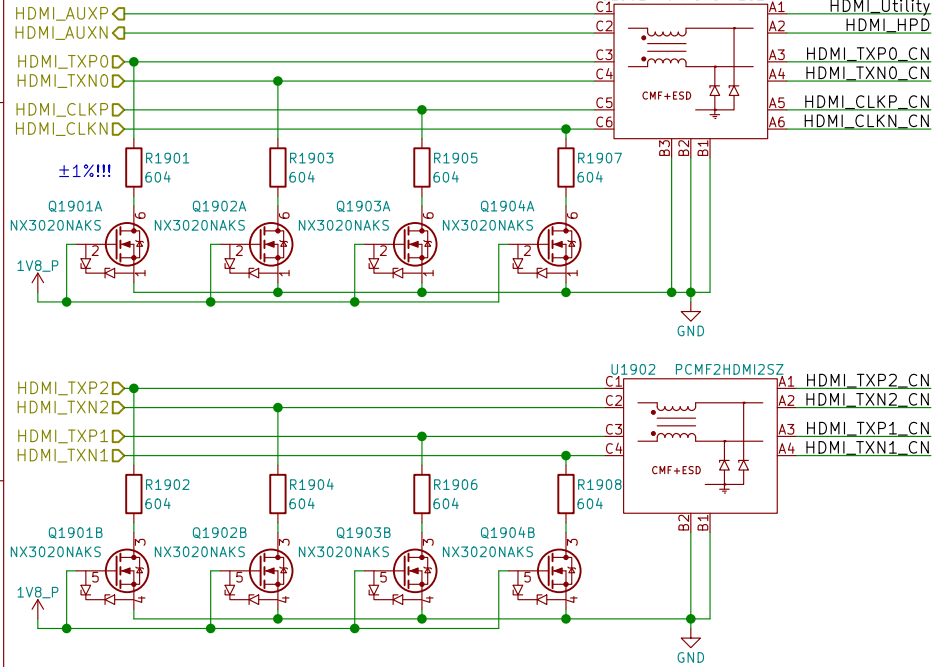
Rev: v0.1.0

Id: 18/23

HD3SS460 can be used for DP over USB-C

Layout Note:
May need swap some signals
due to micro-HDMI pinout diff
depending on pin location/routing

100Ω diff pairs



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Purism SPC

Sheet: /HDMI/
File: hdmi.sch

Title: HDMI

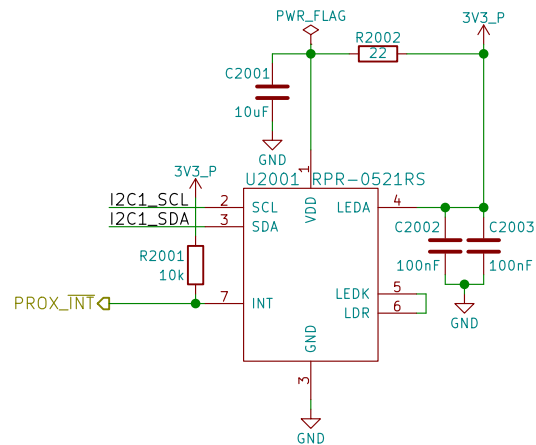
Size: A4
KiCad E.D.A. kicad 4.0.7

Date: 2018-05-23

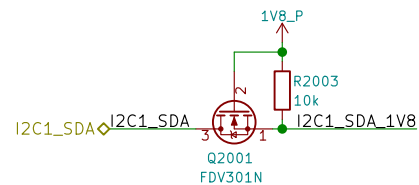
Rev: v0.1.0

Id: 19/23

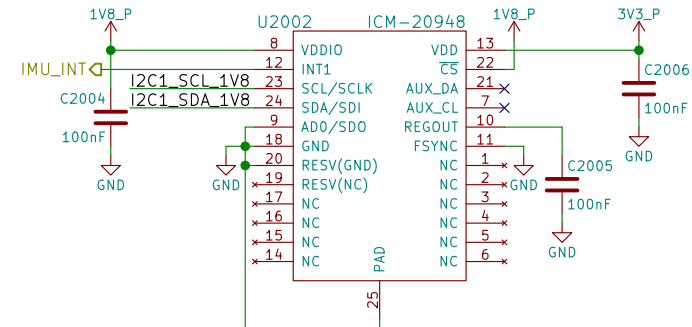
Proximity & Ambient Light



Reference:
<http://www.rohm.com/web/global/sensor-shield-support/ps-als-sensor>



9-Axis IMU



Reference:
<https://store.invensense.com/datasheets/invensense/AN-IVS-0001EVB-00%20v1%202.pdf>

AD0 sets the slave address's LSB (110100X)

INT1_ACTL sets if IMU_INT is active-high or active-low

"FSYNC - Connect to GND if unused"

