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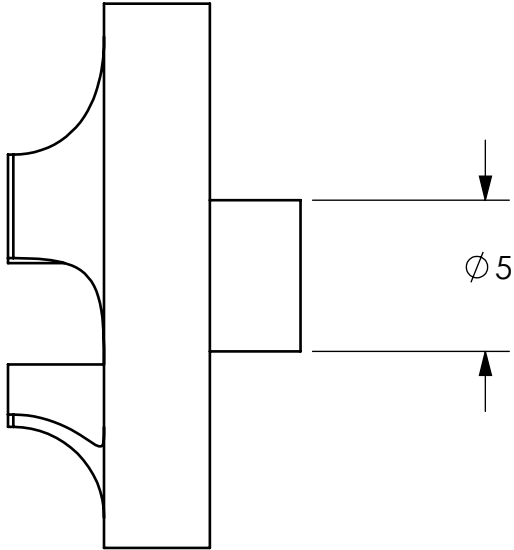
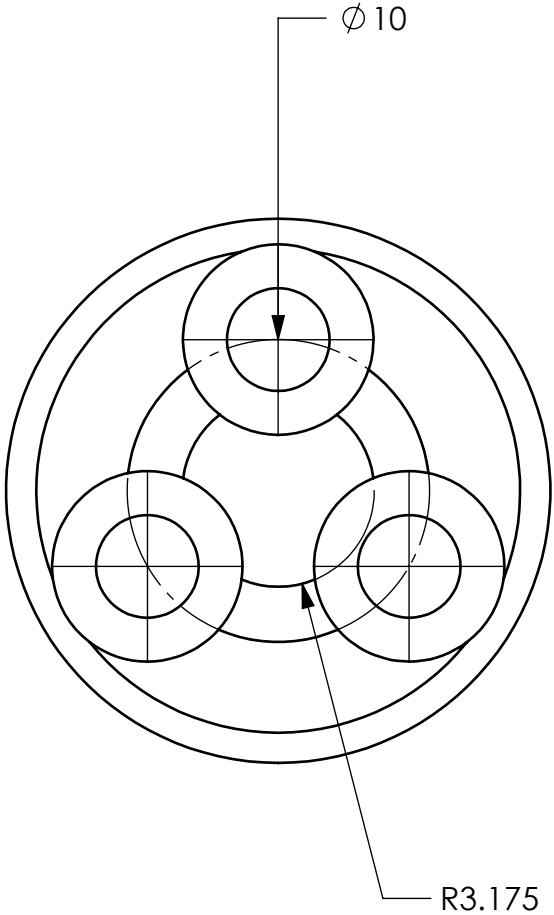
B

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| REVISIONS | | | |
|-----------|-------------|------|----------|
| REV. | DESCRIPTION | DATE | APPROVED |



| | | | | | | | |
|---|--|-----------------------|------|--|---------|--|--------------|
| UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN MM | | AUTHORIZATION | | BIOROBOTICS LAB | | | |
| DO NOT SCALE DRAWING | | | | The Robotics Institute – Carnegie Mellon University 5000 Forbes Ave. Pittsburgh, PA 15213 | | | |
| TOLERANCES: X.XX ±.010 X.XXX ±.003 ANGLES ±1.00° | | DFTG: SIMON KALOUCHE | 1/16 | PROJECT: PUMA | | | |
| SURFACE TEXTURE 64 ✓ | | DSGNR: | | | | | |
| | | CHKR: | | | | | |
| REMOVE ALL BURRS AND BREAK ALL SHARP EDGES TO .015 MAX | | ENGR: | | encoder_magnet_mount | | | |
| CAD GENERATED DRAWING, DO NOT MANUALLY UPDATE | | MATERIAL: ALUMINUM | | | | | |
| INTERNAL CMU MODEL REV: | | TREATMENT: | | | | | |
| | | | | SIZE | REV | | VER |
| | | | | SCALE: 4:1 | WEIGHT: | | SHEET 1 OF 2 |

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CARNEGIE MELLON UNIVERSITY ANY REPRODUCTION IN PART OR WHOLE WITHOUT
WRITTEN PERMISSION IS PROHIBITED.

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FILE NAME: encoder_magnet_mount.SLDDR

