

Physics 622: General relativity

Today: Newtonian Gravity

$$m_a \ddot{\vec{r}}_a(t) = -G \sum_{b \neq a} \frac{m_a m_b (\vec{r}_b - \vec{r}_a)}{|\vec{r}_b - \vec{r}_a|^3}$$

$a=1 \dots N$ particles plus mass to model it
 $G = \text{Newton's constant}$ $10^{-11} \frac{N \cdot m^2}{kg^2} = 1$

Particle = point in space $\vec{r}_a(t)$

Newton: Space is 3D, Euclidean, invertible, homogeneous, isotropic ("featureless properties")
 Time + equal in all terms of equation ("scale-invariance")

Choose $t=0$: time is $t \in \mathbb{R}$

Choose origin O fixed point: Position is displaced \vec{r} from O $\vec{r}_a(t) \rightarrow$ new index s such

Choose \hat{e}_i basis right-hand orthogonal

$$\begin{aligned} \hat{e}_i \cdot \hat{e}_j &= \delta_{ij}, \quad ?\text{-tensor?} \quad \xrightarrow{\text{epsilon summation}} \\ e_i \times \hat{e}_j \cdot \hat{e}_k &= \epsilon_{ijk} \hat{e}_k \quad \xrightarrow{\text{implicit summation}} \end{aligned}$$

$$\vec{r} = \epsilon^{ijk} \hat{e}_i = (\vec{r} \cdot \hat{e}_i) \hat{e}_i$$

$$\begin{aligned} y = Ax &\iff y^i = A_{ij} x^j & x^i = y^i \\ y = A^T x &\iff y^i = A_{ij} x^j & \begin{array}{l} \uparrow \\ \begin{array}{l} \text{(meantime)} \\ \text{index imbalance!} \end{array} \end{array} \\ &\quad \uparrow \quad \begin{array}{l} \text{switch what you sum} \\ \text{over first} \end{array} \end{aligned}$$

$$m_a \ddot{\vec{r}}_a(t) = -G \sum_{b \neq a} \frac{m_a m_b (\vec{r}_b - \vec{r}_a)}{|\vec{r}_b - \vec{r}_a|^3}$$

3 dimensions
 N particles
 $3N$ ODEs $\vec{r}_a(t)$

Ex! solution given $6N$ initial conditions $\{\vec{r}_a(0)\} = \vec{r}_a$
 $\{\dot{\vec{r}}_a(0)\} = \vec{v}_{ao}$

Euclidean space: $|\vec{r}| = \sqrt{r^2}$ pythagorean

Invertible: Laws of Nature don't change with time

Set: $\vec{r}'_a(T) = \vec{r}_{ao}$ $\vec{r}'_a(t) = \vec{r}_a(t-T)$

$$\vec{r}'_a(t) = \vec{v}_{ao}$$

↑ would fail if Newton's constant was time-dependent!

If we choose $t=T$ to be $t'=0$ so $t'=t-T$, everything still works!

Some motion becomes $\vec{r}'_a(t) = \vec{r}_a(t+T)$

$$\frac{d}{dt} \left(\sum_a m_a \vec{r}_a \right) = \sum_a m_a \vec{v}_a$$

Conservation of energy!

$$= -G \sum_{a \neq b} \frac{\vec{r}_a \cdot \vec{r}_b}{|\vec{r}_a - \vec{r}_b|^3} = -\sum_a \vec{r}_a \cdot \vec{v}_a \phi$$

Energy is constant because
of time invariance!

$$\text{Consider } \phi(\vec{r}_a) = -G \sum_{a \neq b} \frac{m_a m_b (\vec{r}_b - \vec{r}_a)}{|\vec{r}_b - \vec{r}_a|^3}$$

$$-\vec{v}_a \phi = -G m_a \sum_{b \neq a} \frac{m_b (\vec{r}_b - \vec{r}_a)}{|\vec{r}_b - \vec{r}_a|^3}$$

$$m_a \vec{r}_a \dot{=} (-G \sum_{b \neq a} \frac{m_a m_b (\vec{r}_b - \vec{r}_a)}{|\vec{r}_b - \vec{r}_a|^3}) + \vec{F}_a(\vec{r}_a)$$

Without homogeneity

"Homogeneous, like homogenized milk, means it's the same everywhere"

= law of nature same everywhere

Action: more experiment, new initial conditions

$$\vec{r}_a(0) = \vec{r}_{a0} + \vec{\delta} \xrightarrow{\text{shift}} \text{constant} \quad \vec{r}'_a(t) = \vec{r}_a(t) + \vec{\delta} \quad \text{"deep shift, but true"}$$

$$\vec{r}'_a(0) = \vec{v}_{a0}$$

Passive choice of origin \mathcal{O}' immaterial

Choose \mathcal{O}' displaced by $\vec{\delta}$

Same motion described by $\vec{r}'_a = \vec{r}_a + \vec{\delta}$

$$\frac{d}{dt} \left(\sum_a m_a \vec{r}_a \right) = \sum_a m_a \vec{v}_a = \vec{0} \xrightarrow{\text{LHS of eqn above, antisymmetric so}} \text{Newton's 3rd law}$$

No gravitational interaction
in Newton physics \rightarrow problem
"speedy action at a distance"

Isotropic \rightarrow laws of nature same in all directions

rotate experiment \rightarrow same results!

Rotations: R linear action on vector

$$(Rv)^i = R^i_j v^j$$

Preserve lengths & angles

$$(Rv)^T (Rw) = v^T R^T R w = v^T w$$

$$R^T R = I \quad R \in O(3)$$

$$(Rv)^i (Rw)_j = v_i w_j = v^k \delta_{ik} \delta_{jk}$$

$$= (R^i_j v^j) (R_k^l w^l)$$

$$= R^i_j R_k^l v^j w^l \quad R^i_j R_k^l = \delta_{jk}$$

$$\det R^T = \det R = \pm 1$$

Rotations: $\det R = 1 \quad SO(3)$

$$P = \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \text{orthogonal but not rotation}$$

Active rotation: $\vec{r}_a'(t) = R_a^i \vec{r}_a^i(t)$

$$\dot{\vec{r}}_a^{i\prime}(t) = R_a^i \dot{\vec{r}}_a^i$$

$$\Rightarrow \vec{r}_a''(t) = R_a^i \vec{v}_a^i$$

Passive: $\hat{\vec{e}}_i' = R^i \vec{e}_i$

Consequence: conservation of angular momentum

$$\hat{L} = \sum_a m_a \vec{r}_a \times \dot{\vec{r}}_a \quad \frac{d\hat{L}}{dt} = 0$$

$$m_a \ddot{\vec{r}}_a(t) = -G \sum_{b \neq a} \frac{m_a m_b (\vec{r}_b - \vec{r}_a)}{|\vec{r}_b - \vec{r}_a|^3}$$

↓
vector
↓
vector

Change of basis: transform both sides by same R

$$\hat{\vec{A}} = \vec{B} \quad \hat{\vec{A}} - \vec{B} = 0$$

Stays zero if you rotate!

Galilean Relativity

$$\vec{r}_a(t) \rightarrow \vec{r}'_a(t) = \vec{r}_a(t) - \vec{\delta}(t)$$

$$\dot{\vec{r}}'(t) = \vec{r}_a(t) - \vec{\dot{\delta}}(t)$$

$$\ddot{\vec{r}}(t) = \ddot{\vec{r}}_a(t) - \cancel{\vec{\ddot{\delta}}(t)}$$

does not change

$$m_a \ddot{\vec{r}}_a(t) = -G \sum_{b \neq a} \frac{m_a m_b (\vec{r}_b - \vec{r}_a)}{|\vec{r}_b - \vec{r}_a|^3}$$

\swarrow same \searrow same

$$\ddot{\vec{r}}_{\text{same}}$$

Action: a point can move at constant \vec{v}

i.e. in relativistic physics, it never nothing to be at rest

Passive: can move from O' many at constant \vec{v} (relative to O)

to validate!

$$\begin{cases} t' = t + T \\ \vec{r}' = R \vec{r} + \vec{\delta} - \vec{v}T \end{cases}$$

Consequence? Homework, I guess...

$$m_a \ddot{\vec{r}}_a(t) = -G \sum_{b \neq a} \frac{m_b (\vec{r}_a - \vec{r}_b)}{|\vec{r}_a - \vec{r}_b|^3}$$

Gravity: pick t , $\vec{r}_a, \vec{r}_b \rightarrow$ can find $\ddot{\vec{r}}_a(t)$
dissolve when particles get very close!

If you change m_a , leave $m_b, \{\vec{r}_a\}$ unchanged
↓ will have same acceleration

$\vec{g}(t, \vec{r})$: any probe accelerates at \vec{g}
(say mass (relative))

Divergence → replace particles with smooth distributions of mass

$$m_a \vec{r}_a(t) \rightarrow \rho(\vec{r}, t) = \sum m_a \delta^{(4)}(\vec{r} - \vec{r}_a(t))$$

$N \rightarrow \infty$

$m_a \rightarrow 0$

Newtonian gravity invariant under $\frac{\text{Galilean Group}}{\text{Euclidean Group}}$

$$G(I, \vec{r}, R, \vec{v}):$$

$$\begin{aligned} + &\rightarrow +' = + - \underline{I} \\ \vec{r} &\rightarrow \vec{r}' = \underline{R}\vec{r} - \underline{\Delta} - \underline{\vec{v}t} \end{aligned}$$

10-dimensional group

identity element

$$G(0, \vec{0}, I, 0): \begin{array}{l} + \rightarrow + \\ \vec{r} \rightarrow \vec{r} \end{array}$$

Introduce a probe $m \ll m_a$ that at (t, \vec{r}) it will accelerate at

$$m \vec{g}(t, \vec{r}) = G \sum_a \frac{m_a (\vec{r}_a - \vec{r})}{|\vec{r}_a - \vec{r}|^3}$$

* Principle of Equivalence: if you move at (t, \vec{r}) with acceleration $\vec{g}(t, \vec{r})$, you are weightless

$$M_a \vec{r}_a(t) = -G \sum_{b \neq a} \frac{m_a m_b (\vec{r}_b - \vec{r}_a)}{|\vec{r}_b - \vec{r}_a|^3}$$

Continuum limit $N \rightarrow \infty$
 $m_a \rightarrow 0$

$$\rho(t, \vec{r}) = \sum_a m_a \delta^{(3)}(\vec{r} - \vec{r}_a(t)) \quad \sim \text{smooth function of space/time}$$

$$\int_V d^3 r \rho(t, \vec{r}) = \sum_a m_a \int_V d^3 r \delta^{(3)}(\vec{r} - \vec{r}_a(t)) = \sum_{a \in V} m_a$$

$$V_t = \left\{ a \mid \vec{r}_a(t) \in V \right\}$$

$$\frac{\partial}{\partial t} \rho(t, \vec{r}) = \sum_a m_a (-\dot{\vec{r}}_a(t)) \cdot \vec{\nabla} \delta^{(3)}(\vec{r} - \vec{r}_a(t)) \\ = -\vec{\nabla} \cdot \left(\sum_a m_a \dot{\vec{r}}_a(t) \delta^{(3)}(\vec{r} - \vec{r}_a(t)) \right)$$

$$\vec{\Pi}(t, \vec{r}) = \sum_a m_a \dot{\vec{r}}_a(t) \delta^{(3)}(\vec{r} - \vec{r}_a(t))$$

mass current
continuity equation = local mass conservation

Momentum density = mass current

$$\frac{\partial}{\partial t} \int_V d^3 r \rho(t, \vec{r}) = - \int_V d^3 r \vec{\nabla} \cdot \vec{\Pi}(t, \vec{r}) \\ = - \left(\frac{\partial \vec{\Pi}}{\partial t} \cdot d\vec{r} \right) \text{ mass locally conserved}$$

$$\text{Is } \vec{\Pi} = \sum_a m_a \dot{\vec{r}}_a(t) \delta^{(3)}(\vec{r} - \vec{r}_a(t)) \text{ conserved? (locally)}$$

$$\text{Of course: (conservation of mass)} \quad \frac{\partial}{\partial t} \left(\int_V d^3 r \vec{\Pi} \right) = \frac{\partial \vec{\Pi}}{\partial t} = 0$$

$$M_a \vec{F}_a(t) = \vec{F}_a(\{ \vec{r}_i \}) = -\vec{\nabla}_a U(\{ \vec{r}_i \})$$

$$\frac{\partial \vec{\Pi}^i}{\partial t} = \frac{\partial}{\partial t} \left(\sum_a m_a \dot{\vec{r}}_a^i(t) \delta^{(3)}(\vec{r} - \vec{r}_a(t)) \right)$$

$$\text{conserv: } \left[= \sum_a m_a \ddot{\vec{r}}_a^i(t) \delta^{(3)}(\vec{r} - \vec{r}_a(t)) \right]$$

$$\text{divergence: } \left[- \sum_a m_a \dot{\vec{r}}_a^i(t) \vec{\nabla}_a^i(t) \cdot \vec{\nabla} \delta^{(3)}(\vec{r} - \vec{r}_a(t)) \right]$$

$$\sum_a \vec{F}_a \delta^{(3)}(\vec{r} - \vec{r}_a(t))$$

Momentum
conserved...
but not locally
conserved

Einstein: "spooky"

$$\frac{\partial \vec{\Pi}^i(t, \vec{r})}{\partial t} + \vec{\nabla}_i \cdot \vec{\Pi}^i(t, \vec{r}) = \vec{f}^i(t, \vec{r})$$

$$\vec{f}^i = \sum_a \vec{F}_a \delta^{(3)}(\vec{r} - \vec{r}_a(t)) \text{ force density}$$

$$+^{ij} = t^{ij} = \sum_a m_a \hat{r}_a^i \hat{r}_a^j \delta^{(3)}(\vec{r} - \vec{r}_a(t))$$

Maxwell tensor

$$\begin{aligned} f(\vec{r}) &= \frac{1}{4\pi} f(\vec{r}(t)) \\ &= \frac{1}{4\pi} f(x(t), y(t), z(t)) \end{aligned}$$

$$\text{Under rotation } \vec{r} \rightarrow \vec{r}' = R \vec{r} \quad r'^i = R^i_j r^j$$

$$+^{ij}(t, \vec{r}') = R^i_k R^j_l +^{kl}(t, R^{-1} \vec{r}')$$

Given $\rho(t, \vec{r})$ determines

$$\vec{g}(t, \vec{r}) = G \int d\vec{r}' \frac{\rho(t, \vec{r}') (\vec{r}' - \vec{r})}{|\vec{r}' - \vec{r}|^3}$$

\vec{F} on m is $\vec{F} = m \vec{g} = -m \vec{\nabla} \phi$

$$\vec{\nabla} \left(\frac{1}{|\vec{r}|} \right) = - \frac{\vec{r}}{|\vec{r}|^3}$$

$$\vec{g}(t, \vec{r}) = -\vec{\nabla} \phi(t, \vec{r})$$

$$\phi(t, \vec{r}) = -G \int d\vec{r}' \frac{\rho(t, \vec{r}')}{|\vec{r} - \vec{r}'|}$$

$$\vec{\nabla} \cdot \left(\frac{\vec{r}}{|\vec{r}|^3} \right) = -\nabla^2 \left(\frac{1}{|\vec{r}|} \right) = 4\pi \delta^{(3)}(\vec{r})$$

$$\nabla^2 \phi(t, \vec{r}) = 4\pi G \rho = -\vec{\nabla} \cdot \vec{g}(t, \vec{r})$$

Tensors

Vectors: \vec{v} has magnitude direction \rightarrow physical

relate: $\vec{v} = v \hat{e}$;

$$\text{using } \hat{e}_i^i = R \hat{e}_i = R^T \hat{e}_i;$$

$$\vec{r} = r^i \hat{e}_i; \quad r^i = \vec{r} \cdot \hat{e}_i^i$$

$$= (R^{-1} \hat{e}_i^i) \cdot \vec{r}$$

$$= \hat{e}_i \cdot R \vec{r}$$

$$= R^i_j r^j$$

\hookrightarrow 3 physical quantities

$$\vec{A} = \vec{B} \leftrightarrow \vec{A} - \vec{B} = \vec{0}$$

q-grabs

$$T^{ij} \rightarrow R^i_k R^j_l T^{kl} \quad (\text{rank } 2\text{-tensor}) \quad \text{representation of the local group}$$

$$T^{i_1 i_2 \dots i_n} \rightarrow R^{i_1}_{j_1} \dots R^{i_n}_{j_n} T^{j_1 j_2 \dots j_n} \quad n\text{-tensor}$$

We already know some tensors!

$$\delta_{ij} \text{ is a 2-tensor} \quad \delta^{ij} = R^i_k R^j_l \delta^{kl} = \delta^{ij}$$

$$\epsilon^{ijk} = R^i_l R^j_m R^k_n \epsilon^{lmn} = \epsilon^{ijk}$$

z) Doing with tensors

$$\cdot ST \text{ rank } n \quad (aS + bT)^{i_1 i_2 \dots i_n} = a S^{i_1 i_2 \dots i_n} + b T^{i_1 i_2 \dots i_n}$$

$$\begin{matrix} S \\ T \end{matrix} \text{ rank-}1 \quad (S \otimes T)^{i_1 i_2 \dots i_m j_1 \dots j_n} = S^{i_1 i_2 \dots i_m} T^{j_1 \dots j_n} \quad \text{rank-}m+n$$

Example:

u^i	v^i
$(u \otimes v)^{ij} = u^i v^j$	
$(u \otimes v)^{ij} \delta_{ij} = u \cdot v$	

$$T^{ij} \rightarrow \underbrace{\delta^{ij}}_{\text{symmetrizing}} = \frac{1}{2} (T^{ij} + T^{ji}) = T^{[ij]} = S^{ij}$$

$$\downarrow A^{ij} : \frac{1}{2} (T^{ij} - T^{ji}) = T^{(ij)} = -A^{ij}$$

~ playing with representation of rotation group

Check how: 8 conserved quantities in Newtonian gravitation

Newtonian Gravity + Galilean Relativity: Nice! ... but wrong :-)

Maxwell's electrodynamics is NOT invariant

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\vec{\nabla} \cdot \vec{E} = 4\pi\rho$$

$$\vec{\nabla} \times \vec{E} + \frac{\partial \vec{B}}{\partial t} = 0$$

$$\vec{\nabla} \times \vec{B} - \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t} = 4\pi \vec{j}$$

speed of light
does not satisfy
Galilean Relativity

* Read up on
Special Relativity

Lorentz transformations: Position + time (t, \vec{r})
of some event measured by two inertial observers

\odot, \odot' with relative velocity $\hat{v} = v\hat{x} = v\hat{x}'$

By shifts, rotations align axes, check $t=t'=0$

$$\begin{aligned} t' &= \frac{t - vx}{\sqrt{1-v^2}} & t &= \frac{t + vx'}{\sqrt{1+v^2}} \\ x' &= \frac{x - vt}{\sqrt{1-v^2}} & x &= \frac{x' + vt'}{\sqrt{1+v^2}} \\ y' &= y & y &= y' \\ z' &= z & z &= z' \end{aligned}$$

$v \ll c$ \downarrow Speed of light
(light units) \rightarrow time passes between relatively (how) large
 \rightarrow rear Galilean at slow velocities (relative to speed of light)

Two inertial frames: Standard Configuration (sc)

$$\begin{aligned} t' &= \frac{t - vx}{\sqrt{1-v^2}} & t &= \frac{t + vx'}{\sqrt{1+v^2}} \\ x' &= \frac{x - vt}{\sqrt{1-v^2}} & x &= \frac{x' + vt'}{\sqrt{1+v^2}} \end{aligned}$$

1. Simultaneity is relative. $t' \neq t$

Space: not a physical (invariant) concept

Solution: spacetime - 4D space \rightarrow free (inertial) motion is
non-world line

important! this proves that
 \rightarrow shift preserves straight lines

2. Since Lorentz Transformations (LT) are linear transforms (in x, y, z, t),

Spacetime is affine space (pick an origin, becomes v.s.)

Event: position @ time

3. Choose inertial frame

Coordinates: (t, \vec{r}) some people write $x^0 = ct$ (but we are working in units where $c=1$)

$$X: X^\mu = (x^0, x^i) = (t, \vec{r}) \quad \mu = 0, 1, 2, 3$$

Greek: $\alpha, \gamma, \alpha, \beta$ go $0, 1, 2, 3$

Latin: i, j, k, l, m go $1, 2, 3$

$$\begin{aligned} t' &= \frac{t-vx}{\sqrt{1-v^2}} & t &= \frac{t+vx'}{\sqrt{1+v^2}} \\ x' &= \frac{x-vt}{\sqrt{1-v^2}} & x &= \frac{x+vt'}{\sqrt{1+v^2}} \end{aligned}$$

4. LT
 label multiple equations $\stackrel{?}{\equiv}$
 $x'^n = \sum_{v=0}^n x^v$
 sum over factors

$$A = \begin{pmatrix} 1^0 & 1^1 & \dots \\ 1^1 & 1^0 & \dots \\ 1^0 & \dots & 1^n \end{pmatrix} = \begin{pmatrix} 1 & -v & 0 & 0 \\ -v & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$v = (1-v^2)^{-\frac{1}{2}}$$

5. This is SC.

Any two inertial frames related by affine (shift + linear)

Bring to SC by shift + rotation

linear structure is preserved.

