

view frames Result
Recorded at time: 1676017731.444028

odom

Broadcaster: /imu_odom_manager
Average rate: 100.19
Buffer length: 5.001
Most recent transform: 1676017731.407
Oldest transform: 1676017726.406

base_link

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

base_footprint

bullet

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

bullet_antenna

mount_base

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

cam1_base

cam2_base

rs_lidar

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

lidar

rslidar

gps

imu_link

inertial_link

payload_frame

rear_bumper_link

rear_right_corner

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

tower_rear_right_corner

tower

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

tower_camera_floor

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

camera_0

camera_1

camera_2

camera_3

imu

jetson

tower_cap

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

tower_cap_top

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

ouster_mount

Broadcaster: /ouster_to_t265_tf_node
Average rate: 10.196
Buffer length: 4.904
Most recent transform: 1676017731.474
Oldest transform: 1676017726.57

camera_pose_frame

ouster_mount_top

Broadcaster: /camera/realSense2_camera_manager
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

camera_link

Broadcaster: /camera/realSense2_camera_manager
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

camera_gyro_frame

camera_accel_frame

Broadcaster: /camera/realSense2_camera_manager
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

camera_gyro_optical_frame

camera_accel_optical_frame

top_chassis_link

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

top_plate_link

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

top_plate_front_link

top_plate_rear_link

user_rail_link

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

front_left_wheel_link

front_right_wheel_link

rear_left_wheel_link

rear_right_wheel_link