

Natural Language Processing: RLHF

HSE Faculty of Computer Science Machine Learning and Data-Intensive Systems

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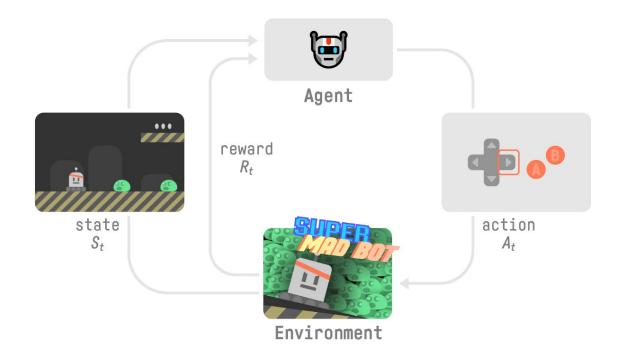
- Intro to RL
- RLHF pipeline
- PPO
- DPO



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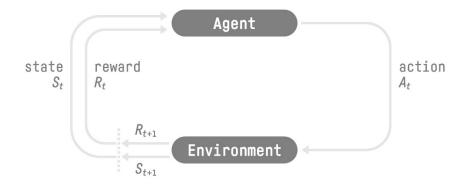
An Agent acts upon an Environment, changes the State and gets a Reward







An Agent acts upon an Environment, changes the State and gets a Reward



Where to learn more?

- Deep RL Course by HF
- YSDA Practical RL



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RLHF consists of 3 main steps: SFT, RM, RL

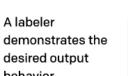
Step 1

Collect demonstration data, and train a supervised policy.

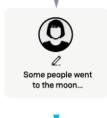
A prompt is sampled from our prompt dataset.

A labeler

behavior.



This data is used to fine-tune GPT-3 with supervised learning.



Explain the moon

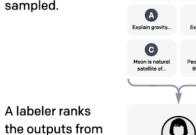
landing to a 6 year old



Step 2

Collect comparison data, and train a reward model.

A prompt and several model outputs are sampled.

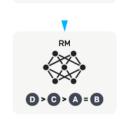


Explain the moon

landing to a 6 year old

This data is used to train our reward model.

best to worst.



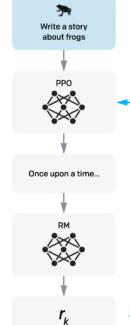
D>G>A=B

Step 3

Optimize a policy against the reward model using reinforcement learning.

A new prompt is sampled from the dataset.

The policy generates an output.

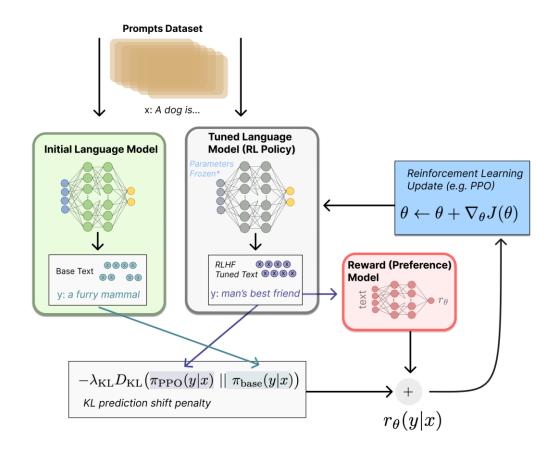


The reward model calculates a reward for the output.

The reward is used to update the policy using PPO.

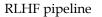


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SFT

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Step 1: Train an initial model with Supervised Finetuning

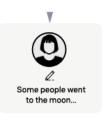
Step 1

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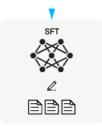
A prompt is sampled from our prompt dataset.