6. By shift, \vec{v} and $\vec{r} = \frac{\vec{r} \cdot \vec{v}}{v^2} \vec{v} + \vec{r}_\perp$

$$t' = \frac{t - \vec{v} \cdot \vec{r}}{\sqrt{1-v^2}} \quad \vec{r}'^\perp = \vec{r}_\perp$$

$$\vec{r}'_0 = \frac{1}{\sqrt{1-v^2}} (\vec{r}_0 - \vec{v}t)$$

7. More structure: Check

$$x'^2 - t'^2 = s^2 = x^2 - t^2$$

$$+y'^2 + z'^2 = +y^2 + z^2$$

$$\vec{r}'^2 - t'^2 = s^2 = \vec{r}^2 - t^2$$

Preserved by LT $O = O'$
 ↳ Linear preserving $\vec{r}^2 - t^2$

$$(CF: (R\vec{v})^2 = \vec{v}^2 \quad R \in O(3))$$

$$\vec{v}^2 = v^2 v^2 S_{ij}$$

with shifts: Poincaré - preserves

$$(\vec{r} - \vec{r}_0)^2 - (t - t_0)^2 = \Delta s^2 \quad A = (t, \vec{r})$$

invariant interval

$$A_2 = (t_2, \vec{r}_2)$$

Note: s^2 is just notation - it need not be anything squared ... or even positive!

C. Invariance \rightarrow physical. What is it?

Consider $A_1 = (t_1, \vec{r}_1)$ where $t_1 > t_0$

$$A_2 = (t_2, \vec{r}_2)$$

If $\Delta s^2 = (\vec{r}_2 - \vec{r}_1)^2 - (t_2 - t_1)^2 < 0$, two events are separated by a timelike interval

$$\Delta \vec{r} = \vec{r}_2 - \vec{r}_1$$

$$\Delta t = t_2 - t_1 > 0$$

$\Delta t > |\Delta \vec{r}|$ i.e. events separated more by time than space

$$\Rightarrow \Delta t^2 = \gamma(v)(\Delta t - \vec{v} \cdot \Delta \vec{r}) \quad |\vec{v}| < 1$$

$$t'_2 - t'_1 \geq \gamma(v)(\Delta t - |\vec{v}| \cdot \Delta \vec{r}) > 0$$

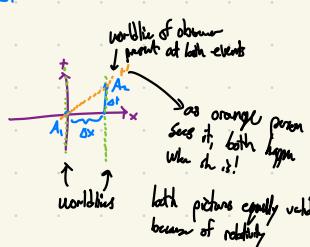
order is invariant: "all observers agree which event happens first"

* A probe from A_1 found \vec{r}_2 @ $\vec{v} = \frac{\Delta \vec{r}}{\Delta t}$ $|\vec{v}| < 1$

arrives @ A_2

* Probe - clock time Δt measures is:

$$\Delta t'^2 - |\Delta \vec{r}|^2 = -\Delta s^2 = (\Delta t)^2 - |\Delta \vec{r}|^2$$



Proper time $\Delta \tau := \sqrt{-\Delta s^2} = \text{time as initial clock present at both events}$
= physical property

* In any inertial frame

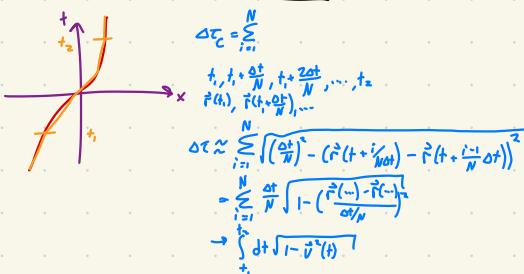
$$\Delta t' - \Delta \vec{r}^2 = -\Delta s^2 = \Delta \tau^2$$

$$\Rightarrow \Delta t > \Delta \tau$$

\uparrow in any other frame

Proper time is shortest time measured by initial observer.

* Noninertial clock? $c = \vec{r}(t)$ in inertial form.



9. If $\Delta s^2 > 0$ $|\Delta \vec{r}| > \Delta t$

* Check \vec{v} $\vec{v} \cdot \Delta \vec{r} > \Delta t$ $|\vec{v}| < 1$

$$\Delta t^2 = t'(t) / (\Delta t - \vec{v} \cdot \Delta \vec{r}) < 0$$

order of events is normal! (if you're moving fast enough in right direction)

(\hookrightarrow order is observer dependent)

Causal theory: information moves @ $|\vec{v}| \leq 1$

* Check $\vec{v} \cdot \Delta \vec{r} = \Delta t$ $\Delta t^2 > 0$

$$(\Delta \vec{r})^2 = \Delta s^2$$

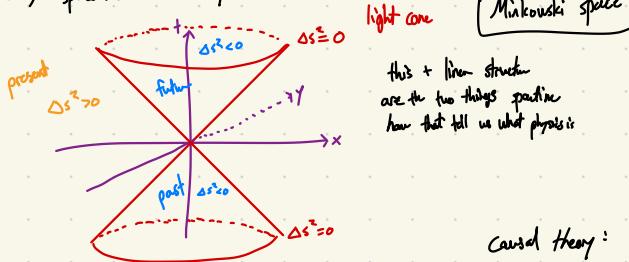
$\sqrt{\Delta s^2}$ proper distance (simultaneous event)

10. $\Delta s^2 = 0$ (boundary) $\Delta t = |\Delta \vec{r}|$ light-like separated.

Not simultaneous or causally related unless moving at speed of light (limit case)

11. Invariant interval endows spacetime with causal structure.

Given \textcircled{O} , spacetime breaks up:

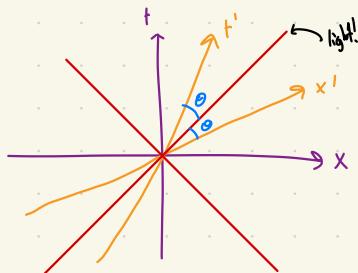


$$\Delta s^2 = \Delta \vec{r}^2 - \Delta t^2$$

$$= \Delta x^\mu \Delta x_\mu$$

$$\gamma = \begin{pmatrix} -1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix}$$

Causal theory: You can't impact any events further away from you than the distance light would travel in the time it takes



$$d = \sqrt{x^2 + t^2} \neq \sqrt{x'^2 + t'^2}$$

not invariant,
so it means nothing!

The Lorentz group

Galilean \xrightarrow{SR} Poincaré

$$M=0, \omega^2 \quad x^M = (x^0, x^i) = (t, \vec{x})$$

$$i=1, \dots, 3$$

- Translations $x^M \rightarrow x'^M = x^M - a^M$

- Rotations $x^M \rightarrow x'^M = \Lambda^M_{\nu} x^\nu$

$$\Lambda = \begin{pmatrix} 1 & 0 \\ 0 & R_{\mu\nu} \end{pmatrix}$$

- Boosts $x^M \rightarrow x'^M = \Lambda^M_{\nu} x^\nu$

$$\Lambda = \begin{pmatrix} \gamma & -\beta v & 0 & 0 \\ -\beta v & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\gamma = \frac{1}{\sqrt{1-v^2}}$$

Lorentz

Lorentz transformation posse

$$x^\mu = \gamma^{\mu}_{\nu} + \gamma^{\mu}_{\nu} = x^\mu \gamma^{\nu}_{\mu\nu} \quad \gamma_{\mu\nu} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

Lorentz posse $x^\mu y^\nu \gamma_{\mu\nu} = x \cdot y$

$$\frac{(x+y)^2}{\text{around}} = \frac{x^2 + 2xy + y^2}{\text{a too much}}$$

$$(\Lambda_x) \cdot (\Lambda_y) = x \cdot y = x^\mu y^\nu \gamma_{\mu\nu}$$

$$= (\Lambda_x)^p (\Lambda_y)^q \gamma_{pq} = x^\mu y^\nu \gamma_{\mu\nu}$$

$$= (\Lambda_\mu^\rho x^\mu) (\Lambda_\nu^\sigma y^\nu) \gamma_{pq}$$

$$= \Lambda_\mu^\rho \Lambda_\nu^\sigma \gamma_{pq} x^\mu y^\nu = \gamma_{\mu\nu} x^\mu y^\nu$$

$$\Lambda_\mu^\rho \Lambda_\nu^\sigma \gamma_{pq} = \gamma_{\mu\nu}$$

$$\Lambda^T \Lambda = \gamma \quad R^T \cdot \underline{1} \cdot R = \underline{1}$$

$$\Lambda \in O(1,3), \quad R \in O(3) = O(0,3)$$

$$\begin{pmatrix} -1 & & & \\ & \downarrow & & \\ & & 0 & \\ & & \uparrow & \\ & & & 1 \end{pmatrix}$$

$$P = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

Lorentz $\neq O(1,3)$

$$\left. \begin{array}{l} \Lambda^T y \Lambda = y \\ \Rightarrow \det(\Lambda)^2 \det(y) = \det(y) = -1 \\ \Rightarrow \det(\Lambda) = \pm 1 \\ \text{Want} = 1 \text{ b/c need subgroup} \end{array} \right\} \quad \begin{array}{l} L \subset SO(1,3) \\ \det(\Lambda) = 1 \quad \forall \Lambda \in L \end{array}$$

$$\begin{aligned} -1 = y_{\mu\nu} &= (\Lambda^T y \Lambda)_{\mu\nu} = \Lambda^\mu{}_\nu y_{\mu\nu} \Lambda^\nu{}_\nu \\ &= -\Lambda^\mu{}_\nu \cdot \Lambda^\nu{}_\nu + \Lambda^\mu{}_\nu \Lambda^\nu{}_\mu \\ &= -(\Lambda^\mu{}_\nu)^2 + (\Lambda^\mu{}_\nu)(\Lambda^\nu{}_\mu) \geq -(\Lambda^\mu{}_\nu)^2 \end{aligned}$$

$$\begin{aligned} (\Lambda^\mu{}_\nu)^2 &\geq 1 & \text{or } \Lambda^\mu{}_\nu \geq 1 & \text{time-preserving} \\ && \Lambda^\mu{}_\nu \leq -1 & \text{time-reversing} \\ &\Rightarrow \text{disconnected} & T = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \end{aligned}$$

$$L = SO(1,3) \uparrow$$

"up"

Lorentz tensors: Any additive physical property not dependent on the observer should be a tensor

Vectors: $u^\mu \rightarrow u'^\mu = \Lambda^\mu{}_\nu u^\nu$ all indices up!

Tensor $T^{m_1 \dots m_n} \rightarrow T'^{m_1 \dots m_n} = \Lambda^{m_1}{}_{n_1} \Lambda^{m_2}{}_{n_2} \dots \Lambda^{m_n}{}_{n_n} T^{n_1 \dots n_n}$

$$u^\mu v^\nu \rightarrow (u \circ v)^{\mu\nu}$$

Contraction used invariant tensor δ_{ij}

$$u \cdot v = u^i v^j \delta_{ij} = (u \circ v)^{ii} \delta_{ii}$$

"I hate myself even more than usual"

$$u^{\mu} \quad v^{\nu}$$

$$u \cdot v = u^{\mu} v^{\nu} y_{\mu\nu}$$

$$\Lambda^T y \Lambda = y$$

$$S^{M_1 \dots M_{n-2}} = T^{M_1 M_2 \dots M_{n-2}} y_{\mu\nu}$$

$$S' = T' \dots y = \underbrace{\Lambda \dots \Lambda}_{\mu\nu} T$$

$$T^{M_1 \dots M_n} = \Lambda_{\mu_1}^{M_1} \dots \Lambda_{\mu_n}^{M_n} T^{\nu_1 \dots \nu_n}$$

$$S^{M_1 \dots M_{n-2}} = T^{M_2 M_3 \dots M_{n-2}} y_{\mu\nu}$$

$$S'^{M_1 \dots M_{n-2}} = T'^{M_2 M_3 \dots M_{n-2}} y_{\mu\nu}$$

$$\Lambda_{\mu}^{M_1} \Lambda_{\nu}^{M_2} \dots \Lambda_{\mu_n}^{M_n} T^{\nu_1 \dots \nu_{n-2}} y_{\mu\nu}$$

$$\Lambda_{\mu}^{M_1} \Lambda_{\nu}^{M_2} y_{\mu\nu} = y_{\mu\nu}$$

$$= \Lambda_{\mu_1}^{M_1} \dots \Lambda_{\mu_{n-2}}^{M_{n-2}} T^{\nu_1 \dots \nu_{n-2}} y_{\mu\nu}$$

In $O(3)$, T two tensor

$$T(v_i, v_j) = T^{ij} v_i^k v_j^l \delta_{ik} \delta_{jl}$$

In $O(1, 3)$,

$$T^{\mu\nu} u_i^{\lambda} u_j^{\rho} y_{\lambda\mu} y_{\nu\rho}$$

$$\text{However: } x^{\mu} x^{\mu} = x^0 x^0 + x^1 x^1 + x^2 x^2 + x^3 x^3$$

$$\text{Now ESC: Contractions use } x^{\mu} y^{\nu} y_{\mu\nu}$$

$$u^{\mu} \rightarrow u^{\mu} = \Lambda_{\nu}^{\mu} u^{\nu}$$

$$y_{\mu} = y_{\mu\nu} u^{\nu} \rightarrow y_{\mu\nu} \Lambda_{\nu}^{\nu} u^{\mu}$$

$$\uparrow \text{not a vector!} \quad u^i = \underline{y \Lambda} u$$

$$u^i = \underline{y(\Lambda^T)^{-1}} u$$

$$\Lambda^T y \Lambda = y$$

$$((\Lambda^T)^{-1})^T \Lambda = \mathbb{1}$$

u_m is a covector

$$u_m \rightarrow (\lambda^T)_m^{-1} v u_n$$

$$u_m v^M = u^\lambda v^M g_{\lambda M} = u \cdot v$$

u^λ vector

$$x^M = (x^0, x^i)^T$$

$u_m = y_{\lambda m} u^\lambda$ covector

$$x_m = (-t, \vec{r})$$

$$\begin{aligned} y_{\mu\nu} \rightarrow y'_{\mu\nu} &= (\lambda^T)_\mu^{-1} \delta^\rho_\nu (\lambda^T)_\rho^{-1} \delta^\sigma_\sigma y_{\rho\sigma} \\ &= ((\lambda^{-1})^T y \lambda^{-1})_{\mu\nu} = y_{\mu\nu} \end{aligned}$$

Notation:

$$\begin{cases} (y^{-1})^{\mu i} y_{\lambda 0} = \delta^\mu_\lambda \\ y^{\mu i} = y^{\mu i} y_{\lambda 0} \end{cases}$$

$$(\lambda^{-1})^T_\mu \delta^\sigma_\nu \lambda^\mu_\lambda = \delta^\sigma_\nu \quad \lambda^\mu_\mu \delta^\sigma_\nu$$

Consistent?

$$\begin{aligned} y_{\mu\nu} \lambda^\nu y^{\rho\sigma} \\ = (y \lambda y^{-1})_\mu^\sigma = (\lambda^T)_\mu^\sigma \end{aligned}$$

$$\lambda^T y \lambda = y$$

$$y \lambda = (\lambda^T)^\lambda_\mu y_\lambda$$

$$y \lambda y^{-1} = (\lambda^T)^{-1}$$

$T^{M_1 \dots M_n}_{\mu_1 \dots \mu_m}$ (n, m) -tensor

$$T \rightarrow T^{M_1 \dots M_n}_{\nu_1 \dots \nu_m} = \underbrace{\Lambda^M_{\mu_1} \dots \Lambda^M_{\mu_n}}_{\mu_i \text{ indices}} \Lambda^{\sigma_1}_{\nu_1} \dots \Lambda^{\sigma_n}_{\nu_m} T^{\mu_i \nu_j}_{\sigma_i \sigma_m}$$

E.S.C.

- Every summand is a (n, m) -tensor
- Unpaired indices (n, m) agree
- Paired indices ($\text{up} + \text{down}$) are dummy
indices to sum over
- Indices bounds:

$$\begin{aligned} u_m &= y_{\mu\nu} u^\nu \\ u^\mu &= y^{\mu\nu} u_\nu \end{aligned} \quad \mu^{-1}$$

$$x^{\mu\nu} = \Lambda^M_{\mu\nu} x^\nu \leftrightarrow x^i = \Lambda^i x$$

$$x^\mu = \Lambda^\mu_\nu x^\nu \leftrightarrow x^i = \Lambda^i x$$

$$\underline{\Lambda^M_{\mu\nu} = \frac{\partial x^\mu}{\partial x^\nu}}$$

$$\underline{\Lambda^\mu_\nu = \frac{\partial x^\mu}{\partial x^\nu}}$$

$$f(x)$$

$$\underline{\frac{\partial f}{\partial x^\mu} = \frac{\partial f}{\partial x^\nu} = \frac{\partial f}{\partial x^\nu} \cdot \frac{\partial x^\nu}{\partial x^\mu}}$$

$$\underline{\frac{\partial f}{\partial x^\mu} = \frac{\partial f}{\partial x^\mu}}$$

$$= \underline{\Lambda^\nu_\mu \frac{\partial f}{\partial x^\nu}}$$

$$\underline{\frac{\partial f}{\partial x^\mu} \cdot \frac{\partial x^\mu}{\partial x^\nu}}$$

$$y^{-1} = y \quad y^{\mu\nu} = y_{\mu\nu}$$

$$\underline{\partial_\mu = (\partial_t, \vec{\nabla})} \quad \underline{\partial^\mu = y^{\mu\nu} \partial_\nu = (\partial_t, \vec{\nabla})^T}$$

Tensors - a summary

Tensors of $SO(1,3)^\dagger$

4th physical quantities: $T^{x_1 \dots x_n} \rightarrow \Lambda_{x_1}^{x_1} \dots \Lambda_{x_n}^{x_n} T^{x_1 \dots x_n}$
 $u^m \rightarrow \Lambda_{x_m}^{x_m} u^m \quad u \rightarrow \Lambda u$

"Some tensor wrt. th. Dow Jones"

T is like antipodal: $u_1 \otimes u_2 \otimes \dots \otimes u_n$
 $S^{x_1 \dots x_n} = u_1^{x_1} u_2^{x_2} \dots u_n^{x_n}$

Add dual $u_m = \sum_{x_m} u^x$

$$u^x = \begin{pmatrix} u_0 \\ u_1 \\ u_2 \\ u_3 \end{pmatrix}$$

$$\begin{aligned} u^* &\rightarrow (\Lambda^T)^{-1} u^* \\ u^{*T} v &\rightarrow [(\Lambda^T)^{-1} u^*]^T \Lambda v \\ &\rightarrow u^{*T} \Lambda^{-1} \Lambda v = u^{*T} v \end{aligned}$$

invert o-tensor

ESC Notation:

- $u \rightarrow (\Lambda^T)^{-1} u^* \rightarrow u_m \rightarrow \underbrace{\Lambda_{x_m}^{x_m}}_{(\Lambda^T)^{-1} \text{ written as matrix}} u_x = y_{x_0} \Lambda^0_{\alpha} y^{\alpha x} u_x$
- $y^{-\mu\nu} \rightarrow y^{\mu\nu} \quad (\Lambda^T)^{-1} = (y \Lambda y)^T \rightarrow \Lambda^T y \Lambda = y$
- $A^{\mu} = B^{\mu} \Rightarrow A_{\mu} = B_{\mu} \quad y_{\mu\nu} A^{\nu} = y_{\mu\nu} B^{\nu}$
- $A_{\mu\nu} B^{\mu} = A^{\mu} B_{\mu} = \Lambda^{\mu} B^{\nu} y_{\mu\nu}$

$$T^{\mu}_{\nu} \quad T_{\mu}^{\nu} = y_{\mu x} y^{\nu x} T^x_{\alpha}$$

\uparrow
numerically, not equal,
but describe same physical
thing

$$X^{\mu} = (t, \vec{x})^T \quad X_{\mu} = y_{\mu x} X^x = (-t, \vec{x})$$

Use the math for physics?

What does SR do to Newton?

Is What replaces $F = ma$

Is What about conservation laws?

Symmetry?

Is What does it all mean for gravity?

