



VOLVO

SIMULATION FOR AIRBAG SENSOR CALIBRATION

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2nd **E**uropean **H**yper**W**orks **T**echnology **C**onference

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AB VOLVO GROUP – Business Area

Volvo Trucks



Renault Trucks



Mack Trucks



Nissan Diesel



Construction Equipment



Buses



Volvo Penta



Volvo Aero

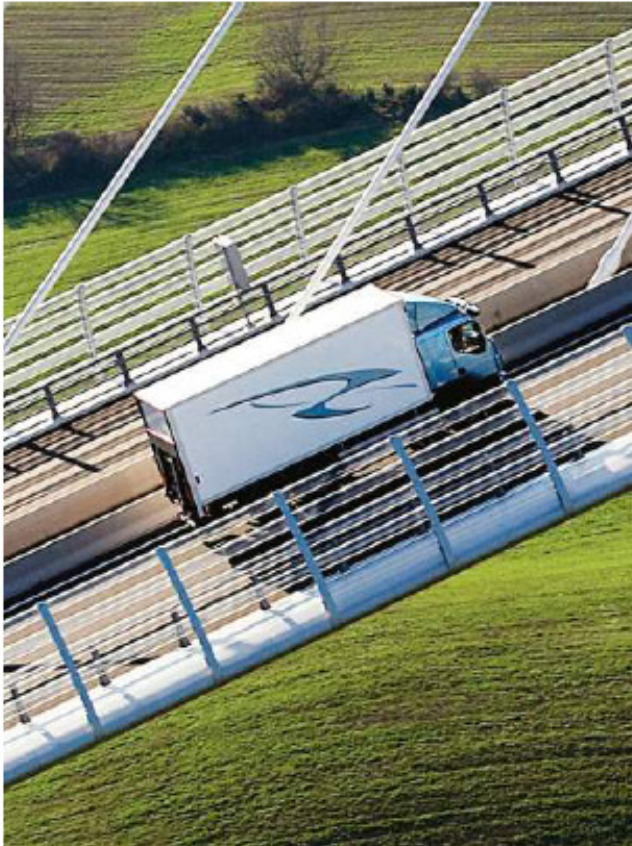


Financial Services



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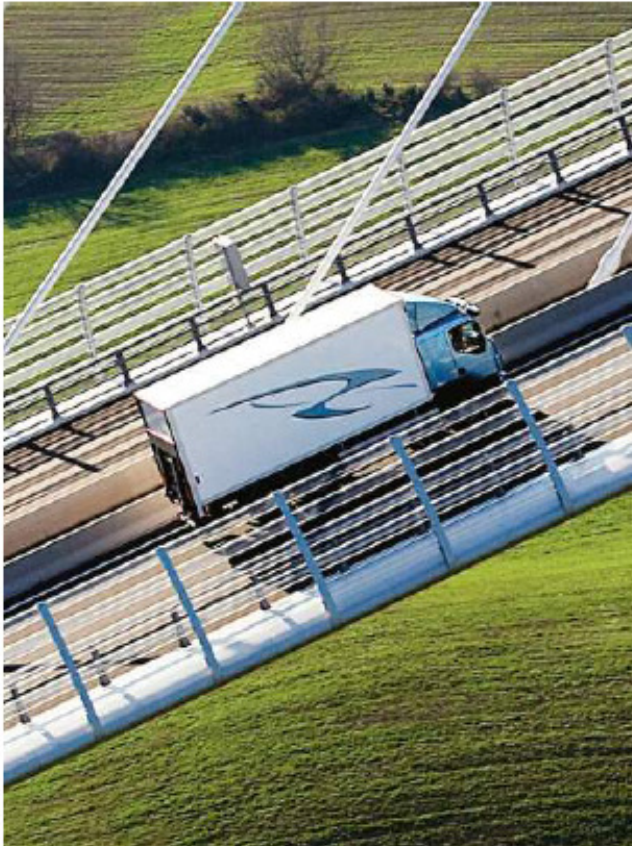
AB VOLVO GROUP – Corporate Values



QUALITY

SAFETY

ENVIRONMENT



QUALITY

“Safety is – and must always be – the fundamental principle of our design work-”

