

# Touch Tap See : A Navigation Assistant for the Visually Impaired person

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**Abstract.** With the exponential advancements in technology each year, a plethora of applications have been developed ranging from the most basic to the most advanced use cases. The amelioration in the smartphone industry has proven to be a major factor in the rapid development of mobile applications. Although technology has been evolving, we are yet to see a big break in the medical field to help the visually impaired people. The visually impaired person misses many opportunities because of a lack of confidence or dependence on others. The proposed work is aiming at reducing this dependence and at the same time improving the confidence of visually impaired person by enabling them to use their other sensory organs to understand their surroundings. The proposed application “Navigation Assistant for Visually impaired Person- Touch Tap See” is aimed at providing real-time assistance to a visually impaired person at workplaces or Educational Institutes, which are generous to offer the opportunity to them along with other common people.

**Keywords:** Navigation assistant, indoor navigation, visually impaired, firebase, mobile application.

## 1 Introduction

Technology evolves quite rapidly. With the exponential increase in technology, we can say that new innovation is being produced every day. These technologies play a

vital role in our lives as they help reshape our world and make a better future. Based on the data as of in 2018, 1.3 billion people in the world suffer from some type of visual impairment. These visually impaired people encounter various problems when it comes to navigation due to dependency on various people for guidance. Functioning in new environments poses a great challenge for them as they are unable to navigate the environment independently. There have been significant attempts to encounter this problem but no concrete results have been achieved.

The proposed navigation assistant-“Touch Tap See” will be responsible for guiding the visually impaired person to understand the surroundings so that the person using application can independently and confidently reach his/her destination. For this purpose, the system is designed using android application which will be taking inputs from Bluetooth beacons placed in the appropriate locations to get the current location of the user. The navigation will be based on the destination user will have to provide using voice command to the application. The application will be making blended use of sensors commonly present in any Smart Phone such as Bluetooth transceivers, GPS sensors to figure out the most suitable path from the current location to the desired destination. Accordingly, the voice instructions will be given to the user. When the user will actually walk on the path suggested by application the application will assist by voice suggestions to the user regarding the path to be taken in detail. This will be done by communication between the Bluetooth beacons and the Mobile device. This application will also be supported by another electronic unit, which will provide the information in terms of vibrations to the end user. This unit will work in standalone fashion to provide confidence to the user as well as avoid dependence on a single source of assistance.

## **2 Related Work**

Several innovations have been proposed to help the visually impaired. In [1] Dr. Stephen Hicks, from the University of Oxford, has created a pair of glasses which can help visually impaired people in better understanding their surroundings, thus starting an initiative to make them independent. Most visually impaired people can differentiate bright and dark light. These glasses increase the brightness in an attempt to let the wearer understand the presence of an obstacle in front of them. In [2], the technology consists of a chunky ring that helps a visually impaired person to read a normal book. The ring transcribes a 12-point letter and reads the word out loud. It also informs the user if his finger diverges from a line. This is currently in the prototype stage. In [3],[4], The ARIANNA app (pAth Recognition for Indoor Assisted NavigatioN with Augmented perception) solves the potential problem of using GPS indoors. It uses colored tape to mark the routes inside the house. The users of the app just have to point their smartphone cameras and once the camera detects a colored tape, it will notify the user of the direction that he has to go in. In [5], Travi-Navi is a vision-guided navigation system that enables a user to easily deploy indoor navigation services. In [6], peer to peer navigation technology has been used in order to help the user navigate to a particular location. In [7], iMoon creates a navigation mesh which

gets generated from 3-D models which are obtained from 2-D photos taken by people. It has been suggested in article [8] by Dragan Ahmetovic navigation assistance to visually impaired can be effectively provided by use of Bluetooth based systems.

In summary of the papers reviewed, it is established that the implementation of computational geometry, artificial intelligence and ultrasound techniques is to be incorporated but the user-oriented approach has been minimal and instead other external obstacles have been addressed.

