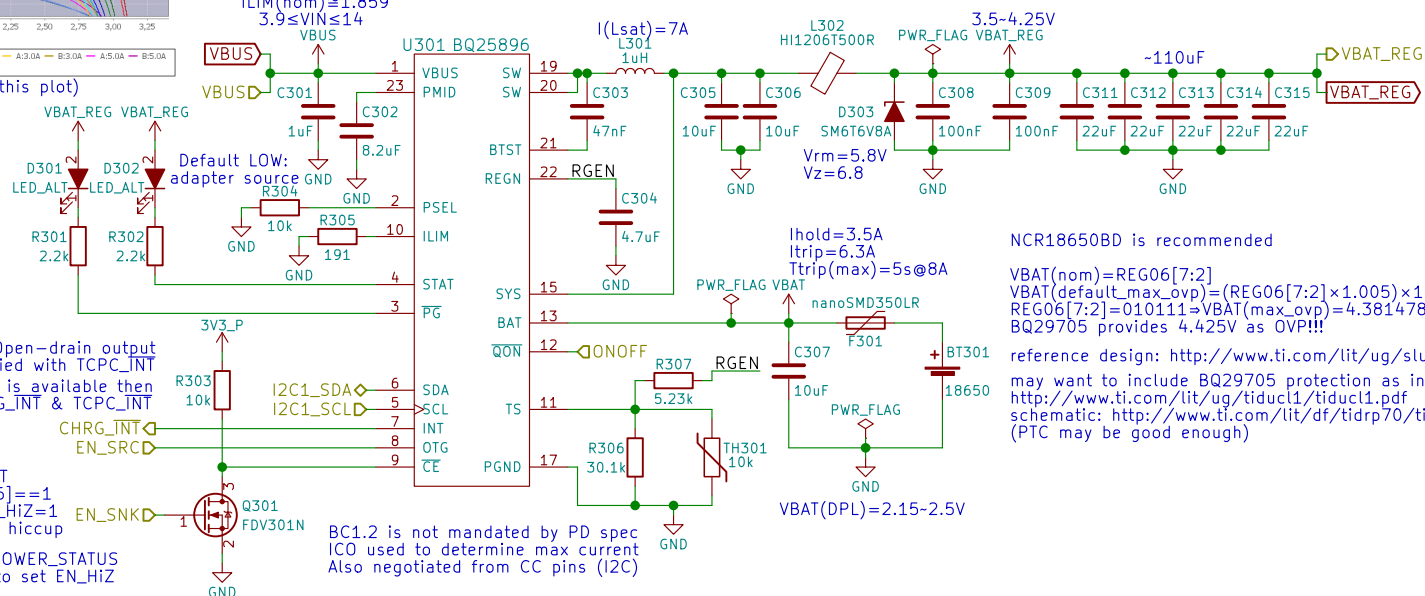


(interpret RSOC% based on this plot)

use AUTO_DPDM_EN
to auto-detect IINLIM

$1.658 \leq I_{LIM} \leq 2.063$
 $I_{LIM}(nom) \approx 1.859$
 $3.9 \leq V_{IN} \leq 14$

Battery Charge Controller



NCR18650BD is recommended

$V_{BAT}(nom) = REG06[7:2]$
 $V_{BAT}(default_max_ovp) = (REG06[7:2] \times 1.005) \times 1.04 = 4.3982016V$
 $REG06[7:2] = 010111 \Rightarrow V_{BAT}(max_ovp) = 4.3814784$
 BQ29705 provides 4.425V as OVP!!!

reference design: <http://www.ti.com/lit/ug/sluuba2b/sluuba2b.pdf>
 may want to include BQ29705 protection as in:
<http://www.ti.com/lit/ug/tiduc1/tiduc1.pdf>
 schematic: <http://www.ti.com/lit/df/tidrp70/tidrp70.pdf>
 (PTC may be good enough)

Open-drain output
tied with TCPC_INT
If enough I/O is available then
separate CHRG_INT & TCPC_INT

This disables charging
but maybe not VBUS->VOUT
if PTN5110HQ's FAULT_STATUS[6]=1
(Force Off VBUS bit) then set EN_HI_Z=1
EN_HI_Z may be auto-set when in hiccup

Reading PTN5110HQ's CC_STATUS and POWER_STATUS
registers will tell TCPM (i.MX8M) when to set EN_HI_Z

Also, reading PTN5110HQ's CC_STATUS and POWER_STATUS
registers will tell TCPM (i.MX8M) when to set OTG_CONFIG=1
(this will also happen when PTN5110HQ sets EN_SRC HIGH)

BC1.2 is not mandated by PD spec
ICO used to determine max current
Also negotiated from CC pins (I2C)

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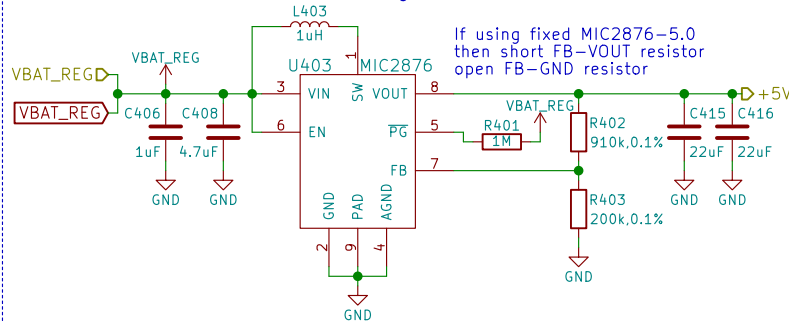
Sheet: /Battery/
File: battery.sch

Title: Battery

Size: A4 Date: 2018-05-15
KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0
Id: 3/21

