SNUPC Jammanbo's Note

Gratus907 (Wonseok Shin)

SNUPC Jammanbo's Note

Contents

1 Settings

1.1 C++

O3, Ofast, avx, avx2, fma 때려넣고 기도메타도 필요하면 사용하기.

```
#include <bits/stdc++.h>
#pragma GCC optimize("O3")
#pragma GCC optimize("Ofast")
#pragma GCC target("avx,avx2,fma")
#pragma GCC target("sse,sse2,sse3,ssse3,sse4")
#pragma GCC target("popcnt,abm,mmx,avx,tune=native")
#pragma GCC optimize("unroll-loops")
#define ll long long
#define eps 1e-7
#define all(x) ((x).begin()),((x).end())
#define usecppio ios::sync_with_stdio(0);cin.tie(0);cout.tie(0);
using namespace std;
using pii = pair<int, int>;
```

2 Data Structures

2.1 Segment Tree - Range Minimum

필요한 연산에 따라 적당히 수정해서 쓸 수 있는 SegTree 구현. 현재 range minimum을 기준으로 작성됨.
주의 : 배열이 0-base 인덱스인 것을 가정하고 작성되어 있음.

```
struct Range_Minimum_Tree
{
    int n;
    vector<int> segtree;

    Range_Minimum_Tree(const vector<int> &data)
    {
        n = data.size();
        segtree.resize(4 * n);
        initialize(data, 0, n - 1, 1);
    }

    int initialize(const vector<int> &data, int l, int r, int node)
    {
        if (l == r)
            return segtree[node] = data[l];
        int mid = (l + r) / 2;
        int lmin = initialize(data, l, mid, node * 2);
        int rmin = initialize(data, mid + 1, r, node * 2 + 1);
        return segtree[node] = min(lmin, rmin);
    }

    int minq(int l, int r, int node, int nodeleft, int noderight)
    {
        if (r < nodeleft || noderight < l)
            return INT_MAX;
        if (l <= nodeleft && noderight <= r)
            return segtree[node];
        int mid = (nodeleft + noderight) / 2;
        return min(minq(l,r,node*2,nodeleft,mid),
        minq(l,r,node*2+1,mid+1,noderight));
    }
};
```

2.2 Segment Tree Lazy Propagation

구간 업데이트 연산을 빠르게 하기 위한 Lazy Propagation이 적용된 SegTree.
주의 : 배열이 0-base 인덱스인 것을 가정하고 작성되어 있음.

```
struct SegTree
{
    int n;
    vector <int> segtree;
    vector <int> lazy;

    SegTree()
    {
        n = 0;
    }

    SegTree(vector <int> &data)
    {
        n = data.size();
        segtree.resize(4*n);
        lazy.resize(4*n);
        init(data,1,0,n-1);
    }

    int init(vector <int> &data, int node, int l, int r)
    {
        if (l==r)
        {
```

```
        segtree[node] = data[l];
        return segtree[node];
    }
    int mid = (l+r)/2;
    int ls = init(data,node*2,l,mid);
    int rs = init(data,node*2+1,mid+1,r);
    segtree[node] = (ls+rs);
    return segtree[node];
}

void propagation(int node, int nl, int nr)
{
    if (lazy[node]!=0)
    {
        segtree[node] += (lazy[node] * (nr-nl+1));
        if (nl != nr)
        {
            lazy[node*2] += lazy[node];
            lazy[node*2+1] += lazy[node];
        }
        lazy[node] = 0;
    }
}

void range_upd(int s, int e, int k)
{
    return range_upd(s,e,k,1,0,n-1);
}

void range_upd(int s, int e, int k, int node, int nl, int nr)
{
    propagation(node,nl,nr);

    if (nr < s || nl > e)
        return;
    if (s <= nl && nr <= e)
    {
        lazy[node] += k;
        propagation(node,nl,nr);
        return;
    }
```

```
        int mid = (nl + nr)/2;
        range_upd(s,e,k,node*2,nl,mid);
        range_upd(s,e,k,node*2+1,mid+1,nr);
        segtree[node] = segtree[node*2] + segtree[node*2+1];
        return;
    }

    int sum(int s, int e)
    {
        return sum(s,e,1,0,n-1);
    }

    int sum(int s, int e, int node, int nl, int nr)
    {
        propagation(node,nl,nr);
        if (nr < s || nl > e)
            return 0;
        if (s <= nl && nr <= e)
        {
            return segtree[node];
        }
        int mid = (nl+nr)/2;
        return (sum(s,e,node*2,nl,mid) + sum(s,e,node*2+1,mid+1,nr));
    }

};
```

2.3 Fenwick Tree

```
const int TSIZE = 100000;
int tree[TSIZE + 1];

// Returns the sum from index 1 to p, inclusive
int query(int p)
{
    int ret = 0;
    for (; p > 0; p -= p & -p)
        ret += tree[p];
    return ret;
}

// Adds val to element with index p
void add(int p, int val)
```

```
{
    for (; p <= TSIZE; p += p & -p) tree[p] += val;
}
```

2.4   Disjoint Set Union (Union - Find)

```
// Original Author : Ashishgup
struct Disjoint_Set_Union
{
    int connected;
    int parent[V], size[V];

    void init(int n)
    {
        for(int i=1;i<=n;i++)
        {
            parent[i]=i;
            size[i]=1;
        }
        connected=n;
    }
    int Find(int k)
    {
        while(k!=parent[k])
        {
            parent[k]=parent[parent[k]];
            k=parent[k];
        }
        return k;
    }
    int getSize(int k)
    {
        return size[Find(k)];
    }
    void unite(int x, int y)
    {
        int u=Find(x), v=Find(y);
        if(u==v)
            return;
        if(size[u]>size[v])
            swap(par1, par2);
        size[v]+=size[u];
```

```
        size[u] = 0;
        parent[u] = parent[v];
    }
} dsu;
```

2.5   Persistent Segment Tree

3   Mathematics

3.1   Useful Mathematical Formula

- Catalan Number : Number of valid parantheses strings with n pairs

$$C_n = \frac{1}{n+1}\binom{2n}{n}$$

- Nim Game : Remember - XOR of all piles.