### 3 PROPOSED SYSTEM

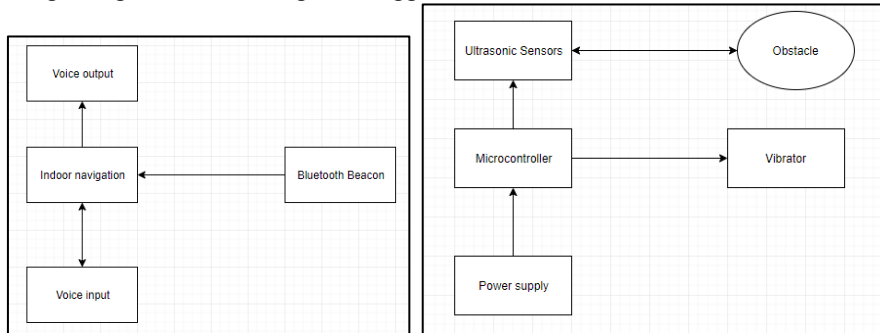
In this paper, the Touch-Tap-See is proposed, that provides an enhanced sense of the navigation environment which works with the help of Bluetooth beacons<sup>[8]</sup> for the indoor navigation of the environment. It also uses a Firebase database for the purpose of location sharing. Whenever the user enters the building which is equipped with Bluetooth beacons and opens the application, various markers related to nearby locations will be displayed on the map and will be intimated to the user using voice-over. Upon selection of a certain location, the path to that location will be displayed on the screen and voice instructions will be given accordingly to the application user. We propose the use of Ultrasonic sensors<sup>[9]</sup> for obstacle detection which will run on a separate base and provide a better understanding of the environment.

The system is divided into two subsystems:

- The Mobile Application –Touch Tap See
- A standalone obstacle avoidance Module

The Assistance provided by the Obstacle avoidance module which is proposed as a standalone wristband will be generating alerts in the form of vibrations generated by output actuators. The purpose of this module is to avoid the complete dependency on mobile application and the Bluetooth beacons installed in the vicinity.

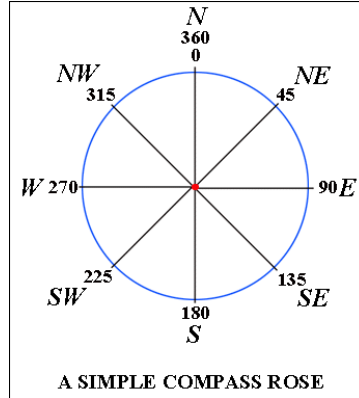
The mobile application will be responsible for providing voice assistance to the user regarding the indoor navigation suggestions.



**Fig. 1.** Mobile Application block diagram **Fig. 2.** Standalone obstacle avoidance Module

## 4 Algorithm Used

The main objective of the algorithm is to generate way points<sup>[10]</sup> and calculate shortest possible path between source and destination. This algorithm is used as it provides accurate results in short span of time.



**Fig. 3.** Compass rose

1. The direction is calculated in ENU coordinates or bearings. In simple words, North is 0 degree, East is 90.
2. Rotation is calculated in the same format.
3. We find the difference and use the below logic in left, right, back, straight.
4. We have created a simple algorithm wherein first we add different legs and then find the nearest leg available.
5. To reach the nearest leg, the approximate distance is calculated from the current leg to the nearest leg and then using text to speech, the corresponding command is given.
6. The same direction is also visible on the application screen.

## 5 System Architecture

TouchTapSee system architecture which was briefly discussed in the introduction consists of the following components: Database, Android Client, Bluetooth Beacon.

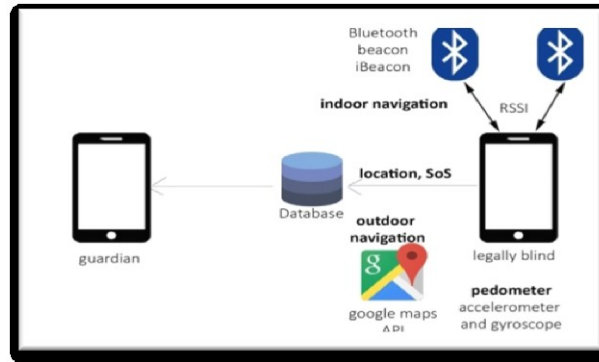


Fig. 4. TouchTapSee architecture

### 5.1 Database:

The database is used to store the client information such as his/her login details and also to share the geographical location.

### 5.2 Android Smartphone:

Components of the software implemented in the Android Smartphone are as follows:

- Bluetooth module*: This module is responsible for exchanging data between the Android Smartphone and the Bluetooth Beacon.
- TouchTapSee application*: This application has various events which can be chosen by the user. The events are processed locally, and the output is converted into an audio form.
- Text To Speech Engine*: as the TouchTapSee system is designed to assist the legally blind, the interaction between the user and the smartphone is done with the help of voice commands.