(try Maxwell first)

Particles: $\vec{r}(t)$ $|\dot{\vec{r}}| < 1$ $\forall t$ worldline

Can find proper time τ along worldline

$$\Delta\tau^2 = -\Delta s^2 = \Delta t^2 - \Delta \vec{r}^2$$

$$ds = \sqrt{dt^2 - d\vec{r}^2}$$

$$\tau = \int dt \sqrt{1 - \vec{v}(t)^2}$$

$$= \int dt \frac{1}{\gamma(v(t))} \quad \text{invariant}$$

Can invert $t(\tau)$

$$\text{describe } x^\mu(\tau) = (t(\tau), \vec{r}(t(\tau)))$$

$$u^\mu = \frac{dx^\mu}{d\tau} \quad \text{4-velocity}$$

$$= \left(\frac{dt}{d\tau}, \frac{d\vec{r}}{d\tau} \right) = (\gamma, \vec{v}) = \gamma(1, \vec{v})$$

$$\frac{dt}{d\tau} = \frac{1}{\gamma} = \frac{1}{\gamma} = \gamma(v(t))$$

$$\gamma = (1 - v^2)^{-1/2}$$

$$\frac{d\vec{r}}{d\tau} = \frac{d\vec{r}}{dt} \frac{dt}{d\tau} = \vec{v} \cdot \gamma$$

photon invariant
but may change numerically
depends on observer

In observer related by $x'^\mu = \Lambda^\mu_{\nu} x^\nu$

$$\text{measures } u'^\mu = \Lambda^\mu_{\nu} u^\nu$$

Note:

can be any parameter

 $s(\tau) \quad \frac{ds}{d\tau} > 0$
 $\frac{dx^\mu}{ds} = \frac{dx^\mu}{d\tau} \frac{d\tau}{ds} = u^\mu \left(\frac{ds}{d\tau} \right)^{-1}$

u is not arbitrary

$$\bullet u^0 > 0 \quad u^0 = \frac{dx^0}{d\tau} = \frac{dt}{d\tau} = \frac{1}{\gamma v_{\text{rel}}}$$

→ timelike, forward-pointing

$$\bullet u^2 = u \cdot u = g_{\mu\nu} u^\mu u^\nu = \vec{v}^2 - (u^0)^2 = \gamma^2 v^2 - 1^2 = \gamma^2 (v^2 - 1) \quad \text{because we used } \tau$$

Inertial worldlines have \vec{v} constant $\Leftrightarrow u$ constant

→ NI: a free particle has a constant $u^\mu(\tau) \quad \forall \tau$

$$a^\mu = \frac{du^\mu}{d\tau} = \frac{d^2x^\mu}{d\tau^2} = \gamma(v(t)) \frac{1}{\gamma} (0, \vec{v})$$

NI: free particle has $a^\mu = 0$ in any frame

Inertial rest frame

$$u^\mu = (1, \vec{0}) \quad a^\mu = (0, \frac{d\vec{r}}{dt})$$

$$u \cdot a = 0$$

Light: a wave: plane wave

$$\underline{\phi}_E(u) = \phi_0 \sin(k \cdot \vec{r} - \omega t) \quad k^2 = \omega^2$$

$$\vec{k} \cdot \vec{r} - \omega t \text{ invariant} \Rightarrow k^M = (\omega, \vec{k}) \quad 4\text{-vector}$$

$$= k \cdot x = k' \cdot x'$$

So $\omega = k^0$ frequency in a frame

An observer moving @ \vec{v} measure $\omega' = k'^0$

$$k' = \gamma u^M$$

$$\text{Let } u^M = (1, \vec{v}) \quad \gamma_{uv} u^{i\nu} = (-1, \vec{v})$$

$$\text{in observer's rest frame } u'^M = (1, \vec{0})^T$$

$$w' = k'^0 = -k' \cdot u^i = -k \cdot u = \gamma(\omega - k \cdot \vec{v})$$

$$\approx \vec{k} \cdot \vec{v} = 0 \text{ transverse} \quad w' = \gamma(v) \omega = \frac{\omega}{\sqrt{1-v^2}} \begin{array}{l} \xrightarrow{\text{moving observer measures}} \\ \xrightarrow{\text{so clock measures slower}} \\ \rightarrow \text{higher frequency} \end{array}$$

$$\approx \vec{k} \cdot \vec{v} = |\vec{k}| \cdot |\vec{v}| \cos \theta \text{ longitudinal}$$

$$w' = \frac{1}{\sqrt{1-v^2}} (w \cdot w v) = w \frac{1-v}{\sqrt{1-v^2}} = w \sqrt{\frac{1-v}{1+v}}$$

Interactions? force law $\vec{F}(\vec{r}_1(t), \vec{r}_2(t))$

Collision: instantaneous, ultralocal interaction

$$\text{Initial state: } m_a^i \quad \vec{r}_a^i \quad a \in \{1, \dots, N\} \quad t=0 \quad \epsilon \quad \vec{p}_a^i = 0$$

$$\text{Final state: } m_b^f \quad \vec{r}_b^f \quad b \in \{1, \dots, N'\} \quad t=0+\epsilon \quad \vec{p}_b^f = 0$$

$$\text{Newton: } \left\{ \begin{array}{l} \vec{p}^i : \vec{p}^i = \sum_a m_a^i \vec{r}_a^i = \sum_b m_b^f \vec{r}_b^f = \vec{p}^f \\ E^i = \frac{1}{2} \sum_a m_a^i (\vec{r}_a^i)^2 = \frac{1}{2} \sum_b m_b^f (\vec{r}_b^f)^2 = E^f \\ \sum_a m_a^i = \sum_b m_b^f \end{array} \right.$$

Not a tensor! Newton candidate: $w^M = \gamma(1, \vec{v})$

$$\begin{aligned} p &= p^M = m w^M \quad 4\text{-momentum} \\ p^i &= \sum_a p_a^i = \sum_b p_b^f = p^f \end{aligned}$$

$$\text{for } |v| \ll 1 \quad \gamma(v) = (1-v^2)^{-\frac{1}{2}} \approx 1 + \frac{1}{2} v^2 + O(v^4)$$

$$p = m(\gamma, \gamma \vec{v}) \approx (m + \frac{1}{2} m v^2, m \vec{v}) + O(v^4)$$

if $|v_a| \ll v_a$ $m \rightarrow \frac{1}{2}mv^2$
 $|v_b'| \ll v_b$

$$\sum m_a' = \sum m_a f \quad O(v^0)$$

$$\sum m_a \vec{v}'_a = \sum m_a \vec{v}_a f \quad O(v)$$

$$\frac{1}{2} \sum m_a' v_a'^2 = \frac{1}{2} \sum m_a^f v_a^2 \quad O(v^2)$$

$$p = mu = m(\gamma, \gamma v)$$

$$E = p^0 = mv$$

$$\vec{p} = \gamma mv \quad \text{momentum}$$

$$p^2 = m^2 u^2 = -m^2 = p^2 - E^2$$

$$E^2 = \vec{p}^2 + m^2$$

$$E^2 = \vec{p}^2 c^2 + m^2 c^4$$

$$m=0 \quad E = |\vec{p}| \quad p^M = (|\vec{p}|, \vec{E})$$

$p^2 = 0$ massless

p^μ conserved quantity

massive:

$$p^\mu = mu^\mu \quad u^\mu = \gamma(v) (1, \vec{v})$$

$$\vec{p} = mv \gamma(v)$$

$$E = mv\gamma(v)$$

$$E^2 = m^2 + \vec{p}^2$$

massless:

$$E = |\vec{p}|$$

A gas of charged particles

N particles m_a q_a

Continuous limit $m_a \rightarrow 0$ $N \rightarrow \infty$

smooth distribution $q_a \rightarrow 0$

$$\rho_E = \sum_a q_a \delta^{(3)}(\vec{r} - \vec{r}_a(t)) \quad \text{charge density}$$

$$\vec{j}_E = \sum_a q_a \vec{r}_a(t) \delta^{(3)}(\vec{r} - \vec{r}_a(t))$$

$$\frac{\partial \rho_E(\vec{r}, t)}{\partial t} = \sum_a q_a \frac{\partial}{\partial t} \delta^{(3)}(\vec{r} - \vec{r}_a(t)) + \nabla \cdot \delta^{(3)}(\vec{r} - \vec{r}_a(t))$$

$$= -\vec{\nabla} \cdot \vec{j}_E$$

$$\frac{\partial p_E(t, \vec{r})}{\partial t} + \nabla \cdot \vec{j}_E = 0 \quad \text{continuity follows from Maxwell's equations}$$

Should be observe insight -

Can we write this as a tensor or scalar?

$$\frac{\partial p_E}{\partial t} + \vec{\nabla} \cdot \vec{j}_E = 0$$

$$\partial_0 p_E + \partial_i j_E^i = 0$$

$$x = (t, \vec{r}) \quad j_E^M(x) = (p_E, \vec{j}_E)$$

lump this together to make p and \vec{j} mix under bonds

$$j_E^M(t, \vec{r}) = \sum_a q_a \frac{\partial x_a^M}{\partial t} \delta^{(3)}(\vec{r} - \vec{r}_a(t))$$

$$j_E^0(t, \vec{r}) = \sum_a q_a \delta^{(3)}(\vec{r} - \vec{r}_a(t)) = j_E^0(t, \vec{r})$$

$$j_E^i(t, \vec{r}) = \sum_a q_a \frac{\partial \vec{x}_a}{\partial t} \delta^{(3)}(\vec{r} - \vec{r}_a(t)) = j_E^i(t, \vec{r})$$

$$\begin{aligned} j^M &= \begin{pmatrix} j^0 \\ j^i \end{pmatrix} \\ &= \begin{pmatrix} Y & -Yv \\ -Yv & Y \\ 0 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} p \\ \vec{j} \end{pmatrix} \end{aligned} \quad \text{volume not Lorentz-invariant}$$

Claim: j_E^M is a vector

$$\begin{aligned} \text{PF: } j_E^M(x) &= \int dt' \delta(t-t') j_E^M(t, \vec{r}) \\ &= \int dt' \sum_a q_a \delta^{(3)}(\vec{r} - \vec{r}_a(t')) \frac{dx_a^M(t')}{dt'} \delta(t-t') \end{aligned}$$

$$= \sum_a \int dt' \cancel{\sum_a} q_a \delta^{(3)}(x - x_a(t')) \frac{dx_a^M(t')}{dt'} \quad \leftarrow \text{invariant under reparameterizations}$$

$$= \sum_a \int d\tau_a q_a \delta^{(3)}(x - x_a(\tau_a)) \frac{dx_a^M(\tau_a)}{d\tau_a} \quad \leftarrow \text{this is a 3-vector!}$$

$$\Phi(t) = \int d^3 r j_E^0(t, \vec{r}) \quad \frac{d\Phi}{dt} = \int d^3 r \partial_0 j^0 = - \int d^3 r \partial_i j^i = 0$$

$$\text{Q conserved} \rightsquigarrow \partial_\mu j^\mu = 0$$

Divergence theorem

We made continuity consistent!

$$p^M \text{ conserved} \rightsquigarrow \partial_\nu T^{M\nu} = 0$$

$$T^{M\nu}(x) = \sum_a p_a^M(t) \frac{dx_a^M(t)}{dt} \delta^{(3)}(\vec{r} - \vec{r}_a(t))$$

$$T^{00}(x) = \sum_a p_a^{\mu}(t) \delta^{(3)}(\vec{r} - \vec{r}_a(t)) \quad \text{density of } p^{\mu}!$$

* Tensor we did similar above!

* conserved?

$$T^{\mu\nu} = \int dt' \delta(t-t') \sum_a p_a^{\mu}(t') \frac{dx^{\nu}}{dt'} \delta^{(3)}(\vec{r} - \vec{r}_a(t'))$$

$$= \sum_a \left(\int d\tau \delta^{(3)}(x(\tau) - x) p_a^{\mu}(\tau) \frac{dx^{\nu}}{d\tau} \right) = T^{\nu\mu}$$

$m_a u_a^{\mu} u_a^{\nu}$ covariant...
and symmetric!

$T^{\mu\nu} = T^{\nu\mu}$ = energy-momentum-stress tensor

$$\underset{p}{\frac{T^{00}}{T^{0\mu}}} = \text{density of } p^0 = \text{density of energy!}$$

$$\underset{p}{\frac{T^{00}}{T^{0i}}} = \text{density of } p^i = \text{current of energy}$$

$$\begin{aligned} T^{0i} &= T^{i0} && \text{density of } p^i = \text{current of energy} \\ T^{ij} &= T^{ji} && i \text{ flux of } p^j = j \text{ flux of } p^i \\ && \text{in direction } \end{aligned}$$

Conservation:

$$\begin{aligned} \partial_i T^{0i}(t, \vec{r}) &= \partial_i \sum_a p_a^{\mu}(t) \frac{dx_a^i(t)}{dt} \delta^{(3)}(\vec{r} - \vec{r}_a(t)) \\ &= \sum_a p_a^{\mu}(t) \frac{dx_a^i(t)}{dt} \partial_i \delta^{(3)}(\vec{r} - \vec{r}_a(t)) \\ &\quad \frac{dx_a^i}{dt} \partial_i \delta^{(3)}(\vec{r} - \vec{r}_a(t)) \quad \rightarrow \quad \frac{\partial \delta}{\partial x^i} \cdot \frac{dx_a^i(t)}{dt} \\ &= - \sum_a p_a^{\mu}(t) \partial_i \delta^{(3)}(\vec{r} - \vec{r}_a(t)) \\ &= - \partial_0 \sum_a p_a^{\mu}(t) \delta^{(3)}(\vec{r} - \vec{r}_a(t)) + \sum_a \frac{dp_a^{\mu}}{dt} \delta^{(3)}(\vec{r} - \vec{r}_a(t)) \end{aligned}$$

$$\partial_{\nu} T^{\mu\nu} = \frac{\partial_0 T^{00} + \partial_i T^{0i}}{\partial_0 + \partial_i} = \sum_a \frac{dp_a^{\mu}}{dt} \delta^{(3)}(\vec{r} - \vec{r}_a(t))$$

time change
of total p^{μ} $\frac{dp^{\mu}}{dt}$ - amount
in which heavy value \hookrightarrow particles not free — they interact!

$$f^{\mu} = \frac{dp^{\mu}}{dt} \rightarrow \text{looks like force & rest from}$$

$$= m \frac{dw^{\mu}}{dt} = m a^{\mu}$$

$$\text{rest frame: } u^\mu = (1, \vec{0}) \quad \omega^\mu = (0, \vec{\omega}) \quad f^\mu = (0, \vec{m\omega})$$

Conservation for:

- ① free $\frac{dp^\mu}{dt} = 0$
- ② collisions that conserve p^μ

$$\partial_\mu T^{\mu\nu} = \sum_a \delta(\vec{r} - \vec{r}_a) \frac{1}{dt} \sum_{\text{coll}} p_a^\mu = 0$$

Charged: $f^\mu = m \frac{dx^\mu}{dt} = q \vec{f}^\mu \cdot \vec{u}^\nu$ Lorentz force
 $\vec{f}^\mu = (0, \vec{E})$ field strength tensor

rest frame: $u^\nu = (1, \vec{0})$
 $f = q(0, \vec{E}) = (0, \vec{f}^\mu)$

$$\partial_\mu T^{\mu\nu} = \sum_a q_a \vec{f}^\mu \cdot \vec{u}^\nu \frac{dx_a^\nu}{dt} \delta^{(3)}(\vec{r} - \vec{r}_a(t))$$

\uparrow doesn't look like tensor but can make it look like one

$$= \vec{f}^\mu \cdot \vec{u}^\nu \sum_a q_a \frac{dx_a^\nu}{dt} \delta^{(3)}(\vec{r} - \vec{r}_a)$$

$$= \vec{f}^\mu \cdot \vec{u}^\nu j_E^\mu(x)$$

together, conserved $\left\{ \begin{array}{l} \text{Poynting vector } \vec{E} \times \vec{B} \\ \text{Energy density } \frac{E^2 + B^2}{8\pi} \end{array} \right.$ - momentum density of EM field

$$\phi_c \quad \nabla^\nu \phi_c = 4\pi \rho \quad \text{scalar}$$

$$\nabla^\nu \phi_E = 4\pi j_E^0 \quad \text{O-component of current}$$

Today: gravity

Relativistic field theory of E&M ✓

Gravity ?

EM couples to j_E^μ for constant scalar charge $\phi = \int d^3r j^0$

Can gravity couple to mass? Not conserved

energy \downarrow not conserved!

$$p^0 = m\gamma \approx m + \frac{1}{2}mv^2 + \dots$$

Couple to $T_{\text{current}}^{\mu\nu}$ for conserved $p^\mu = E$. Not invariant

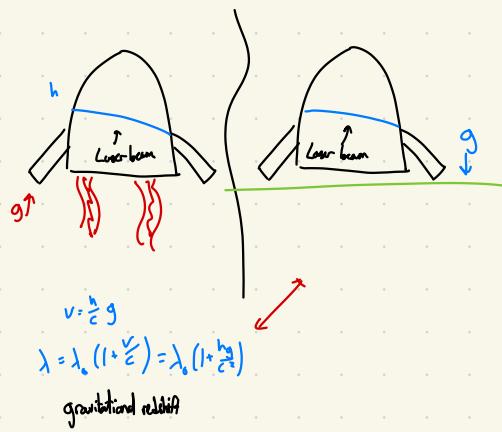
Couple to $T^{\mu\nu}$ for conserved p^μ

Special relativity: inertial frame

Universality of gravity: problem

Also a solution:

In freefall - no gravity S.R. works
 $\nabla x \exists \vec{g}(x) \quad g \mapsto \frac{GM}{R^2}$ tidal effects are real!
equivalence principle



Gravity is geometry
can make inertial frame locally

$$x = (t, \vec{r}) \quad \text{NOT Poincaré!!}$$
$$x' = (t', \vec{r}') \quad \text{model differently}$$

$x'(x)$ worse - invariant under this?

No global linear structure

What do we have? Differential geometry

Spacetime is a globally hyperbolic ⁽¹⁾ smooth ⁽²⁾

Lorentzian 4-manifold

A manifold is like \mathbb{R}^n (locally) ... like enough to do calculus
not like enough for global linear structure

A smooth manifold is a set \mathcal{M} together
with an atlas or cover $\left\{ \Omega_\alpha, \psi_\alpha \right\}_{\alpha \in A}$

$$\Omega_\alpha \subset M \quad \forall \alpha$$

$$\bigcup_{\alpha \in A} \Omega_\alpha = M$$

$$\Psi_\alpha : \Omega_\alpha \rightarrow \mathbb{R}^n \quad \text{Im } \Psi_\alpha = V_\alpha \subset \mathbb{R}^n \text{ open}$$

$$\left[\forall y \in V_\alpha \exists \epsilon > 0 \mid B_{y,\epsilon} = \{z \in V_\alpha \mid (z - y)^2 < \epsilon^2\} \subset V_\alpha \right]$$

$\exists \psi_\alpha^{-1} : V_\alpha \rightarrow \Omega_\alpha$ we will identify them

$$\psi_\alpha^{-1}(B_{y,\epsilon}) \subset \Omega_\alpha \quad \text{define it open}$$

$p \in \Omega_\alpha \subset M$ a point

Spec of "point" $\Psi_\alpha(p) \in V_\alpha \subset \mathbb{R}^n$

↑ and interchangeably

Denote this $x_\alpha^\mu(p)$

A function $f : M \rightarrow \mathbb{R}$ produces V_α

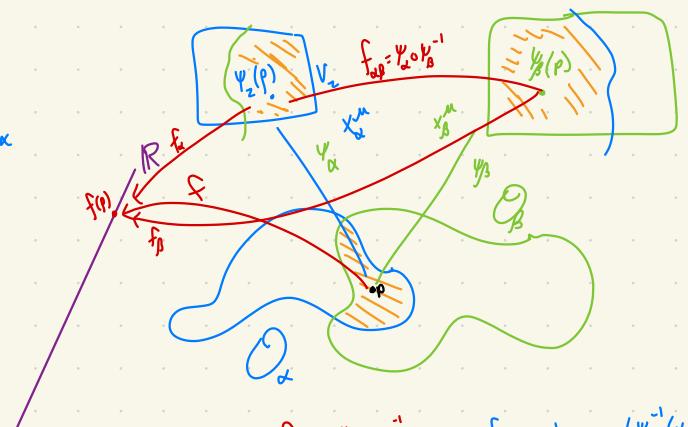
$$f_\alpha = f \circ \psi_\alpha^{-1} : V_\alpha \rightarrow \mathbb{R}$$

$$f_\alpha'(x)$$

$$f(\psi_\alpha^{-1}(x_\alpha))$$

f is called smooth if f_α smooth V_α

* On overlaps $\Omega_\alpha \cap \Omega_\beta \neq \emptyset$



$$f_{\alpha,p} = \psi_\alpha \circ f$$

$$f_{\alpha,p}(x_\beta) = x_\alpha (\psi_\beta^{-1}(x_\beta))$$

* Demand $f_{\alpha\beta}$ smooth

$$f_{\beta\alpha} = f_{\alpha\beta}^{-1} \quad x_\beta^\alpha(x_\alpha)$$

$f: M \rightarrow \mathbb{R}$ smooth if f_α smooth b/c

$$\begin{aligned} f(x_\alpha) &= f(\psi_\alpha^{-1}(x_\alpha)) \quad \text{if } \rho \in \Omega_\alpha \cap \Omega_\beta \\ f_\beta(x_\beta) &= f(\psi_\beta^{-1}(x_\beta)) \end{aligned}$$

$$f_{\alpha\beta} = \psi_\alpha \circ \psi_\beta^{-1} \quad \text{smooth}$$

$$f_\beta(x_\beta) = f_\alpha(f_{\alpha\beta}(x_\beta))$$

Examples

1) $\mathbb{R}^n \quad \Omega = \mathbb{M} = \mathbb{R}^n \quad \psi = \text{id}$

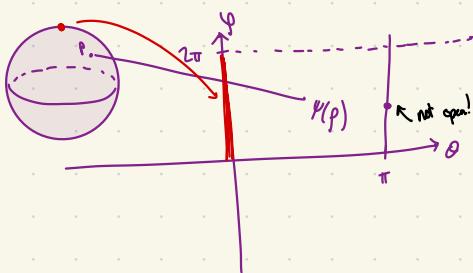
2) Consider $S^2 = \{\vec{r} \in \mathbb{R}^3 \mid |\vec{r}|=1\}$ unit sphere

Not open

Parts of S^2 look like \mathbb{R}^2 (maps)

Fundamentally:

