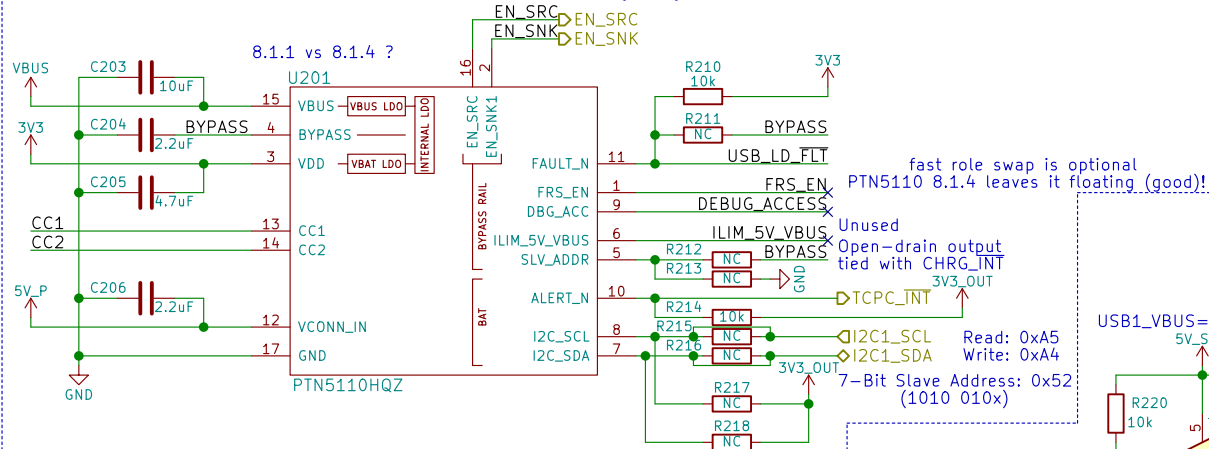


USB-C TCPC - Config Channel (CC) and PD Role Controller



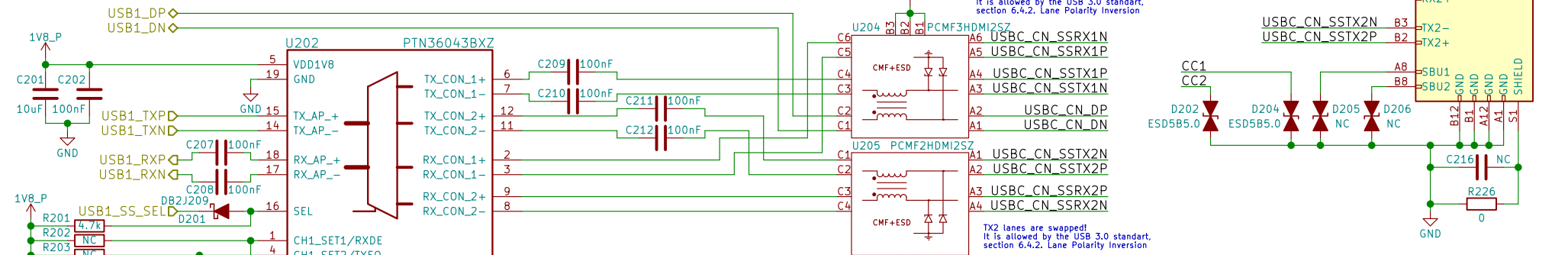
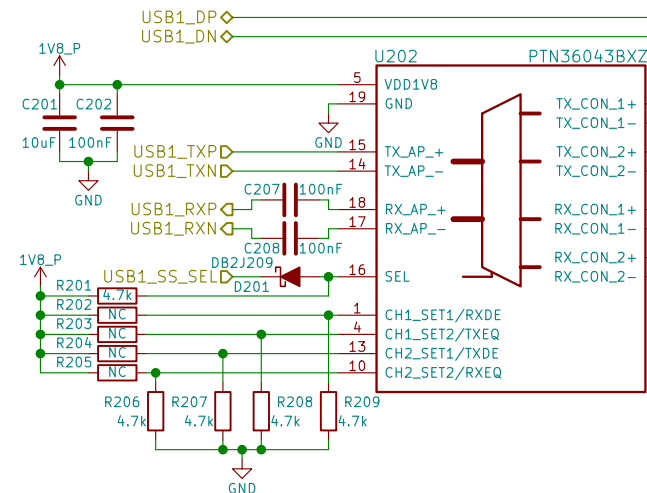
"Under dead battery operation, PTN5110 applies voltage clamps to both CC pins so that the system may receive power as a Sink. To support platforms with buck-boost configuration, PTN5110 asserts EN_SNK1 pin based on validity of VBUS voltage (facilitates 5 V VBUS sinking)."

fast role swap is optional
PTN5110 8.1.4 leaves it floating (good!)

Unused
Open-drain output
tied with CHRG_INT
3V3_OUT
Read: 0xA5
Write: 0xA4
7-Bit Slave Address: 0x52
(1010 010x)

Initialize as the UFP (device)
read CC_STATUS to determine role
use Host Negotiation Protocol (HNP)
to become an DFP (host)
∴ USB ID is effectively unused
⇒ Legacy devices would "wait" for this
⇒ If CC initializes as UFP then no HNP needed

USB-C



USB Type C

Purism

Copyright 2018 GNU GPLv3

Sheet: /USB-C/
File: usb-c.sch

Size: A4
KiCad E.D.A. kicad 4.0.7

eric.kuzmenko@puri.sm

angus.ainstlie@puri.sm

nicole.farber@puri.sm

christian.schilmoeller@puri.sm

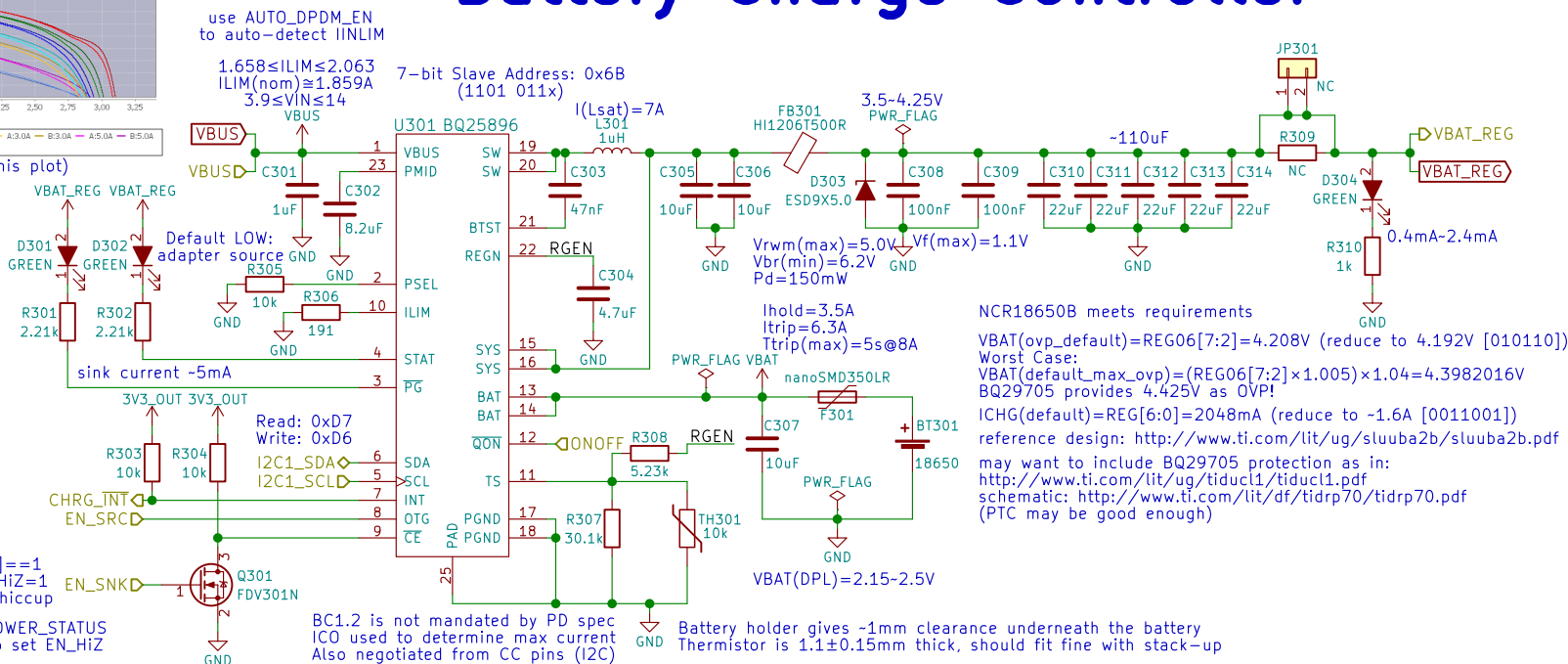
Rev: v0.1.0

Id: 2/24



(interpret RSOC% based on this plot)

Drawing ~333.33mA, or consuming <1.2W, should give close to 10 hours going from 100% to 0% charge



This disables charging but maybe not VBUS->VOUT if PTN5110HQ's FAULT_STATUS[6]=1 (Force Off VBUS bit) then set EN_HI_Z=1 (EN_HI_Z may be auto-set when in hiccup)

Reading PTN5110HQ's CC_STATUS and POWER_STATUS registers will tell TCPM (i.MX8M) when to set EN_HI_Z

Also, reading PTN5110HQ's CC_STATUS and POWER_STATUS registers will tell TCPM (i.MX8M) when to set OTG_CONFIG=1 (this will also happen when PTN5110HQ sets EN_SRC HIGH)

BC1.2 is not mandated by PD spec
 ICO used to determine max current
 Also negotiated from CC pins (I2C)

Battery holder gives ~1mm clearance underneath the battery
 Thermistor is 1.1±0.15mm thick, should fit fine with stack-up

Battery holder seems to fit up to ~68.88mm long batteries
 need to test 18650 protected cells which are ~69.35mm long

