Numerical Linear Algebra – Pivoting and FLOP counting CS370 Lecture 30 – March 27, 2017

Gaussian Elimination: Ax = b

(Some) numerical algorithms use Gaussian elimination, too. But it is interpreted differently...

Our view will be the following:

- **1.** Factor matrix A into A = LU, where L and U are triangular.
- **2.** Solve Lz = b for intermediate vector z.
- **3.** Solve Ux = z for x.

(Later: We may also want to reorder (*permute*) the equations, which leads to the factorization PA = LU.)

Numerical Problems – Factorization

During factoring, what if a diagonal entry, $a_{k,k}$ is zero? Or close to zero?

```
For k=1,...,n For i=k+1,...,n mult:=a_{ik}/a_{kk} Divide by (exactly or nearly) zero? a_{ik}:=mult For j=k+1,...,n a_{ij}:=a_{ij}-mult*a_{kj} EndFor EndFor
```

Numerical Problems

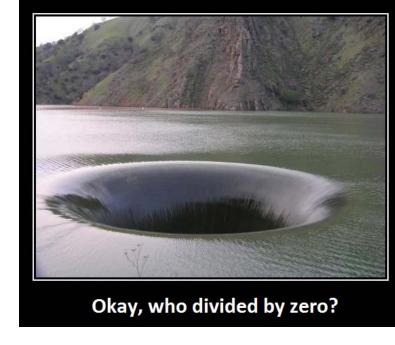
A division by zero is obviously bad news.

What about nearly zero?

This will make the multiplicative factor, $a_{i,k}/a_{k,k}$, large in magnitude.

A large factor can cause large floating point error during subtraction and magnify existing floating point error.

Leads to numerical instability!



Solution: Row/Partial Pivoting

In earlier classes, you likely swapped rows if a diagonal entry was zero. This is called "row pivoting" or "partial pivoting".

For numerical algorithms, one difference: we will **always** swap, to minimize floating point error incurred.

Strategy: Find the row with the *largest magnitude entry* in the current column beneath the current row, and swap those rows if larger than the current entry.

Row/Partial Pivoting

Strategy: Find the row with the *largest magnitude entry* in the current column beneath the current row, and swap those rows if larger than the current entry.

e.g.
$$\begin{bmatrix} 0 & 2 & 3 \\ 1 & 4 & 2 \\ -3 & 2 & -1 \end{bmatrix}$$

We immediately swap the first and third rows, since |-3| > |1| > 0.

Pivoting with a Permutation Matrix

How can our factorization view account for row swaps?

Find a modified factorization of A such that PA = LU where P is a **permutation matrix**.

A permutation matrix P is a matrix whose effect is to swap rows of the matrix it is applied to (i.e., multiplied with).

Permutation Matrix

P is simply a permuted (row-swapped) version of identity matrix, I.

e.g. to swap rows 2 and 3 of a 3x3 matrix, swap rows 2 and 3 of I.

$$P = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$

Multiplying with a matrix performs the same swap:

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 2 & 3 & 1 \\ 1 & 2 & 2 \\ 5 & 4 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 3 & 1 \\ 5 & 4 & -1 \\ 1 & 2 & 2 \end{bmatrix}$$

Solving with the new factorization

Given the factorization PA = LU, multiplying Ax = b by P shows that PAx = Pb.

Using our factorization to replace PA, we have LUx = Pb.

Solve by first permuting entries of b according to P.

Then forward and backward substitution lets us find x as usual.

How do we determine *P* during factorization?

Finding the permutation matrix, P

Start with P set to be an $n \times n$ identity matrix, I.

Whenever we swap a pair of rows during LU factorization, also swap the corresponding rows of P (including the already stored factors).

The final P will be the desired permutation matrix.

Example with pivoting

Let's try an example!

$$\begin{bmatrix} 1 & 4 & 5 \\ -2 & 3 & 3 \\ 3 & 0 & 6 \end{bmatrix} x = \begin{bmatrix} 4 \\ 1 \\ -3 \end{bmatrix}$$

Summary: Gaussian Elimination with Row Pivoting

- 1. Perform LU factorization on A to find P, L, and U.
- 2. Solve Lz = Pb for z. (Forward Solve.)
- 3. Solve Ux = z for x. (Backward Solve.)

Matlab's built-in LU factorization is the command: [L,U,P] = lu(A);

Costs of Gaussian Elimination

We want to know the (asymptotic) cost to solve a system of size $n \times n$.

We will measure cost in total *FLOPs: FLoating point OPerations*. Approximate as the number of: *adds+subtracts+multiplies+divides*.

A true operation count would be hardware-dependent.

• e.g. Fused-multiply-add (FMA) may be a single operation.

(Careful: FLOPS is also floating-point-operations-per-second.)

Cost of Factorization

For
$$k = 1, ..., n$$

For $i = k + 1, ..., n$
 $mult := a_{ik}/a_{kk}$
 $a_{ik} := mult$
For $j = k + 1, ..., n$
 $a_{ij} := a_{ij} - mult * a_{kj}$
EndFor
EndFor
EndFor

2 FLOPs (1 subtraction, 1 multiply) in the innermost loop.

Summing over all the loops we get:

$$\sum_{k=1}^{n} \sum_{i=k+1}^{n} \sum_{j=k+1}^{n} 2 = \frac{2n^3}{3} + O(n^2)$$

The above requires using the following sum identities...

$$\sum_{i=1}^{n} i = \frac{n(n+1)}{2}$$
and
$$\sum_{i=1}^{n} i^{2} = \frac{n(n+1)(2n+1)}{6}$$