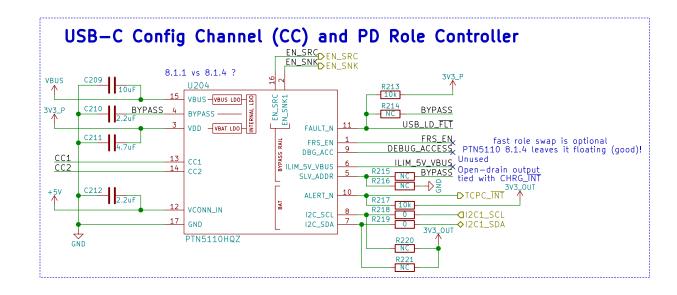
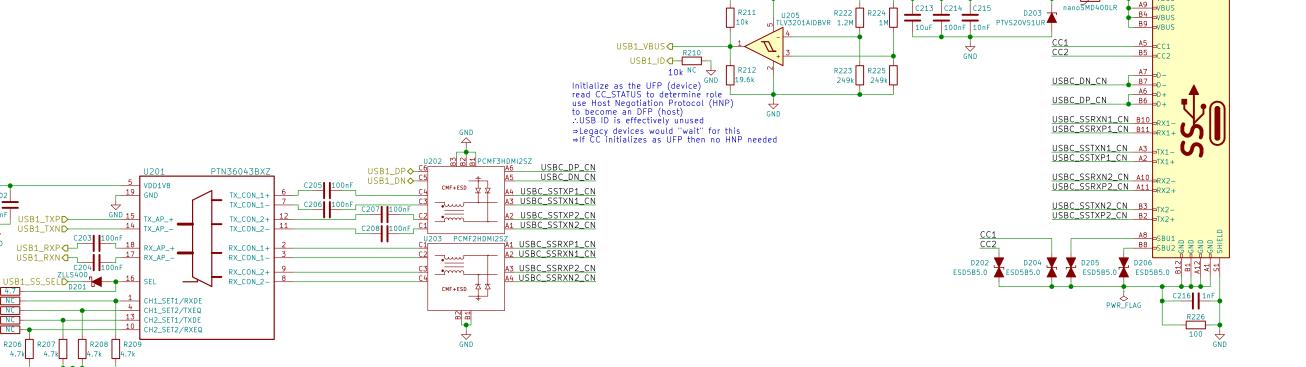


"Under dead battery operation, PTN5110 applies voltage clamps to both CC pins so that the system may receive power as a Sink. To support platforms with buck—boost configuration, PTN5110 asserts EN_SNK1 pin based on validity of VBUS voltage (facilitates 5 V VBUS sinking)."



