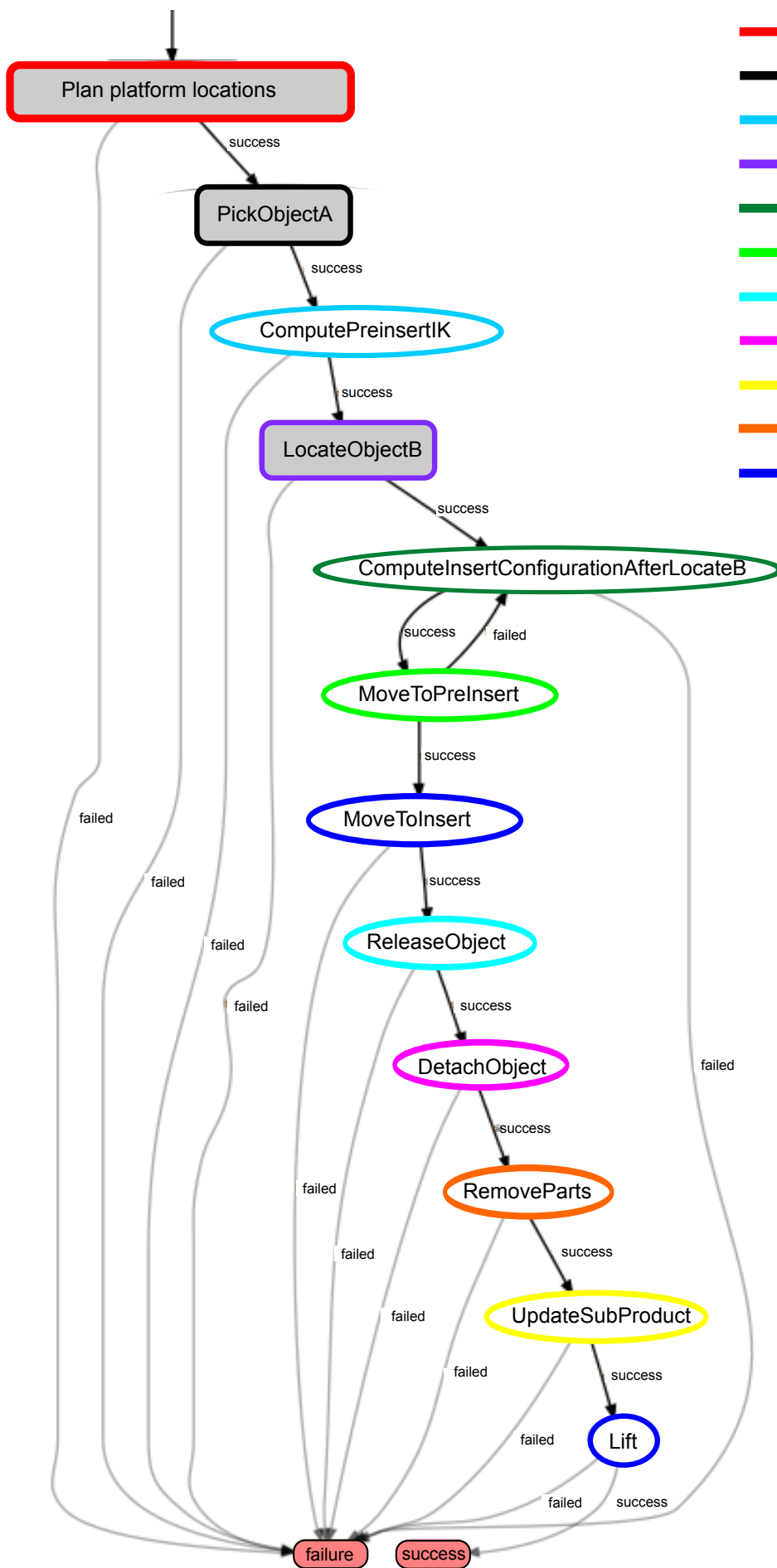


Low level Skills



Plan platform locations



Grasp object



Plan IK



Move and locate



Plan insert pose



Move joint goal



Control gripper



Detach object



Merge assembly parts



Remove part



Move cartesian goal