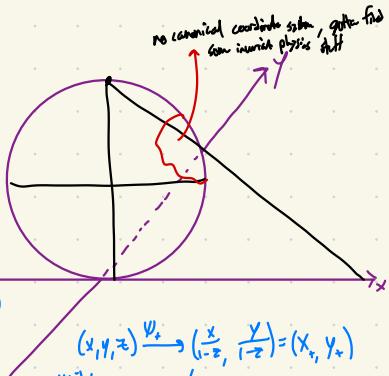
$x = \sin\theta \cos\varphi$	$y = \sin\theta \sin\varphi$	$\varphi = \tan^{-1}(y/x)$
$z = \cos\theta$	$\theta = \tan^{-1}(\sqrt{x^2+y^2}/z)$	ψ



better:

$$(0, 0, 1) \rightarrow (0, 1)$$

$$\begin{aligned} \Omega_+ &= \Omega^2 \setminus \text{North pole} \\ V_+ &= \mathbb{R}^2 \end{aligned}$$



$$\text{analogously def: } \Omega_- = S^2 \setminus \text{South pole}$$

$$V_- = \mathbb{R}^2$$

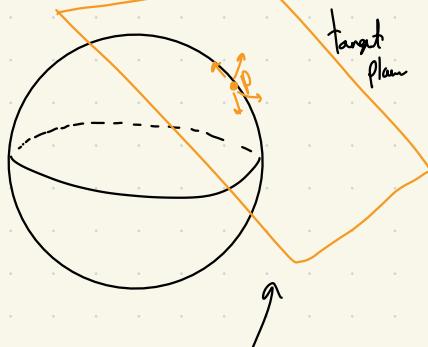
$$\psi_-(NP) = (0, 0)$$

$$\begin{aligned} f_{+-} : (x_+, y_+) &= \begin{pmatrix} x_- \\ x_+^2 y_+ \\ x_+^2 + y_+^2 \end{pmatrix} \\ f_{--} &= f_{+-}^{-1} \end{aligned}$$

Spacetime: Different inertial observers get different coordinates

Do not share linear structure. Share smooth maps

Temporary, \mathcal{M} a space in which particles move \rightarrow ignore spacetime (for now)



tool advantage of inclusion $S^2 \subset \mathbb{R}^3$

Velocity \approx a way to take derivatives

$f: M \rightarrow \mathbb{R}$, more through p velocity derivative \dot{f}

A tangent vector V_p to M at $p \in M$

takes $f: M \rightarrow \mathbb{R}$ to $V_p(f) \in \mathbb{R}$

* Linear: $V_p(af + bg) = aV_p(f) + bV_p(g)$ $a, b \in \mathbb{R}$
 f, g maps

* Leibniz: $V_p(fg) = f(p)V_p(g) + V_p(f) \cdot g(p)$

Show: $f(p) = 0 \quad V_p \Rightarrow V_p(f) = 0 \quad \forall V_p$

Set of tangent vectors $T_p M$ is a linear space

$$(aV_p + bW_p)(f) = aV_p(f) + bW_p(f) \quad \text{stability condition}$$

If M is n dimensional, $\dim T_p M = n$

Proof: use coordinates $p \in \mathcal{O}_\alpha$

$$\forall f: M \rightarrow \mathbb{R}$$

$$f_\alpha: V_\alpha \rightarrow \mathbb{R} \quad f_\alpha(x_\alpha) = f(\psi^{-1}(x_\alpha))$$

Define $X_\mu^\alpha \in T_p M : f \mapsto \left. \frac{\partial f_\alpha}{\partial x_\mu^\alpha} \right|_{x(p)}$

• Show $X_\mu^\alpha \in T_p M \quad X_\alpha^r: \mathcal{O}_\alpha \rightarrow \mathbb{R}$

$$X_\mu^\alpha(X_\nu^r) = \delta_{\mu\nu}^r \text{ independent}$$

• Span:

Lemma: $h: V_\alpha \rightarrow \mathbb{R}$

$$h(x) = h(x_0) + \sum_{m=1}^n (x^m - x_0^m) H_m(x)$$

\downarrow smooth

$$\left. \frac{\partial h}{\partial x^m} \right|_{x_0} = H_m(x_0)$$

$$f_\alpha(x) = f_\alpha(x(p)) + \sum_{m=1}^n (x^m - x^m(p)) \cdot H_m(x)$$

$$H_m = \left. \frac{\partial f_\alpha}{\partial x^m} \right|_p = X_\mu^\alpha(f)$$

$$V_p(f) = \sum_m V_p(x^m) \cdot H_m(x(p))$$

\downarrow

$$V_p = \sum_m V_p(x_\alpha^m) \cdot X_\mu^\alpha$$

$$T_p M \hookrightarrow T_p^* M \quad \text{dual vector}$$

w cotangent vector

$$w(v): M \rightarrow \mathbb{R}$$

$$f: M \rightarrow \mathbb{R} \rightsquigarrow df(v)(p) = V_p(f)$$

$$\text{choose } f = x_\alpha^m \quad dx_\alpha^m(\partial_\mu^\alpha) = \delta_\nu^\alpha$$

$$w = w_\mu^\alpha dx_\alpha^m \quad \begin{matrix} \text{basis} \\ \int \text{components} \end{matrix} \quad / \quad v = v_\mu^\alpha \partial_\mu^\alpha$$

$$dx_\beta^M = \frac{\partial x_\beta^M}{\partial x_\alpha^\nu} dx_\alpha^\nu$$

$$v_\beta^M = \frac{\partial x_\beta^M}{\partial x_\alpha^\nu} v_\alpha^\nu$$

$$w_\mu = \frac{\partial x_\mu}{\partial x_\beta^\nu} w_\nu^\beta$$

$$\partial_\mu^\beta = \frac{\partial x_\mu}{\partial x_\nu^\beta} \partial_\nu^\nu$$

$$\partial_\beta^M (\partial_\nu^\beta) = \delta_\nu^M$$

define an (l, m) -tensor field T at p is an object

$$T_p \in (T_p M)^{\otimes l} \times (T_p^* M)^{\otimes m}$$

$$T = T_{\nu_1 \dots \nu_m}^{M_1 M_2 \dots M_l} \partial_{M_1}^\nu \partial_{M_2}^\nu \dots \partial_{M_l}^\nu dx_{\nu_1} \dots dx_{\nu_m}$$

* Space of tensors is a vector space

* Can form tensor products

* Can (anti)symmetrize

* Can contract

$$T_{\nu_1 \dots \nu_m}^{M_1 M_2 \dots M_l} \quad (l-1, m-1)\text{-tensor}$$

$$(w_\alpha \otimes u^\alpha)_{(0,0)} \rightarrow (0,0)$$

$$\delta_\nu^M \rightarrow J \cdot \mathbb{I} \cdot J^{-1} = \mathbb{I}$$

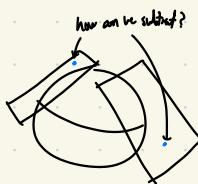
↑
Jacobian

$$T=0 \leftarrow \begin{array}{l} \text{want to find some} \\ \text{invariant equation} \\ \text{coordinate-independent} \end{array}$$

Calculator? $v(A)$ directional derivative?

$T_p M$ vector space \rightarrow at p $v_p - w_p$

$T_p M$ vector space $v_p - w_p \leftarrow$ what???



$$\text{Indeed: } v = v_\alpha^\nu \partial_\nu^\alpha$$

so: $\partial_\mu^\beta (v_\nu^\sigma) \partial_\nu^\alpha \partial_\alpha^\nu$ is this $(1,1)$ -tensor?

$$\frac{\partial}{\partial x_\beta^M} (v_\nu^\sigma) = \frac{\partial x_\beta^M}{\partial x_\alpha^\nu} \partial_\nu^\alpha \left(\frac{\partial x_\nu^\sigma}{\partial x_\mu^\alpha} v_\alpha^\sigma \right)$$

$$= \frac{\partial x_\alpha^\rho}{\partial x_\beta^m} \frac{\partial x_\beta^\sigma}{\partial x_\alpha^\sigma} (\partial_\rho v_\alpha^\sigma)$$

\uparrow
womp
womp

$$+ \frac{\partial x_\alpha^\rho}{\partial x_\alpha^m} \left(\frac{\partial x_\beta^\sigma}{\partial x_\alpha^\sigma} \right) v_\beta^\sigma$$

$\downarrow \nu^\sigma$ ~~not a tensor!~~

$\partial_\mu|_p$ - coordinate basis
a basis for $T_p M$

$$\partial_\mu(f) = \frac{\partial f}{\partial x_\mu^\alpha} = \frac{\partial}{\partial x_\mu^\alpha} (f \circ \gamma_\alpha^{-1})$$

$$M \xrightarrow{f} N \quad f: \text{smooth}$$

f differentiable

preserves differential structure

cubes & spheres diffeomorphic

\rightarrow topology, not geometry

In Minkowski space we had linear structure.

To a worldline:

$$c: \mathbb{R} \rightarrow M$$

$$\lambda \mapsto c(\lambda)$$

$$\lambda \mapsto x^\alpha(\lambda) \text{ in some coordinates}$$

$$v_\lambda(f) = \frac{d}{d\lambda} (f(c(\lambda)))$$

$$= \frac{dx^\alpha}{d\lambda} \cdot \frac{\partial f}{\partial x^\alpha}|_{x(\lambda)}$$

$$v_\lambda = \frac{dx^\alpha}{d\lambda} \cdot \partial_\mu$$

The equivalence principle (SEP) \Rightarrow we can choose x_α^m to be locally inertial coordinates

of $p(\lambda)$ associated to freely falling observer $\oplus p(\lambda)$

then

$$ds^2 = g_{\mu\nu} dx^\mu dx^\nu \text{ invariant interval}$$

A different local inertial observer at $p(\lambda)$

$$x_{\beta}^M = \Lambda_{\beta}^{\mu} x_{\mu}^{\nu} \quad \Lambda_{\mu}^{\mu} \Lambda^{\nu}_{\nu} \circ g_{\mu\nu} = g_{\mu\nu}$$

$$g_{\mu\nu} x_{\mu}^{\mu} x_{\nu}^{\nu} = g_{\mu\nu} x_{\beta}^{\mu} x_{\beta}^{\nu}$$

other coordinates not so simply related to x_{μ}^{μ}

Inertial invariant becomes physical

if $ds^2 < 0$ timelike
 $ds = \sqrt{-ds^2}$ is proper time

A physical property of $p(\lambda)$ worldline
Proper time measured by a clock - physical property
of $p(\lambda)$.

In general coordinates $x'(x)$ nonlinear

$$\frac{dx^{\mu}}{d\lambda} = \frac{\partial x^{\mu}}{\partial x^{\nu}} \frac{dx^{\nu}}{d\lambda} \quad \text{chain rule}$$

$$\begin{aligned} ds &= \sqrt{-g_{\mu\nu} \frac{\partial x^{\mu}}{\partial t} \frac{\partial x^{\nu}}{\partial t}} d\lambda \\ &= \sqrt{-g_{\mu\nu} \frac{\partial x^{\mu}}{\partial x^{\rho}} \frac{\partial x^{\rho}}{\partial t} \frac{\partial x^{\nu}}{\partial x^{\sigma}} \frac{\partial x^{\sigma}}{\partial t}} d\lambda \\ &= \sqrt{-g_{\mu\nu}(x) \frac{dx^{\mu}}{dt} \frac{dx^{\nu}}{dt}} d\lambda \end{aligned}$$

Not invariant

$(0,1)$ -tensor. The metric tensor

Newton $\vec{g}(x)$ acceleration physical
not invariant

$g_{\mu\nu}(x)$ breaks coordinate invariance

\uparrow
property of universe encodes gravitational fields

question: how does g encode gravity?

The Metric

1. What kind of matrix is $g_{\mu\nu}(x)$? (rows)

$$g_{\mu\nu}(x) = y_{\mu\nu} \frac{\partial x^\mu}{\partial x^a} \frac{\partial x^\nu}{\partial x^b}$$

$$g = J^T y J$$

$$J^T y J_{ab}$$

$\det J \neq 0$ non-singular

$\det J > 0$ oriented

$J^T y J_{ab} > 0$ time-preserving

- * $g_{\mu\nu} = g_{\nu\mu}$ symmetric $(0,2)$ -tensor

- * $\det(g) = \det(J)^2 \cdot \det(y) = \det(J)^2 \cdot (-1) < 0$ non-singular
time direction

- * g has signature $(1,3)$
 ↓
 neg. eigenvalue pos. eigenvalue

- * Lorentzian Metric

Riemannian metric: signature $(0,n)$

$$\mathbb{R}^n \quad g_{\mu\nu} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$ds^2 = dx^2 + dy^2 \quad \text{Euclidean plane}$$

Recall Spacetime is a smooth, orientable, time oriented 4-manifold

Intuitively: equipped with a Lorentzian metric

- Equivalence principle (E.P.) $\forall x \in M \exists$ choice of coords s.t.

$\gamma: \mathbb{R} \rightarrow M$ with $\gamma(0) = x \leftarrow$ curve in spacetime starting at x

Worldline of observer then

$$ds = \sqrt{-g_{\mu\nu} dx^\mu dx^\nu}$$

any small region of spacetime: special relativity applies

Let x^μ be coords of such an observer (Local Inertial Observer LIO) @ x

If $x^\mu(\lambda)$ trajectory of a clock

$$\frac{dx^\mu}{d\lambda} \frac{dx^\nu}{d\lambda} < 0 \text{ timelike}$$

Then $d\tau = \sqrt{-g_{\mu\nu} dx^\mu dx^\nu} d\lambda$
 ↑ rate clock is ticking locally

Then in $x^i(x)$

$$j^{\mu}_{\nu\rho}(x) = \frac{\partial x^{\mu}}{\partial x^\nu} \quad j^{\mu}_{\nu\rho} > 0$$

$$\begin{aligned} \gamma(\lambda) &\leftrightarrow x^{\mu}(\gamma(\lambda)) \quad x(\lambda) = x^i(\lambda) \\ d\tau &= \sqrt{-g_{\mu\nu} \frac{\partial x^\mu}{\partial \lambda} \frac{\partial x^\nu}{\partial \lambda}} d\lambda \quad \checkmark \text{nonzero eigenvalues, positive def.} \\ &= \sqrt{-g_{\mu\nu} \frac{\partial x^\mu}{\partial x^\rho} \frac{\partial x^\nu}{\partial x^\sigma} j^\rho_\mu j^\sigma_\nu} d\lambda \\ &= \sqrt{-g_{\mu\nu} j^\mu_\rho j^\nu_\sigma} d\lambda \end{aligned}$$

- Metric $g'_{\mu\nu}(x')$ is a $(0,2)$ -tensor.

- encodes gravitational field

$$g'_{\mu\nu}(x') = g_{\mu\nu} \underbrace{\frac{\partial x^\mu}{\partial x'^\rho} \frac{\partial x^\nu}{\partial x'^\sigma}}_{J \text{ Jacobian}} \text{ for some } x^\mu(x')$$

1)

$$\begin{aligned} g &= J \circ J^T \\ \text{in gravity, this becomes} \\ \text{this becomes} \uparrow & \det(g) = (\det J)^2 \det J = (-1)^n (\det J)^2 < 0 \\ g \text{ has signature } (1,3) &\rightarrow \text{Lorentzian} \end{aligned}$$

2) Can view g to map (l,n) -tensors to $(l-1,m)$ -tensors

$$T^{M_1 \dots M_{l-1} M_l}_{\quad \quad \quad N_1 \dots N_m} g_{\mu\nu} = T^{M_1 \dots M_{l-1}}_{\quad \quad \quad N_1 \dots N_m \nu}$$

$$g_{\mu\nu} V^\nu = V_\mu \quad g_{\mu\nu} V^\mu U^\nu \} \text{ inner product}$$

$$g_{\mu\nu} = g^{\mu\nu} g_{\nu\rho} g_{\mu\alpha}$$

$$(g^{\mu\nu}) = (g^{-1})^{\mu\nu}$$

Example $(0,n)$ Riemannian

"Describe shape via distance"

* $ds^2 = dx^2 + dy^2 = g_{\mu\nu}(x) dx^\mu dx^\nu \quad g = (1,0)$

$$dl = \sqrt{g_{\mu\nu}(x^\lambda) dx^\mu dx^\nu} dt$$

$$= (x^3 y^3)^{1/4} dt$$

dotted and have $dot = 0$

(2nd equivalent example) *

$$ds^2 = dx^2 + x^2 dy^2 \quad (x \neq 0)$$

$$g_{\mu\nu} = \begin{pmatrix} 1 & 0 \\ 0 & x^2 \end{pmatrix}$$

$$dl = \sqrt{dx^2 + x dy^2} = x dy$$

$$y = y + 2\pi$$

→ vertical lines are circles

→ cross-section \rightarrow x

→ plane! This is just polar coordinates

* $ds^2 = dr^2 + f(r)^2 dy^2$

$$\varphi = \varphi + 2\pi$$

→ all directions in plane are same

- $f(r) = 1 \rightarrow$ cylinder

- $f(r) = \alpha r \rightarrow$ cone
↑ ratio of quantity (related to angle)

$$dr^2 = dx^2 + x^2 r^2 d\varphi^2 \quad \alpha = \exp$$

$$= dr^2 + r^2 d\varphi^2 \quad \varphi \sim \theta + \pi/2$$

Invariant tensor: $\delta^\mu_\nu = g^{\mu\rho} g_{\rho\nu}$

$$\epsilon \leftrightarrow dt ds \quad \text{not invariant}$$

$$\int ds \times f(s) \quad \text{not invariant}$$

$\epsilon \rightarrow dt J \zeta$ $g = |g_{\mu\nu}|$

$$g \rightarrow J^{-1} g J^{-1}$$

$$dt dg \rightarrow (\det J)^2 dt dg$$

$$g_{\mu\nu}(x) = g_{\mu\nu} \frac{\partial x^\rho}{\partial x^\mu} \frac{\partial x^\sigma}{\partial x^\nu}$$

Claim 8 $\exists g'_{\mu\nu} \quad x'(x) \text{ s.t. } g'_{\mu\nu} = g_{\mu\nu}$

$x'(x) \text{ s.t. } g'(x'(x=0)) = g_{\mu\nu}$

$x'(0) = 0 \quad g'(0) = g_{\mu\nu}$

$$x'^\lambda(x) = \left. \frac{\partial x'^\lambda}{\partial x^\mu} \right|_{x=0} x^\mu + \frac{1}{2} \left. \frac{\partial^2 x'^\lambda}{\partial x^\mu \partial x^\nu} \right|_{x=0} x^\mu x^\nu + \dots$$

$$g'_{\mu\nu} \Big|_{x=0} = g_{\mu\nu}$$

↑
10 pairs
↔
6 pairs
Lorentz

↑
90 of them (cyclic points)

So can set equal and find $x'(x)$
accordingly

$$g'_{\mu\nu}(x') = g_{\mu\nu} + \partial_\lambda g'_{\mu\nu} \Big|_{x=0} x^\lambda + \dots$$

↑
10 functions → 90 first derivatives

Riemann Normal Coordinates

for us ↓

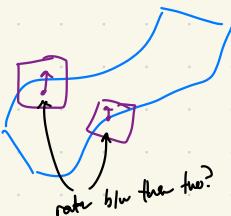
Local Inertial Coordinates

Connections

Def) smooth function if $f: M \rightarrow \mathbb{R}$ smooth

$V_p \in T_p M \quad V_p \in M$

Need: rate of change of a tensor



Def. A connection ∇ on TM is
an action on vector fields.

- ∇u is a $(1,1)$ -tensor recall: $\partial_\mu u^\tau$ is not a $(1,1)$ -tensor
 - $\nabla(u+v) = \nabla u + \nabla v$ ← linear
 - $\nabla(fu) = f\partial_\mu u + df \otimes u$ ← Leibniz
- \uparrow
corrected version
of this

A way to relate $T_p M$ to $T_{p'} M$

In coordinates:

$$u^m \rightarrow (\nabla u)_v^m = \partial_v u^m + A_{v\lambda}^{\mu} u^\lambda$$

↑ not coords of a tensor

$$[(\nabla fu)]_v^m = \partial_v(fu^m) + A_{v\lambda}^{\mu} f u^\lambda$$
$$= f \cdot (\nabla u)_v^m + (\partial_v f) u^m$$

$A_{v\lambda}^{\mu}$ (A) coords of a connection

In coords $x'(x)$ $J^{\mu'}_\lambda = \frac{\partial x'^\mu}{\partial x^\lambda}$ $J^{-1}{}^\lambda_\mu = \frac{\partial x^\lambda}{\partial x'^\mu}$

$$(\nabla u')_{v'}^{\mu'} = J_{v'}^\lambda J_{\lambda}^{\mu'} (\nabla u)_\lambda^p = J_{v'}^\lambda J_{\lambda}^{\mu'} (\partial_\lambda u^p + A_{\lambda\sigma}^p u^\sigma)$$

$$\begin{aligned} &= \underbrace{\left(\frac{\partial}{\partial x'^\mu} u_{\lambda}^{\lambda'} \right)}_{\text{tensor object}} + \underbrace{A_{v'\lambda'}^{\mu'} u^{\lambda'}}_{\text{tensor}} \\ &= J_{v'}^\lambda \partial_\lambda (J_{\lambda}^{\mu'}) + A_{v'\lambda'}^{\mu'} J_{\lambda}^{\lambda'} u^{\lambda'} \\ &\quad - \cancel{J_{v'}^\lambda J_{\lambda}^{\mu'} \partial_\lambda u^{\lambda'} + u^{\lambda'} J_{v'}^\lambda (\partial_\lambda J_{\lambda}^{\mu'})} + A_{v'\lambda'}^{\mu'} J_{\lambda}^{\lambda'} u^{\lambda'} \end{aligned}$$

not
equiv \uparrow $J_{v'}^\lambda J_{\lambda}^{\mu'} (\partial_\lambda u^p + A_{\lambda\sigma}^p u^\sigma)$

$$J_{v'}^\lambda J_{\lambda}^{\mu'} A_{\lambda\sigma}^p u^{\lambda'} = \cancel{J_{v'}^\lambda J_{\lambda}^{\mu'} A_{\lambda\sigma}^p u^{\lambda'}} - \cancel{J_{v'}^\lambda (\partial_\lambda J_{\lambda}^{\mu'}) J_{\lambda}^{\lambda'}}$$

$$A_{v'\lambda'}^{\mu'} = J_{v'}^\lambda J_{\lambda}^{\mu'} A_{\lambda\sigma}^p - J_{v'}^\lambda J_{\lambda}^{\mu'} (\partial_\lambda J_{\lambda}^{\lambda'})$$

If we find such an A , ∇ becomes connection/coordinate derivative

we write $(\nabla u)_v^m = \partial_v u^m$
misleading notation,
interpreted as

"Connections are like projectors. You can't have just one!"

