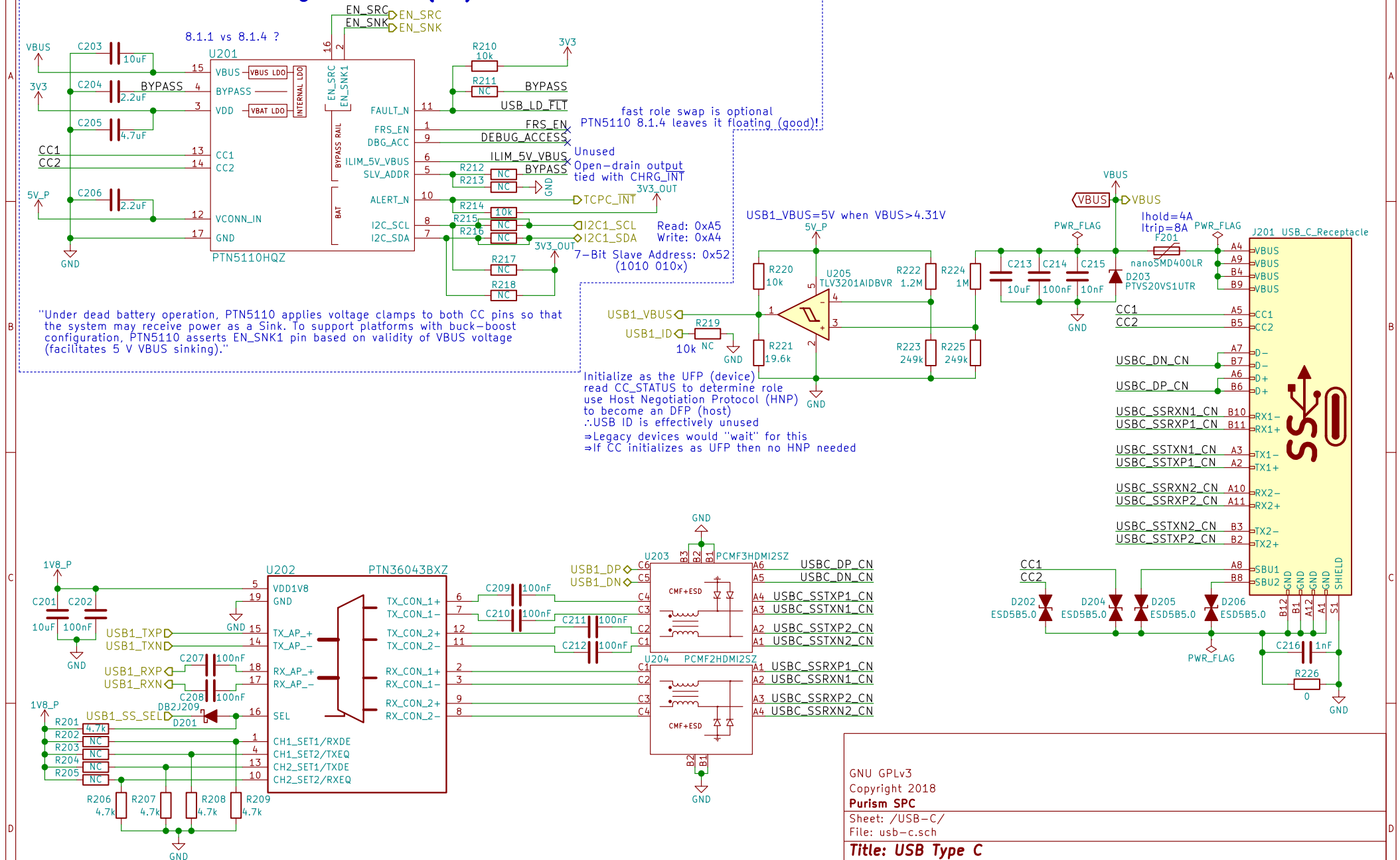


USB-C TCPC – Config Channel (CC) and PD Role Controller



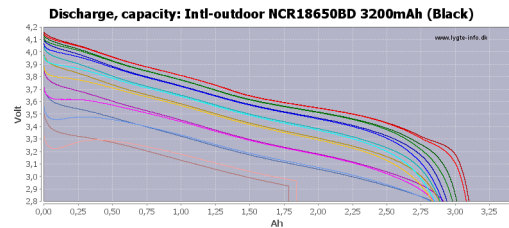
GNU GPLv3
Copyright 2018
Purism SPC

Sheet: /USB-C/
File: usb-c.sch

Title: USB Type C

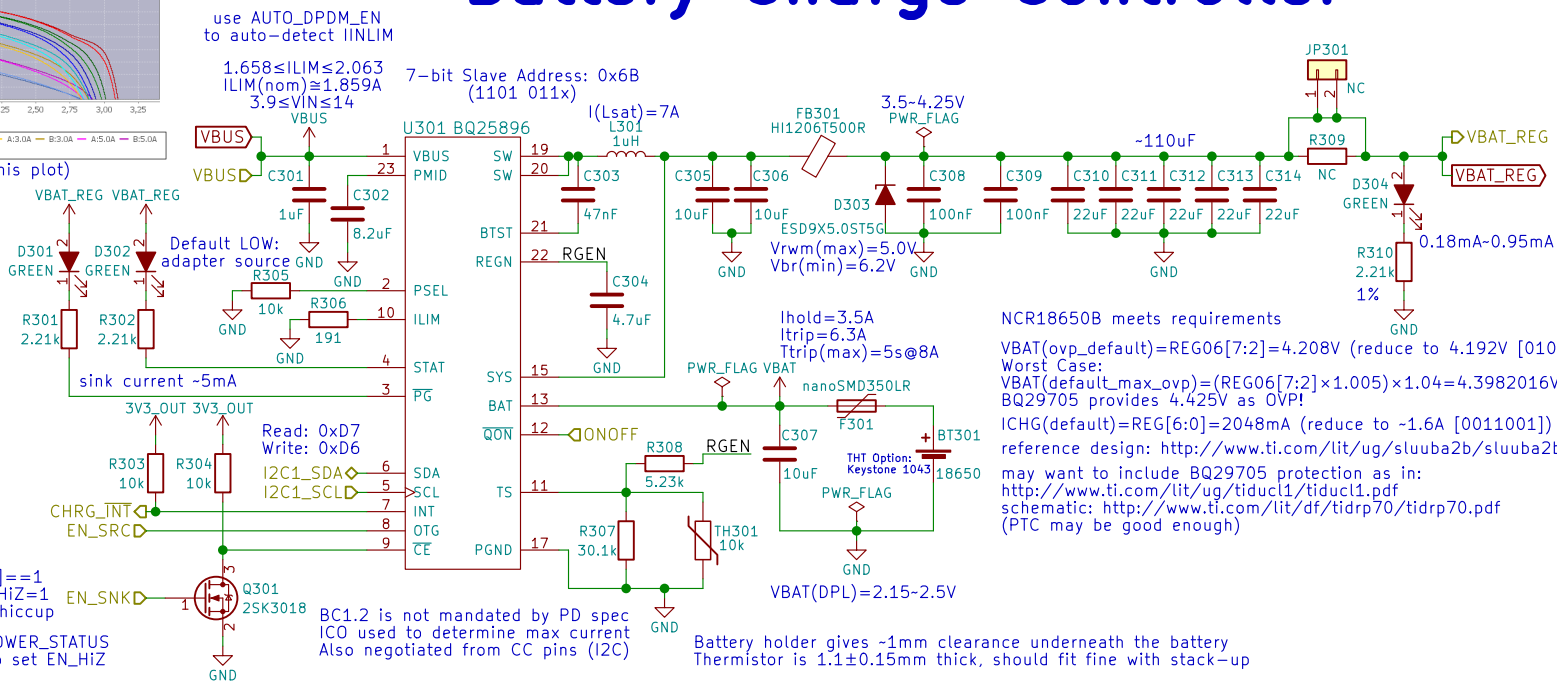
Size: A4	Date: 2018-06-07
KiCad E.D.A. kicad 4.0.6	