NCR18650B meets requirements

VBAT(ovp_default)=REG06[7:2]=4.208V (reduce to 4.192V [010110])
 Worst Case:
 VBAT(default_max_ovp)=(REG06[7:2]×1.005)×1.04=4.3982016V
 BQ29705 provides 4.425V as OVP!
 ICHG(default)=REG[6:0]=2048mA (reduce to ~1.6A [0011001])
 reference design: <http://www.ti.com/lit/ug/sluuba2b/sluuba2b.pdf>
 may want to include BQ29705 protection as in:
<http://www.ti.com/lit/ug/tiduc1/tiduc1.pdf>
 schematic: <http://www.ti.com/lit/df/tidrp70/tidrp70.pdf>
 (PTC may be good enough)

Battery

Purism

Copyright 2018 GNU GPLv3

Sheet: /Battery/
 File: battery.sch

Size: A4 Date: 2018-06-15
 KiCad E.D.A. kicad 4.0.7

eric.kuzmenko@puri.sm
 angus.ainslie@puri.sm
 nicole.farber@puri.sm
 christian.schilmoeller@puri.sm

Rev: v0.1.0
 Id: 3/24

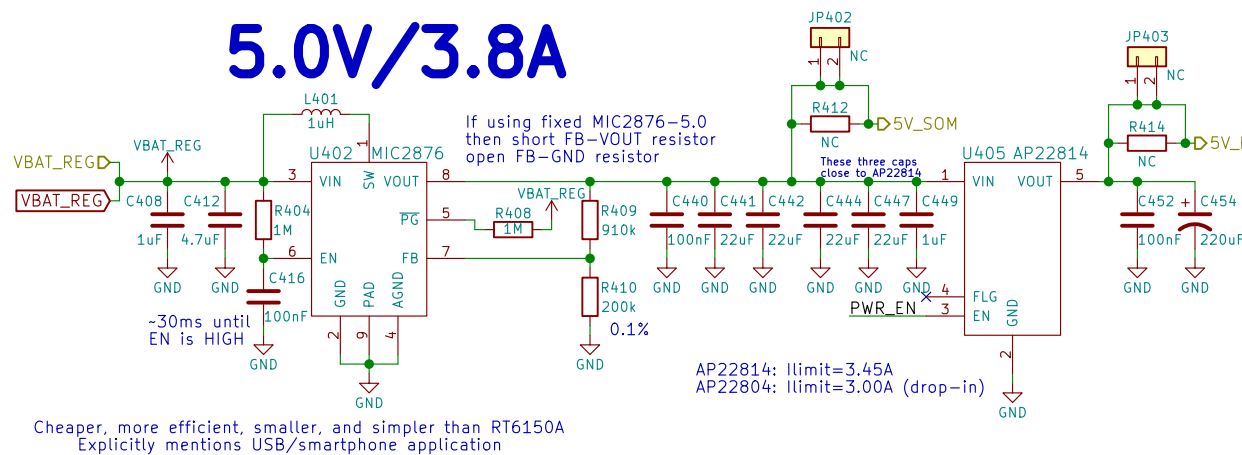
3.3V/3A



1.8V/600mA



5.0V/3.8A



22.4V/40mA



2.8V/150mA



Power

Power

Purism

Copyright 2018 GNU GPLv3

Sheet: /Power/
File: power.sch

Size: A4
KiCad E.D.A. kicad 4.0.7

Date: 2018-06-15

Rev: v0.1.0

Id: 4/24

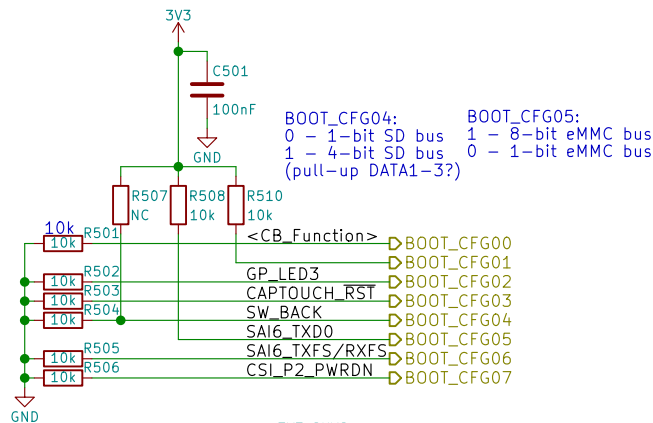
eric.kuzmenko@puri.sm

angus.ainslie@puri.sm

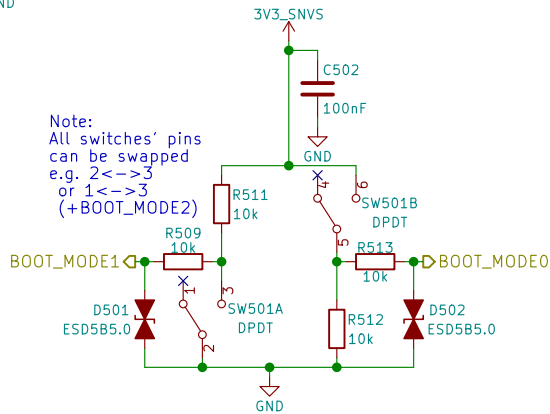
nicole.farber@puri.sm

christian.schilmoeller@puri.sm

Boot Config



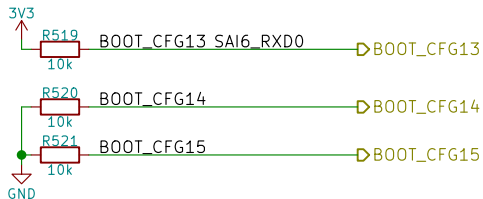
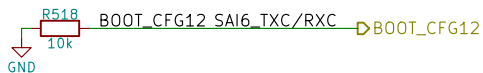
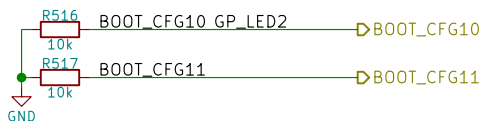
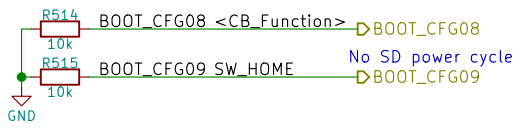
BOOT_CFG04: 0 - 1-bit SD bus
1 - 4-bit SD bus (pull-up DATA1-3?)
BOOT_CFG05: 1 - 8-bit eMMC bus
0 - 1-bit eMMC bus



Note:
All switches' pins
can be swapped
e.g. 2<->3
or 1<->3
(+BOOT_MODE2)

2->1: eMMC 2->3: USB (Serial Downloader)	
BOOT_MODE[1:0]	Boot Type
00	Boot From Fuses
01	Serial Downloader
10	Internal Boot
11	Reserved

Only eMMC					
BOOT_CFG[14:12]			Boot device		
001			SD/eSD		
010			MMC/eMMC		
011			NAND		
Fuse	Config	Definition	GPIO ¹	Shipped value	Settings
BOOT_CFG[11:10]	OEM	USDHC port selection	Yes	00	00 - USDHC-1 01 - USDHC-2 10 - USDHC-3 else - reserved



Boot Configuration

Purism

Copyright 2018 GNU GPLv3

Sheet: /Boot Config/
File: boot.sch

Size: A4
KiCad E.D.A. kicad 4.0.7

Date: 2018-06-15

Rev: v0.1.0
Id: 5/24

eric.kuzmenko@puri.sm
angus.ainstlie@puri.sm
nicole.farber@puri.sm
christian.schilmoeller@puri.sm

Real-Time Clock



Note:
Datasheet says slave address is 0xD0
with a R/W bit appended, since 0xD must
be 4-bits wide the actual 7-bit address is
0x68 (110 1000), and becomes 0xD0 during a
write operation (1101 0000)

Reference:
https://github.com/HIO-Project/linux-imx6-nano-imx_3.10.17_1.0.1_ga/blob/8848e94b2f889fe44f6736e2d4c98851a2282275/arch/arm/boot/dts/imx6qdl-mtp.dtsi#L351

