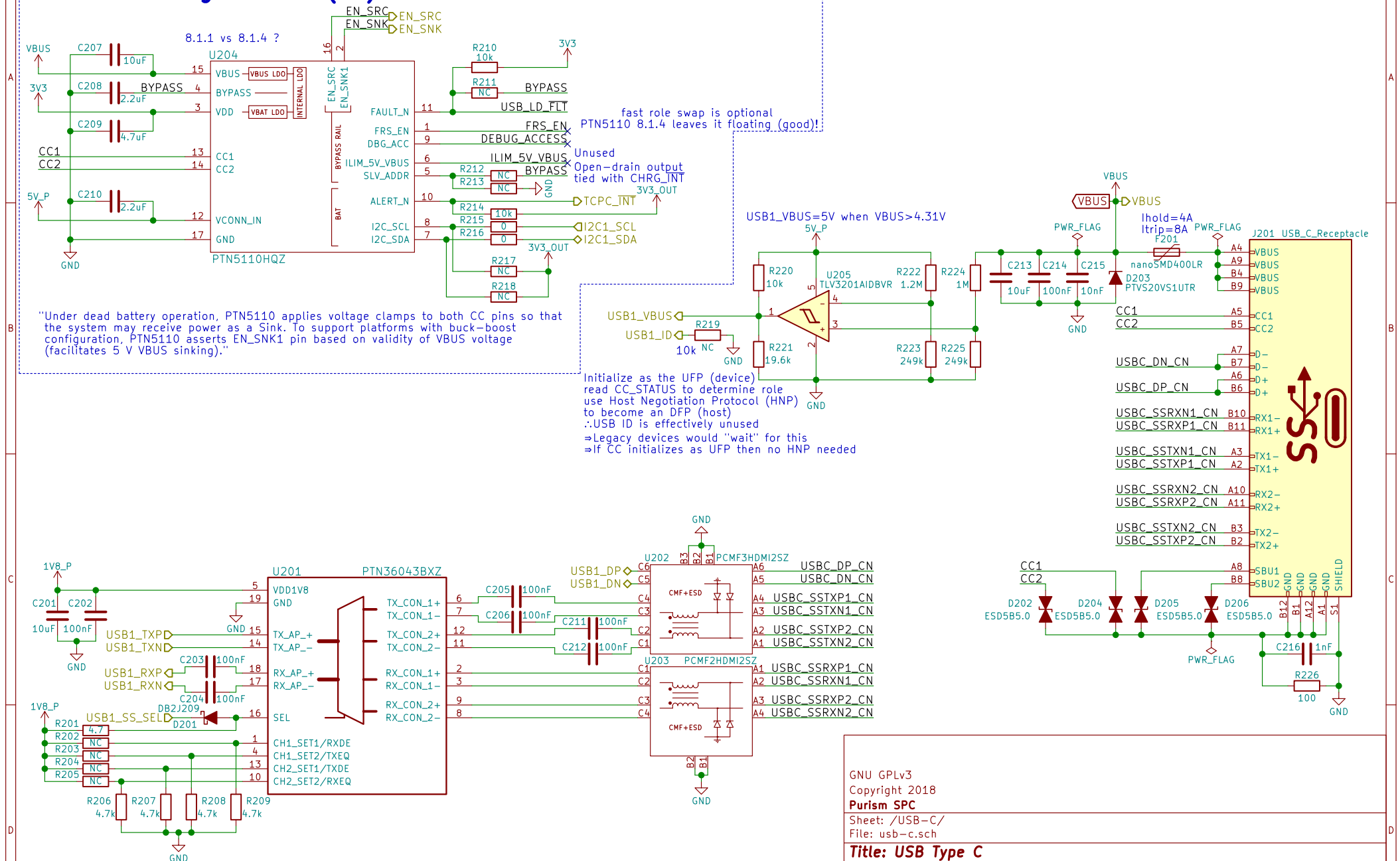


USB-C Config Channel (CC) and PD Role Controller



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Sheet: /USB-C/
File: usb-c.sch