If ∇ is a connection,

$$(\nabla u)_v^m = (\nabla u)_v^m + S_{v\lambda}^{\mu} u^\lambda \quad \text{for any } (1,2)\text{-tensor}$$

is also a connection

∇, ∇' both connections: $\nabla u - \nabla' u = S u$ for some S

Only need to check once:

$$\partial(\omega v) = \nabla(\omega v) := (\partial\omega) \cdot v + \omega \cdot (\nabla v)$$

(ω, v) $(\partial\omega)$ (v)

$$\partial_\mu(\omega v) = (\partial\omega)_\mu v^\lambda + \omega_\lambda (\nabla v)_\mu^\lambda$$

$$\rightarrow (\partial\omega)_\mu v^\lambda = \partial_\mu(\omega v) - \omega_\lambda (\nabla v)_\mu^\lambda$$

$$(\partial_\mu \omega_\lambda)v^\lambda + \omega_\lambda \partial_\mu v^\lambda = \partial_\mu(\omega v) = (\partial\omega)_\mu v^\lambda \quad \omega_\lambda (\nabla v)_\mu^\lambda = (\partial\omega)_\mu v^\lambda + \omega_\sigma^\sigma (\partial_\mu v^\lambda + A_{\mu\sigma}^\sigma v^\lambda)$$

$$(\partial\omega)_\mu = \partial_\mu \omega_\lambda - A_{\mu\sigma}^\sigma \omega_\sigma$$

Let S be (k, m) -tensor

∇S $(k, m+1)$ -tensor

$$(\nabla S)^{M_1 \dots M_k}_{\mu_1 \nu_1 \dots \nu_m} = \partial_\mu S^{M_1 \dots M_k}_{\nu_1 \dots \nu_m}$$

$A_{\mu\nu}^{\sigma\tau} S^{\alpha\beta\dots\mu\sigma}$

$$k \text{ terms} \rightarrow + A_{\mu\alpha}^{M_k} S^{\mu\alpha\dots}$$

$$m \text{ terms} \rightarrow - A_{\mu\nu}^{\sigma} S^{\mu\dots\mu\sigma}_{\nu\dots\nu}$$

Use ∇ to perform parallel transport a tensor $p \rightarrow p'$

Let $\gamma: R \rightarrow M$ be a curve

$$\gamma(0) = p \quad \gamma(1) = p'$$

T parallel transported along γ if

$$\dot{\gamma} \cdot \nabla T = 0$$

$$\frac{d\gamma^\mu}{d\lambda} \cdot (\nabla T)^{M_1 \dots M_k}_{\mu \nu_1 \dots \nu_m} = \frac{d\gamma^\mu}{d\lambda} \partial_\mu T^{M_1 \dots M_k}_{\nu_1 \dots \nu_m}(\gamma(\lambda)) + [\text{connection terms}]$$

u under PT

$$u^m(\gamma(\lambda)) \quad \text{const}$$

$$\frac{\partial \gamma^m}{\partial \lambda} (\partial_\mu u^\nu + A_{\mu\nu}^\sigma \cdot u^\nu) = 0$$

for any connection ∇ , can define

$$T(w, u, v) = w((\nabla v) \cdot u - (\nabla u) \cdot v - [u, v])$$

$$T_{\mu\nu}^\sigma = A_{\mu\nu}^\sigma - A_{\nu\mu}^\sigma$$

$\underbrace{\phantom{A_{\mu\nu}^\sigma - A_{\nu\mu}^\sigma}}$
antisymmetric A
turns this into tensor

torsion tensor of ∇ .

Metric connection

Haus non-degenerate
symmetric
signature $(1,3)$ tensor $g_{\mu\nu}$

Produce ∇ :

- Torsion free $A_{\mu\nu}^\lambda = A_{\nu\mu}^\lambda$
- $Dg = 0$ $(0,3)$ -tensor $\underbrace{}$ replaces A

$$(1) \quad (\partial g)_{\mu\nu\rho} = 0 = \partial_\mu g_{\nu\rho} - \Gamma_{\mu\nu}^\rho g_{\nu\rho} - \cancel{\Gamma_{\nu\mu}^\rho g_{\nu\rho}}$$

$$(2) \quad (\partial g)_{\nu\lambda\mu} = 0 = \partial_\nu g_{\lambda\mu} - \cancel{\Gamma_{\nu\lambda}^\rho g_{\mu\rho}} - \Gamma_{\nu\mu}^\rho g_{\lambda\rho}$$

$$(3) \quad (\partial g)_{\lambda\mu\nu} = 0 = \partial_\lambda g_{\mu\nu} - \cancel{\Gamma_{\lambda\mu}^\rho g_{\rho\nu}} - \cancel{\Gamma_{\lambda\nu}^\rho g_{\mu\rho}}$$

$$\Rightarrow \frac{\partial}{\partial} (\partial_\mu g_{\nu\rho} + \partial_\nu g_{\lambda\rho} - \partial_\lambda g_{\mu\rho}) = (2 \cancel{\Gamma_{\mu\nu}^\rho g_{\rho\lambda}}) g^{\mu\nu} = \Gamma_{\mu\nu}^\sigma$$

Levi-Civita connection

Γ - Christoffel symbols

Spacetime:

- 4-manifold M , oriented, time-oriented

- Lorentzian metric $g_{\mu\nu}$

- Levi-Civita (metric) connection

$$(Dv)_\mu^\nu = \partial_\mu v^\nu + \Gamma_{\mu\lambda}^\nu v^\lambda$$

christoffel symbols

$$\Gamma_{\mu\lambda}^\nu = \frac{1}{2} g^{\nu\rho} (\partial_\mu g_{\rho\lambda} + \partial_\lambda g_{\mu\rho} - \partial_\rho g_{\mu\lambda}) = \Gamma_{\lambda\mu}^\nu$$

This is a connection:

- $(Dv)_\mu^\nu$ is a $(1,1)$ -tensor \rightarrow right Jacobian, no derivatives of Jacobian
- $(Dg)_{\mu\nu\lambda} = \partial_\mu g_{\nu\lambda} - \Gamma_{\mu\nu}^\rho g_{\rho\lambda} - \Gamma_{\mu\lambda}^\rho g_{\nu\rho} = 0$

$$(1) \quad \partial_\lambda (u_\mu v^\mu) = \partial_\lambda (u^\mu v^\nu g_{\mu\nu}) \quad \begin{matrix} \text{disappears} \\ \uparrow \end{matrix} \\ = (\partial_\lambda u^\mu) v_\mu + u_\mu (\partial_\lambda v^\mu) + u^\mu \cancel{\partial_\lambda g_{\mu\nu}}$$

normal partial equal to covariant derivative
for functions $\partial_\mu = D_\mu$

$$D_{\mu\nu} v^\mu = D^\mu v_\mu$$

At any $x \in M \exists$ L.I.C. riemann
metric
(parallel vector)

$$\begin{aligned} & \hat{g}_{\mu\nu} = g_{\mu\nu} \\ & \hat{\partial}_\lambda \hat{g}_{\mu\nu} = 0 \quad \Rightarrow \quad \hat{\Gamma}_\mu^{\nu\lambda} = 0 \end{aligned}$$

Parallel Transport:

$$\gamma: [0,1] \rightarrow M \quad x^\mu(t)$$

T is parallel transported along γ if

$$\dot{x}^\mu (\nabla_T)_{\mu}^{\nu} = 0$$

flat space $(\vec{x} \cdot \vec{v}) f = 0$

f constant along curve

$$\frac{d}{dt} f(x(t)) = (\vec{x} \cdot \vec{v}) f(x(t))$$

If T tangent vector

$$\begin{aligned} \dot{x}^\mu (\nabla_T)_{\mu}^{\nu} &= \dot{x}^\mu \partial_\mu v^\nu + \Gamma_{\mu\lambda}^\nu \dot{x}^\mu v^\lambda \\ &= \frac{d}{dt} v^\nu(x(t)) + \Gamma_{\mu\lambda}^\nu(x(t)) \dot{x}^\mu(t) v^\lambda(x(t)) \end{aligned}$$

"Is the velocity p.t.d along the curve staff"

Spatial axes

$y \leftrightarrow x^m(t)$ is a geode of g if

$u^{\mu}(t) = x^\mu$ is P.T. along γ

$$\begin{aligned} \frac{d}{ds} \lambda \left(u^m(s) \right) + \int_{\nu_p}^{s^*} x^\gamma(s) u^p(s) = & \frac{d}{ds} u^m(s) + \int_{\nu_p}^{s^*} u^\gamma u^p \\ = & \frac{d}{ds} x^m(s) + \int_{\nu_p}^{s^*} x^\gamma x^p \\ = & (\hat{u}^\gamma D_x \hat{u}^m)(x(s)) \quad \hat{u}^\gamma(s) \quad \hat{u}^m(x(s)) = u^m(s) \end{aligned}$$

In LIC. @ x,

$$\begin{aligned} \hat{g}_{\mu\nu} &= g_{\mu\nu} \\ \hat{\Gamma}^{\lambda}_{\mu\nu} &= 0 \end{aligned}$$

$\frac{d}{dt} \hat{x}^\mu + \sum_{\nu=1}^M \hat{\Gamma}^{\mu}_{\nu\nu} \dot{x}^\nu = 0$

constant velocity = initial trajectory of freely falling

Inverted: free-falling (FF) paths' worldlines are timelike geodesics

$$\text{Note: } \frac{d}{dt} (g_{\mu\nu}(x(t)) u^\mu(t) u^\nu(t)) = \hat{u}^\mu D_\mu(g_{\mu\nu} \hat{u}^\nu) - g_{\mu\nu} [\hat{u}^\rho (D_\rho \hat{u}^\mu) \hat{u}^\nu + \hat{u}^\mu \hat{u}^\nu D_\rho \hat{u}^\rho]$$

$$\frac{d^2}{dt^2} x^* + \int_{-\infty}^M (x(\lambda)) \dot{x}^*(\lambda) \dot{x}^*(\lambda) = 0$$

number scores onto age

Initial address: $\chi^m(0)$

$$x^m(0) \quad x^{m_{x,v}} g_{uv}(x(0)) = 1 \quad x^0 > 0$$

3! Solution $x^m(\tau)$

fəʊls:

- (1) Goodies cross :-
 (2) Goodies end :- } singularities

$$M_{\text{eigenvectors}} : \frac{d}{dt} k^m(\lambda) + \Gamma_{k^m}^{k^n} k^n(\lambda) k^o(\lambda) = 0$$

- affine parameter $k^2 = 0$

$$V^M = 4 - \text{new_dim}$$

Curvature

For any $u^\mu(x)$

$$\begin{aligned} D_\lambda D_\sigma u^\mu &= \partial_\lambda (D_\sigma u^\mu) - \Gamma_{\lambda\sigma}^\rho D_\rho u^\mu + \Gamma_{\sigma\lambda}^\mu D_\sigma u^\rho \\ &= \partial_\lambda \partial_\sigma u^\mu + (\partial_\lambda \Gamma_{\sigma\rho}^\mu) u^\rho + \Gamma_{\sigma\lambda}^\mu \partial_\sigma u^\rho \\ &\quad - \Gamma_{\lambda\sigma}^\rho \partial_\rho u^\mu - \Gamma_{\sigma\lambda}^\rho \Gamma_{\rho\sigma}^\mu u^\mu + \Gamma_{\sigma\lambda}^\mu \partial_\sigma u^\rho + \Gamma_{\sigma\lambda}^\mu \Gamma_{\rho\sigma}^\rho u^\mu \end{aligned}$$

$\lambda \leftrightarrow \sigma$

$(1,2)$ -tensor

$$[D_\lambda, D_\sigma] u^\mu = \left[\partial_\lambda \Gamma_{\sigma\rho}^\mu - \partial_\sigma \Gamma_{\lambda\rho}^\mu + \Gamma_{\sigma\lambda}^\rho \Gamma_{\rho\mu}^\mu - \Gamma_{\sigma\lambda}^\mu \Gamma_{\rho\mu}^\rho \right] u^\rho$$

commutator

Must be $(1,3)$ -tensor

$$R^\mu_{\rho\lambda\sigma} = \partial_\lambda \Gamma_{\sigma\rho}^\mu - \partial_\sigma \Gamma_{\lambda\rho}^\mu + \Gamma_{\sigma\lambda}^\rho \Gamma_{\rho\mu}^\mu - \Gamma_{\sigma\lambda}^\mu \Gamma_{\rho\mu}^\rho$$

Riemann curvature

$$F_{\lambda\sigma} = \partial_\lambda A_\sigma - \partial_\sigma A_\lambda + A_\lambda A_\sigma$$

Torsion

Spacetime has:

$$ds^2 = g_{\mu\nu}(x) dx^\mu dx^\nu$$

• A metric $g_{\mu\nu}$ invertible

• A connection $\Gamma_{\mu\nu}^\lambda = \frac{1}{2} g^{\lambda\rho} (\partial_\mu g_{\rho\nu} + \partial_\nu g_{\rho\mu} - \partial_\rho g_{\mu\nu})$

• Geodesics $\frac{dx^\mu}{d\lambda} + \Gamma_{\mu\nu}^\lambda \frac{dx^\nu}{d\lambda} \frac{dx^\lambda}{d\lambda} = 0$ - invertible worldlines

• Curvature $[D_\lambda, D_\sigma] V^\mu = R^\mu_{\rho\lambda\sigma} V^\rho$

$$R^\mu_{\rho\lambda\sigma} = \partial_\lambda \Gamma_{\sigma\rho}^\mu - \partial_\sigma \Gamma_{\lambda\rho}^\mu + \Gamma_{\sigma\lambda}^\rho \Gamma_{\rho\mu}^\mu - \Gamma_{\sigma\lambda}^\mu \Gamma_{\rho\mu}^\rho$$

\hookrightarrow is a tensor!

How many independent components does $R^\mu_{\rho\lambda\sigma}$ have in d -dimensional space?

Naively: $\frac{d^4 \times 256}{d \cdot 4!}$

$$\text{but } R^\mu_{\rho\lambda\sigma} = -R^\mu_{\lambda\sigma\rho}$$

$$\text{So } \cancel{\frac{d^4 \times 256}{d \cdot 4!}} = \frac{d^4 \times 96}{2}$$

$$R_{\mu\nu\rho\sigma} = g_{\mu\rho} R^\rho_{\nu\lambda\sigma}$$

In L.I.C. @ x

$$\hat{g}_{\mu\nu} = g_{\mu\nu}$$

$$\partial_\lambda \hat{g}_{\mu\nu} = 0 \Rightarrow \hat{\Gamma}_{\mu\nu}^\lambda = 0$$

$$\hat{R}_{\mu\nu\rho\sigma} = g_{\mu\rho} (\partial_\lambda \hat{\Gamma}_{\sigma\nu}^\lambda - \partial_\sigma \hat{\Gamma}_{\lambda\nu}^\lambda)$$

$$\hat{R}_{\mu\nu}^{\lambda\sigma}(r) = \frac{1}{2}\hat{g}^{\lambda\sigma}(\partial_\mu\hat{g}_{\nu\lambda} + \partial_\nu\hat{g}_{\mu\lambda} - \partial_\lambda\hat{g}_{\mu\nu}) \quad \hat{g} = g + \mathcal{O}(r^{-1})$$

$$\hat{R}_{\mu\nu\lambda\sigma} = \frac{1}{2}(\partial_\mu\partial_\nu\hat{g}_{\lambda\sigma} + \partial_\lambda\partial_\sigma\hat{g}_{\mu\nu} - \partial_\lambda\partial_\mu\hat{g}_{\nu\sigma} - \partial_\nu\partial_\sigma\hat{g}_{\mu\lambda} - \partial_\lambda\partial_\nu\hat{g}_{\mu\sigma} + \partial_\sigma\partial_\mu\hat{g}_{\nu\lambda})$$

Symmetry: antisymmetric in $\mu \leftrightarrow \nu$

$$R_{\mu\nu\lambda\sigma} = -R_{\lambda\sigma\mu\nu}$$

$$\cancel{\frac{1-d}{2}} \rightarrow \frac{(d-1)}{2} \quad d=4 \text{ "36"}$$

$$(\mu\nu) \leftrightarrow (\lambda\sigma)$$

$$R_{\mu\nu\lambda\sigma} = R_{\lambda\sigma\mu\nu}$$

$$\cancel{\frac{1}{2}(1-d)} \rightarrow \frac{d(d-1)}{2} \left[\frac{d(d-1)}{2} + 1 \right] \quad d=4 \text{ "21"}$$

More symmetry:

$$R_{\mu\nu\lambda\sigma} + R_{\mu\lambda\sigma\nu} + R_{\mu\lambda\nu\sigma} = 0$$

$$\Leftrightarrow R_{\mu[\nu\lambda\sigma]} = 0$$

$$\Leftrightarrow R_{[\mu\nu\lambda\sigma]} = 0$$

$$\frac{d(d-1)}{4} \left(\cancel{\frac{1}{2}(1-1)} + 1 \right) \rightarrow \frac{d(d-1)}{4} \left[\frac{d(d-1)}{2} + 1 \right] - \binom{d}{2}$$

$$d=4 \Rightarrow 20$$

$$= \frac{1}{16} d^2 (d^2 - 1)$$

$$\hat{D}_\rho \hat{R}^\mu_{\nu\lambda\sigma} = \partial_\rho \hat{R}^\mu_{\nu\lambda\sigma}$$

$$= \partial_\rho \partial_\lambda \hat{R}^\mu_{\nu\sigma} - \partial_\rho \partial_\sigma \hat{R}^\mu_{\nu\lambda}$$

$$\underbrace{\hat{D}_\rho \hat{R}^\mu_{\nu\lambda\sigma} + \hat{D}_\lambda \hat{R}^\mu_{\nu\rho\sigma} + \hat{D}_\sigma \hat{R}^\mu_{\nu\lambda\rho}}_{\text{torsion antisymmetry}} = 0$$

$$\hat{D}_[\rho R_{\mu\nu]\lambda\sigma} = 0 \quad \text{Bianchi identity}$$

$$R^\mu_{\nu\lambda\sigma} = R_{\nu\lambda} = R_{\lambda\nu} \quad \text{Ricci tensor}$$

$$R_{\nu\lambda} = g^{\mu\sigma} R_{\mu\lambda\sigma}$$

$$g^{\mu\nu} R_{\mu\nu} = R \quad \text{Ricci scalar}$$

$$\text{Bianchi: } O = g^{\mu\nu} g^{\lambda\sigma} (D_\mu R_{\nu\sigma\lambda} + D_\nu R_{\mu\sigma\lambda} + D_\sigma R_{\mu\nu\lambda}) \\ \Rightarrow D^\mu R_{\mu\nu} + D^\nu R_{\mu\lambda} - D_\mu R = \frac{1}{2} D^\mu R_{\mu\nu}$$

