Algorithm 1: Clustermatch algorithm

Function `get_partitions`($\mathbf{v}$, $k_{\max}$):

  Output:

    Ω_r: clustering with r clusters over n objects

  if $\mathbf{v} \in \mathbb{R}^n$ **then**

    for $r \leftarrow 2$ **to** $\min\{k_{\max}, |\mathbf{v}| - 1\}$ **do**

      $\boldsymbol{\rho} \leftarrow (\rho_\ell \mid \Pr(v_i < \rho_\ell) \leq (\ell - 1)/r), \forall \ell \in [1, r+1]$

      $\Omega_{r\ell} \leftarrow \{i \mid \rho_\ell < v_i \leq \rho_{\ell+1}\}, \forall \ell \in [1, r]$

  else

    $\mathcal{C} \leftarrow \cup_j \{v_i\}$

    $r \leftarrow |\mathcal{C}|$

    $\Omega_{rc} \leftarrow \{i \mid v_i = \mathcal{C}_c\}, \forall c \in [1, r]$

  `// Remove singleton partitions`

  $\Omega \leftarrow \{\Omega_r \mid |\Omega_r| > 1\}, \forall r$

  return Ω

Function `clustermatch`($\mathbf{x}$, $\mathbf{y}$, $k_{\max}$):

  Input:

    $\mathbf{x}$: feature values on n objects

    $\mathbf{y}$: feature values on n objects

    $k_{\max}$: maximum number of internal clusters

  Output:

    c: similarity value for $\mathbf{x}$ and $\mathbf{y}$ ($c \in [0, 1]$)

  $\Omega^{\mathbf{x}} = \text{get\_partitions}(\mathbf{x}, k_{\max})$

  $\Omega^{\mathbf{y}} = \text{get\_partitions}(\mathbf{y}, k_{\max})$

  $c \leftarrow \max\{\mathcal{A}(\Omega^{\mathbf{x}}_p, \Omega^{\mathbf{y}}_q)\}, \forall p, q$

  return c