Title: USB Type C

Size: A4	Date: 2018-05-23
KiCad E.D.A. kicad 4.0.7	

Rev: v0.1.0
Id: 2/23

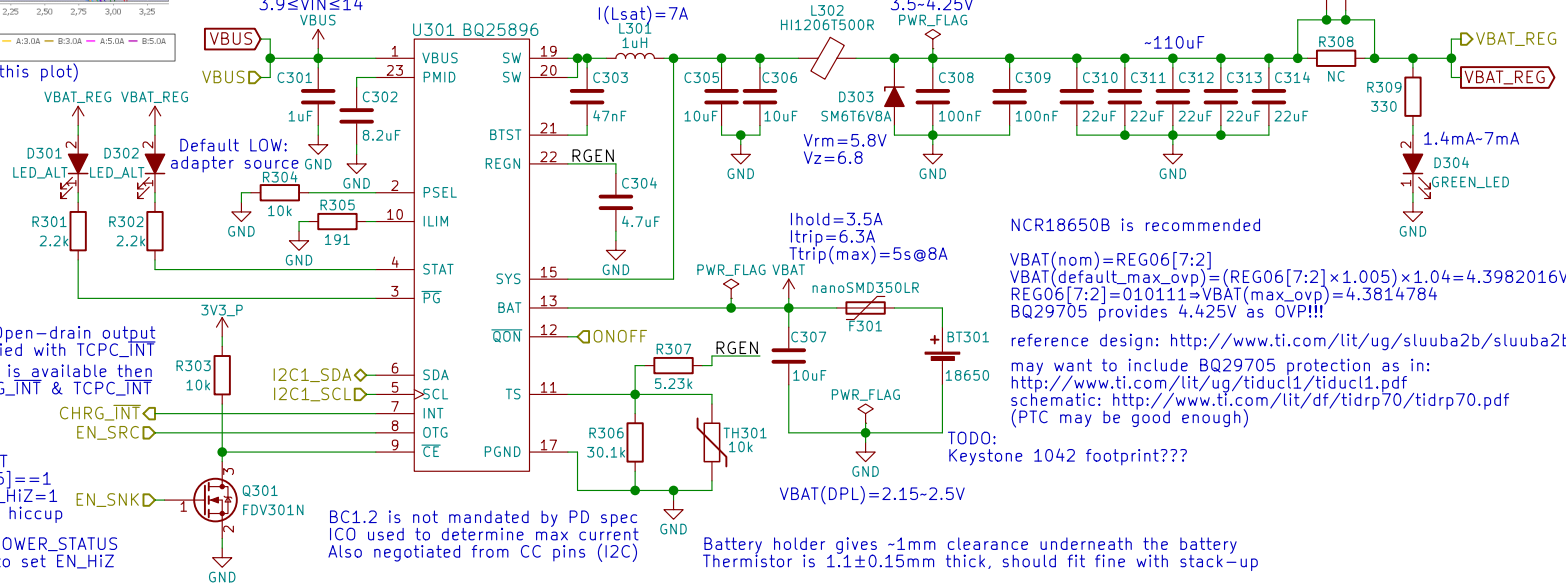


(interpret RSOC% based on this plot)

use AUTO_DPDM_EN
to auto-detect IINLIM

$1.658 \leq I_{LIM} \leq 2.063$
 $I_{LIM}(nom) \approx 1.859$
 $3.9 \leq V_{IN} \leq 14$

Battery Charge Controller



NCR18650B is recommended

$V_{BAT}(nom) = REG06[7:2]$
 $V_{BAT}(default_max_ovp) = (REG06[7:2] \times 1.005) \times 1.04 = 4.3982016V$
 $REG06[7:2] = 010111 \Rightarrow V_{BAT}(max_ovp) = 4.3814784$
 BQ29705 provides 4.425V as OVP!!!

reference design: <http://www.ti.com/lit/ug/sluuba2b/sluuba2b.pdf>
 may want to include BQ29705 protection as in:
<http://www.ti.com/lit/ug/tiduc1/tiduc1.pdf>
 schematic: <http://www.ti.com/lit/df/tidrp70/tidrp70.pdf>
 (PTC may be good enough)

TODO:
Keystone 1042 footprint???

Battery holder gives ~1mm clearance underneath the battery
 Thermistor is $1.1 \pm 0.15mm$ thick, should fit fine with stack-up

Battery holder seems to fit up to ~68.88mm long batteries
 need to test 18650 protected cells which are ~69.35mm long

Open-drain output
tied with TCPC_INT
If enough I/O is available then
separate CHRG_INT & TCPC_INT

This disables charging
but maybe not VBUS->VOUT
if PTN5110HQ's FAULT_STATUS[6]=1
(Force Off VBUS bit) then set EN_HI_Z=1
EN_HI_Z may be auto-set when in hiccup

Reading PTN5110HQ's CC_STATUS and POWER_STATUS
registers will tell TCPM (i.MX8M) when to set EN_HI_Z

Also, reading PTN5110HQ's CC_STATUS and POWER_STATUS
registers will tell TCPM (i.MX8M) when to set OTG_CONFIG=1
(this will also happen when PTN5110HQ sets EN_SRC HIGH)

BC1.2 is not mandated by PD spec
ICO used to determine max current
Also negotiated from CC pins (I2C)

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Sheet: /Battery/

File: battery.sch

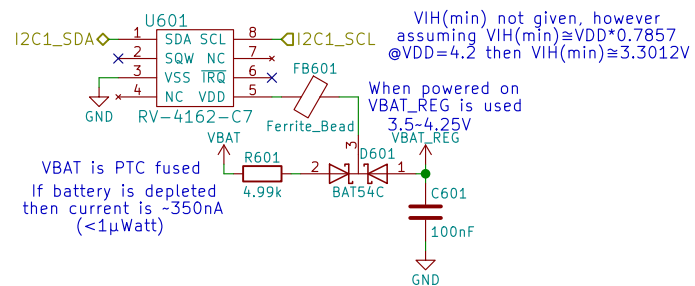
Title: Battery

Size: A4 Date: 2018-05-23

KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0

Id: 3/23



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Sheet: /RTC/

File: rtc.sch

Title: RTC

Size: A4 Date: 2018-05-23

KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0

Id: 6/23



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Sheet: /UART Debug/
File: uart.sch

Title: UART Debug

Size: A4 Date: 2018-05-23

KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0

Id: 7/23



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Sheet: /JTAG/
File: jtag.sch

