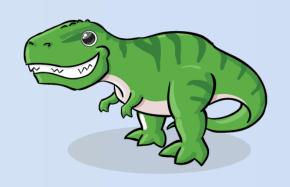


Chapter 5.

CPU Scheduling



Operating System Concepts (10th Ed.)





- CPU scheduling is
 - the basis of multiprogrammed operating systems.
 - The objective of *multiprogramming* is
 - to have some processes running at all times
 - to maximize CPU utilization.



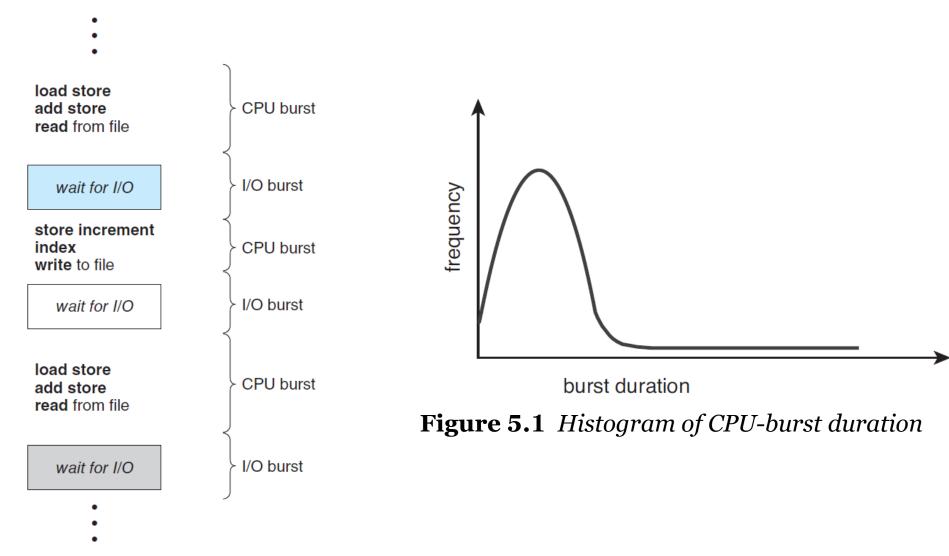


Figure 5.1 Alternating sequence of CPU-bursts and I/O-bursts.





- CPU scheduler
 - selects a process from the processes in memory
 - that are *ready* to execute and *allocates* the CPU to that process.
 - Then, how can we select a next process?
 - Linked List? or Binary Tree?
 - FIFO Queue: First-In, First-Out
 - Priority Queue: How can we determine the priority of a process?





• Preemptive .vs. Non-preemptive:

- *Non-preemptive* scheduling
 - a process keeps the CPU until it releases it,
 - either by terminating or by switching to the waiting state.
- **Preemptive** scheduling
 - a process can be preempted by the scheduler.





- Decision Making for CPU-scheduling:
 - 1. When a process switches from the *running* to *waiting* state.
 - 2. When a process switches from the *running* to *ready* state.
 - 3. When a process switches from the *waiting* to *ready* state.
 - 4. When a process terminates.
 - No. 1 & 4: no choice non-preemptive.
 - No. 2 & 3: choices preemptive or non-preemptive.





- The **dispatcher** is
 - a module that gives control of the CPU's core
 - to the process selected by the CPU scheduler.
 - The functions of dispatcher:
 - switching context from one process to another
 - switching to user mode
 - jumping to the proper location to resume the user program





- The dispatcher should be as fast as possible
 - since it is invoked during every context switch.
 - The **dispatcher latency** is
 - the time to stop one process and start another running.

