$$\mathbf{P}_t = \begin{pmatrix} \mathbf{H} & \mathbf{S1} & \mathbf{S2} & \mathbf{DOC} & \mathbf{DS} \\ \mathbf{H} & \mathbf{p.HS1}_t & \mathbf{p.HS2}_t & \mathbf{p.HD0C}_t & \mathbf{p.HDS}_t \\ \mathbf{p.S1H}_t & \mathbf{p.S1S1}_t & \mathbf{p.S1S2}_t & \mathbf{p.S1DOC}_t & \mathbf{p.S1DS}_t \\ \mathbf{S2} & \mathbf{DOC} & \mathbf{0} & \mathbf{p.S2S2}_t & \mathbf{p.S2DOC}_t & \mathbf{p.S2DS}_t \\ \mathbf{DOC} & \mathbf{0} & \mathbf{0} & \mathbf{1.0} & \mathbf{0} \\ \mathbf{DS} & \mathbf{0} & \mathbf{0} & \mathbf{0} & \mathbf{1.0} \end{pmatrix}$$

$$\mathbf{P}_t = \begin{bmatrix} \mathbf{H} & \mathbf{S1} & \mathbf{S2} & \mathbf{D} & \text{trDS} \\ \mathbf{H} & \mathbf{p.HH}_t & \mathbf{p.HS1}_t & \mathbf{p.HS2}_t & \mathbf{p.HD}_t & \mathbf{p.HDs}_t \\ \mathbf{p.S1H}_t & \mathbf{p.S1S1}_t & \mathbf{p.S1S2}_t & \mathbf{p.S1D}_t & \mathbf{p.S1DS}_t \\ \mathbf{S2} & \mathbf{0} & \mathbf{0} & \mathbf{p.S2S2}_t & \mathbf{p.S2D}_t \\ \mathbf{D} & \mathbf{0} & \mathbf{0} & \mathbf{1.0} & \mathbf{0} \\ \mathbf{trDS} & \mathbf{0} & \mathbf{0} & \mathbf{0} & \mathbf{0.0} \end{bmatrix}$$

$$S = \begin{bmatrix} s_{01} & s_{02} & \dots & s_{0k} \\ s_{11} & s_{12} & \dots & s_{1k} \\ \vdots & \vdots & \ddots & \vdots \\ s_{\omega 1} & s_{\omega 2} & \dots & s_{\omega k} \end{bmatrix}$$

$$s_t = s_0 \cdot P^t$$