RTC



Copyright 2018 GNU GPLv3

Sheet: /RTC/

File: rtc.sch

Size: A4

Date: 2018-06-15

KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0

Id: 6/24

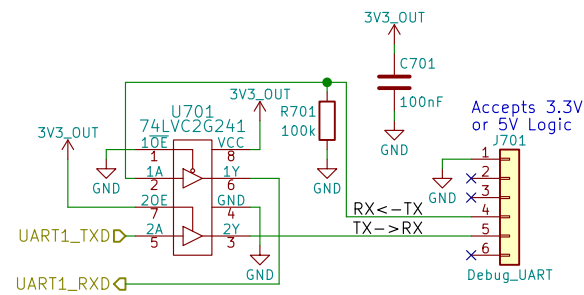
eric.kuzmenko@puri.sm

angus.ainstlie@puri.sm

nicole.farber@puri.sm

christian.schilmoeller@puri.sm

UART Debug



UART Debug



Copyright 2018 GNU GPLv3

Sheet: /UART Debug/

File: uart.sch

Size: A4

Date: 2018-06-15

KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0

Id: 7/24

eric.kuzmenko@puri.sm

angus.ainstlie@puri.sm

nicole.farber@puri.sm

christian.schilmoeller@puri.sm

JTAG



JTAG



Copyright 2018 GNU GPLv3

Sheet: /JTAG/

File: jtag.sch

Size: A4

Date: 2018-06-15

KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0

Id: 8/24

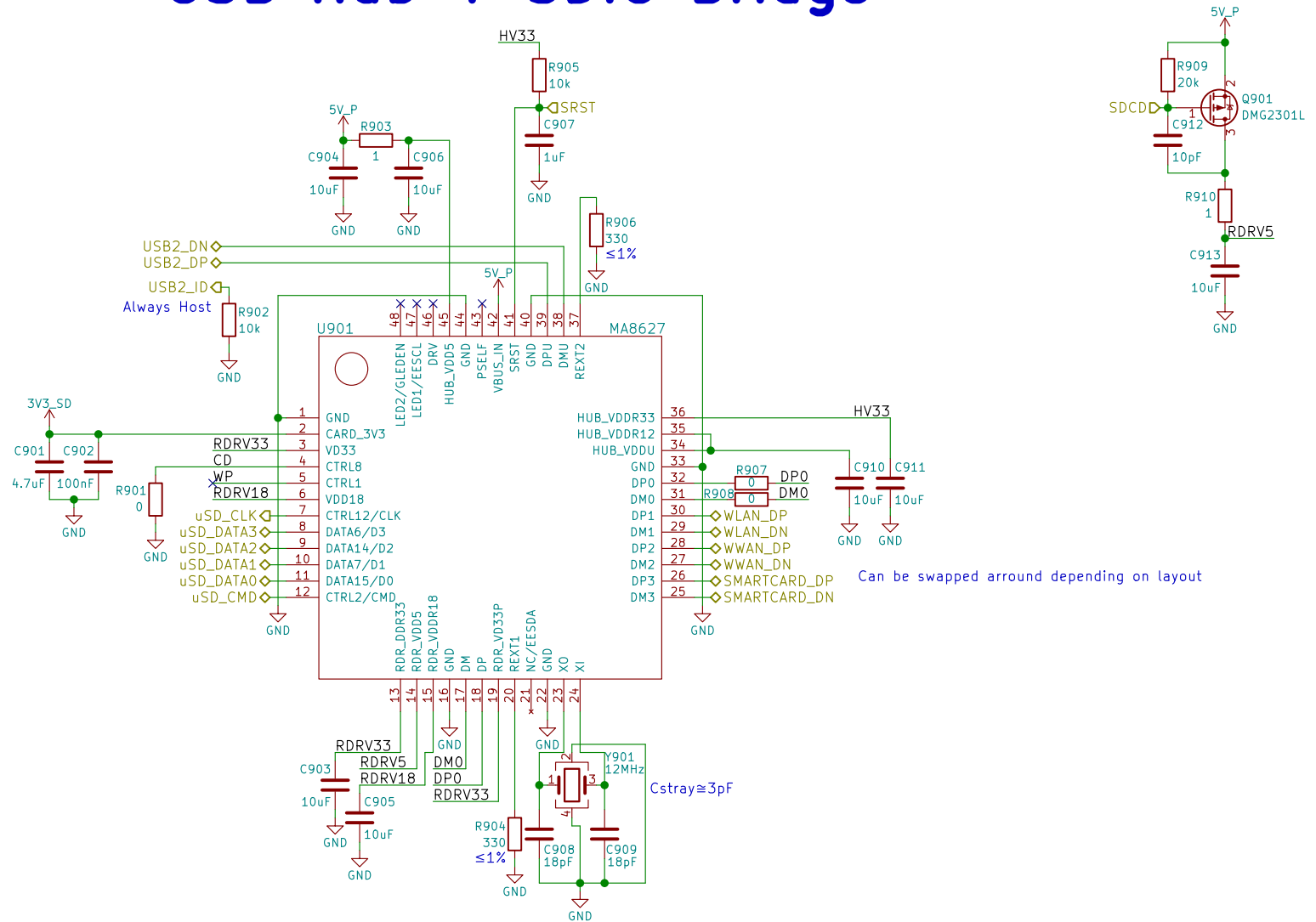
eric.kuzmenko@puri.sm

angus.ainstlie@puri.sm

nicole.farber@puri.sm

christian.schilmoeller@puri.sm

USB Hub + SDIO Bridge



USB Hub + SDIO Bridge



Copyright 2018 GNU GPLv3

Sheet: /USB Hub + SDIO Bridge/

File: usb_hub_sdio.sch

Size: A4	Date: 2018-06-15
----------	------------------

KiCad E.D.A. kicad 4.0.7

eric.kuzmenko@puri.sm

angus.ainslie@puri.sm

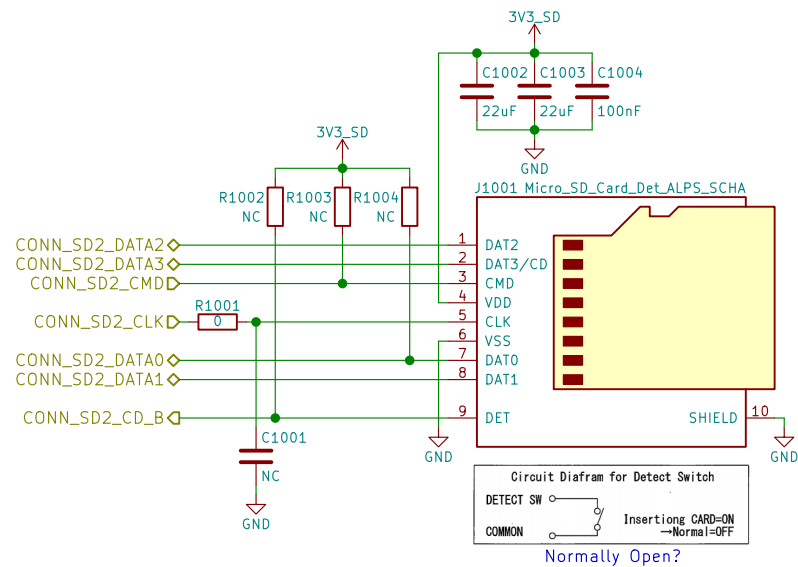
nicole.faerber@puri.sm

christian.schilmoeller@puri.sm

Rev: v0.1.0

Id: 9/24

μ SD



uSD Card



Purism

Copyright 2018 GNU GPLv3

Sheet: /uSD Card/

File: sd.sch

eric.kuzmenko@puri.sm

angus.ainslie@puri.sm

nicole.faeber@puri.sm

christian.schilmoeller@puri.sm

Size: A4

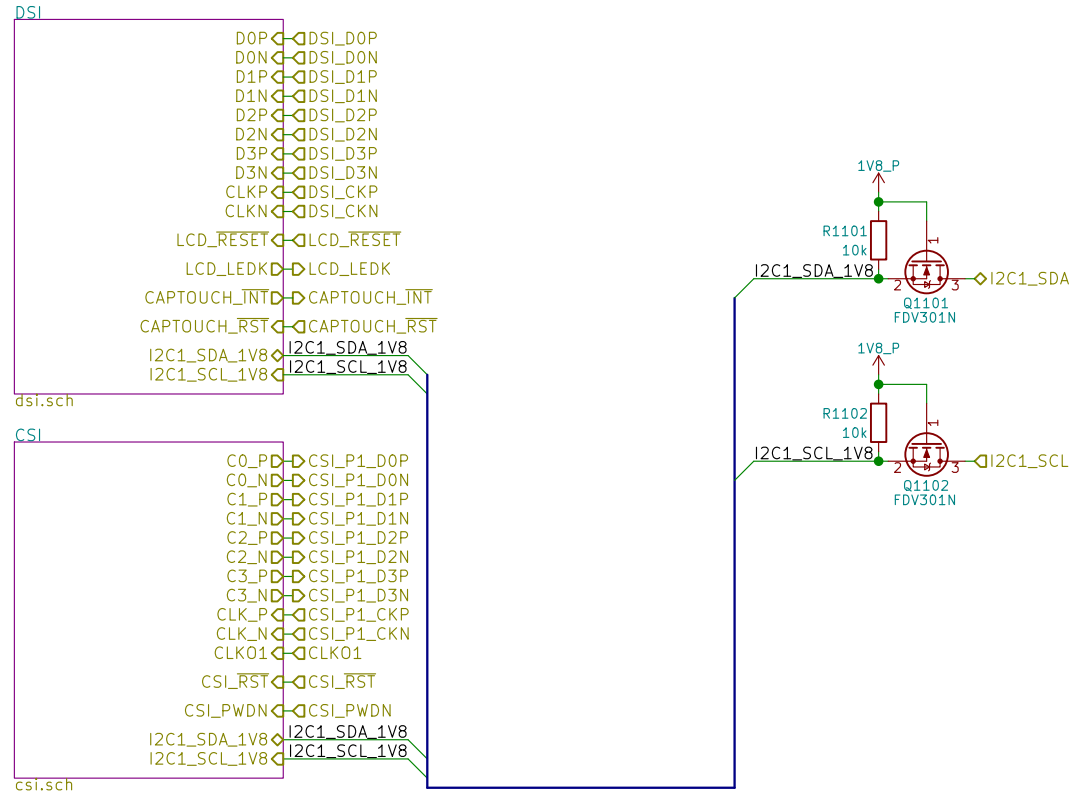
Date: 2018-06-15

Rev: v0.1.0

Size: A4	Date: 11/01/2025
KiCad E.D.A.	kicad 4.0.7

Id: 10/24

MIPI



MIPI



Copyright 2018 GNU GPLv3

Sheet: /MIPI/

File: mipi.sch

Size: A4 Date: 2018-06-15

KiCad E.D.A. kicad 4.0.7

eric.kuzmenko@puri.sm

angus.ainstlie@puri.sm

nicole.farber@puri.sm

christian.schilmoeller@puri.sm

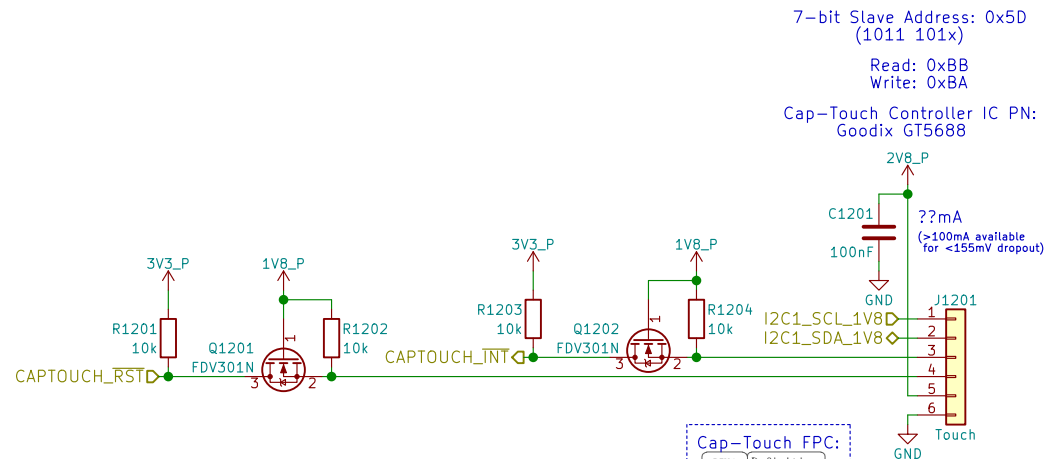
Rev: v0.1.0

Id: 11/24

Display & Touch Controller

LCD PN:
Shenzhen Jinghong Electronics Co., Ltd.
JH057N00900

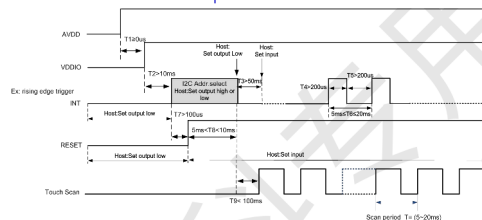
Note:
No power-up sequence is
given in the spec sheet



