A Sufficient Statistics Approach to Ex Ante Health Policy Evaluation

John A. Graves

# Introduction

Models projecting the impact of reforms to health insurance programs and markets play an important role in shaping U.S. health policy. For example, in 2017 Congressional attempts to repeal and replace the 2010 Affordable Care Act (ACA) collapsed, in part, under public outcry after the Congressional Budget Office (CBO) [projected](https://www.nytimes.com/2017/05/24/us/politics/cbo-congressional-budget-office-health-care.html) that upwards of 23 million people would become uninsured. The [twists](https://prescriptions.blogs.nytimes.com/2009/10/07/analysis-sees-baucus-bill-meeting-obamas-cost-and-deficit-targets/) [and](https://www.nytimes.com/2009/10/19/us/19iht-letter.html) [turns](https://www.nytimes.com/2009/10/06/health/policy/06health.html) of earlier debates over the ACA–and before it, [the Clinton health plan](figures/01_nyt-clinton-cbo.png)–also were shaped by modelers’ assessments of how reform would impact insurance coverage, premiums, health care spending, and government costs.

Microsimulation models used by the CBO and by others to produce these estimates draw on economic theory and on a large and growing literature evaluating past state and federal reform efforts. Yet while models derive inputs from this shared evidence base, the evidence is uncertain and not in uniform agreement. Models also differ in their structure, underlying data sources and assumptions. It should come as no surprise, then, that models often produce [widely varying projections of the same reform proposal](https://www.nytimes.com/interactive/2019/04/10/upshot/medicare-for-all-bernie-sanders-cost-estimates.html).

This current state of affairs has subjected microsimulation models to criticism over their “black box” like qualities and their tendency to produce estimates with a limited accompanying sense of uncertainty or sensitivity to alternative parameter values and assumptions. Moreover, modelers have understandably but unfortunately shied away from producing comparative assessments of overall welfare impact. Existing models typically produce an array of intermediary point estimates on welfare-relevant outcomes (e.g., changes in coverage, premiums, spending and government costs) and leave it to policymakers to weigh those factors when comparing policy choices.

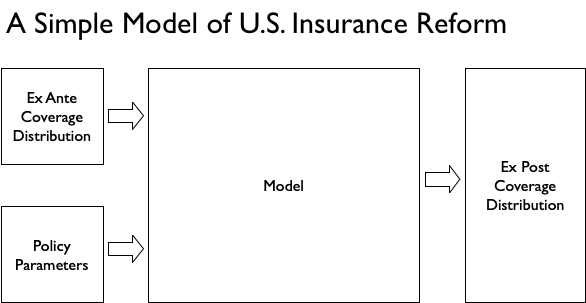
This approach to health policy modeling has a number of important shortcomings. First, despite modelers’ attempts to caveat the high degree of uncertainty in their estimates, modeled projections are often afforded a false sense of precision in high-stakes policy debates. This results in decisions being made in spite of a high degree of uncertainty surrounding the budgetary, health and coverage impact of proposed reforms. Second, the “black box”-like opacity of microsimulation models makes it difficult for researchersto know whether and how their work can inform and improve modeling efforts. Finally, the development, execution, and maintenance costs of microsimulation models are considerable. Combined, these factors contribute to high barriers to understanding and a muddled sense of how the health economic and policy research enterprise could be further refined to improve policy decision making.

This study outlines an approach to ex ante policy evaluation that addresses many of the above shortcomings. First, I outline a generalized discrete time modeling framework for assessing the cost, coverage and welfare impact of health reform policies. This framework has roots in health economic modeling methods used worldwide for health technology assessment, and in the “sufficient statistics” approach to welfare evaluation developed in public finance. I demonstrate that this modeling framework not only encompasses many existing approaches to health policy microsimulation, but also facilitates simple yet powerful counterfactual policy aassessments based on reduced form estimates. That is, the framework provides researchers with a simple tool to investigate the coverage and cost impacts of reform alternatives without the need for a detailed individual-level microsimulation model.