$R \rightsquigarrow$ measure of how much covariant derivatives commute

R measures path-dependence of P.T. \leftarrow parallel transport

$$\gamma: [0, 1] \rightarrow M$$

$$\gamma(0) = \gamma(1) = p$$

$$v(0) \in T_p M$$

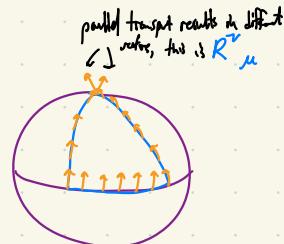
$$ds = \gamma$$

$$= \sum ds_i$$

$$\frac{dv^\mu(\lambda)}{d\lambda} + \Gamma_{\nu\sigma}^\mu(x(\lambda)) v^\nu(\lambda) \cdot \frac{dx^\sigma(\lambda)}{d\lambda} = 0$$

$$\text{Plug in IC + solve } \Rightarrow v(1) = v(0) + R_{(x)}^M v(0)$$

$$R_{(x)} \ll 1 \quad R_{(x)} = \sum R_{(x_i)}$$



$$v^\mu(\lambda) = v^\mu(0) - \int_0^\lambda \Gamma_{\nu\sigma}^\mu(x(s)) \frac{dx^\nu(s)}{ds} v^\sigma(s) ds$$

$$v^\sigma(s) \approx v^\sigma(0) - \Gamma_{\rho\lambda}^\sigma(x(0)) v^\lambda(0) (x^\rho(s) - x^\rho(0)) + \mathcal{O}(s^2)$$

$$\Gamma_{\nu\sigma}^\mu(x(s)) = \Gamma_{\nu\sigma}^\mu(x(0)) + \partial_\rho \Gamma_{\nu\sigma}^\mu(x(0)) (x^\rho(s) - x^\rho(0)) + \mathcal{O}(s^2)$$

$$v^\mu(\lambda) \approx v^\mu(0) - \Gamma_{\nu\sigma}^\mu(p) v^\sigma(0) \int_0^\lambda \frac{dx^\nu(s)}{ds} ds + \left(\partial_\rho \Gamma_{\nu\sigma}^\mu(p) - \Gamma_{\nu\lambda}^\mu(p) \Gamma_{\lambda\sigma}^\lambda(p) \right) v^\sigma(0) \int_0^\lambda (x^\rho(s) - x^\rho(0)) \frac{dx^\nu}{ds} ds$$

$$\int_0^\lambda (x^\rho(s) - x^\rho(0)) \frac{dx^\nu}{ds} ds \quad (\partial_\rho \Gamma_{\nu\sigma}^\mu + \Gamma_{\nu\lambda}^\mu \Gamma_{\lambda\sigma}^\lambda)$$

$$R_{(x)}^\mu \approx R_{(x)}^\mu \text{ for } \partial_\rho \Gamma_{\nu\sigma}^\mu$$

$$R_{(x)}^\mu = \int_s R_{(x)}^\mu ds$$

Cloud of infinitesimal probes

$$u^\mu(x)$$

$$u^\nu D_\nu u^\mu(x) = 0$$

\odot $x^\mu(z)$

$$\frac{dx^\mu}{dz} + \Gamma_{\nu\sigma}^\mu(x(z)) \frac{dx^\nu}{dz} \frac{dx^\sigma}{dz} = 0$$

$y^M(\lambda)$ nearly vertical

$$\frac{dx^M(\tau)}{d\tau} = u^M(\tau)$$

$$y^M(\tau) = x^M(\tau) + y^M(\tau)$$

$$u_{\mu\nu} y^\mu = 0$$

$$\tau \approx \text{parameter } \frac{dy^M}{d\tau} \frac{dy^\nu}{d\tau} g_{\mu\nu}(y(\tau))$$

$$\frac{dy^M}{d\tau} = u^M(y(\tau))$$

$$H(v(x)) \text{ defn } D_{(u)} v^\mu = u^\nu D_\nu v^\mu$$

$$\textcircled{2} \quad x(\tau) \quad D_{(u)} v^\mu \Big|_{y(x)} = \frac{dx^\nu}{d\tau} \left(D_\nu v^\mu + \Gamma_{\nu\lambda}^\mu v^\lambda \right) \\ = \frac{du^\mu(x(\tau))}{d\tau} + \Gamma_{\nu\lambda}^\mu v^\nu \frac{dx^\lambda}{d\tau}$$

$$D = D_{(u)}(u_{\mu\nu} y^\mu) = u_{\mu\nu} D_{(u)} y^\mu \\ = \boxed{D_{(u)} u_{\mu\nu}} y^\mu$$

$$u^\mu = (1, \vec{v})$$

$$y^\mu = (0, \vec{y})$$

$$D_{(u)} y^\mu \frac{dy^\nu}{d\tau} = (0, \vec{v})$$

$$D_{(u)}^2 y^\mu = (0, \vec{a})$$

$$a^i = R^i_{00j} y^j$$

$$u^\mu(y(\tau)) = \frac{dy^\mu}{d\tau} = \frac{dx^\mu}{d\tau} + \frac{dy^\mu}{d\tau} = u^\mu(\tau) + \frac{dy^\mu}{d\tau}$$

$$u^\mu(y) - u^\mu(x) = \frac{dy^\mu}{d\tau} = y^\nu \partial_\nu u^\mu(x(\tau))$$

$$D_{(u)} y^\mu = \frac{dy^\mu}{d\tau} + \Gamma_{\nu\lambda}^\mu u^\nu y^\lambda$$

$$y^\nu \partial_\nu + \Gamma_{\nu\lambda}^\mu u^\nu y^\lambda$$

$$y^\nu (D_\nu u^\mu + \Gamma_{\nu\lambda}^\mu u^\nu) = y^\nu D_\nu u^\mu$$

$$\begin{aligned} D_{(u)}^2 y^\mu &= D_{(u)}(y^\nu D_\nu u^\mu) \\ &= (D_{(u)} y^\nu)(D_\nu u^\mu) + y^\nu (D_{(u)} D_\nu u^\mu) \\ &= (y^\lambda D_\lambda u^\mu)(D_\nu u^\mu) + y^\nu u^\lambda D_\lambda D_\nu u^\mu \\ &\quad + y^\lambda D_\lambda u^\mu \cdot D_\nu u^\mu + y^\nu u^\lambda (D_\nu D_\lambda u^\mu + D_\lambda D_\nu u^\mu) \end{aligned}$$

$$u^\lambda D_\lambda D_\nu u^\mu = D_\nu (u^\lambda D_\lambda u^\mu) - (D_\lambda u^\mu) D_\lambda u^\mu$$

$$D_{(u)}^2 y^\mu = R^M_{\sigma\lambda\nu} u^\sigma u^\lambda y^\nu$$

$$\text{Gauß'sche: } \frac{d^2 x^\mu}{dt^2} + \Gamma_{\nu\sigma}^\mu \frac{dx^\nu}{dt} \frac{dx^\sigma}{dt} = 0$$

$$\text{In L.I.C.: } \frac{d^2 \tilde{x}^\mu}{dt^2} = 0$$

More generally: Lorentz-invariant equation

$$\partial_\mu \rightarrow D_\mu \quad \text{Minimal Coupling}$$

↑
replace

- Tensor
- Reduces to S.R. in L.I.C.

Maxwell:

$$\begin{aligned} \text{curls inhom.} & \rightarrow \partial_\mu f^{\mu\nu} = -4\pi j^\nu \\ \text{curls homogeneous} & \rightarrow \partial_{[\mu} f_{\nu]\sigma} = 0 \quad \Rightarrow \quad \partial_\mu j^\mu = 0 \\ & \quad \quad \quad \text{continuity equation for charge} \\ & \quad \quad \quad = \frac{1}{3!} \epsilon^{\mu\nu\rho} \partial_\mu P_{\nu\rho} \end{aligned}$$

Minimally coupl.:

$$\begin{aligned} D_\mu P^{\mu\nu} &= -4\pi j^\nu \\ D_{[\mu} P_{\nu]\sigma} &= 0 \quad \Rightarrow \quad D_\mu j^\mu = 0 \end{aligned}$$

$$Q(t) = \int d^3 \vec{r} j^0(t, \vec{r})$$

- Lorentz-invariant
- Conserved with suitable boundary condition
- $\frac{dQ}{dt} = 0$

$$Q(t) = \int d^3 \vec{r} j^0(t, \vec{r})$$

- not transformation invariant
- not conserved

$$\text{General coordinate theory: } Q(t) = \int d^3 \vec{r} \sqrt{|g|} j^0(t, \vec{r})$$

$$0 = \partial_\mu (\sqrt{|g|} j^\mu) = \sqrt{|g|} D_\mu j^\mu$$

- conserved
- invariant

$$M \frac{d^2 \tilde{x}^\mu}{dt^2} = -q F_\sigma^\mu(x(c)) \frac{dx^\sigma}{dt}$$

$$\frac{d^2 x^\mu}{dt^2} + \Gamma_{\nu\sigma}^\mu \frac{dx^\nu}{dt} \frac{dx^\sigma}{dt} = -q_m F_\sigma^\mu \frac{dx^\sigma}{dt}$$

$$T_{\sigma\mu}^{\mu\nu} = \frac{1}{9\pi} (f^{\mu\alpha} f^{\nu\beta} g_{\alpha\beta} - \frac{1}{3} g^{\mu\nu} f^{\alpha\beta} f_{\alpha\beta})$$

$$D_\mu T_{\sigma\mu}^{\mu\nu} = -f^{\nu\sigma}_\alpha j^\alpha$$

$$D_\mu T_{\sigma\mu}^{\mu\nu} = -f^{\nu\sigma}_\alpha j^\alpha$$

Note: $0 = D_\mu T^{\mu\nu} = \underbrace{\partial_\mu T^{\mu\nu}}_{\frac{1}{\sqrt{|g|}} \partial_\mu (\sqrt{|g|} T^{\mu\nu})} + \underbrace{\Gamma_{\mu\sigma}^\mu T^{\sigma\nu}}_{\Gamma_{\mu\sigma}^\mu} + \underbrace{\Gamma_{\sigma\mu}^\mu T^{\mu\nu}}_{\Gamma_{\sigma\mu}^\mu}$

\downarrow means it's a tensor
 $p^{\mu\nu}(t) = \int d^3\vec{r} \sqrt{-g} T^{\mu\nu}(t, \vec{r})$

- tensor
- not conserved

"No shift; gravity does not conserve energy"

Free particle

$$T_{\alpha\beta}^{\mu\nu} = p^\mu(t) \frac{dx^\nu}{dt} \delta^{(1)}(\vec{r} - \vec{r}(t))$$

$$= \frac{m}{\sqrt{-g}} \left(\int d\tau \frac{dx^\mu}{d\tau} \frac{dx^\nu}{d\tau} \right) \delta^{(1)}(\vec{x} - \vec{x}(\tau))$$

minimized coupling not a tensor, mass still up

$$I = \int d\tau \delta^{(1)}(\vec{x} - \vec{y}) = \int d\tau \sqrt{-g} \left[\frac{1}{\sqrt{-g}} \delta^{(1)}(\vec{y}) \right]$$

Tensor yay!

Is it conserved?

$$D_\mu T^{\mu\nu} = \frac{m}{\sqrt{-g}} \left[\int d\tau \frac{dx^\mu}{d\tau} \frac{dx^\nu}{d\tau} \partial_\mu \delta^{(1)}(\vec{x} - \vec{x}(\tau)) + \Gamma^{\mu\nu} \int d\tau \frac{dx^\mu}{d\tau} \frac{dx^\nu}{d\tau} \delta^{(1)}(\vec{x} - \vec{x}(\tau)) \right. \\ \left. - \frac{d}{d\tau} \delta^{(1)}(\vec{x} - \vec{x}(\tau)) \right]$$

$$= \frac{m}{\sqrt{-g}} \int d\tau \left[\frac{d^2x^\nu}{d\tau^2} + \Gamma^{\mu\nu}(\vec{x}(\tau)) \frac{dx^\mu}{d\tau} \frac{dx^\nu}{d\tau} \right] \delta^{(1)}(\vec{x} - \vec{x}(\tau))$$

A free particle conserves energy (conservatively)

\Leftrightarrow it follows a geodesic

\Leftrightarrow it is in freefall

Def: $T^{\mu\nu} u^\alpha = p^\alpha u^\mu(x) u^\nu(x)$

 $u^\mu D_\mu u^\nu = 0$ geodesics
 $p^\mu u^\nu D_\mu u^\nu = f^\nu \circ j^\mu$ charge
 $\Rightarrow D_\mu T^{\mu\nu} = f^\nu \circ j^\mu$

Takeaway:

- ① $D_\mu T^{\mu\nu}$ is equation of motion
- ② $\mathcal{O}(t) = \int d^3\vec{r} \sqrt{-g} f^\nu \circ j^\mu$ total scale invariant
- $p^\mu(t) = \int d^3\vec{r} \sqrt{-g} T^{\mu\nu}(t, \vec{r})$ vector not conserved

An observer w/ 4-velocity $\vec{\zeta}^\mu$ means
E-M density $T^{\mu\nu} \zeta_\mu = j^\mu(z)$

Is $D_\mu j^\mu_{(E)} = 0$?

$$D_\mu j^\mu_{(E)} = D_\mu T^{\mu\nu} \bar{e}_\nu + T^{\mu\nu} D_\mu \bar{e}_\nu$$

$$D_\mu j^\mu_{(E)} = 0 \text{ iff } D_\mu \bar{e}_\nu + D_\nu \bar{e}_\mu = 0 \text{ Killing's equation}$$

metric \rightarrow connection

$$\text{E.O.M. } D_\mu T^{\mu\nu} = 0$$

$$\text{Local (tidal) effects } R^\mu_{\sigma\mu\nu} = \partial_\sigma \Gamma^\mu_{\nu\nu} - \partial_\nu \Gamma^\mu_{\sigma\nu} + \Gamma^\mu_{\lambda\mu} \Gamma^\lambda_{\sigma\nu} - \Gamma^\mu_{\sigma\mu} \Gamma^\lambda_{\lambda\nu}$$

Geometric Derivation

limit, weak static fields

$$D^\mu y^\mu = -R^\mu_{\sigma\mu\nu} u^\sigma u^\nu \stackrel{?}{=} j^\mu \partial_\mu \phi \gamma^\nu$$

$$\text{L.C.G. } a^\mu = -R^\mu_{\sigma\mu\nu} u^\sigma u^\nu$$

$$\text{Newtonian: } a^\mu = y^\mu \partial_\mu (-\partial_\nu \phi) = -\partial_\nu \partial_\mu \phi y^\mu \quad \partial^\mu \partial_\mu \phi \sim \partial_\nu \partial_\mu \phi y^\mu = 4\pi G \rho = 4\pi G u^\mu u^\nu T_{\mu\nu}$$

$$R^\mu_{\sigma\mu\nu} u^\sigma u^\nu$$

$$R_{\mu\nu\rho} = 4\pi G T_{\mu\nu\rho} \quad \text{Einstein!}$$
$$R = 8\pi G T$$
$$T_{\mu\nu} = T$$

$$\text{Bianchi: } D^\mu R_{\mu\nu} = \frac{1}{2} D_\nu R = \frac{1}{2} \partial_\nu R$$

$$G_{\mu\nu} = R_{\mu\nu} - \frac{1}{2} g_{\mu\nu} R$$

$$D^\mu G_{\mu\nu} = D^\mu R_{\mu\nu} - \frac{1}{2} g_{\mu\nu} D^\mu R = 0$$

$$G_{\mu\nu} = k T_{\mu\nu} \Rightarrow D_\mu T^{\mu\nu} = 0$$

$$G = kT$$

$$= R - 2R = -R$$

$$R_{\mu\nu} = k \left(T^{\mu\nu} - \frac{1}{2} g_{\mu\nu} T \right) = k \left(\rho + \frac{1}{3} u^2 (\rho) \right) = \frac{k}{3} \rho = 4\pi G \rho$$

$$\text{If } T_{\mu\nu} = \rho u^\mu u^\nu = g_{\mu\nu} g(u^\mu)$$
$$\sim -\rho$$

$$T = \rho u^2 = -\rho$$

$$G_{\mu\nu} = R_{\mu\nu} - \frac{1}{2} g_{\mu\nu} R = 8\pi G T_{\mu\nu}$$

Einstein's equations

$$\text{Einstein's equation: } G_{\mu\nu} = R_{\mu\nu} - \frac{1}{2} g_{\mu\nu} R = 8\pi G T_{\mu\nu}$$

$$\Rightarrow D_\mu T^{\mu\nu} = 0$$

1) 10 unknown nonlinear PDEs for $g_{\mu\nu}$ given $T_{\mu\nu}$

$$+ \text{constraint: } D_\mu G^{\mu\nu} = 0$$

\Rightarrow 6 eqns for 10 $g_{\mu\nu}$ \Rightarrow determine $g_{\mu\nu}$ up to 4 functions $\rightarrow x^i(x)$

coordinate transformation!

2) In vacuum $T_{\mu\nu} = 0$

independently,

$$\left[\begin{array}{l} g^{\mu\nu} G_{\mu\nu} = R - 2R = 8\pi G T \\ R_{\mu\nu} = 8\pi G (T_{\mu\nu} - \frac{1}{2} g_{\mu\nu} T) \end{array} \right]$$

Specifying with $R_{\mu\nu} = 0$: Einstein Manifolds

Ricci flat

Still nonlinear!

3) Traceless part of $R^\mu_{\mu\nu\rho\sigma}$

Way:

$$\begin{aligned} C_{\mu\nu\rho\sigma} &= R_{\mu\nu\rho\sigma} - \frac{1}{d-2} [g_{\mu\rho} R_{\nu\sigma} - g_{\mu\sigma} R_{\nu\rho} \\ &\quad + g_{\nu\rho} R_{\mu\sigma} - g_{\nu\sigma} R_{\mu\rho}] \\ &\quad + \frac{1}{(d-2)(d-1)} (g_{\mu\rho} g_{\nu\sigma} - g_{\mu\sigma} g_{\nu\rho}) R \\ &= \frac{d^2(d-1)}{12} - \frac{1}{2} d(d-1) = \frac{1}{12} d(d+1)(d-3) \quad d \geq 3 \\ &\quad J=4 \quad d=10 \end{aligned}$$

$$C^\mu_{\mu\nu\rho\sigma} = 0$$

4) Read it backwards (left-to-right!)

10 (9) algebraic equation for $T_{\mu\nu}$

Any $g_{\mu\nu}$ "solves" Einstein Equations
most require "nonphysical" $T_{\mu\nu}$

Restriction on $T_{\mu\nu}$:

- Energy density positive, Weak Energy Condition

$$T_{\mu\nu} \text{ timelike, } T_{\mu\nu} u^\mu u^\nu \geq 0$$

coordinate-independent

$$p \geq 0 \quad p = \rho \geq 0$$

- Null energy condition:

$$V \text{ null} \quad T_{\mu\nu} k^\mu k^\nu \geq 0$$

$$\rho + p \geq 0$$

- Dominant energy condition: timelike or null

weak \rightarrow future-directed causal y^μ

$$T^\mu_\nu \rightarrow Y^\mu \quad \text{future-directed}$$

causal

$$\rho \geq |p|$$

$$Y^\mu = (Y^0, \vec{y}) \quad c \text{ light} = \text{speed of light}$$

\hookrightarrow causal: $g_{\mu\nu} Y^\mu Y^\nu \leq 0$

\hookrightarrow future-directed: $y^0 > 0$

- Strong EC:

$$V \text{ timelike } u^\mu, \quad R_{\mu\nu} u^\mu u^\nu \times (T_{\mu\nu} - \frac{1}{2} g_{\mu\nu} T) u^\mu u^\nu \geq 0$$

$$T_{\mu\nu} = \begin{pmatrix} \rho & p & p & p \\ p & p & 0 & 0 \\ p & 0 & p & 0 \\ p & 0 & 0 & p \end{pmatrix} \quad \begin{array}{l} \rho + p \geq 0 \\ \rho + 3p \geq 0 \end{array} \quad \begin{array}{l} \text{spacelike hyperbolae} \\ (@t=0) \end{array}$$

- 5) Hypo: specify suitable initial condition on $T_{\mu\nu}$ (+ boundary conditions)
 $\rightarrow \exists!$ solution for some time

Singularity Theorems (1970 ...):

general initial conditions exclude singularities

in finite proper time in future and/or past

GR is incomplete!

