Next-Event Simulation

Lawrence M. Leemis and Stephen K. Park, Discrete-Event Simulation - A First Course, Prentice Hall, 2006

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Motivation

- Making small modifications to our simple discrete-event simulations is non-trivial
 - Add feedback to ssq2
 - ▶ Add delivery lag to sis2
- ▶ Next-event simulation is a *more general approach* to discrete-event simulation, based on,
 - System state
 - Events
 - Simulation clocks
 - Event scheduling
 - Event list

System State

- ► The state of a system is a complete characterization of the system at an *instance* in time
 - Conceptual model: abstract collection of variables and how they evolve over time
 - Specification model: collection of mathematical variables together with logic and equations
 - Computational model: collection of program variables systematically updated
- ► Example 5.1.1: state of *ssq* is the *number of jobs in the node*
- ► Example 5.1.2: state of sis is current inventory level and the amount of inventory on order (if any)

Events

- ▶ An event is an occurrence that may change the state of the system
- Example 5.1.3: For *ssq*, events are *arrivals* or *completion* of a jobs
 - ▶ An arrival will always increase the number of jobs in the node by 1
 - ▶ If there is *no feedback*, a *completion* of a job will *always* decrease the number of jobs in the node by 1
 - ▶ With feedback, a *completion* of a job *may* decrease the *number of jobs in the node* by 1
- ► Example 5.1.4: For *sis* with delivery lag, events are *demand* instances, *inventory reviews*, and *arrival of inventory replenishment orders*
 - A demand will decrease the inventory level by 1
 - An inventory review might lead to an increase in the amount of inventory on order
 - ► The arrival of an order will increase the *inventory level* and decrease the *amount of inventory on order*.
- ▶ We can also define artificial events, e.g.,
 - Statistically sample the state of the system
 - Schedule an event at a prescribed time

Simulation Clock

- ▶ The *simulation clock* represents the current value of simulated time
- Previously introduced discrete-event simulation models lack definitive simulated time
 - ▶ As a result, it is difficult to generalize or embellish models
 - Example 5.1.5: It is hard to reason about ssq2 because there are effectively two simulation clocks
 - Arrival times and completion times are not synchronized
 - It is difficult to reason about the temporal order of events if arrivals are merged by feedback with completion of service.
 - ▶ Example 5.1.6: In sis2, the only event is inventory review
 - ► The simulation clock is integer-valued and we have to aggregate all demand and to do some calculus to derive equations for the time-averaged holding and shortage levels
 - When there is a delivery lag that happens in a non-integer-valued time, the derivation of those equations is a significant task. (see Example 3.3.3 or In-Class Exercise 7-2)

Event Scheduling

- ▶ It is necessary to use a *time-advance* mechanism to guarantee that events occur in the correct order
- Next-event time advance is typically used in discrete-event simulation
- ► To build a next-event simulation model:
 - construct a set of state variables
 - identify the event types
 - construct a set of algorithms that define state changes for each event type
- ► The simulated system evolves in simulated time by executing the events in increasing order of their scheduled time of occurrence.
 - Simulation clock is advanced discontinuously from event time to event time

Event List

- ► The event list (or calendar is the data structure containing the time of next occurrence for each event type
- ➤ The event list is often, but not necessarily, represented as a priority queue sorted by the next scheduled time of occurrence of each event type
- ► More detailed discussion in the examples and a later discussion on event-list management.

Next-Event Simulation

Algorithm 5.1.1

- 1. Initialize.
 - 1.1 set simulation clock (usually to zero)
 - 1.2 set first time of occurrence for each event type
- Process current event.
 - 2.1 scan event list to determine most imminent event
 - 2.2 advance simulation clock
 - 2.3 update state
- 3. Schedule new events
 - 3.1 The current event may spawn new events. The new events, if any, are placed in the event list
 - 3.2 The algorithm returns to step 2 if not terminated as in step 4
- 4. Terminate
 - Continue advancing the clock and handling events until termination condition is satisfied

Next-Event Simulation

- ▶ The simulation clock runs asynchronously; inactive periods are ignored
 - Simulation clock is advanced discontinuously from event time to event time
- ► Clearly, a computational advantage over fixed-increment time-advance mechanism