Rev: v0.1.0
Id: 2/24



(interpret RSOC% based on this plot)

Drawing ~333.33mA, or consuming <1.2W, should give close to 10 hours going from 100% to 0% charge



Reading PTN5110HQ's CC_STATUS and POWER_STATUS registers will tell TCPM (i.MX8M) when to set EN_HI_Z

Also, reading PTN5110HQ's CC_STATUS and POWER_STATUS registers will tell TCPM (i.MX8M) when to set OTG_CONFIG=1 (this will also happen when PTN5110HQ sets EN_SRC HIGH)

Battery holder gives ~1mm clearance underneath the battery Thermistor is 1.1±0.15mm thick, should fit fine with stack-up

Battery holder seems to fit up to ~68.88mm long batteries need to test 18650 protected cells which are ~69.35mm long

GNU GPLv3

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Purism SPC

Sheet: /Battery/

File: battery.sch

Title: Battery

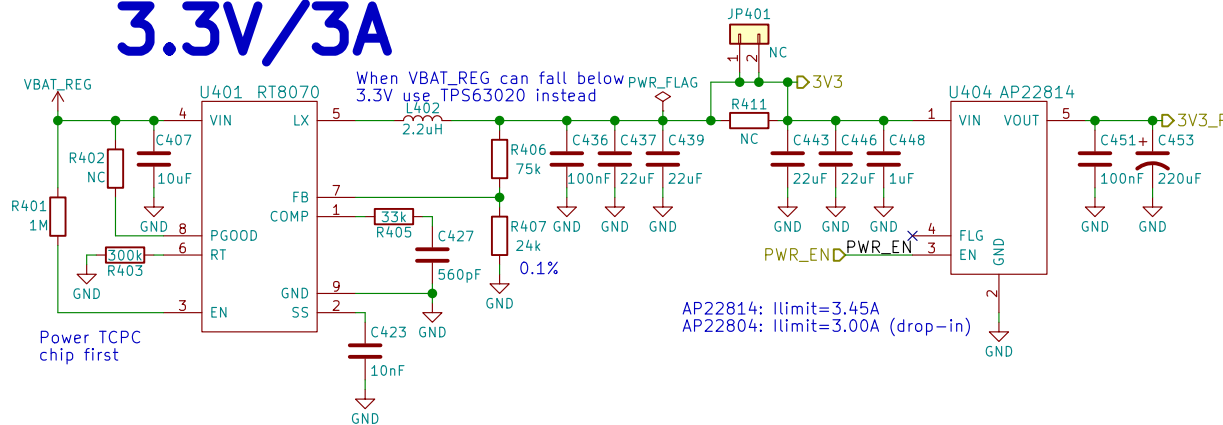
Size: A4 Date: 2018-06-07

KiCad E.D.A. kicad 4.0.6

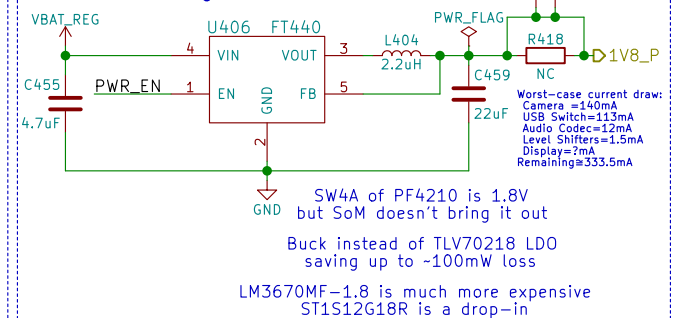
Rev: v0.1.0

Id: 3/24

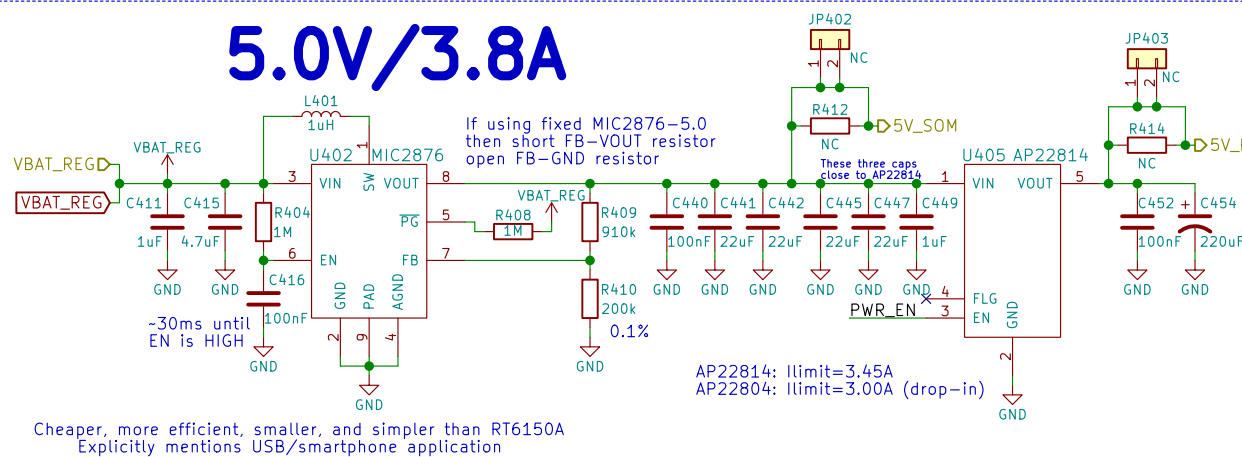
3.3V/3A



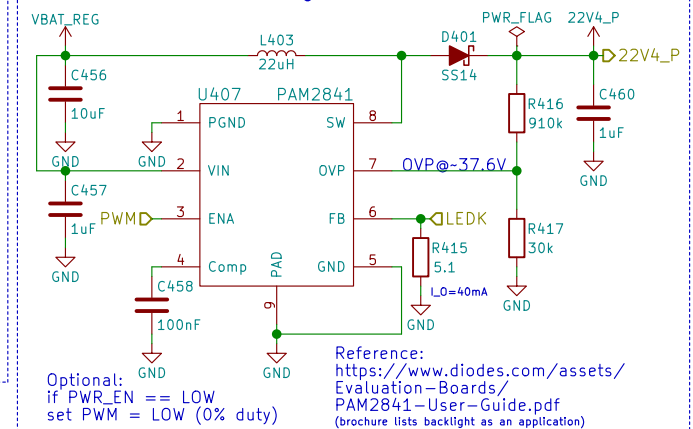
1.8V/600mA



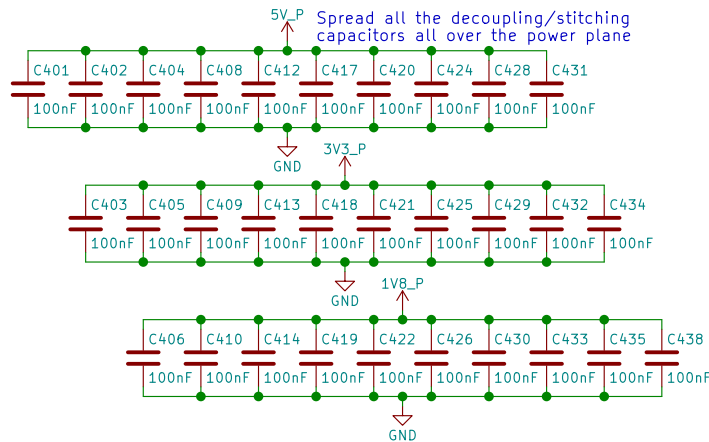
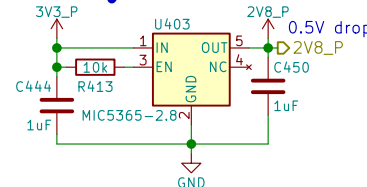
5.0V/3.8A