- Lucas Formula : $\binom{n}{m} = \prod \binom{n_i}{m_i} \mod p$

3.2   Number of Integer Partition

```python
def partitions(n):
    parts = [1]+[0]*n
    for t in range(1, n+1):
        for i, x in enumerate(range(t, n+1)):
            parts[x] += parts[i]
    return parts[n]
```

3.3   Binomial Coefficient

Fast-to-Type Binomial coefficient, in $O(k)$ time.

```c
int Binom(int n, int k)
{
    if (n < k)
        return 0;
    if (k == n || k == 0)
        return 1;
    int res = 1;
    if ( k > n - k )
        k = n - k;
    for (int i = 0; i < k; ++i)
    {
        res *= (n - i);
        res /= (i + 1);
    }
    return res;
}
```

3.4   Extended Euclidean Algorithm

```c
int Extended_Euclid(int a, int b, int *x, int *y)
```

```c
{
    if (a == 0)
    {
        *x = 0;
        *y = 1;
        return b;
    }
    int x1, y1;
    int EEd = Extended_Euclid(b%a, a, &x1, &y1);
    *x = y1 - (b/a) * x1;
    *y = x1;
    return EEd;
}
```

3.5   Fast Modulo Exponentiation

Calculating $x^y \mod p$ in $\mathcal{O}(\log y)$ time.

```c
/*
Fast Modulo Exponentiation algorithm
Runs on O(log y) time,
calculate x^y mod p
*/

ll modpow(ll x, ll y, ll p)
{
    ll res = 1;
    x = x % p;
    while (y > 0)
    {
        if (y & 1)
            res = (res*x) % p;
        y = y>>1;
        x = (x*x) % p;
    }
    return res;
}
```

3.6   Miller-Rabin Primality Testing

Base values of a chosen so that results are tested to be correct up to 10^{14}.

```c
bool MRwitness(ll n, ll s, ll d, ll a)
{
    ll x = modpow(a, d, n);
```

```
    ll y = -1;

    while (s)
    {
        y = (x * x) % n;
        if (y == 1 && x != 1 && x != n-1)
            return false;
        x = y;
        s--;
    }
    return (y==1);
}


bool Miller_Rabin(ll n)
{
    if (n<2)
        return false;
    if (n == 2 || n == 3 || n == 5 || n == 7 ||
     n == 11 || n == 13 || n == 17)
        return true;
    if (n%2 == 0 || n%3 == 0 || n%5 == 0)
        return false;
    ll d = (n-1) / 2;
    ll s = 1;
    while (d%2==0)
    {
        d /= 2;
        s++;
    }
    int candidate[7] = {2,3,5,7,11,13,17};
    bool result = true;
    for (auto i : candidate)
    {
        result = result & MRwitness(n,s,d,i);
        if (!result)
            break;
    }
    return result;
}
```

3.7   Pollard-Rho Factorization

```
ll PollardRho(ll n)
```

```
{
    srand (time(NULL));
    if (n==1)
        return n;
    if (n % 2 == 0)
        return 2;
    ll x = (rand()%(n-2))+2;
    ll y = x;
    ll c = (rand()%(n-1))+1;
    ll d = 1;
    while (d==1)
    {
        x = (modpow(x, 2, n) + c + n)%n;
        y = (modpow(y, 2, n) + c + n)%n;
        y = (modpow(y, 2, n) + c + n)%n;
        d = gcd(abs(x-y), n);
        if (d==n)
            return PollardRho(n);
    }
    return d;
}
```

3.8   Euler Totient

Calculating number of integers below n which is coprime with n.

```
#define ll long long
ll euler_phi(ll n)
{
    ll p=2;
    ll ephi = n;
    while(p*p<=n)
    {
        if (n%p == 0)
            ephi = ephi/p * (p-1);
        while(n%p==0)
            n/=p;
        p++;
    }
    if (n!=1)
    {
        ephi /= n;
        ephi *= (n-1);
    }
```

```
    return ephi;
}
```

3.9   Modular Multiplicative Inverse

```
ll modinv(ll x, ll p)
{
    return modpow(x,p-2,p);
}
```

3.10   Fast Fourier Transform

Convolution C_i 를 $O(n \log n)$ 에 구한다.

