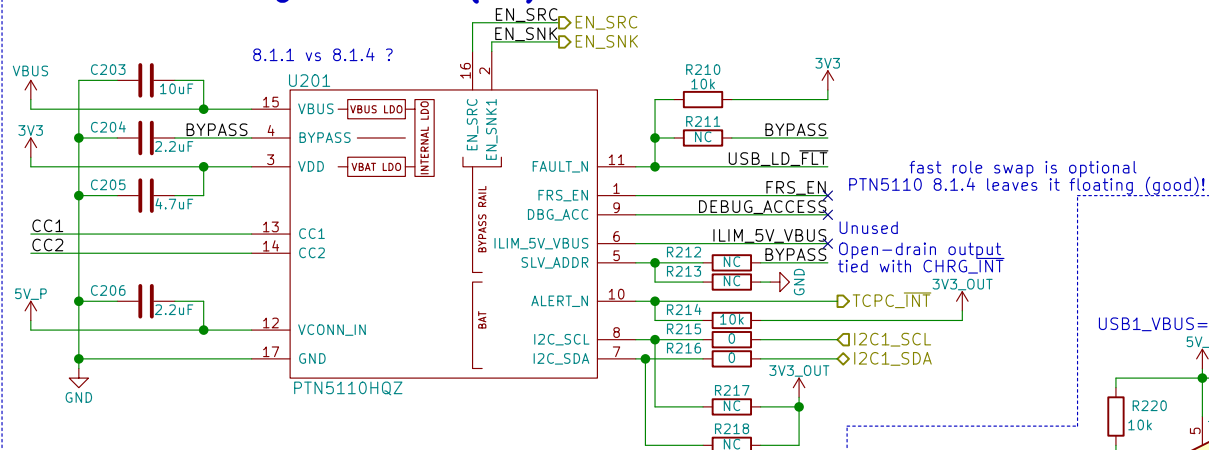
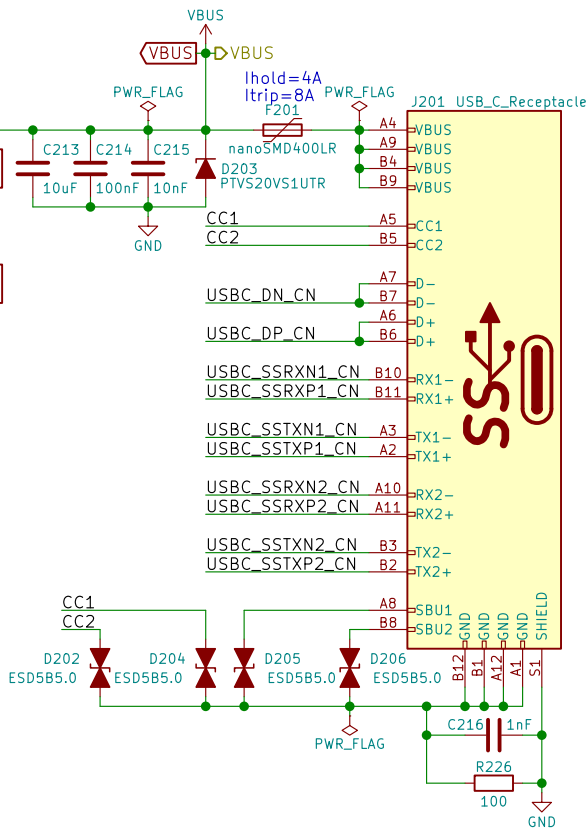
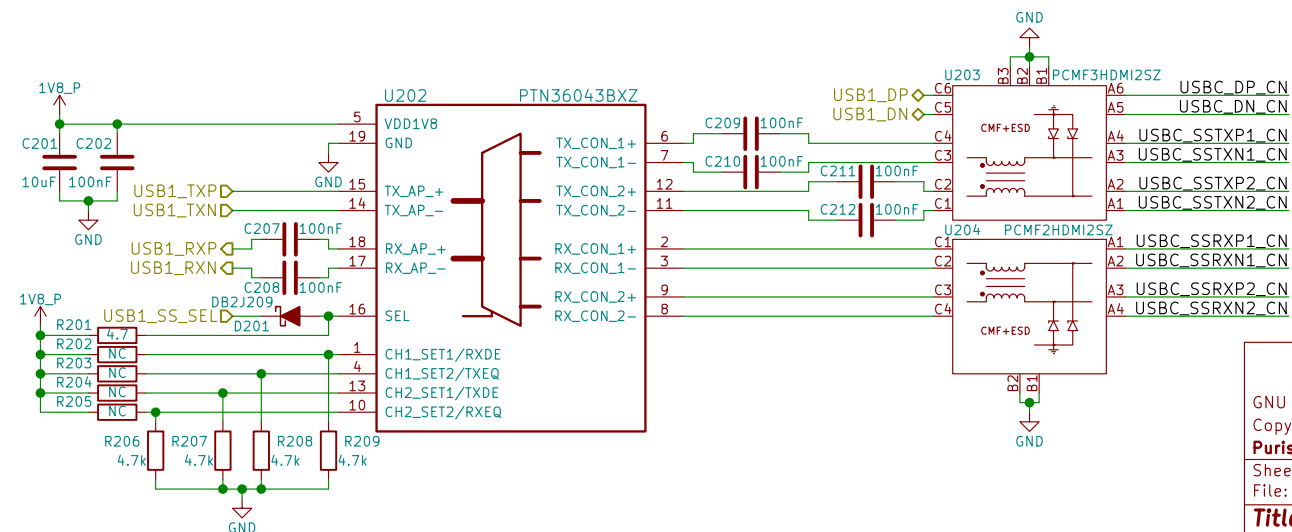


# USB-C Config Channel (CC) and PD Role Controller



"Under dead battery operation, PTN5110 applies voltage clamps to both CC pins so that the system may receive power as a Sink. To support platforms with buck-boost configuration, PTN5110 asserts EN\_SNK1 pin based on validity of VBUS voltage (facilitates 5 V VBUS sinking)."

Initialize as the UFP (device)  
read CC\_STATUS to determine role  
use Host Negotiation Protocol (HNP)  
to become an DFP (host)  
∴ USB ID is effectively unused  
⇒ Legacy devices would "wait" for this  
⇒ If CC initializes as UFP then no HNP needed