22.4V/40mA



2.8V/150mA



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Purism SPC

Sheet: /Power/
File: power.sch

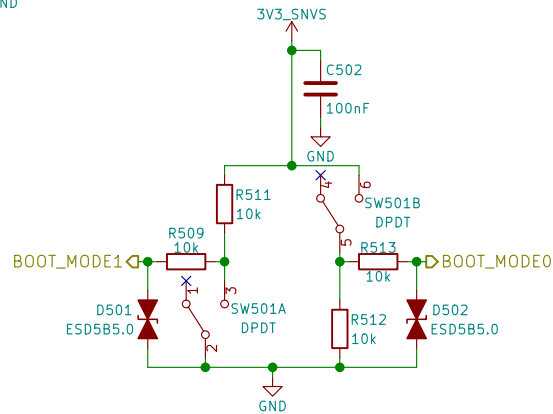
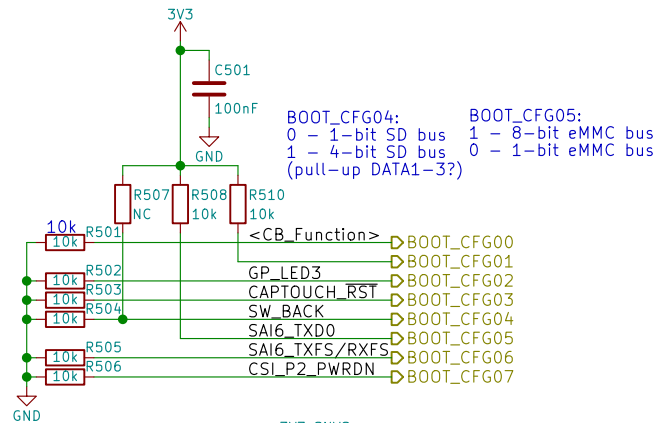
Title: Power

Size: A4
KiCad E.D.A. kicad 4.0.6

Date: 2018-06-07

Rev: v0.1.0

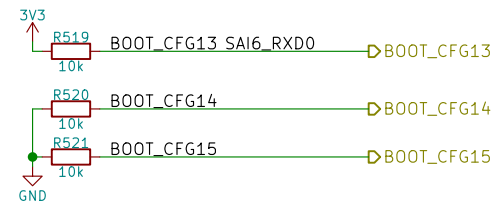
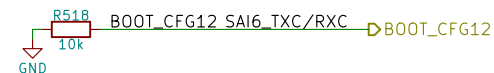
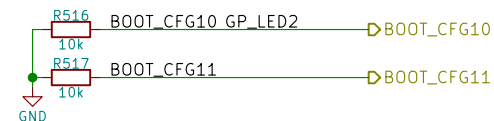
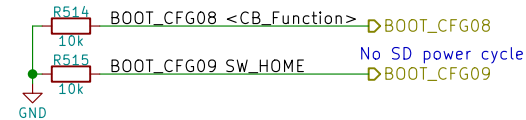
Id: 4/24



BOOT_MODE[1:0]		Boot Type
00	2->1: eMMC	Boot From Fuses
01	2->3: USB (Serial Downloader)	Serial Downloader
10		Internal Boot
11		Reserved

BOOT_CFG[14:12]		Boot device
001		SD/eSD
010		MMC/eMMC
011		NAND

Fuse	Config	Definition	GPIO ¹	Shipped value	Settings
BOOT_CFG[11:10]	OEM	USDHC port selection	Yes	00	00 - USDHC-1 01 - USDHC-2 10 - USDHC-3 else - reserved



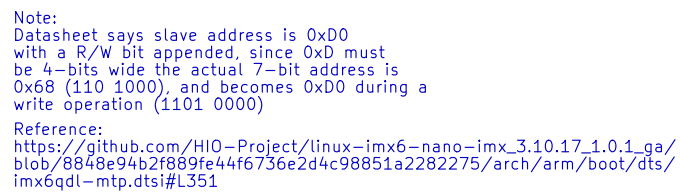
GNU GPLv3
 Copyright 2018
 Purism SPC

Sheet: /Boot Config/
 File: boot.sch

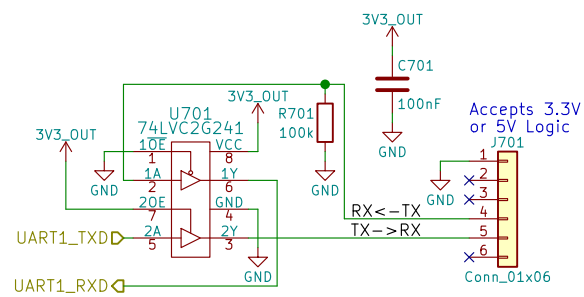
Title: Boot Configuration

Size: A4 Date: 2018-06-07
 KiCad E.D.A. kicad 4.0.6

Rev: v0.1.0
 Id: 5/24



Id: 6/24



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Sheet: /UART Debug/
File: uart.sch

Title: UART Debug

Size: A4 Date: 2018-06-07

KiCad E.D.A. kicad 4.0.6

Rev: v0.1.0

Id: 7/24



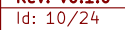
GNU GPLv3
Copyright 2018
Purism SPC
Sheet: /JTAG/
File: jtag.sch

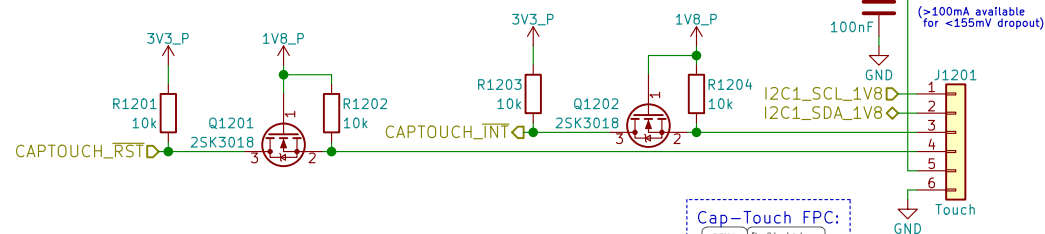
Title: JTAG

Size: A4 Date: 2018-06-07
KiCad E.D.A. kicad 4.0.6

Rev: v0.1.0
Id: 8/24

Id: 9/24

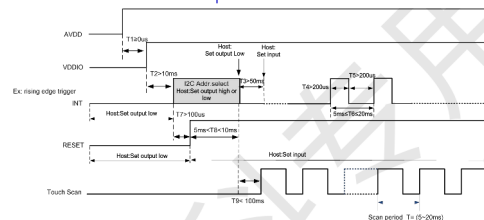




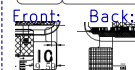
The upper 7 bits are the address, and bit 0 is used to select read or write. GT5688 has two slave device addresses to choose from:

INT	7-Bit Address	8-Bit Write Address	8-Bit Read Address
LOW	0x5D	0xBA	0xBB
HIGH	0x14	0x28	0x29

Every time you power on or reset, you need to use the INT pin to set the I2C address:

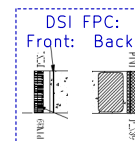
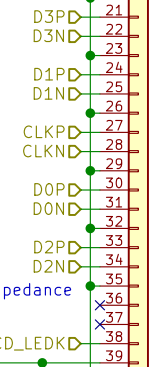
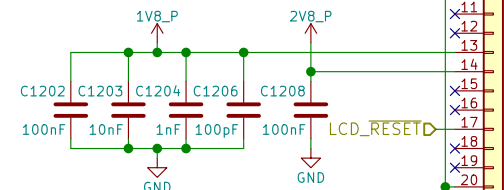


Pin#	Definition
1	SCL
2	SDA
3	INT
4	RESET
5	VDD2_R5
6	GND

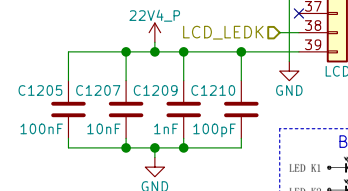


LCD PN:
Shenzhen Jinghong Electronics Co., Ltd.
JH057N00900

Note:
No power-up sequence is given in the spec sheet



100Ω Differential Impedance



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Purism SPC

Sheet: /MIPI/DSI/
File: dsi.sch

Title: MIPI DSI

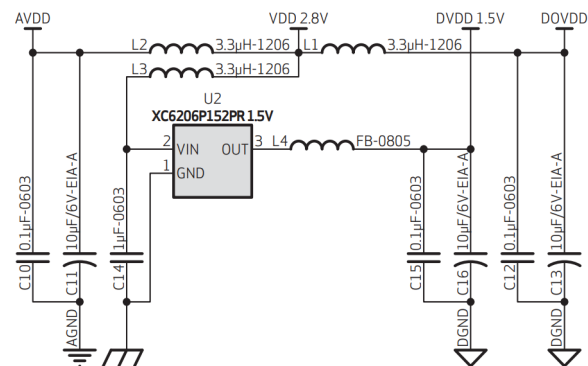
Size: A4 Date: 2018-06-07

KiCad E.D.A. kicad 4.0.6

Rev: v0.1.0

Id: 12/24

Using Internal DVDD 1.5V Regulator:



2.7 POWER UP SEQUENCE

Based on the system power configuration (1.8V or 2.8V for I/O power, using external DVDD or internal DVDD, requiring access to the I2C during power up period or not), the power up sequence will differ. If 1.8V is used for I/O power, using the internal DVDD is preferred. If 2.8V is used for I/O power, due to a high voltage drop at the internal DVDD regulator, there is a potential heat issue. Hence, for a 2.8V power system, OmniVision recommends using an external DVDD source. Due to the higher power down current when using an external DVDD source, OmniVision strongly recommends cutting off all powers, including the external DVDD, when the sensor is not in use in the case of 2.8V I/O and external DVDD.

2.7.1 POWER UP WITH INTERNAL DVDD

For powering up with the internal DVDD and I2C access during the power ON period, the following conditions must occur:

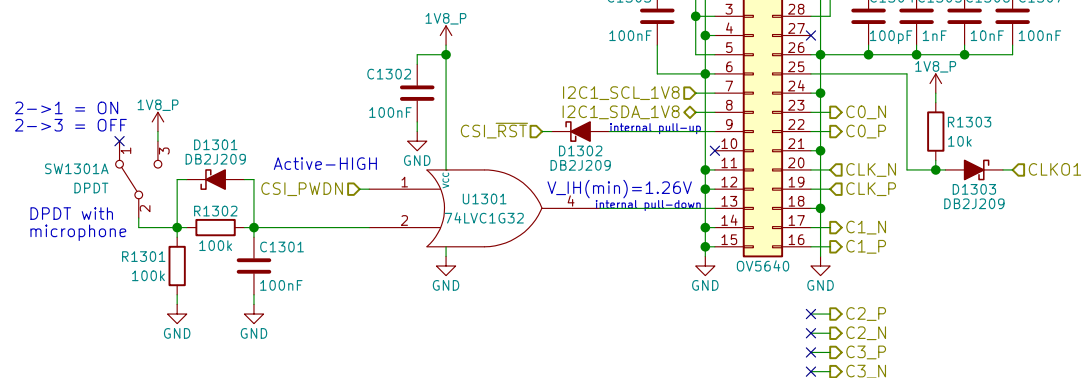
1. when DOVDD and AVDD are turned ON, make sure DOVDD becomes stable before AVDD becomes stable
2. PWDN is active high with an asynchronized design (does not need clock)
3. PWDN pin tied to digital ground if it is not controlled.
4. if PWDN pin is controlled as below, for PWDN to go low, power must first become stable (AVDD to PWDN ≥ 5 ms)
5. RESETB is active low with an asynchronized design
6. master clock XVCLK should provide at least 1 ms before host accesses the sensor's registers
7. host can access I2C bus (if shared) during entire period. 20ms after RESETB goes high, host can access the sensor's registers to initialize sensor

figure 2-3 power up timing with internal DVDD



note $t_0 \geq 0$ ms, delay from DOVDD stable to AVDD stable, it is recommended to power up AVDD shortly after DOVDD has been powered up
 $t_1 \geq 0$ ms, delay from XVCLK off to AVDD off
 $t_2 \geq 5$ ms, delay from AVDD stable to sensor power up stable, PWDN can be pulled low after this point, XVCLK can be turned on after power on
 $t_3 \geq 1$ ms, delay from sensor power up stable to RESETB pull up
 $t_4 \geq 20$ ms, delay from RESETB pull high to SCCB initialization
 $t_5 \geq 0$ ms, delay from AVDD off to DOVDD off
 $t_6 \geq 0$ ms, delay from RESETB pull low to AVDD off

5640_05_2-2



Camera PN:
 Truly C08725-B5SA-E
 7-bit Slave Address: 0x78
 (1111 000x)
 Read: 0xF1
 Write 0xF0

OV5640 CMOS Image Sensor Datasheet:
https://cdn.sparkfun.com/datasheets/Sensors/LightImaging/OV5640_datasheet.pdf

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Sheet: /MIPI/CSI/
 File: csi.sch

