

EQUATIONS

$$\bar{X} = X_{rms} e^{j\theta} = X_{rms} \angle \theta \quad (1)$$

$$S = V_{rms}^{LN} I_{rms} \quad P = V_{rms}^{LN} I_{rms} \cos(\theta_v - \theta_i) \quad Q = V_{rms}^{LN} I_{rms} \sin(\theta_v - \theta_i) \quad (2)$$

$$S = \sqrt{3} V_{rms}^{LL} I_{rms} \quad P = \sqrt{3} V_{rms}^{LL} I_{rms} \cos(\theta_v - \theta_i) \quad Q = \sqrt{3} V_{rms}^{LL} I_{rms} \sin(\theta_v - \theta_i) \quad (3)$$

$$\cos(\theta_v - \theta_i) = \frac{P}{S} \quad \bar{S} = \bar{V} \bar{I}^* = S \angle \theta_S = P + jQ \quad (4)$$

$$\bar{V}_{ab} = \sqrt{3} \bar{V}_{an} e^{j30^\circ} \quad \bar{I}_a = \sqrt{3} \bar{I}_{ab} e^{-j30^\circ} \quad \bar{Z}_\Delta = 3 \bar{Z}_Y \quad (5)$$

$$\bar{E}_1 N_2 = \bar{E}_2 N_1 \quad \bar{I}_1 N_1 - \bar{I}_2 N_2 = 0 \quad \bar{Z}'_2 = \left(\frac{N_1}{N_2} \right)^2 \bar{Z}_2 \quad v(t) = \frac{d}{dt} \lambda(t) \quad \lambda(t) = Li(t) \quad (6)$$

$$B = \mu_r \mu_0 H \quad \mu_0 = 4\pi \times 10^{-7} \quad (7)$$

$$S_{base, 3ph.} = 3 S_{base, 1ph.} \quad V_{base, LL} = \sqrt{3} V_{base, LN} \quad (8)$$

$$I_{base} = \frac{S_{base, 1ph.}}{V_{base, LN}} = \frac{S_{base, 3ph.}}{\sqrt{3} V_{base, LL}} \quad Z_{base} = \frac{V_{base, LN}}{I_{base}} = \frac{V_{base, LN}^2}{S_{base, 1ph.}} = \frac{V_{base, LL}^2}{S_{base, 3ph.}} \quad (9)$$

$$Z_{pu}^{new} = Z_{pu}^{old} \left(\frac{V_{base, old}}{V_{base, new}} \right)^2 \left(\frac{S_{base, new}}{S_{base, old}} \right) \quad (10)$$

$$\begin{bmatrix} \bar{X}_a \\ \bar{X}_b \\ \bar{X}_c \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & a^2 & a \\ 1 & a & a^2 \end{bmatrix} \begin{bmatrix} \bar{X}_{a0} \\ \bar{X}_{a1} \\ \bar{X}_{a2} \end{bmatrix} \quad \begin{bmatrix} \bar{X}_{a0} \\ \bar{X}_{a1} \\ \bar{X}_{a2} \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 1 & 1 & 1 \\ 1 & a & a^2 \\ 1 & a^2 & a \end{bmatrix} \begin{bmatrix} \bar{X}_a \\ \bar{X}_b \\ \bar{X}_c \end{bmatrix} \quad a = e^{j120^\circ} \quad (11)$$

$$L_{total} = L_{phase} = \frac{1}{2} L_{loop} = \frac{\mu_0}{2\pi} \ln \left(\frac{R}{e^{-1/4} r} \right) \quad i(t) = \frac{d}{dt} q(t) \quad q(t) = Cv(t) \quad (12)$$

$$V_{12} = \frac{q}{2\pi\epsilon_0} \ln \left(\frac{R_2}{R_1} \right) \quad C_{xy} = \frac{\pi\epsilon_0}{\ln \left(\frac{R}{r} \right)} \quad C_n = C_{phase} = \frac{2\pi\epsilon_0}{\ln \left(\frac{R}{r} \right)} \quad \epsilon_0 = 8.85 \times 10^{-12} \quad (13)$$

$$\bar{z} = R + j\omega L \quad \bar{y} = G + j\omega C \quad \bar{Z}_C = \sqrt{\frac{\bar{z}}{\bar{y}}} \quad \gamma = \sqrt{\bar{z}\bar{y}} = \alpha + j\beta \quad (14)$$

$$\cosh(\gamma x) = \frac{e^{\gamma x} + e^{-\gamma x}}{2} = \frac{e^{\alpha x} \angle \beta x + e^{-\alpha x} \angle -\beta x}{2} \quad (15)$$

$$\sinh(\gamma x) = \frac{e^{\gamma x} - e^{-\gamma x}}{2} = \frac{e^{\alpha x} \angle \beta x - e^{-\alpha x} \angle -\beta x}{2} \quad (16)$$

$$A(x) = D(x) = \cosh(\gamma x) \quad B(x) = \bar{Z}_C \sinh(\gamma x) \quad C(x) = \frac{1}{\bar{Z}_C} \sinh(\gamma x) \quad (17)$$

$$A(x) = D(x) = \cos(\beta x) \quad B(x) = j \bar{Z}_C \sin(\beta x) \quad C(x) = \frac{j}{\bar{Z}_C} \sin(\beta x) \quad (18)$$

$$\bar{V}(x) = \bar{V}_i e^{\alpha x} e^{j\beta x} + \bar{V}_r e^{-\alpha x} e^{-j\beta x} \quad \text{where} \quad \bar{V}_i = \frac{\bar{V}_R + \bar{Z}_C \bar{I}_R}{2} \quad \bar{V}_r = \frac{\bar{V}_R - \bar{Z}_C \bar{I}_R}{2} \quad (19)$$

$$\bar{Z}' = B(x) \quad \bar{Y}' = \frac{2(A(x) - 1)}{B(x)} \quad \bar{Z} = \bar{z}x \quad \bar{Y} = \bar{y}x \quad (20)$$

$$\text{Percent V.R.} = \frac{|\bar{V}_{R, NL}| - |\bar{V}_{R, FL}|}{|\bar{V}_{R, FL}|} \times 100 \quad P = \frac{V_R V_S}{X_L} \sin(\delta) \quad (21)$$