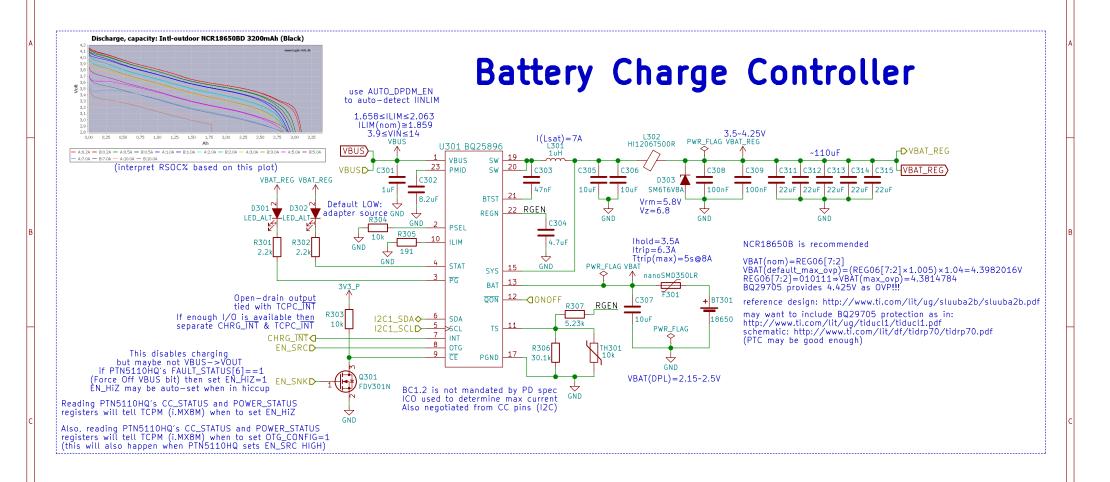
 $USB1_VBUS=+5V$ when VBUS>4.31V

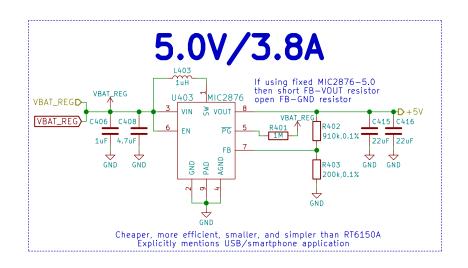


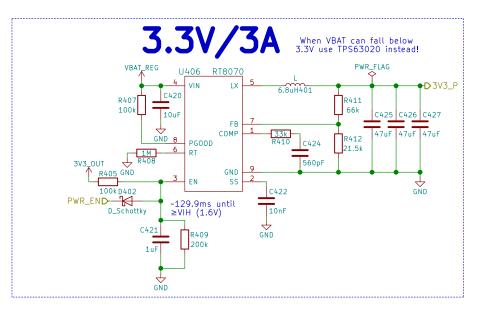
VBUS ◆ D VBUS

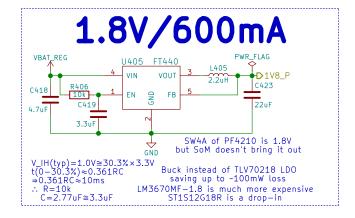