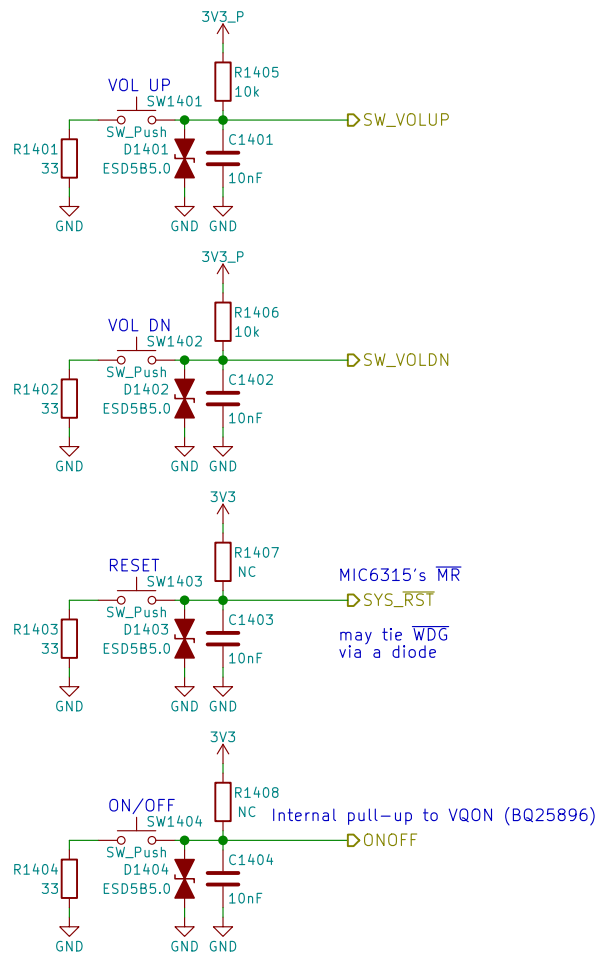
Title: MIPI CSI

Size: A4 Date: 2018-06-07

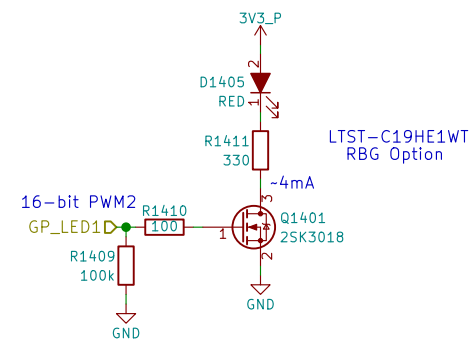
KiCad E.D.A. kicad 4.0.6

Rev: v0.1.0

Id: 13/24



Use PWM2_PWMSAR to set the compare value (duty cycle)
 Use PWM2_PWMCR[15:4] to set the PRESCALER (frequency)
 Use PWM2_PWMPR to set the top of the counter (frequency)



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Purism SPC

Sheet: /Buttons & LED/
 File: buttons_led.sch

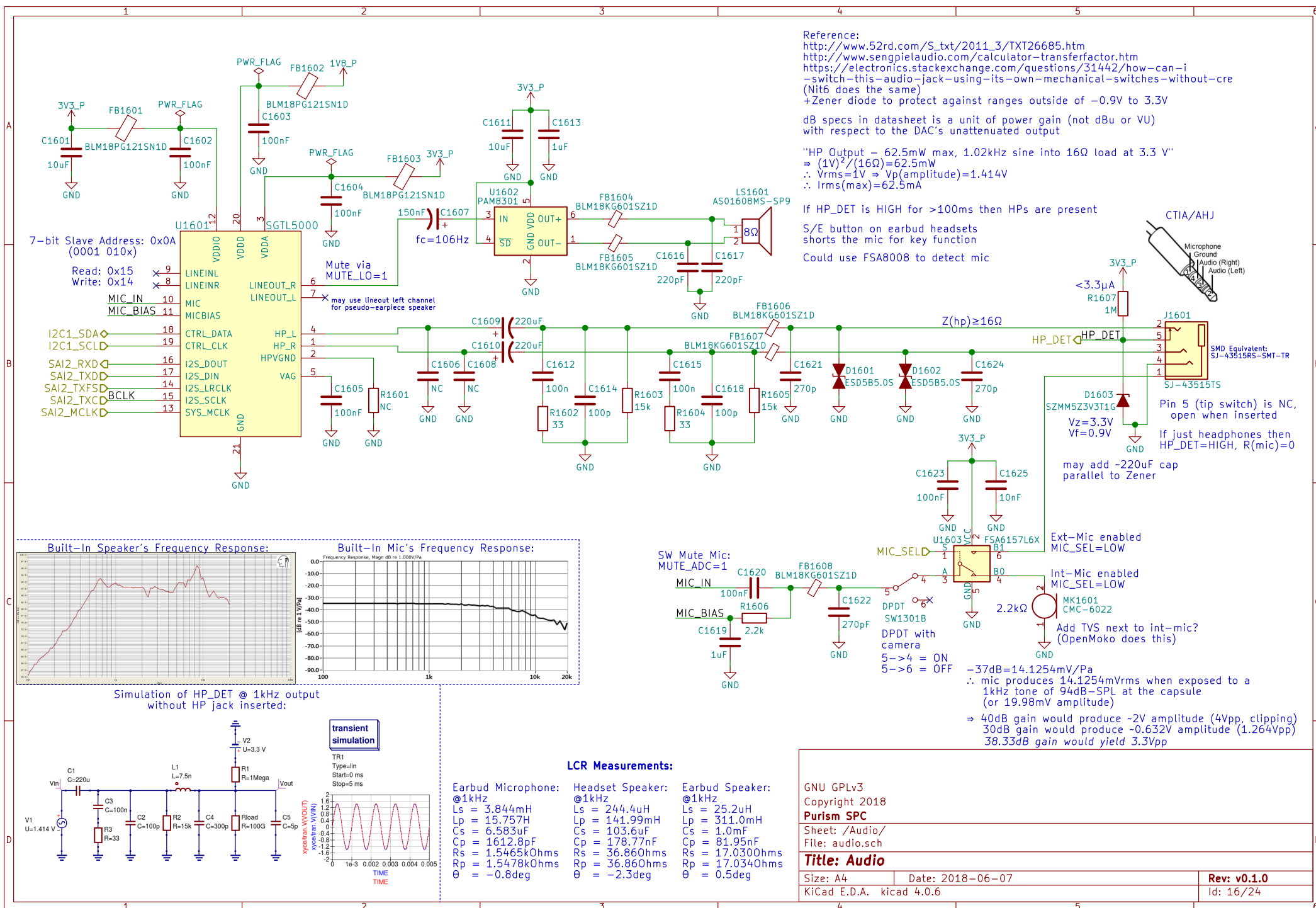
Title: Buttons & LED

Size: A4 Date: 2018-06-07

KiCad E.D.A. kicad 4.0.6

Rev: v0.1.0

Id: 14/24



RGMII 10/100/1000 Ethernet

The schematic diagram illustrates the RGMII 10/100/1000 Ethernet interface. It shows the connection of the AR8031 Ethernet controller to the Ethernet PHY (J1703) and various power and control signals. Key components include resistors (R1701-R1725), capacitors (C1701-C1719), inductors (L1701, L1702), and a crystal (Y1701). The PHY is connected to a RJ45 connector (J1703) with a green LED (D1702).

Power and Control Signals:

- 3V3_P:** Power supply for the PHY and controller.
- ENET_2V5:** 2.5V supply for the PHY.
- ENET_1V1:** 1.1V supply for the PHY.
- PWR_FLAG:** Power flag signal.
- LED_ACT:** LED activity signal.
- LED_LINK1000:** 1000Mbps link signal.
- LED_LINK10_100:** 10/100Mbps link signal.
- CLK02:** 25MHz crystal oscillator.
- TEST_1P:** Test point for the crystal.