$$C_i = \sum_{j=0}^{i} a_j b_{i-j}$$

```
//Code from blog.myungwoo.kr
#include <complex>
#define sz(v) ((int)(v).size())
#define all(v) (v).begin(),(v).end()
typedef complex<double> base;
typedef vector <int> vi;
void fft(vector <base> &a, bool invert)
{
    int n = sz(a);
    for (int i=1,j=0;i<n;i++)
    {
        int bit = n >> 1;
        for (;j>=bit;bit>>=1)
            j -= bit;
        j += bit;
        if (i < j)
            swap(a[i],a[j]);
    }
    for (int len=2;len<=n;len<<=1)
    {
        double ang = 2*M_PI/len*(invert?-1:1);
        base wlen(cos(ang),sin(ang));
        for (int i=0;i<n;i+=len)
        {
            base w(1);
            for (int j=0;j<len/2;j++)
            {
```

```
                base u = a[i+j], v = a[i+j+len/2]*w;
                a[i+j] = u+v;
                a[i+j+len/2] = u-v;
                w *= wlen;
            }
        }
    }
    if (invert)
        for (int i=0;i<n;i++)
            a[i] /= n;

}

void multiply(const vi &a,const vi &b, vi &res)
{
    vector <base> fa(all(a)), fb(all(b));
    int n = 1;
    while (n < max(sz(a),sz(b)))
        n <<= 1;
    fa.resize(n); fb.resize(n);
    fft(fa,false); fft(fb,false);
    for (int i=0;i<n;i++)
        fa[i] *= fb[i];
    fft(fa,true);
    res.resize(n);
    for (int i=0;i<n;i++)
        res[i] = int(fa[i].real()+
        (fa[i].real()>0?0.5:-0.5));
}
```

3.11   Number Theoretic Transform

Modulo version FFT.

```
const int mod = 7340033;
const int root = 5;
const int root_1 = 4404020;
const int root_pw = 1 << 20;

void fft(vector<int> & a, bool invert) {
    int n = a.size();

    for (int i = 1, j = 0; i < n; i++) {
        int bit = n >> 1;
```

```
    for (; j & bit; bit >>= 1)
        j ^= bit;
    j ^= bit;

    if (i < j)
        swap(a[i], a[j]);
}

for (int len = 2; len <= n; len <<= 1) {
    int wlen = invert ? root_1 : root;
    for (int i = len; i < root_pw; i <<= 1)
        wlen = (int)(1LL * wlen * wlen % mod);

    for (int i = 0; i < n; i += len) {
        int w = 1;
        for (int j = 0; j < len / 2; j++) {
            int u = a[i+j], v = (int)(1LL * a[i+j+len/2] * w % mod);
            a[i+j] = u + v < mod ? u + v : u + v - mod;
            a[i+j+len/2] = u - v >= 0 ? u - v : u - v + mod;
            w = (int)(1LL * w * wlen % mod);
        }
    }
}

if (invert) {
    int n_1 = inverse(n, mod);
    for (int & x : a)
        x = (int)(1LL * x * n_1 % mod);
}
}
```

4   Geometry

4.1   CCW

```
//Is 3 points Counterclockwise? 1 : -1
//0 : on same line
int CCW(Point a, Point b, Point c)
{
    int op = a.x*b.y + b.x*c.y + c.x*a.y;
    op -= (a.y*b.x + b.y*c.x + c.y*a.x);
    if (op > 0)
        return 1;
    else if (op == 0)
        return 0;
    else
        return -1;
}
```

4.2   Point in polygon

Returns boolean, if point is in the polygon (represented as vector of points).

```
// point in polygon test
inline double is_left(Point p0, Point p1, Point p2)
{
    return (p1.x - p0.x) * (p2.y - p0.y) - (p2.x - p0.x) * (p1.y - p0.y);
}
bool is_in_polygon(Point p, vector<Point>& poly)
{
    int wn = 0;
    for (int i = 0; i < poly.size(); ++i)
    {
        int ni = (i + 1 == poly.size()) ? 0 : i + 1;
        if (poly[i].y <= p.y)
        {
            if (poly[ni].y > p.y)
                if (is_left(poly[i], poly[ni], p) > 0)
                    ++wn;
        }
        else
        {
            if (poly[ni].y <= p.y)
                if (is_left(poly[i], poly[ni], p) < 0)
                    --wn;
        }
```

```
    }
    return wn != 0;
}
```

4.3   Length of Segment Union

Length of segment union, from vector of {start, end}.

```
//Src : e-maxx
int length_union(const vector<pair<int, int>> &a)
{
    int n = a.size();
    vector<pair<int, bool>> x(n*2);
    for (int i = 0; i < n; i++)
    {
        x[i*2] = {a[i].first, false};
        x[i*2+1] = {a[i].second, true};
    }

    sort(x.begin(), x.end());

    int result = 0;
    int c = 0;
    for (int i = 0; i < n * 2; i++)
    {
        if (i > 0 && x[i].first > x[i-1].first && c > 0)
            result += x[i].first - x[i-1].first;
        if (x[i].second)
            c--;
        else
            c++;
    }
    return result;
}
```

4.4   Closest Pair Problem

Requires : Points must be sorted with x-axis.
Runs in $\mathcal{O}(n \log^2 n)$

```
int dist (Point &p, Point &q)
{   return (p.x-q.x)*(p.x-q.x) + (p.y-q.y)*(p.y-q.y);
}
```

```
bool compare(Point &p, Point &q)
{
    return (p.x < q.x);
}


bool ycompare(Point &p, Point &q)
{
    return (p.y<q.y);
}
Point pts[101010];

int closest_pair(Point p[], int n)
{
    //printf("%p call %d\n",p,n);
    if (n==2)
    {
        return dist(p[0], p[1]);
    }
    if (n==3)
    {
        return min(dist(p[0],p[1]),
        min(dist(p[1],p[2]),dist(p[0],p[2])));
    }
    Point mid[n];
    int line = (p[n/2 - 1].x + p[n/2].x) / 2;
    int d = min(closest_pair(p, n/2), closest_pair(p + n/2, n - n/2));
    int pp = 0;
    for (int i = 0; i < n; i++)
    {
        int t = line - p[i].x;
        if (t*t < d)
        {
            mid[pp] = p[i];
            pp++;
        }
    }
    sort(mid,mid+pp,ycompare);
    for (int i = 0; i < pp - 1; i++)
        for (int j = i + 1; j < pp && mid[j].y - mid[i].y < d; j++)
            d = min(d, dist(mid[i], mid[j]));
    return d;
}
```