GNU GPLv3

Copyright 2018

Purism SPC

Sheet: /USB-C/

File: usb-c.sch

Title: USB Type C

Size: A4 Date: 2018-05-23

KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0

Id: 2/23



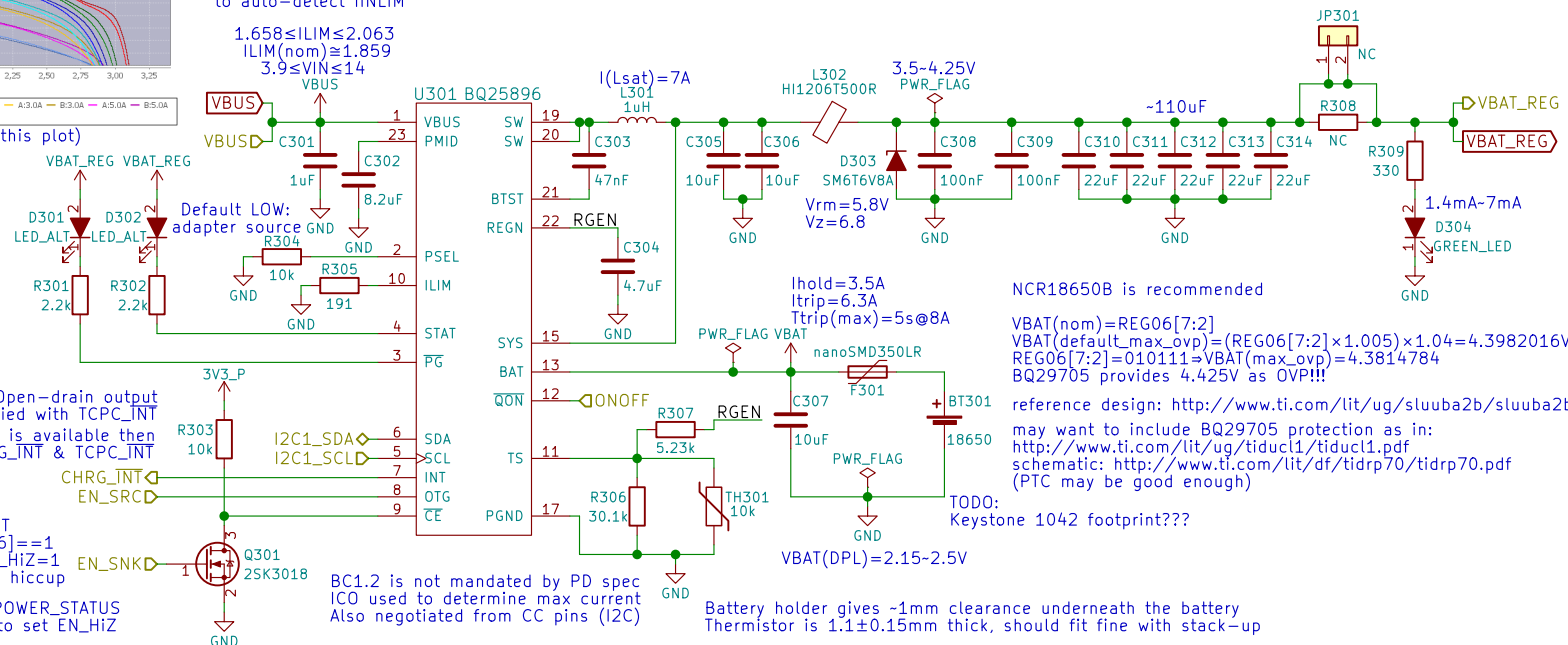
use AUTO\_DPDM\_EN  
to auto-detect IINLIM

$$1.658 \leq I_{LIM} \leq 2.063$$

$$I_{LIM}(nom) \approx 1.859$$

$$3.9 \leq V_{IN} \leq 14$$

# Battery Charge Controller



Reading PTN5110HQ's CC\_STATUS and POWER\_STATUS registers will tell TCPM (i.MX8M) when to set EN\_HI\_Z

Also, reading PTN5110HQ's CC\_STATUS and POWER\_STATUS registers will tell TCPM (i.MX8M) when to set OTG\_CONFIG=1 (this will also happen when PTN5110HQ sets EN\_SRC HIGH)