I2C's VIH=1.8V

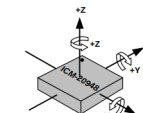


Figure 12. Orientation of Axes of Sensitivity and Polarity of Rotation

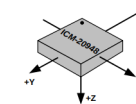


Figure 13. Orientation of Axes of Sensitivity for Magnetometer

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Purism SPC

Sheet: /Sensors/
 File: sensors.sch

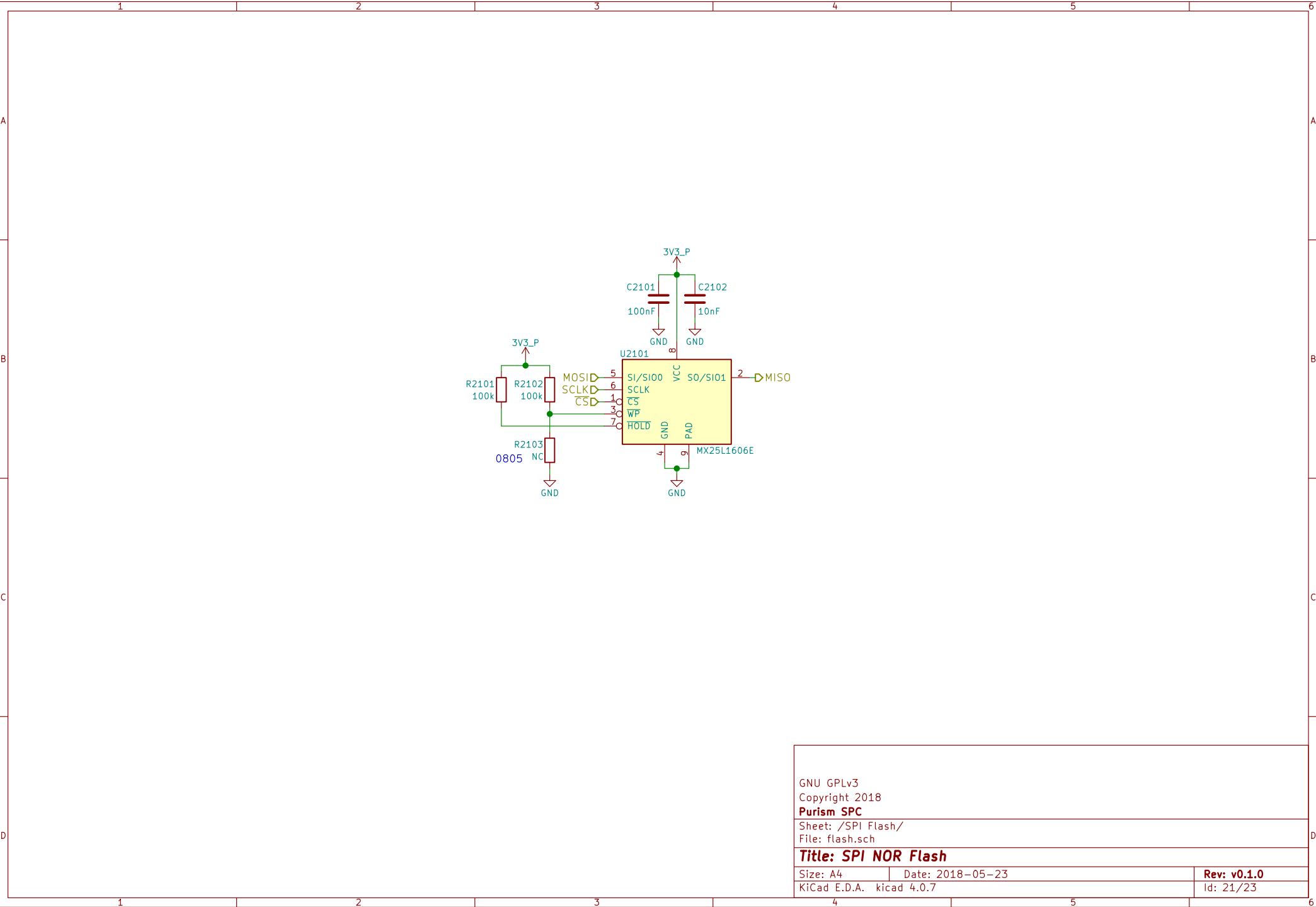
Title: Sensors

Size: A4 Date: 2018-05-23

KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0

Id: 20/23



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Purism SPC

Sheet: /SPI Flash/

File: flash.sch

Title: SPI NOR Flash

Size: A4

Date: 2018-05-23

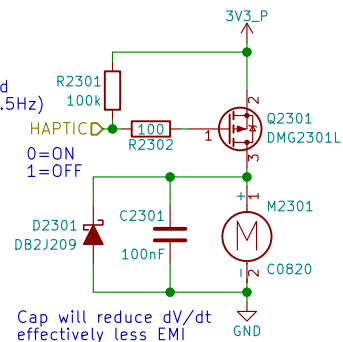
Rev: v0.1.0

KiCad E.D.A. kicad 4.0.7

Id: 21/23

PWM pins occupied:
 GPIO1_I001 - DSI (DSI_BL_PWM??)
 GPIO1_I013 - LED
 GPIO1_I014 - Ethernet (CLKO_25MHz)
 GPIO1_I015 - CSI (CLKO2)

PWM needed?
 Only needs to be toggled
 ON 1 sec, OFF 1 sec (0.5Hz)
 Can MUX as either
 GPIO or PWM2
 swapping with LED



When the motor is off
 both terminals are at GND

Motor will have wire leads
 with a 2-pin Molex or JST
 connector installed (by request)!

Motor Connector:
https://lcsc.com/product-detail/1-25T-Connectors_1-25T-1-2AW_C10832.html

Alibaba Alternative Motor:
https://www.alibaba.com/product-detail/Coin-motor-vibration-dc-motor-cellphone_1994583657.html?spm=a2700.8443308.0.0.5aa13e5f1wxHgs

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Purism SPC

Sheet: /Haptic Motor/
 File: haptic.sch

Title: Haptic/Vibration Motor

Size: A4 Date: 2018-05-23

KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0

Id: 23/23