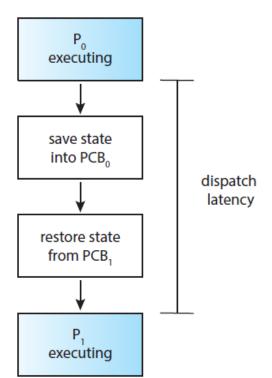


Figure 5.3 *The role of the dispatcher.*





• How often do context switches occur?

```
joonion@joonionpc:/proc/9$ vmstat 1 3
procs -------memory------------------io---- -system-- -----cpu-
  b
                                                           cs us sy id wa st
                     buff cache
       swpd
               free
                                            bi
                                                  bo
                                       SO
                                         8 791
         0 12879788
                     7896
                          53084
                                                       2 5 0 0 100 0 0
                                                   0 4 <mark>30</mark> 0 0 100 0 0
0
         0 12879796
                     7896
                          53084
                                                           <mark>27</mark> 0 0 100 0
0
         0 12879796
                     7896 53084
```

```
joonion@joonionpc:/proc$ cat /proc/1/status | grep ctxt
```

voluntary ctxt switches: 62 nonvoluntary_ctxt_switches:





5.2 Scheduling Criteria

Scheduling Criteria

- *CPU utilization*: to keep the CPU as busy as possible.
- *Throughput*: the number of processes completed per time unit.
- Turnaround time:
 - how long does it take to execute a process?
 - from the time of submission to the time of completion.

• Waiting time:

- the amount of time that a process spends waiting in the ready queue.
- the sum of periods spend waiting in the ready queue.
- Response time:
 - the time it takes to start responding





- CPU Scheduling Problem:
 - decide which of the processes in the ready queue
 - is to be allocated the CPU's core.



- The solutions for the scheduling problem:
 - FCFS: First-Come, First-Served
 - **SJF**: Shortest Job First (**SRTF**: Shortest Remaining Time First)
 - **RR**: Round-Robin
 - Priority-based
 - MLQ: Multi-Level Queue
 - MLFQ: Multi-Level Feedback Queue



- FCFS Scheduling
 - First-Come, First-Served: the simplest CPU-scheduling algorithm.
 - The process that requests the CPU first
 - is allocated the CPU first.
 - can be easily implemented with a FIFO queue.

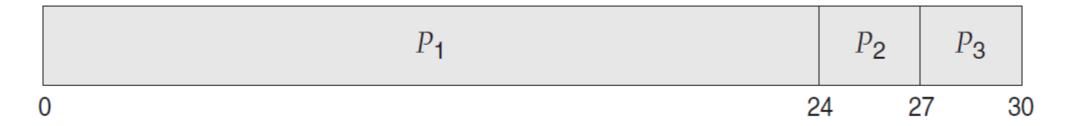


- Consider the following set of processes
 - that arrive at time 0,
 - with the length of the CPU burst given in milliseconds:

Process	<u>Burst Time</u>
P_1	24
P_2^{-}	3
P_3^-	3



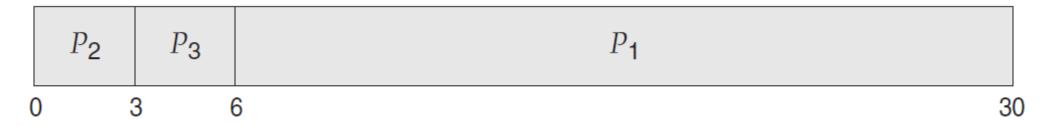
- If the processes arrive in the order P_1, P_2, P_3 :
 - Gantt Chart served by the FCFS policy:



- Calculate the waiting time of this schedule.
 - Waiting Time for $P_1 = 0$, $P_2 = 24$, $P_3 = 27$
 - *Total* Waiting Time: (0 + 24 + 27) = 51
 - Average Waiting Time: 51/3 = 17



- If the processes arrive in the order P_2 , P_3 , P_1 :
 - Gantt Chart served by the FCFS policy:



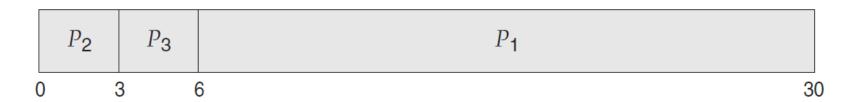
- Calculate the waiting time of this schedule.
 - Waiting Time for $P_1 = 6$, $P_2 = 0$, $P_3 = 3$
 - *Total* Waiting Time: (6 + 0 + 3) = 9
 - *Average* Waiting Time: 9/3 = 3



• Let us calculate the *turnaround time*:



- Turnaround Time for $P_1 = 24$, $P_2 = 27$, $P_3 = 30$
- *Total* Turnaround Time: (24 + 27 + 30) = 81
- Average Turnaround Time: 81/3 = 27



• Do it on your own:



- Note that
 - The average waiting time under the FCFS policy
 - is generally *not minimal* and *may vary substantially*
 - if the processes' *CPU-burst times* vary greatly.
 - Preemptive or non-preemptive?
 - The FCFS scheduling algorithm is *non-preemptive*.





