

USB-C





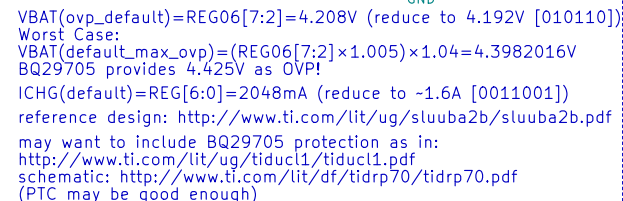
Drawing ~333.33mA,
or consuming <1.2W,
should give close to
10 hours going from
100% to 0% charge

$$1.658 \leq I_{LIM} \leq 2.063$$

$$I_{LIM(nom)} \cong 1.859A$$

$$3.9 < V_{IN} \leq 14$$
$$I(\text{sat}) = 7\text{A}$$

L301



Also, reading PTN5110HQ's CC_STATUS and POWER_STATUS registers will tell TCPM (i.MX8M) when to set OTG_CONFIG=1 (this will also happen when PTN5110HQ sets EN_SRC HIGH)

Battery holder gives ~1mm clearance underneath the battery
Thermistor is 1.1 ± 0.15 mm thick, should fit fine with stack-up

Battery holder seems to fit up to ~68.88mm long batteries
need to test 18650 protected cells which are ~69.35mm long

Purism

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christian.schilmoeller@puri.sm

Id: 3/24

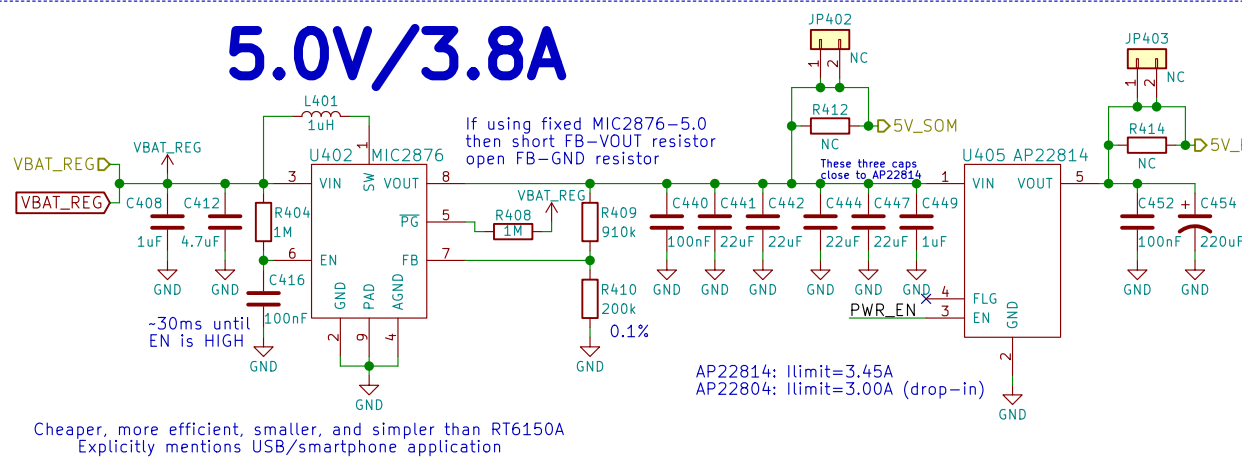
3.3V/3A



1.8V/600mA



5.0V/3.8A



22.4V/40mA



2.8V/150mA



Power

Power

Purism

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Sheet: /Power/
File: power.sch

Size: A4 Date: 2018-06-18

KiCad E.D.A. kicad 4.0.6

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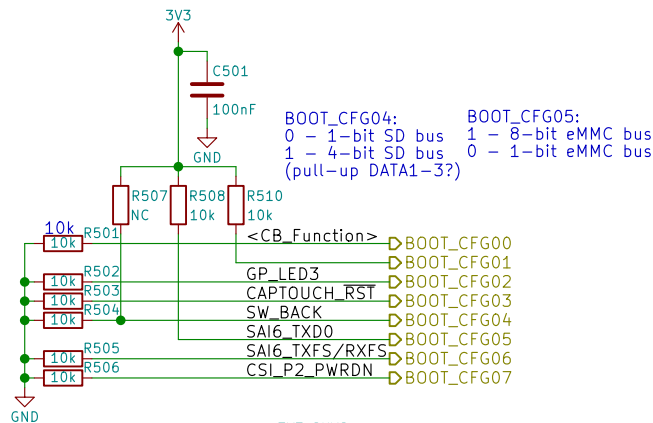
nicole.farber@puri.sm

christian.schilmoeller@puri.sm

Rev: v0.1.0

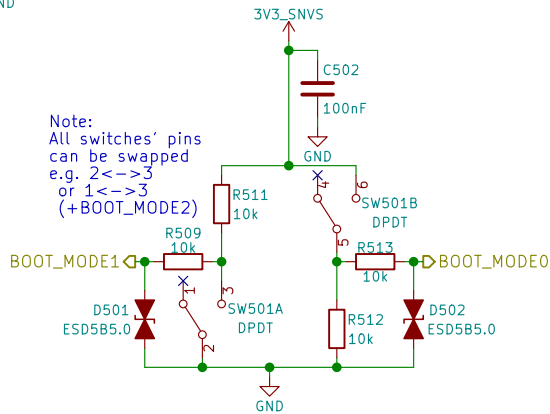
Id: 4/24

Boot Config



BOOT_CFG04: 0 - 1-bit SD bus
1 - 4-bit SD bus (pull-up DATA1-3?)

BOOT_CFG05: 1 - 8-bit eMMC bus
0 - 1-bit eMMC bus



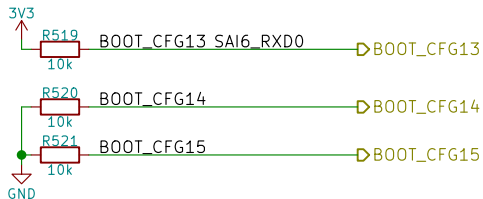
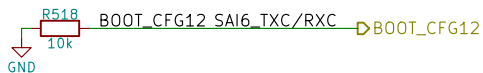
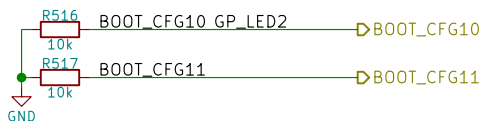
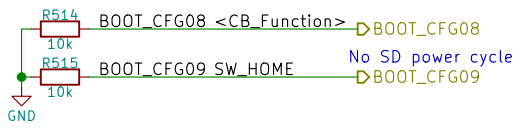
Note:
All switches' pins
can be swapped
e.g. 2<->3
or 1<->3
(+BOOT_MODE2)

2->1: eMMC 2->3: USB (Serial Downloader)	
BOOT_MODE[1:0]	Boot Type
00	Boot From Fuses
01	Serial Downloader
10	Internal Boot
11	Reserved

Only eMMC

BOOT_CFG[14:12]		Boot device			
001		SD/eSD			
010		MMC/eMMC			
011		NAND			

Fuse	Config	Definition	GPIO ¹	Shipped value	Settings
BOOT_CFG[11:10]	OEM	USDHC port selection	Yes	00	00 - USDHC-1 01 - USDHC-2 10 - USDHC-3 else - reserved



Boot Configuration

Purism

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Sheet: /Boot Config/
File: boot.sch