Ihold=4A Itrip=8A PWR_FLAG F201 →

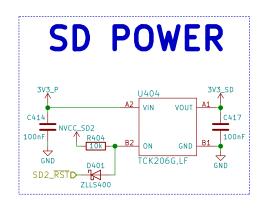
J201 USB_C_Receptacle



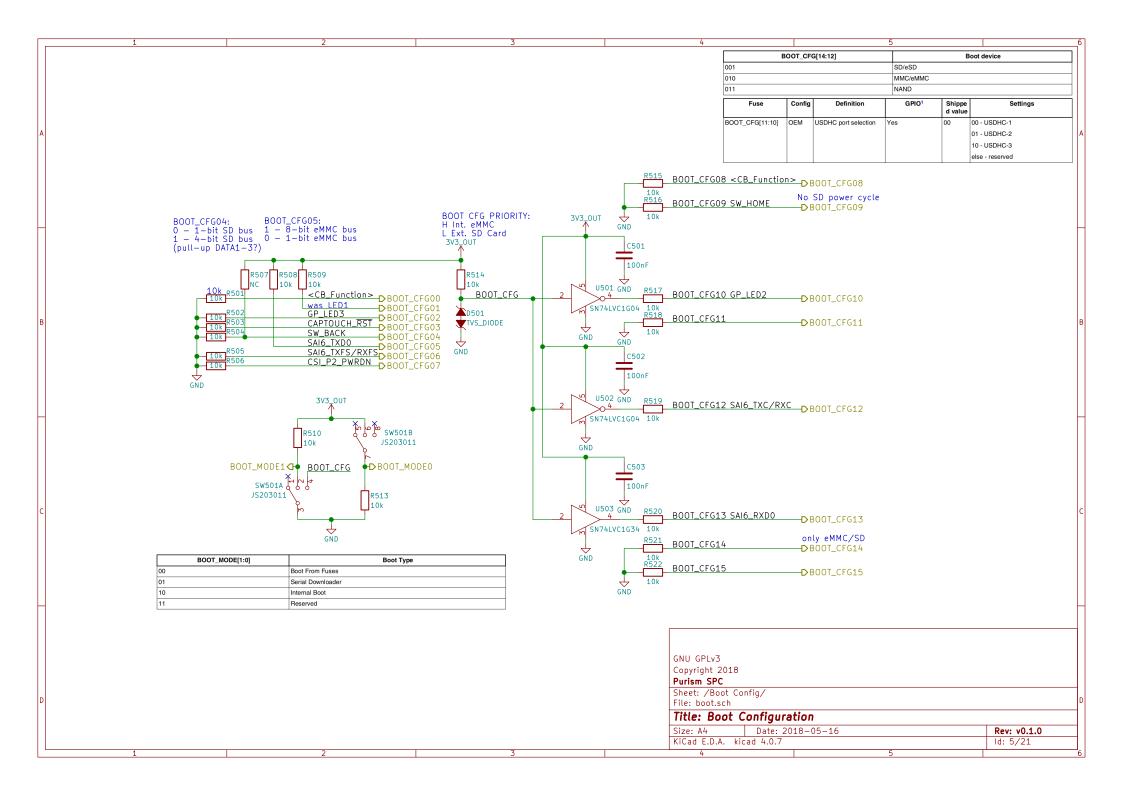


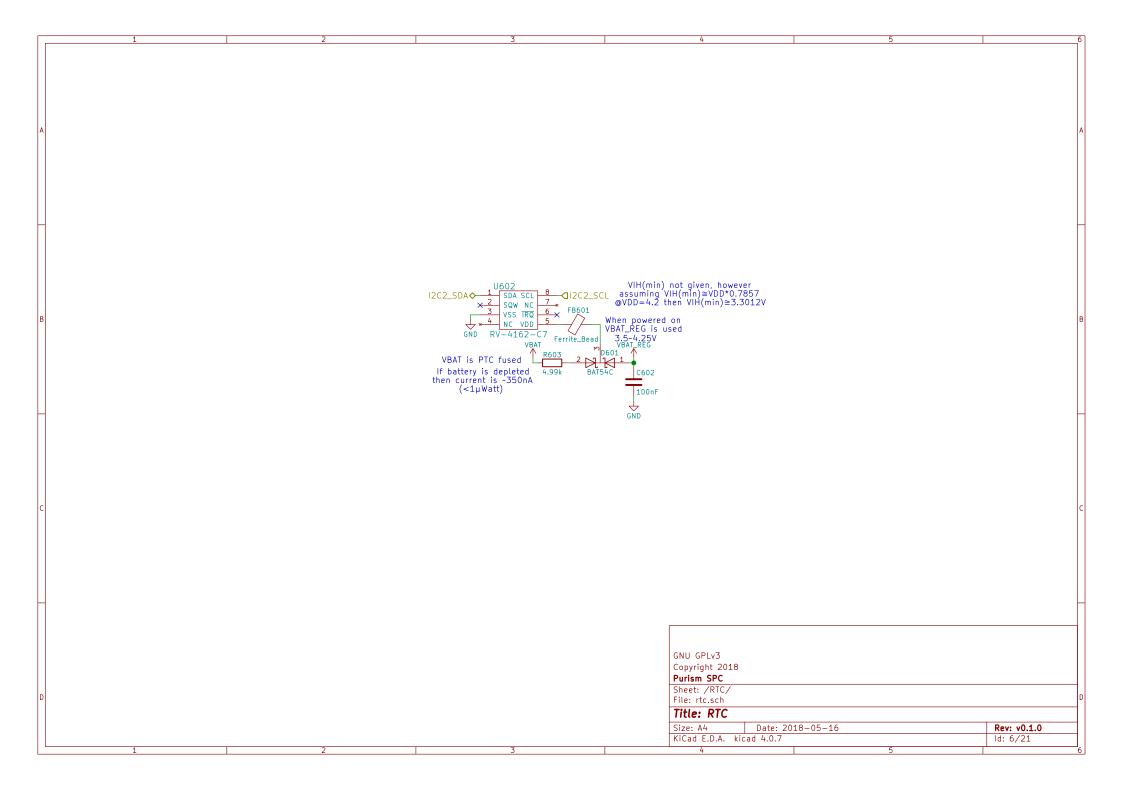