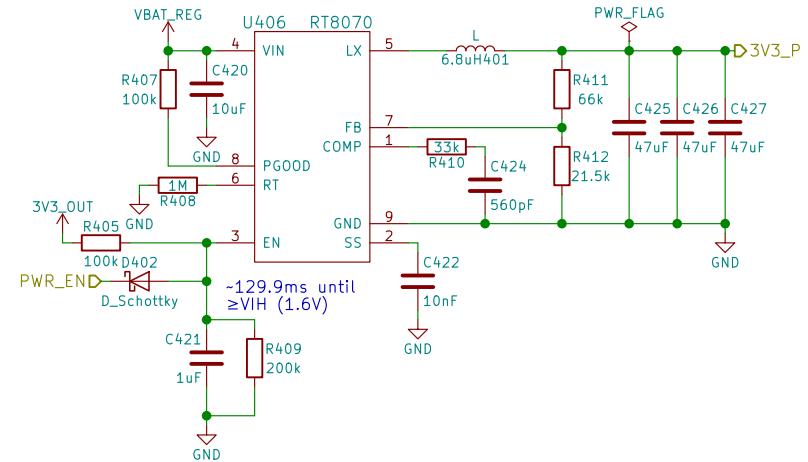
5.0V/3.8A



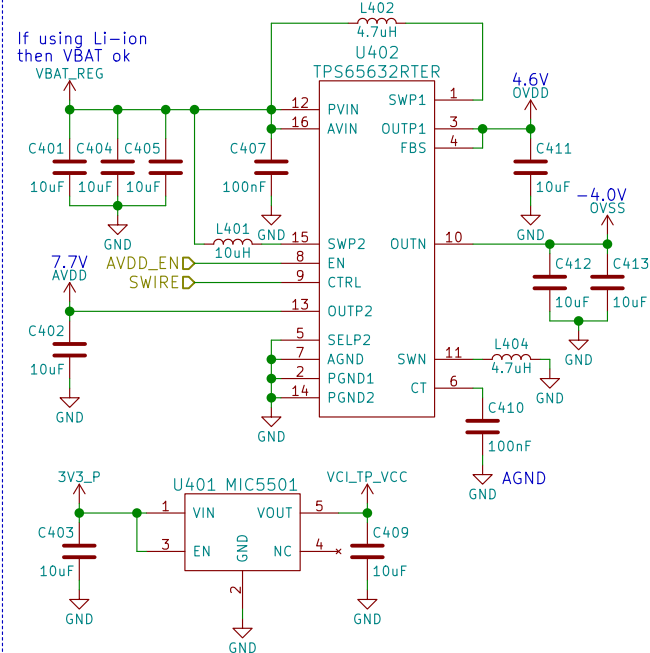
Cheaper, more efficient, smaller, and simpler than RT6150A
Explicitly mentions USB/smartphone application

3.3V/3A

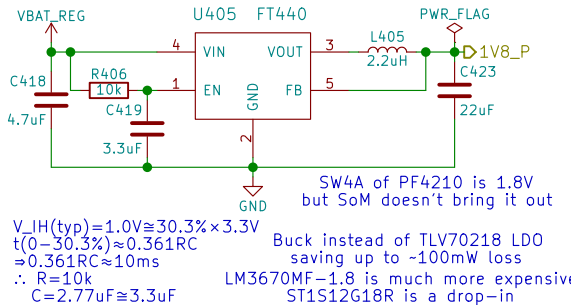
When VBAT can fall below 3.3V use TPS63020 instead!



AMOLED POWER



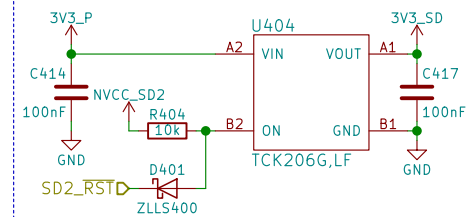
1.8V/600mA



$V_{IH}(typ)=1.0V \approx 30.3\% \times 3.3V$
 $t(0-30.3\%) \approx 0.361RC$
 $\approx 0.361 \times 10k \times 10ms$
 $\therefore R=10k$
 $C=2.77uF \approx 3.3uF$

Buck instead of TLV70218 LDO
saving up to ~100mW loss
LM3670MF-1.8 is much more expensive
ST1S12G18R is a drop-in

SD POWER



TODO:
add parallel 100nF bulk caps!
& spread all over the power plane

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Sheet: /Power/
File: power.sch

