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OpenClaw Adapter – E-T Systems Module Integration for OpenClaw Skills

Bridges the framework-agnostic NGEcosystem to OpenClaw's skill interface.
Any E-T Systems module that wants to function as an OpenClaw skill vendors
this file alongside `ng_ecosystem.py` and `ng_lite.py`.

The adapter provides the standard OpenClaw skill vocabulary:

```
on_message(text)  → process one conversation turn
recall(text)      → semantic context retrieval
stats()           → telemetry for OpenClaw's skill system
```

It also writes structured JSONL events to `{workspace}/memory/events.jsonl`
so OpenClaw's memory system can parse activity without stdout scraping.

Usage (inside a module's `openclaw` hook file):

```
from openclaw_adapter import OpenClawAdapter

class TrollGuardHook(OpenClawAdapter):
    MODULE_ID = "trollguard"
    SKILL_NAME = "TrollGuard Security"
    WORKSPACE_ENV = "TROLLGUARD_WORKSPACE_DIR"
    DEFAULT_WORKSPACE = "~/openclaw/trollguard"

    def _embed(self, text: str) -> "np.ndarray":
        # Return your module's embedding for text.
        # If you have no embedder, use the fallback:
        return self._hash_embed(text)

    def _module_on_message(self, text: str, embedding: "np.ndarray") -> dict:
        # Module-specific processing (scan, route, classify, etc.)
        # Return a dict to merge into the on_message result.
        return {}

    def _module_stats(self) -> dict:
        # Module-specific stats to merge into stats().
        return {}

# Singleton wiring – identical across all modules:
_INSTANCE = None

def get_instance():
    global _INSTANCE
```

```

    if _INSTANCE is None:
        _INSTANCE = TrollGuardHook()
    return _INSTANCE

```

Then in SKILL.md, autoload: true and set the hook to this file.
 OpenClaw calls `get_instance().on_message(text)` on every turn.

Canonical source: <https://github.com/greatnorthernfishguy-hub/NeuroGraph>
 License: AGPL-3.0

```

# ---- Changelog ----
# [2026-02-22] Claude (Sonnet 4.6) - Initial creation.
#   What: OpenClawAdapter ABC - base class for all E-T Systems module
#         OpenClaw hooks. Provides on_message(), recall(), stats(),
#         memory event logging, and embedding fallback. Subclasses
#         supply MODULE_ID, WORKSPACE_ENV, _embed(), _module_on_message(),
#         and _module_stats().
#   Why: Each module was implementing the OpenClaw hook pattern from
#         scratch. This standardizes the interface so OpenClaw sees
#         identical vocabulary from every E-T Systems skill, and modules
#         only implement what's unique to them.
#   Settings: auto_save_interval=10 messages (matches NeuroGraph's own
#         hook; balances persistence safety vs I/O overhead).
#   How: ABC with abstract properties + three hook methods. NGEcosystem
#         is initialized in __init__ via ng_ecosystem.init(). Memory
#         event log written to {workspace}/memory/events.jsonl - OpenClaw
#         standard location, same as NeuroGraph's own hook.
# -----
"""

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from __future__ import annotations

```

```

import json
import logging
import os
import time
from abc import ABC, abstractmethod
from pathlib import Path
from typing import Any, Dict, Optional

```

```

import numpy as np

```

```

logger = logging.getLogger("openclaw_adapter")

```

```

class OpenClawAdapter(ABC):
    """Base class for OpenClaw skill hooks over NGEcosystem.

```

Subclass this in each module. Override:

MODULE_ID	- module identifier string (required)
SKILL_NAME	- human-readable name for logs/stats (required)
WORKSPACE_ENV	- env var name for workspace dir (required)
DEFAULT_WORKSPACE	- fallback workspace path (required)
_embed(text)	- return np.ndarray embedding for text (required)
_module_on_message	- module-specific processing per message (optional)
_module_stats	- module-specific stats dict (optional)

Do NOT override on_message(), recall(), or stats() directly.

"""

--- Override in subclass ---

MODULE_ID: str = ""

SKILL_NAME: str = ""

WORKSPACE_ENV: str = ""

DEFAULT_WORKSPACE: str = ""

AUTO_SAVE_INTERVAL: int = 10 # messages between auto-saves

def __init__(self) -> None:

if not self.MODULE_ID:

raise ValueError("Subclass must set MODULE_ID")

Workspace

ws_raw = os.environ.get(self.WORKSPACE_ENV, self.DEFAULT_WORKSPACE)

self._workspace = Path(ws_raw).expanduser()

self._workspace.mkdir(parents=True, exist_ok=True)

(self._workspace / "memory").mkdir(exist_ok=True)

self._events_log = self._workspace / "memory" / "events.jsonl"

NGEcosystem (shared with the rest of the module)

import ng_ecosystem

self._eco = ng_ecosystem.init(

module_id=self.MODULE_ID,

state_path=str(self._workspace / "ng_lite_state.json"),

)

self._message_count = 0

self._start_time = time.time()

logger.info("[%s] OpenClawAdapter ready (tier %d)", self.MODULE_ID, self.