Size: A4
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Date: 2018-06-18

Rev: v0.1.0
Id: 5/24

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Real-Time Clock



Note:
Datasheet says slave address is 0xD0
with a R/W bit appended, since 0xD must
be 4-bits wide the actual 7-bit address is
0x68 (110 1000), and becomes 0xD0 during a
write operation (1101 0000)

Reference:
https://github.com/HIO-Project/linux-imx6-nano-imx_3.10.17_1.0.1_ga/blob/8848e94b2f889fe44f6736e2d4c98851a2282275/arch/arm/boot/dts/imx6qdl-mtp.dtsi#L351

RTC



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Sheet: /RTC/

File: rtc.sch

Size: A4

Date: 2018-06-18

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Rev: v0.1.0

Id: 6/24

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[illegible]

Purism

Rev: v0.1.0
Id: 7/24

JTAG



JTAG



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Sheet: /JTAG/

File: jtag.sch

Size: A4 Date: 2018-06-18

KiCad E.D.A. kicad 4.0.6

eric.kuzmenko@puri.sm

angus.ainstlie@puri.sm

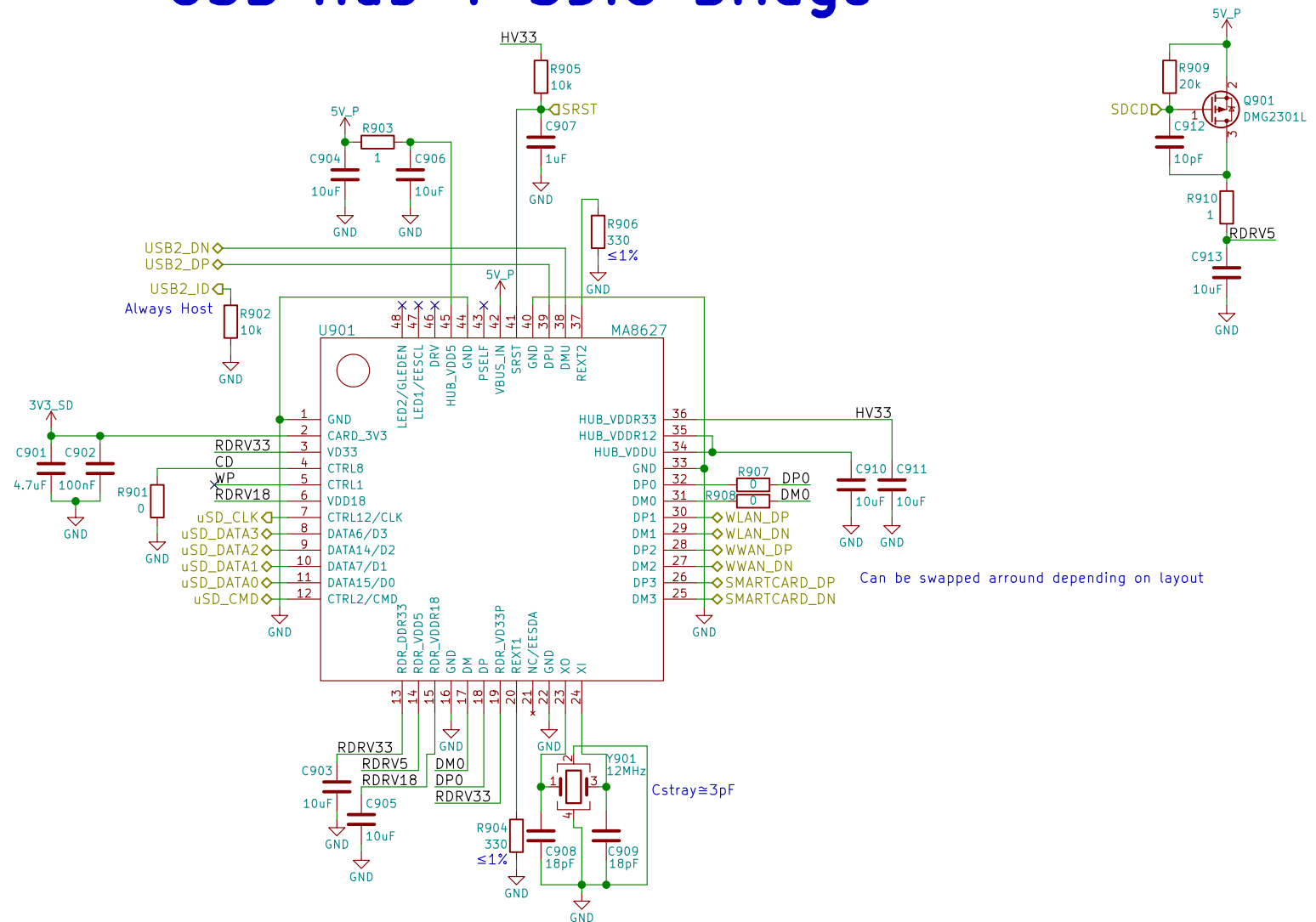
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Rev: v0.1.0

Id: 8/24

USB Hub + SDIO Bridge



USB Hub + SDIO Bridge



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Sheet: /USB Hub + SDIO Bridge/

File: usb_hub_sdio.sch

Size: A4	Date: 2018-06-18
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Size: A4	Date:
KiCad E.D.A.	kicad 4.0.6

eric.kuzmenko@puri.sm

angus.ainslie@puri.sm

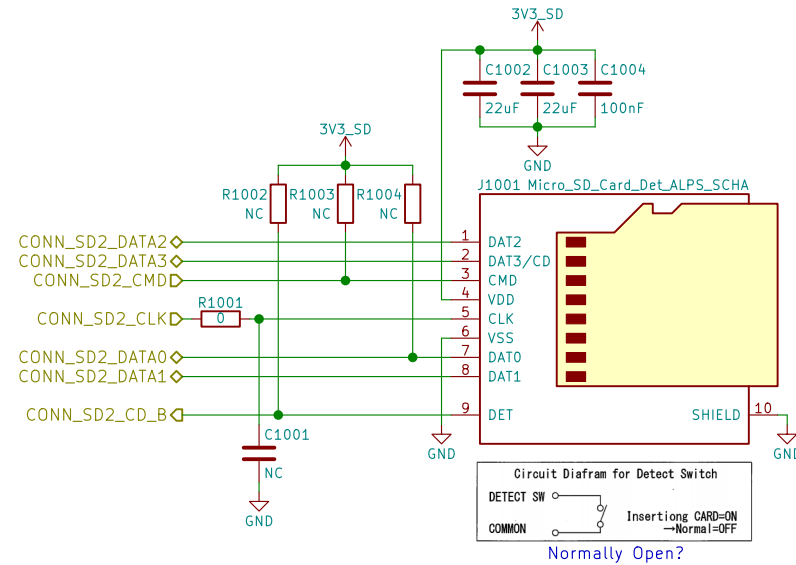
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Rev: v0.1.0