Title: Power

Size: A4
KiCad E.D.A. kicad 4.0.7

Date: 2018-05-15

Rev: v0.1.0

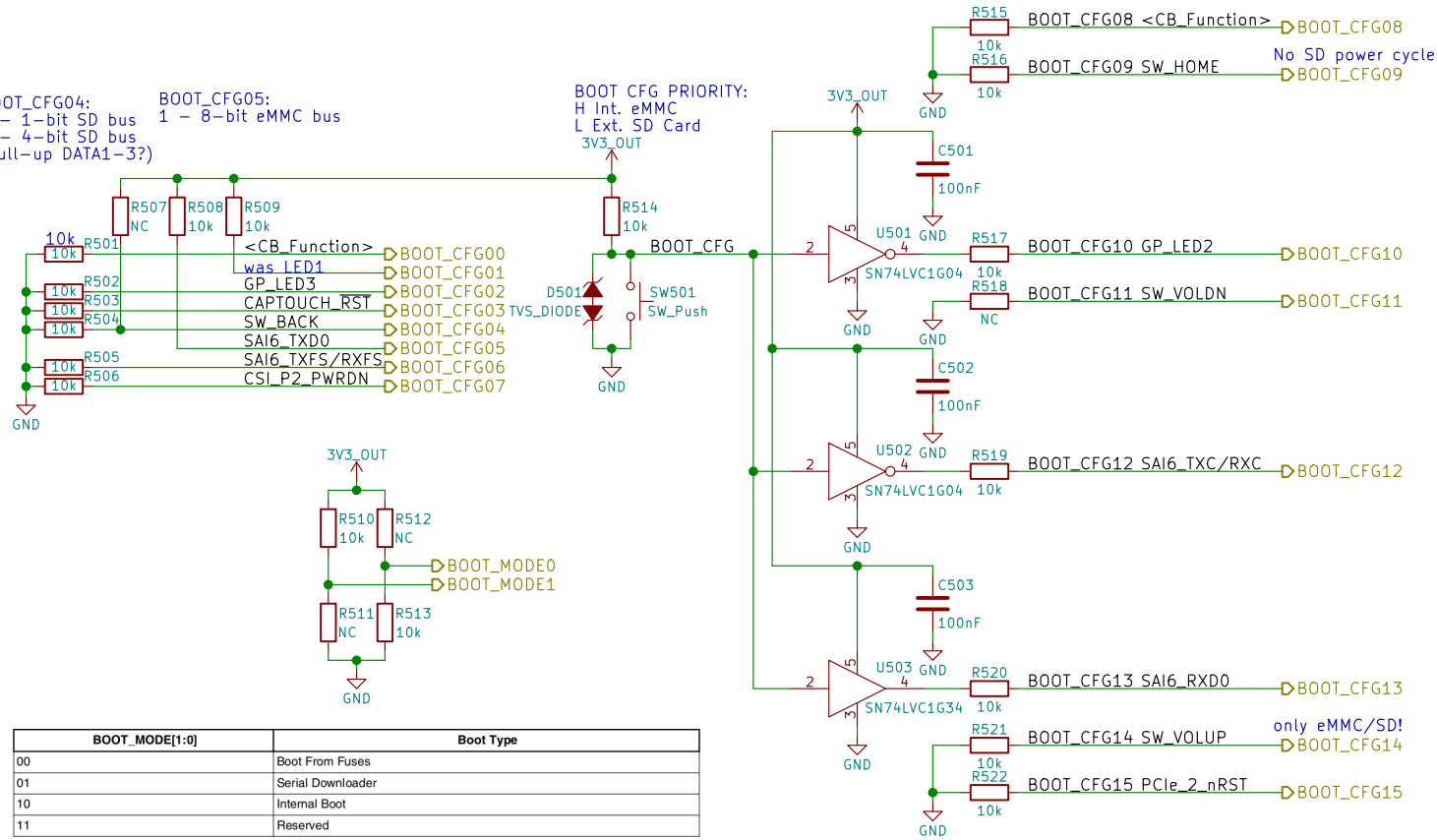
Id: 4/21

| BOOT_CFG[14:12] | | | Boot device | | |
|-----------------|--------|----------------------|-------------------|---------------|---|
| 001 | | | SD/eSD | | |
| 010 | | | MMC/eMMC | | |
| 011 | | | NAND | | |
| Fuse | Config | Definition | GPIO ¹ | Shipped value | Settings |
| BOOT_CFG[11:10] | OEM | USDHC port selection | Yes | 00 | 00 - USDHC-1 01 - USDHC-2 10 - USDHC-3 else - reserved |

BOOT_CFG04:
0 - 1-bit SD bus
0 - 4-bit SD bus
(pull-up DATA1-3?)

BOOT_CFG05:
1 - 8-bit eMMC bus

BOOT CFG PRIORITY:
H Int. eMMC
L Ext. SD Card



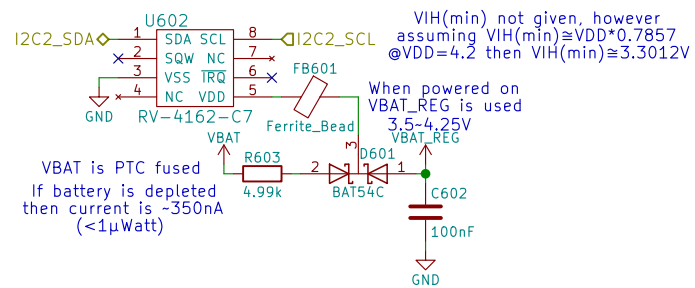
GNU GPLv3
Copyright 2018
Purism SPC

Sheet: /Boot Config/
File: boot.sch

Title: Boot Configuration

Size: A4 Date: 2018-05-15
KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0
Id: 5/21



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Sheet: /RTC/
File: rtc.sch

Title: RTC

Size: A4 Date: 2018-05-15

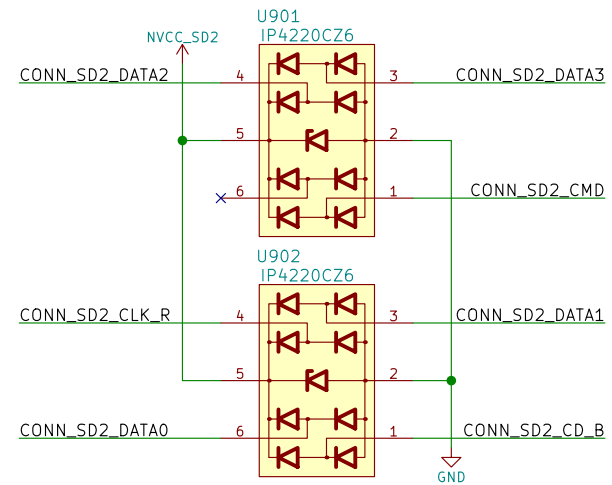
KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0