GNU GPLv3

Copyright 2018

Purism SPC

Sheet: /Battery/

File: battery.sch

Title: Battery

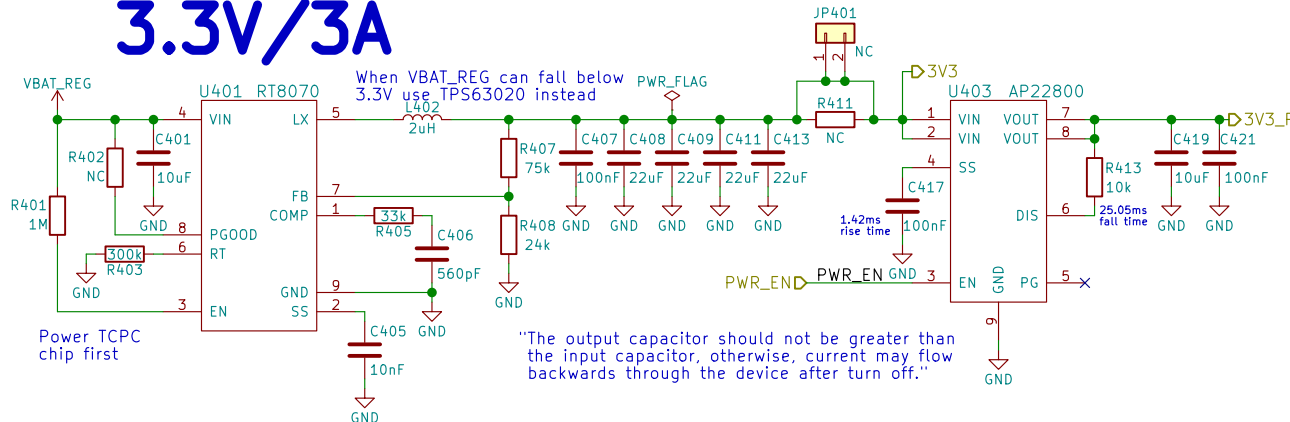
Size: A4 Date: 2018-05-23

KiCad E.D.A. kicad 4.0.7

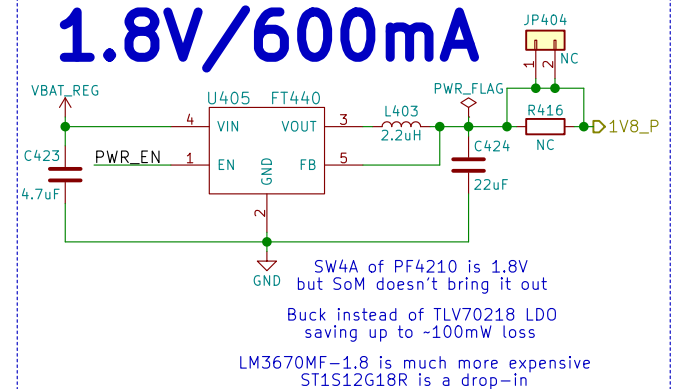
Rev: v0.1.0

Id: 3/23

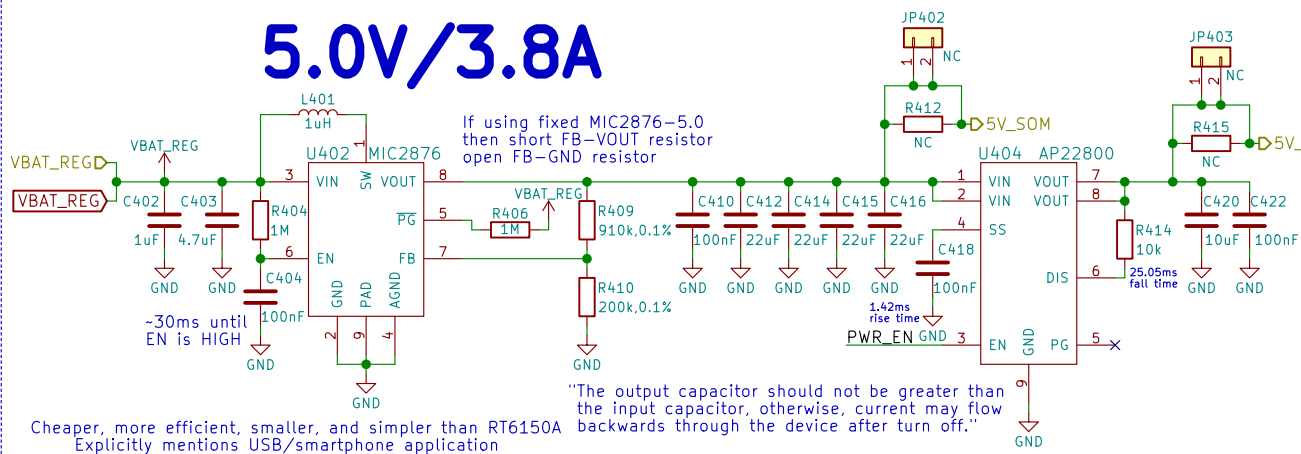
## 3.3V/3A



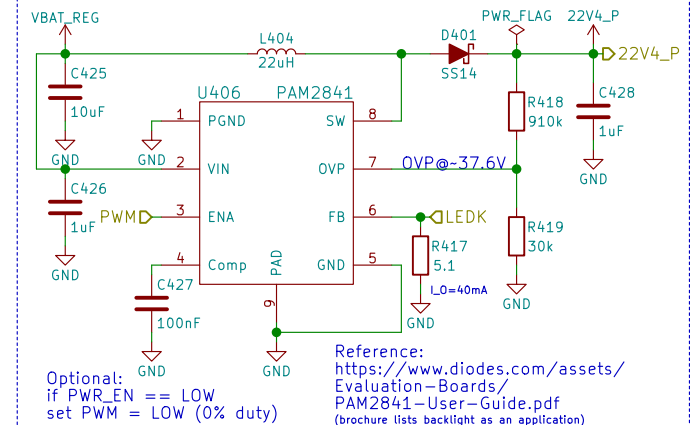
## 1.8V/600mA



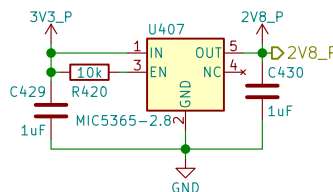
## 5.0V/3.8A



## 22.4V/40mA



TODO:  
add parallel 100nF bulk caps!  
& spread all over the power plane



GNU GPLv3  
Copyright 2018  
**Purism SPC**

Sheet: /Power/  
File: power.sch

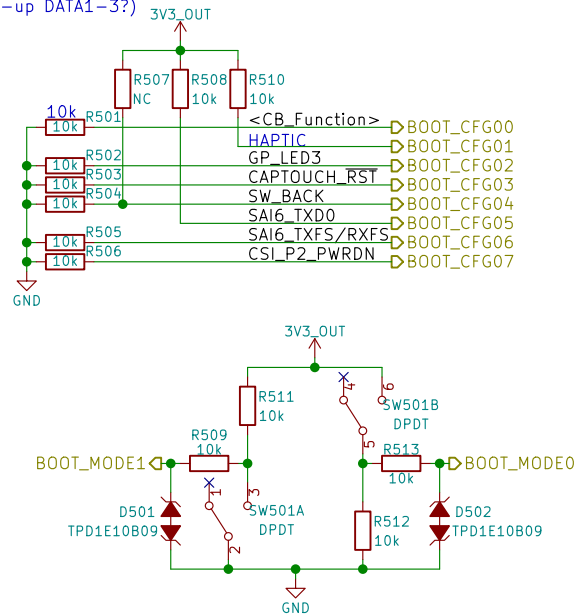
### Title: Power

Size: A4 Date: 2018-05-23  
KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0  
Id: 4/23

BOOT\_CFG04: 0 - 1-bit SD bus  
1 - 4-bit SD bus (pull-up DATA1-3?)

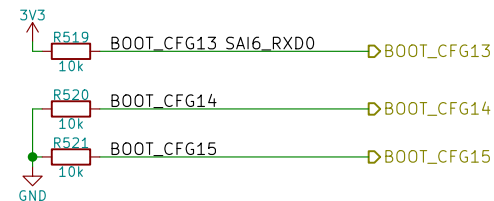
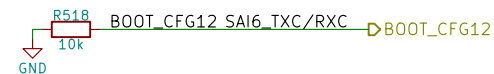
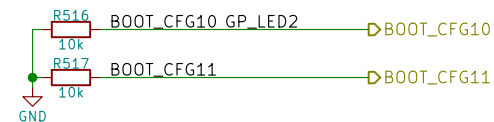
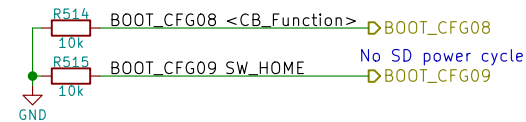
BOOT\_CFG05: 1 - 8-bit eMMC bus  
0 - 1-bit eMMC bus



| 2->1: eMMC<br>2->3: USB (Serial Downloader) |                   |
|---|-------------------|
| BOOT_MODE[1:0]                              | Boot Type         |
| 00  | Boot From Fuses   |
| 01  | Serial Downloader |
| 10  | Internal Boot     |
| 11  | Reserved          |

Only eMMC

| BOOT_CFG[14:12] |        | Boot device          |                   |               |   |
|-----------------|--------|----------------------|-------------------|---------------|---|
| 001             |        | SD/eSD               |                   |               |   |
| 010             |        | MMC/eMMC             |                   |               |   |
| 011             |        | NAND                 |                   |               |   |
| Fuse            | Config | Definition           | GPIO <sup>1</sup> | Shipped value | Settings  |
| BOOT_CFG[11:10] | OEM    | USDHC port selection | Yes               | 00            | 00 - USDHC-1<br>01 - USDHC-2<br>10 - USDHC-3<br>else - reserved |



GNU GPLv3  
Copyright 2018

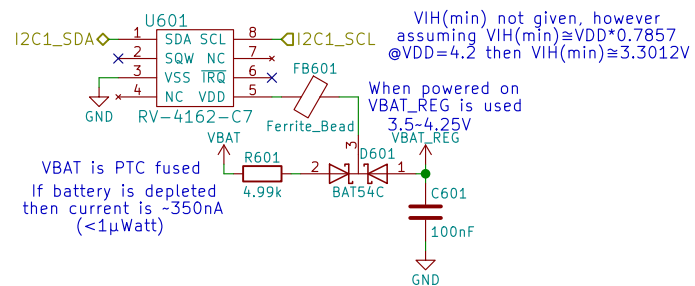
Purism SPC

Sheet: /Boot Config/  
File: boot.sch

Title: Boot Configuration

Size: A4 Date: 2018-05-23  
KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0  
Id: 5/23