Quantum Mechanical effects significant

$$@ M_p C^2 \sim 10^{28} \text{ GeV}$$

6) V tensor: $\stackrel{\text{symmetric}}{g_{\mu\nu}} \stackrel{\text{conserved}}{J_{\mu\nu}} \Leftrightarrow G_{\mu\nu} + \Lambda g_{\mu\nu} = kT_{\mu\nu}$

$$\frac{1}{2} \nabla^\mu h_{\mu\nu} = R_{\mu\nu} \sim R_{\mu\nu} u^\mu u^\nu$$

$$R_{\mu\nu} = \frac{1}{2} \partial_\mu \partial_\nu h_{\alpha\beta} - \partial_\mu \partial_\nu \phi$$

$$k \cdot \epsilon \pi G \quad \nabla^2 \phi = \frac{k}{\epsilon} \rho - \Lambda$$

$$\vec{\nabla} \phi = \vec{\theta} = -\frac{GM}{r^2} \hat{r} + \Lambda \hat{r}$$

$$G_{\mu\nu} = 8\pi G (T_{\mu\nu} - \frac{1}{8\pi G} g_{\mu\nu})$$

$$\rho = + \frac{\Lambda}{8\pi G} \quad p = -\rho$$

$$\frac{\Lambda}{8\pi G} \sim 10^{-4} \text{ erg/cm}^3$$

$$R_{\mu\nu} - \frac{1}{2} g_{\mu\nu} R = 8\pi G T_{\mu\nu}$$

* Vacuum Solution $T_{\mu\nu} = 0$

$$R_{\mu\nu} = 0$$

$$g_{\mu\nu} = g_{\mu\nu} \checkmark \text{ more?}$$

* Lie symmetries \leftrightarrow isometries \leftrightarrow Killing vectors

* Perturbation / linearization $D_\mu \tilde{\xi}_\nu + D_\nu \tilde{\xi}_\mu = 0$

* Numerical $j_z^\mu = T^{\mu\nu} \tilde{\xi}_\nu \Rightarrow D_\mu j_z^\mu = 0$

Start: vacuum outside a spherical static distribution

$$\text{Newton: } \phi_g = -\frac{GM}{r}$$

@ x , basis for $T_x M$

$$u = u^\mu \frac{\partial}{\partial x^\mu} = u^\mu j_\mu$$

$$\frac{\partial}{\partial t} \quad \frac{\partial}{\partial x^i} \quad \frac{\partial}{\partial (x^i)} = \left(\begin{array}{c} 1 \\ 0 \end{array} \right)$$

$$\frac{\partial}{\partial x^i} \quad \frac{\partial^{(1)}}{\partial (x^i)} \cdot \frac{\partial^{(1)}}{\partial (x^j)} : g_{\mu\nu}(x)$$

Stationary spacetime: symmetry under time translations

\exists const (t, \vec{x}) s.t. $ds^2 = g_{\mu\nu}(t) dx^\mu dx^\nu$

we distinguish time by \downarrow invariant under time translation
 $(\partial_t)^2 < 0 \quad (\partial_i)^2 > 0 \forall i$

$$\tilde{\xi} = \partial_t \quad \tilde{\xi}^\mu = \left(\begin{array}{c} 1 \\ 0 \end{array} \right) \quad \tilde{\xi}_\nu = g_{\nu t}$$

$$D_\mu \tilde{\xi}_\nu + D_\nu \tilde{\xi}_\mu = \partial_\mu g_{\nu t} - \sqrt{-g} \partial_\nu g_{t\lambda}$$

$$+ \partial_\nu g_{\mu t} - \sqrt{-g} \partial_\mu g_{t\lambda}$$

$$= \cancel{\partial_\mu g_{\nu t}} + \cancel{\partial_\nu g_{\mu t}} - \cancel{g_{\mu t}} \cancel{g_{\nu t}} \left(\cancel{\partial_\nu g_{t\lambda}} + \cancel{\partial_\mu g_{t\lambda}} - \cancel{\partial_\lambda g_{\mu\nu}} \right)$$

$$S_0^0$$

$$= -\partial_0 g_{\mu\nu} \rightarrow \text{Metric} \Rightarrow \text{no fine details}$$

Static Spacetime

\exists const (t, \vec{x}) in which

$$ds^2 = g_{tt}(t) dt^2 + g_{ij}(t) dx^i dx^j$$

Space

Vacuum outside spherical static distribution

$$ds^2 = g_{tt}(t) dt^2 + g_{ij}(t) dx^i dx^j$$

Spherical Symmetry

$SO(3)$ acts on M

$$\forall x \in M \rightarrow R \in SO(3) \quad x \in S \quad T_x S = \left[\begin{array}{c} \partial_{\theta} \\ \partial_{\phi} \end{array} \right]$$

spanned by these

$$O_x = \{R_x \mid R \in SO(3)\}$$
 orbit of x by $SO(3)$

$$O_x \cap S^2 = S^2 \text{ for most } x$$

On each orbit $ds^2 = r^2(d\theta^2 + \sin^2\theta d\phi^2)$

can line up such that $g_{ij}(r)dr^i dr^j = e^{2\alpha(r)}dr^2 + r^2(d\theta^2 + \sin^2\theta d\phi^2)$

So metric of the form

$$ds^2 = -e^{2\alpha(r)}dt^2 + e^{2\beta(r)}dr^2 + r^2(d\theta^2 + \sin^2\theta d\phi^2) \quad g = \begin{pmatrix} -e^{2\alpha} & e^{2\beta} & 0 \\ 0 & r^2 & 0 \\ 0 & 0 & r^2 \sin^2\theta \end{pmatrix}$$

→ everything is an variable → ODE's!

$$\begin{aligned} \int_{tr}^t \frac{dt}{\sqrt{-g}} &= \frac{1}{2} \cancel{g^{tt}} \left(\cancel{\partial_t g_{tt}} + \cancel{\partial_r g_{tr}} - \cancel{\partial_t g_{tr}} \right) \\ &= \frac{1}{2} (-e^{-2\alpha}) \partial_r (-e^{-2\alpha}) \\ &= \alpha' \\ \int_{tr}^r \frac{dr}{\sqrt{-g}} &= \frac{1}{2} \cancel{g^{rr}} \left(\cancel{\partial_t g_{tr}} + \cancel{\partial_r g_{rr}} - \cancel{\partial_r g_{tr}} \right) \\ &= \frac{1}{2} e^{-2\beta} \cdot (-\alpha' e^{2\alpha}) = -\alpha' e^{2(\alpha-\beta)} \end{aligned}$$

$$R_{tt} = -e^{2(\alpha-\beta)} [\alpha'' + (\alpha')^2 - \alpha'\beta' + \frac{3}{r}\alpha']$$

$$R_{rr} = [\alpha'' + (\alpha')^2 - 2\beta' - \frac{3}{r}\beta']$$

$$R_{\theta\theta} = e^{-2\beta} [r(\beta' - \alpha') - 1] + 1$$

$$R_{\phi\phi} = R_{\theta\theta} \sin^2\theta$$

$$e^{2(\beta-\alpha)} R_{tt} + R_{rr} = 0 \Rightarrow \alpha' + \beta' = 0$$

$$\Rightarrow \alpha = C - \beta \quad \leftarrow t \mapsto e^{Ct} t$$

$$\Rightarrow C = 0$$

$$R_{\theta\theta} = e^{2\alpha} (2\alpha\alpha' + 1) - 1 = 0$$

$$\frac{d}{dr}(re^{2\alpha}) \cdot e^{2\alpha} (1 + 2\alpha') = 1$$

$$\Rightarrow re^{2\alpha} = r - R$$

constant of integration

$$ds^2 = -\left(1 - \frac{R}{r}\right)dt^2 + \left(1 - \frac{R}{r}\right)^{-1}dr^2 + r^2(d\theta^2 + \sin^2\theta d\phi^2) \quad \underline{\text{Swartzchild}}$$

$$* e^{2\kappa} > 0 \Leftrightarrow r > R$$

* $r \rightarrow \infty$

$$ds^2 = -dt^2 + dr^2 + r^2 d\Omega^2 \quad R_{\text{outer}} \rightarrow 0$$

weak field gravity

$r \rightarrow \infty$

$$ds^2 = (g_{\mu\nu} + h_{\mu\nu}) dt^\mu dt^\nu$$

$$h_{\mu\nu} = \frac{R}{r} \ll 1$$

$$\begin{aligned} h_{rr} &= \frac{1}{1-R/r} - 1 = \frac{r}{r-R} - \frac{r-R}{r-R} \\ &= \frac{R}{r-R} \ll 1 \end{aligned}$$

Compare Newton:

$$R_s = \frac{2GM}{c^2}$$

Schwarzschild radius

$$= \frac{M}{M_\odot} = 2.95 \text{ km}$$

Nontrivial solution to Einstein

Best known: Schwarzschild

$$ds^2 = -(1 - \frac{R}{r})dt^2 + (1 - \frac{R}{r})^{-1}dr^2 + r^2 d\Omega^2$$

$$* r \rightarrow \infty \quad ds^2 \sim g_{\mu\nu} dt^2 dt^2 \quad \text{Minkowski: } R = \frac{2GM}{c^2} = \left(\frac{M}{M_\odot}\right) \cdot 2.95 \text{ km}$$

$$* R_{\mu\nu} = 0 \Leftrightarrow T_{\mu\nu} = 0 \quad \& \quad r > R$$

$$* r? \quad \text{2D circumference} \quad (dr = d\theta + \sin\theta d\phi)$$

πr^2 area

r is NOT distance

$$\int_r^{\infty} (1 - \frac{R}{r})^{-\frac{1}{2}} dr$$

What is r ?

$$\int_{r_0}^r \neq 0 \quad \text{static such that } r, \theta, \phi \text{ radial}$$

$$u^\mu = \frac{1}{\sqrt{1 - R/r}} (1, \vec{0})$$

$$x^\mu(\lambda) \quad u^\mu = \frac{dx^\mu}{d\lambda} = \left(u^0, \vec{0} \right) = \left((1 - \frac{R}{r})^{-\frac{1}{2}}, \vec{0} \right)$$

$$g_{\mu\nu} u^\mu u^\nu = -1$$

$$dt = (1 - \frac{R}{r})^{\frac{1}{2}} dt \quad \text{gravitational redshift}$$

Birkhoff's theorem: any spherically symmetric vacuum spacetime \rightarrow Schwarzschild
 * Irrelevant at spherical shell, possibly moving \rightarrow Vaidya spacetime

Geodesics:

$$ds^2 = -(1 - \frac{R}{r}) dt^2 + (1 - \frac{R}{r})^{-1} dr^2 + r^2 d\Omega^2$$

+ Killing vectors

$\xrightarrow{\text{Symmetry: time translation}}$

$$\cdot \vec{e}_t = \partial_t \quad \vec{e}_t^\mu = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\cdot \vec{e}_\phi \quad \vec{e}_\phi^\mu = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\cdot \vec{e}_\theta$$

$$\cdot \vec{e}_r$$

$$[\vec{e}^i, \vec{e}^j] = \epsilon^{ijk} \vec{e}^k$$

$$p^\mu = m \frac{dx^\mu}{d\tau} \quad u^\mu = \frac{dx^\mu}{d\tau} \xrightarrow{\text{or affine}}$$

Conserved quantity

$$K_+ = g_{\mu\nu}(x(\lambda)) p^\mu(\lambda) \vec{e}_+(\lambda)^\nu = - (1 - \frac{R}{r}) p^0 = -E$$

$$K_\phi = g_{\mu\nu} p^\mu \vec{e}_\phi^\nu = r^2 \sin^2 \theta p^\phi = L$$

$$\left| \begin{array}{l} E = (1 - \frac{R}{r}) \frac{dt}{d\lambda} \\ \uparrow \text{energy (per unit mass)} \\ L = r^2 \sin^2 \theta \frac{dp}{d\lambda} \\ \uparrow \text{angular momentum (per unit mass)} \end{array} \right.$$

$$\frac{d^2 x^\mu}{d\lambda^2} + \Gamma^\mu_{\alpha\beta} \frac{dx^\alpha}{d\lambda} \frac{dx^\beta}{d\lambda} = 0$$

$$(4) \quad \frac{dt^2}{dr^2} + \frac{R}{r(r-R)} \frac{dr}{dt} \frac{dt}{dr} = 0$$

$$(5) \quad \frac{d^2 r}{d\lambda^2} + \frac{R}{2r(r-R)} \left[\left(1 - \frac{R}{r}\right)^2 \left(\frac{dt}{dr}\right)^2 - \left(\frac{dr}{dt}\right)^2 \right] - (r-R) \left[\left(\frac{dt}{dr}\right)^2 + \sin^2 \theta \left(\frac{dp}{d\lambda}\right)^2 \right] = 0$$

$$(6) \quad \frac{d^2 \theta}{d\lambda^2} + \frac{2}{r} \frac{dr}{dt} \frac{d\theta}{dr} - \sin \theta \cos \theta \left(\frac{dp}{d\lambda}\right)^2 = 0$$

$$(9) \quad \frac{d\dot{\theta}}{dt} + \frac{2}{r} \frac{dr}{dt} \frac{d\phi}{dr} + 2\cot\theta \left(\frac{dr}{dt} \right) \left(\frac{d\phi}{dt} \right) = 0$$

$$(1) = \left(1 - \frac{R_N}{r} \right)^{-1} \frac{d}{dt} \left[\left(1 - \frac{R_N}{r} \right) \frac{d\phi}{dt} \right] = 0 \\ = \left(1 - \frac{R_N}{r} \right)^{-1} \frac{dE}{dt} = 0$$

$$\theta(0) = \frac{1}{r} \frac{d\phi}{dt}(0) = 0 \Rightarrow \phi(0) = \frac{\pi}{2} \quad \text{HJ}$$

orbits are planar!

$$(p) \quad \frac{1}{r^2 \sin\theta} \frac{d}{dt} \left(r^2 \sin\theta \frac{dp}{dt} \right) = 0$$

\angle constant

$$E = \left(1 - \frac{R_N}{r} \right) \frac{dt}{dr}$$

$$L = r^2 \sin\theta \frac{dp}{dt}$$

planar

Choose λ proper (timelike) / affine (null)

$$g_{\mu\nu} \left(X(\lambda) \right) \frac{dx^\mu}{d\lambda} \frac{dx^\nu}{d\lambda} = -\epsilon$$

what is this? $\epsilon = \begin{cases} 1 & \text{matter} \\ 0 & \text{light} \end{cases}$

$$-\epsilon = -\left(1 - \frac{R_N}{r} \right) \left(\frac{dt}{dr} \right)^2 + \left(1 - \frac{R_N}{r} \right)^{-1} \left(\frac{dr}{dt} \right)^2 + r^2 \left(\frac{d\phi}{dt} \right)^2 + \sin^2\theta \left(\frac{dp}{dt} \right)^2$$

$$-\frac{\epsilon}{2} = \frac{1}{2} \left(1 - \frac{R_N}{r} \right)^{-1} \left(-E^2 + \dot{r}^2 \right) + \frac{L^2}{2r^2}$$

$\dot{r} = \frac{dt}{dr} \quad V(r)$

$$\frac{1}{2} \dot{r}^2 = \frac{1}{2} E^2 - \underbrace{\frac{1}{2} \left(1 - \frac{R_N}{r} \right)}_{V(r)} \left(\epsilon + \frac{L^2}{r^2} \right)$$

$$\frac{1}{2} \dot{r}^2 + V(r) = \frac{1}{2} E^2 = \epsilon$$

recall $R = \frac{GM}{c^2}$

$$V(r) = \frac{1}{2} \left(1 - \frac{R_N}{r} \right) \left(\epsilon + \frac{L^2}{r^2} \right)$$

$$(10) \quad = \frac{1}{2} - \frac{GM}{r} + \frac{L^2}{2r^2} + \frac{GM^2}{r^3}$$

elliptic precession

$\varepsilon = 1$

$$V' = \frac{M}{r^2} - \frac{L^2}{r^3} + \frac{3ML^2}{r^4}$$

$$V=0 \quad r = \pm \frac{L^2}{2M} \left(1 \pm \sqrt{1 - \frac{4M^2}{L^2}} \right)$$

For $L < 2\sqrt{3}M$

$$L > 2\sqrt{3}M$$

$$0 < x = \frac{r_0 M^2}{L^2} < 1$$

$$\text{closed stable orbit}$$

$$\frac{3x+6M}{x} \leq r_c = \frac{6M}{x} \left(1 + \sqrt{1-x} \right) \xrightarrow{x \rightarrow 0} \frac{6M}{x} = \frac{L^2}{M} \rightarrow \infty$$

$$\frac{3R}{2} = 3M \leftarrow r_- = \frac{6M}{x} \left(1 - \sqrt{1-x} \right) \leq 3R$$

unstable orbit

$$\frac{1}{2} E^2 = E_c = V(r_c) = \frac{(r_c - 3M)}{2(r_c - 3M)} \stackrel{r_c = 3R = 6M}{=} \frac{1}{4} \Rightarrow E = \frac{2\sqrt{3}}{2} = 0.99$$

\checkmark 6% of mass turns to energy. That is a lot!

$$V' = 0 = Mr^2 - L^2(r - 3M)$$

$$w_p^2 = \frac{L^2}{r_0^2} = \frac{Mr_0^2}{r_0^2(r_0 - 3M)} = \frac{M}{r_0^2(r_0 - 3M)} \underset{\substack{r \gg M \\ \text{law corrected!}}}{\sim} \frac{M}{r_0^3}$$

\checkmark Kepler's 3rd

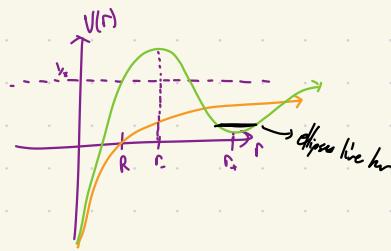
$$w_r^2 = V'' = \frac{M}{r_0^3} \frac{r_0 - 6M}{r_0 - 3M}$$

$$r_0 \gg M \quad w_r^2 < w_p^2$$

precession

$$\frac{w_p - w_r}{w_p} = 1 - \sqrt{\frac{r_0 - 6M}{r_0}}$$

$$\approx 3M/r_0 \rightarrow \text{result of } \frac{GM\omega^2}{r^3} \text{ from earlier}$$



Stars n shift

$$ds^2 = -e^{2\alpha(r)} dt^2 + e^{2\beta(r)} dr^2 + r^2 d\Omega^2$$

$$T_{\mu\nu} = \begin{pmatrix} \rho(r) & p(r) & 0 & 0 \\ p(r) & p(r) & 0 & 0 \\ 0 & 0 & p(r) & 0 \\ 0 & 0 & 0 & p(r) \end{pmatrix} \quad u^\mu = e^{-\alpha(r)}(1)$$

$$G_{tt} = r^2 e^{\alpha(r)} (2r\beta' - 1 + e^{2\beta}) = 8\pi e^{\alpha(r)} \rho(r) \quad \checkmark$$

$$G_{rr} = r^2 (2r\alpha' + 1 - e^{-2\beta}) = 8\pi e^{\alpha(r)} p(r) \quad \checkmark$$

$$G_{\theta\theta} = r^2 e^{-2\beta} (\alpha'' + \alpha')^2 - \alpha\beta' + \frac{1}{r} (\alpha'^2 - p) = 8\pi r^2 p(r)$$

$$G_{\phi\phi} = \sin^2\theta G_{\theta\theta} = 8\pi T_{\phi\phi} + 8\pi \sin^2\theta T_{\theta\theta}$$

Equation of state: $p(\rho)$

$$e^{2\beta(r)} = \left(1 - \frac{2\alpha(r)}{r}\right)^{-1}$$
$$m(r) = 8\pi \int_0^r r^2 r^2 p(r) \quad \left. \begin{array}{l} \text{total energy in} \\ \text{spacetime radius} \end{array} \right\}$$

$$\text{At } r=r_0 \quad \begin{array}{l} p \rightarrow 0 \\ p \rightarrow 0 \end{array} \quad m(r_0) = M$$

$$\alpha' = \frac{4\pi r^3 p(r) + m(r)}{r(r - 2m(r))}$$

Check (nonrotating, static, weak field)

$$r^3 p(r) \ll m(r) \ll r$$

$$\alpha' \sim \frac{m(r)}{r^2} = \phi'$$

$$g_{\phi\phi} \sim -(1 + 2\alpha) \quad \alpha = \phi$$

$$0 = D_\mu T^{\mu\nu} = \bar{e}^{-2\phi} \left(\underbrace{p^1 - \alpha'(p \cdot p)}_{=0} \right)$$

$$\text{nonrotating} \quad p^1(r) = -(p \cdot p) \frac{4\pi r^3 p(r) + m(r)}{r(r - 2m(r))} \quad \text{Tolman} \\ \text{operator} \\ \text{definition}$$

$$p^1 = -p\phi' = -\frac{Gm(r)p(r)}{r^2}$$

$$p^1(r) = \frac{Gm(r)}{r^2} p(r) \left(1 + \frac{4\pi r^3 p(r)}{m(r)c^2} \right) \left(1 - \frac{2m(r)}{r^2} \right)$$

$$\text{Assume } p(r=0) \xrightarrow[\text{two equations of state}]{\text{the two}} p(r=0)$$
$$\rightarrow p(r) \rightarrow p_0 @ p \rightarrow 0$$

$$\text{Ex: } P(n) = \begin{cases} P_0 & n < r_0 \\ 0 & n > r_0 \\ \frac{(1-\frac{n}{r_0})^{1/2} - (1-\frac{r_0}{r})^{1/2}}{3(1-\frac{n}{r_0})^{1/2} - (1-\frac{r_0}{r})^{1/2}} P_0 & \end{cases}$$

$$m(r) = \begin{cases} \frac{4\pi}{3} P_0 & n < r_0 \\ M & n > r_0 \end{cases}$$

$$P_N(0) = \frac{\pi^2}{3} P_0 r_0^2 \sim M^{2/3} P_0^{4/3}$$

$$P_{TOV}(0) = P_0 \frac{1 - \sqrt{1 - \frac{2M}{R}}}{3\sqrt{1 - \frac{2M}{R}}} + 1$$

$$\downarrow \quad r_0 = \frac{9M}{8} > 2M$$

Chandrasekhar Degenerate e^- gas

$$M \lesssim M_{\text{ch}} = 1.4M_{\odot}$$

TOV Degenerate n gas

$$M \lesssim M_{\text{NS}} = 3-5M_{\odot}$$

Schöenberg-Chandrasekhan:

$$\text{Internal core } M_{\text{core}} \lesssim 0.37M_{\odot}$$

$$\begin{aligned} \text{Near } r \approx R? & \quad R_{\text{inner}} = 0 \\ r < R? & \quad R_{\text{inner}} \neq 0 \end{aligned}$$

Check: Radial infalling matter ($\theta = \theta_0, \dot{\theta} = 0, \dot{r} = 0$)

$$\begin{aligned} E &= (1 - \frac{R}{r}) \dot{t}^2 \\ -1 &= -(1 - \frac{R}{r}) \dot{t}^2 + (1 - \frac{R}{r}) \dot{r}^2 = \frac{\dot{r}^2 - E^2}{1 - \frac{R}{r}} \end{aligned}$$

$$\dot{r}^2 = E^2 - 1 + \frac{R}{r}$$

$$\dot{r} = \pm \sqrt{E^2 - 1 + \frac{R}{r}}$$

$$\text{Choose } E = 1$$

$$E = 1 \pm \sqrt{1 - \frac{R}{r}}$$

$$\begin{aligned} dt &= -\sqrt{\frac{r}{R}} dr \\ \Delta t &= \frac{1}{\sqrt{R}} \int_R^r dr \approx -\frac{R}{3\sqrt{R}} (r_p^{3/2} - R^{3/2}) \end{aligned}$$

$$\Delta t = -\sqrt{R} \int_{r=R}^{\infty} \frac{dr}{r-R} \sim R \log t \rightarrow \infty$$

$$R_{\text{outward}} \sim \frac{6R^2}{r^6}$$

$r=0 \leftrightarrow$ curvature singularity
 $r \approx R \leftrightarrow$ No " "

$$ds^2 = dr^2 + r^2 d\theta^2$$

problems:

- 1) $g_{\theta\theta} = r^2 \omega$ fine, not a problem
 $\omega \rightarrow 0$ can never reach ω
- 2) $g_{rr} = r^2 \omega$ $\omega \rightarrow 0$ bad choice of coordinate



$$t=\infty \rightarrow t'=$$

$$+ \infty \quad dt = -\frac{dr}{r^2} + dx^2 = -dt' + dx^2 \\ x \in R \quad g_{tt} \rightarrow 0 \quad \underbrace{t'/\omega}_{t'/\omega \rightarrow 0} \\ r \rightarrow \infty \quad \overline{|||||} \quad t' \rightarrow -\infty$$

$$t' = -\frac{1}{t} < 0$$

$$dt' = \frac{dt}{t^2}$$

Null radial geodesics

$$(1-R_n)r = (1-\chi_n)^{-1} r^2$$

$$dt = \pm (1-R_n) dr$$

$$t = \pm r \pm R \log(r-R) + C \\ = C \pm f_n(r)$$

$$f_n(r) = r + R \log(\chi_n - 1)$$

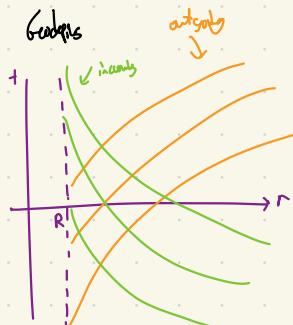
$$\frac{dr}{dr} = (1-R_n)^{-1}$$

Regge-Wheeler-Tortoise

(without drag)

$$\text{outgoing } u = t - f_n(r)$$

$$\text{incoming } v = t + f_n(r)$$



$$t = \frac{1}{\varepsilon}(u+v)$$

$$\frac{1}{\varepsilon}(u-v) = t_0$$

$$e^{\frac{1}{\varepsilon}t(u+v)} = e^{t_0/\varepsilon} = (\frac{r}{R}-1)e^{r/R}$$

$$du = dt - (1-B_n)^{-1}dr$$

$$dv = dt + (1-B_n)^{-1}dr \quad r=R: u \rightarrow -\infty$$

$$ds^2 = -(1-B_n)t^2 + (1-B_n)r^2 dr^2$$

$$= -(1-B_n)du^2 + r^2(u,v)dr^2 = -\frac{4R^3}{r}e^{\frac{r}{R}}dudv + r^2(u,v)dr^2$$

gets rid of singularity

$$U = -e^{-u/R} \quad u \rightarrow \infty \quad U \rightarrow 0 \quad "boring initially in so we can see it"$$

$$V = e^{v/R} \quad v \rightarrow -\infty \quad V \rightarrow 0$$

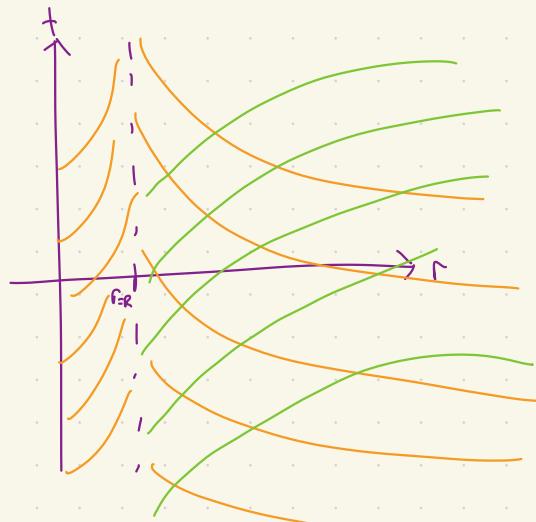
$$ds^2 = -(1-B_n)t^2 + (1-B_n)r^2 dr^2 + r^2 d\Omega^2$$

Infalling null geodesics

$$(1-B_n)\dot{t}^2 = (1-B_n)^{-1}\dot{r}^2$$

$$dt = \pm (1-B_n)^{-1/2}dr$$

$$t = \pm r \pm R \log(r-R) + C$$



replace $t \leftarrow v = t + r + R \log(r-R)$ constant on incoming null geodesics

$$dv = dt + dr(1+\frac{R}{r-R}) \quad \text{Eddington-Finkelstein}$$

$$ds^2 = -(1-B_n)dv^2 + 2dvdr + r^2 d\Omega^2$$

$$\sqrt{dr^2} = d\tau$$

$$r < R$$

$$0 > ds^2 > (1-B_n)^{-1}dr^2 = -\frac{r}{R} \frac{dr^2}{1+B_n}$$

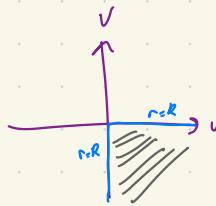
$$\Delta\tau = \int \sqrt{-g} dr \leq \frac{1}{\sqrt{R}} \int \frac{R}{\sqrt{1+B_n}} \frac{dr}{\varepsilon} \xrightarrow{\varepsilon \rightarrow 0} \frac{R\pi}{\varepsilon}$$

new coord: $u = t - r - R \log |r - R|$ outgoing
 $v = r \log |r - R|$ Regge-Wheeler

$$t = \frac{1}{2}(u+v)$$

$$r = \frac{1}{2}(v-u)$$

$$e^{R/r} = (r/R - 1) e^{r/R}$$



$$ds^2 = -(1 - \frac{r}{r}) du dv + r^2 (u, v) d\Omega^2$$

$$\begin{aligned} r &\rightarrow R & v &\rightarrow -\infty & (V \rightarrow 0) \\ u &\rightarrow \infty & && (U \rightarrow 0) \end{aligned}$$

Kruskal

$$U = -e^{-V/R} \leq 0$$

$$V = e^{V/R} \geq 0$$

$$UV = (1 - \frac{r}{R}) e^{V/R} = T^2 X^2$$

$$R \log(\frac{V}{U}) = t = R \log \frac{T+X}{T-X}$$

noncausal at $r=R$!

$$ds^2 = -\frac{4R^3}{r} e^{-V/R} du dv + r^2 (u, v) d\Omega^2$$

One last time!

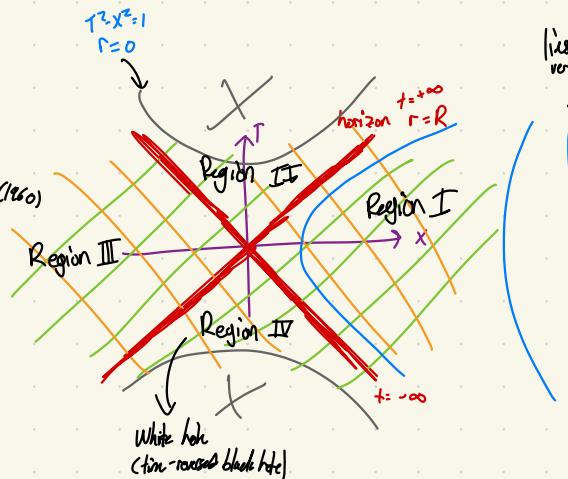
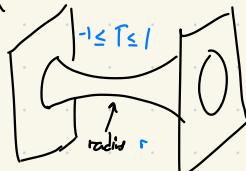
$$T = \frac{1}{2}(V+U) \quad \text{everywhere finite}$$

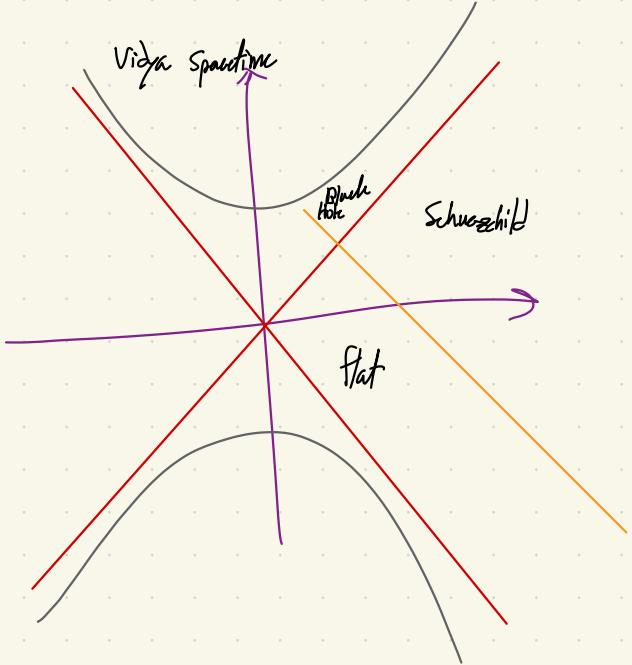
$$X = \frac{1}{2}(V-U) \quad \text{everywhere finite}$$

$$ds^2 = -\frac{4R^3}{r} e^{-V/R} (dT^2 - dX^2) + r^2 d\Omega^2$$



Non-traversable
wormhole - not enough
time to cross it
at speed of light





Yummy metric:

$$ds^2 = - \left(1 - \frac{2Mr}{\rho^2} \right) dt^2 - \frac{4Mr \sin^2\theta}{\rho^2} dt d\phi + \frac{\rho^2}{\Delta} dr^2 + \rho^2 d\theta^2 + \left[r^2 + a^2 + 2Ma^2r \sin^2\theta \right] \sin^2\theta d\phi^2$$

Neutral spinning black hole

angular momentum $J = aM$
 $\rho^2 = r^2 + a^2 \cos^2\theta$
 $\Delta = r^2 + a^2 - 2Mr$

$$\Sigma_+ = \{r^2 + a^2 \cos^2\theta = 2Mr\}$$

Surface (not seen)
1) $g_{tt} = 0$

2) Causal propagation ($a^2 \leq 0$)
has $\dot{p} \geq 0$

$$W_- < W = \frac{dp}{dt} < W_+$$

$$W_{\pm} = - \frac{g_{t\rho}}{g_{\rho\rho}} \pm \sqrt{\left(\frac{g_{tt}}{g_{\rho\rho}}\right)^2 - \frac{g_{tt}}{g_{\rho\rho}}}$$

$$(\text{outer}) \quad \underline{\text{Horizon}} \quad S_K = r = r_+ = M + \sqrt{M^2 - a^2}$$

- 1) ∂_r timelike (null on S_K)
- 2) $\partial_t + \mathcal{L}_H \partial_p = K$

$$\begin{aligned} \mathcal{L}_H &= \omega(r, \theta) = \frac{a}{r_+^2 + a^2} = \frac{a}{2Mr_+} \\ &= \cancel{GM/r_+} \sin^2\theta / \rho_+^2 \\ &= \left[\frac{r_+^2 + a^2 + 1/a^2 \sin^2\theta / \rho_+^2}{2Mr_+} \right] \sin^2\theta \\ &= \frac{2a \sin\theta}{1 + a^2 \sin^2\theta / \rho_+^2} \\ &= \frac{a}{r_+^2 + a^2}. \end{aligned}$$

S_K : Killing Horizon

$$f = g_{\mu\nu} \chi^\mu \chi^\nu = 0 \quad T_p(S_K) \subset T_p M$$

$\overset{!}{\leftrightarrow} \quad \leftrightarrow v^\mu \partial_\mu f = 0$

Penrose: Throw in a probe with $E < 0$.

$$\begin{aligned} E &= -g_{\mu\nu} p^\mu \chi^\nu \text{ conserved} \\ p^0 &= mu^0 > 0 \text{ & timelike trajectories} \end{aligned}$$

In ergoregion ∂_t spacelike

① start with $E_0 = p^0 > 0 \quad @ \quad r \gg M, a$

② carefully blow it up $E_+ + E_2 E_0$

$$\text{con arrange } E_2 < 0 \Rightarrow E_+ > E_0$$

① ejected back to $r \gg M$

② crossed $r = r_+ \rightarrow \text{absorbed}$

$$K = \partial_t + \mathcal{L}_H \partial_p \text{ timelike}$$

$$-p \cdot K > 0$$

$$= -p (\partial_t + \mathcal{L}_H \partial_p)$$

$$= E - \mathcal{L}_H L > 0$$

$$E_2 < 0 \Rightarrow L_2 < 0$$

$$\delta J = L < \frac{E}{\mathcal{L}_H} = \frac{EM}{\mathcal{L}_H} < 0$$

$$M_{\text{in}}(M, J) = \frac{1}{2} (M^2 + \sqrt{M^2 - J^2})$$

$$\text{implied} \quad = \frac{M}{2} (M + \sqrt{M^2 - J^2}) = \frac{M^2}{2}$$

$$M^2(M_{\text{in}}, J) = M_{\text{in}}^2 + \frac{J^2}{2M_{\text{in}}^2}$$

$$2M_{\text{in}} \delta M_{\text{in}} = M \delta M + \frac{1}{\sqrt{M^2 - J^2}} (SM^2 \delta M - 2J \delta SJ)$$

$$= \frac{M}{\sqrt{M^2 - J^2}} (2M_{\text{in}}^2 \delta M - \frac{J}{2M} \delta SJ)$$

$$= \frac{2M M_{\text{in}}^2}{\sqrt{M^2 - J^2}} (\delta M - S_{\text{in}} \delta SJ) \geq 0$$

$$S_{\text{in}} = \frac{\alpha}{r_{\text{in}}^{1+\epsilon}} = \frac{J/m}{2M_{\text{in}}} = \frac{J}{2m M_{\text{in}}}$$

$$A_{\infty} = 8\pi M_{\text{in}} = 16\pi M_{\text{in}}^2$$

↑
area of horizon

Perturbative GR

for the metric "small"

Weak fields: $\exists x$ s.t. $g_{\mu\nu} = g_{\mu\nu}^0 + h_{\mu\nu}$

Work to order h

fix to order h^0 , up to points $x^M \rightarrow x^T + a^M$
 closed foliation

Linearized gravity is CFT of speeds $(0,7)$ -term

in Minkowski

To order h : $g^{\mu\nu} = g^{\mu\nu}_0 - h^{\mu\nu}$

$$h^{\mu\nu} = g^{\mu\rho} g^{\nu\lambda} h_{\rho\lambda} \approx g^{\mu\rho} g^{\nu\lambda} h_{\rho\lambda}$$

$$\Gamma_{\mu\nu}^\lambda = \frac{1}{2} g^{\lambda\sigma} (\partial_\mu h_{\nu\sigma} + \partial_\nu h_{\mu\sigma} - \partial_\sigma h_{\mu\nu})$$

$$R_{\mu\nu}^M = \partial_\lambda \Gamma_{\mu\nu}^M - \partial_\nu \Gamma_{\mu\lambda}^M$$

$$= g^{\lambda\rho} (\partial_\mu \partial_\nu h_{\lambda\rho} - \partial_\rho \partial_\lambda h_{\mu\nu})$$

$$\bar{h}_{\mu\nu} = h_{\mu\nu} - \frac{1}{2} g_{\mu\nu} h^{\text{trace}}$$

$$h = g^{\mu\nu} h_{\mu\nu}$$

$$R_{\mu\nu} = \frac{1}{2} \left[\partial^\lambda \partial_\mu \bar{h}_{\nu\lambda} + \partial^\lambda \partial_\nu \bar{h}_{\mu\lambda} - \partial^\lambda \bar{h}_{\mu\nu} \right] + \frac{1}{2} g_{\mu\nu} \partial^\lambda \bar{h}^{\lambda\alpha}$$

$$R = \partial^\lambda \partial^\mu \bar{h}_{\mu\lambda} + \frac{1}{2} \partial^\lambda \bar{h}^{\lambda\alpha}$$

$$G_{\mu\nu} \approx \frac{1}{2} \left[\partial^\lambda \partial_\mu \bar{h}_{\nu\lambda} + \partial^\lambda \partial_\nu \bar{h}_{\mu\lambda} - \partial^\lambda \bar{h}_{\mu\nu} - g_{\mu\nu} \partial_\lambda \partial_\rho \bar{h}^{\lambda\rho} \right]$$

$$= 8\pi G T_{\mu\nu}$$

Einstein eqn 1

Coordinate change

$$g'_{\mu\nu} \quad g_{\mu\nu} = \text{same physics if } \mathcal{F}$$

$x(x')$ s.t.

$$g'_{\mu\nu} = \frac{\partial x^\lambda}{\partial x^\mu} \frac{\partial x^\rho}{\partial x^\nu} g_{\lambda\rho}$$

$$\text{If } x'^m = x^m + \zeta^m(x) \quad \left\{ \begin{array}{l} \text{small} \\ x^m = x'^m - \zeta^m(x') \end{array} \right.$$

$$x^m = x'^m - \zeta^m(x')$$

oder ζ

$$g' \sim g + O(\zeta)$$

$$g'_{\mu\nu}(x) = g_{\mu\nu}(x) - D_\mu \zeta_\nu - D_\nu \zeta_\mu$$

$$h'_{\mu\nu} = h_{\mu\nu} - \partial_\mu \zeta_\nu - \partial_\nu \zeta_\mu$$

$$\bar{h}'_{\mu\nu} = h'_{\mu\nu} - \frac{1}{2} g_{\mu\nu} h'$$

$$= h_{\mu\nu} - \partial_\mu \zeta_\nu - \partial_\nu \zeta_\mu - \frac{1}{2} g_{\mu\nu} (h - 2 \partial^\lambda \zeta_\lambda)$$

$$= \bar{h}_{\mu\nu} - \partial_\mu \zeta_\nu - \partial_\nu \zeta_\mu + \frac{1}{2} \partial^\lambda \zeta_\lambda$$

$$\partial_\mu \bar{h}'^{\mu\nu} = \underline{\partial_\mu \bar{h}^{\mu\nu}} - \underline{\partial^\lambda \zeta_\lambda} - \underline{\partial^\mu (\partial_\mu \zeta^\nu)} + \underline{\partial_\mu \partial^\lambda \zeta_\lambda}$$

Solve "Poisson" wave: $\partial^\lambda \zeta^\nu = \partial_\mu \bar{h}^{\mu\nu}$

$$\Rightarrow \partial_\mu \bar{h}^{\mu\nu} = 0 \quad \text{Laplace's law}$$

$$(\partial_\mu A^\mu = 0)$$

$$G_{\mu\nu} = \frac{1}{2} \left[\partial^\lambda \partial_\mu \bar{h}_{\nu\lambda} + \partial^\lambda \partial_\nu \bar{h}_{\mu\lambda} - \partial^\lambda \bar{h}_{\mu\nu} - g_{\mu\nu} \partial_\lambda \partial_\rho \bar{h}^{\lambda\rho} \right]$$

Einstein: $\partial^\lambda \bar{h}_{\mu\nu} - 16\pi G T_{\mu\nu}$

$$\partial_\mu \bar{h}^{\mu\nu} = 0 \Rightarrow \partial_\mu T^{\mu\nu} = 0$$

Waves:

$$\int u = -g_0 f(x)$$

Construct $G(x, x')$ s.t. $\partial_x^2 G = -g_0 \delta^{(4)}(x-x')$
 Green function

1) Translation invariance $G(x, x') = G(x-x')$

2) Lorentz $G(\Lambda x) = G(x)$

$$G^\pm(x) = \frac{1}{r} S(t \mp r)$$

$$x = (t, \vec{r}) \quad r = |\vec{r}|$$

$$u(x) = \int d^4x' G(x, x') f(x')$$

$$\bar{h}^{\mu\nu}(t, \vec{r}) = g/\beta_{\vec{r}}^{-1} \frac{T^{\mu\nu}(t - |\vec{r} - \vec{r}'|, \vec{r}')}{|\vec{r} - \vec{r}'|}$$

Lorentz gauge if $\partial_\mu T^{\mu\nu} = 0$

Waves: $\partial_\mu \bar{h}^{\mu\nu} = 0 \quad \partial_\mu h^{\mu\nu} = 0$
 $\bar{h}^{\mu\nu} \rightarrow \bar{h}^{\mu\nu} - \partial_\nu^\perp \partial_\mu^\perp + \epsilon^{\mu\nu\lambda\sigma} \partial_\lambda \partial_\sigma^\perp$

$$\partial_\nu^\perp \epsilon^{\mu\nu} = 0$$

Can achieve: Transverse Traceless (TT)

$$\bar{h}_{\perp\perp} = h_{\perp\perp} = 0 \quad h_{\perp i}^{0i} = 0$$

$$0 = \partial_\nu h^{00} + \partial_i h^{i0} = 0 \Rightarrow \partial_\nu h^{00} = 0$$

$$\int^2 h^{00} = 0 \Rightarrow \bar{\nabla}^2 h^{00} = 0$$

Plane Waves

$$h_{\perp\perp}^{\mu\nu} = A_{(4)}^{\mu\nu} e^{ik_\perp x_\perp} \quad \partial_\perp \bar{h}^{\mu\nu} = A^{\mu\nu} i k_\perp e^{ik_\perp x_\perp}$$

Graviton: $\bar{\nabla}^2 h^{\mu\nu} = 0 \Leftrightarrow k_\perp^2 = \text{lightlike}$

Lorentz: $\partial_\mu h^{\mu\nu} = 0 \Leftrightarrow A_{\perp\perp}^{0i} = 0$

choose $k = (w, 0, 0, w)$

$$A^{uv} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & a & b & 0 \\ 0 & b & -a & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} = a e_z^{uv}(k) + b e_x^{uv}$$