As a proof of concept, I demonstrate how differences-in-differences evidence on the impact of Medicaid expansion on coverage, combined with regression-discontinuity estimates on willingness to pay for subsidized health insurance (Finkelstein, Hendren and Shepard 2019) can be harnessed to model the impact of further expansion of coverage via public programs versus via increased subsidies for private coverage.

Second, within this framework I tie together diverse approaches to assessing uncertainty and the welfare impacts of policy. Specifically, I draw linkages between standard wefare impact measures used in health technology assessment (e.g., net health benefit and net monetary benefit) and the marginal value of public funds (MVPFs), a summary measure of the costs and benefits of public policies (Hendren 2017). This linkage allows for a systematic approach to understanding parameter and modeling uncertainty based on probalistic sensitivity anlayses (PSAs) and value of information (VOI) methods.

Intuitively, VOI methods quantify uncertainty in model output through a summary measure of welfare impact. At a given policy efficiency or willingness-to-pay threshold (e.g., a decision rule based on a MVPF value of 0.8, above which a policy might be implemented but below which may may not), the magnitude of this uncertaninty may or may not affect optimal decision making when comparing policy alternatives. If policy decisions based on comparative MVPF values are insensitive to varying assumptions or to estimation uncertainty in model parameters, then the value of information on these parameters is low – i.e., it is not worth pursuing additional research to reduce uncertainty. If policy decisions are sensitive to this uncertainty, however, then these methods provide a guidepost for priortizing and refining future research. As an example, I apply VOI methos to reduced form evidence on teh MVPF willingness to pay (WTP) for subsidized health insurance, which i



# Health Reform Modeling as a Discrete Time Markov Process

This section outlines a simple discrete time markov model for health insurance coverage in the U.S. population. We begin by defining an ex ante occupancy vector that summarizes the fraction of the population in each major health insurance type (employer-sponsored insurance, other private insurance, public insurance, and uninsured) in the pre-reform period.

where is the fraction of the population in each insurance category in the ex ante period.

Now define the transition probability matrix:

where is the probability of transitioning from ex ante category to ex post category .

Finally, we can define an ex post occupancy vector:

Basic matrix algebra links the two occupancy vectors as follows:

In the equation above, the set of transition probabilities can be considered sufficient statistics for evaluating the impact of a policy change on health insurance coverage in the population. That is, once we know these probabilities and how they change under a given reform option, we can simulate the impact on the overall coverage distribution in the population. By attaching costs to population movements among insurance types, we can simulate the cost impact to the government. And finally, as we show below, social welfare weights can also be attached to population movements. These weights can then be aggregated and compared across reform alternatives to make comparative evaluations of policy options.

### Estimating the Transition Probability Matrix

We first obtain a simple cross tabulation of insurance coverage in January 2013 from the SIPP.

Ex Ante Distribution of Insurance Coverage, January 2013

Category

SIPP: Number (millions)

SIPP: Percent

MEPS: Number (millions)

MEPS: Percent

ESI

118.7

62.4

113.5

61.5

Private-Other

11.1

5.9

4.4

2.4

Public

20.9

11.0

20.9

11.3

Uninsured

39.5

20.8

45.7

24.8

Next we fit nonpaarametric (Kaplan-Meier) and parametric multi-state models to obtain the transition probabilities by December 2013.

Transition Probabilities

baseline

01\_esi

02\_priv\_oth

03\_public

04\_uninsured

01\_esi

88.3

3.5

1.2

7.0

02\_priv\_oth

27.5

53.0

6.7

12.8

03\_public

5.5

3.7

79.1

11.7

04\_uninsured

18.4

9.1

20.0

52.5

Transition Probabilities

baseline

01\_esi

02\_priv\_oth

03\_public

04\_uninsured

01\_esi

85.8

0.9

2.1

10.9

02\_priv\_oth

23.9

62.9

2.5

10.7

03\_public

6.5

1.1

68.2

22.8

04\_uninsured

24.1

5.8

19.3

50.3