Next-Event Simualtion by Examples

- Single-Server Service Node
 - Model extension: immediate feedback
 - Model extension: alternative queue disciplines
 - Model extension: finite service node capacity
 - Model extension: random sampling
- Simple inventory system with delivery lag and random demand
- Multi-server service node

Single-Server Service Node: Concept Model

▶ The state variable I(t) (the number of jobs at time t at the node) provides a complete characterization of the state of a ssq

$$I(t) = 0 \iff q(t) = 0$$
 and $x(t) = 0$

$$I(t) > 0 \iff q(t) = I(t) - 1$$
 and $x(t) = 1$

- ▶ Two events cause this variable to change
 - 1. An arrival causes I(t) to increase by 1
 - 2. A completion of service causes I(t) to decrease by 1

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Single-Server Service Node: Specification Model

- \triangleright The initial state I(0) can have any non-negative value, typically 0
- ▶ The terminal state can be any non-negative value
 - \triangleright Assume at time τ arrival process stopped. Remaining jobs processed before termination
- Some mechanism must be used to denote an event impossible
 - Only store possible events in event list
 - Denote impossible events with event time of ∞

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Single-Server Service Node: Specification Model

- The simulation clock (current time) is t
- ▶ The terminal ("close the door") time is τ
- ► The next scheduled arrival time is t_a
- ▶ The next scheduled service completion time is t_c
- ▶ The number in the node (state variable) is /

Note the following,

- ▶ It is not necessary to generate and store all arrivals prior to the execution of the simulation.
- ▶ It only nees to schedule the 1st arrival in the intialization phase and then to schedule each subsequent arrival while processing the current arrival
- It inserts completion event in the event list.

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Single-Server Service Node: Computational Model

Algorithm 5.1.2

```
/* 1. Initialize */
I = 0:
t = 0.0:
t_a = GetArrival(); /* initialize the event list */
t_c = \infty:
while ((t_a < \tau) \text{ or } (I > 0)) \{ /* 4. \text{ Terminate or not } */
  /* process current event */
  /* 2.1 - 2.2 scan the event list and advance simulation time */
  t = min(t_a, t_c);
  if (t == t_a) { /* process an arrival */
     I + +:
     /* 3. schedule new arrival event */
     t_a = GetArrival();
     if (t_a > \tau)
        t_2 = \infty:
     /* 3. schedule new service event */
     if (I == 1)
        t_c = t + GetService();
  } else { /* process a completion */
     1 - -;
     /* 3. schedule new service event */
     if (1 > 0)
        t_c = t + GetService();
     else
        t_c = \infty:
```

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Program ssq3

- In ssq3, long variable number represents I(t) and structure variable t represents time
 - ▶ the event list t.arrival and t.completion, i.e., t_a and t_c from Algorithm 5.1.2;
 - ▶ the simulation clock *t.current*, i.e., *t* from Algorithm 5.1.2;
 - ▶ the next event time t.next, i.e., $min(t_a, t_c)$ from Algorithm 5.1.2
 - ▶ the last arrival time t.last
- ▶ Time-averaged statistics are gathered with the structure variable area
 - $ightharpoonup \int_0^t I(s)ds$ evaluated as area.node
 - $ightharpoonup \int_0^t q(s)ds$ evaluated as area.queue
 - $\rightarrow \int_0^t x(s)ds$ evaluated as area.service

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World Views and Synchronization

- Programs ssq2 and ssq3 simulate exactly the same system
- The two have different world views
 - ssq2: process-interaction world view, naturally produces job-averaged statistics
 - ssq3: event-scheduling world view, naturally produces time-averaged statistics

The event-scheduling world view is the discrete-event simulation world view of cohice for the rest of the discussion.

- ▶ The programs should produce exactly the same statistics
 - Both requires requires rngs

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Model Extension: Immediate Feedback

It is simple to accomodate immediate feedback in the next-event simulation model.

```
Immediate Feedback
```

```
else { /* process a completion of service */
    if (GetFeedback() = 0) { /* this statement is new */
        index ++:
        number --;
```

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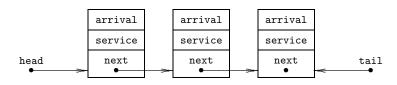
In-Class Exericse L10-1

You are to extend the *ssq3* program with *immediate feedback*. You may find *ssq3* in Blackboard. The instructor also provides a solution to In-Class Exercise L7-2 (Examples 3.3.2 only) and the program is *ssq2v2*. Complete the following.

