```
#include <TimerOne.h>
const int ResetPin = 2, MutePin = 3, SecurityPin = 4;
volatile bool FindEnable = false;
bool Reboot = true;
void setup()
 pinMode(ResetPin, OUTPUT);
 pinMode(MutePin, OUTPUT);
 pinMode(SecurityPin, INPUT);
 Serial.begin(9600);
 Serial.setTimeout(1000);
 Timer1.initialize(10000000);
 Timer1.attachInterrupt(Check);
 digitalWrite(MutePin, HIGH);
}
void Check()
 FindEnable = true;
}
void loop()
 if (FindEnable && !Reboot)
   Serial.write("Hello\n");
   FindEnable = false;
   if (Serial.find("Imthere"))
     digitalWrite(ResetPin, LOW);
    }
    else
     Reboot = true;
     digitalWrite(ResetPin, HIGH);
     delay(1000);
     digitalWrite(ResetPin, LOW);
  }
```

```
else if (Reboot)
 {
  if (Serial.find("Rebooted"))
    Reboot = false;
    FindEnable = false;
 }
//----
 if (Serial.available())
  if (Serial.find("Imclosing"))
    Reboot = true;
   if (Serial.find("Enable"))
    digitalWrite(MutePin, HIGH);
  if (Serial.find("Disable"))
    digitalWrite(MutePin, LOW);
 }
//----
 if (digitalRead(SecurityPin))
  Serial.write("Securitybreached");
}
```