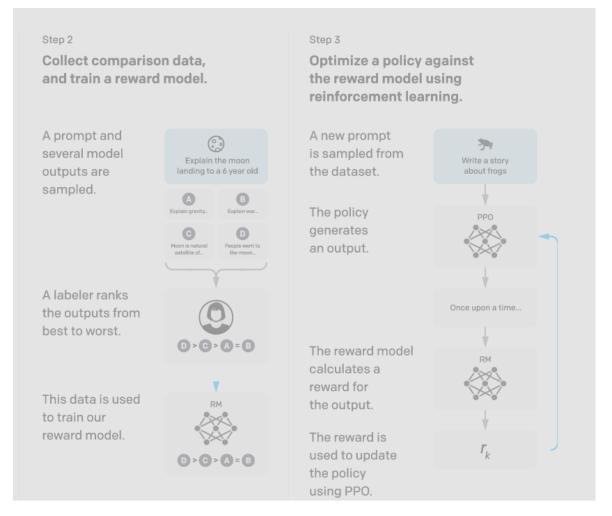


A labeler demonstrates the desired output behavior.



This data is used to fine-tune GPT-3 with supervised learning.



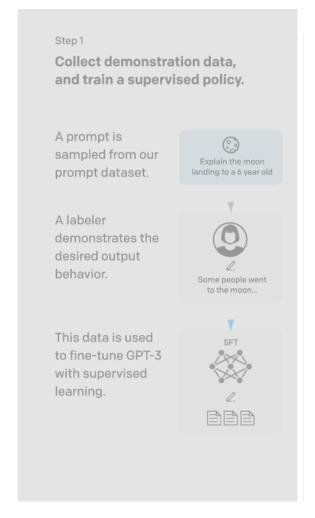


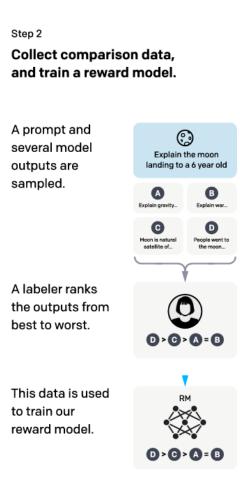
Source: https://arxiv.org/abs/2203.02155

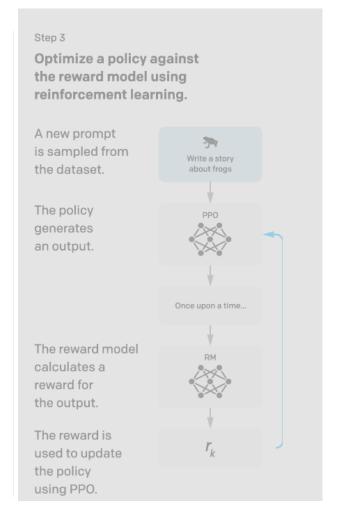
RLHF pipeline



Step 2: Train a Reward Model







Source: https://arxiv.org/abs/2203.02155



Reward Model learns to differentiate between winner's and loser's scores

$$loss(\theta) = -\frac{1}{\binom{K}{2}} E_{(x,y_w,y_l)\sim D} \left[log\left(\sigma\left(r_\theta\left(x,y_w\right) - r_\theta\left(x,y_l\right)\right)\right)\right]$$



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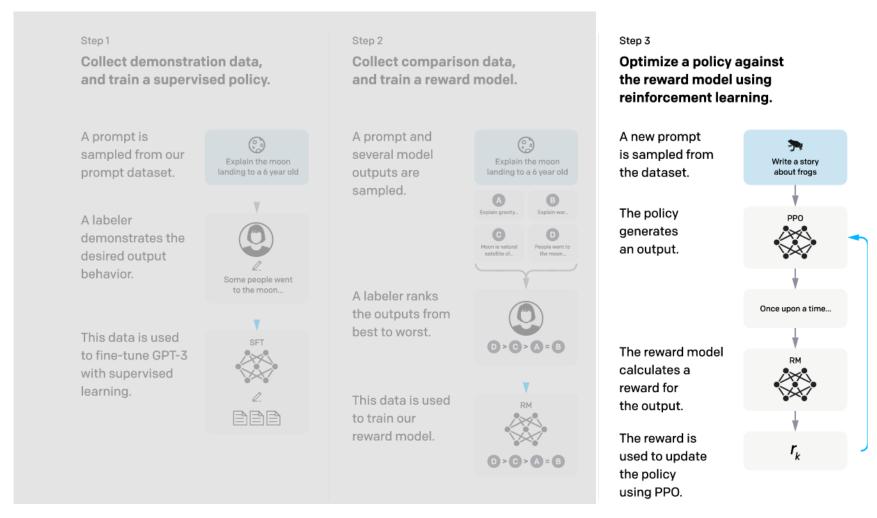
...see the whiteboard for more!