Title: JTAG

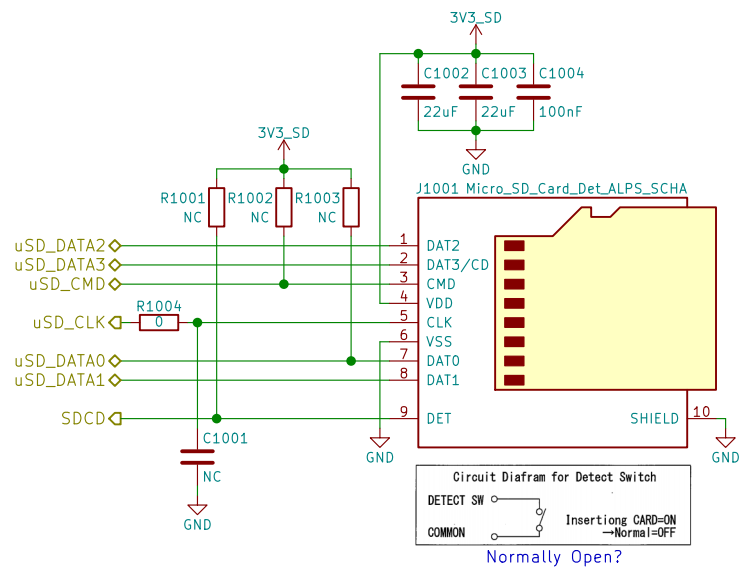
Size: A4 Date: 2018-05-23

KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0

Id: 8/23

Id: 9/23



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Purism SPC

Sheet: /uSD Card/
File: sd.sch

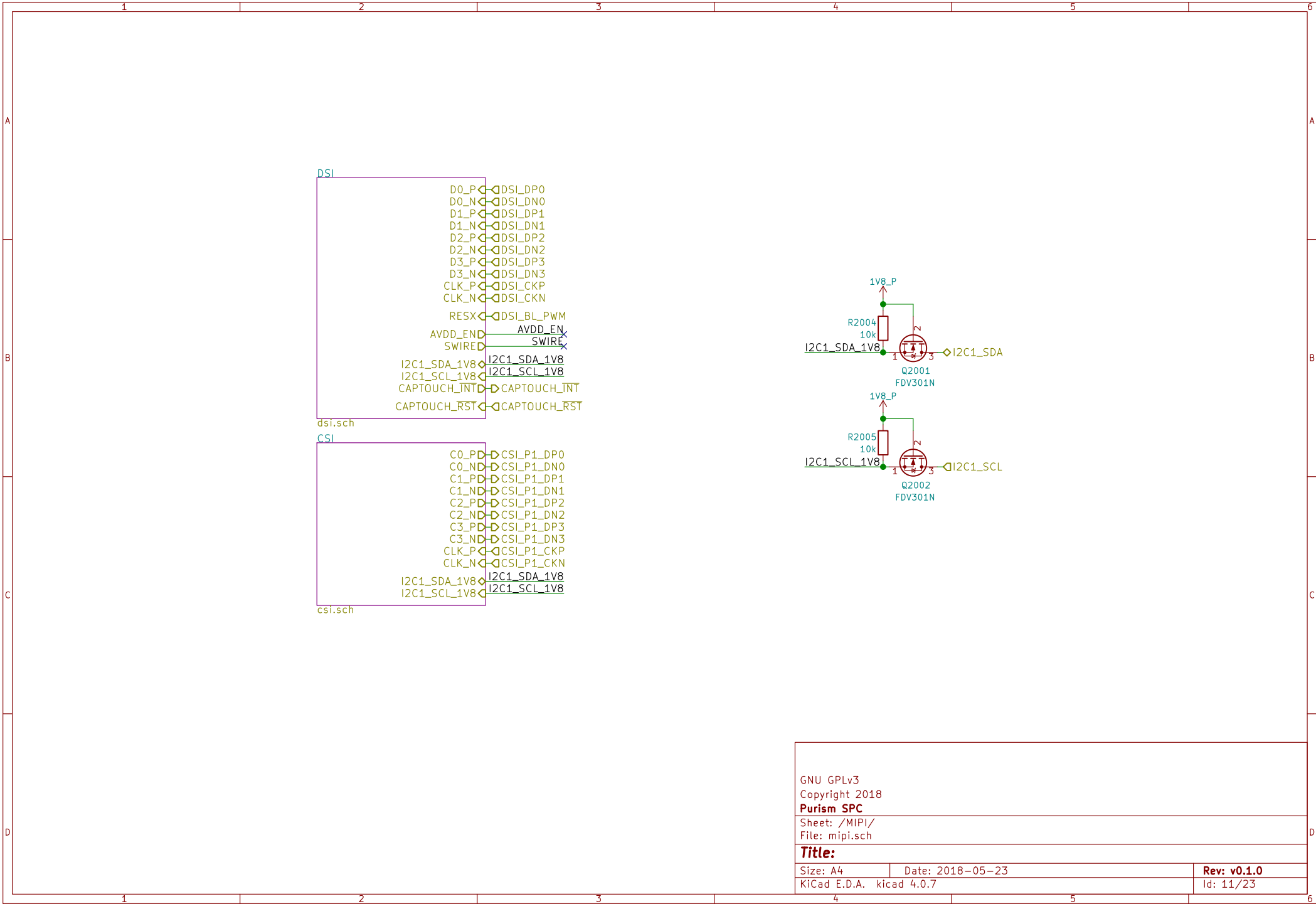
Title: uSD Card

Size: A4 Date: 2018-05-23

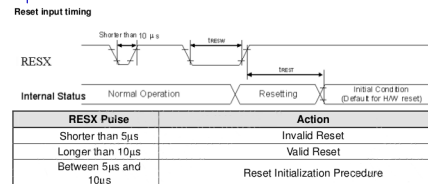
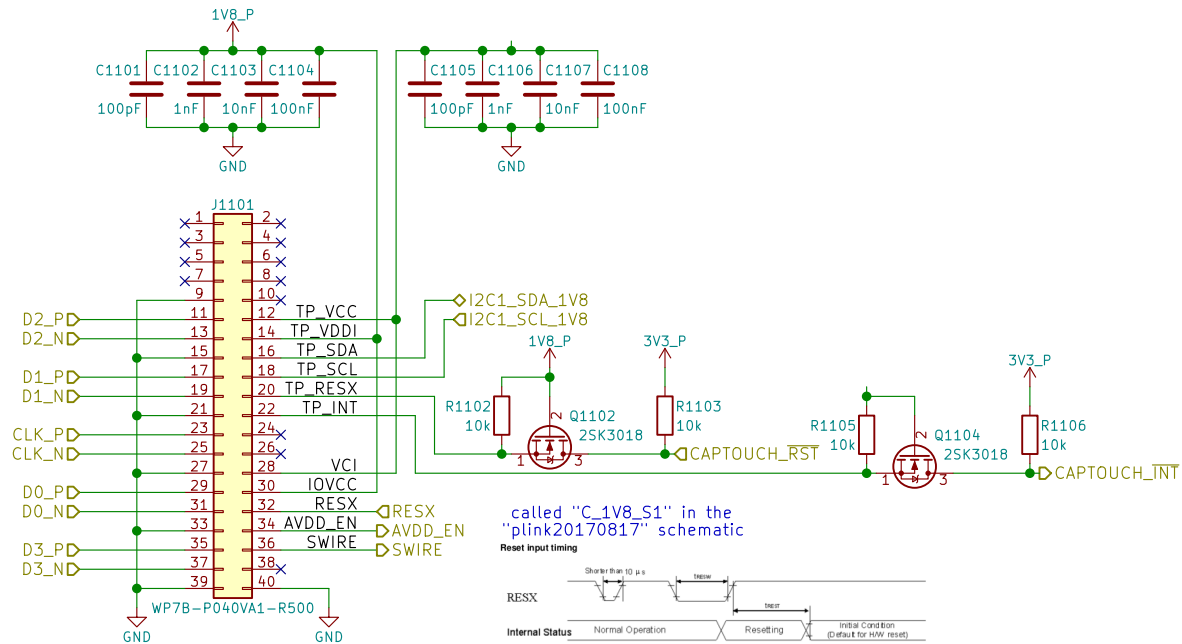
KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0

Id: 10/23



TODO:
ensure power sequence is satisfied
based on the display used



TODO: low power state signal??

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Sheet: /MIPI/DSI/
File: dsi.sch