GNU GPLv3  
Copyright 2018

**Purism SPC**

Sheet: /RTC/  
File: rtc.sch

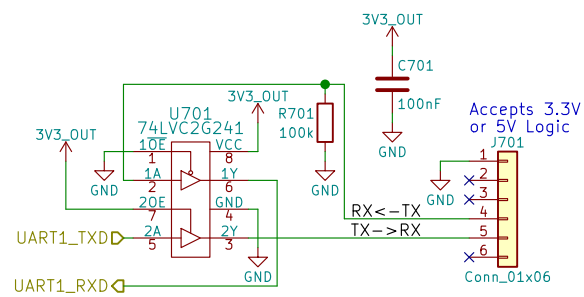
**Title: RTC**

Size: A4 Date: 2018-05-23

KiCad E.D.A. kicad 4.0.7

**Rev: v0.1.0**

Id: 6/23



GNU GPLv3  
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**Purism SPC**

Sheet: /UART Debug/  
File: uart.sch

**Title: UART Debug**

Size: A4 Date: 2018-05-23

KiCad E.D.A. kicad 4.0.7

**Rev: v0.1.0**

Id: 7/23



GNU GPLv3  
Copyright 2018  
**Purism SPC**  
Sheet: /JTAG/  
File: jtag.sch

**Title: JTAG**

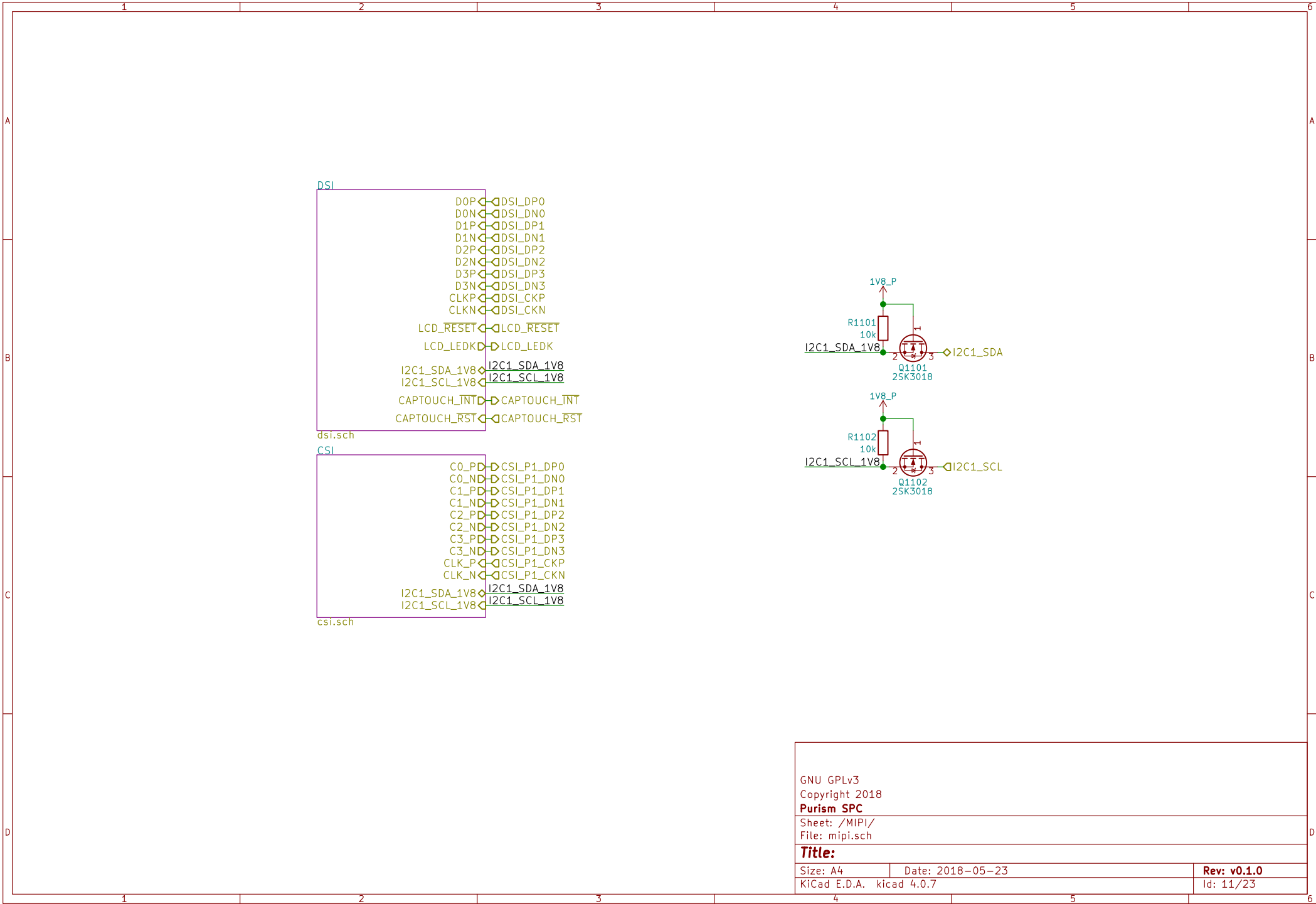
Size: A4  
Date: 2018-05-23  
KiCad E.D.A. kicad 4.0.7

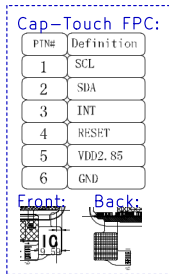
**Rev: v0.1.0**  
Id: 8/23



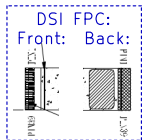
Id: 9/23

Id: 10/23





Cap-Touch Controller IC PN:  
Goodix GT5688



Backlight Array:

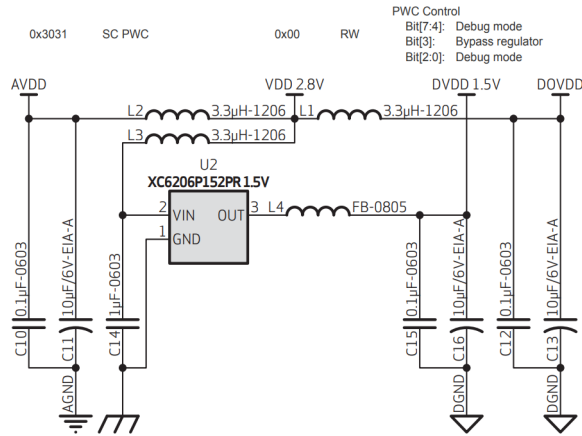


LED K1 LEDA1

LED K2 LEDA2

Id: 12/23

### Using Internal DVDD 1.5V Regulator:



## 2.7 POWER UP SEQUENCE

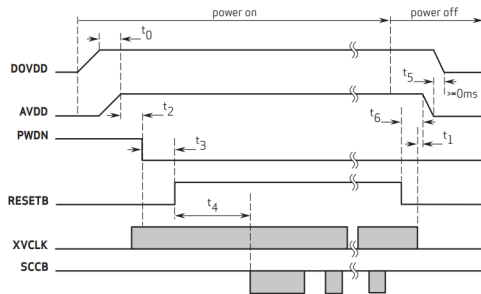
Based on the system power configuration (1.8V or 2.8V for I/O power, using external DVDD or internal DVDD, requiring access to the I2C during power up period or not), the power up sequence will differ. If 1.8V is used for I/O power, using the internal DVDD is preferred. If 2.8V is used for I/O power, due to a high voltage drop at the internal DVDD regulator, there is a potential heat issue. Hence, for a 2.8V power system, OmniVision recommends using an external DVDD source. Due to the higher power down current when using an external DVDD source, OmniVision strongly recommends cutting off all powers, including the external DVDD, when the sensor is not in use in the case of 2.8V I/O and external DVDD.

### 2.7.1 POWER UP WITH INTERNAL DVDD

For powering up with the internal DVDD and I2C access during the power ON period, the following conditions must occur:

1. when DOVDD and AVDD are turned ON, make sure DOVDD becomes stable before AVDD becomes stable
2. PWDN is active high with an asynchronized design (does not need clock)
3. PWDN pin tied to digital ground if it is not controlled.
4. if PWDN pin is controlled as below, for PWDN to go low, power must first become stable (AVDD to PWDN  $\geq 5$  ms)
5. RESETB is active low with an asynchronized design
6. master clock XVCLK should provide at least 1 ms before host accesses the sensor's registers
7. host can access I2C bus (if shared) during entire period. 20ms after RESETB goes high, host can access the sensor's registers to initialize sensor

figure 2-3 power up timing with internal DVDD



- note  $t_0 \geq 0$ ms, delay from DOVDD stable to AVDD stable, it is recommended to power up AVDD shortly after DOVDD has been powered up
- $t_1 \geq 0$ ms, delay from XVCLK off to AVDD off
- $t_2 \geq 5$ ms, delay from AVDD stable to sensor power up stable, PWDN can be pulled low after this point. XVCLK can be turned on after power on
- $t_3 \geq 1$ ms, delay from sensor power up stable to RESETB pull up
- $t_4 \geq 20$ ms, delay from RESETB pull high to SCCB initialization
- $t_5 \geq 0$ ms, delay from AVDD off to DOVDD off
- $t_6 \geq 0$ ms, delay from RESETB pull low to AVDD off

✕D C0\_P  
✕D C0\_N  
✕D C1\_P  
✕D C1\_N  
✕D C2\_P  
✕D C2\_N  
✕D C3\_P  
✕D C3\_N  
✕D CLK\_P  
✕D CLK\_N  
◇ I2C1\_SDA\_1V8  
◇ I2C1\_SCL\_1V8