Id: 9/24

μSD



uSD Card



Purism

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Sheet: /uSD Card/

File: sd.sch

Size: A4

Date: 2018-06-18

KiCad E.D.A. kicad 4.0.6

Rev: v0.1.0

Id: 10/24

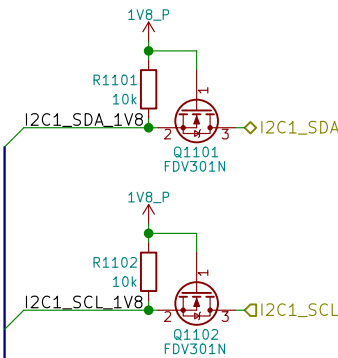
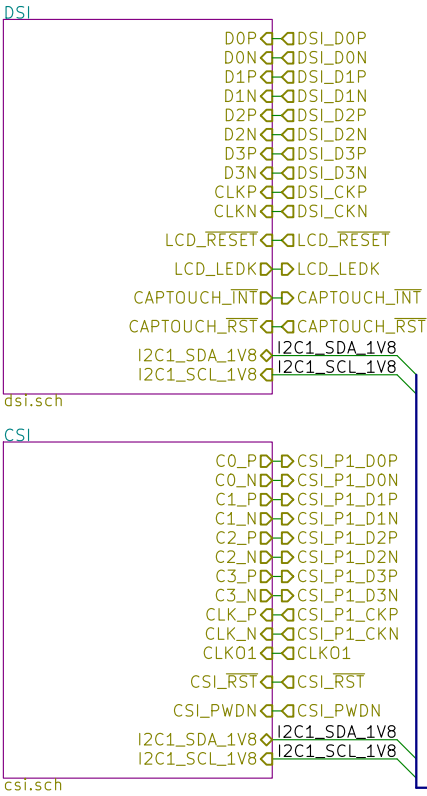
eric.kuzmenko@puri.sm

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MIPI



MIPI



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Sheet: /MIPI/

File: mipi.sch

Size: A4

Date: 2018-06-18

KiCad E.D.A. kicad 4.0.6

Rev: v0.1.0

Id: 11/24

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Display & Touch Controller

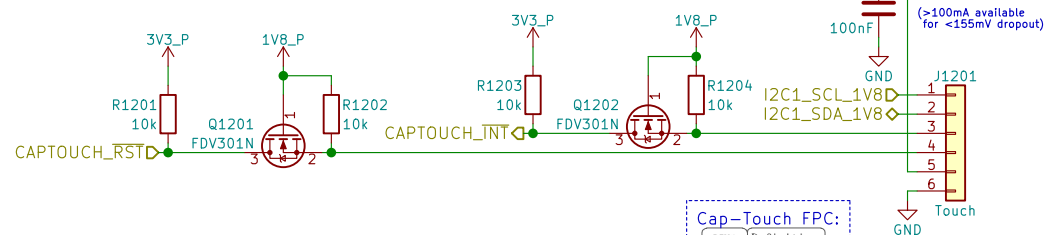
LCD PN:
Shenzhen Jinghong Electronics Co., Ltd.
JH057N00900

Note:
No power-up sequence is
given in the spec sheet

7-bit Slave Address: 0x5D
(1011 101x)

Read: 0xBB
Write: 0xBA

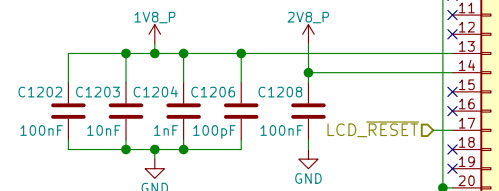
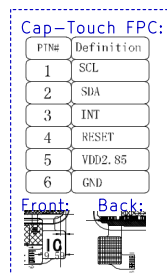
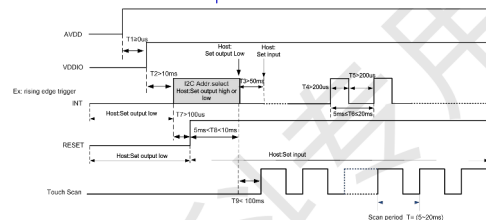
Cap-Touch Controller IC PN:
Goodix GT5688



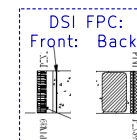
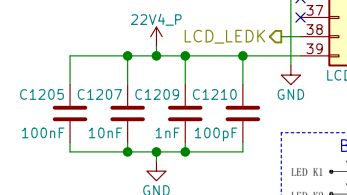
The upper 7 bits are the address,
and bit 0 is used to select read or write.
GT5688 has two slave device addresses to choose from:

	7-bit Address	8-bit Write Address	8-bit Read Address
INT LOW	0x5D	0xBA	0xBB
INT HIGH	0x14	0x28	0x29

Every time you power on or reset, you need
to use the INT pin to set the I2C address:



100Ω Differential Impedance



Backlight Array:



Display_JH057N00900

DISP1201

5.7 "
RGB
720 x 1440
pixels

FPC6
Touch

FPC39
Display +
Backlight

MIPI DSI

Purism

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Sheet: /MIPI/DSI/
File: dsi.sch

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christian.schilmoeller@puri.sm

Size: A4
KiCad E.D.A. kicad 4.0.6

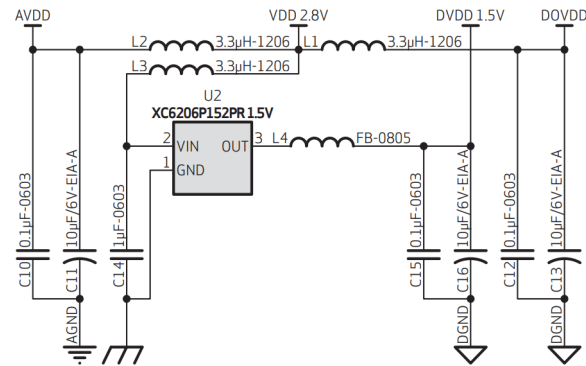
Date: 2018-06-18

Rev: v0.1.0

Id: 12/24

Camera

Using Internal DVDD 1.5V Regulator:



2.7 POWER UP SEQUENCE

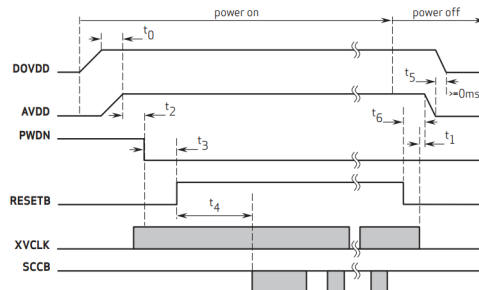
Based on the system power configuration (1.8V or 2.8V for I/O power, using external DVDD or internal DVDD, requiring access to the I2C during power up period or not), the power up sequence will differ. If 1.8V is used for I/O power, using the internal DVDD is preferred. If 2.8V is used for I/O power, due to a high voltage drop at the internal DVDD regulator, there is a potential heat issue. Hence, for a 2.8V power system, OmniVision recommends using an external DVDD source. Due to the higher power down current when using an external DVDD source, OmniVision strongly recommends cutting off all powers, including the external DVDD, when the sensor is not in use in the case of 2.8V I/O and external DVDD.