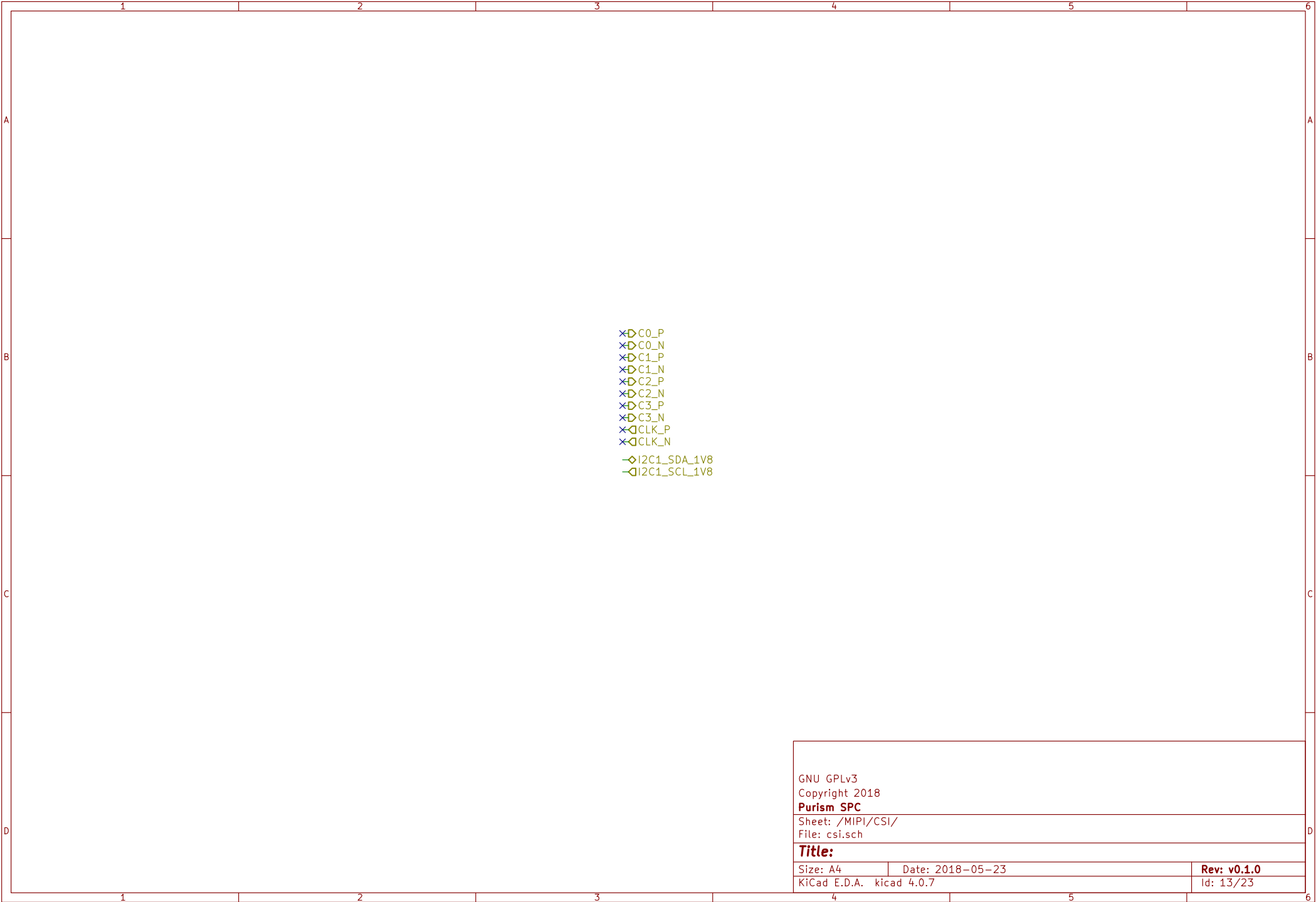
Title: MIPI DSI

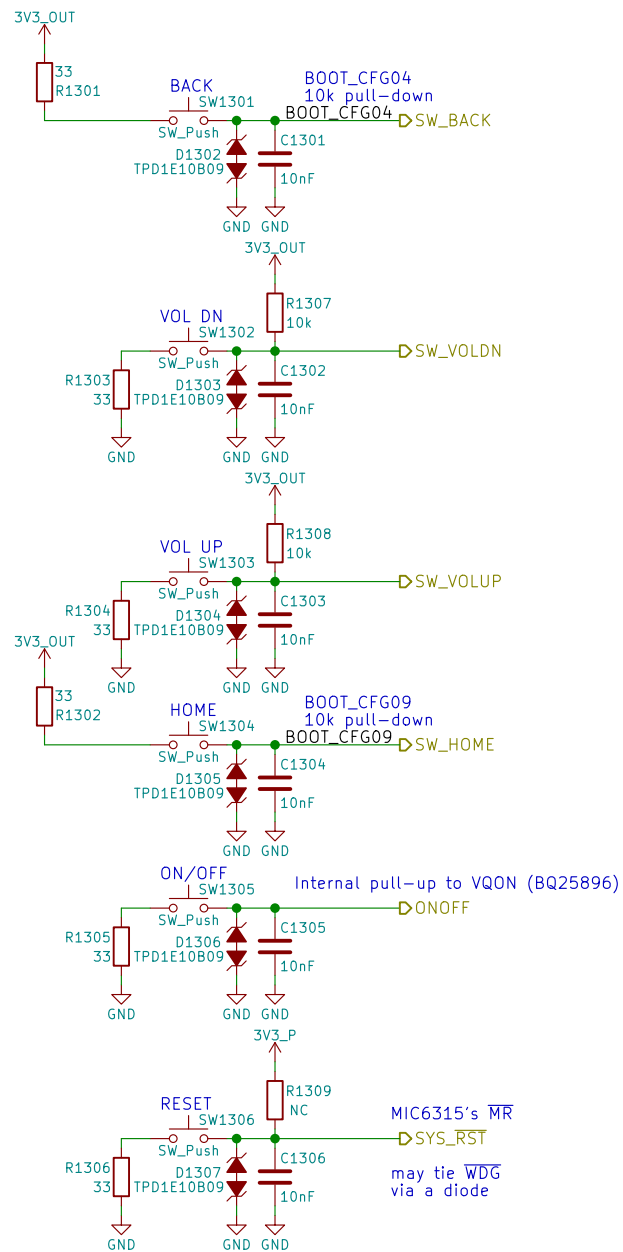
Size: A4 Date: 2018-05-23

KiCad E.D.A. kicad 4.0.7

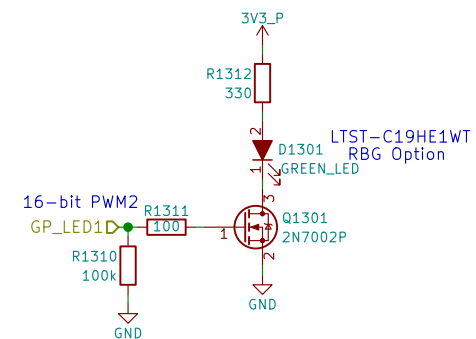
Rev: v0.1.0

Id: 12/23





Use PWM2_PWMSAR to set the compare value (duty cycle)
 Use PWM2_PWMCR[15:4] to set the PRESCALER (frequency)
 Use PWM2_PWMPR to set the top of the counter (frequency)



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Sheet: /Buttons & LED/
 File: buttons_led.sch