4.5   Convex Hull (Graham Scan)

```
// From GeeksforGeeks.
Point nextToTop(stack<Point> &S)
{
    Point p = S.top();
    S.pop();
    Point res = S.top();
    S.push(p);
    return res;
}


int swap(Point &p1, Point &p2)
{
    Point temp = p1;
    p1 = p2;
    p2 = temp;
}


int distSq(Point p1, Point p2)
{
    return (p1.x - p2.x)*(p1.x - p2.x) +
            (p1.y - p2.y)*(p1.y - p2.y);
}


int orientation(Point p, Point q, Point r) // Basically CCW
{
    int val = (q.y - p.y) * (r.x - q.x) -
                (q.x - p.x) * (r.y - q.y);

    if (val == 0) return 0;  // colinear
    return (val > 0)? 1: 2; // clock or counterclock wise
}


int compare(const void *vp1, const void *vp2)
{
    Point *p1 = (Point *)vp1;
    Point *p2 = (Point *)vp2;

    // Find orientation
    int o = orientation(p0, *p1, *p2);
    if (o == 0)
```

```
        return (distSq(p0, *p2) >= distSq(p0, *p1))? -1 : 1;

    return (o == 2)? -1: 1;
}


// Prints convex hull of a set of n points.
void convexHull(Point points[], int n)
{
    // Find the bottommost point
    int ymin = points[0].y, min = 0;
    for (int i = 1; i < n; i++)
    {
      int y = points[i].y;
      if ((y < ymin) || (ymin == y &&
          points[i].x < points[min].x))
          ymin = points[i].y, min = i;
    }

    // Place the bottom-most point at first position
    swap(points[0], points[min]);

    // Sort n-1 points with respect to the first point.
    p0 = points[0];
    qsort(&points[1], n-1, sizeof(Point), compare);

    // If two or more points make same angle with p0,
    // Remove all but the one that is farthest from p0
    int m = 1;
    for (int i=1; i<n; i++)
    {
        while (i < n-1 && orientation(p0, points[i],
                                         points[i+1]) == 0)
            i++;
        points[m] = points[i];
        m++;
    }

    // If modified array of points has less than 3 points,
    // convex hull is not possible
    if (m < 3) return;

    // Create an empty stack and push first three points
```

```
    // to it.
    stack <Point> S;
    S.push(points[0]);
    S.push(points[1]);
    S.push(points[2]);

    // Process remaining n-3 points
    for (int i = 3; i < m; i++)
    {
        while (orientation(nextToTop(S), S.top(), points[i]) != 2)
            S.pop();
        S.push(points[i]);
    }

    // Now stack has the output points, print contents of stack
    while (!S.empty())
    {
        Point p = S.top();
        cout << "(" << p.x << ", " << p.y <<")" << endl;
        S.pop();
    }
}
```

4.6 Intersection of Line Segment

```
//jason9319.tistory.com/358. modified
int isIntersect(Point a, Point b, Point c, Point d)
{
    int ab = ccw(a, b, c)*ccw(a, b, d);
    int cd = ccw(c, d, a)*ccw(c, d, b);
    if (ab == 0 && cd == 0)
    {
        if (a > b)swap(a, b);
        if (c > d)swap(c, d);
        return (c <= b&&a <= d);
    }
    return (ab <= 0 && cd <= 0);
}
```

5 Graphs

5.1 Topological Sorting

Topological sorting with dfs

```
vector <int> graph[V];
bool visited[V];
vector <int> sorted;

void dfs(int root)
{
    visited[root] = 1;
    for (auto it:graph[root])
    {
        if (!visited[it])
            dfs(it);
    }
    sorted.push_back(root);
}


int main()
{
    int n, m;
    scanf("%d%d",&n,&m);
    for (int i = 0; i<m; i++)
    {
        int small,big;
        scanf("%d%d",&small,&big);
        graph[small].push_back(big);
    }
    for (int i = 1; i<=n; i++)
        if (!visited[i])
            dfs(i);
    reverse(sorted.begin(),sorted.end()); // must reverse!
}
```

