

1. Description

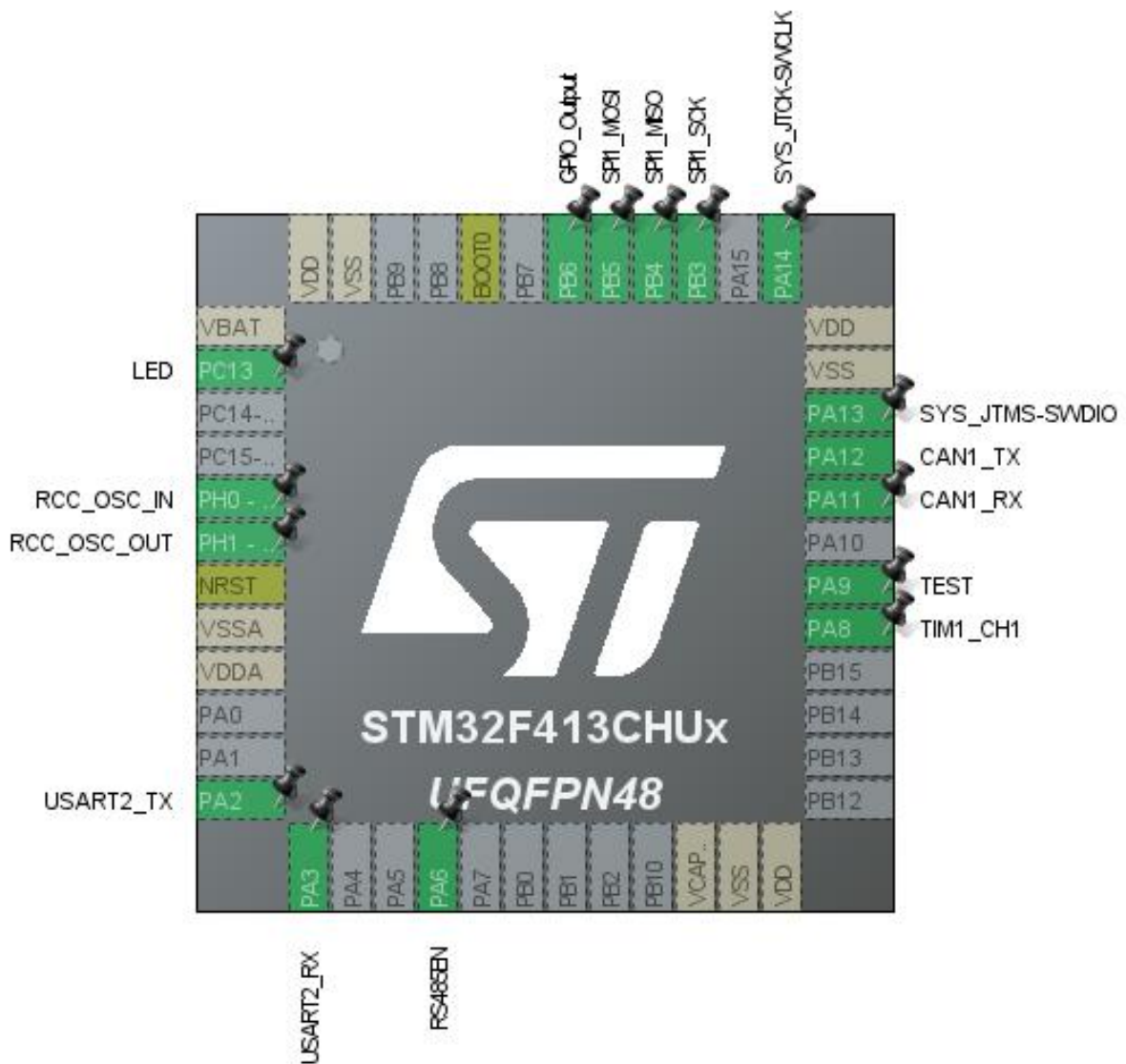
1.1. Project

Project Name	neuron
Board Name	custom
Generated with:	STM32CubeMX 5.4.0
Date	12/26/2019

1.2. MCU

MCU Series	STM32F4
MCU Line	STM32F413/423
MCU name	STM32F413CHUx
MCU Package	UFQFPN48
MCU Pin number	48