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Copyright 2018

Purism SPC

Sheet: /MIPI/CSI/  
File: csi.sch

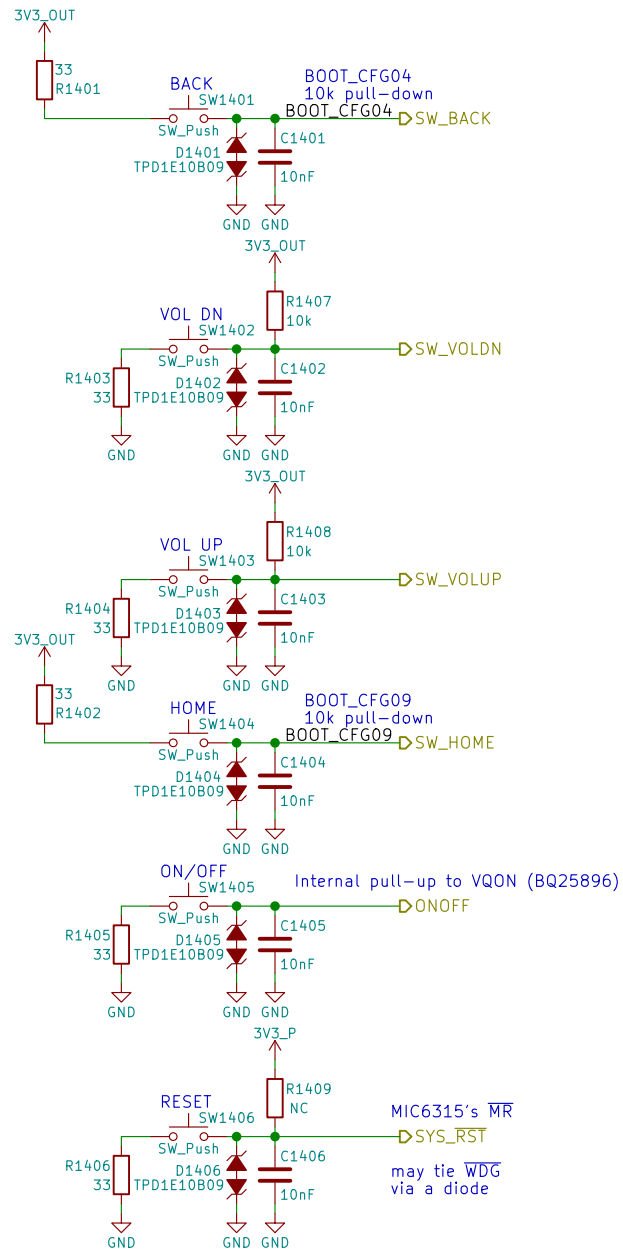
Title:

Size: A4 Date: 2018-05-23

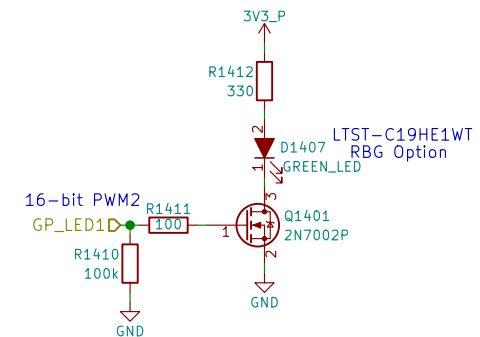
KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0

Id: 13/23



Use PWM2\_PWMSAR to set the compare value (duty cycle)  
 Use PWM2\_PWMCR[15:4] to set the PRESCALER (frequency)  
 Use PWM2\_PWMPR to set the top of the counter (frequency)