5.2 Lowest Common Ancestor

LCA Algorithm by sparse table. minlen : (x, y) 사이를 잇는 간선 중 최소 길이 간선.
maxlen : (x, y) 사이를 잇는 간선 중 최대 길이 간선.

```
int n, k;
bool visited[101010];
int par[101010][21], maxedge[101010][21], minedge[101010][21];
int d[101010];
```

```
vector <pii> graph[101010]; // {destination, weight}
void dfs(int here,int depth) // run dfs(root,0)
{
    visited[here] = true;
    d[here] = depth;
    for (auto there : graph[here])
    {
        if (visited[there.first])
            continue;
        dfs(there.first, depth + 1);
        par[there.first][0] = here;
        maxedge[there.first][0] = there.second;
        minedge[there.first][0] = there.second;
    }
}


void precomputation()
{
    for (int i = 1; i<21; i++)
    {
        for (int j = 1; j<=n; j++)
        {
            par[j][i] = par[par[j][i-1]][i-1];
            maxedge[j][i] = max(maxedge[j][i - 1],
                maxedge[par[j][i - 1]][i - 1]);
            minedge[j][i] = min(minedge[j][i - 1],
                minedge[par[j][i - 1]][i - 1]);
        }
    }
}


pii lca(int x, int y)
{
    int maxlen = INT_MIN;
    int minlen = INT_MAX;
    if (d[x]>d[y])
        swap(x,y);
    for (int i = 20; i>=0; i--)
    {
        if (d[y]-d[x] >= (1<<i))
        {
```

```
            minlen = min(minlen,minedge[y][i]);
            maxlen = max(maxlen,maxedge[y][i]);
            y = par[y][i];
        }
    }
    if (x==y)
        return {minlen, maxlen};
    for (int i = 20; i>=0; i--)
    {
        if (par[x][i] != par[y][i])
        {
            minlen = min(minlen,min(minedge[x][i],minedge[y][i]));
            maxlen = max(maxlen,max(maxedge[x][i],maxedge[y][i]));
            x = par[x][i];
            y = par[y][i];
        }
    }
    minlen = min(minlen,min(minedge[x][0],minedge[y][0]));
    maxlen = max(maxlen,max(maxedge[x][0],maxedge[y][0]));

    int lca_point = par[x][0];
    return {minlen,maxlen};
}


void tobedone()
{
    dfs(1,0);
    precomputation();
}
```

5.3   MST Kruskal Algorithm
Based on Union-Find implementation
$\mathcal{O}(E \log E)$ if path-compressed Union Find.

```
int Kruskal()
{
    int mstlen = 0;
    sort(edgelist.begin(),edgelist.end());
    for (auto it:edgelist)
    {
        if (Find(it.s)==Find(it.e)) // Cycle Detection
            continue;
        else
```

```
        {
              Union(it.s,it.e);
              mstlen += it.w;
        }
    }
    return mstlen;
}
```

5.4   MST Prim Algorithm

```
vector <pii> Tree[101010];
// Note that we use {weight, destination} pair here.
// This is to use priority_queue!
bool visit[101010];
priority_queue <pii, vector<pii>, greater<pii>> pq;
void add(int i)
{
    visit[i] = true;
    for (auto it:Tree[i])
        pq.push(it);
}

int Prim(int start)
{
    int mstlen = 0;
    add(start);
    while(!pq.empty())
    {
        int cur = pq.top().second;
        int weight = pq.top().first;
        pq.pop();
        if (visit[cur])
            continue;
        else
        {
            mstlen+=weight;
            add(cur);
        }
    }
    return mstlen;
}
```

5.5   Dinic's Algorithm

```
//Original Author : https://plzrun.tistory.com/

int r[V][V]; // flow capacity
bool chk[V][V]; // edge existence
int level[V];
vector<int> v[V];
queue<int> q;

bool bfs(int src, int sink)
{
    memset(level,-1,sizeof(level));
    level[src]=0;
    q.push(src);
    while(!q.empty())
    {
        int x = q.front();
        q.pop();
        for(int y: v[x])
        {
            if(r[x][y]>0 && level[y]<0) {
                level[y]=level[x]+1;
                q.push(y);
            }
        }
    }
    return level[sink]>=0;
}

int work[V];

int dfs(int x, int sink, int f)
{
    if(x==sink) return f;
    for(int &i=work[x]; i<v[x].size(); i++)
    {
        int y=v[x][i];
        if(level[y]>level[x] && r[x][y]>0)
        {
            int t = dfs(y,sink,min(f,r[x][y]));
            if(t>0)
            {
```

```
            r[x][y]-=t;
            r[y][x]+=t;
            return t;
        }
    }
}
return 0;
}


int dinic(int src, int sink)
{
    int flow=0;
    while(bfs(src,sink))
    {
        int f=0;
        memset(work,0,sizeof(work));
        while((f=dfs(src,sink,INT_MAX))>0)
            flow+=f;
    }
    return flow;
}
```

6 Shortest Path

6.1 Dijkstra

$\mathcal{O}(E \log V)$ Single-Start-Shortest-Path.
Not working for graph with minus weight.

```
const int INF = 987654321;
const int MX = 105050;
struct Edge
{
    int dest, w;
    bool operator<(const Edge &p) const
    {
        return w > p.w;
    }
};

bool relax(Edge edge, int u, int dist[])
{
    bool flag = 0;
    int v = edge.dest, w = edge.w;
    if (dist[v] > dist[u] + w && (dist[u]!=INF))
    {
        flag = true;
        dist[v] = dist[u]+w;
    }
    return flag;
}


int dijkstra(int dist[], int start, vector<Edge> graph[])
{
    fill(dist,dist+MX,INF);
    dist[start] = 0;
    priority_queue<Edge> pq;
    pq.push({start,0});
    while(!pq.empty())
    {
        Edge x = pq.top();
        int v = x.dest, w = x.w;
        pq.pop();
        if (w>dist[v])
            continue;
        for (auto ed : graph[v])
```

```
            if (relax(ed, v, dist))
                pq.push({ed.dest,dist[ed.dest]});
    }
}
```

6.2   Bellman Ford

$\mathcal{O}(EV)$ Single-Start-Shortest-Path.