Assar Gabrielsson and Gustaf Larson,
founders of Volvo

ENVIRONMENT

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AIRBAG TEST



FM
30 km/h
0° TRAILER BACK

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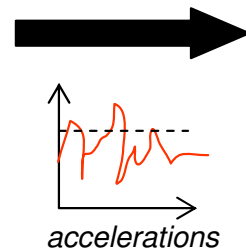
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AIRBAG CONTROL



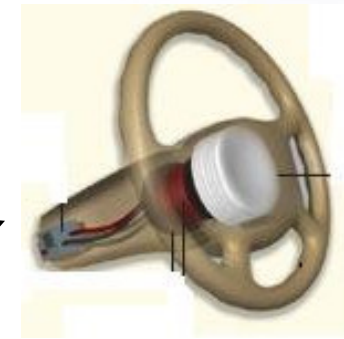
ECU
Electronic Control Unit

**CRASH
SITUATION**

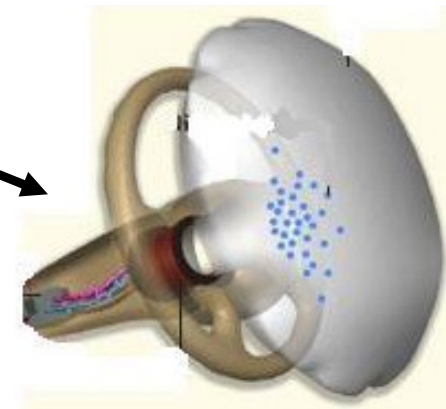


ECU

algorithm



**NON
FIRE**

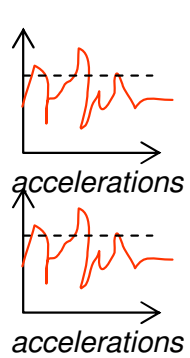


FIRE

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HOW TO CALIBRATE AN AIRBAG ECU ?