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 Copyright 2018

**Purism SPC**

Sheet: /Buttons & LED/  
 File: buttons\_led.sch

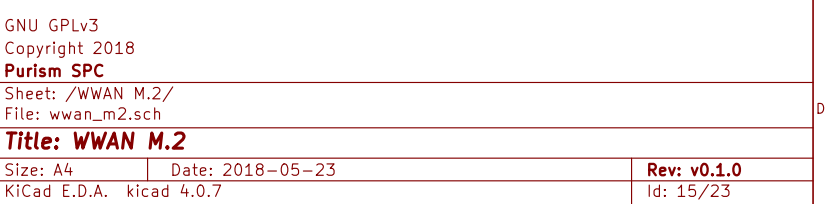
**Title: Buttons & LED**

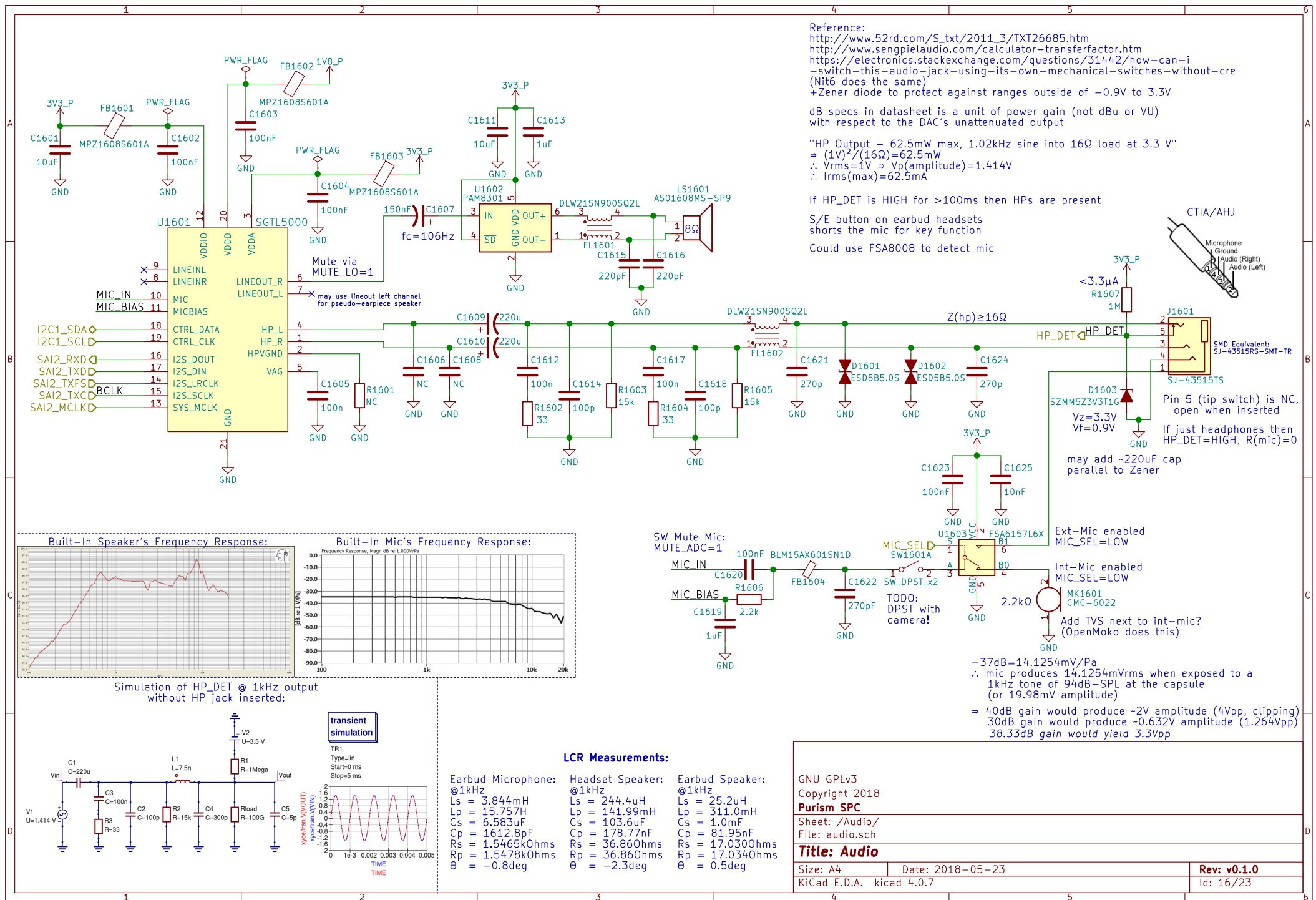
Size: A4 Date: 2018-05-23

KiCad E.D.A. kicad 4.0.7

**Rev: v0.1.0**

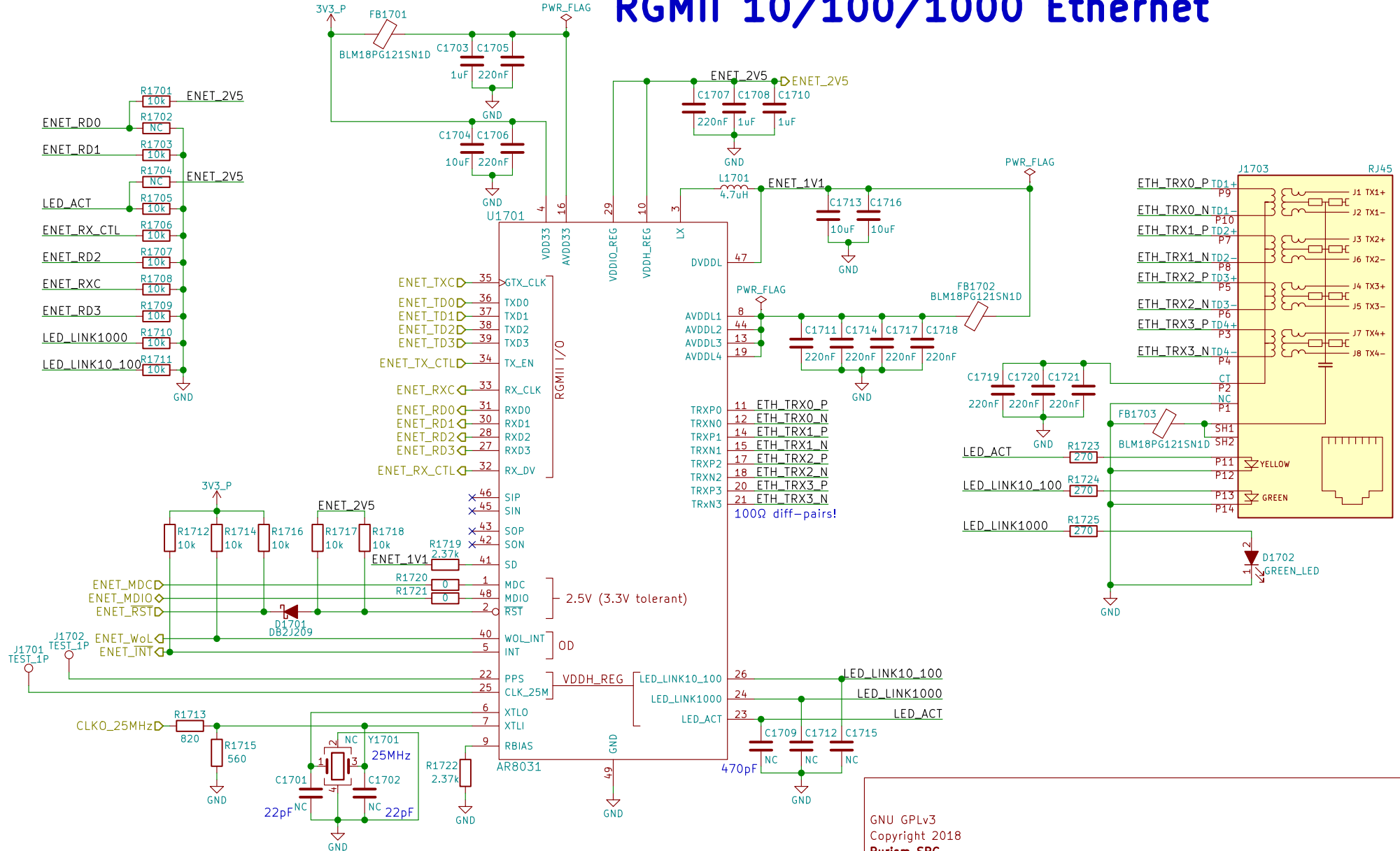
Id: 14/23







# RGMII 10/100/1000 Ethernet



GNU GPLv3  
Copyright 2018

**Purism SPC**

Sheet: /Ethernet/  
File: ethernet.sch

**Title: Ethernet**

Size: A4  
KiCad E.D.A. kicad 4.0.7

Date: 2018-05-23

Rev: v0.1.0

Id: 17/23

RS9116 NC:  
RTS, CTS, BT\_HOST\_WAKE

RS9116 datasheet says  
no WIFI\_WAKE  
but the schematic has it

RedPine RS9116 MB0  
Requires 5V on  
Pin 54 for USB!

USB\_WLAN\_DP  
USB\_WLAN\_DN

WIFI\_CLK  
WIFI\_CMD  
WIFI\_DATA0  
WIFI\_DATA1  
WIFI\_DATA2  
WIFI\_DATA3  
WIFI\_WAKE

WIFI\_RST

W\_DISABLE1

RedPine RS9116  
has 100k pull-up to  
3.3V making SDIO\_RST  
~2.55V when HIGH

Module: Table 23  
Socket: Table 46

3V3\_P

JP1801

NC

NC

M2\_PCM\_CLK

M2\_PCM\_SYNC

M2\_PCM\_IN

M2\_PCM\_OUT

SoC's IN/OUT

BT\_HOST\_WAKE

BT\_UART\_RXD

SoC's RX

Module's TX

SoC's TX

Module's RX

BT\_UART\_TXD

BT\_UART\_RTS

BT\_UART\_CTS

i.MX8M in DCE mode (POR state)

has CTS output, RTS input

RS9116 SUSCLK  
is a GPIO (unused)

SUSCLK

W\_DISABLE2

W\_DISABLE1

M2\_I2C\_SDA

M2\_I2C\_SCL

M2\_Key\_E

GND

GND

GND

GND

GND

GND

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GND

## 6.2 M.2 Signal Directions

UARTn\_UFCR[DCEDTE]=0 on POR

DCE Mode (UARTn\_UFCR[DCEDTE]=0)

UARTn\_TX\_DATA

UARTn\_RX\_DATA

CTS\_B

RTS\_B

TX output

RX input

CTS output

RTS input

TX→RX

RX→TX

CTS→CTS

RTS→RTS

Note:  
Dual 2-input AND much more  
available and cheaper than NOR

TODO:  
Pin 54 on RS9116 is USB\_VBUS Sink!!!