PHY Connections (J1703):

- ETH_TRX0_P, ETH_TRX0_N:** TX0+ and TX0- pairs.
- ETH_TRX1_P, ETH_TRX1_N:** TX1+ and TX1- pairs.
- ETH_TRX2_P, ETH_TRX2_N:** TX2+ and TX2- pairs.
- ETH_TRX3_P, ETH_TRX3_N:** TX3+ and TX3- pairs.
- ETH_TRX0_P, ETH_TRX0_N, ETH_TRX1_P, ETH_TRX1_N, ETH_TRX2_P, ETH_TRX2_N, ETH_TRX3_P, ETH_TRX3_N:** RX0+, RX0-, RX1+, RX1-, RX2+, RX2-, RX3+, RX3- pairs.
- GREEN:** Green LED (D1702).
- YELLOW:** Yellow LED (D1702).

Controller Connections (AR8031):

- ENET_TXC, ENET_TD0, ENET_TD1, ENET_TD2, ENET_TD3, ENET_TX_CTL:** TX signals.
- ENET_RXC, ENET_RD0, ENET_RD1, ENET_RD2, ENET_RD3, ENET_RX_CTL:** RX signals.
- ENET_MDC, ENET_MDIO, ENET_RST:** MDIO signals.
- ENET_WoL, ENET_INT:** Wake-on-LAN and interrupt signals.
- PPS, CLK_25M:** Precision Pulse and 25MHz clock signals.
- XTLO, XTLI, RBIAS:** Crystal and bias signals.

Legend:

- GREEN:** Green LED (D1702).
- YELLOW:** Yellow LED (D1702).

Metadata:

- GNU GPLv3
- Copyright 2018
- Purism SPC
- Sheet: /Ethernet/
- File: ethernet.sch
- Title: Ethernet**
- Size: A4
- Date: 2018-06-07
- KiCad E.D.A. kicad 4.0.6
- Rev: v0.1.0
- Id: 17/24

Id: 17/24

RS9116 NC:
RTS, CTS, BT_HOST_WAKE

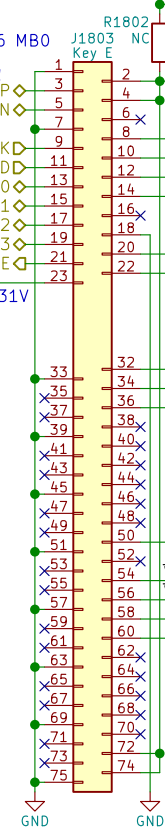
RS9116 datasheet says
no WIFI_WAKE
but the schematic has it

RedPine RS9116 MB0
Requires 5V on
Pin 54 for USB!

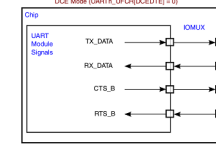
WIFI_CLK
WIFI_CMD
WIFI_DATA0
WIFI_DATA1
WIFI_DATA2
WIFI_DATA3
WIFI_WAKE

RedPine RS9116
has 100k pull-up to
3.3V making SDIO_RST
~2.55V when HIGH

Module: Table 23
Socket: Table 46
M.2 Key E



6.2 M.2 Signal Directions
UARTn_UFCR[DCEDTE]=0 on POR



TX output
RX input
CTS output
RTS input

Pin 54 on RS9116 is
USB_VBUS Sink

RS9116 SUSCLK
is a GPIO (unused)
SUSCLK

W_DISABLE2
W_DISABLE1
M2_I2C_SDA
M2_I2C_SCL

U1803A
74AUP2G08

U1803B
74AUP2G08

BT_DISABLE
WIFI_DISABLE

SW1801A
WLAN_HKS

SW1801B
WLAN_HKS

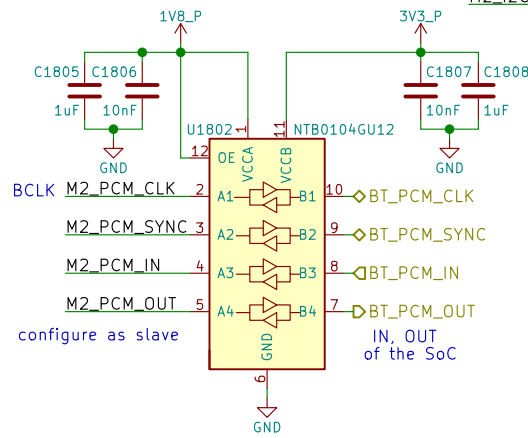
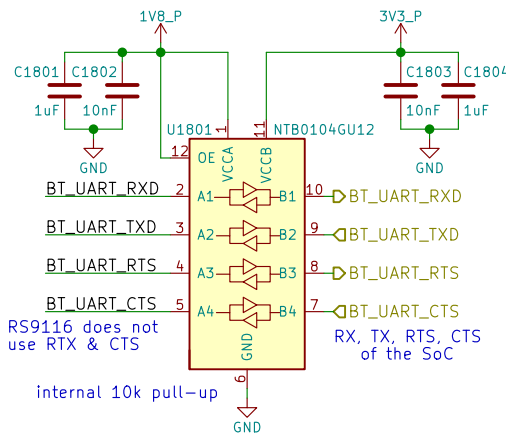
Open = ON
Closed = OFF

RS9116 is an I2C master
= its SCL is an output
(ok bc only device on I2C2)