Not working for graph with minus cycle $\rightarrow$ must detect.

```
struct Edge
{
    int u, v, w;
};


vector <Edge> edgelist;
int V, E;
int dist[V+1];


bool relax_all_edge()
{
    bool flag = false;
    for (auto it:edgelist)
    {
        int u = it.u, v = it.v, w = it.w;
        if (dist[v] > dist[u] + w && (dist[u]!=INF))
        {
            flag = true;
            dist[v] = dist[u]+w;
        }
    }
    return flag;
}


int bellman_ford()
{
    fill(dist,dist+V+2,INF);
    dist[1] = 0;
    for (int i = 0; i<V-1; i++)
    {
        relax_all_edge();
    }
    if (relax_all_edge())
```

```
        return -1;
    else
        return 0;
}
```

6.3   SPFA Algorithm

Average $\mathcal{O}(E)$, worst $\mathcal{O}(VE)$ time. Average-case improvement of Bellman Ford by using an additional queue.

```
//https://www.crocus.co.kr/1089
struct Edge
{
    int dest, w;
    bool operator<(const Edge &p) const
    {
        return w > p.w;
    }
};


bool inQ[100500];
int cycle[100500];
int spfa(int dist[], int start, vector<Edge> graph[])
{
    fill(dist, dist + MX, INF);

    queue<int> q;
    dist[start] = 0;
    inQ[start] = true;

    q.push(start);
    cycle[start]++;

    while (!q.empty())
    {
        int here = q.front();
        q.pop();

        inQ[here] = false;

        for (int i = 0; i < graph[here].size(); i++)
        {
            int next = graph[here][i].dest;
            int cost = graph[here][i].w;
```

```
            if(dist[next] > dist[here] + cost)
            {
                dist[next] = dist[here] + cost;

                if (!inQ[next])
                {
                    cycle[next]++;
                    if (cycle[next] >= graph->size())
                    {
                        printf("-1\n");
                        return 0;
                    }
                    q.push(next);
                    inQ[next] = true;
                }
            }
        }
    }
}
```

6.4 Floyd-Warshall

Works on adjacency matrix, in $\mathcal{O}(V^3)$.

```
int d[120][120];
int n;
void Floyd_Warshall()
{
    for (int i = 1; i<=n; i++)
        for (int j = 1; j<=n; j++)
            for (int k = 1; k<=n; k++)
                d[j][k] = MIN(d[j][k],d[j][i]+d[i][k]);
}
```

7 Dynamic

7.1 Longest Increasing Subsequence

Find LIS in $\mathcal{O}(n \log n)$ time.

```
vector <int> sequence;
vector <int> L;
int lis_len;
int position[BIG];
int lis[BIG];
int lis_pushed[BIG];
int n;
void FindLIS(vector <int> &seq)
{
    L.push_back(seq[0]);
    position[0] = 0;
    for (int i = 1; i<n; i++)
    {
        int u = L.size();
        if (seq[i] > L[u-1])
        {
            position[i] = u;
            L.push_back(seq[i]);
        }
        else
        {
            int pos = lower_bound(L.begin(),L.end(),seq[i])-L.begin();
            L[pos] = seq[i];
            position[i] = pos;
        }
    }
    lis_len=L.size();
    int lookingfor = lis_len-1;
    for (int i = n-1; i>=0; i--)
    {
        if (lis_pushed[position[i]]==0 && lookingfor == position[i])
        {
            lis[position[i]] = seq[i];
            lis_pushed[position[i]]=1;
            lookingfor--;
        }
    }
}
```

Multiset 기반으로 더 짧게 구현

```cpp
vector <int> sequence;
int n, lislen;
multiset<int> increase;

void find_lis()
{
for (int i = 0; i<n; i++)
{
auto it = lower_bound(all(increase),sequence[i]);
if (it == increase.begin())
increase.insert(sequence[i]);
else
{
--it;
increase.erase(it);
increase.insert(sequence[i]);
}
}
lislen = increase.size();
}
```

7.2   Largest Sum Subarray

Computes sum of largest sum subarray in $\mathcal{O}(N)$

```cpp
void consecsum(int n)
{
    dp[0] = number[0];
    for (int i = 1; i<n; i++)
        dp[i] = MAX(dp[i-1]+number[i],number[i]);
}

int maxsum(int n)
{
    consecsum(n);
    int max_sum=-INF;
    for (int i = 0; i<n; i++)
        dp[i] > max_sum ? max_sum = dp[i] : 0;
    return max_sum;
}
```

7.3   0-1 Knapsack

```cpp
int dp[N][W];
int weight[N];
int value[N];
void knapsack()
{
    for (int i = 1; i<=n; i++)
    {
        for (int j = 0; j<=W; j++)
            dp[i][j] = dp[i-1][j];
        for (int j = weight[i]; j<=W; j++)
            dp[i][j] = max(dp[i][j], dp[i-1][j-weight[i]]+value[i]);
    }
}
```

7.4   Longest Common Subsequence

```cpp
//input : two const char*
//output : their LCS, in c++ std::string type
string lcsf(const char *X,const char *Y)
{
    int m = (int)strlen(X);
    int n = (int)strlen(Y);
    int L[m+1][n+1];
    for (int i=0; i<=m; i++)
    {
        for (int j=0; j<=n; j++)
        {
            if (i == 0 || j == 0)
                L[i][j] = 0;
            else if (X[i-1] == Y[j-1])
                L[i][j] = L[i-1][j-1] + 1;
            else
                L[i][j] = max(L[i-1][j], L[i][j-1]);
        }
    }
    int index = L[m][n];

    char lcsstring[index+1];
    lcsstring[index] = 0;

    int i = m, j = n;
    while (i > 0 && j > 0)
```

```
    {
        if (X[i-1] == Y[j-1])
        {
            lcsstring[index-1] = X[i-1];
            i--; j--; index--;
        }
        else if (L[i-1][j] > L[i][j-1])
            i--;
        else
            j--;
    }
    string lcsstr = lcsstring;
    return lcsstr;
}
```