- 1. Extend *ssq3* to accommodate *immediate feedback* as outlined in slide 18.
- Adjust the parameters in the revised ssq3 to match those in ssq2v2.
 Compare the output from the revised ssq3 program to that of ssq2v2 by (a) graphing the result in a single figure and (b) computing and graphing the relative difference of the two outputs in a second figure.
- 3. Observe both ssq2v2 and the revised ssq3. Explain briefly the difference between the revision on ssq2 (to obtain ssq2v2) and that on ssq3 (to obtain the revised ssq3)
- 4. Submit the revised *ssq3*, the graphs, and your answer to bullet 3 above to Blackboard.

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Model Extension: Alternate Queue Discipline



Program ssq3 can be modified to simulate any queue discipline.

- Need to add a dynamic-queue data structure.
- Example: singly linked list.
 - ▶ Each list node contains the arrival time and service time for a job in the queue
 - ▶ Use *Enqueue* each time an arrival event occurs and the server is busy.
 - Dequeue each time a completion-of-service event occurs and the gueue is not empty.
- ▶ Can be combined with with the immediate-feedback modification.
 - The arrival field in the linked list would hold the time of feeback for those fedback jobs.

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Model Extension: Finite Service Node Capacity

Previously, assume the queue has *infinite* capacity. Program *ssq3* can be modified to account for a finite capacity.

Finite Service Node Capacity

```
if (t.current == t.arrival) {
    if (number < CAPACITY) {</pre>
        number++:
        if (number = 1)
            t.completion = t.current + GetService();
    else
        reject++;
    t.arrival = GetArrival();
    if (t.arrival > STOP) {
        t.last = t.current:
        t.arrival = INFINITY;
```

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In-Class Exericse L10-2

You are to extend the *ssq3* program with *finite capacity*. You may find *ssq3* in Blackboard. Complete the following.

- 1. Extend ssq3 to accommodate finite capacity as outlined in slide 21.
- 2. What consistency check have you performed? What are the results?
- 3. Graph utilization versus capacity
- 4. What is the maximum queue capacity needed if we do not want to reject any jobs?
- 5. Submit the revised *ssq3*, the graphs, and your answers to bullet 2 and 4 above to Blackboard.

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Model Extension: Random Sampling

- ▶ The structure of ssq3 facilitates adding sampling
- Add a sampling event to the event list
 - \triangleright Sample deterministically, every δ time units
 - \triangleright Sample Randomly, every Exponential(δ) time units

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Simple Inventory System with Delivery Lag and Random Demand

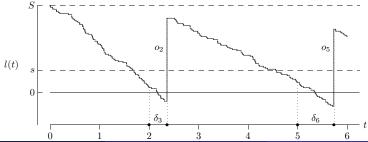
Two changes relative to sis2

- ightharpoonup Uniform(0,1) lag between inventory review and order delivery
- More realistic demand model
 - Demand instances for a single item occur at random
 - \triangleright Average rate is λ demand instances per time interval
 - ▶ Time between demand instances is Exponential $(1/\lambda)$

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Demand Models: A Comparison

- ► sis2 used an aggregate demand for each time interval, generated as an Equilikely (10, 50) random variate
 - Aggregate demand per time interval is random
 - Within an interval, time between demand instances is constant
 - ▶ Example: if aggregate demand is 25, inter-demand time is 0.04
- Now using Exponential $(1/\lambda)$ inter-demand times
 - Demand is modeled as an arrival process
 - Average demand per time interval is λ



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Specification Model: States and Notation

- The simulation clock is t (real-valued)
- ▶ The terminal time is τ (integer-valued)
- Current inventory level is I(t) (integer-valued)
- Amount of inventory on order, if any, is o(t) (integer-valued). Necessary due to delivery lag
- \triangleright I(t) and o(t) provide complete state description
- Initial state is assumed to be I(0) = S and o(0) = 0
- ▶ Terminal state is assumed to be $I(\tau) = S$ and $o(\tau) = 0$
- \triangleright Cost to bring I(t) to S at simulation end (with no lag) must be included in accumulated statistics