## 6 Implementation Tools

Keeping in mind the advanced technologies available for providing sleek, modern and efficient functionalities, the system has taken advantage of the following technologies to develop this application:

### 6.1 Android Studio:

It is the officially integrated development environment (IDE) for Google's Android operating system, built on JetBrains' IntelliJ IDEA software and designed specifically

for Android development. It gave us the required options with ease to implement the project.

## 6.2 Google Firebase:

Firebase Cloud Storage provides features to quickly and easily store and serve user-generated content, such as photos and videos, effortlessly grow from prototype to production using the same technology. Real-time syncing of data is required in order to achieve real-time location sharing which is done through Firebase Real-time Database which is a cloud-hosted NoSQL database that lets you store and sync JSON data between users in real time. NoSQL feature provides flexibility in the schema of the database.

## 6.3 IndoorAtlas:

IndoorAtlas is an open source indoor positioning platform for mobile applications providing features like indoor positioning, wayfinding, geofencing, asset tracking, and location intelligence.

# 7 Compare and Contrast

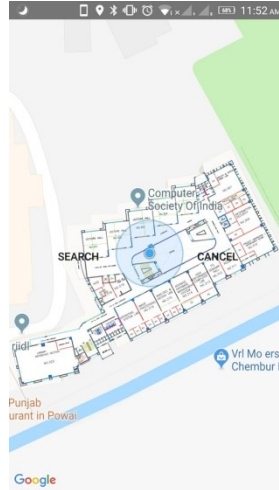
The proposed system is compared with the existing systems in the same area the observations are presented in the following table.

Table 1 Comparison with existing systems.

Comparison Factor	Ariana App	TouchTapSee	Travi Navi
Tactile Interface	✓	✗	✓
Haptic Feedback	✓	✓	✓
Augmented Reality	✓	✗	✗
Phone Camera not required	✗	✓	✗
QR Code not required	✗	✓	✓
Stable net connection required	✗	✓	✗
Marker Tape not Required	✗	✓	✓
Voice-activated Commands	✗	✓	✗

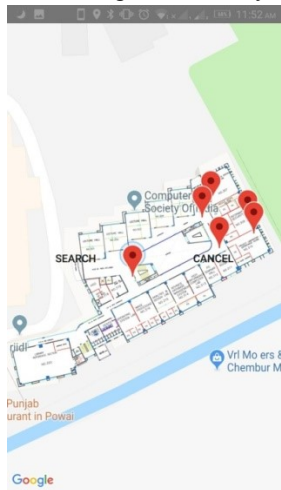
## 8 Results and discussion

The Application Touch Tap See is implemented and tested. The results of the proposed system prototype are fairly promising. The floor map was effectively used to mark the locations nearby. The bluetooth beacons provided the required accuracy with least power consumption.



**Fig. 5.** User location during indoor navigation

This is how the map will initially appear before the search is made.



**Fig. 6.** Highlighted Waypoints **Fig.**



**7.** Path from Source to Destination

Above figures shows how it appears after the location has been identified via Bluetooth beacons and how the path looks like from the current location to the place which is searched for

## **9 Future Scope**

The final outcome of the research work is expected to be a navigation assistant consisting of a Mobile app and a wearable obstacle avoidance unit which will assist the blind person to navigate himself independently in the indoor area. We plan to include more detailed assistance to blind people such as briefing the blind person about the place he or she is currently positioned and the path he /she will take to reach the destination. The system can be made offline (not using mobile data) using the network signal of the network service provider. The way-finding algorithm can be extended to process the distance data measured as per the signal strength of the network. Availability of data services is a major issue going ahead for the system to work at a mass scale.

## **10 Conclusion**

The current systems available in the market are not viable options for everyone since they are paid and provide very less accuracy. Wayfinding algorithm gives a much higher accuracy compared to the generalized algorithms used in the available systems. Obstacle detection as well as indoor and outdoor navigation provides an overall package in order to lead a productive and efficient life. Application crashes are effectively handled by obstacle detection module which negates complete dependency on the application. Hence the proposed system provides a robust solution to the problem faced by visually impaired people in handling their basic requirements of indoor navigation. Thus the system serves as a helping hand and also maintains the dignity of visually impaired person.

## **11 Acknowledgement**

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