

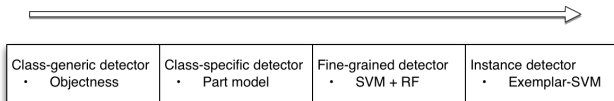
# Paper Reading Seminar

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September 11, 2012

# Combining Randomization and Discrimination for Fine-Grained Image Categorization

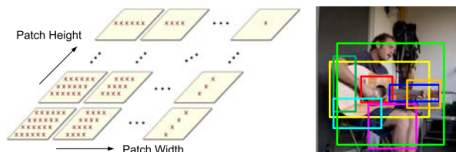
## ► Motivation



- Fine-grained image categorization
  - Bird species
  - Human activity classification
- ## ► Intuition
- Dense sampling  $\Rightarrow$  patches
  - Correlation among patches
  - Random forest + SVM

# Approach

- Dense sampling

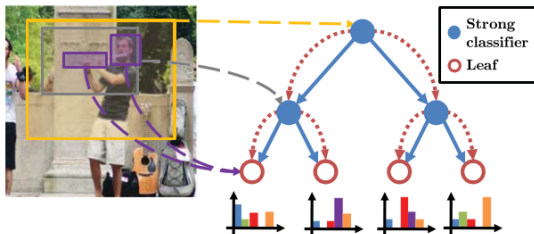


- Feature

- Single patch: BoW
- Patch pair: concatenation/intersection/absolute of difference of BoW histogram

# Approach

## ► Random forest + SVM

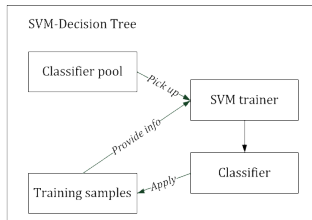
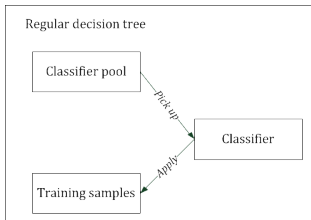


(b) Discriminative decision tree.

- Randomly select patches (or patch pairs) + SVM
- Train random forest with information gain
- Use “ancestor” features
- Q: invariance?

# Discussions

- ▶ How to train the SVM?
  - ▶ Images  $\Rightarrow$  patches  $\Leftrightarrow$  SVM
  - ▶ When: SVMs are trained right before evaluating the information gain



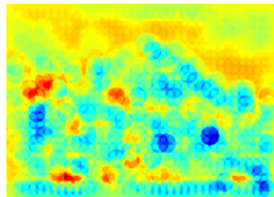
- ▶ Train with features extracted from patches, image with labels
- ▶ How to maintain visual invariance?
  - ▶ Decision trees are able to achieve the invariance (appeared in the training data)

# Application

- ▶ Heatmap



(a) Original Image

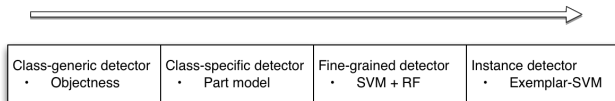


(b) Heat Map Image

- ▶ Frequency a region picked up by the random forest
- ▶ Visualize from a classifier's perspective

# Measuring the objectness of image windows

## ► Motivation



- Hand-crafted model  $\Rightarrow$  different from conventional “detectors”
- Applications
  - Preprocessing for detection
  - Visualization of classifier
  - Foreground/background separation?

# Approach

- ▶ Intuition: an object should have...
  - ▶ A well defined closed boundary in space
  - ▶ A different appearance from its surroundings
  - ▶ Sometimes unique within the image (salient)
- ▶ Bayesian fusion of the cues



# Approach

- ▶ Multi-scale saliency
  - ▶ Spectral residual of FFT in multiple scales
  - ▶ Measure the uniqueness of the window within the image

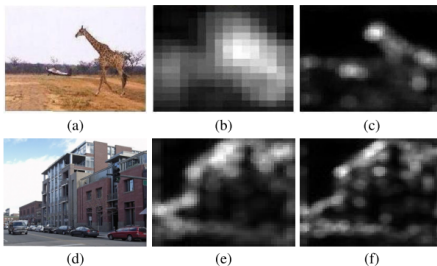


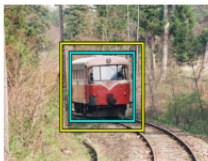
Fig. 2: **MS success and failure.** **Success:** the large giraffe in the original image (a) appears as a blob in the saliency map for a high scale (b), while the tiny airplane in the map for a low scale (c). Having multi-scale saliency maps is important for finding more objects in challenging datasets. Interestingly, at the low scale the head of the giraffe is salient, rather than the whole giraffe. **Failure:** the numerous cars in the original image (d) are not salient at any scale. We show the saliency maps for 2 scales in (e) and (f). The contour of the building appears more salient than the cars.

# Approach

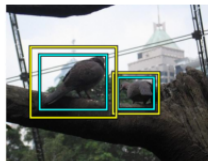
- ▶ Color contrast
  - ▶ Dissimilarity of a window to its immediate surrounding area
  - ▶ Chi-square distance between LAB histogram
  - ▶ Scores a whole window as whether it contains an entire project



(a)



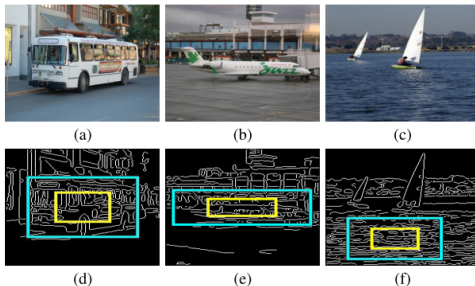
(b)



(c)

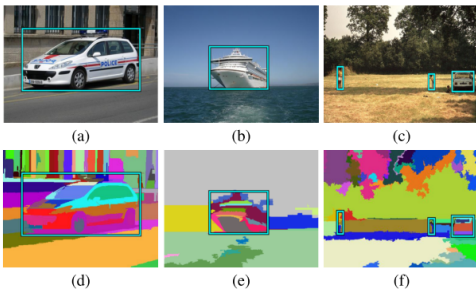
# Approach

- ▶ Edge Density
  - ▶ Canny detector in the inner ring. Normalized with perimeter
  - ▶ Captures the closed boundary characteristic of objects



# Approach

- ▶ Superpixel Straddling
  - ▶ Superpixels shouldn't cross the boundary
  - ▶ Rely on over-segmentation



# Approach

- ▶ Spatial priori
  - ▶ Location and size
  - ▶ Kernel density estimation from training data
- ▶ Bayesian fusion

$$p(\text{obj}|C) = \frac{p(C|\text{obj})p(\text{obj})}{p(C)}$$