**TODAY =
TESTS**

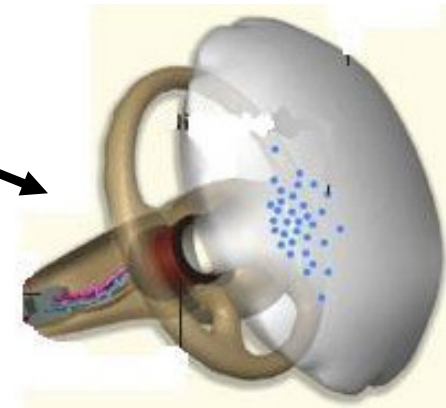


ECU

algorithm

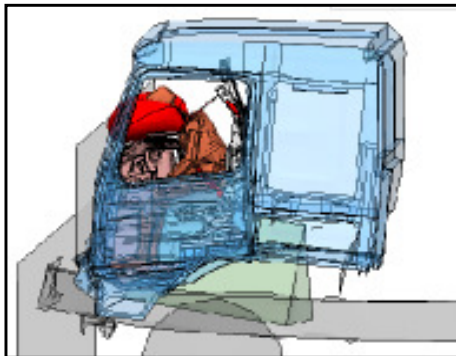


**NON
FIRE**



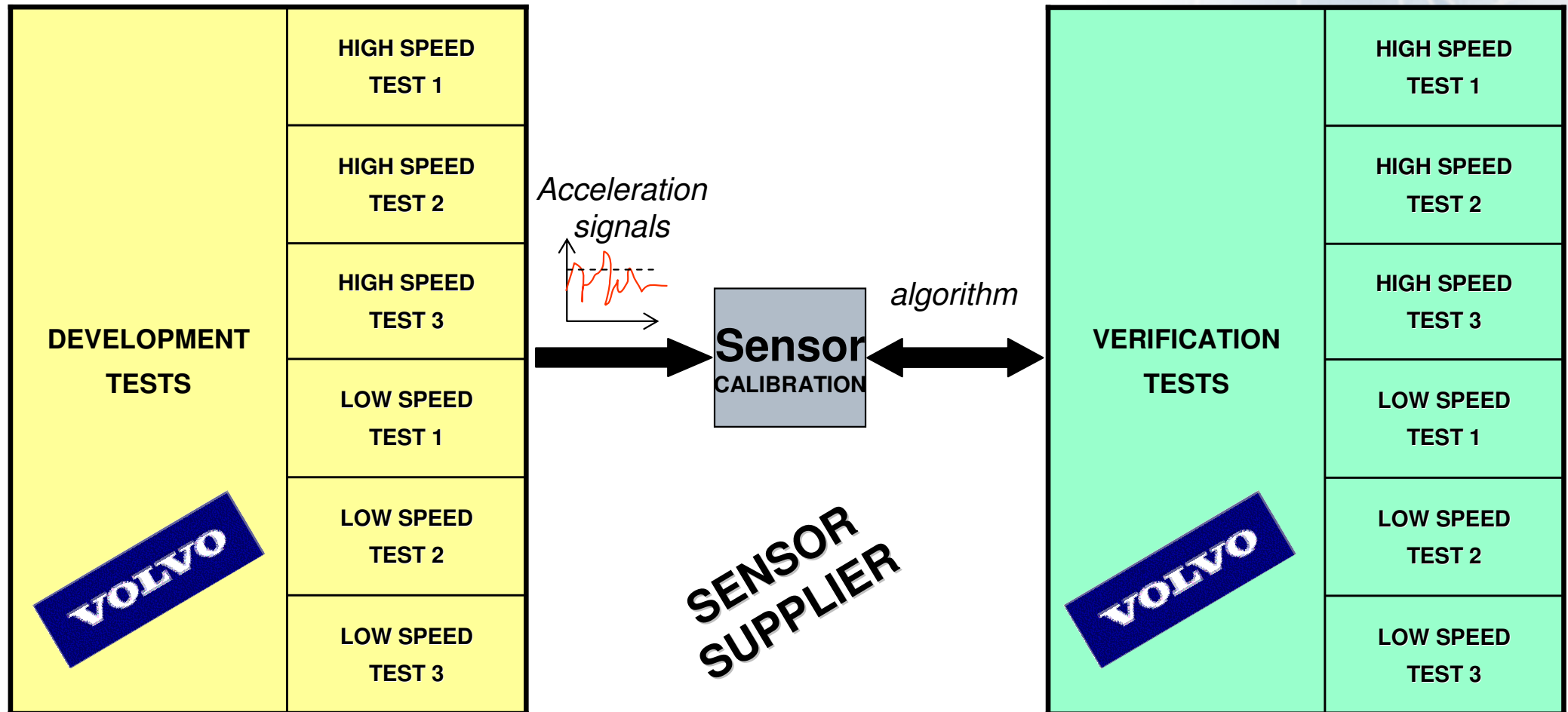
FIRE

**FUTURE =
SIMULATION**



HOW TO CALIBRATE AN AIRBAG ECU ?

An **airbag sensor** has to be **calibrated** based on acceleration signals.



RESEARCH AND DEVELOPMENT PROJECT

A two years **research and development** project has been done to define the **simulation methodology**:

- **MESH GUIDELINES**: recommendations for the mesh quality, mesh size (mesh class) and element formulation
- **TEST SENSOR ACCELERATION**: frequency analysis to find the frequency spectrum that needs to be caught
- **FILTERING**: cut off frequency and sampling rate have been set up to filter numerical noise and catch physical accelerations
- **SENSOR MODELING**: recommendations to represent the sensors

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PROJECT APPLICATION: FH trucks

A new airbag sensor will be introduced in **FH trucks** and in the mean time, some parts will be modified:

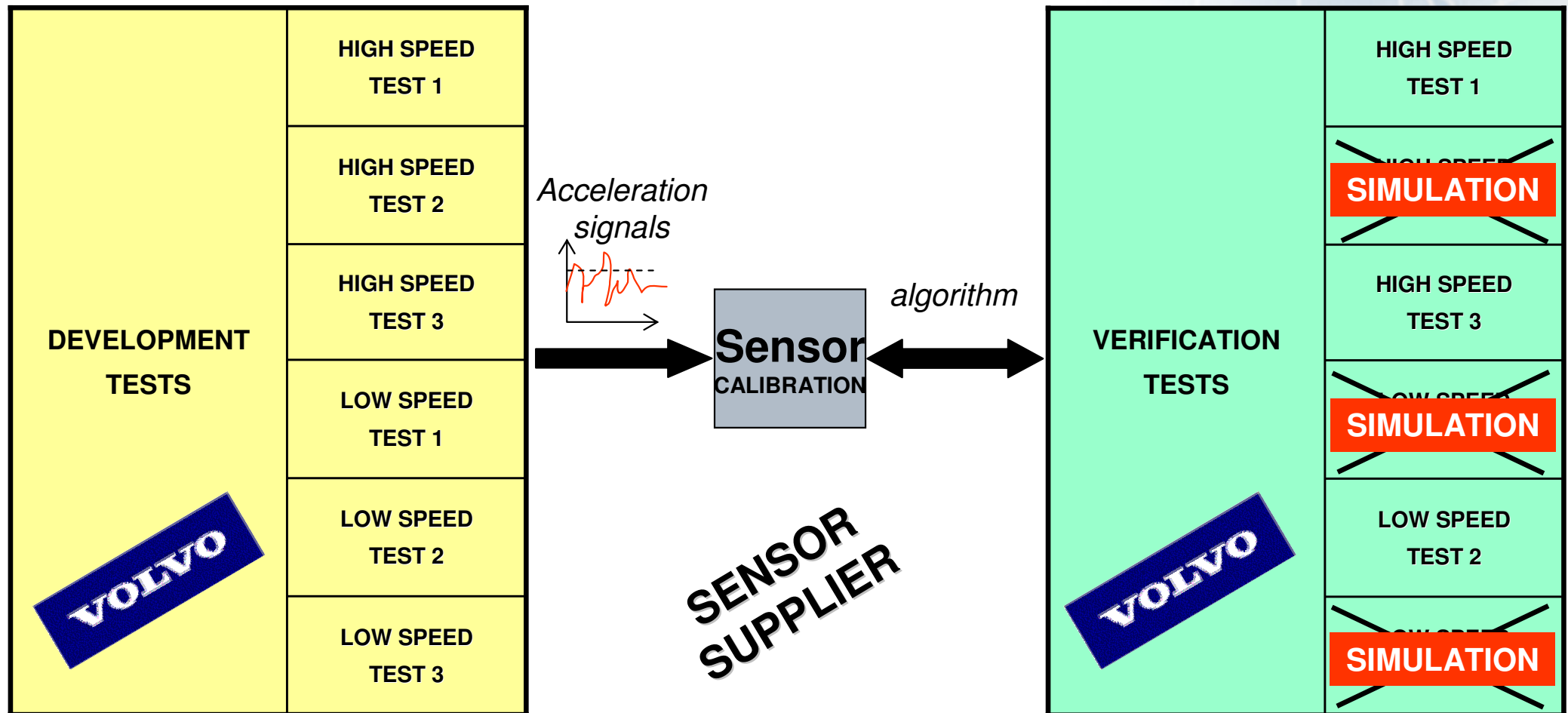


**2007-2008: 1st application
of airbag sensor
calibration with simulation
help in the VOLVO Group**

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PROJECT APPLICATION: FH trucks