- Note also that
 - The performance in a *dynamic* situation:
 - What if we have *one* CPU-bound and many I/O-bound processes?

• Convoy Effect:

- all the other processes wait for the one big process to get off the CPU.
- results in lower CPU and device utilization than might be possible
- if the shorter processes were allowed to go first.



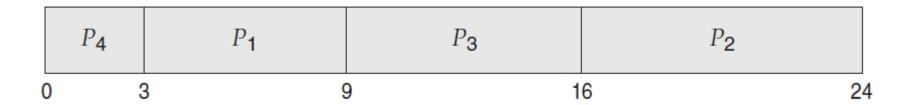


- SJF Scheduling
 - Shortest-Job-First: *shortest-next-CPU-burst-first* scheduling.
 - SJF associates with each process
 - the length of the process's next CPU burst.
 - When the CPU is available,
 - assign it to the process that has the smallest next CPU burst.
 - If two or more processes are even,
 - break the tie with the FCFS.

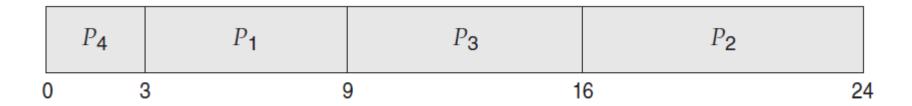


Process	Burst Time
P_1	6
P_2	8
P_3^-	7
P_{4}	3

- Using the SJF scheduling,
 - Gantt Chart would be:

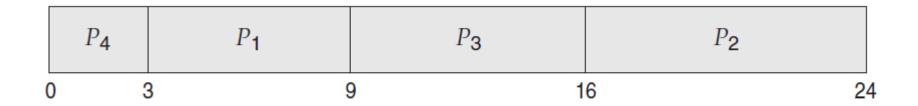






- Calculate the waiting time:
 - Waiting Time for $P_1 = 3$, $P_2 = 16$, $P_3 = 9$, $P_4 = 0$
 - *Total* Waiting Time: (3 + 16 + 9 + 0) = 28
 - *Average* Waiting Time: 28/4 = 7





- Calculate the turnaround time:
 - Turnaround Time for $P_1 = 9$, $P_2 = 24$, $P_3 = 16$, $P_4 = 3$
 - *Total* Turnaround Time: (9 + 24 + 16 + 3) = 52
 - *Average* Turnaround Time: 52/4 = 13



- Note that
 - The SJF scheduling algorithm is *provably optimal*,
 - it gives the minimum average waiting time for a given set of processes.
 - Moving a short process before a long one
 - decreases the waiting time of the short process
 - more than it increases the waiting time of the long process.
 - Consequently, the average waiting time decreases.





- Can you implement the SJF scheduling?
 - There is *no way* to know the length of the *next CPU burst*.
 - Try to *approximate* the SJF scheduling:
 - We may be able to **predict** the length of the next CPU.
 - Pick a process with the shortest *predicted* CPU burst.





- How to predict the next CPU burst?
 - *exponential average* of the measured lengths of *previous* CPU burst.
 - $\tau_{n+1} = \alpha \tau_n + (1-\alpha)\tau_n$, where
 - τ_n is the length of nth CPU burst,
 - τ_{n+1} is our predicted value for the next CPU burst,
 - for $0 < \alpha < 1$