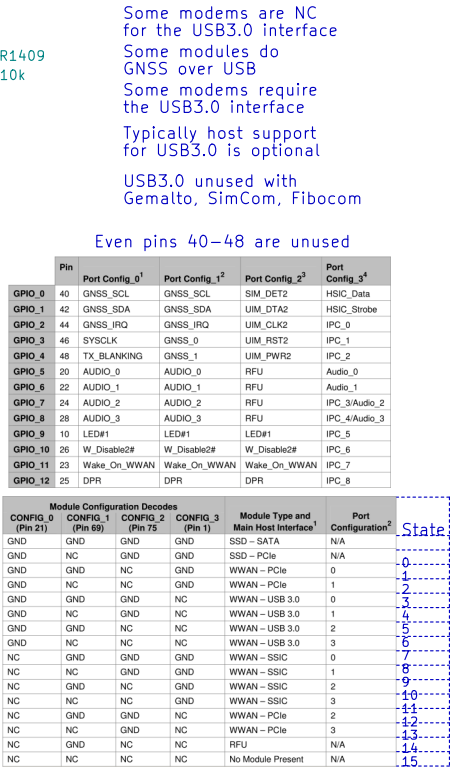
Title: Buttons & LED

Size: A4 Date: 2018-05-23

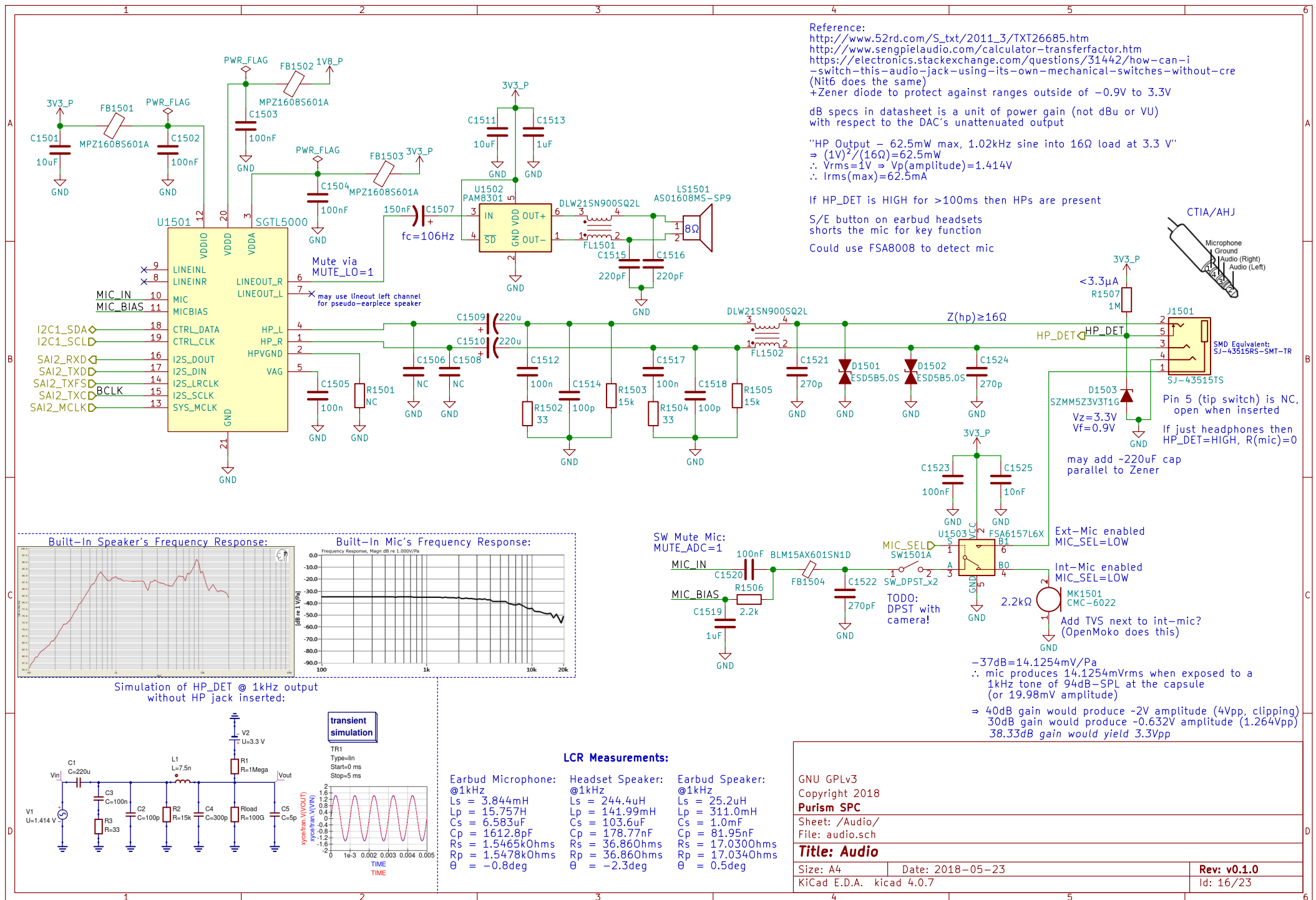
KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0