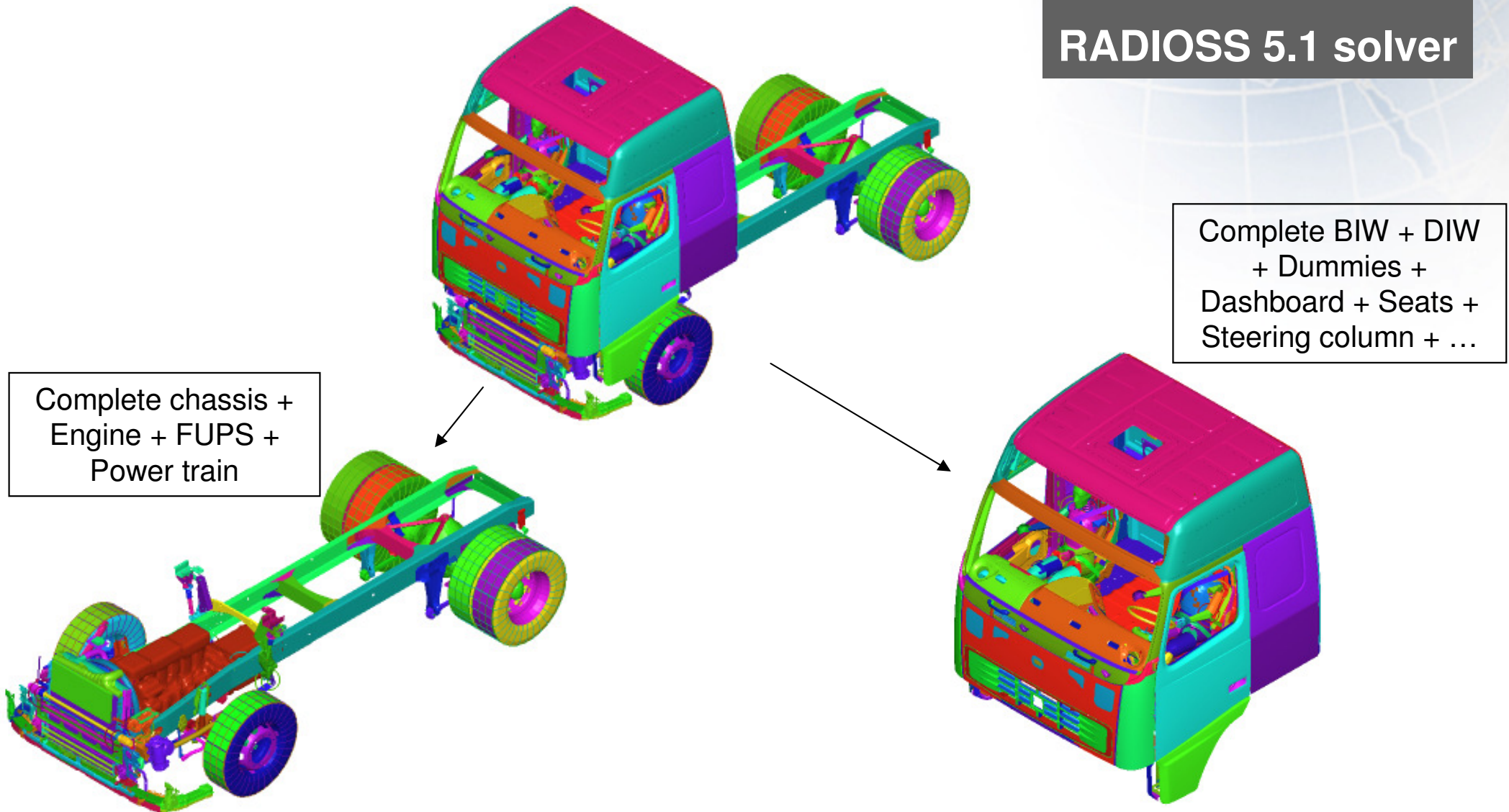
Airbag sensor calibration matrix



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PROJECT APPLICATION: FH trucks

Finite Element model
1.5 million elements
RADIOSS 5.1 solver

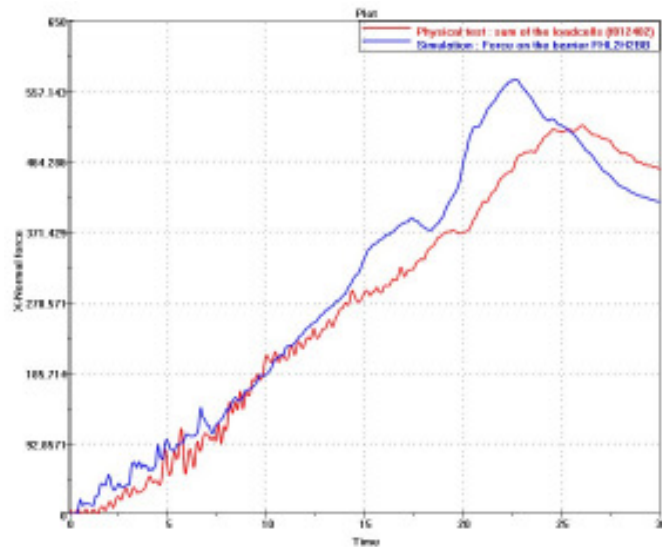
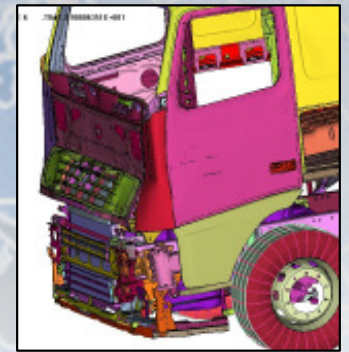