Id: 6/21

Id: 7/21

Id: 8/21



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Sheet: /uSD Card/

File: sd.sch

Title: uSD Card

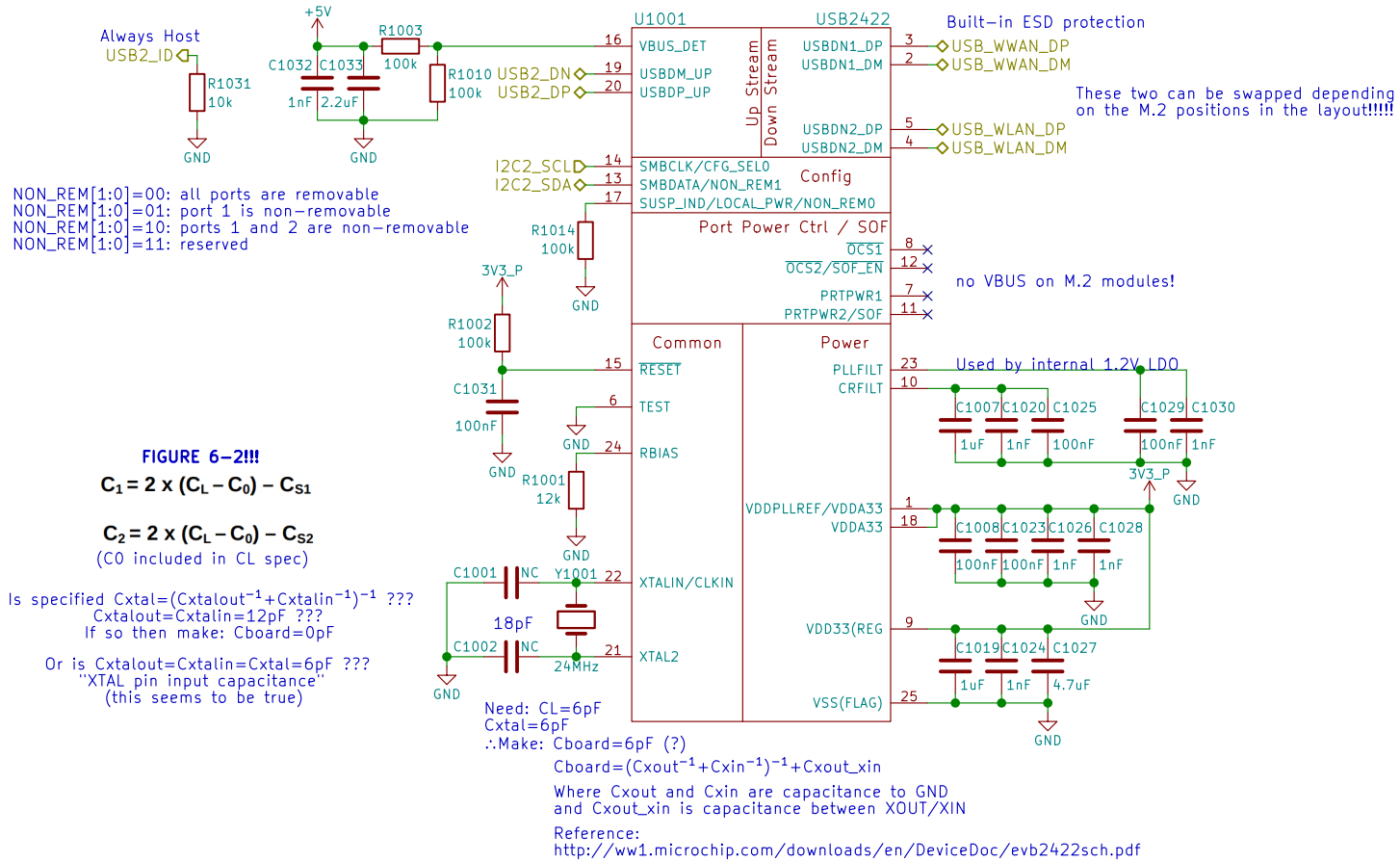
Size: A4 Date: 2018-05-15

KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0

Id: 9/21

TODO:
Use USB4640???



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Sheet: /USB Hub/

File: usb_hub.sch

Title:

Size: A4

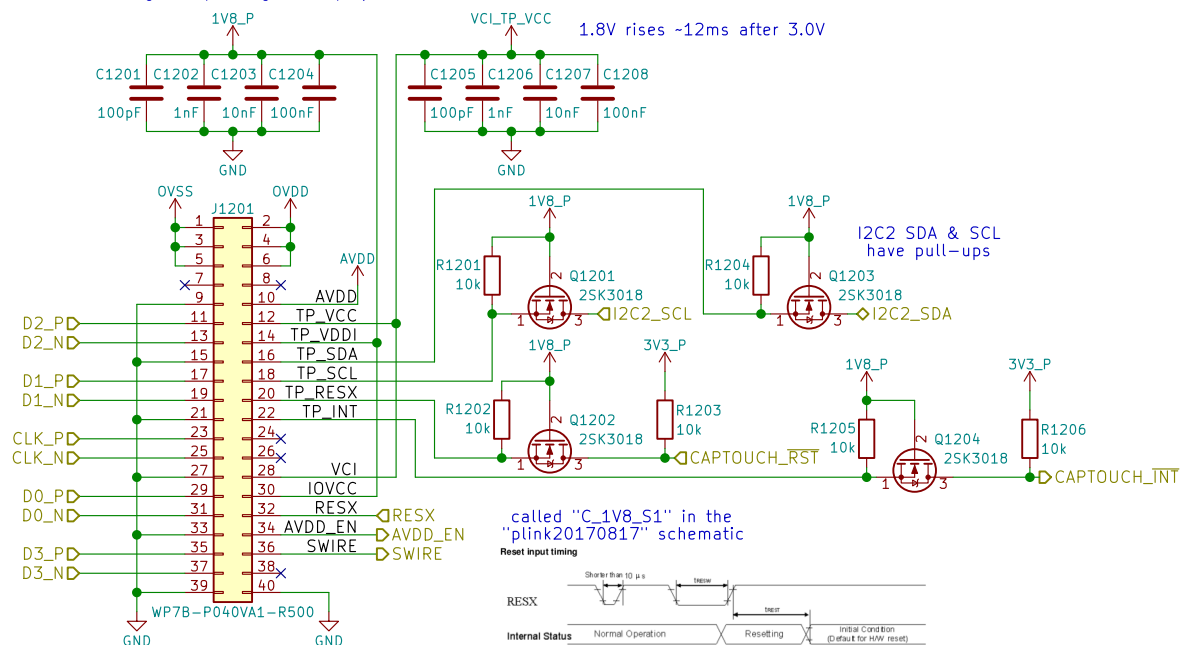
Date: 2018-05-15

Rev: v0.1.0

KiCad E.D.A. kicad 4.0.7

Id: 10/21

Using H546DLB01.1 pin assignment may need to be changed depending on display used



TODO: low power state signal??

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Sheet: /MIPI DSI/
File: mipi_dsi.sch

Title: MIPI DSI

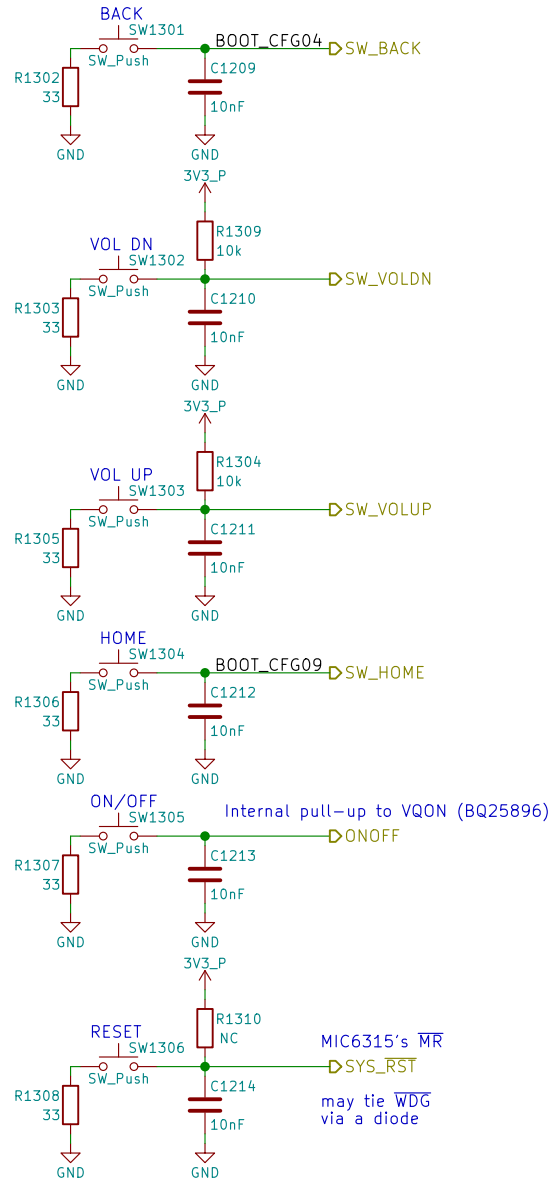
Size: A4 Date: 2018-05-15

KiCad E.D.A. kicad 4.0.7

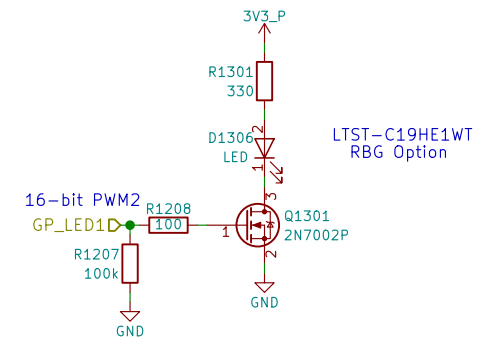
Rev: v0.1.0

Id: 11/21

SW NOTE:
Need to set Int. PU in SOC
on SW_BACK and SW_HOME



Use PWM2_PWMSAR to set the compare value (duty cycle)
Use PWM2_PWMCR[15:4] to set the PRESCALER (frequency)
Use PWM2_PWMPR to set the top of the counter (frequency)



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Purism SPC

Sheet: /Buttons & LED/
File: buttons_led.sch

Title: Buttons & LED

Size: A4 Date: 2018-05-15

KiCad E.D.A. kicad 4.0.7

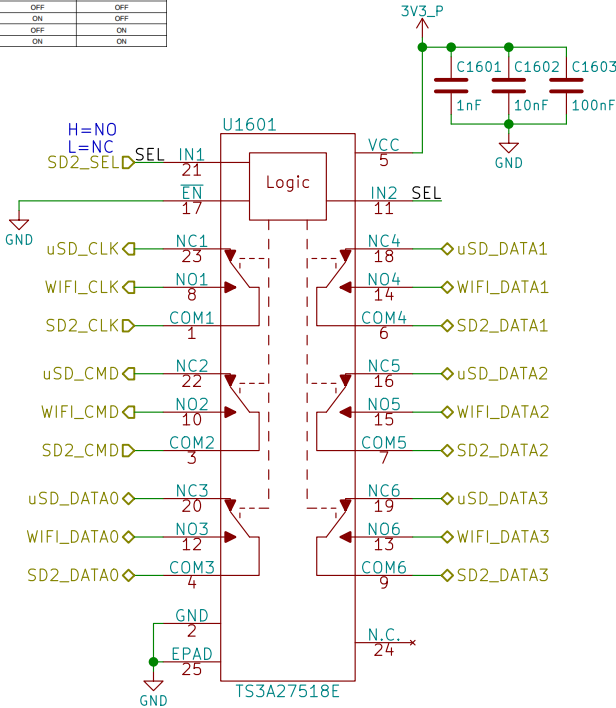
Rev: v0.1.0

Id: 12/21



Can swap around signals in the layout:

| EN | IN1 | IN2 | NC1023 TO COM1023, COM1023 TO NC1023 | NC4056 TO COM4056, COM4056 TO NC4056 | NC1023 TO COM1023, COM1023 TO NC1023 | NC4056 TO COM4056, COM4056 TO NC4056 |
|----|-----|-----|---|---|---|---|
| H | X | X | OFF | OFF | OFF | OFF |
| L | L | L | ON | ON | OFF | OFF |
| L | H | L | OFF | ON | ON | OFF |
| L | L | H | ON | OFF | OFF | ON |
| L | H | H | OFF | OFF | ON | ON |



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Sheet: /SDIO DEMUX/
File: sdio_demux.sch

Title: SDIO Demultiplexer

Size: A4 Date: 2018-05-15
KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0
Id: 15/21

Id: 16/21

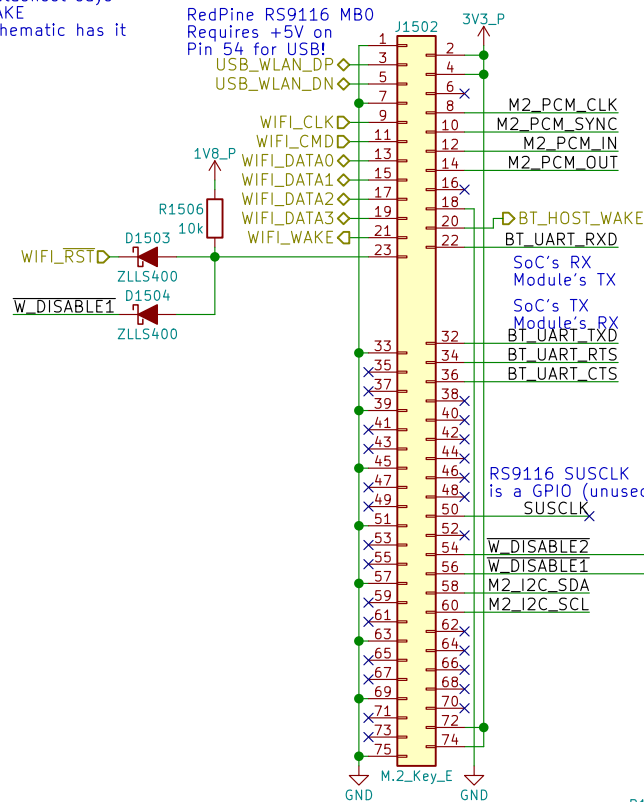
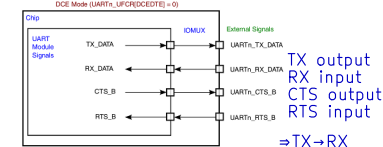
RS9116 NC:
RTS, CTS, BT_HOST_WAKE

RS9116 datasheet says
no WIFI_WAKE
but the schematic has it

6.2 M.2 Signal Directions

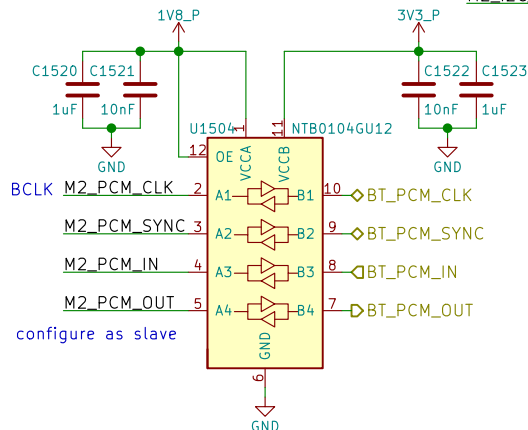
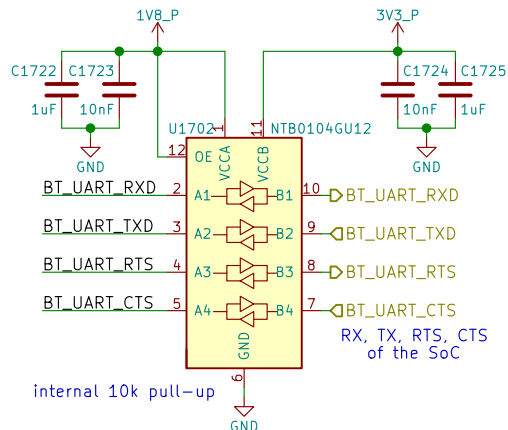
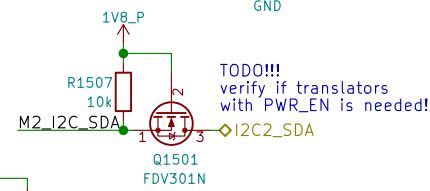
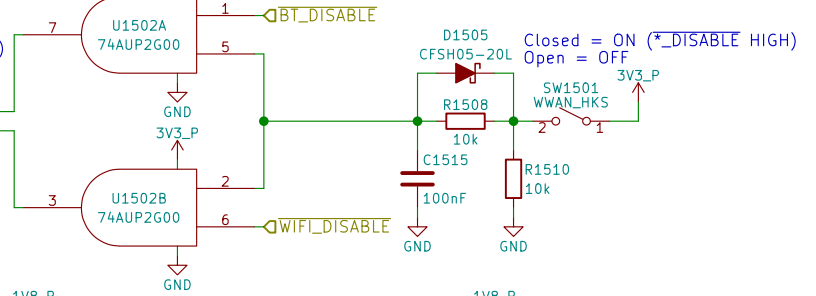
Module: Table 23
Socket: Table 46