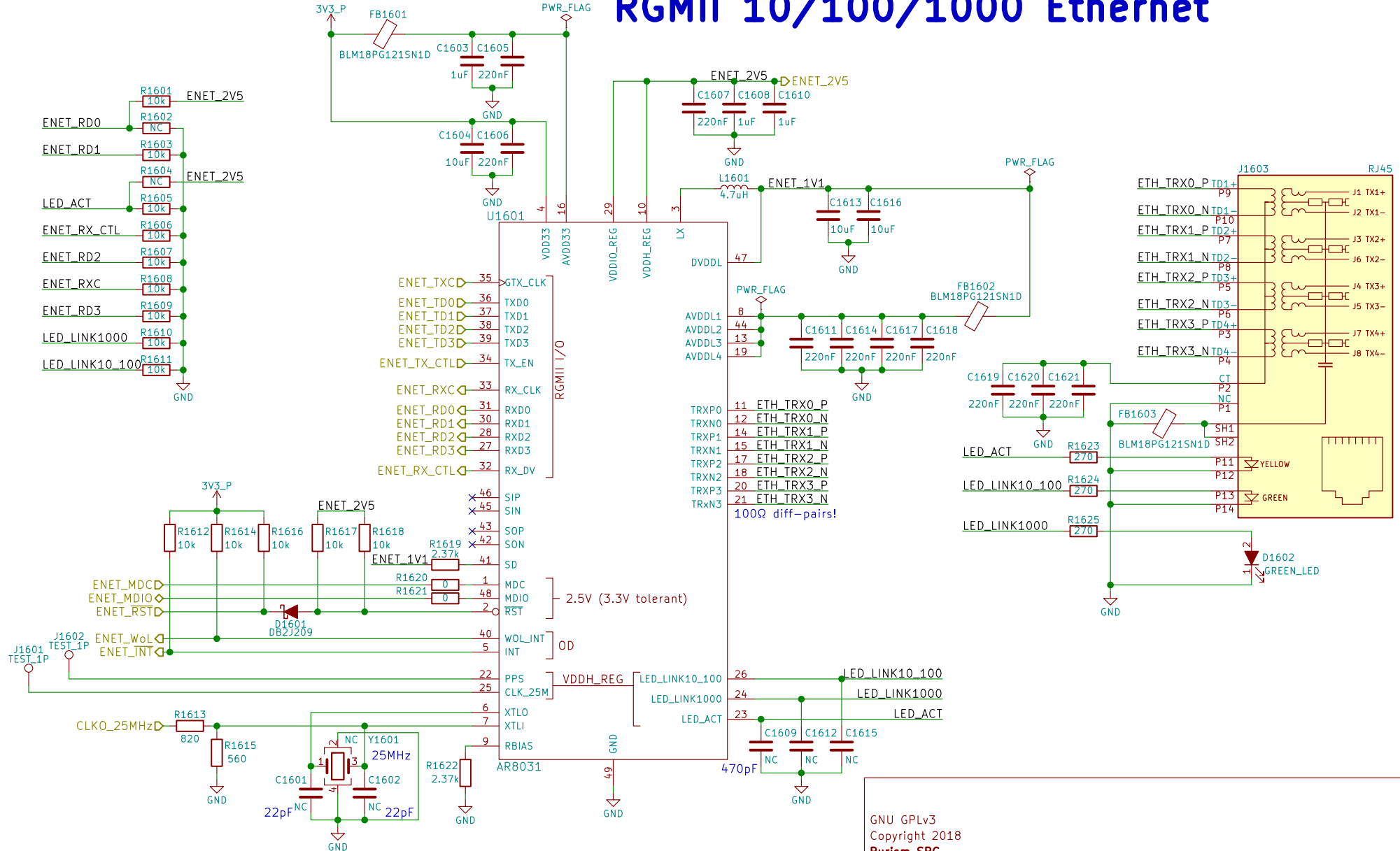
Id: 14/23



Rev: v0.1.0
Id: 15/23



RGMII 10/100/1000 Ethernet



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Sheet: /Ethernet/