M2_I2C_SDA
M2_I2C_SCL

Q1801
25K3018

Q1802
25K3018



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Purism SPC

Sheet: /WLAN+BT M.2/

File: wifi_bt_m2.sch

Title: WLAN+BT M.2

Size: A4

Date: 2018-06-07

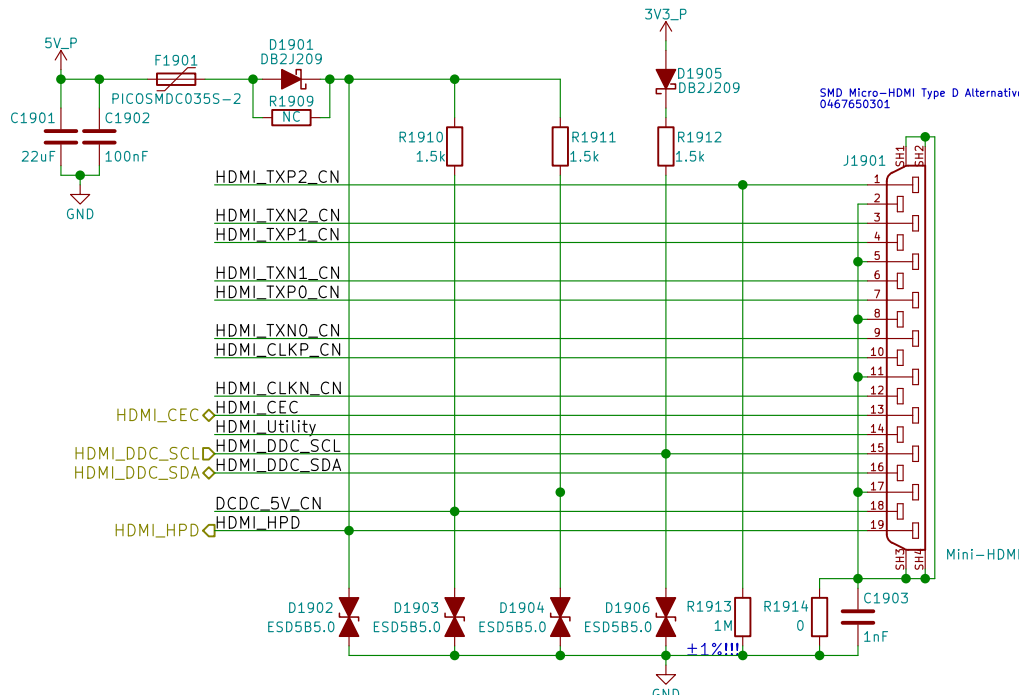
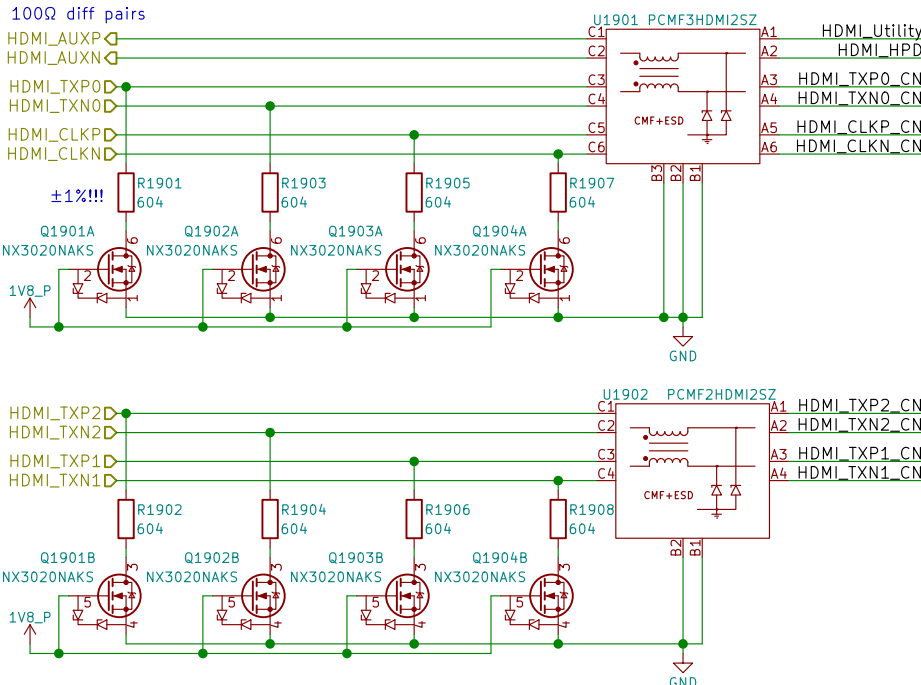
KiCad E.D.A. kicad 4.0.6

Rev: v0.1.0

Id: 18/24

HD3SS460 can be used for DP over USB-C

Layout Note:
May need swap some signals
due to micro-HDMI pinout diff
depending on pin location/routing



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Purism SPC

Sheet: /HDMI/
File: hdmi.sch

Title: HDMM

Size: A4	Date: 2018-06-07
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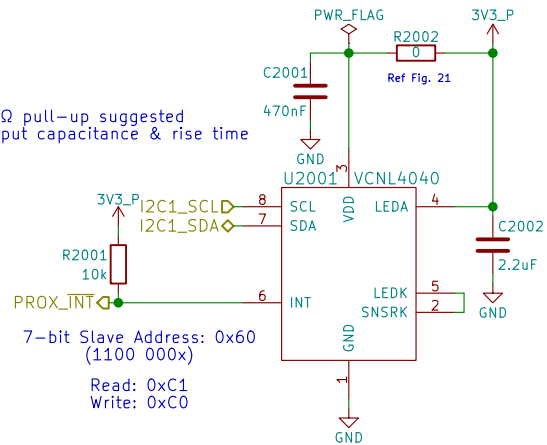
KiCad E.D.A. kicad 4.0.6

Rev: v0.1.0

Id: 19/24

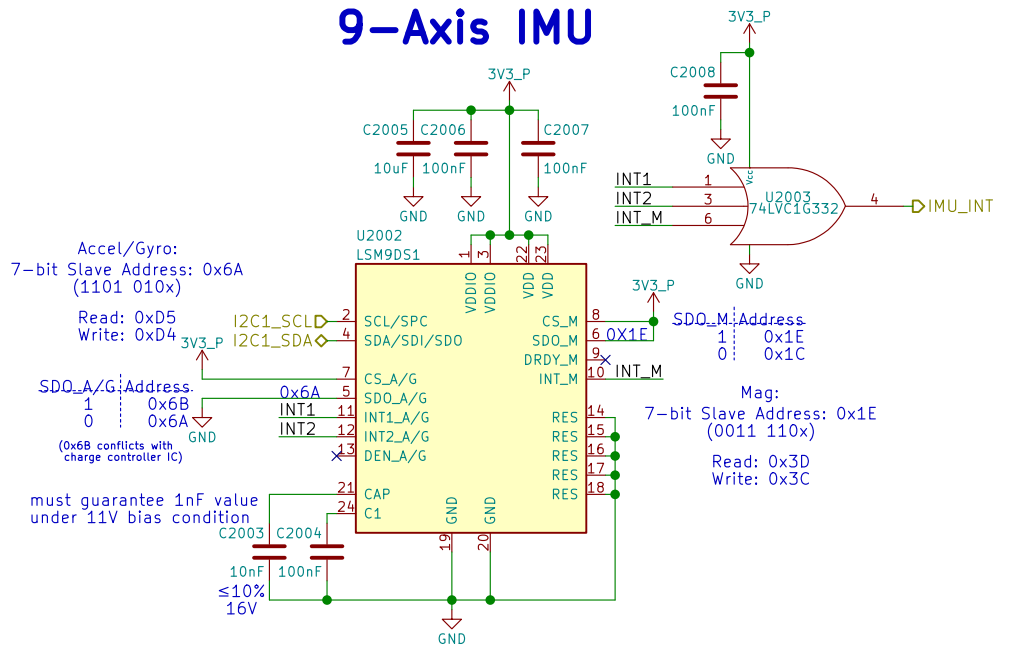
Proximity & Ambient Light

Note:
I2C 2.2kΩ pull-up suggested
check input capacitance & rise time

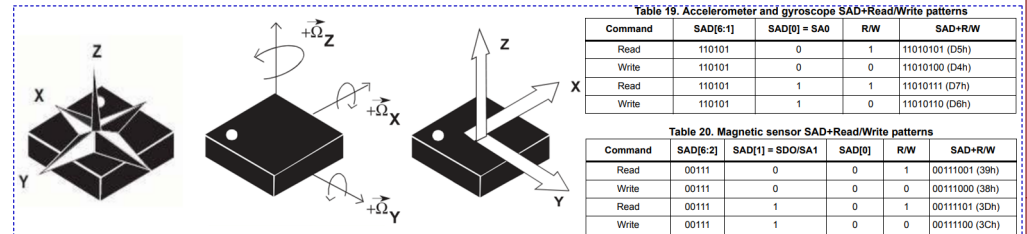


Reference:
<https://www.vishay.com/docs/84307/designingvcnl4040.pdf>
<http://www.vishay.com/docs/84931/vcnl4040sensorboardfiles.pdf>

