

We wish to prove $\int d\vec{\ell} \times \vec{F} = \int (\vec{G} \times \vec{\nabla}) \times \vec{F} dS$

Define $\vec{G} = \vec{F} \times \vec{A}$ where \vec{A} is a constant vector and apply Stokes theorem

$$\int d\vec{\ell} \cdot \vec{G} = \int (\vec{\nabla} \times \vec{G}) \cdot \hat{n} dS$$

Now the LHS can be rewritten

$$\int d\vec{\ell} \cdot \vec{G} = \int d\vec{\ell} \cdot (\vec{F} \times \vec{A}) = \int \vec{A} \cdot (d\vec{\ell} \times \vec{F})$$

and the RHS can also be rewritten by re-writing the integrand

$$\begin{aligned} \hat{n} \cdot (\vec{\nabla} \times \vec{G}) &= n_i \epsilon_{ijk} \partial_j G_k \\ &= n_i \epsilon_{ijk} \partial_j \epsilon_{klm} F_l A_m \\ &= A_m \epsilon_{mk\ell} (\epsilon_{kij} n_i \partial_j) F_\ell \\ &= A_m \epsilon_{mk\ell} \{ \hat{n} \times \vec{\nabla} \}_k F_\ell \\ &= \vec{A} \cdot (\hat{n} \times \vec{\nabla}) \times \vec{F} \end{aligned}$$

Equating and re-arranging yields

$$\vec{A} \cdot [\int d\vec{\ell} \times \vec{F} - \int (\hat{n} \times \vec{\nabla}) \times \vec{F} dS] = 0$$

and since \vec{A} is arbitrary

$$\boxed{\int d\vec{\ell} \times \vec{F} = \int (\vec{G} \times \vec{\nabla}) \times \vec{F} dS}$$