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Specification Model: Events

Three types of events can change the system state

- ▶ A demand for an item at time t. I(t) decreases by 1.
- ▶ An inventory review at integer-valued time t
 - If $I(t) \geq s$, then o(t) = 0
 - If I(t) < s, then o(t) = SI(t)
- ▶ An arrival of an inventory replenishment order at time t
 - \blacktriangleright I(t) increases by o(t)
 - ▶ o(t) becomes 0

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Algorithm 5.2.1: Initialization

- ▶ Time variables used for event list:
 - ▶ t_d: next scheduled inventory demand
 - ▶ t_r: next scheduled inventory review
 - ▶ ta: next scheduled inventory arrival
- infty denotes impossible events

Initialization Step of Algorithm 5.2.1

```
I=S; /* initialize inventory level */
o = 0; /* initialize amount on order */
t = 0.0; /* initialize simulation clock */
t_d= GetDemand(); /* initialize event list */
t_r=t+1.0; /* initialize event list */
t_a=\infty; /* initialize event list */
```

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Algorithm 5.2.1: Main Loop

Main Loop of Algorithm 5.2.1

```
while (t < \tau) {
  t = min(t_d, t_r, t_a); /* scan the event list */
  if (t == t_d) { /* process an inventory demand */
    1 - -:
    t_d = GetDemand();
  } else if (t == t_r) { /* process an inventory review */
    if (1 < s) {
       o = S - I:
       end = GetLag();
       t_2 = t + end:
    t_r += 1.0:
  } else { /* process an inventory arrival */
    I += o:
    0 = 0:
    t_a = 1:
```

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Program sis3

Implements Algorithm 5.2.1

- \triangleright t.demand, t.review and t.arrive correspond to t_d , t_r , t_a
- ▶ State variables inventory and order correspond to I(t) and o(t)
- sum.hold and sum.short accumulate the time-integrated holding and shortage integrals

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A Multi-Server Service Node

- ▶ The single-server service node is extended to support multiple servers
- It is a natural generalization
 - Multi-server service nodes have both practical and theoretical importance
 - ▶ The event list size depends on the number of servers
 - For large numbers of servers, the event list data structure becomes important
 - Extensions of the multi-server node (immediate feedback, finite capacity, non-FIFO) are left as exercises

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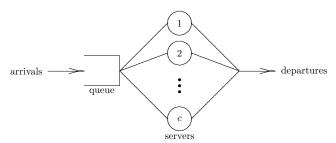
Conceptual Model

Definition 5.2.1: A multi-server service node consists of

- A single queue (if any)
- ▶ Two or more servers operating in parallel

At any instant in time,

- Each server is either busy or idle
- The queue is either empty or not empty
- If one or more servers is idle, the queue must be empty
- ▶ If the queue is not empty, all servers must be busy



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Conceptual Model

- ▶ When a job arrives
 - If all servers are busy, the job enters the queue
 - ▶ Else an idle server is selected and the job enters service
- ▶ When a job departs a server
 - ▶ If the queue is empty, the server becomes idle
 - ► Else a job is removed from the queue, served by server Servers process jobs independently

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Server Selection

- ▶ Definition 5.2.2: The algorithm used to select an idle server is called the *server selection rule*
- Common selection rules
 - Random selection: at random from the idle servers
 - Selection in order: lowest-numbered idle server
 - Cyclic selection: first available, starting after last selected (circular search may be required)
 - Equity selection: use longest-idle or lowest-utilized
 - Priority selection: choose the best idle server (modeler specifies how to dermine best)
- Random, cyclic, equity: designed to achieve equal utilizations
- ▶ If servers are statistically identical and independent, the selection rule has no effect on average performance of the service node
- ► The *statistically identical assumption* is useful for mathematicians; unnecessary for discrete-event simulation

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Specification Model: States and Notation

- Servers in a multi-server service node are called service channels
 - c is the number of servers (channels)
 - ▶ The server index is s = 1, 2, ..., c
- \triangleright I(t) denotes the number of jobs in the service node at time t
 - ▶ $I(t) \ge c$, all servers are busy and q(t) = I(t)c
 - ▶ If I(t) < c, some servers are idle
 - ▶ If servers are distinct, need to know which servers are idle
- ▶ For s = 1, 2, ..., c, define $x_s(t)$: the number of jobs in service (0 or 1) at server s at time t
- ▶ The complete state description is $I(t), x_1(t), x_2(t), \dots, x_c(t)$

$$q(t) = I(t) - \sum_{s=1}^{c} x_s(t)$$

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Specification Model: Events

What types of events can change state variables $I(t), x1(t), x2(t), \dots, x_c(t)$?

