Paper Reading Seminar

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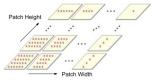
Combining Randomization and Discrimination for Fine-Grained Image Categorization

Motivation



- ► Fine-grained image categorization
- Bird species
- Human activity classification
- Intuition
 - ▶ Dense sampling ⇒ patches
 - Correlation among patches
 - ▶ Random forest + SVM

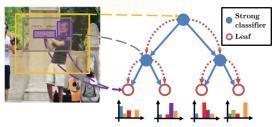
▶ Dense sampling





- Feature
 - ▶ Single patch: BoW
 - Patch pair: concatenation/intersection/absolute of difference of BoW histogram

Random forest + SVM

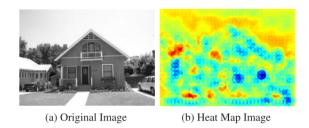


(b) Discriminative decision tree.

- ▶ Randomly select patches (or patch pairs) + SVM
- ▶ Train random forest with information gain
- ▶ Use "ancestor" features
- Q: invariance?

Application

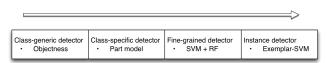
Heatmap



- ▶ Frequency a region picked up by the random forest
- Visualize from a classifier's perspective

Measuring the objectness of image windows

Motivation



- ► Hand-crafted model ⇒ different from conventional "detectors"
- Applications
 - Preprocessing for detection
 - Visualization of classifier
 - Foreground/background separation?

- ▶ Intuition: an object should have...
 - A well defined closed boundary in space
 - A different appearance from its surroundings
 - Sometimes unique within the image (salient)
- Bayesian fusion of the cues

- Multi-scale saliency
 - Spectral residual of FFT in multiple scales
 - Measure the uniqueness of the window within the image

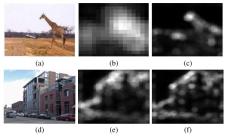
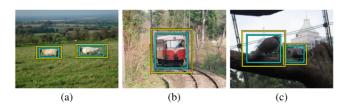
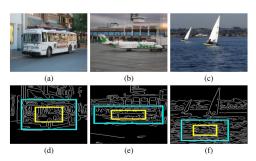


Fig. 2: MS success and failure. Success: the large giraffe in the original image (a) appears as a blob in the saliency map for a high scale (b), while the tiny airplane in the map for a low scale (c). Having multi-scale saliency maps is important for finding more objects in challenging datasets. Interestingly, at the low scale the head of the giraffe is salient, rather than the whole giraffe. Failure: the numerous cars in the original image (d) are not salient at any scale. We show the saliency maps for 2 scales in (e) and (f). The contour of the building appears more salient than the cars.

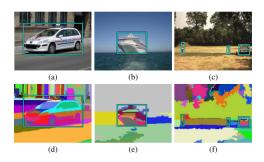
- Color contrast
 - Dissimilarity of a window to its immediate surrounding area
 - ► Chi-square distance between LAB histogram
 - Scores a whole window as whether it contains an entire project



- Edge Density
 - ► Canny detector in the inner ring. Normalized with perimeter
 - Captures the closed boundary characteristic of objects



- Superpixel Straddling
 - Superpixels shouldn't cross the bondary
 - ▶ Rely on over-segmentation



- Spatial priori
 - Location and size
 - Kernel density estimation from training data
- Bayesian fusion

$$p(\text{obj}|C) = \frac{p(C|\text{obj})p(\text{obj})}{p(C)}$$