BT\_DISABLE

WIFI\_DISABLE

W\_DISABLE2

W\_DISABLE1

M2\_I2C\_SDA

M2\_I2C\_SCL

M2\_Key\_E

GND

GND

GND

GND

GND

GND

GND

GND

GND

GND

GND

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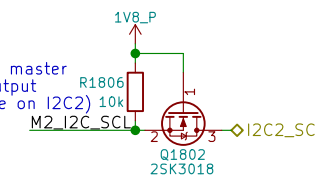
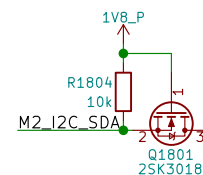
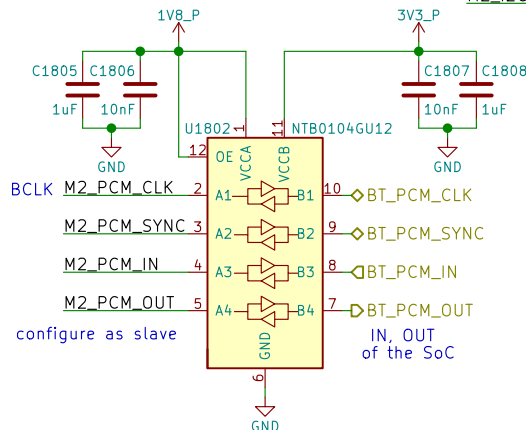
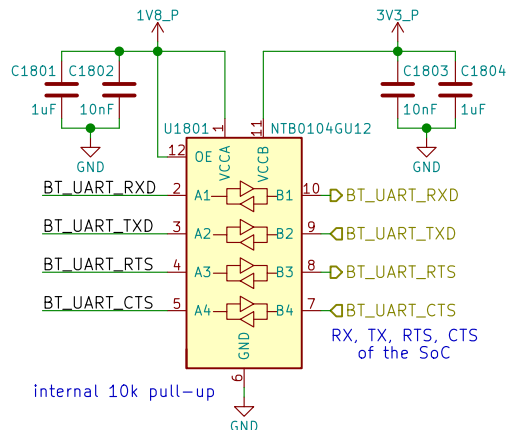
GND

GND

GND

GND

GND



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Copyright 2018

Purism SPC

Sheet: /WLAN+BT M.2/  
File: wifi\_bt\_m2.sch

Title: WLAN+BT M.2

Size: A4 Date: 2018-05-23

KiCad E.D.A. kicad 4.0.7

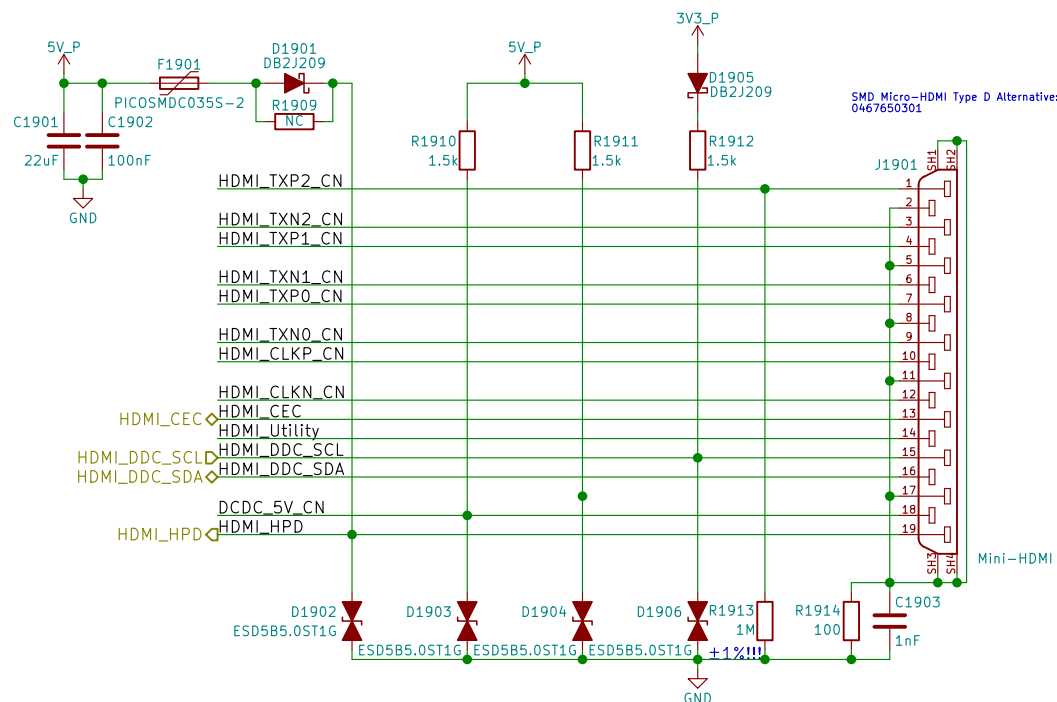
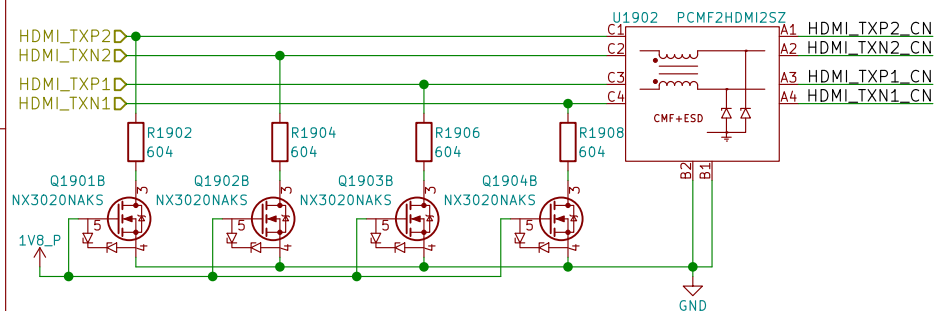
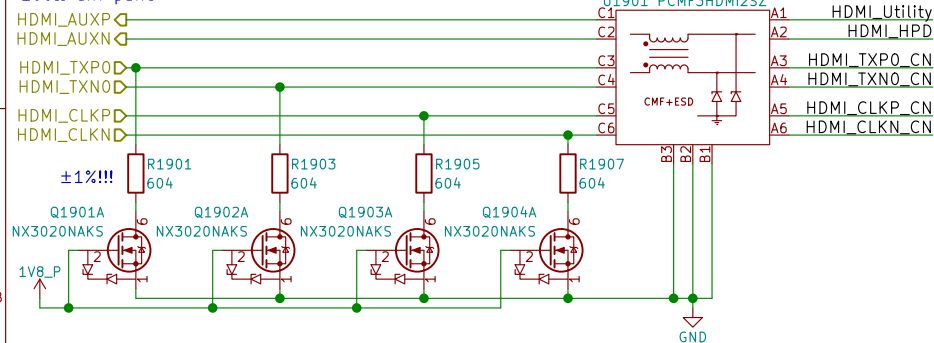
Rev: v0.1.0

Id: 18/23

HD3SS460 can be used for DP over USB-C

Layout Note:  
May need swap some signals  
due to micro-HDMI pinout diff  
depending on pin location/routing

100Ω diff pairs



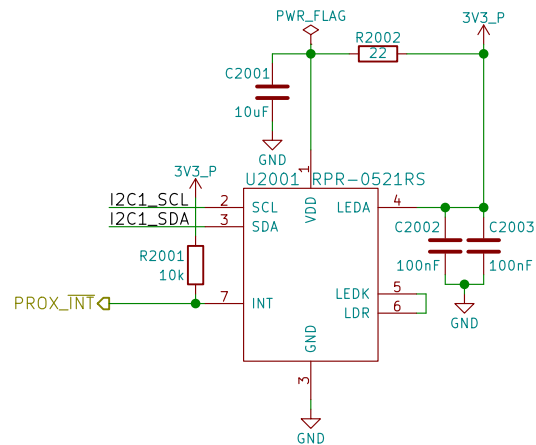
GNU GPLv3  
Copyright 2018  
**Purism SPC**

Sheet: /HDMI/  
File: hdmi.sch

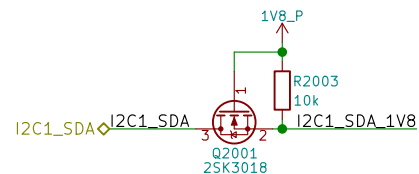
|                          |                  |
|--------------------------|------------------|
| <b>Title: HDMI</b>       |                  |
| Size: A4                 | Date: 2018-05-23 |
| KiCad E.D.A. kicad 4.0.7 |                  |