7.5   Edit Distance

```
int edit_dist[1010][1010];
int Editdist(string &s, string &t)
{
    int slen = s.length();
    int tlen = t.length();
    for (int i = 1; i<=slen; i++)
        edit_dist[i][0] = i;
    for (int i = 1; i<=tlen; i++)
        edit_dist[0][i] = i;
    for (int i = 1; i<=tlen; i++)
    {
        for (int j = 1; j<=slen; j++)
        {
            if (s[j-1]==t[i-1])
                edit_dist[j][i] = edit_dist[j-1][i-1];
            else
                edit_dist[j][i] = min(edit_dist[j-1][i]+1,
                    min(edit_dist[j-1][i-1]+1,edit_dist[j][i-1]+1));
        }
    }
    return edit_dist[slen][tlen];
}
```

8   String

8.1   KMP Algorithm

```
// Original Author : bowbowbow (bowbowbow.tistory.com)
vector<int> getPi(string p)
{
    int j = 0;
    int plen = p.length();
    vector<int> pi;
    pi.resize(plen);
    for(int i = 1; i< plen; i++)
    {
        while((j > 0) && (p[i] !=  p[j]))
            j = pi[j-1];
        if(p[i] == p[j])
        {
            j++;
            pi[i] = j;
        }
    }
    return pi;
}
vector <int> kmp(string s, string p)
{
    vector<int> ans;
    auto pi = getPi(p);
    int slen = s.length(), plen = p.length(), j = 0;
    for(int i = 0 ; i < slen ; i++)
    {
        while(j>0 && s[i] != p[j])
            j = pi[j-1];
        if(s[i] == p[j])
        {
            if(j==plen-1)
            {
                ans.push_back(i-plen+1);
                j = pi[j];
            }
            else
                j++;
        }
    }
}
```

```
    return ans;
}
```

8.2   Manacher's Algorithm

A[i] = i 번을 중심으로 하는 가장 긴 팰린드롬이 되는 반지름.

```
//original Author : Myungwoo (blog.myungwoo.kr)
int N,A[MAXN];
char S[MAXN];

void Manachers()
{
    int r = 0, p = 0;
    for (int i=1;i<=N;i++)
    {
        if (i <= r)
            A[i] = min(A[2*p-i],r-i);
        else
            A[i] = 0;
        while (i-A[i]-1 > 0 && i+A[i]+1 <= N
        && S[i-A[i]-1] == S[i+A[i]+1])
            A[i]++;
        if (r < i+A[i])
            r = i+A[i], p = i;
    }
}
```

8.3   Trie

```
struct Trie
{
    int trie[NODE_MAX][CHAR_N];
    int nxt = 1;
    void insert(const char* s)
    {
        int k = 0;
        for (int i = 0; s[i]; i++)
        {
            int t = s[i] - 'a';
            if (!trie[k][t])
            {
                trie[k][t] = nxt;
                nxt++;
```

```
            }
            k = trie[k][t];
        }
        trie[k][26] = 1;
    }
    bool find(const char* s, bool exact = false)
    {
        int k = 0;
        for (int i = 0; s[i]; i++)
        {
            int t = s[i] - 'a';
            if (!trie[k][t])
                return false;
            k = trie[k][t];
        }
        if (exact)
        {
            return trie[k][26];
        }
        return true;
    }
};
```

8.4   Rabin-Karp Hashing

Hashmap[k]에, 길이가 len인 부분 문자열의 해시값이 k 가 되는 시작점 인덱스 i 를 push.

```
const ll MOD = BIG_PRIME;
int L;
char S[STR_LEN];
int safemod(int n)
{
    if(n >= 0)
        return n % MOD;
    return ((-n/MOD+1)*MOD + n) % MOD;
}
vector <int> hashmap[MOD];
void Rabin_Karp(int len)
{
    int Hash = 0;
    int pp = 1;
    for(int i=0; i<=L-len; i++)
    {
        if(i == 0)
```

```
    {
        for(int j = 0; j<len; j++)
        {
            Hash = safemod(Hash + S[len-j-1]*pp);
            if(j < len-1)
                pp = safemod(pp*2);
        }
    }
    else
        Hash = safemod(2*(Hash - S[i-1]*pp) + S[len+i-1]);
    hashmap[Hash].push_back(i);
    }
    return;
}
```

9   Miscellaneous

9.1   Binary and Ternary Search

Preventing stupid mistakes by writing garbage instead of proper binary search.
Depends on problem and situation, what we want is either `lo` or `hi`.

```
//Finding minimum value with chk() == true
while(lo+1 < hi)
{
    int mid = (lo+hi)/2;

    if(chk(mid))
        lo = mid;
    else
        hi = mid;
}
```

Ternary search

```
double ternary_search(double l, double r)
{
    double eps = 1e-9;                  //set the error limit here
    while (r - l > eps)
    {
        double m1 = l + (r - l) / 3;
        double m2 = r - (r - l) / 3;
        double f1 = f(m1);      //evaluates the function at m1
        double f2 = f(m2);      //evaluates the function at m2
        if (f1 < f2)
            l = m1;
        else
            r = m2;
    }
    return f(l);                        //return the maximum of f(x) in [l, r]
}
```