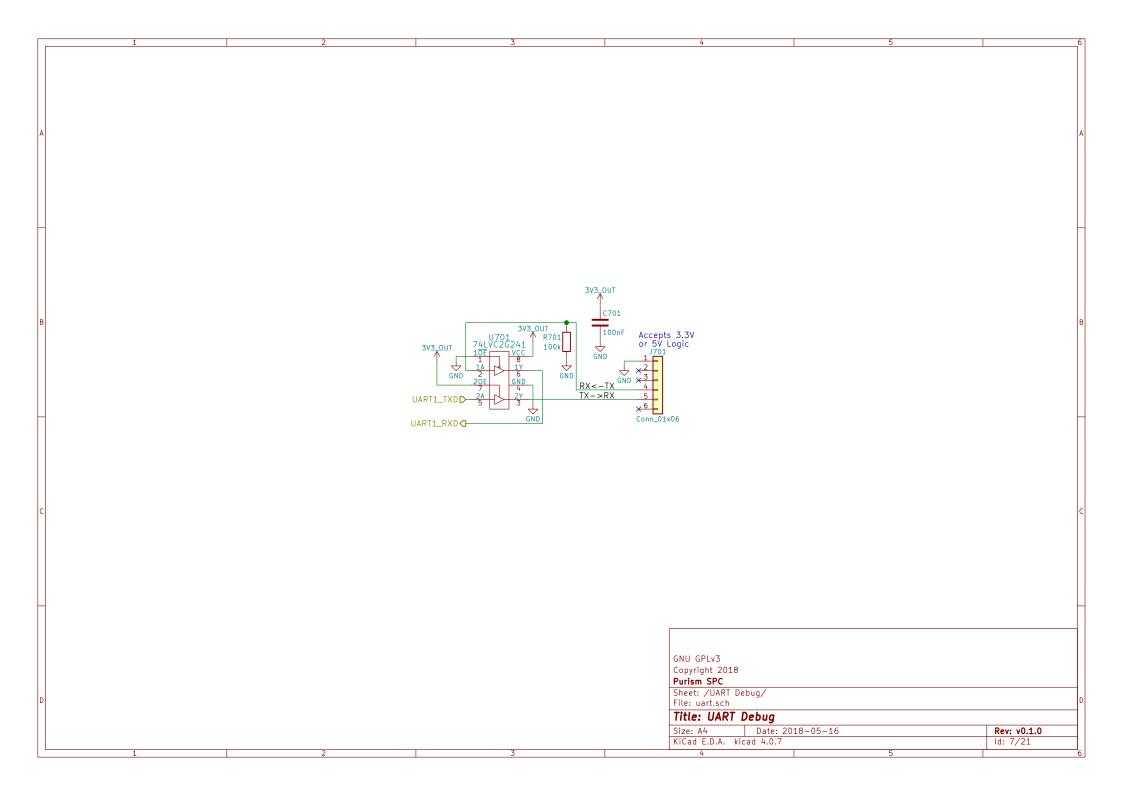


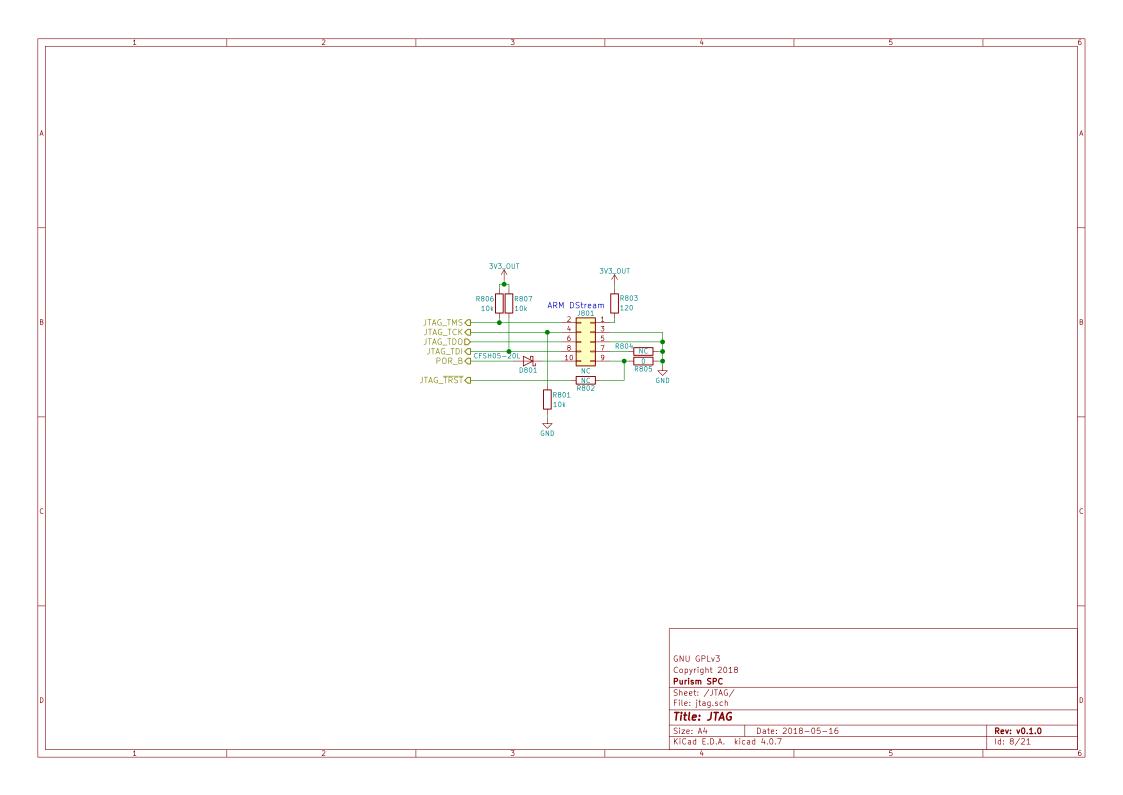


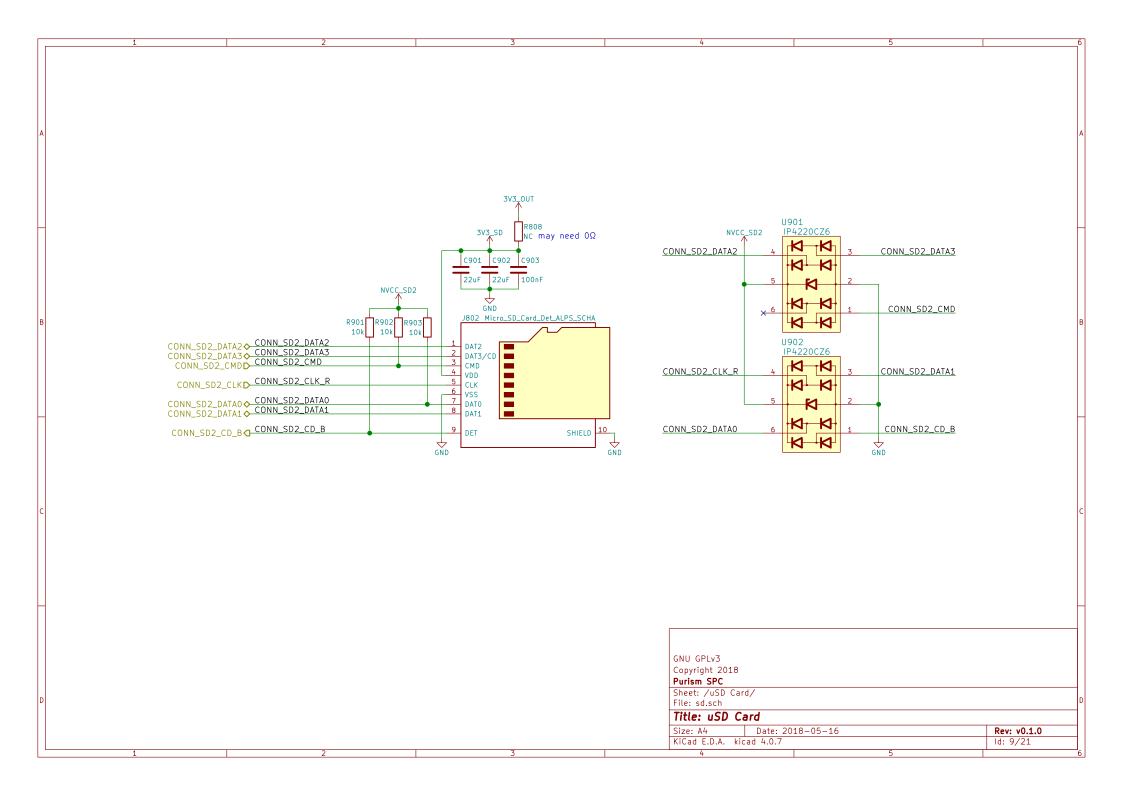
TODO: add parallel 100nF bulk caps! & spread all over the power plane