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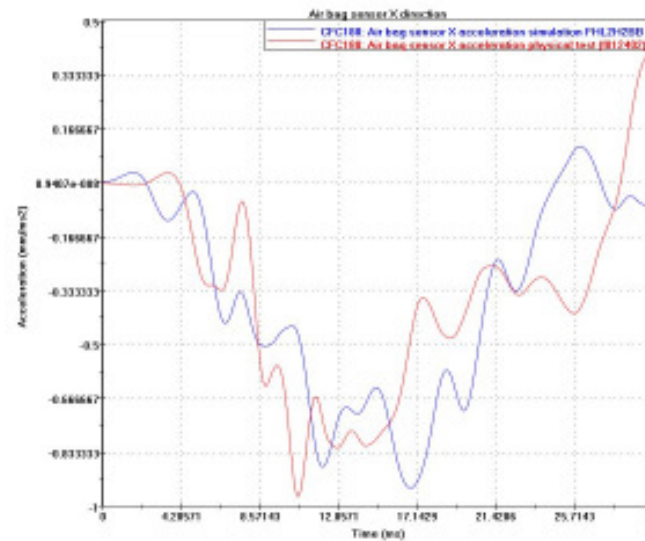
PROJECT APPLICATION: FH trucks

Test versus simulation **correlation:**

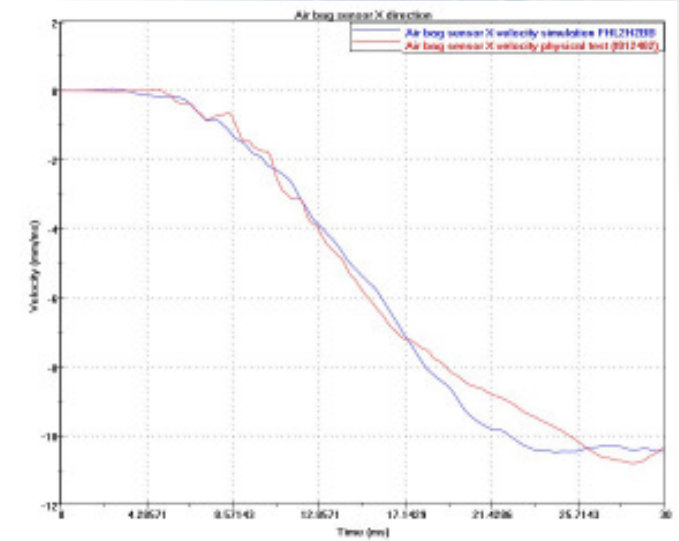
Simulation / **Physical test**



BARRIER FORCE



**AIRBAG SENSOR
ACCELERATION**



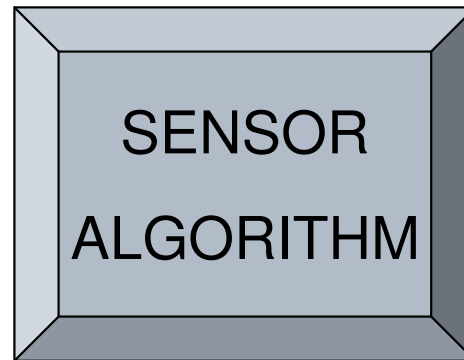
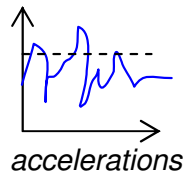
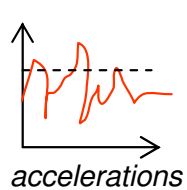
**AIRBAG SENSOR
VELOCITY**