9.2   Useful Bitwise Functions in C++

```
        int __builtin_clz(int x);// number of leading zero
        int __builtin_ctz(int x);// number of trailing zero
        int __builtin_clzll(ll x);// number of leading zero
        int __builtin_ctzll(ll x);// number of trailing zero
        int __builtin_popcount(int x);// number of 1-bits in x
        int __builtin_popcountll(ll x);// number of 1-bits in x
```

```
lsb(n): (n & -n); // last bit (smallest)
floor(log2(n)): 31 - __builtin_clz(n | 1);
floor(log2(n)): 63 - __builtin_clzll(n | 1);


// compute next perm. ex) 00111, 01011, 01101, 01110, 10011, 10101..
ll next_perm(ll v)
{
  ll t = v | (v-1);
  return (t + 1) | (((~t & -~t) - 1) >> (__builtin_ctz(v) + 1));
}
```

9.3   List of Useful Numbers

```
< 10^k      prime    # of prime         < 10^k                  prime
-----------------------------------------------------------------
1              7            4            10               9999999967
2             97           25            11              99999999977
3            997          168            12             999999999989
4           9973         1229            13            9999999999971
5          99991         9592            14           99999999999973
6         999983        78498            15          999999999999989
7        9999991       664579            16         999999999999937
8       99999989      5761455            17        99999999999999997
9      999999937     50847534            18       999999999999999989
```

9.4   Order Statistics Tree

k번째 수 쿼리를 $O(\log n)$ 에 알아서 잘 처리해 주는 마법의 자료구조. 생각보다 상수가 크니 조심해야 함. Merge Sort Tree를 짜는 거보단 나은 선택일 것 같다.

```
#include <ext/pb_ds/assoc_container.hpp>
#include <ext/pb_ds/tree_policy.hpp>
#include <ext/pb_ds/detail/standard_policies.hpp>
typedef tree<int, null_type, less<int>, rb_tree_tag,
tree_order_statistics_node_update> ordered_set;

void test()
{
   ordered_set X;
   X.insert(1);
   X.insert(2);
   X.insert(4);
   X.insert(8);
   X.insert(16);

   cout<<*X.find_by_order(1)<<endl; // 2
   cout<<*X.find_by_order(2)<<endl; // 4
   cout<<*X.find_by_order(4)<<endl; // 16
   cout<<(end(X)==X.find_by_order(6))<<endl; // true

   cout<<X.order_of_key(-5)<<endl;  // 0
   cout<<X.order_of_key(1)<<endl;   // 0
   cout<<X.order_of_key(3)<<endl;   // 2
   cout<<X.order_of_key(4)<<endl;   // 2
   cout<<X.order_of_key(400)<<endl; // 5
}
```

10   Checkpoints

10.1   Debugging

- $10^5 * 10^5 \Rightarrow$ INTEGER OVERFLOW. 특히 for문 안에서 $i * i$ 할 때 조심하기.

- If unsure with overflow, use
  `#define int long long` and stop caring. 이때 `int32_t main()`.

- 행렬과 기하의 i, j 인덱스 조심. 헷갈리면 쓰면서 가기. 문제에 x, y 좌표로 주면 그걸로 가도 좋을듯.

- output이 특정 수열/OX 형태 : 작은 예제를 By hand 또는 간단한 코드로 Exhausive Search. 모르는 무언가를 알기 위해서는 데이터가 필요하다.

10.2   Thinking

- 모든 경우를 다 할 수 없나? 왜 안 되지? 시간 복잡도 잘 생각해 보기. 알고리즘 생각하기 전에 Bruteforce에서 출발하기. 정해의 Target Complexity를 먼저 생각하고 주요 알고리즘들의 Complexity로 짜맞추기.
  예를들어, 쿼리가 30만개 들어온다면 한 쿼리를 적어도 $\log n$ 에 처리할 방법이 아무튼 있다는 뜻.

- 단조함수이며, 충분히 빠르게 검증가능한가 : Binary Search.

- 차원이 높은 문제 : 차원 내려서 생각하기. 3 → 2.

- 이 문제가 사실 그래프 관련 문제는 아닐까? 모델링이 가능할까?

    – 만약 그렇다면, '간선' 과 '정점' 은 각각..?
    – 간선과 정점이 몇 개 정도 있는가?

- 이 문제에 Overlapping Subproblem이 보이나?
  → Dynamic Programming 을 적용.

- 답의 상한이 Reasonable 하게 작은가?

- 그래프 문제에서, 어떤 "조건" 이 들어갔을 때 → 이 문제를 "정점을 늘림으로써" 단순한 그래프 문제로 바꿀 수 있나? (ex : SNUPC 2018 달빛 여우) 이를테면, 홀짝성에 따라 점을 2배로 늘림으로써?

- DP도 마찬가지. 어떤 조건을 단순화하기 위해 상태의 수를 사이사이에 집어넣을 수 있나?

- Square root Decomposition : $O(n \log n)$ 이 생각나면 좋을 것 같지만 잘 생각나지 않고, 제한을 보니 $O(n\sqrt{n})$ 이면 될것도 같이 생겼을 때 생각해 보기.

- 마지막 생각 : 조금 추하지만 해싱이나 Random, `bitset` 을 이용한 $n^2/64$ 같은걸로 뚫을 수 있나?

업데이트 노트 / To-Do
이 페이지는 실제 인쇄 팀노트에 포함되지 않습니다

- 190731 : Rabin-Karp Hashing 추가.

- 190731 : LCA 코드에 최단 / 최장 거리 간선, 거리 구하기 추가.

- 190731 : Segment Tree Lazy Propagation 추가.

- 190731 : Segment Tree Struct 구현체로 변경. (UCPC Finalized)

- 190817 : SPFA Algorithm 추가.

- 190826 : FFT, NTT 추가.

- To-do : HLD 코드 넣기.

- To-do : Centroid Decomposition

- To-do : Trie 구현체 두가지 방식 넣기.