UARTn_UFCR[DCEDTE]=0 on POR



i.MX8M in DCE mode has
CTS output, RTS input

TODO:
Pin 54 on RS9116 is USB_VBUS Sink!!!



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Purism SPC

Sheet: /WLAN+BT M.2/
File: wifi_bt_m2.sch

Title: WLAN+BT M.2

Size: A4 Date: 2018-05-15

KiCad E.D.A. kicad 4.0.7

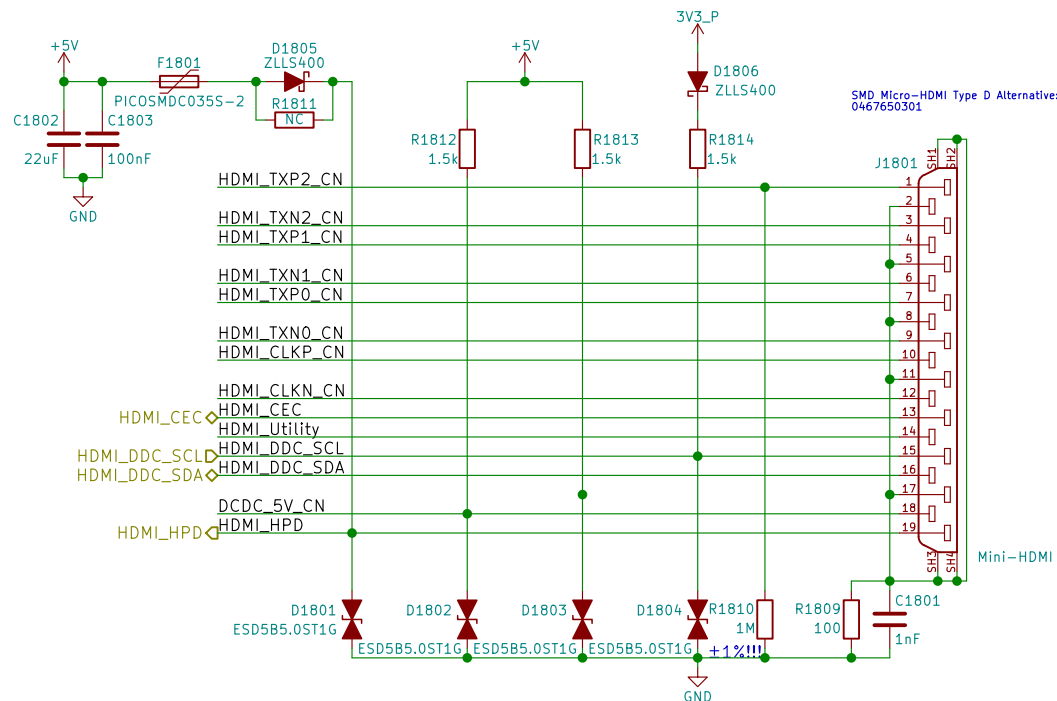
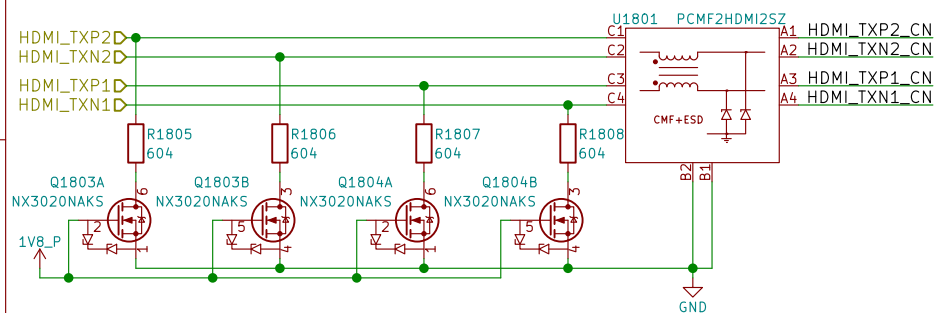
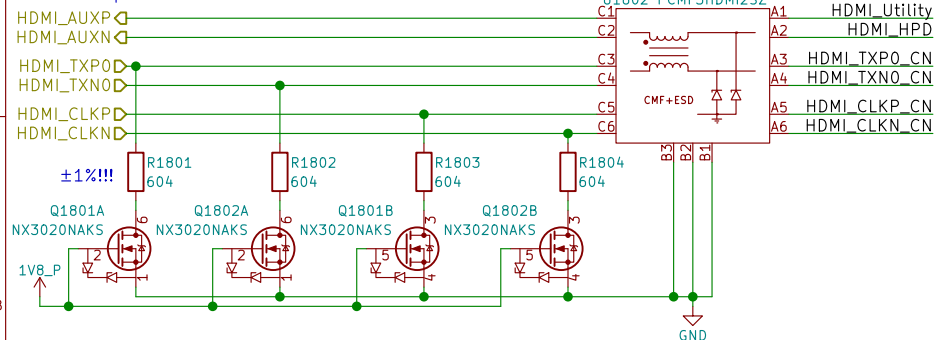
Rev: v0.1.0

