





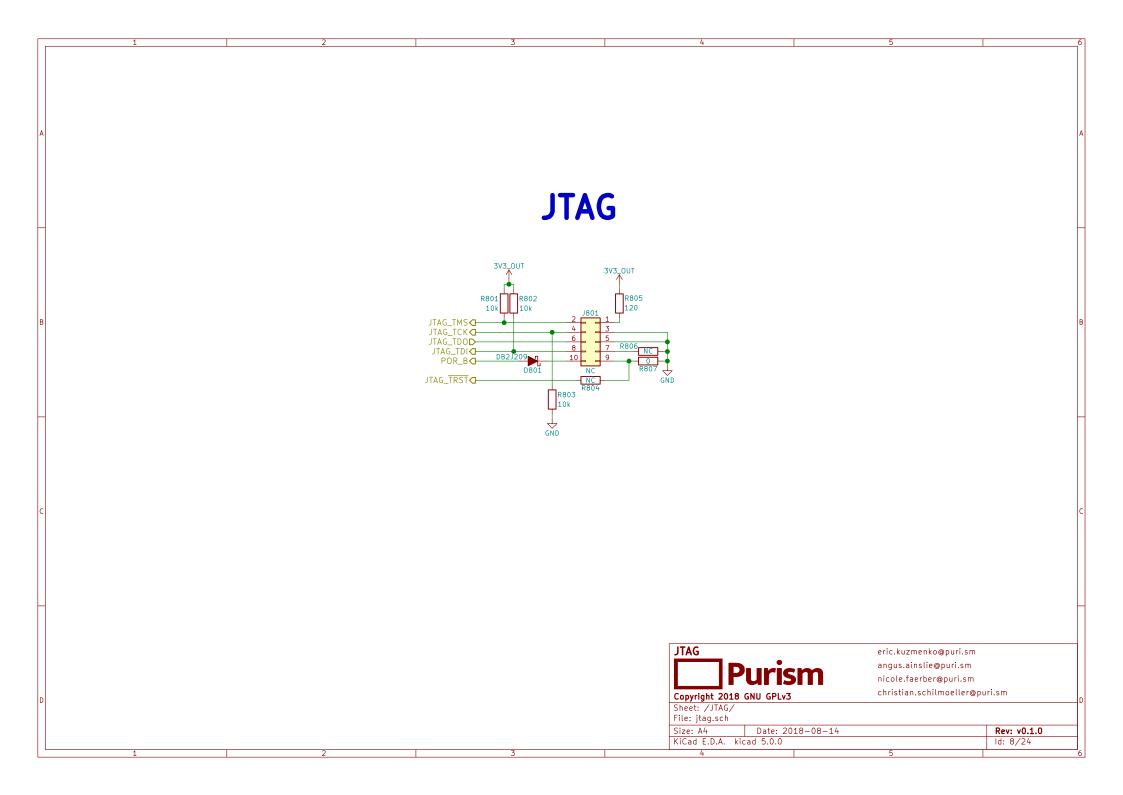


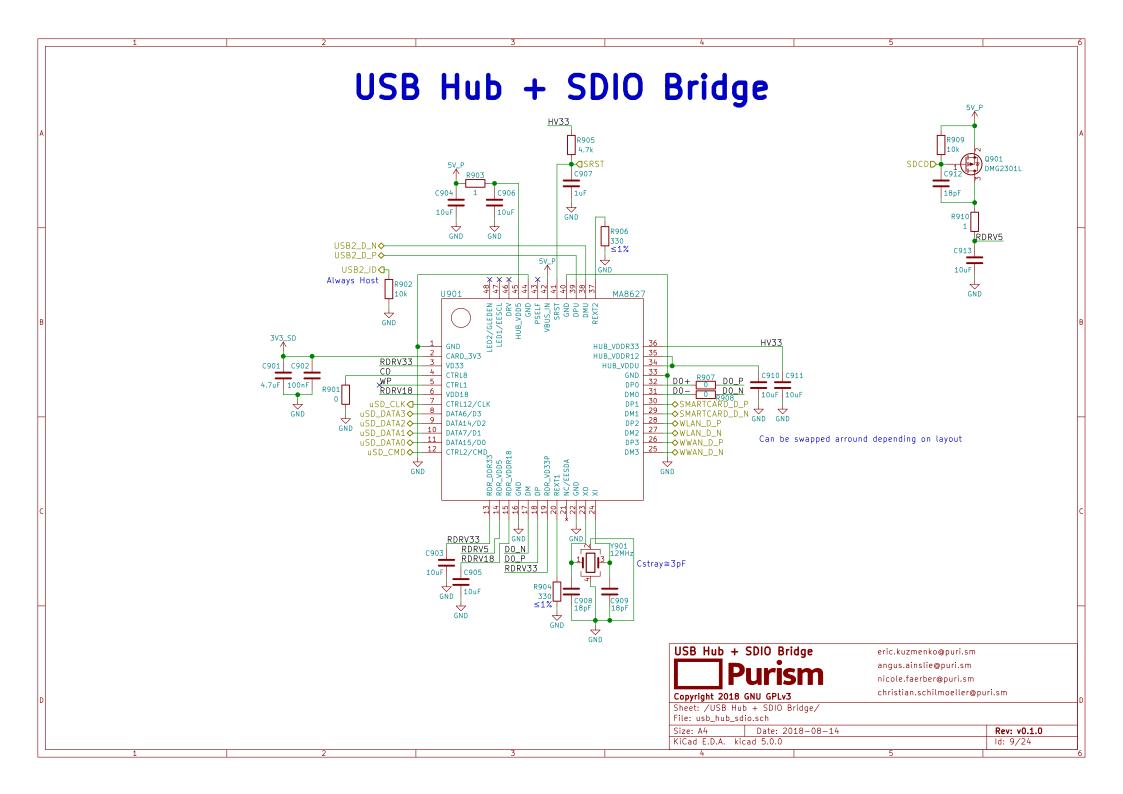
Real-Time Clock

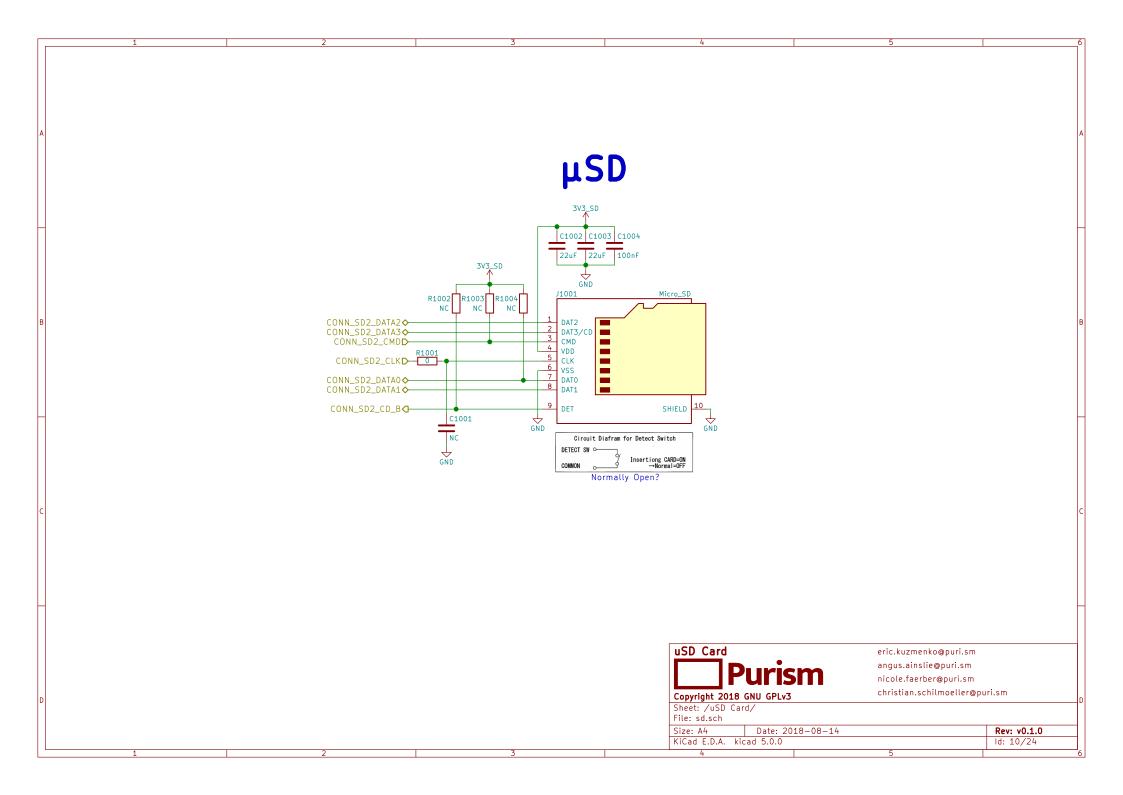