2.7.1 POWER UP WITH INTERNAL DVDD

For powering up with the internal DVDD and I2C access during the power ON period, the following conditions must occur:

1. when DOVDD and AVDD are turned ON, make sure DOVDD becomes stable before AVDD becomes stable
2. PWDN is active high with an asynchronous design (does not need clock)
3. PWDN pin tied to digital ground if it is not controlled.
4. if PWDN pin is controlled as below, for PWDN to go low, power must first become stable (AVDD to PWDN ≥ 5 ms)
5. RESETB is active low with an asynchronous design
6. master clock XVCLK should provide at least 1 ms before host accesses the sensor's registers
7. host can access I2C bus (if shared) during entire period. 20ms after RESETB goes high, host can access the sensor's registers to initialize sensor

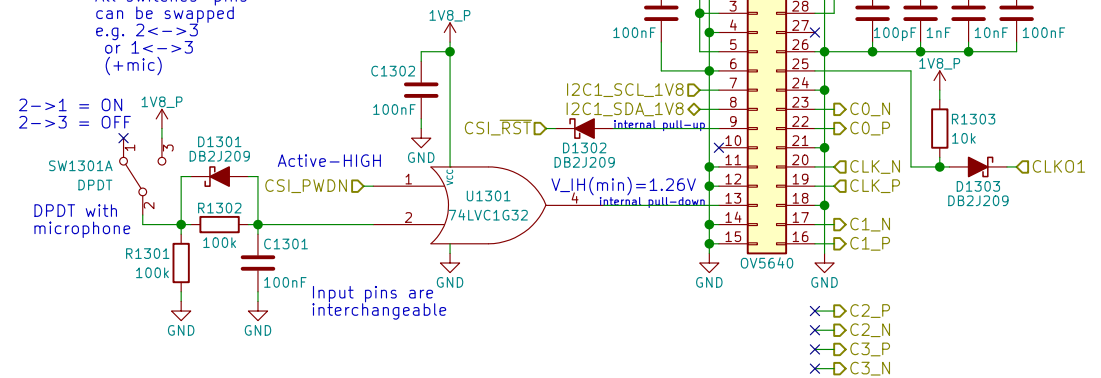
figure 2-3 power up timing with internal DVDD



note $t_0 \geq 0$ ms, delay from DOVDD stable to AVDD stable, it is recommended to power up AVDD shortly after DOVDD has been powered up
 $t_1 \geq 0$ ms, delay from XVCLK off to AVDD off
 $t_2 \geq 5$ ms, delay from AVDD stable to sensor power up stable, PWDN can be pulled low after this point. XVCLK can be turned on after power on
 $t_3 \geq 1$ ms, delay from sensor power up stable to RESETB pull up
 $t_4 \geq 20$ ms, delay from RESETB pull high to SCCB initialization
 $t_5 \geq 0$ ms, delay from AVDD off to DOVDD off
 $t_6 \geq 0$ ms, delay from RESETB pull low to AVDD off

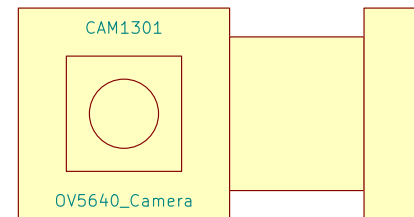
5640_05_2.2

Note:
All switches' pins can be swapped
e.g. 2<->3
or 1<->3
(+mic)



Camera PN:
Truly C08725-B5SA-E
7-bit Slave Address: 0x78
(1111 000x)
Read: 0xF1
Write 0xF0

OV5640 CMOS Image Sensor Datasheet:
https://cdn.sparkfun.com/datasheets/Sensors/LightImaging/OV5640_datasheet.pdf



MIPI CSI

Purism

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Sheet: /MIPI/CSI/
File: csi.sch

Size: A4 Date: 2018-06-18

KiCad E.D.A. kicad 4.0.6

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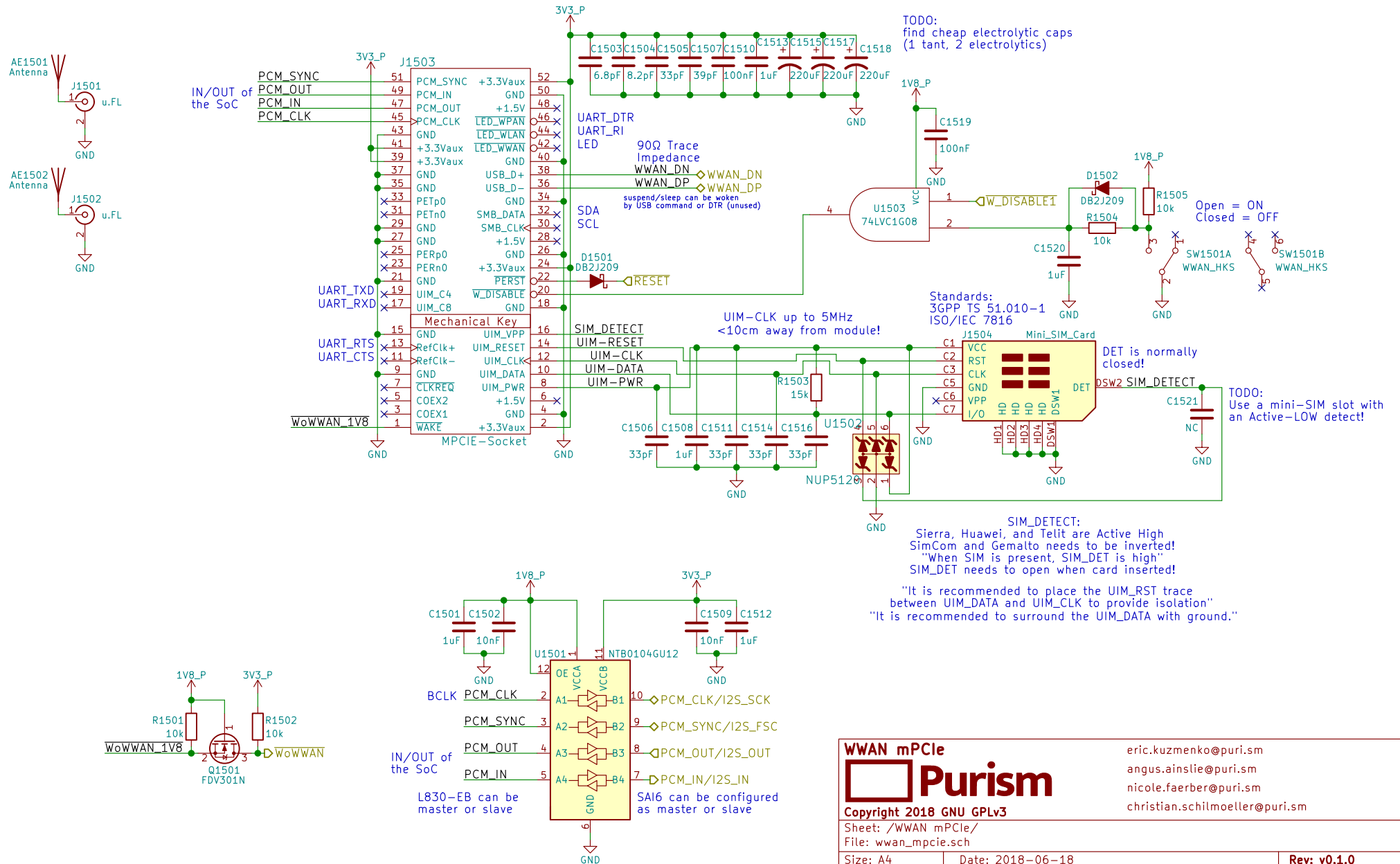
Rev: v0.1.0

Id: 13/24

C

D

WWAN mPCIe



WWAN mPCIe		eric.kuzmenko@puri.sm	
		angus.ainstlie@puri.sm	
Copyright 2018 GNU GPLv3		nicole.faeber@puri.sm	
Sheet: /WWAN mPCIe/		christian.schilmoeller@puri.sm	
File: wwan_mpcie.sch			
Size: A4	Date: 2018-06-18	Rev: v0.1.0	
KiCad E.D.A. kicad 4.0.6	Id: 15/24		