File: ethernet.sch

Title: Ethernet

Size: A4
KiCad E.D.A. kicad 4.0.7

Date: 2018-05-23

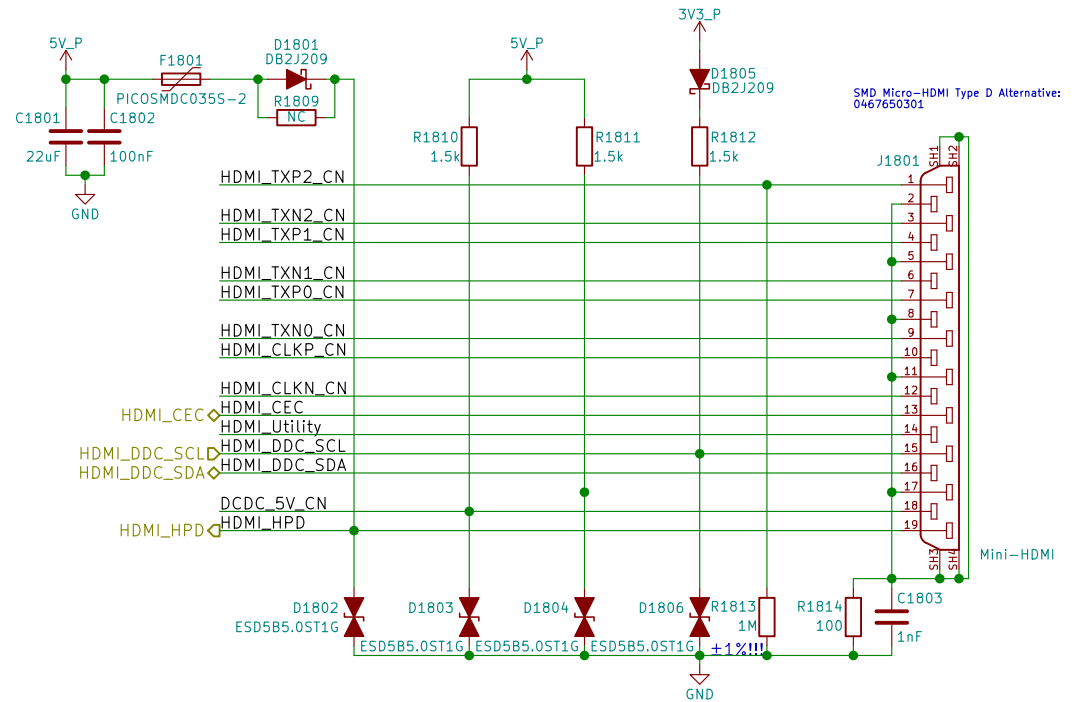
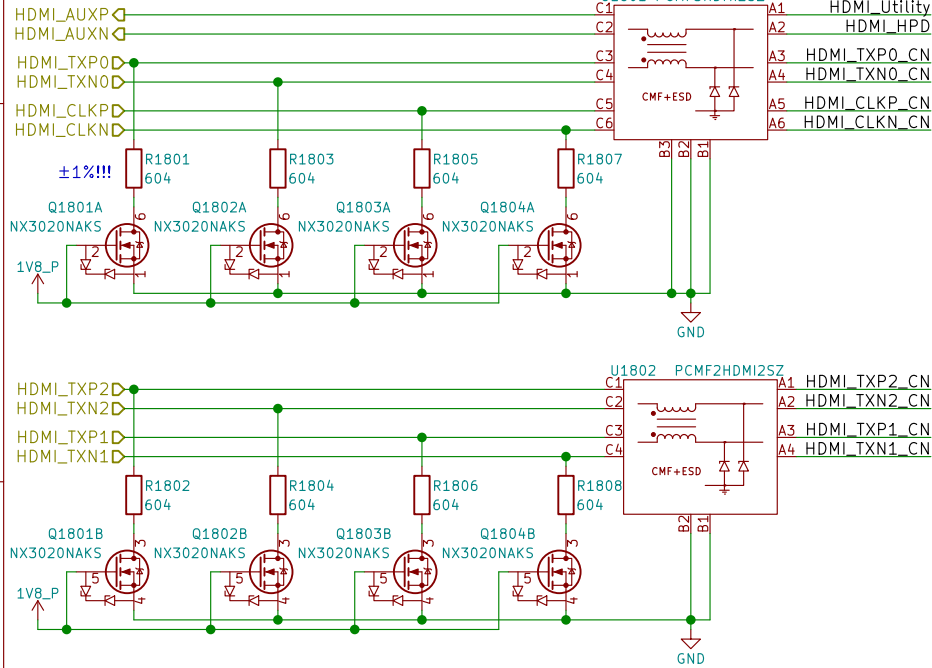
Rev: v0.1.0