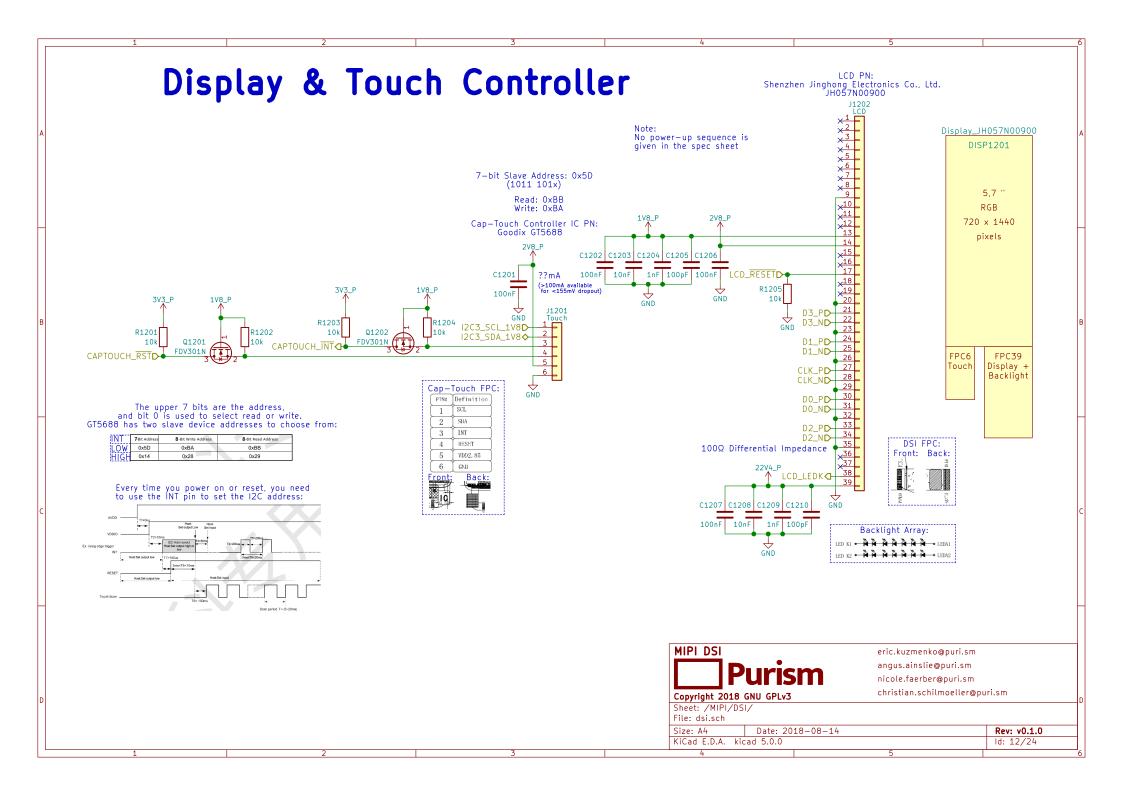






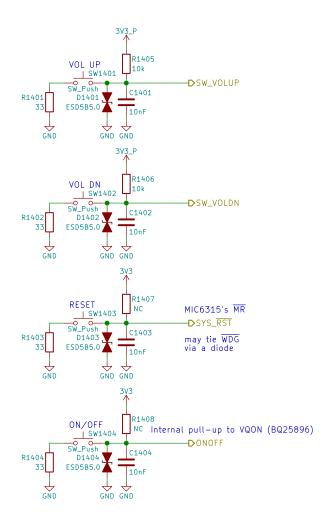


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Buttons & LED

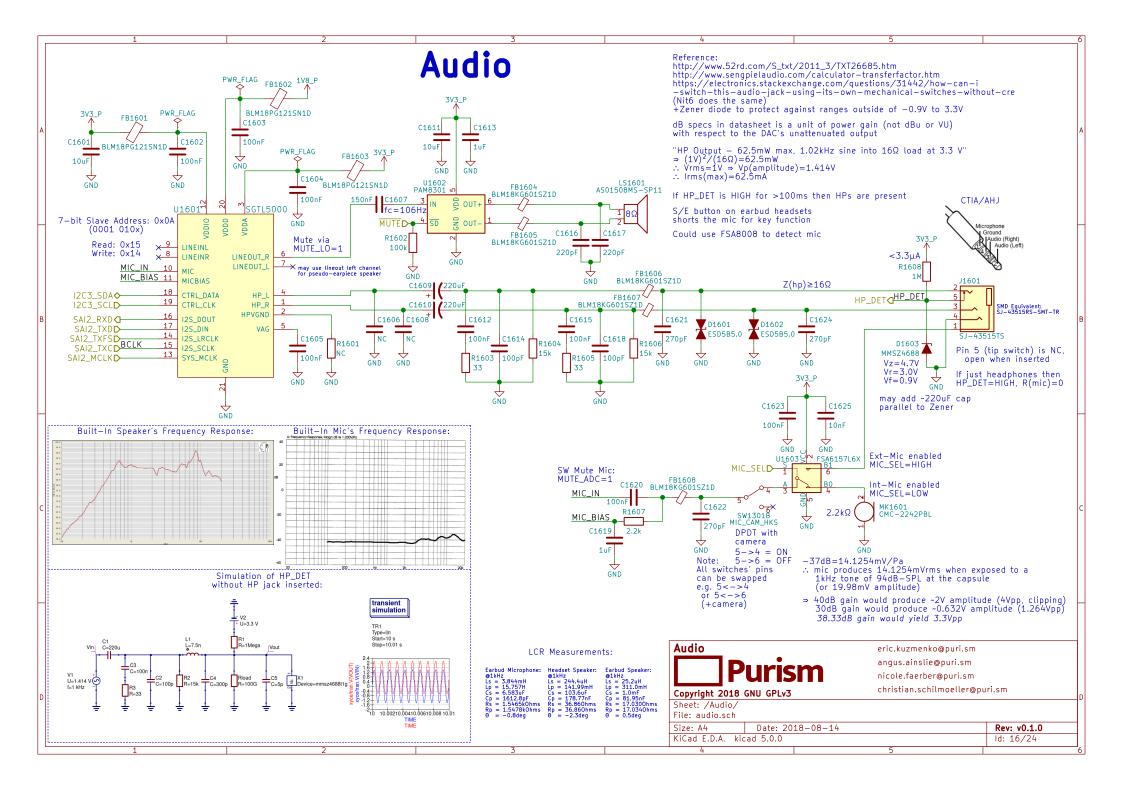


Use PWM2_PWMSAR to set the compare value (duty cycle)
Use PWM2_PWMCR[15:4] to set the PRESCALER (frequency)
Use PWM2_PWMPR to set the top of the counter (frequency)