Audio

Reference:
http://www.52rd.com/S_txt/2011_3/TXT26685.htm
<http://www.sengpielaudio.com/calculator-transferfactor.htm>
<https://electronics.stackexchange.com/questions/31442/how-can-i-switch-this-audio-jack-using-its-own-mechanical-switches-without-cre>
 (Nit6 does the same)
 +Zener diode to protect against ranges outside of -0.9V to 3.3V

dB specs in datasheet is a unit of power gain (not dBu or VU) with respect to the DAC's unattenuated output

"HP Output - 62.5mW max, 1.02kHz sine into 16Ω load at 3.3 V"
 $\Rightarrow (1V)^2/(16\Omega)=62.5mW$
 $\therefore V_{rms}=1V \Rightarrow V_p(\text{amplitude})=1.414V$
 $\therefore I_{rms}(\text{max})=62.5mA$

If HP_DET is HIGH for >100ms then HPs are present

S/E button on earbud headsets shorts the mic for key function

Could use FSA8008 to detect mic



$Z(\text{hp}) \geq 16\Omega$

Pin 5 (tip switch) is NC, open when inserted
 If just headphones then HP_DET=HIGH, R(mic)=0

may add ~220uF cap parallel to Zener

Ext-Mic enabled MIC_SEL=LOW
 Int-Mic enabled MIC_SEL=LOW
 Add TVS next to int-mic? (OpenMoko does this)
 $-37dB=14.1254mV/Pa$
 $\therefore \text{mic produces } 14.1254mV_{rms} \text{ when exposed to a } 1kHz \text{ tone of } 94dB-SPL \text{ at the capsule (or } 19.98mV \text{ amplitude)}$
 $\Rightarrow 40dB \text{ gain would produce } -2V \text{ amplitude (4Vpp, clipping)}$
 $30dB \text{ gain would produce } -0.632V \text{ amplitude (1.264Vpp)}$
 $38.33dB \text{ gain would yield } 3.3V_{pp}$

LCR Measurements:

Earbud Microphone: @1kHz
 $L_s = 3.844mH$
 $L_p = 15.757H$
 $C_s = 6.583uF$
 $C_p = 1612.8pF$
 $R_s = 1.5465k\Omega$
 $R_p = 1.5478k\Omega$
 $\theta = -0.8deg$

Headset Speaker: @1kHz
 $L_s = 244.4uH$
 $L_p = 141.99mH$
 $C_s = 103.6uF$
 $C_p = 178.77nF$
 $R_s = 36.860\Omega$
 $R_p = 36.860\Omega$
 $\theta = -2.3deg$

Earbud Speaker: @1kHz
 $L_s = 25.2uH$
 $L_p = 311.0mH$
 $C_s = 1.0mF$
 $C_p = 81.95nF$
 $R_s = 17.0300\Omega$
 $R_p = 17.0340\Omega$
 $\theta = 0.5deg$

Audio

Purism

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Sheet: /Audio/
 File: audio.sch

Size: A4 Date: 2018-06-18

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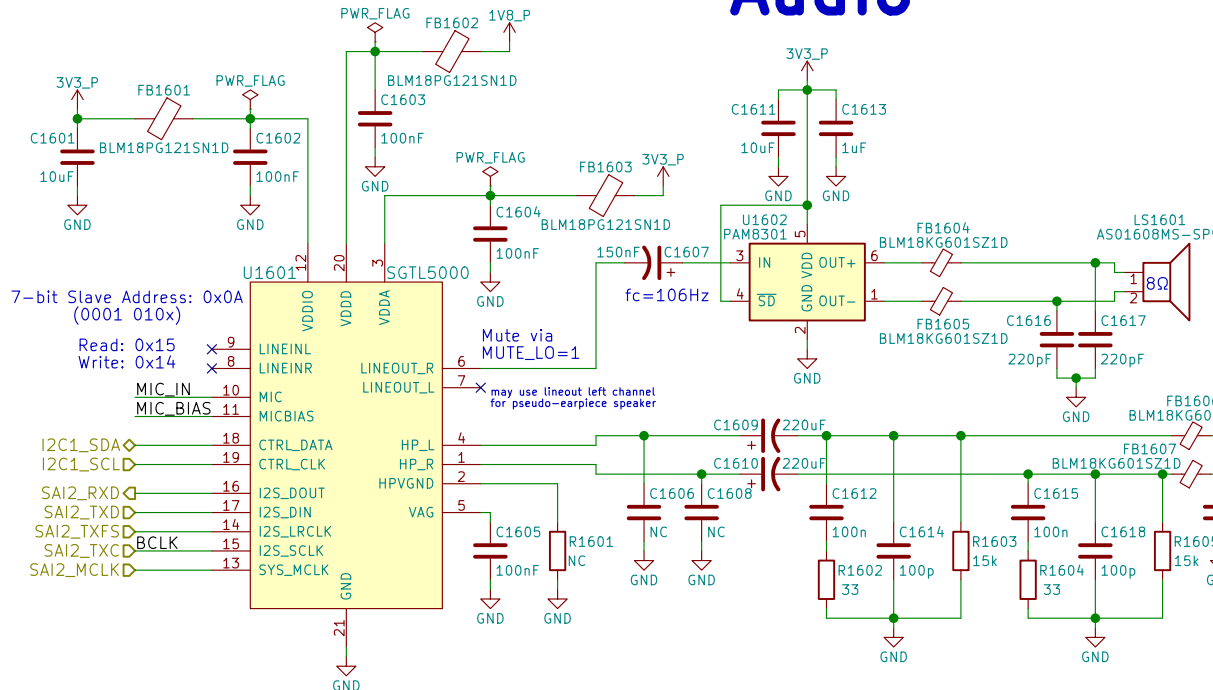
angus.ainslie@puri.sm

nicole.farber@puri.sm

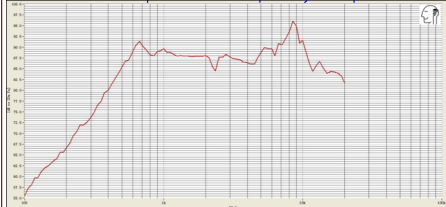
christian.schilmoeller@puri.sm

Rev: v0.1.0

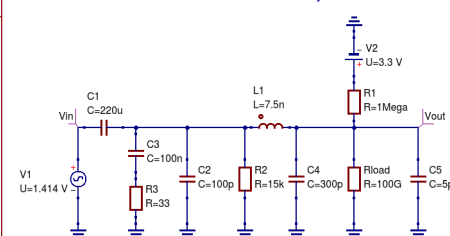
Id: 16/24



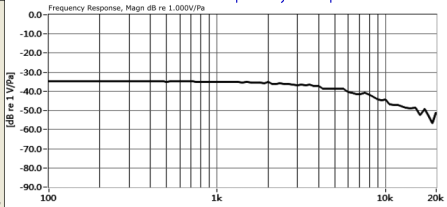
Built-In Speaker's Frequency Response:



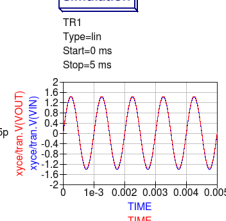
Simulation of HP_DET @ 1kHz output without HP jack inserted:



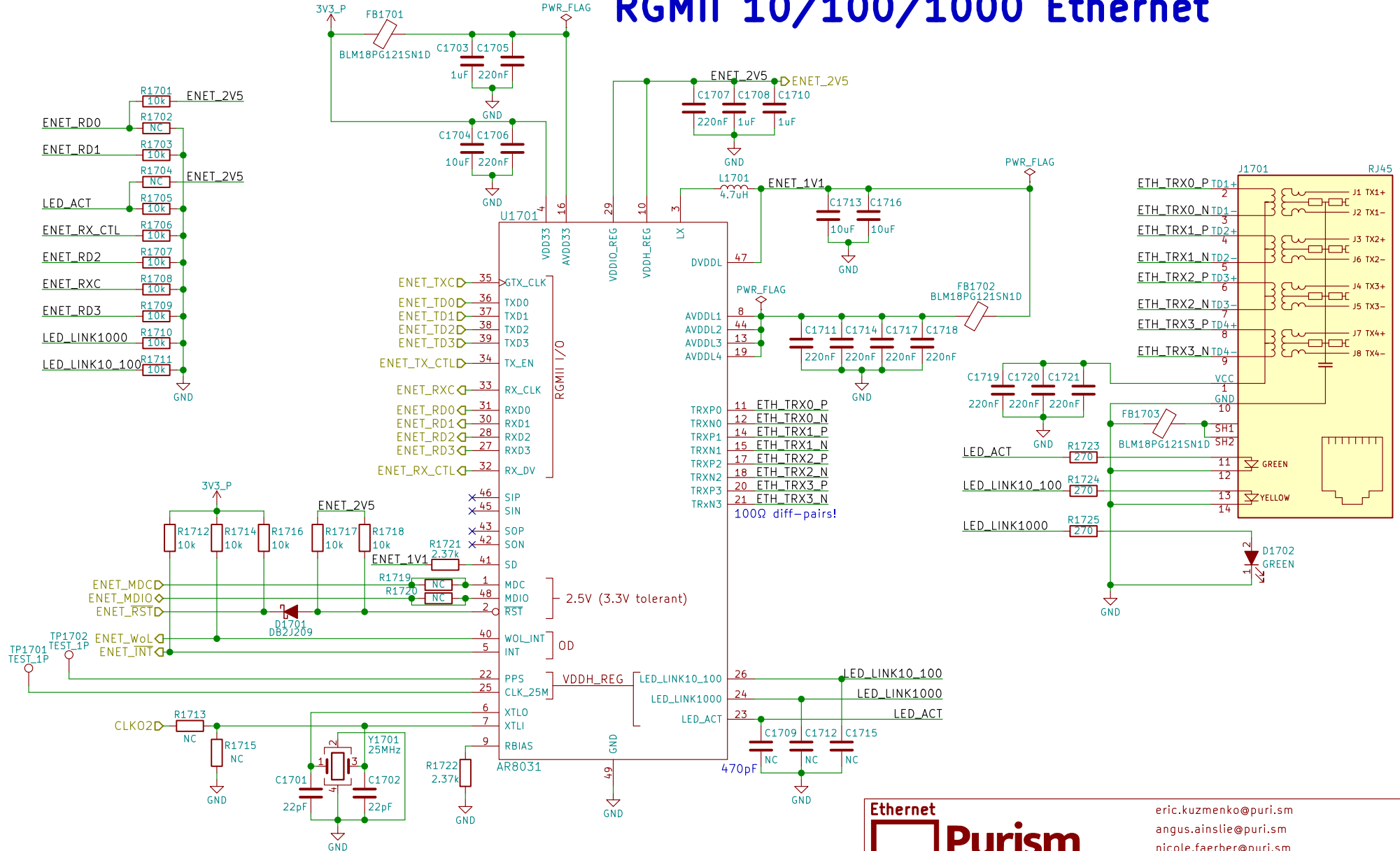
Built-In Mic's Frequency Response:



transient simulation



RGMII 10/100/1000 Ethernet



Ethernet

Purism

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Sheet: /Ethernet/
File: ethernet.sch

Size: A4 Date: 2018-06-18
KiCad E.D.A. kicad 4.0.6

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christian.schilmoeller@puri.sm

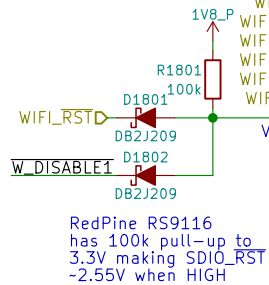
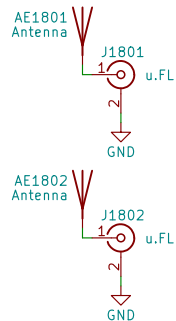
Rev: v0.1.0

Id: 17/24

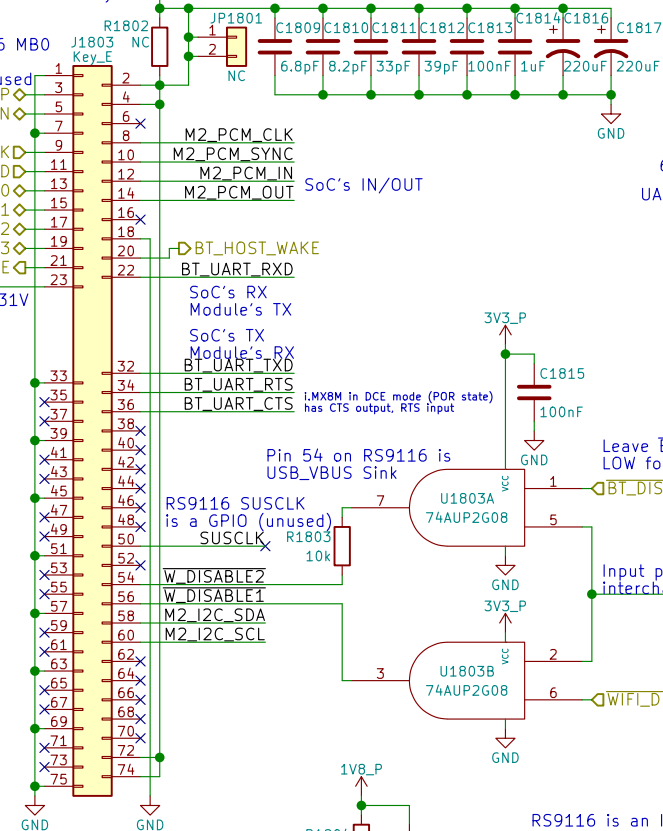
WLAN+BT M.2

RS9116 NC:
RTS, CTS, BT_HOST_WAKE

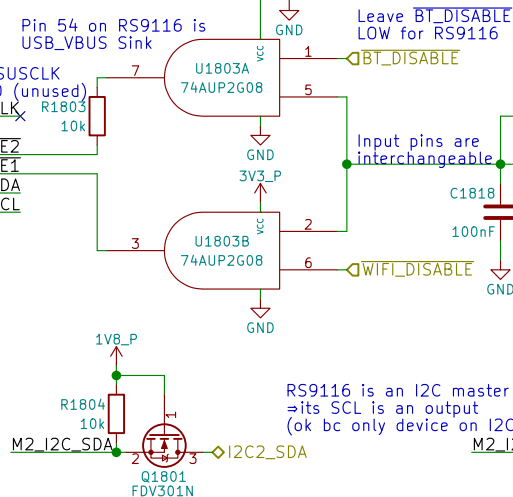
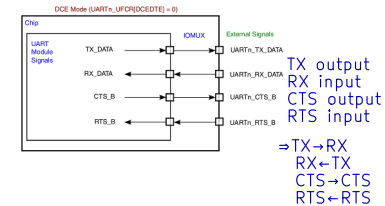
RS9116 datasheet says
no WIFI_WAKE
but the schematic has it