The upper 7 bits are the address,
and bit 0 is used to select read or write.
GT5688 has two slave device addresses to choose from:

INT	7-Bit Address	8-Bit Write Address	8-Bit Read Address
LOW	0x5D	0xBA	0xBB
HIGH	0x14	0x28	0x29

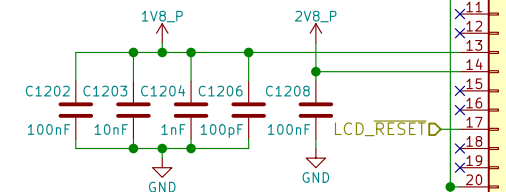
Every time you power on or reset, you need
to use the INT pin to set the I2C address:



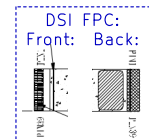
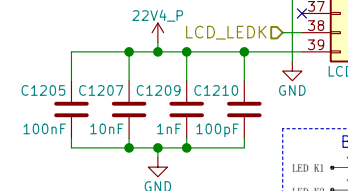
Cap-Touch FPC:

Pin#	Definition
1	SCL
2	SDA
3	INT
4	RESET
5	VDD2_R5
6	GND

Front: Back:



100Ω Differential Impedance



Backlight Array:



MIPI DSI



Copyright 2018 GNU GPLv3

Sheet: /MIPI/DSI/
File: dsi.sch

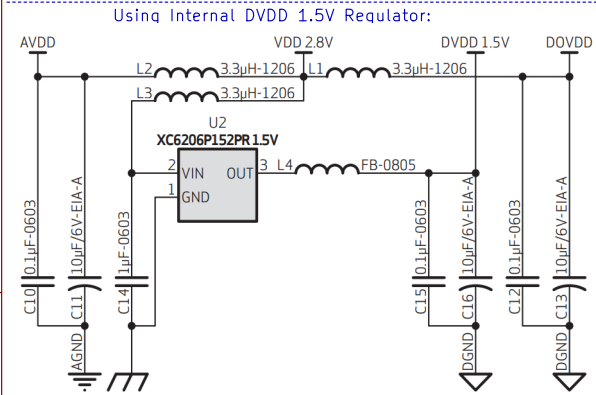
Size: A4
KiCad E.D.A. kicad 4.0.7

Date: 2018-06-15

eric.kuzmenko@puri.sm
angus.ainslie@puri.sm
nicole.farber@puri.sm
christian.schilmoeller@puri.sm

Rev: v0.1.0
Id: 12/24

Camera



2.7 POWER UP SEQUENCE

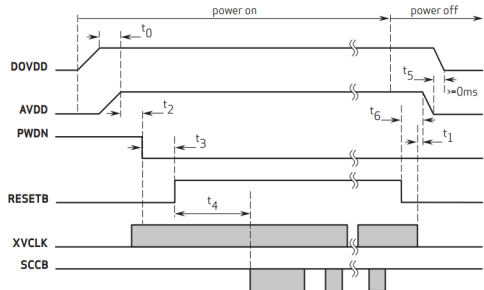
Based on the system power configuration (1.8V or 2.8V for I/O power, using external DVDD or internal DVDD, requiring access to the I2C during power up period or not), the power up sequence will differ. If 1.8V is used for I/O power, using the internal DVDD is preferred. If 2.8V is used for I/O power, due to a high voltage drop at the internal DVDD regulator, there is a potential heat issue. Hence, for a 2.8V power system, OmniVision recommends using an external DVDD source. Due to the higher power down current when using an external DVDD source, OmniVision strongly recommends cutting off all powers, including the external DVDD, when the sensor is not in use in the case of 2.8V I/O and external DVDD.

2.7.1 POWER UP WITH INTERNAL DVDD

For powering up with the internal DVDD and I2C access during the power ON period, the following conditions must occur:

1. when DOVDD and AVDD are turned ON, make sure DOVDD becomes stable before AVDD becomes stable
2. PWDN is active high with an asynchronous design (does not need clock)
3. PWDN pin tied to digital ground if it is not controlled.
4. if PWDN pin is controlled as below, for PWDN to go low, power must first become stable (AVDD to PWDN ≥ 5 ms)
5. RESETB is active low with an asynchronous design
6. master clock XVCLK should provide at least 1 ms before host accesses the sensor's registers
7. host can access I2C bus (if shared) during entire period. 20ms after RESETB goes high, host can access the sensor's registers to initialize sensor

figure 2-3 power up timing with internal DVDD



note $t_0 \geq 0\text{ms}$, delay from DOVDD stable to AVDD stable, it is recommended to power up AVDD shortly after DOVDD has been powered up

$t_1 \geq 0\text{ms}$, delay from XVCLK off to AVDD off

$t_2 \geq 5\text{ms}$, delay from AVDD stable to sensor power up stable, PWDN can be pulled low after this point, XVCLK can be turned on after power on

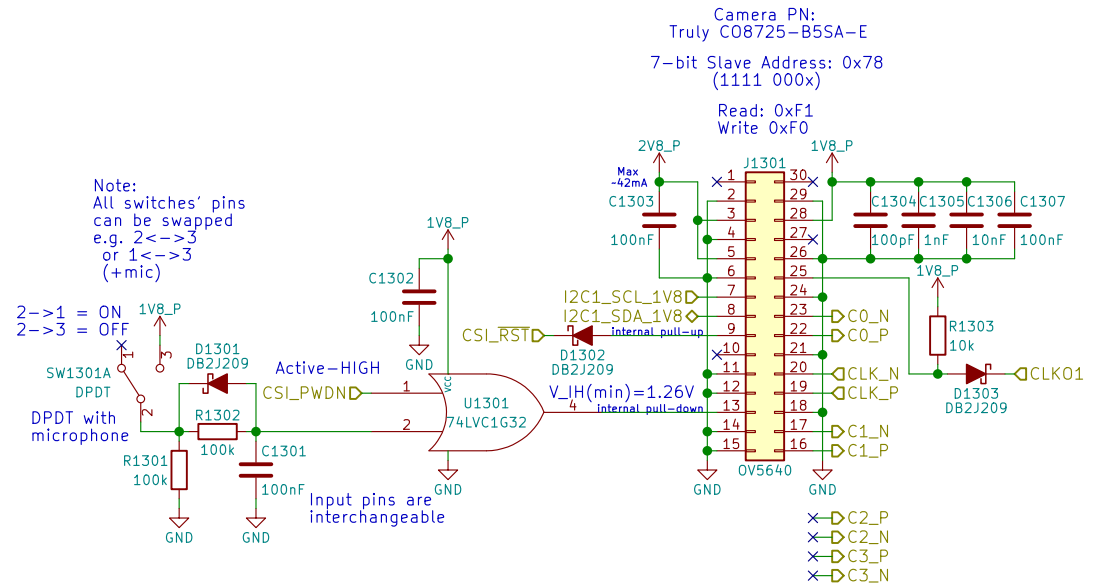
$t_3 \geq 1\text{ms}$, delay from sensor power up stable to RESETB pull up

$t_4 \geq 20\text{ms}$, delay from RESETB pull high to SCCB initialization

$t_5 \geq 0\text{ms}$, delay from AVDD off to DOVDD off

$t_6 \geq 0\text{ms}$, delay from RESETB pull low to AVDD off

5640 DS 2.2



OV5640 CMOS Image Sensor Datasheet:
https://cdn.sparkfun.com/datasheets/Sensors/LightImaging/OV5640_datasheet.pdf



Copyright 2018 GNU GPLv3

Sheet: /MIPI/CSI/

File: csi.sch

Size: A4

KiCad E

eric.kuzmenko@puri.sm

angus.ainslie@puri.sm

nicola.faeber@uniri.sm

nicole.faeber@puri.sm

christian.schilmoeller@puri.sm

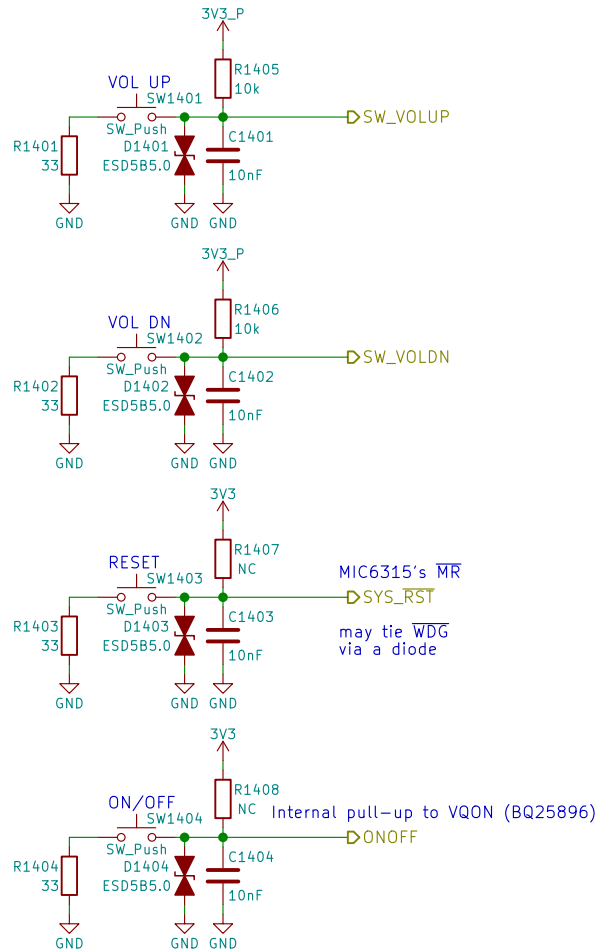
Size: A4	Date: 2018-06-15
----------	------------------