Id: 17/21

HD3SS460 can be used for DP over USB-C

Layout Note:
May need swap some signals
due to micro-HDMI pinout diff
depending on pin location/routing

100Ω diff pairs



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Purism SPC

Sheet: /HDMI/
File: hdmi.sch

Title: HDMI

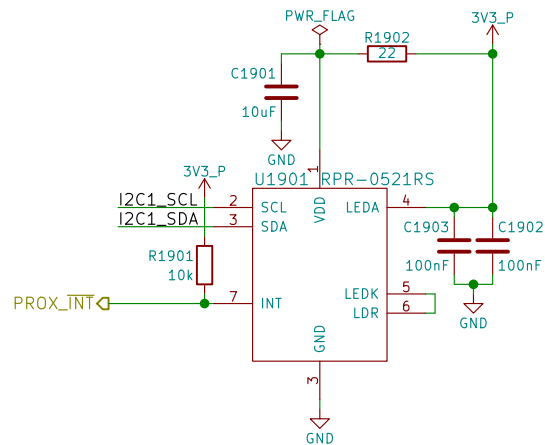
| | |
|----------|------------------|
| Size: A4 | Date: 2018-05-15 |
|----------|------------------|

| | |
|--------------|-------------|
| Size: A1 | Date: |
| KiCad E.D.A. | kicad 4.0.7 |

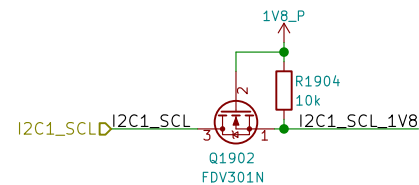
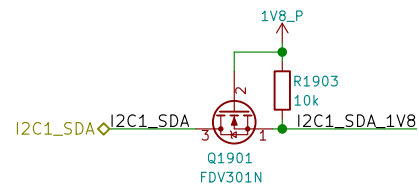
Rev: v0.1.0

Id: 18/21

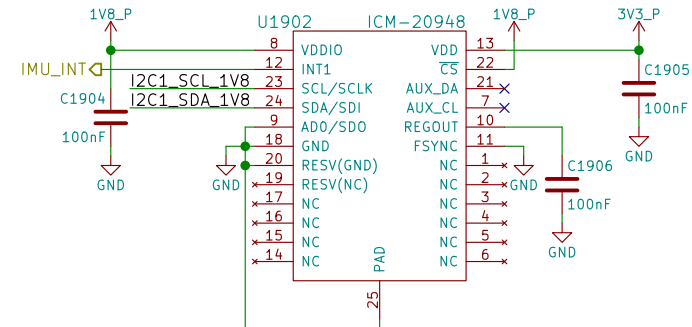
Proximity & Ambient Light



Reference:
<http://www.rohm.com/web/global/sensor-shield-support/ps-als-sensor>



9-Axis IMU



Reference:
<https://store.invensense.com/datasheets/invensense/AN-IVS-0001EVB-00%20v1%202.pdf>

AD0 sets the slave address's LSB (110100X)

INT1_ACTL sets if IMU_INT is active-high or active-low

"FSYNC - Connect to GND if unused"

I2C's VIH=1.8V

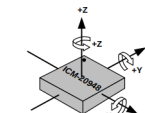


Figure 12. Orientation of Axes of Sensitivity and Polarity of Rotation

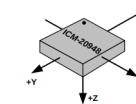


Figure 13. Orientation of Axes of Sensitivity for Magnetometer

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Purism SPC

Sheet: /Sensors/
 File: sensors.sch

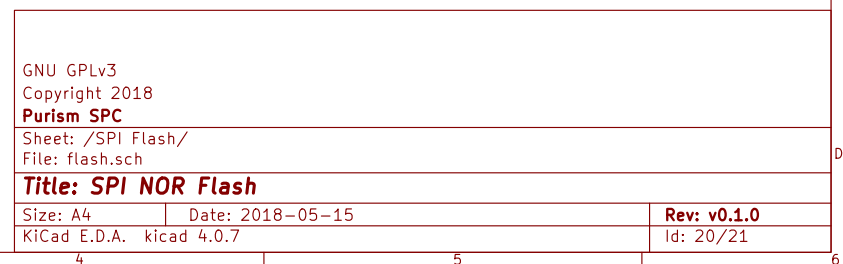
Title: Sensors

Size: A4 Date: 2018-05-15

KiCad E.D.A. kicad 4.0.7

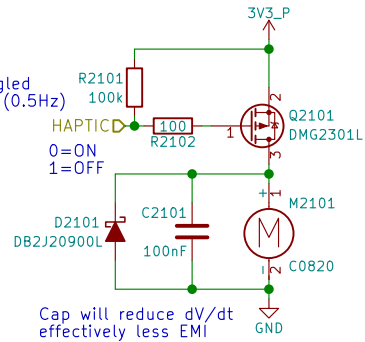
Rev: v0.1.0

Id: 19/21



PWM pins occupied:
 GPIO1_I001 - DSI (DSL_BL_PWM??)
 GPIO1_I013 - LED
 GPIO1_I014 - Ethernet (CLKO_25MHz)
 GPIO1_I015 - CSI (CLKO2)

PWM needed?
 Only needs to be toggled
 ON 1 sec, OFF 1 sec (0.5Hz)



When the motor is off
 both terminals are at GND

Motor will have wire leads
 with a 2-pin Molex or JST
 connector installed (by request)!

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Purism SPC

Sheet: /Haptic Motor/
 File: haptic.sch

Title: Haptic/Vibration Motor

Size: A4 Date: 2018-05-15

KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0

Id: 21/21