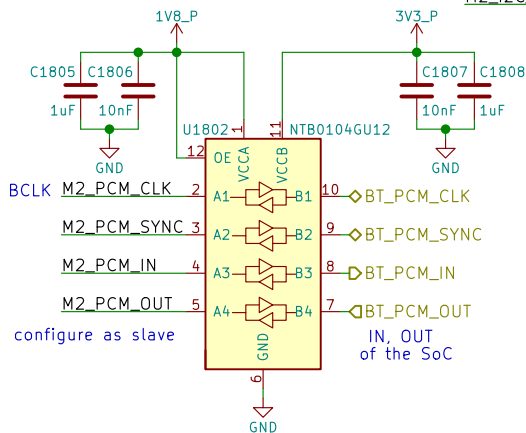
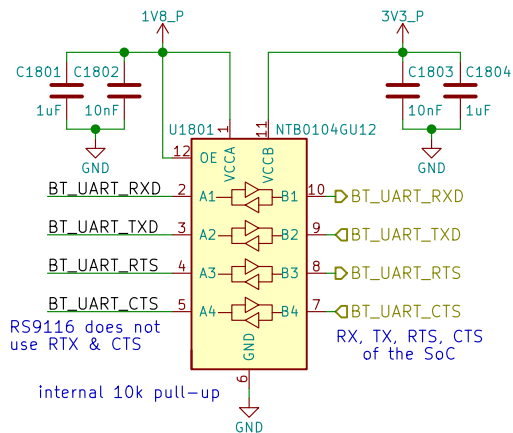
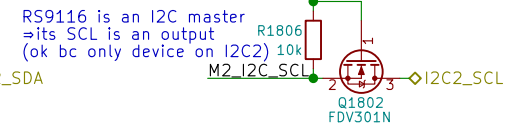
Module: Table 23
Socket: Table 46
3V3_P
M.2 Key E



6.2 M.2 Signal Directions
UARTn_UFCR[DCEDTE]=0 on POR



Note:
All switches' pins
can be swapped
e.g. 2<->3
or 1<->3
SW1801A
WLAN_HKS
Open = ON
Closed = OFF



WLAN+BT M.2

Purism

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Sheet: /WLAN+BT M.2/
File: wifi_bt_m2.sch

Size: A4 Date: 2018-06-18
KiCad E.D.A. kicad 4.0.6

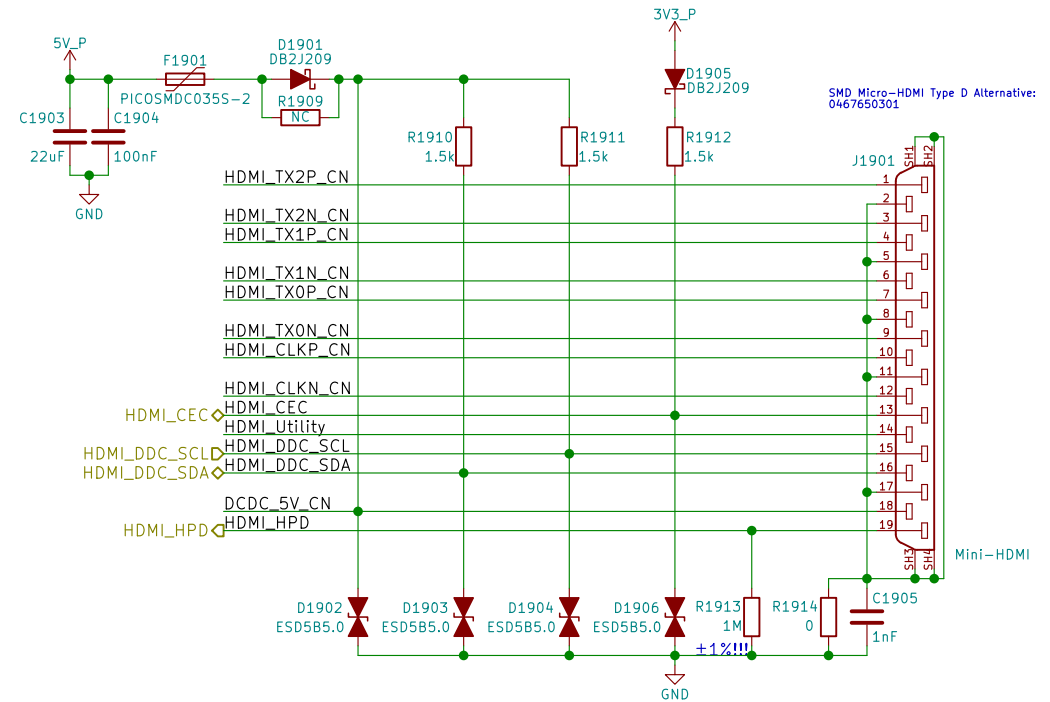
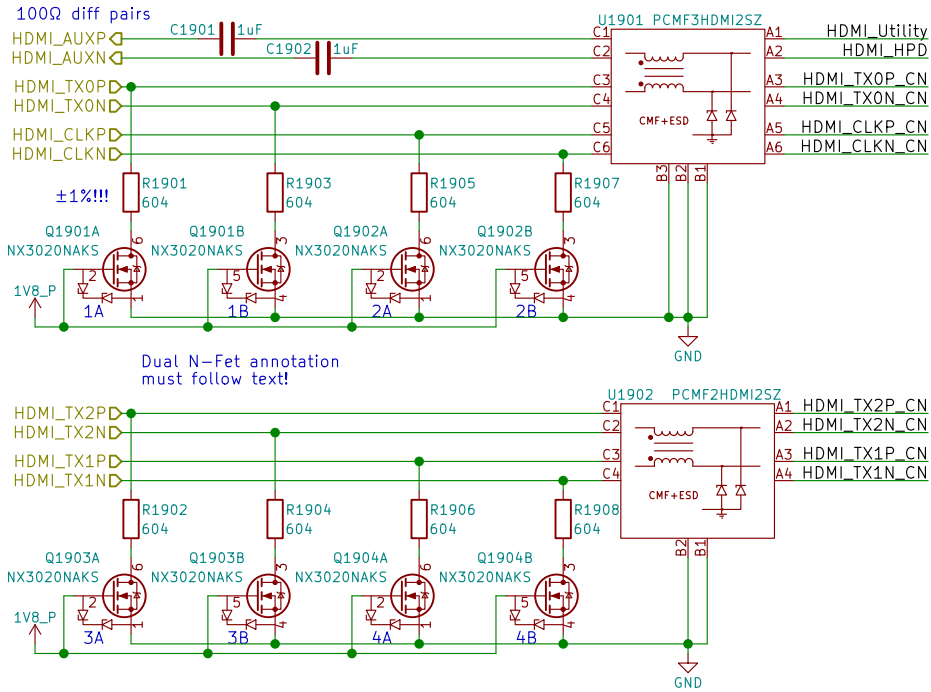
eric.kuzmenko@puri.sm
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nicole.farber@puri.sm
christian.schilmoeller@puri.sm

Rev: v0.1.0
Id: 18/24

TUSB1046 can be used for DP over USB-C

HDMI

Layout Note:
May need swap some signals
due to micro-HDMI pinout diff
depending on pin location/routing