Id: 17/23

HD3SS460 can be used for DP over USB-C

Layout Note:
May need swap some signals
due to micro-HDMI pinout diff
depending on pin location/routing

100Ω diff pairs



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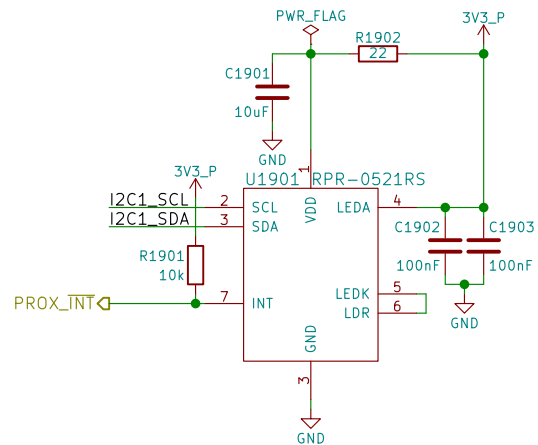
Sheet: /HDMI/
File: hdmi.sch

Title: HDMI

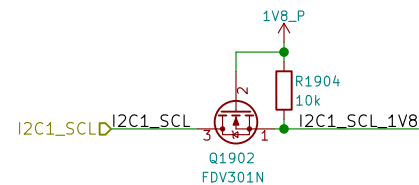
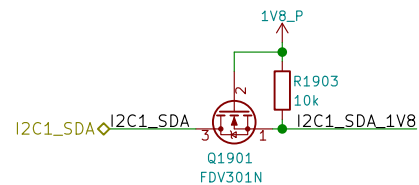
Size: A4 Date: 2018-05-23
KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0
Id: 19/23

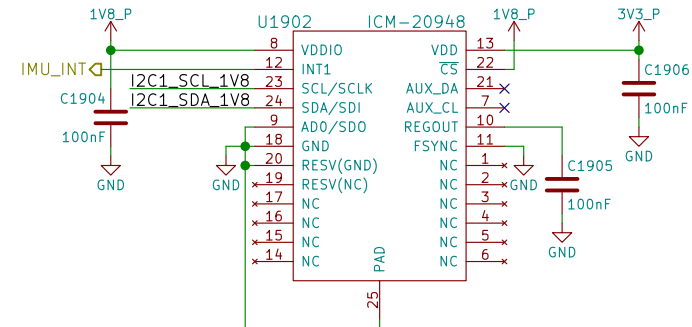
Proximity & Ambient Light



Reference:
<http://www.rohm.com/web/global/sensor-shield-support/ps-als-sensor>



9-Axis IMU



Reference:
<https://store.invensense.com/datasheets/invensense/AN-IVS-0001EVB-00%20v1%202.pdf>

AD0 sets the slave address's LSB (110100X)

INT1_ACTL sets if IMU_INT is active-high or active-low

"FSYNC - Connect to GND if unused"

I2C's VIH=1.8V

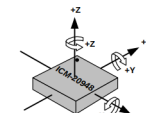


Figure 12. Orientation of Axes of Sensitivity and Polarity of Rotation

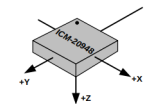


Figure 13. Orientation of Axes of Sensitivity for Magnetometer

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Purism SPC

Sheet: /Sensors/
 File: sensors.sch

Title: Sensors

Size: A4 Date: 2018-05-23

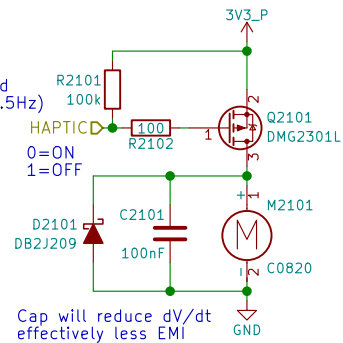
KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0

Id: 20/23

PWM pins occupied:
 GPIO1_I001 - DSI (DSI_BL_PWM??)
 GPIO1_I013 - LED
 GPIO1_I014 - Ethernet (CLKO_25MHz)
 GPIO1_I015 - CSI (CLKO2)

PWM needed?
 Only needs to be toggled
 ON 1 sec, OFF 1 sec (0.5Hz)
 Can MUX as either
 GPIO or PWM2
 swapping with LED



When the motor is off
 both terminals are at GND

Motor will have wire leads
 with a 2-pin Molex or JST
 connector installed (by request)!

Motor Connector:
https://lcsc.com/product-detail/1-25T-Connectors_1-25T-1-2AW_C10832.html
 Alibaba Alternative Motor:
https://www.alibaba.com/product-detail/Coin-motor-vibration-dc-motor-cellphone_1994583657.html?spm=a2700.8443308.0.0.5aa13e5f1wxHgs

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Purism SPC

Sheet: /Haptic Motor/
 File: haptic.sch

Title: Haptic/Vibration Motor

Size: A4 Date: 2018-05-23

KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0

Id: 23/23