Knapsack Problem	Solution .	 	 20
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Chapter 3: Brute Force

Adequacy is sufficient. (Adam Osborne)

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Introduction

Brute force is a straightforward approach to solving a problem without regard for efficiency. Example: an O(n) algorithm for a^n :

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Bubble Sort and Selection Sort

Bubble Sort

My bubble sort varies from the book.

```
 \begin{tabular}{ll} \textbf{algorithm} & BubbleSort(A[0..n-1])\\ & // & Sorts a given array by bubble sort\\ & // & Input: & An array $A$ of orderable elements\\ & // & Output: & Array $A[0..n-1]$ in ascending order <math display="block"> sorted \leftarrow \textbf{false}\\ & \textbf{while} \neg sorted \ \textbf{do}\\ & sorted \leftarrow \textbf{true}\\ & \textbf{for} \ j \leftarrow 0 \ \textbf{to} \ n-2 \ \textbf{do}\\ & \textbf{if} \ A[j] > A[j+1] \ \textbf{then}\\ & swap \ A[j] \ and \ A[j+1]\\ & sorted \leftarrow \textbf{false} \\ \end{tabular}
```

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Correctness of Bubble Sort

- \Box If A is not sorted, sorted is set to false, and loop continues.
- □ Once a pair of elements are swapped, they won't be swapped again.
- $\ \square$ n elements have n(n-1)/2 different pairs, so at most n(n-1)/2 swaps, so loop must eventually exit.
- \square The number of comparisons is $\Theta(n^2)$. See book.

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Selection Sort

```
 \begin{tabular}{ll} \textbf{algorithm} & SelectionSort(A[0..n-1])\\ & // & Sorts a given array by selection sort\\ & // & Input: & An array $A$ of orderable elements\\ & // & Output: & Array $A[0..n-1]$ in ascending order\\ & \textbf{for } i \leftarrow 0 \ \textbf{to } n-2 \ \textbf{do}\\ & & min \leftarrow i\\ & \textbf{for } j \leftarrow i+1 \ \textbf{to } n-1 \ \textbf{do}\\ & & \textbf{if } A[j] < A[min] \ \textbf{then } min \leftarrow i\\ & & swap $A[i]$ and $A[min]$ \end{tabular}
```

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Efficiency of Selection Sort

- \Box Correct because A[i] is minimum of A[i..n-1].
- \Box The i=0 pass (outer loop iteration) performs n-1 comparisons.
- $\ \square$ The i=1 pass performs n-2 comparisons.
- \square The last i = n 2 pass performs 1 comparison.
- \Box The number of comparisons C(n) is $\Theta(n^2)$.

$$C(n) = \sum_{i=0}^{n-2} (n-1-i) = \sum_{k=1}^{n-1} k = \frac{(n-1)n}{2} \approx \frac{n^2}{2}$$

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Brute-Force String Matching

Analysis of Brute-Force String Matching

- \Box Correct because every possible index i is checked.
- \Box i=n-m is the highest possible index.
- $\ \square$ At worst, m comparisons are made for a given value of i.
- \Box There are n-m+1 values for i.
- \square The number of comparisons is $\leq m(n-m+1) \leq mn \in O(mn)$.

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Closest-Pair and Convex-Hull

Closest Pair Problem

- \Box A point (2D case) is an ordered pair of values (x, y).
- \square The (Euclidean) distance between two points $P_i = (x_i, y_i)$ and $P_j = (x_i, y_j)$ is:

$$d(p_i, p_j) = \sqrt{(x_i - x_j)^2 + (y_i - y_j)^2}$$

- $\hfill\Box$ The closest-pair problem is finding the two closest points in a set of n points.
- $\hfill\Box$ The brute force algorithm checks every pair of points, which will make it $\Theta(n^2).$
- □ We can avoid computing square roots by using squared distance.

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Closest-Pair Brute-Force Algorithm

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The Convex Hull Problem

- □ A region (set of points) in the plane is *convex* if every line segment between two points in the region is also in the region.
- \Box The convex hull of a finite set of points P is the smallest convex region containing P.
- \Box Theorem: The *convex hull* of a finite set of points P is a convex polygon whose vertices is a subset of P.
- \Box The *convex hull problem* is finding the convex hull given P.

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Examples of Convex Sets

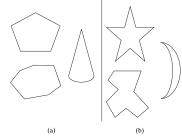


FIGURE 3.4 (a) Convex sets. (b) Sets that are not convex.

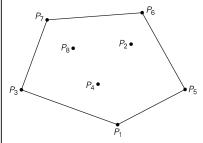
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Example of Convex Hull



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Idea for Solving Convex Hull

- \Box Consider the straight line that goes through two points P_i and P_i .
- \Box Suppose there are points in P on both sides of this line.
 - This implies that the line segment between P_i and P_j is not on the boundary of the convex hull.
- \Box Suppose all the points in P are on one side of the line (or on the line).
 - This implies that the line segment between P_i and P_j is on the boundary of the convex hull.

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Development of Idea for Convex Hull

 $\hfill\Box$ The straight line through $P_i=(x_i,y_i)$ and $P_j=(x_j,y_j)$ can be defined by a nonzero solution for:

$$a x_i + b y_i = c$$

$$a x_j + b y_j = c$$

- $\quad \square \quad \text{One solution is } a=y_j-y_i\text{, } b=x_i-x_j\text{, and } c=x_iy_j-y_ix_j.$
- The line segment from P_i to P_j is on the convex hull if either $a\,x+b\,y\geq c$ or $a\,x+b\,y\leq c$ is true for all the points.
- \square Brute force algorithm is $\Theta(n^3)$. See book.

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Exhaustive Search

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Exhaustive Search

- □ *Exhaustive search* generates all combinatorial objects (e.g., permutations, combinations, subsets) for a problem.
- $\ \square$ The traveling salesman problem (TSP) is finding the shortest tour through n cities
 - Brute Force Approach: Calculate the distance of all cycles of n vertices in a weighted graph.
- $\hfill\Box$ The knapsack problem is finding the most valuable subset of items \leq a given weight.
 - Brute Force Approach: Calculate the value and weight of all subsets.

TSP Example

TSP Solution

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 Tour
 Length

 $a \rightarrow b \rightarrow c \rightarrow d \rightarrow a$ I = 2 + 8 + 1 + 7 = 18

 $a \rightarrow b \rightarrow d \rightarrow c \rightarrow a$ I = 2 + 3 + 1 + 5 = 11 optimal

 $a \rightarrow c \rightarrow b \rightarrow d \rightarrow a$ I = 5 + 8 + 3 + 7 = 23

 $a \rightarrow c \rightarrow d \rightarrow b \rightarrow a$ I = 5 + 1 + 3 + 2 = 11 optimal

 $a \rightarrow d \rightarrow b \rightarrow c \rightarrow a$ I = 7 + 3 + 8 + 5 = 23

FIGURE 3.7 Solution to a small instance of the traveling salesman problem by exhaustive

/ = 7 + 1 + 8 + 2 = 18

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