HDMI



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Sheet: /HDMI/
File: hdmi.sch

Size: A4
KiCad E.D.A. kicad 4.0.6

Date: 2018-06-18

Rev: v0.1.0
Id: 19/24

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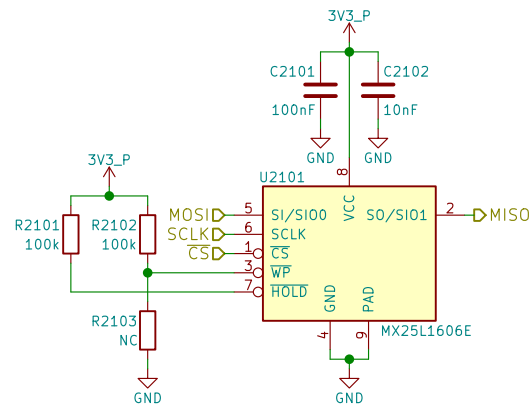


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SPI NOR Flash



SPI NOR Flash



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Sheet: /SPI Flash/
File: flash.sch

Size: A4 Date: 2018-06-18

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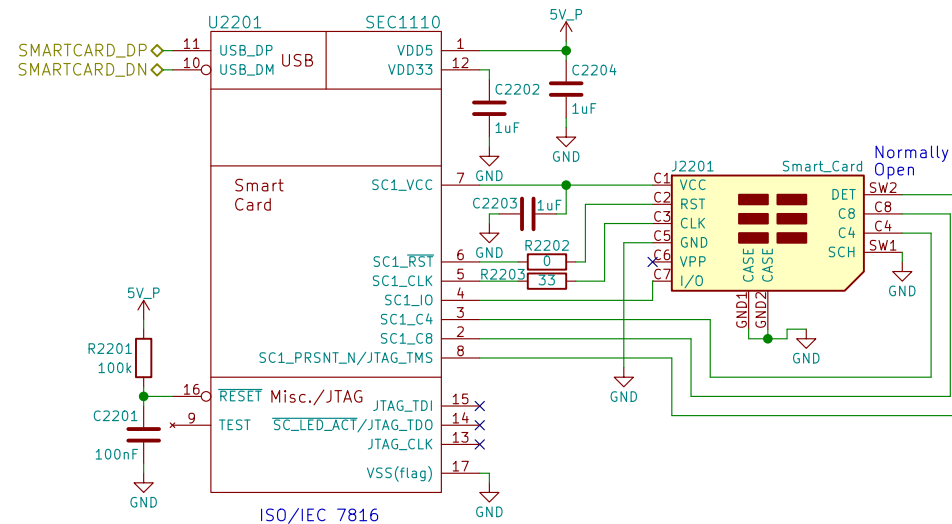
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Rev: v0.1.0

Id: 21/24

Smart Card



Reference:
<http://www.microchip.com/DevelopmentTools/ProductDetails.aspx?PartNO=EVB-SEC1110>

Smart Card



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Sheet: /Smart Card/

File: smartcard.sch

Size: A4 Date: 2018-06-18

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The diagram illustrates the connection of a GNSS module (U2301 MAX-M8Q) to an ESP32. The GNSS module's pins are connected to the ESP32's pins as follows:

- VCC** (Pin 8) to **VCC** (Pin 1)
- VCC_IO** (Pin 7) to **VCC_IO** (Pin 2)
- V_BACKUP** (Pin 6) to **V_BACKUP** (Pin 3)
- EXT_INT** (Pin 5) to **EXT_INT** (Pin 4)
- RESET_N** (Pin 9) to **RESET_N** (Pin 5)
- TIMEPULSE** (Pin 4) to **TIMEPULSE** (Pin 6)

The GNSS module also has a **RF_IN** pin (Pin 11) connected to the **VCC_RF** pin (Pin 14) via a matching circuit (L2302, C2306, C2307). The **VCC_RF** pin is connected to the antenna via a matching circuit (L2301, C2305, 33nH, 22pF, 10Ω). The **RF_IN** pin is also connected to the **RF_IN** pin (Pin 11) via a matching circuit (L2302, C2306, C2307). The **RF_IN** pin is also connected to the **RF_IN** pin (Pin 11) via a matching circuit (L2302, C2306, C2307).

The GNSS module also has a **TXD** pin (Pin 2) connected to the **UART3_RXD** pin (Pin 16) and a **RXD** pin (Pin 3) connected to the **UART3_TXD** pin (Pin 17). The GNSS module also has a **SDA** pin (Pin 16) connected to the **SDA** pin (Pin 16) and a **SCL** pin (Pin 17) connected to the **SCL** pin (Pin 17).

The GNSS module also has a **SAFEBOOT/RESV** pin (Pin 18) connected to the **SAFEBOOT/RESV** pin (Pin 18). The GNSS module also has a **ANT_ON/RESV** pin (Pin 13) connected to the **ANT_ON/RESV** pin (Pin 13). The GNSS module also has a **V_ANT/RESV** pin (Pin 15) connected to the **V_ANT/RESV** pin (Pin 15).

The GNSS module also has a **SAFEBOOT/RESV** pin (Pin 18) connected to the **SAFEBOOT/RESV** pin (Pin 18). The GNSS module also has a **ANT_ON/RESV** pin (Pin 13) connected to the **ANT_ON/RESV** pin (Pin 13). The GNSS module also has a **V_ANT/RESV** pin (Pin 15) connected to the **V_ANT/RESV** pin (Pin 15).

https://www.u-blox.com/sites/default/files/MAX-M8_HardwareIntegrationManual_L%28UBX-13004876%29.pdf
https://www.u-blox.com/sites/default/files/MAX-8-M8-FW3_HardwareIntegrationManual_L%28UBX-15030059%29.pdf

 Purism

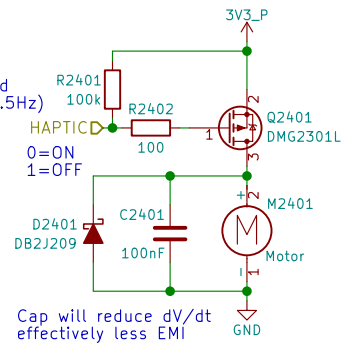
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Id: 23/24

Haptic Motor

PWM pins occupied:
 GPIO1_I001 - LCD Backlight
 GPIO1_I013 - LED
 GPIO1_I014 - Ethernet (CLKO_25MHz)
 GPIO1_I015 - CSI (CLKO2)

PWM needed?
 Only needs to be toggled
 ON 1 sec, OFF 1 sec (0.5Hz)
 Can MUX as either
 GPIO or PWM2
 swapping with LED



When the motor is off
 both terminals are at GND

Motor will have wire leads
 with a 2-pin Molex or Boom Precision
 connector installed (by request!)
 Metal housing is floating
 (not connected to either pin)
 => could connect housing to GND

Cheaper Motor Connector:
https://lcsc.com/product-detail/1-25T-Connectors_1-25T-1-2AW_C10832.html

Motor Source:
https://www.alibaba.com/product-detail/Coin-motor-vibration-dc-motor-cellphone_1994583657.html?spm=a2700.8443308.0.0.5aa13e5f1wxHgs

Motor Datasheet:
<https://cloud.puri.sm/s/z8JR6DJ4KrJYzoW>

Motor PN:
 BY0820Z021L20

Haptic/Vibration Motor



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Sheet: /Haptic Motor/
 File: haptic.sch

Size: A4 Date: 2018-06-18

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