- An arrival at time t
 - ▶ *I*(*t*) increases by 1
 - ▶ If $I(t) \le c$, an idle server s is selected, and $x_s(t)$ becomes 1
 - ► Else all servers are busy
- A completion of service by server s at time t
 - ▶ *I*(*t*) decreases by 1
 - If $I(t) \ge c$, a job is selected from the queue to enter service
 - Else $x_s(t)$ becomes 0

There are c+1 event types

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Specification Model: Additional Assumption

- ▶ The initial state is an empty node
 - I(0) = 0
 - $x_1(0) = x_2(0) = \dots = x_c(0) = 0$
 - ► The first event must be an arrival
- ightharpoonup The arrival process is turned off at time au
 - ightharpoonup The node continues operation after time au until empty
 - ▶ The terminal state is an empty node
 - ► The last event is a completion of service
- ► For simplicity, all servers are independent and statistically identical
- Equity selection is the server selection rule

All of these assumptions can be relaxed

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Specification Model: Event List

0	t	Х	arrival
1	t	Х	completion of service by server 1
2	t	Х	completion of service by server 2
3	t	Х	completion of service by server 3
4	t	Х	completion of service by server 1 completion of service by server 2 completion of service by server 3 completion of service by server 4

- ▶ Can be organized as an array of c + 1 event types
- Field t: scheduled time of next occurrence for the event
- Field x: current activity status of the event
 - Superior alternative to using 1 to denote impossible events
 - For 0th event type, x denotes if arrival process is on or off
 - ► For other event types, x denotes if server is busy or idle
- ▶ For large c, consider alternate event-list structures (see later discussion)

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Program msq

Implements this next-event multi-server service node simulation model

- ▶ State variable I(t) is number
- ▶ State variables $x_1(t), x_2(t), \dots, x_c(t)$ are part of the event list
- ► Time-integrated statistic $\int_0^t I(\theta) d\theta$
- Array sum records for each server
 - the sum of service times
 - the number served
- Function NextEvent searches the event list to find the next event
- ► Function FindOne searches the event list to find the longest-idle server (because equity selection is used)

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Event-List Management

Some next-event simulations can have a great number of events on their event list simultaneously.

- ▶ An event list is the data structure that contains a list of events scheduled to occur in the future.
- ▶ The list is not necessarily sorted by the scheduled time of occurrence.
- Also called calendar, future events chain, sequencing set, future event set, . . .
- ► Event lists are also called future events, event notices, transactions, records, . . .

Event-list management is important

Many next-event simulation models spend more CPU time on managing the event list than on any other aspects of the simulations.

Event-List Management: 4 Categories

2 boolean classifications

- ► fixed maximum or variable maximum number of events on the event list
- devised for one specific model or for a general-purpose simulation language

Based on the 2 boolean classifications, there are 4 categories of event-list management

No.	Number of Events	Model
1	fixed maximum	specific model
2	fixed maximum	general-purpose
3	variable maximum	specific model
4	variable maximum	general-purpose

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Event-List Management: Operations

2 critical operations

- ▶ Insertion (enqueue or scheduling)
- ► Deletion (*dequeue*)

Additional operation

- Change Operation: change of an existing event
- Examine Operation: searches for an existing event
- Count: determine the number of events on the list

Event-List Management Criteria

3 criteria are used to assess the effectiveness oft he data structure and algorithms for an event-management scheme

- Speed
- Robustness
- Adaptability

Event-List Management by Example

Consider the timesharing computer system model (Henriksen 1983) to discuss event-list management schemes.

- ▶ Simulation models for the timesharing computer system
 - ▶ Concept, specification, and computational models
- Event-list management schemes
 - Using array
 - Using a single linked list
 - Using multiple linked lists
 - Using binary trees
 - Using heaps
 - Hybrid schemes

Summary

- ► A generic approach to discrete-event simulation: next-event simulation
- Examples of next-event simulations
- Event-list management by examples