KiCad E.D.A. kicad 4.0.7

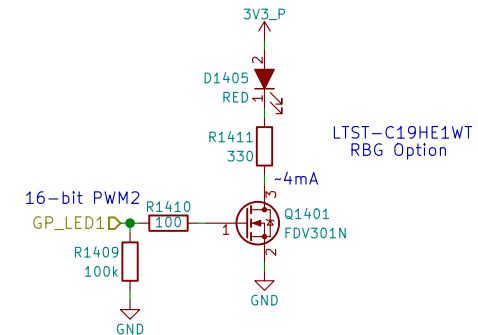
Rev: v0.1.0

Id: 13/24

Buttons & LED



Use PWM2_PWMSAR to set the compare value (duty cycle)
Use PWM2_PWMCR[15:4] to set the PRESCALER (frequency)
Use PWM2_PWMPR to set the top of the counter (frequency)



Buttons & LED



Copyright 2018 GNU GPLv3

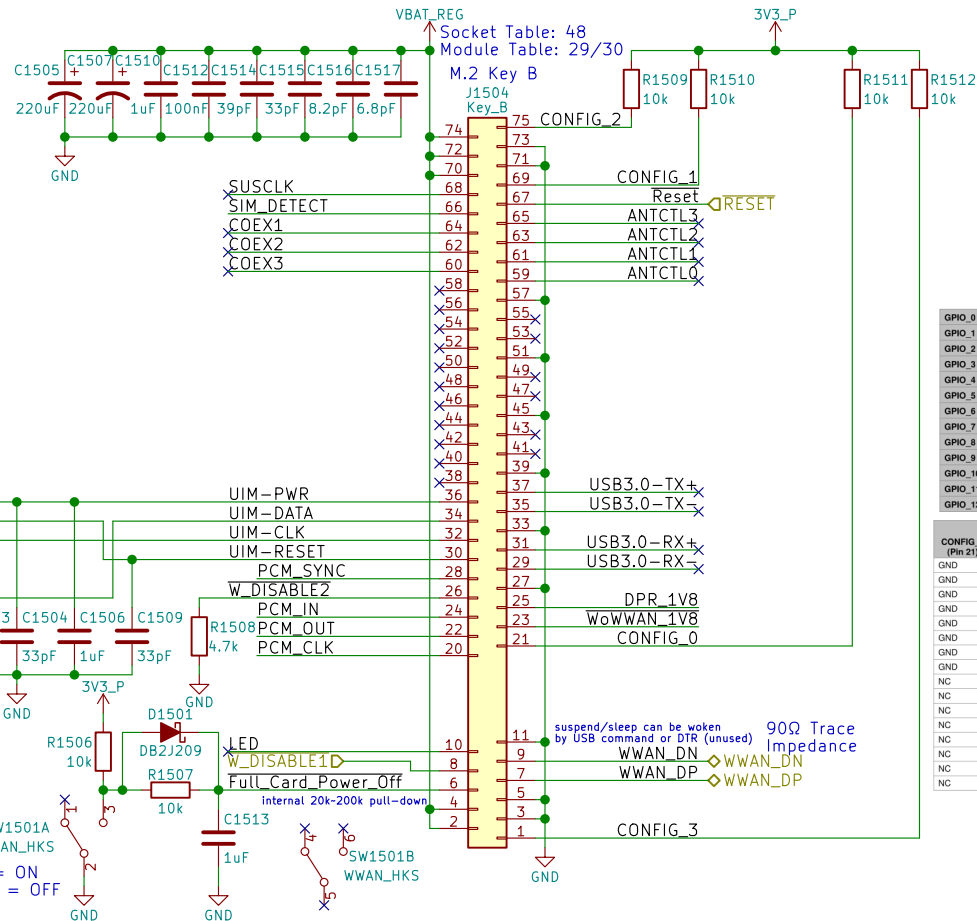
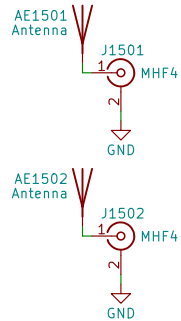
Sheet: /Buttons & LED/
File: buttons_led.sch

Size: A4 Date: 2018-06-15
KiCad E.D.A. kicad 4.0.7

eric.kuzmenko@puri.sm
angus.ainslie@puri.sm
nicole.farber@puri.sm
christian.schilmoeller@puri.sm

Rev: v0.1.0
Id: 14/24

WWAN M.2

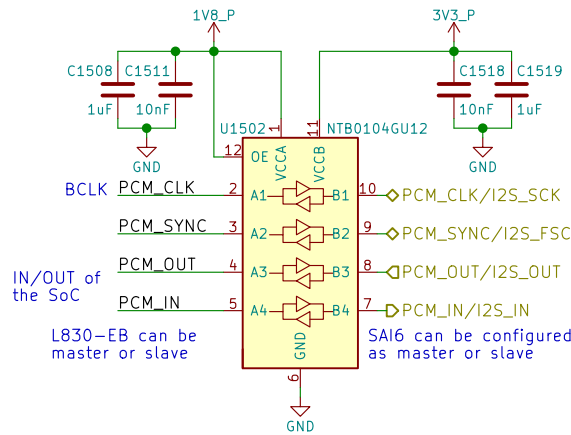
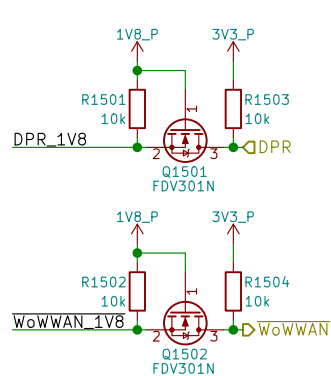


Some modems are NC
for the USB3.0 interface
Some modules do
GNSS over USB
Some modems require
the USB3.0 interface
Typically host support
for USB3.0 is optional
USB3.0 unused with
Gemalto, SimCom, Fibocom

Even pins 40-48 are unused

	Pin	Port Config_0 ¹	Port Config_1 ²	Port Config_2 ³	Port Config_3 ⁴
GPIO_0	40	GNSS_SCL	GNSS_SCL	SIM_DET2	HSIC_Data
GPIO_1	42	GNSS_SDA	GNSS_SDA	UIM_DTA2	HSIC_Strobe
GPIO_2	44	GNSS_IRQ	GNSS_IRQ	UIM_CLK2	IPC_0
GPIO_3	46	SYSCLK	GNSS_0	UIM_RST2	IPC_1
GPIO_4	48	TX_BLANKING	GNSS_1	UIM_PWR2	IPC_2
GPIO_5	20	AUDIO_0	AUDIO_0	RFU	Audio_0
GPIO_6	22	AUDIO_1	AUDIO_1	RFU	Audio_1
GPIO_7	24	AUDIO_2	AUDIO_2	RFU	IPC_3/Audio_2
GPIO_8	28	AUDIO_3	AUDIO_3	RFU	IPC_4/Audio_3
GPIO_9	10	LED#1	LED#1	LED#1	IPC_5
GPIO_10	26	W_Disable2#	W_Disable2#	W_Disable2#	IPC_6
GPIO_11	23	Wake_On_WWAN	Wake_On_WWAN	Wake_On_WWAN	IPC_7
GPIO_12	25	DPR	DPR	DPR	IPC_8

Module Configuration Decodes				Module Type and Main Host Interface ¹	Port Configuration ²	State
CONFIG_0 (Pin 21)	CONFIG_1 (Pin 69)	CONFIG_2 (Pin 75)	CONFIG_3 (Pin 1)			
GND	GND	GND	GND	SSD - SATA	N/A	0
GND	NC	GND	GND	SSD - PCIe	N/A	1
GND	GND	NC	GND	WWAN - PCIe	0	2
GND	NC	NC	GND	WWAN - PCIe	1	3
GND	GND	GND	NC	WWAN - USB 3.0	0	4
GND	NC	GND	NC	WWAN - USB 3.0	1	5
GND	GND	NC	NC	WWAN - USB 3.0	2	6
GND	NC	NC	NC	WWAN - USB 3.0	3	7
NC	GND	GND	GND	WWAN - SSIC	0	8
NC	NC	GND	GND	WWAN - SSIC	1	9
NC	GND	NC	GND	WWAN - SSIC	2	10
NC	NC	GND	GND	WWAN - SSIC	3	11
NC	GND	NC	GND	WWAN - SSIC	2	12
NC	NC	GND	NC	WWAN - PCIe	3	13
NC	GND	NC	NC	RFU	N/A	14
NC	NC	NC	NC	No Module Present	N/A	15



WWAN M.2

Purism

Copyright 2018 GNU GPLv3

Sheet: /WWAN M.2/
File: wwan_m2.sch

Size: A4
KiCad E.D.A. kicad 4.0.7

eric.kuzmenko@puri.sm
angus.ainslie@puri.sm
nicole.farber@puri.sm
christian.schilmoeller@puri.sm

Rev: v0.1.0
Id: 15/24

Audio

Reference:
http://www.52rd.com/S_txt/2011_3/TXT26685.htm
<http://www.sengpielaudio.com/calculator-transferfactor.htm>
<https://electronics.stackexchange.com/questions/31442/how-can-i-switch-this-audio-jack-using-its-own-mechanical-switches-without-cre>
 (Nit6 does the same)
 +Zener diode to protect against ranges outside of -0.9V to 3.3V

dB specs in datasheet is a unit of power gain (not dBu or VU) with respect to the DAC's unattenuated output