RL

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Source: https://arxiv.org/abs/2203.02155



Leverage a vanilla Proximal Policy Optimization setup

objective
$$(\phi) = E_{(x,y) \sim D_{\pi_{\phi}^{RL}}} \left[r_{\theta}(x,y) - \beta \log \left(\pi_{\phi}^{RL}(y \mid x) / \pi^{SFT}(y \mid x) \right) \right]$$



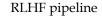
Add regularization via pretrain tasks to prevent deterioration

objective
$$(\phi) = E_{(x,y)\sim D_{\pi_{\phi}^{\text{RL}}}} \left[r_{\theta}(x,y) - \beta \log \left(\pi_{\phi}^{\text{RL}}(y \mid x) / \pi^{\text{SFT}}(y \mid x) \right) \right] + \gamma E_{x\sim D_{\text{pretrain}}} \left[\log(\pi_{\phi}^{\text{RL}}(x)) \right]$$

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RL



Your Language Model is Secretly a Reward Model

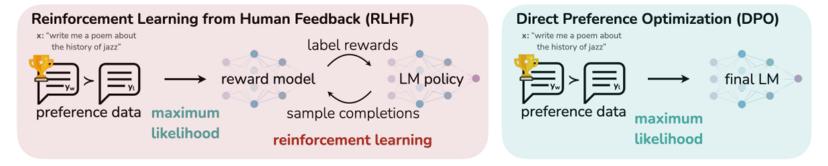


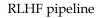
Figure 1: **DPO optimizes for human preferences while avoiding reinforcement learning.** Existing methods for fine-tuning language models with human feedback first fit a reward model to a dataset of prompts and human preferences over pairs of responses, and then use RL to find a policy that maximizes the learned reward. In contrast, DPO directly optimizes for the policy best satisfying the preferences with a simple classification objective, fitting an *implicit* reward model whose corresponding optimal policy can be extracted in closed form.



Your Language Model is Secretly a Reward Model

$$\mathcal{L}_{\text{DPO}}(\pi_{\theta}; \pi_{\text{ref}}) = -\mathbb{E}_{(x, y_w, y_l) \sim \mathcal{D}} \left[\log \sigma \left(\beta \log \frac{\pi_{\theta}(y_w \mid x)}{\pi_{\text{ref}}(y_w \mid x)} - \beta \log \frac{\pi_{\theta}(y_l \mid x)}{\pi_{\text{ref}}(y_l \mid x)} \right) \right]$$

...see the whiteboard for more!





Your Language Model is Secretly a Reward Model

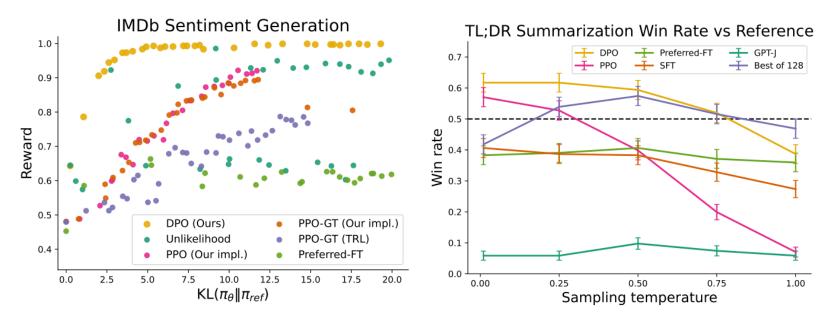


Figure 2: **Left.** The frontier of expected reward vs KL to the reference policy. DPO provides the highest expected reward for all KL values, demonstrating the quality of the optimization. **Right.** TL;DR summarization win rates vs. human-written summaries, using GPT-4 as evaluator. DPO exceeds PPO's best-case performance on summarization, while being more robust to changes in the sampling temperature.