PROJECT APPLICATION: FH trucks

Test versus simulation **correlation**: validation of the model with the airbag sensor supplier

PHYSICAL TEST

(from the development test phase)



Same Time To Fire
⇒ Model is validated

Different Time To Fire
⇒ Model is not validated

SIMULATION

PROJECT APPLICATION: FH trucks

Sensitivity analysis: done if the model is validated to improve the **robustness** of the algorithm

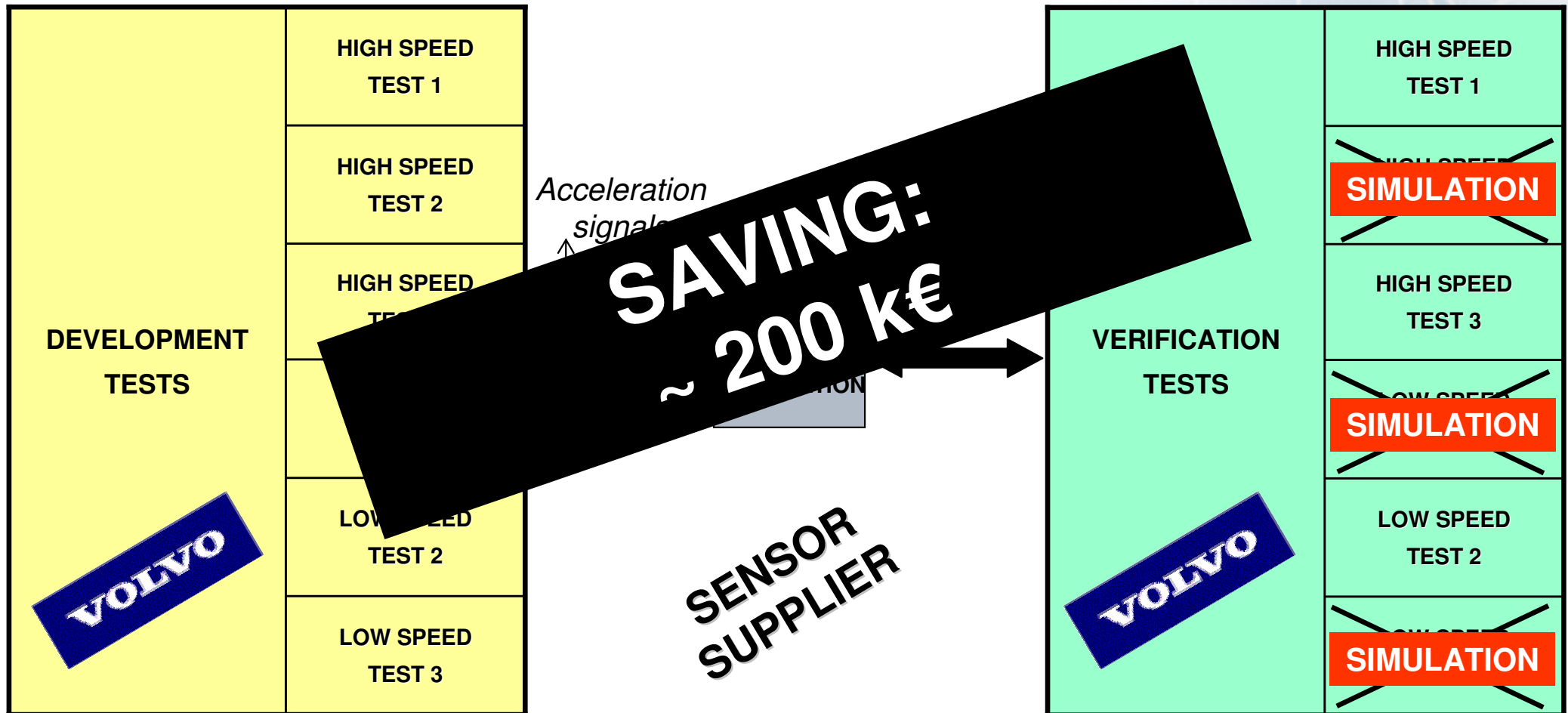
- influence of new or modified parts
- influence of cab variants
- influence of chassis variants
- influence of truck mass
- influence of test speed
- influence of barrier position (height, angle...)