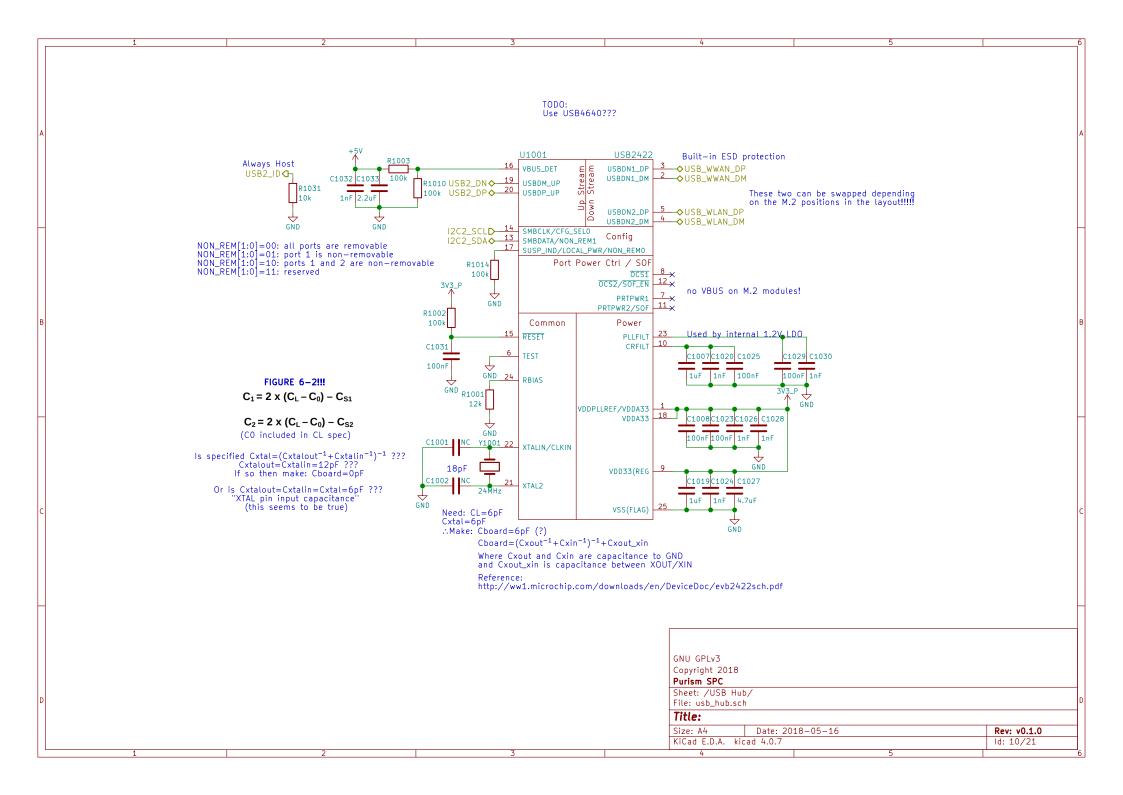


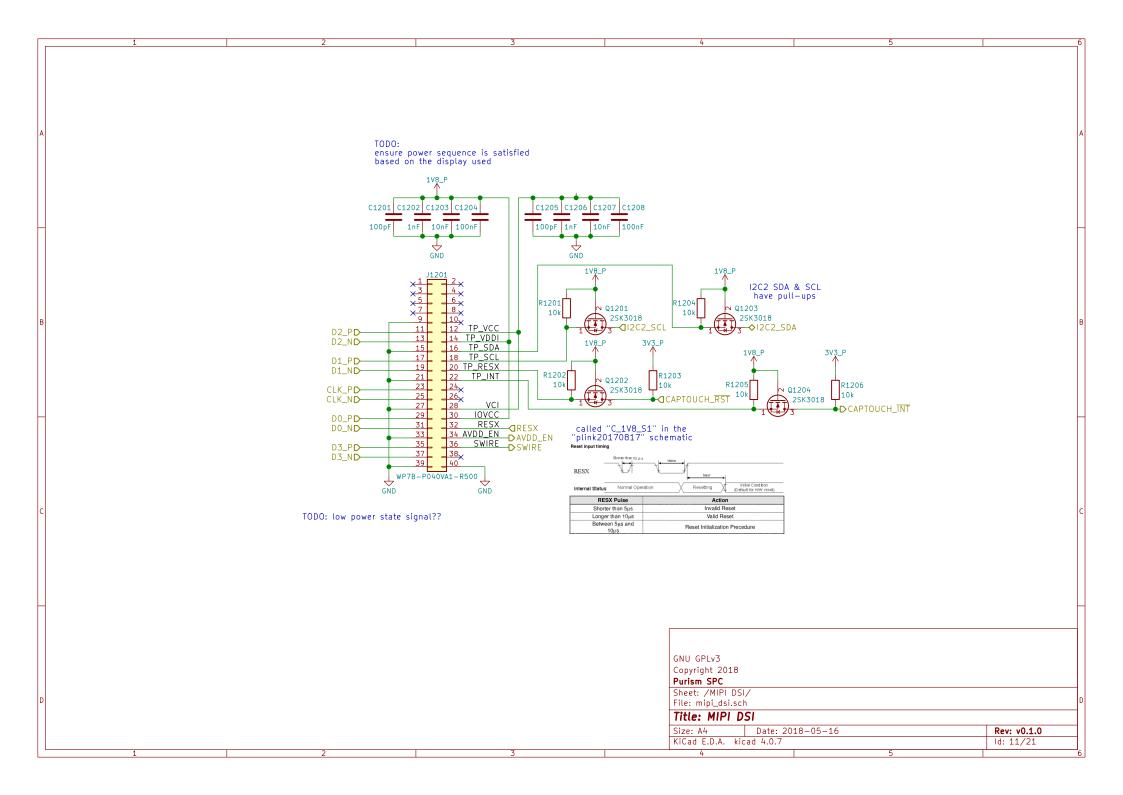


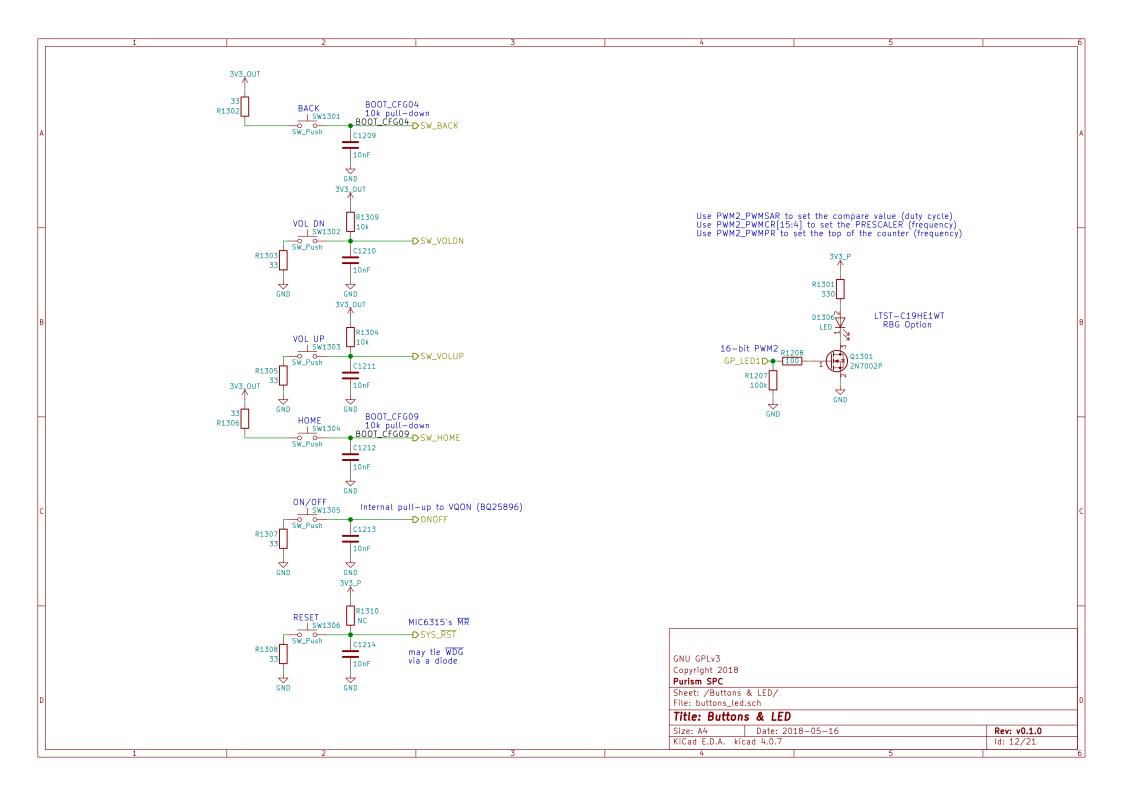


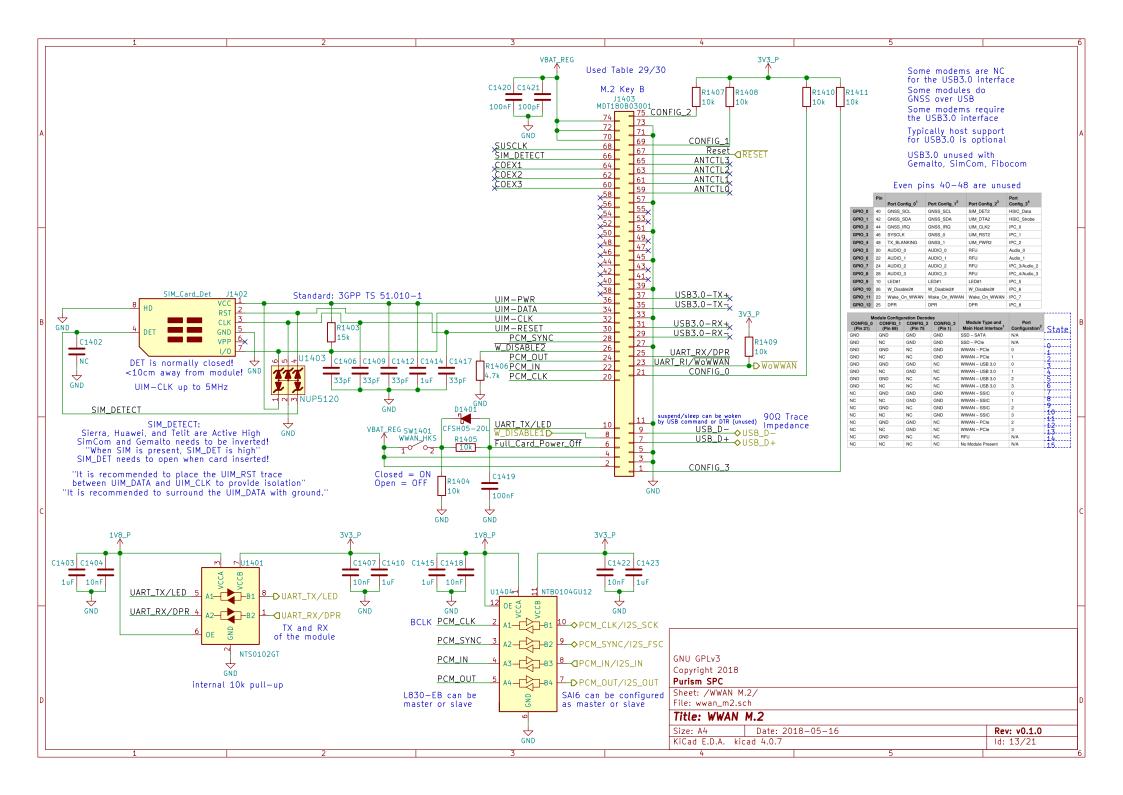


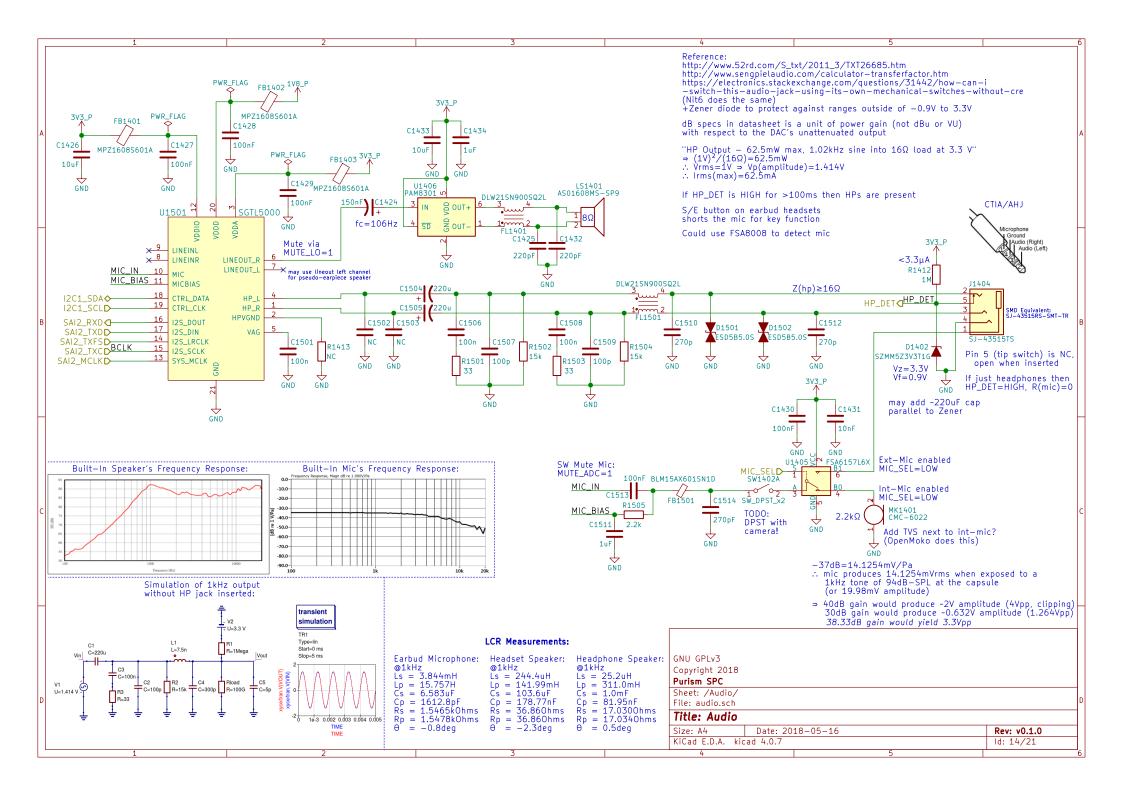


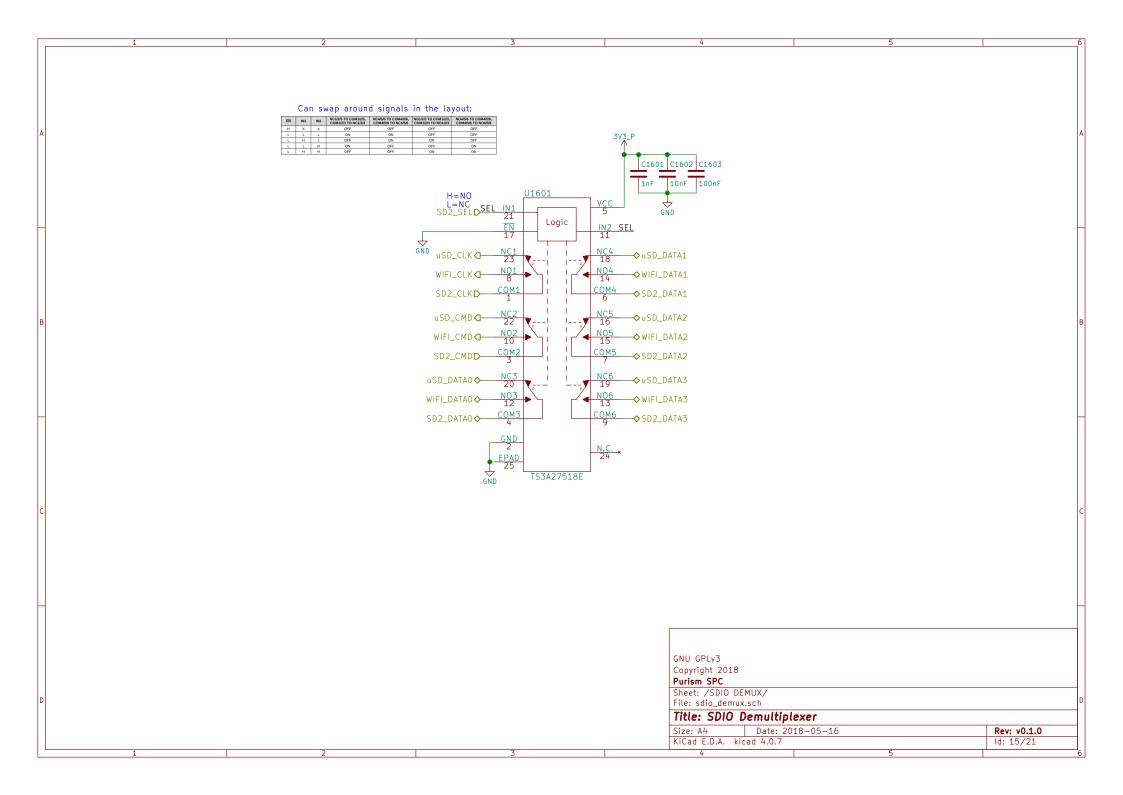


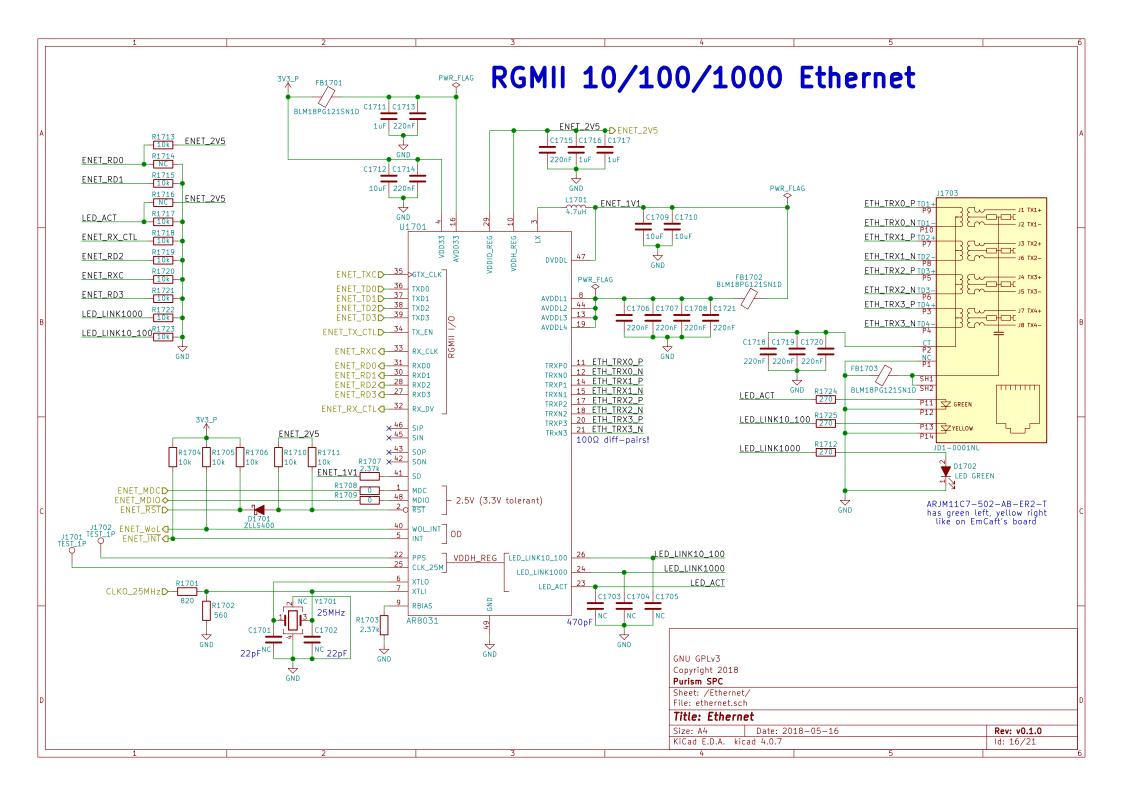