Rev: v0.1.0  
Id: 19/23

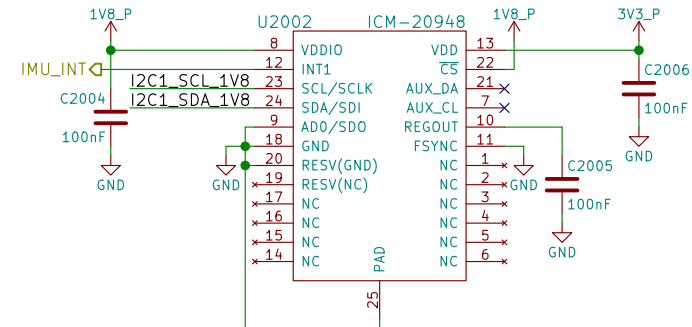
## Proximity & Ambient Light



Reference:  
<http://www.rohm.com/web/global/sensor-shield-support/ps-als-sensor>



## 9-Axis IMU



Reference:  
<https://store.invensense.com/datasheets/invensense/AN-IVS-0001EVB-00%20v1%202.pdf>

AD0 sets the slave address's LSB (110100X)

INT1\_ACTL sets if IMU\_INT is active-high or active-low

"FSYNC - Connect to GND if unused"

I2C's VIH=1.8V

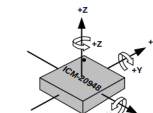


Figure 12. Orientation of Axes of Sensitivity and Polarity of Rotation

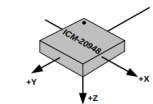


Figure 13. Orientation of Axes of Sensitivity for Magnetometer

GNU GPLv3  
 Copyright 2018

**Purism SPC**

Sheet: /Sensors/  
 File: sensors.sch

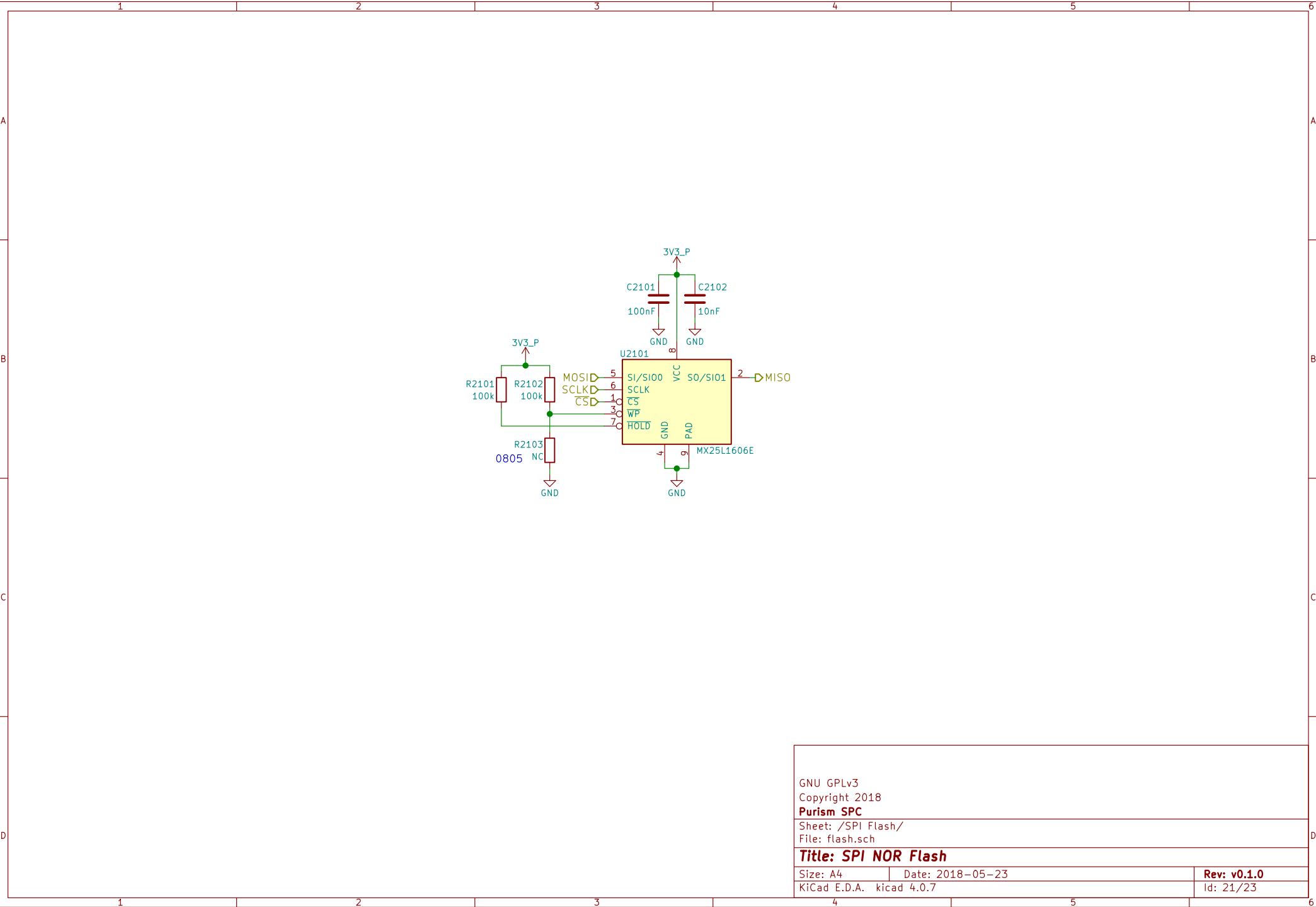
**Title: Sensors**

Size: A4 Date: 2018-05-23

KiCad E.D.A. kicad 4.0.7

**Rev: v0.1.0**

Id: 20/23



GNU GPLv3

Copyright 2018

**Purism SPC**

Sheet: /SPI Flash/

File: flash.sch

**Title: SPI NOR Flash**

Size: A4

Date: 2018-05-23

**Rev: v0.1.0**

KiCad E.D.A. kicad 4.0.7

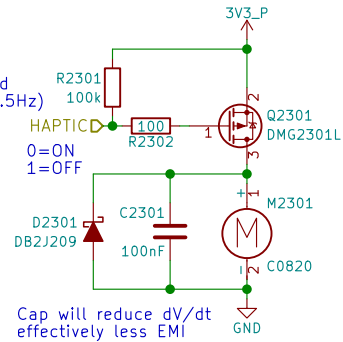
Id: 21/23



Id: 22/23

PWM pins occupied:  
 GPIO1\_I001 - LCD Backlight  
 GPIO1\_I013 - LED  
 GPIO1\_I014 - Ethernet (CLKO\_25MHz)  
 GPIO1\_I015 - CSI (CLKO2)

PWM needed?  
 Only needs to be toggled  
 ON 1 sec, OFF 1 sec (0.5Hz)  
 Can MUX as either  
 GPIO or PWM2  
 swapping with LED



When the motor is off  
 both terminals are at GND

Motor will have wire leads  
 with a 2-pin Molex or JST  
 connector installed (by request)!

Motor Connector:  
[https://lcsc.com/product-detail/1-25T-Connectors\\_1-25T-1-2AW\\_C10832.html](https://lcsc.com/product-detail/1-25T-Connectors_1-25T-1-2AW_C10832.html)  
 Alibaba Alternative Motor:  
[https://www.alibaba.com/product-detail/Coin-motor-vibration-dc-motor-cellphone\\_1994583657.html?spm=a2700.8443308.0.0.5aa13e5f1wxHgs](https://www.alibaba.com/product-detail/Coin-motor-vibration-dc-motor-cellphone_1994583657.html?spm=a2700.8443308.0.0.5aa13e5f1wxHgs)

GNU GPLv3  
 Copyright 2018

**Purism SPC**

Sheet: /Haptic Motor/  
 File: haptic.sch

**Title: Haptic/Vibration Motor**

Size: A4 Date: 2018-05-23

KiCad E.D.A. kicad 4.0.7

**Rev: v0.1.0**

Id: 23/23