"HP Output - 62.5mW max, 1.02kHz sine into 16Ω load at 3.3 V"
 $\Rightarrow (1V)^2/(16\Omega)=62.5mW$
 $\therefore V_{rms}=1V \Rightarrow V_p(\text{amplitude})=1.414V$
 $\therefore I_{rms}(\text{max})=62.5mA$

If HP_DET is HIGH for >100ms then HPs are present

S/E button on earbud headsets shorts the mic for key function

Could use FSA8008 to detect mic



$Z(\text{hp}) \geq 16\Omega$

<3.3μA

1M

3V3_P

HP_DET

HP_DET

SMD Equivalents:

SJ-43515RS-SMT-TR

SJ-43515TS

Pin 5 (tip switch) is NC,

open when inserted

If just headphones then

HP_DET=HIGH, R(mic)=0

may add ~220uF cap parallel to Zener

Ext-Mic enabled MIC_SEL=LOW

Int-Mic enabled MIC_SEL=LOW

Add TVS next to int-mic? (OpenMoko does this)

-37dB=14.1254mV/Pa

\therefore mic produces 14.1254mVrms when exposed to a

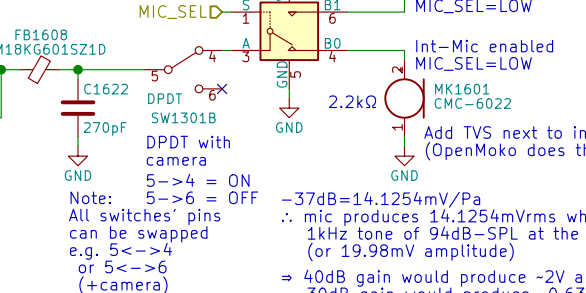
1kHz tone of 94dB-SPL at the capsule

(or 19.98mV amplitude)

\Rightarrow 40dB gain would produce -2V amplitude (4Vpp, clipping)

30dB gain would produce -0.632V amplitude (1.264Vpp)

38.33dB gain would yield 3.3Vpp



Note: 5->4 = ON

5->6 = OFF

All switches' pins can be swapped

e.g. 5<->4 or 5<->6 (+camera)

SW Mute Mic: MUTE_ADC=1

MIC_IN

MIC_BIAS

MIC_SEL

MIC_SEL

MIC_SEL

MIC_SEL

MIC_SEL

MIC_SEL

MIC_SEL

Audio

Purism

Copyright 2018 GNU GPLv3

Sheet: /Audio/
 File: audio.sch

Size: A4

Date: 2018-06-15

KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0

Id: 16/24

eric.kuzmenko@puri.sm

angus.ainslie@puri.sm

nicole.farber@puri.sm

christian.schilmoeller@puri.sm

LCR Measurements:

Earbud Microphone:

@1kHz

LS = 3.844mH

LP = 15.757H

CS = 6.583uF

CP = 1612.8pF

RS = 1.5465kOhms

RP = 1.5478kOhms

θ = -0.8deg

Headset Speaker:

@1kHz

LS = 244.4uH

LP = 141.99mH

CS = 103.6uF

CP = 178.77nF

RS = 36.860hms

RP = 36.860hms

θ = -2.3deg

Earbud Speaker:

@1kHz

LS = 25.2uH

LP = 311.0mH

CS = 1.0mF

CP = 81.95nF

RS = 17.0300hms

RP = 17.0340hms

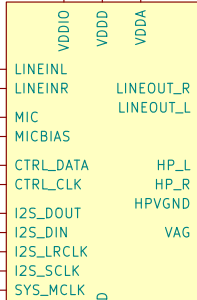
θ = 0.5deg

7-bit Slave Address: 0x0A (0001 010x)

Read: 0x15
 Write: 0x14

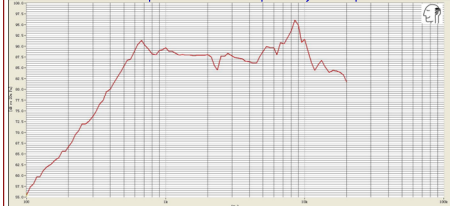
MIC_IN 10
 MIC_BIAS 11

I2C1_SDA 18
 I2C1_SCL 19
 SAI2_RXD 16
 SAI2_TXD 17
 SAI2_TXFS 14
 SAI2_TXCK 15
 SAI2_MCLK 13

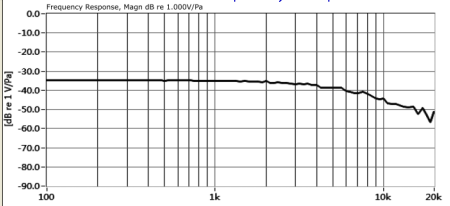


Mute via MUTE_LO=1
 may use lineout left channel for pseudo-earpiece speaker

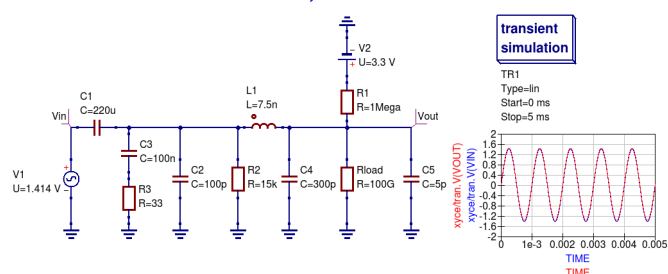
Built-In Speaker's Frequency Response:



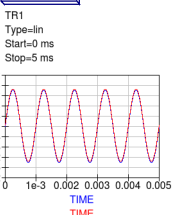
Built-In Mic's Frequency Response:



Simulation of HP_DET @ 1kHz output without HP jack inserted:



transient simulation



RGMII 10/100/1000 Ethernet

3V3_P FB1701 BLM18PG121SN1D C1703 1uF C1705 220nF ENET_2V5 C1707 220nF C1708 1uF C1710 1uF C1704 10uF C1706 220nF GND U1701 4 16 VDD33 AVDD33 VDDIO_REG VDDH_REG LX 29 10 3 DVDDL 47 PWR_FLAG ENET_1V1 L1701 4.7uH C1713 10uF C1716 10uF GND FB1702 BLM18PG121SN1D C1711 220nF C1714 220nF C1717 220nF C1718 220nF GND C1719 220nF C1720 220nF C1721 220nF GND LED_ACT R1723 270 LED_LINK10_100 R1724 270 LED_LINK1000 R1725 270 GND

ENET_RD0 R1701 10k ENET_2V5 R1702 NC ENET_RD1 R1703 10k ENET_2V5 R1704 NC LED_ACT R1705 10k ENET_RX_CTL R1706 10k ENET_RD2 R1707 10k ENET_RXC R1708 10k ENET_RD3 R1709 10k LED_LINK1000 R1710 10k LED_LINK10_100 R1711 10k GND

ENET_TXC 35 GTX_CLK 36 TXD0 37 TXD1 38 TXD2 39 TXD3 34 ENET_TX_CTL TX_EN 33 ENET_RXC RX_CLK 31 RXD0 30 RXD1 28 RXD2 27 RXD3 32 ENET_RX_CTL RX_DV 46 SIP 45 SIN 43 SOP 42 SON 41 SD 1 MDC 48 MDIO 2 RST 40 WOL_INT 5 INT 22 PPS 25 CLK_25M VDDH_REG LED_LINK10_100 26 LED_LINK1000 24 LED_ACT 23 XTLO 7 XTLI 9 RBIAS AR8031 49 GND

ENET_MDCC ENET_MDIO ENET_RST ENET_WoL ENET_INT TP1701 TEST_1P TP1702 TEST_1P CLK02 R1712 10k R1714 10k R1716 10k R1717 10k R1718 10k R1721 2.37k R1719 NC R1720 NC D1701 DB2J209 D1702 GREEN Y1701 25MHz C1701 22pF C1702 22pF R1722 2.37k GND

ETH_TRX0_P TD1+ J1701 RJ45 J1 TX1+ J2 TX1- J3 TX2+ J6 TX2- J4 TX3+ J5 TX3- J7 TX4+ J8 TX4- VCC 1 GND 10 SH1 SH2 GREEN YELLOW 1 2 D1702 GREEN

Ethernet
Purism
Copyright 2018 GNU GPLv3
Sheet: /Ethernet/
File: ethernet.sch
Size: A4 Date: 2018-06-15 Rev: v0.1.0
KiCad E.D.A. kicad 4.0.7 Id: 17/24