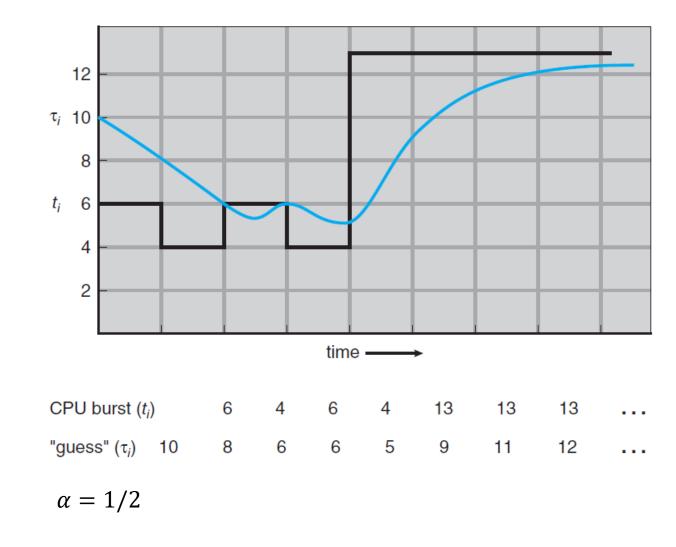


Figure 5.4 *Prediction of the length of the next CPU burst.*





- Note also that
 - The SJF algorithm can be either *preemptive* or *non-preemptive*.
 - The choice arises:
 - when a new process arrives at the *ready* queue
 - while a *previous* process is still executing.
 - What if a *newly* arrived process is *shorter* than
 - what is left of the currently executing process?

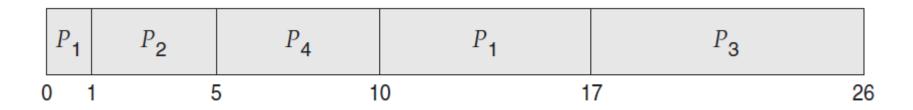


- SRTF Scheduling
 - Shortest-Remaining-Time-First: *Preemptive SJF* scheduling
 - SRTF will preempt the currently running process,
 - whereas a non-preemptive SJF will *allow* it to *finish* its CPU burst.

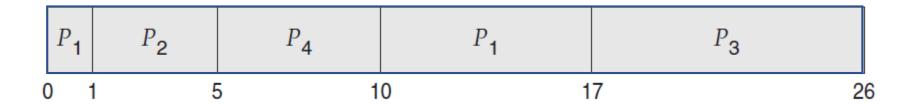


- Consider the following:
 - if the processes arrive at the ready queue at the arrival time.

Process	<u>Arrival Time</u>	Burst Time
P_1	0	8
P_2	1	4
P_3	2	9
P_4	3	5







• The waiting time:

- *Total* Waiting Time: [(10-1)+(1-1)+(17-2)+(5-3)]=26
- Average Waiting Time: 26/4 = 6.5



- Draw a Gantt chart for non-preemptive SJF scheduling,
 - then calculate the average waiting time to be 7.75.

■ Do the same thing with the *turnaround* time.

- with a *non-preemptive SJF* scheduling algorithm
- with a *preemptive SRTF* scheduling algorithm.



- RR Scheduling
 - Round-Robin: *preemptive FCFS* with a *time quantum*.
 - A time quantum (or time slice) is a small unit of time.
 - generally from 10 to 100 milliseconds in length.
 - The ready queue is treated as a *circular queue*.
 - The scheduler goes around the ready queue,
 - allocating the CPU to each process
 - for a time interval of up to 1 time quantum.

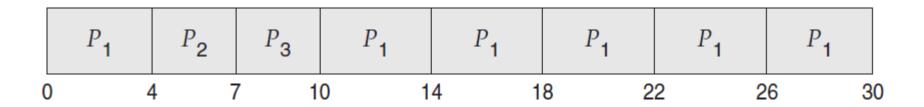


- One of two things will happen:
 - The process may have a CPU burst of *less than* one time quantum.
 - the process itself will release the CPU voluntarily
 - the scheduler will proceed to the next process in the ready queue.
 - If the CPU burst is **longer than** one time quantum,
 - the timer will go off and will cause an interrupt to the OS.
 - a context switch will be executed,
 - the process will be put at the tail of the ready queue.



Process	Burst Time
P_1	24
P_2	3
P_3^2	3

• When we use a time quantum of 4 milliseconds





• The waiting time:

- Waiting Time for $P_1 = 10 4 = 6$, $P_2 = 4$, $P_3 = 7$
- *Total* Waiting Time: (6 + 4 + 7) = 17
- *Average* Waiting Time: 17/3 = 5.66



- Note that
 - The average waiting time under the RR policy is often long.
 - The RR scheduling algorithm is *preemptive*.
 - if a process's CPU burst exceeds one time quantum,
 - that process is *preempted* and is put back in the ready queue.