9-Axis IMU



Reference:
<http://www.st.com/en/evaluation-tools/steval-mki159v1.html>



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Purism SPC

Sheet: /Sensors/

File: sensors.sch

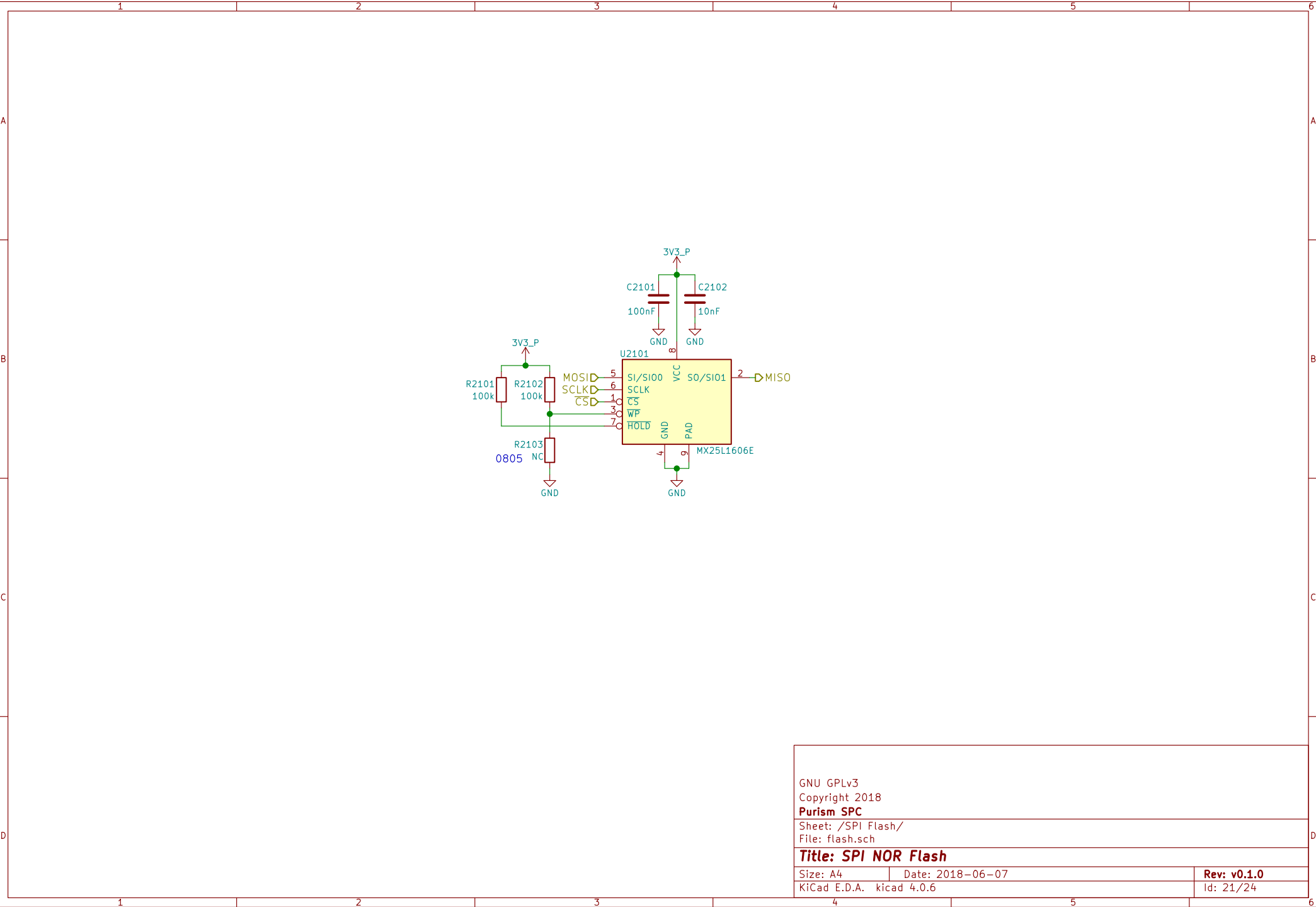
Title: Sensors

Size: A4 Date: 2018-06-07

KiCad E.D.A. kicad 4.0.6

Rev: v0.1.0

Id: 20/24



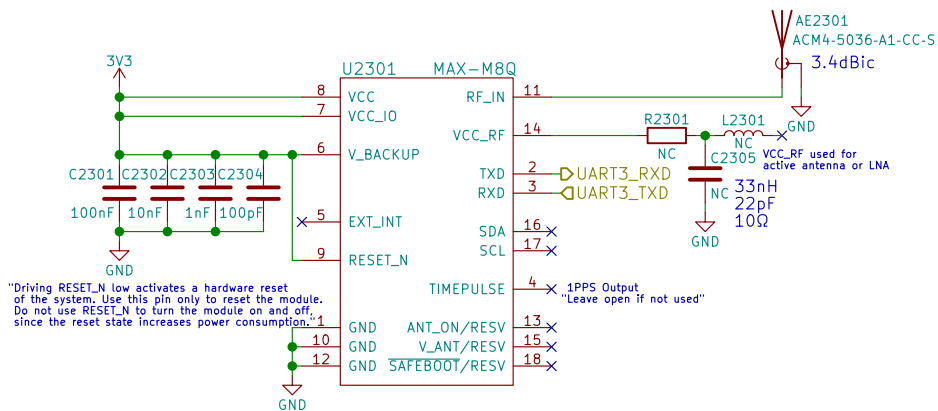
GNU GPLv3
Copyright 2018

Purism SPC

Sheet: /SPI Flash/
File: flash.sch

Title: SPI NOR Flash

Size: A4	Date: 2018-06-07	Rev: v0.1.0
KiCad E.D.A. kicad 4.0.6		Id: 21/24



Reference:
https://www.u-blox.com/sites/default/files/MAX-8-M8-FW3_HardwareIntegrationManual_1503005929.pdf

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Purism SPC

Sheet: /GNSS/
 File: gnss.sch

Title: GNSS

Size: A4 Date: 2018-06-07

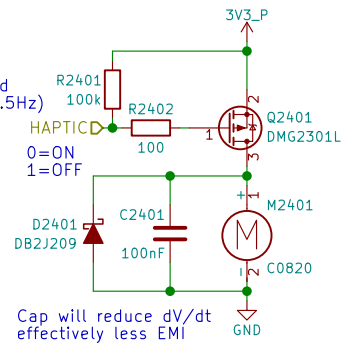
KiCad E.D.A. kicad 4.0.6

Rev: v0.1.0

Id: 23/24

PWM pins occupied:
 GPIO1_I001 - LCD Backlight
 GPIO1_I013 - LED
 GPIO1_I014 - Ethernet (CLKO_25MHz)
 GPIO1_I015 - CSI (CLKO2)

PWM needed?
 Only needs to be toggled
 ON 1 sec, OFF 1 sec (0.5Hz)
 Can MUX as either
 GPIO or PWM2
 swapping with LED



When the motor is off
 both terminals are at GND

Motor will have wire leads
 with a 2-pin Molex or Boom Precision
 connector installed (by request)!

Cheaper Motor Connector:
https://lcsc.com/product-detail/1-25T-Connectors_1-25T-1-2AW_C10832.html

Motor Source:
https://www.alibaba.com/product-detail/Coin-motor-vibration-dc-motor-cellphone_1994583657.html?spm=a2700.8443308.0.0.5aa13e5f1wxHgs
 Motor Datasheet:
<https://cloud.puri.sm/s/z8JR6DJ4KrJYzoW>

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Purism SPC

Sheet: /Haptic Motor/
 File: haptic.sch

Title: Haptic/Vibration Motor

Size: A4 Date: 2018-06-07

KiCad E.D.A. kicad 4.0.6

Rev: v0.1.0

Id: 24/24