 **Purism**

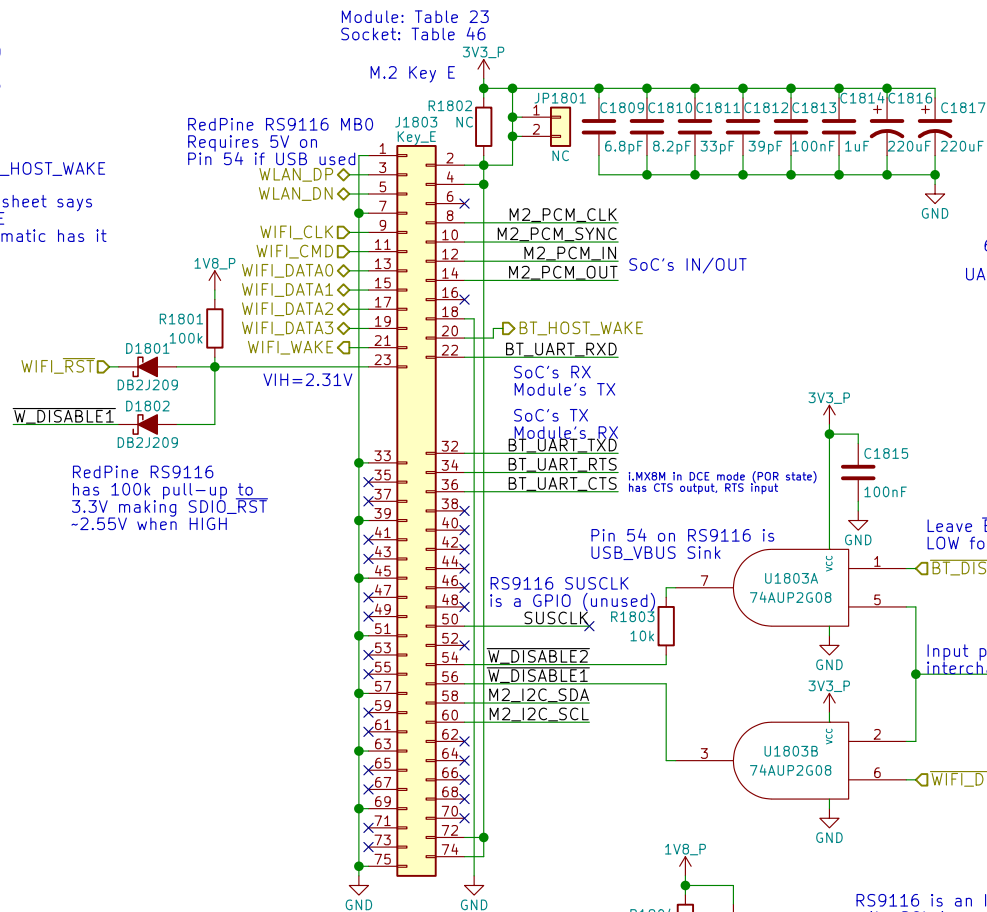
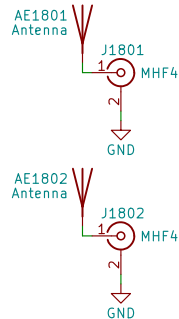
eric.kuzmenko@puri.sm
angus.ainslie@puri.sm
nicole.faeber@puri.sm
christian.schilmoeller@puri.sm

Rev: v0.1.0
Id: 17/24

WLAN+BT M.2

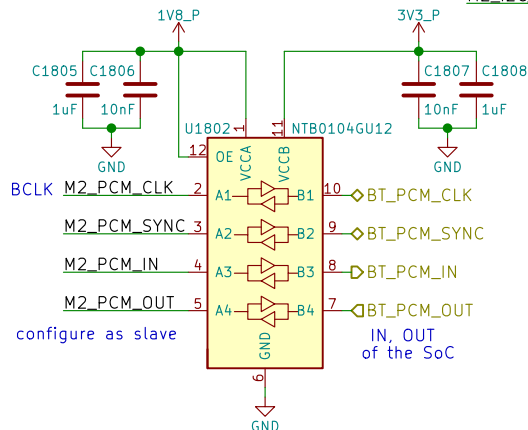
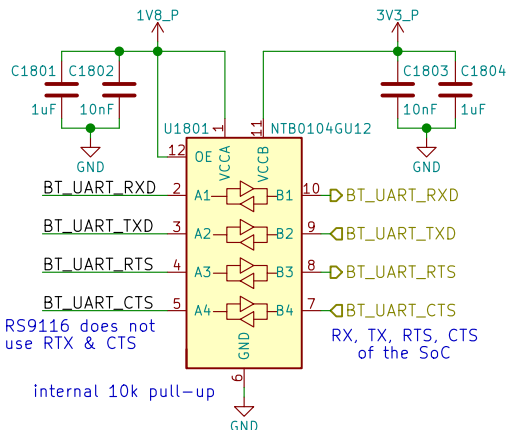
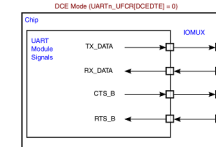
RS9116 NC:
RTS, CTS, BT_HOST_WAKE

RS9116 datasheet says
no WIFI_WAKE
but the schematic has it



6.2 M.2 Signal Directions

UARTn_UFCR[DCEDTE]=0 on POR



WLAN+BT M.2

Purism

Copyright 2018 GNU GPLv3

Sheet: /WLAN+BT M.2/
File: wifi_bt_m2.sch

Size: A4
KiCad E.D.A. kicad 4.0.7

eric.kuzmenko@puri.sm

angus.ainslie@puri.sm

nicole.farber@puri.sm

christian.schilmoeller@puri.sm

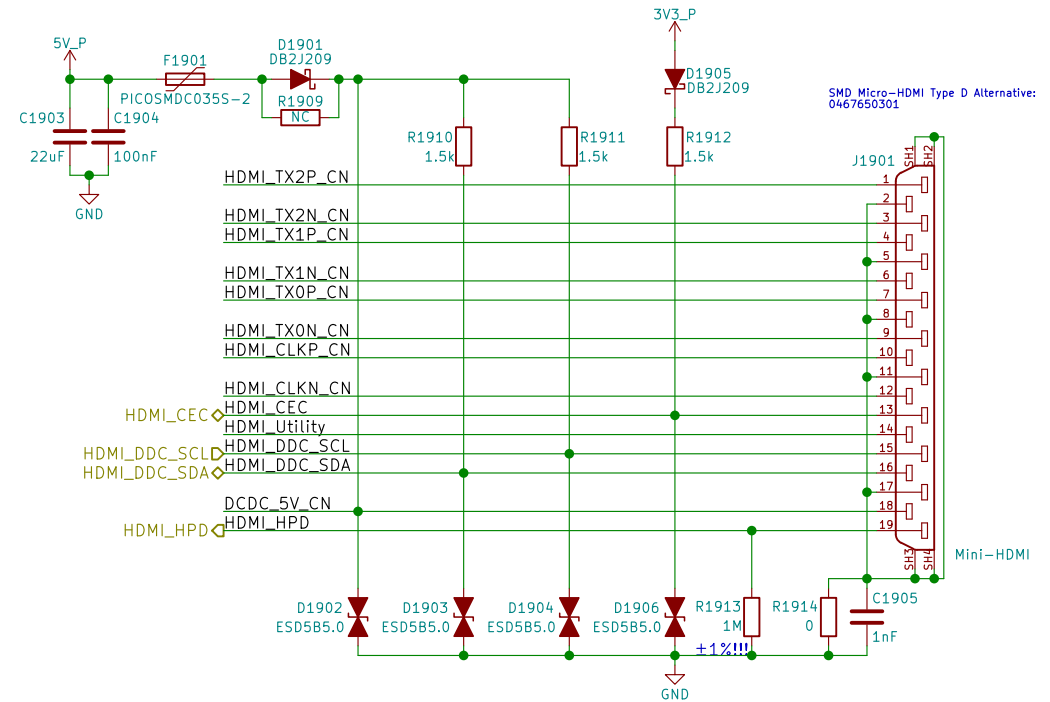
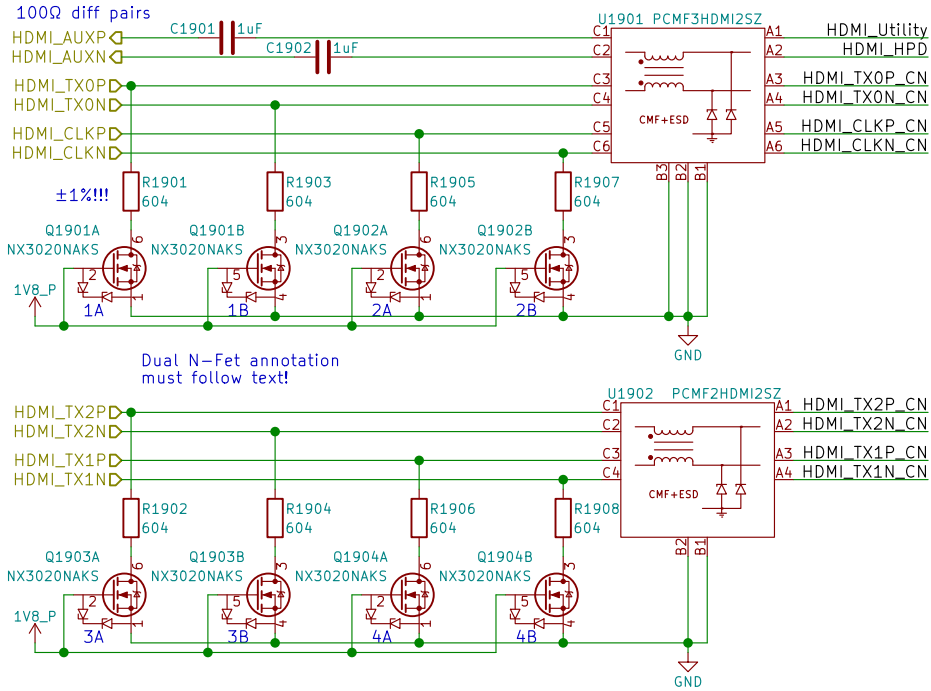
Rev: v0.1.0

Id: 18/24

TUSB1046 can be used for DP over USB-C

HDMI

Layout Note:
May need swap some signals
due to micro-HDMI pinout diff
depending on pin location/routing



HDMI



Copyright 2018 GNU GPLv3

Sheet: /HDMI/
File: hdmi.sch

Size: A4
KiCad E.D.A. kicad 4.0.7

Date: 2018-06-15

Rev: v0.1.0
Id: 19/24

eric.kuzmenko@puri.sm

angus.ainstie@puri.sm

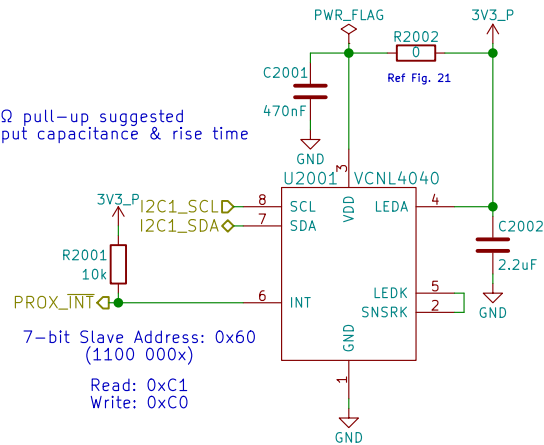
nicole.farber@puri.sm

christian.schilmoeller@puri.sm

Sensors

Proximity & Ambient Light

Note:
I2C 2.2kΩ pull-up suggested
check input capacitance & rise time



Reference:
<https://www.vishay.com/docs/84307/designingvcnl4040.pdf>
<http://www.vishay.com/docs/84931/vcnl4040sensorboardfiles.pdf>