- The performance of the RR scheduling algorithm
 - depends heavily on the size of the time quantum.

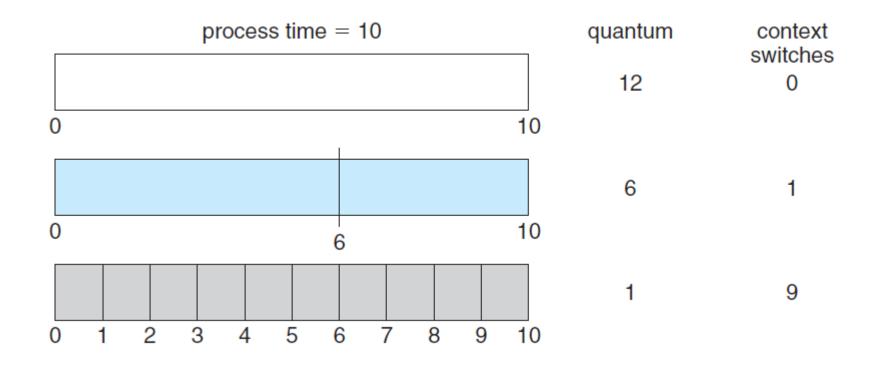
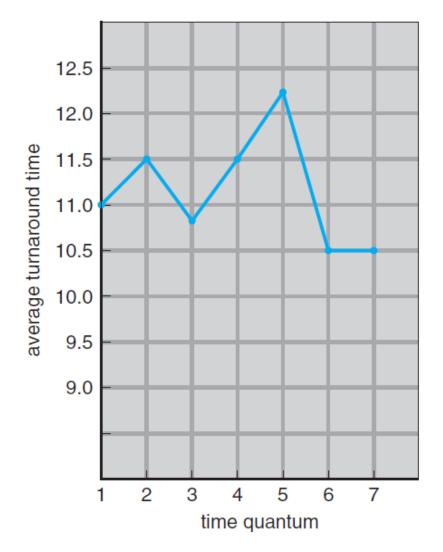


Figure 5.5 How a smaller time quantum increases context switches.







process	time
P_1	6
P_2	3
P_3	1
P_4	7

Figure 5.6 How turnaround time varies with the time quantum.





Priority-base Scheduling

- A *priority* is associated with each process,
 - and the CPU is allocated to the process with the *highest priority*.
 - Processes with *equal* priority are scheduled in FCFS order.
- Note that the *SJF* is a *special case* of the *priority-based* scheduling.
 - in this case, the priority is the *inverse* of the *next CPU burst*.
- We assume that *low* numbers represent *high* priority.



Process	Burst Time	Priority
P_1	10	3
P_2	1	1
P_3	2	4
P_4	1	5
P_5^{-}	5	2



- the average waiting time: 8.2
- the average turnaround time: ?



- Priority scheduling can be
 - either *preemptive* or *non-preemptive*.
- The problem of *starvation* (*indefinite blocking*)
 - a *blocked process*: ready to run, but waiting for the CPU.
 - some low-priority processes may wait indefinitely.

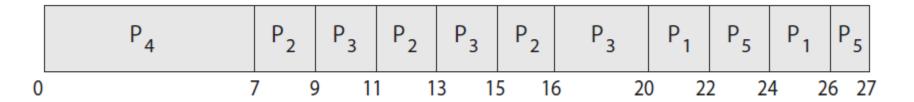
- A solution to the starvation problem is aging
 - gradually increase the priority of processes
 - that wait in the system for a long time.



- Combine RR and Priority scheduling:
 - execute the *highest-priority* process and
 - runs processes with the *same* priority using *round-robin* scheduling.

Process	Burst Time	Priority
P_1	4	3
P_2	5	2
P_3^2	8	2
P_{4}^{σ}	7	1
P_5	3	3

• time quantum = 2







• Multi-Level Queue(MLQ) Scheduling

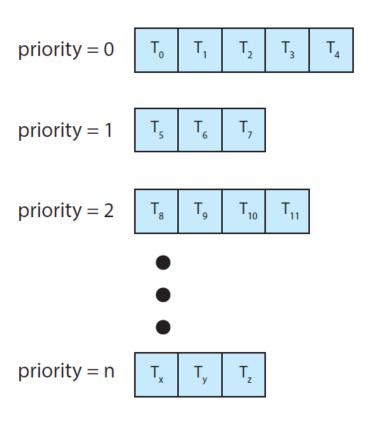


Figure 5.7 Separate queues for each priority.