Abstract methods - module must implement

```

@abstractmethod
def _embed(self, text: str) -> np.ndarray:
    """Return a normalized np.ndarray embedding for text.

    If your module has no embedder, call self._hash_embed(text) as
    a zero-dependency fallback.
    """
    ...

def _module_on_message(self, text: str, embedding: np.ndarray) -> Dict[str, A
    """Module-specific processing for each message.

    Override to run your module's core logic (scan, route, classify...).
    The return dict is merged into the on_message() result.
    Default: no-op.
    """
    return {}

def _module_stats(self) -> Dict[str, Any]:
    """Module-specific stats to merge into stats(). Default: no-op."""
    return {}

# -----
# OpenClaw skill interface
# -----

def on_message(self, text: str) -> Dict[str, Any]:
    """Process one OpenClaw conversation turn.

    Called by OpenClaw on every user message. Embeds text, runs
    ecosystem learning, runs module-specific processing, logs event.

    Returns:
        {
            "status":      "ingested" | "skipped",
            "tier":        int,
            "tier_name":   str,
            "message_count": int,
            "module_results": dict (from _module_on_message),
            "recommendations": list,
            "novelty":     float,
        }
    """
    if not text or not text.strip():
        return {"status": "skipped", "tier": self._eco.tier, "message_count":

    self._message_count += 1

```

```

embedding = self._embed(text)

# Record to ecosystem (Tier 1/2/3 transparently)
self._eco.record_outcome(
    embedding,
    target_id=f"message:{self._message_count}",
    success=True,
    metadata={"source": "openclaw", "module": self.MODULE_ID},
)

# Module-specific processing
module_results = self._module_on_message(text, embedding)

# Context from ecosystem
ctx = self._eco.get_context(embedding)

result = {
    "status": "ingested",
    "tier": self._eco.tier,
    "tier_name": self._eco.tier_name,
    "message_count": self._message_count,
    "module_results": module_results,
    "recommendations": ctx["recommendations"],
    "novelty": ctx["novelty"],
}

self._write_event("message", result)

# Auto-save
if self._message_count % self.AUTO_SAVE_INTERVAL == 0:
    self._eco.save()

return result

def recall(self, query: str, top_k: int = 5) -> Dict[str, Any]:
    """Retrieve cross-module context for a query.

    Called by OpenClaw when context retrieval is requested.

    Returns:
        {
            "tier": int,
            "recommendations": list of (target_id, confidence, reasoning),
            "novelty": float,
            "ng_context": str | None (Tier 3 only),
        }
    """

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        embedding = self._embed(query)
        ctx = self._eco.get_context(embedding, top_k=top_k)
        self._write_event("recall", {"query": query[:200], **ctx})
        return ctx

def stats(self) -> Dict[str, Any]:
    """Return unified stats for OpenClaw skill telemetry."""
    eco = self._eco.stats()
    module = self._module_stats()
    uptime = time.time() - self._start_time
    return {
        "skill": self.SKILL_NAME,
        "module_id": self.MODULE_ID,
        "uptime_seconds": round(uptime, 1),
        "message_count": self._message_count,
        "workspace": str(self._workspace),
        "ecosystem": eco,
        "module": module,
    }

# -----
# Memory event logging (OpenClaw standard)
# -----

def _write_event(self, event_type: str, data: Dict[str, Any]) -> None:
    """Append a structured event to the memory/events.jsonl log."""
    event = {
        "ts": time.time(),
        "type": event_type,
        "module": self.MODULE_ID,
        **data,
    }
    try:
        with open(self._events_log, "a") as f:
            f.write(json.dumps(event) + "\n")
    except Exception as exc:
        logger.debug("Event log write failed: %s", exc)

# -----
# Embedding fallback (zero-dependency)
# -----

def _hash_embed(self, text: str, dims: int = 384) -> np.ndarray:
    """Hash-based embedding fallback requiring only numpy + stdlib.

    Produces a deterministic, normalized vector from text.
    Lower quality than sentence-transformers but always available.

```

Use when your module has no dedicated embedder.

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"""
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```
import hashlib
```

```
rng_seed = int(hashlib.sha256(text.encode()).hexdigest(), 16) % (2**32)
```

```
rng = np.random.RandomState(rng_seed)
```

```
vec = rng.randn(dims).astype(np.float32)
```

```
norm = np.linalg.norm(vec)
```

```
return vec / norm if norm > 0 else vec
```