**Influence on the
airbag *Time To Fire*
⇒ Algorithm
adjustments**

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PROJECT APPLICATION: FH trucks

Airbag sensor calibration matrix



CONCLUSIONS: DIFFICULTIES ENCOUNTERED

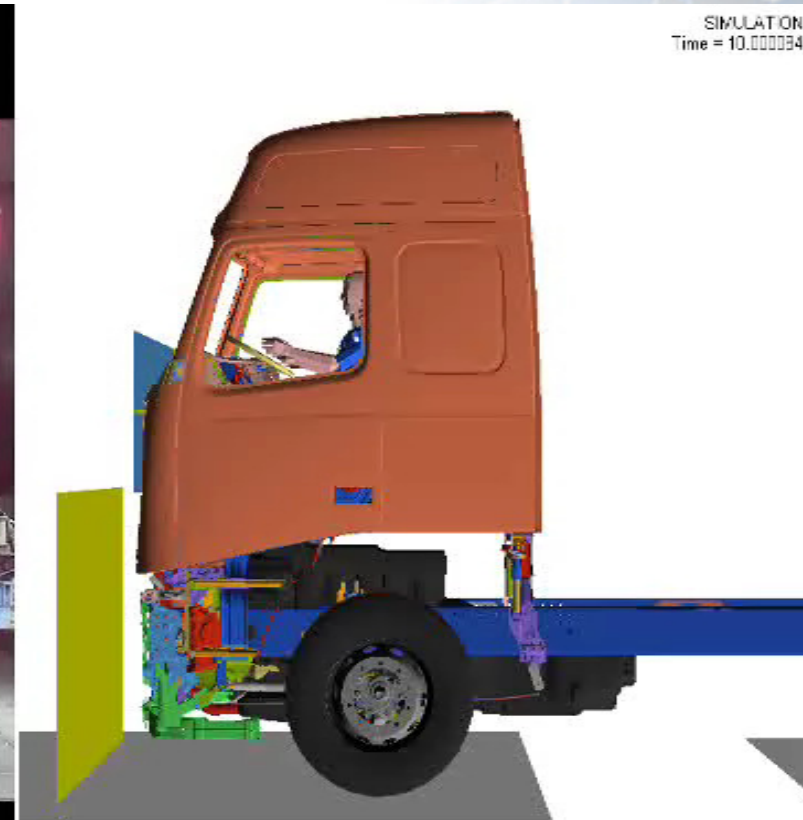
- Level of details needed in the models (pipes, tanks, brackets...)
- Material characteristics for crash application
- Rupture, tearing (welds, glue, bolts, sheet metal...)
- Model size: 64 bits workstations and software needed
- Model size : CPU time
- Test robustness

CONCLUSIONS: CAE BENEFITS

- Many variants can be simulated (cab size, engine...)
- Details can be seen in simulation and not in test (transparent vehicle)
- The worst case scenario can be found by computation and influence the verification test configuration
- New test conditions can be tested (speed, angle...)
- Simulations will bring higher robustness to the algorithm
- Simulations can show how new introduced parts (eg Front lid in steel instead of plastic) will effect the sensor signal and the algorithm

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THANK YOU FOR YOUR ATTENTION



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Jerome LAGRUT

EHTC 2008 Sept. 30 - Oct. 1

BACKUP SLIDE: sampling rate

If we need 10 sampling points per period and if we want to catch accelerations up to 1500 Hz we need a sampling frequency :

$$T_{\text{samp}} = \frac{1}{10\nu} = \frac{1}{15 / \text{ms}} = 0.06\text{ms}$$

BACKUP SLIDE: mesh size

- We need 10 elements ($10.l_c$) per wavelength ($c.T = c/v$) for the highest frequency and the slowest (plastic) stress wave :

$$l_c \leq \frac{c}{10v} = \frac{50\text{mm/ms}}{15/\text{ms}} = 3.333\text{mm}$$

- For thicknesses of 2.mm or less this is close to the mesh convergence requirement