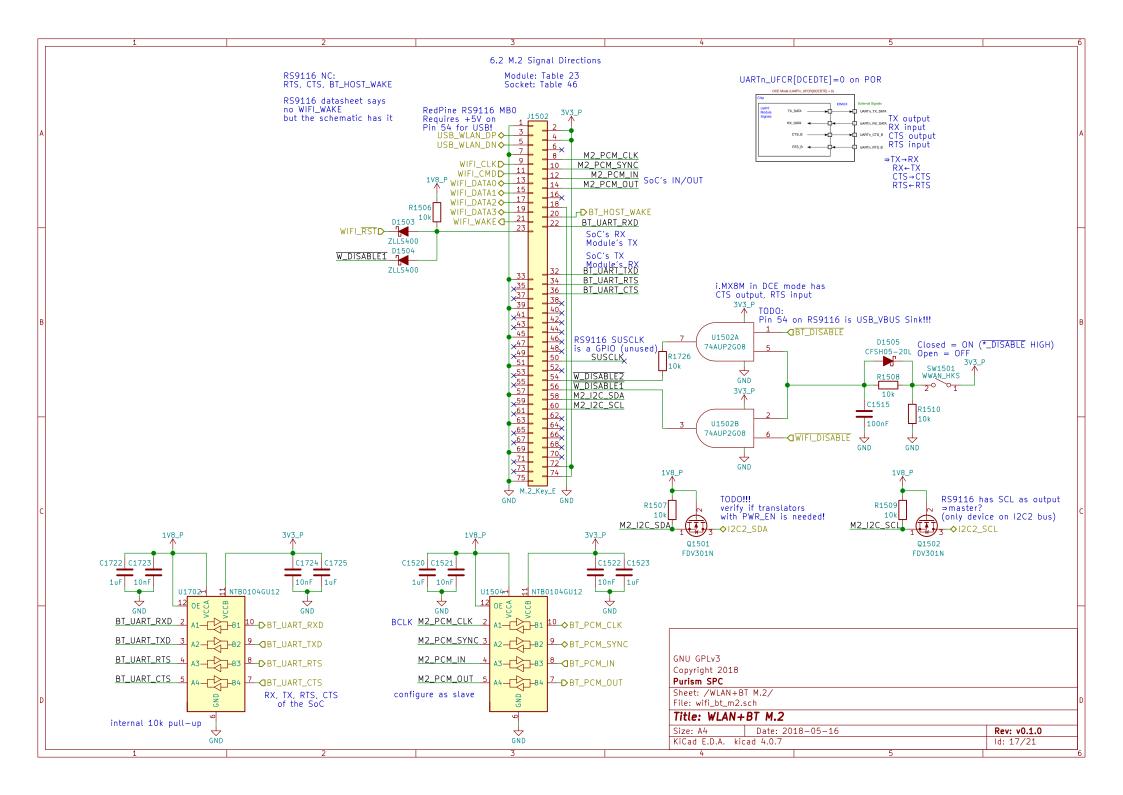


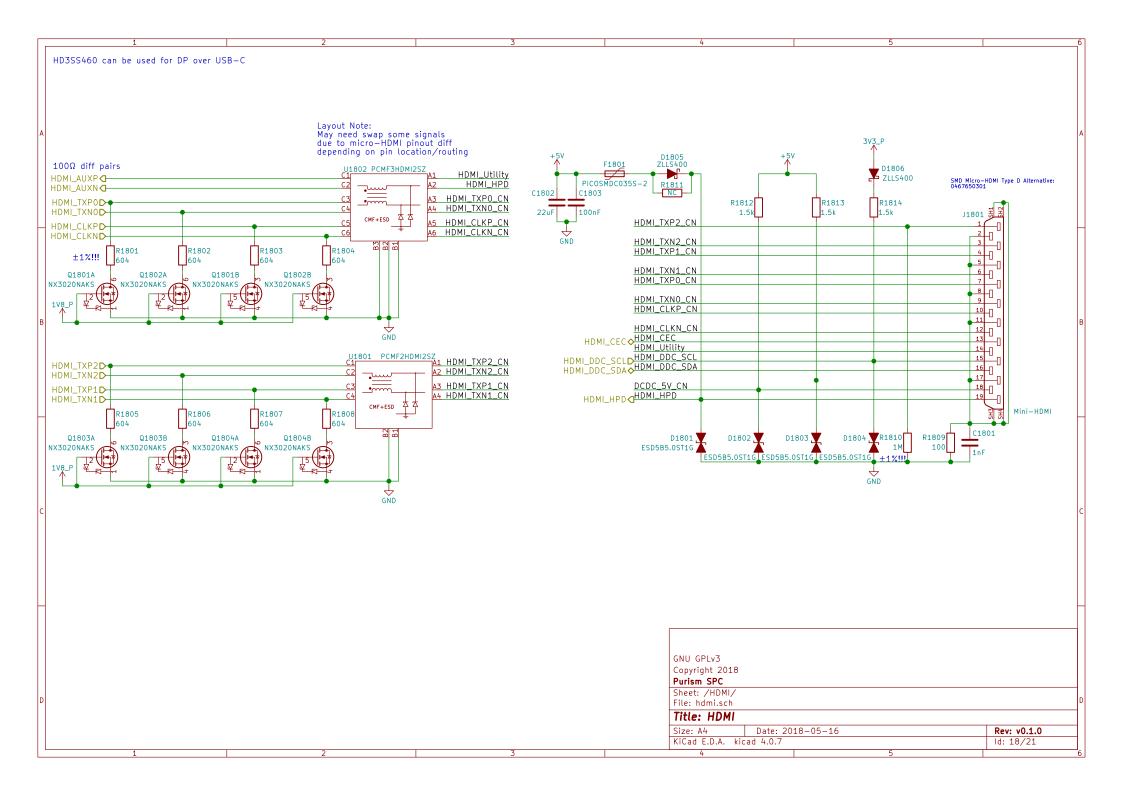




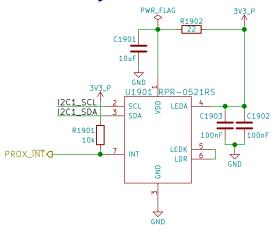




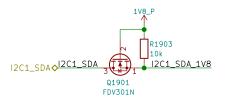




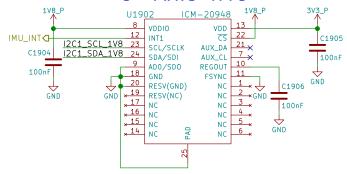
Proximity & Ambient Light



Reference: http://www.rohm.com/web/global/sensor-shield-support/ps-als-sensor



9-Axis IMU



Peference:

https://store.invensense.com/datasheets/invensense/AN-IVS-0001EVB-00%20v1%202.pdf

ADO sets the slave address's LSB (110100X)

INT1_ACTL sets if IMU_INT
is active—high or active—low

"FSYNC - Connect to GND if unused"

12C's VIH=1.8V

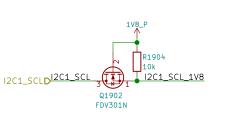




Figure 12. Orientation of Axes of Sensitivity and Polarity of Rotation



Figure 13. Orientation of Axes of Sensitivity for Magnetometer

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