

## Adaptive time stepping

Key idea: Run 2 methods simultaneously with different truncation errors (orders):

e.g. 1)  $y_{n+1}^A = \langle \text{method A} \rangle$ , e.g.  $O(h^4)$  LTE

2)  $y_{n+1}^B = \langle \text{method B} \rangle$ , e.g.  $O(h^5)$  LTE

Approximate the error as

$$\text{err} = |y_{n+1}^A - y_{n+1}^B|$$

If  $\text{err} >$  a user-chosen tolerance, reduce  $h$  (e.g. by half) and recompute the whole step, repeating until the bound is satisfied.

Q: Is this reasonable? Why?

Observe  $y_{n+1}^A = y(t_{n+1}) + O(h^p) = y(t_{n+1}) + \underset{\substack{\uparrow \\ \text{unknown error} \\ \text{coefficient.}}}{Ch^p} + O(h^{p+1})$   
for some value  $C$ .

If method B is one order more accurate,  $O(h^{p+1})$ , then

$$y_{n+1}^B = y(t_{n+1}) + O(h^{p+1}).$$

Method A's true error is  $|y_{n+1}^A - y(t_{n+1})| = Ch^p + O(h^{p+1})$

Our estimated error is  $|y_{n+1}^A - y_{n+1}^B| = Ch^p + O(h^{p+1})$  also...

The dominant (lowest order) term of the error matches!

∴ Our estimated error is a reasonable approximation to use to adjust  $h$ , without knowing the true sol'n.

## Predicting A Good Step Size

We can estimate the leading error coefficient  $C$  as

$$C \approx \frac{|y_{n+1}^A - y_{n+1}^B|}{(h_{\text{old}})^p} \quad \text{where "hold" is the current (most recent) step size.}$$

Assuming  $C$  changes slowly/smoothly in time, we can estimate the next step's error as

$$\text{err}_{\text{next}} = |y_{n+2}^A - y(t_{n+2})| \approx C(h_{\text{new}})^p$$

Plugging in for  $C$ , we have: ↑ next step size, to be determined.

$$\text{err}_{\text{next}} = \frac{|y_{n+1}^A - y_{n+1}^B|}{(h_{\text{old}})^p} (h_{\text{new}})^p = \left(\frac{h_{\text{new}}}{h_{\text{old}}}\right)^p |y_{n+1}^A - y_{n+1}^B|.$$

Given a desired error tolerance, "tol", set  $\text{err}_{\text{next}} = \text{tol}$ , and solve for  $h_{\text{new}}$ :

$$h_{\text{new}} = h_{\text{old}} \left( \frac{\text{tol}}{|y_{n+1}^A - y_{n+1}^B|} \right)^{\frac{1}{p}}.$$

To (roughly!) compensate for our approximations, we may be conservative by scaling our tolerance down by some factor  $\alpha$ , e.g.  $\alpha = \frac{1}{2}$  or  $\alpha = \frac{3}{4}$ , etc.

$h_{\text{new}}$  will not be exact, but hopefully a good guess.