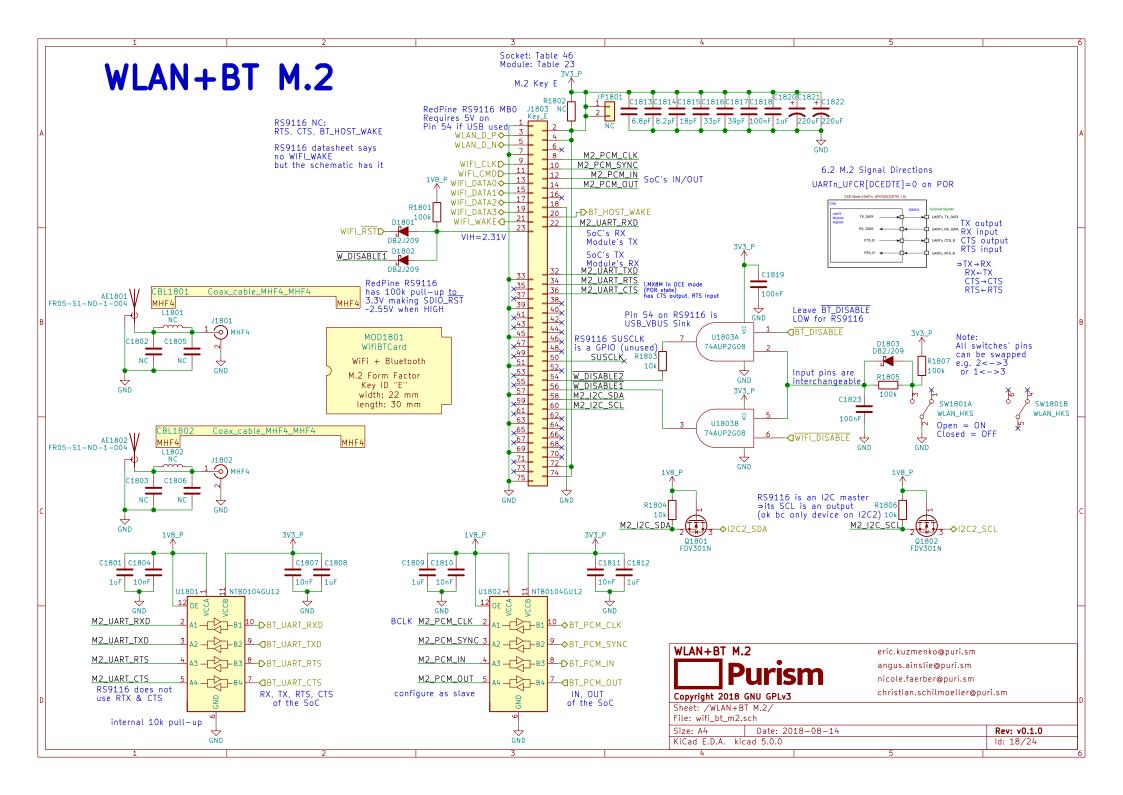


Buttons & LED		eric.kuzmenko@puri.sm				
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Copyright 2018	GNU GPLv3	christian.schilmoeller@puri.sm				
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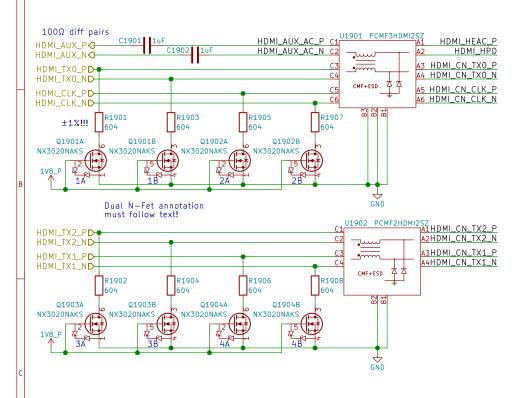


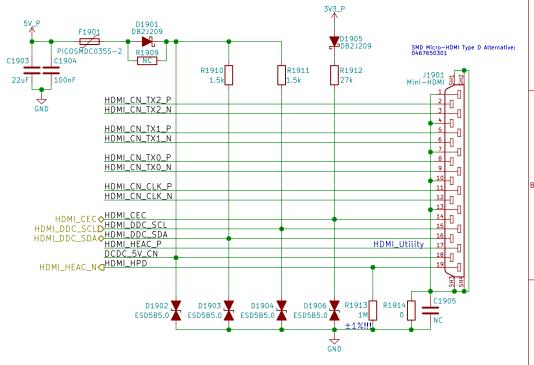






TUSB1046 can be used for DP over USB-C

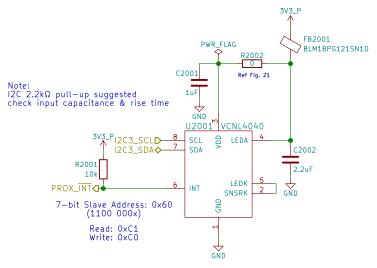






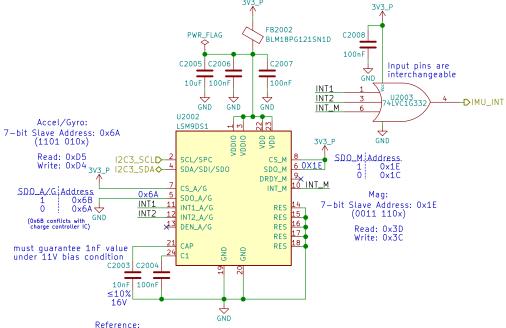
Sensors

Proximity & Ambient Light

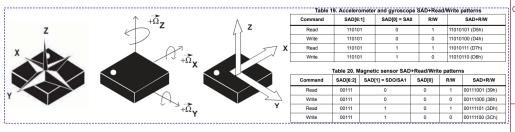


Reference: https://www.vishay.com/docs/84307/designingvcnl4040.pdf http://www.vishay.com/docs/84931/vcnl4040sensorboardfiles.pdf

9-Axis IMU



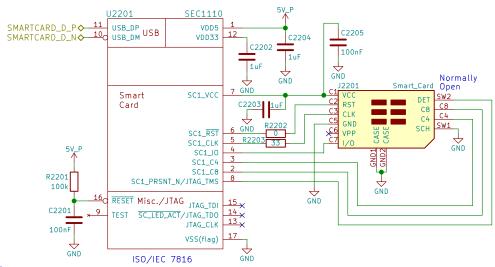
http://www.st.com/en/evaluation-tools/steval-mki159v1.html







Smart Card



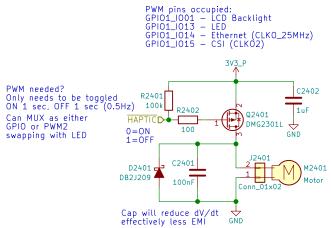
Reference: http://www.microchip.com/DevelopmentTools/ProductDetails.aspx?PartN0=EVB-SEC1110







Haptic Motor



When the motor is off both terminals are at GND Motor will have wire leads
with a 2-pin Molex or Boom Precision
connector installed (by request) Metal housing is floating thick adhesive layer underneath (not connected to either pin)

Haptic/Vibration Motor Copyright 2018 GNU GPLv3

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