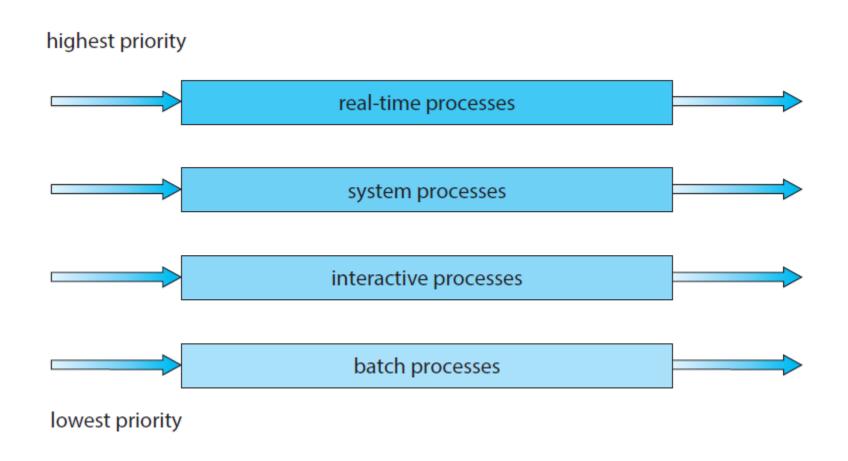


Figure 5.8 Multi-Level Queue scheduling.



Multi-Level Feedback Queue(MLFQ) Scheduling

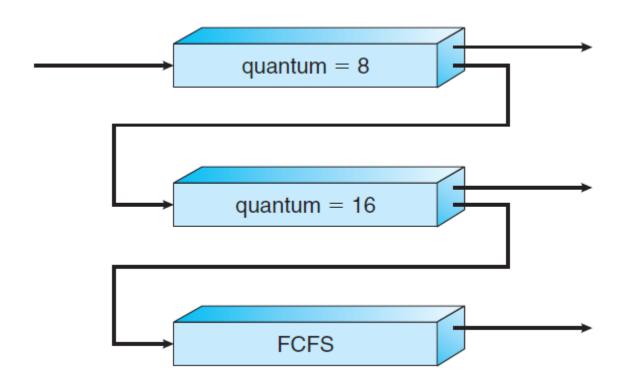


Figure 5.9 Multi-Level Feedback Queue scheduling.





5.4 Thread Scheduling

- On most modern operating systems
 - it is *kernel threads* not *processes* that are being scheduled,
 - and *user threads* are managed by a thread library.
 - So, the kernel is unaware of them,
 - ultimately mapped to associated kernel threads.



5.6 Real-Time CPU Scheduling

- Scheduling in the Real-Time Operating System.
 - Soft Realtime .vs. Hard Realtime
 - Soft real-time systems provide no guarantee
 - as to when a critical real-time process will be scheduled.
 - guarantee only that a critical process is preferred to noncritical one.
 - Hard real-time systems have stricter requirements.
 - A task must be services by its deadline.





Practice Exercises

Exercise 5.3 (p.251)

Process	Arrival Time	Burst Time
P_1	0.0	8
P_2	0.4	4
P_3^-	1.0	1

- a. What is the average turnaround time for these processes with the FCFS scheduling algorithm?
- b. What is the average turnaround time for these processes with the SJF scheduling algorithm?



Practice Exercises

Process	Arrival Time	Burst Time
$\overline{P_1}$	0.0	8
P_2	0.4	4
P_3^-	1.0	1

c. The SJF algorithm is supposed to improve performance, but notice that we chose to run process P_1 at time 0 because we did not know that two shorter processes would arrive soon. Compute what the average turnaround time will be if the CPU is left idle for the first 1 unit and then SJF scheduling is used. Remember that processes P_1 and P_2 are waiting during this idle time, so their waiting time may increase. This algorithm could be known as *future-knowledge scheduling*.



Any Questions?