9-Axis IMU

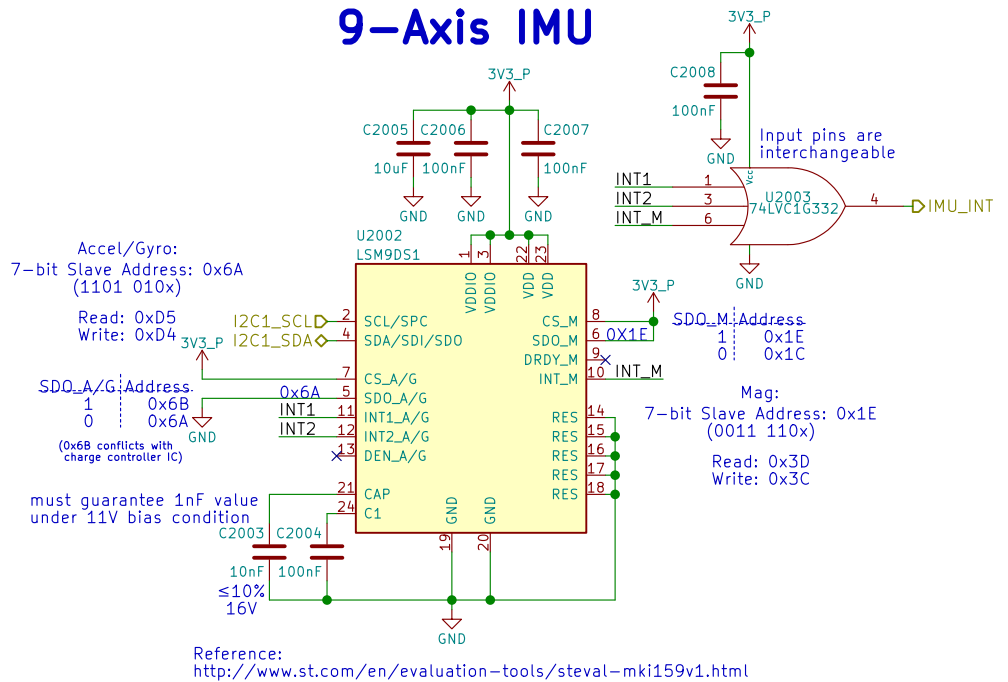


Table 19. Accelerometer and gyroscope SAD•Read/Write patterns

Command	SAD[6:1]	SAD[0] = SA0	R/W	SAD•R/W
Read	110101	0	1	11010101 (D5h)
Write	110101	0	0	11010100 (D4h)
Read	110101	1	1	11010111 (D7h)
Write	110101	1	0	11010110 (D6h)

Table 20. Magnetic sensor SAD•Read/Write patterns

Command	SAD[6:2]	SAD[1] = SDO/SA1	SAD[0]	R/W	SAD•R/W
Read	00111	0	0	1	00111001 (39h)
Write	00111	0	0	0	00111000 (38h)
Read	00111	1	0	1	00111101 (3Dh)
Write	00111	1	0	0	00111100 (3Ch)

Sensors



Copyright 2018 GNU GPLv3

Sheet: /Sensors/
File: sensors.sch

Size: A4 Date: 2018-06-15

KiCad E.D.A. kicad 4.0.7

eric.kuzmenko@puri.sm

angus.ainslie@puri.sm

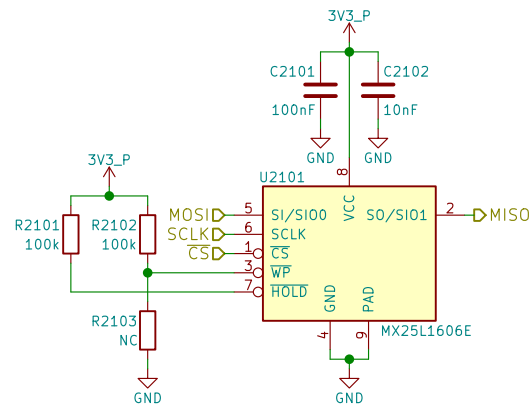
nicole.farber@puri.sm

christian.schilmoeller@puri.sm

Rev: v0.1.0

Id: 20/24

SPI NOR Flash



SPI NOR Flash



Copyright 2018 GNU GPLv3

Sheet: /SPI Flash/
File: flash.sch

Size: A4 Date: 2018-06-15

KiCad E.D.A. kicad 4.0.7

eric.kuzmenko@puri.sm

angus.ainstlie@puri.sm

nicole.ferber@puri.sm

christian.schilmoeller@puri.sm

Rev: v0.1.0

Id: 21/24

The diagram illustrates the electrical connections for the Smart Card module (U2201) within the SEC11110 system. The module is connected to the SEC11110 via a series of pins, including power (VDD5, VDD33), control signals (SC1_VCC, SC1_RST, SC1_CLK, SC1_I/O, SC1_C4, SC1_C8, SC1_PRSTN/JTAG_TMS, RESET, TEST, JTAG_TDI, JTAG_TDO, JTAG_CLK, VSS(flag)), and status signals (DET, C8, C4, SCH). The Smart Card module (U2201) is shown with its internal components, including capacitors (C2201, C2202, C2203) and resistors (R2201, R2202, R2203). The J2201 connector provides power (VCC, RST, CLK, GND, VPP, I/O) and status signals (DET, C8, C4, SCH). The diagram also shows external components like capacitors (C2201, C2202, C2203) and resistors (R2201, R2202, R2203) connected to the module pins.

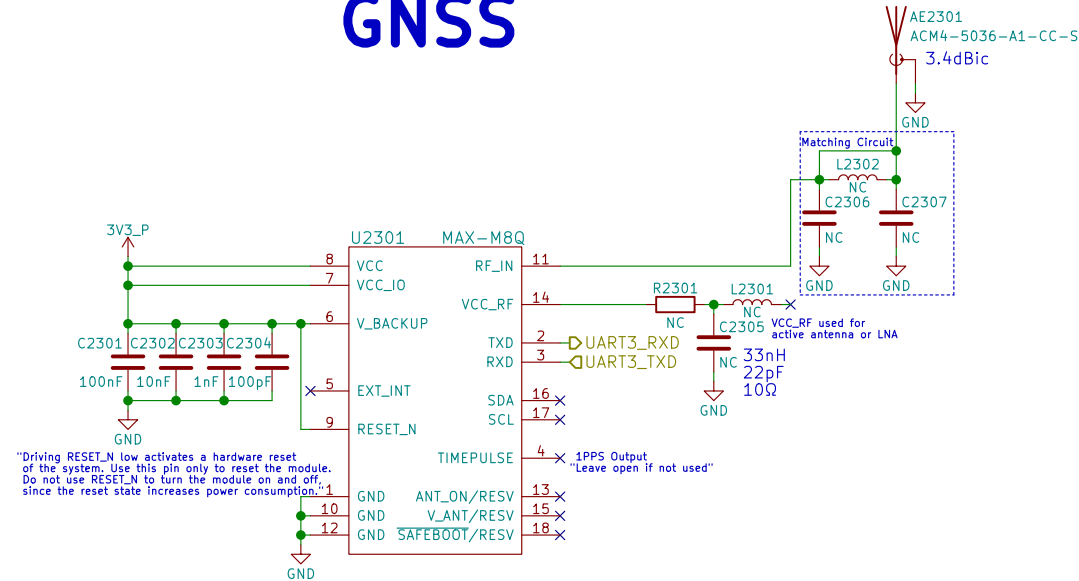
Smart Card



christian.schilmoeller@puri.sm

Id: 22/24

GNSS



GNSS



Copyright 2018 GNU GPLv3

Sheet: /GNSS/

File: gnss.sch

Size: A4

Date: 2018-06-15

KiCad E.D.A. kicad 4.0.7

Rev: v0.1.0

Id: 23/24

eric.kuzmenko@puri.sm

angus.ainstlie@puri.sm

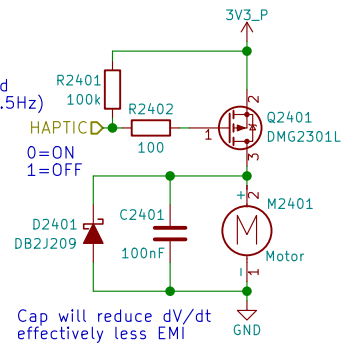
nicole.farber@puri.sm

christian.schilmoeller@puri.sm

Haptic Motor

PWM pins occupied:
 GPIO1_I001 - LCD Backlight
 GPIO1_I013 - LED
 GPIO1_I014 - Ethernet (CLKO_25MHz)
 GPIO1_I015 - CSI (CLKO2)

PWM needed?
 Only needs to be toggled
 ON 1 sec, OFF 1 sec (0.5Hz)
 Can MUX as either
 GPIO or PWM2
 swapping with LED



When the motor is off
 both terminals are at GND

Motor will have wire leads
 with a 2-pin Molex or Boom Precision
 connector installed (by request!)
 Metal housing is floating
 (not connected to either pin)
 => could connect housing to GND

Cheaper Motor Connector:
https://lcsc.com/product-detail/1-25T-Connectors_1-25T-1-2AW_C10832.html

Motor Source:
https://www.alibaba.com/product-detail/Coin-motor-vibration-dc-motor-cellphone_1994583657.html?spm=a2700.8443308.0.0.5aa13e5f1wxHgs

Motor Datasheet:
<https://cloud.puri.sm/s/z8JR6DJ4KrJYzoW>

Motor PN:
 BY0820Z021L20

Haptic/Vibration Motor



Copyright 2018 GNU GPLv3

Sheet: /Haptic Motor/
 File: haptic.sch

Size: A4 Date: 2018-06-15

KiCad E.D.A. kicad 4.0.7

eric.kuzmenko@puri.sm

angus.ainstlie@puri.sm

nicole.farber@puri.sm

christian.schilmoeller@puri.sm

Rev: v0.1.0

Id: 24/24