2. Pinout Configuration

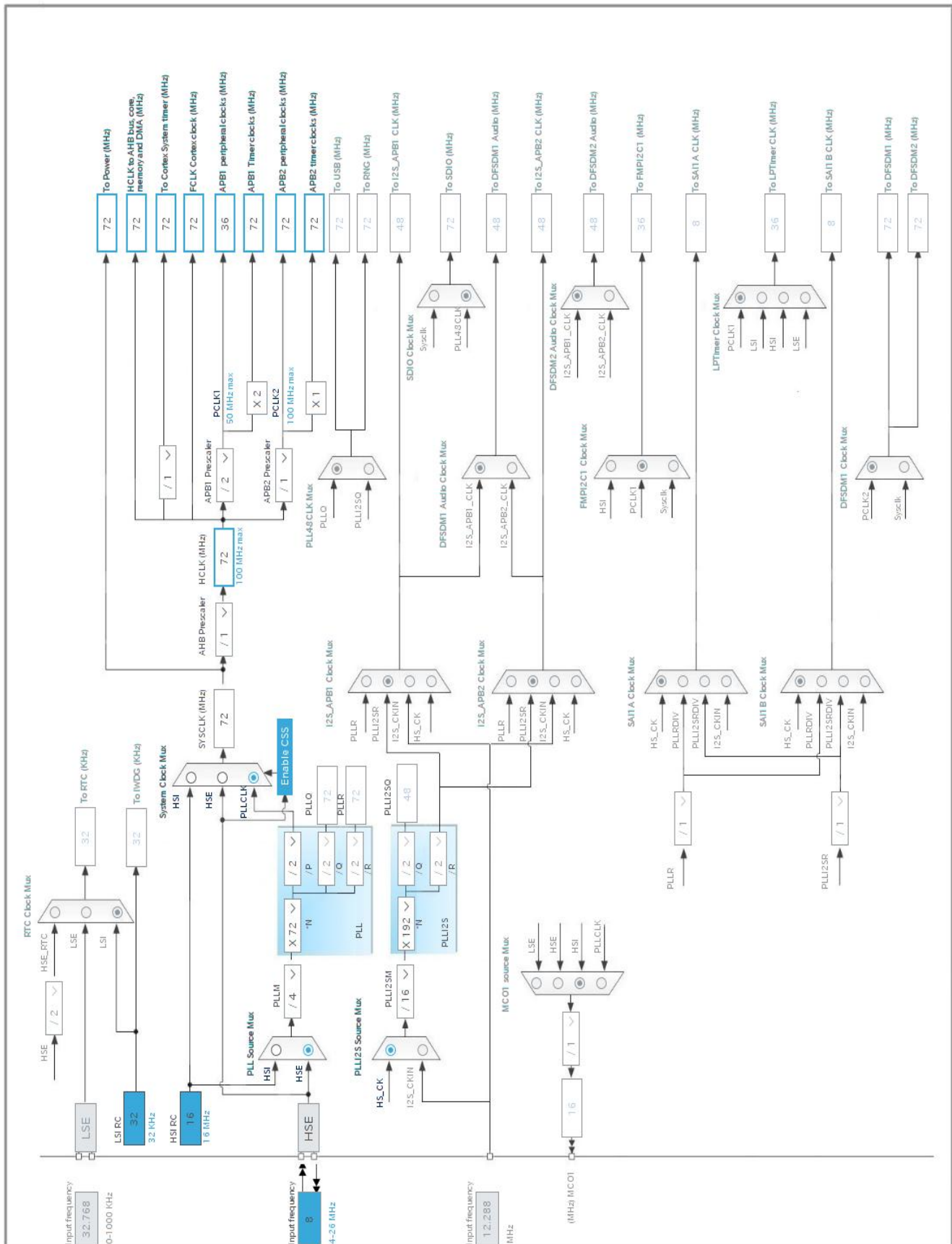


3. Pins Configuration

Pin Number UFQFPN48	Pin Name (function after reset)	Pin Type	Alternate Function(s)	Label
1	VBAT	Power		
2	PC13 *	I/O	GPIO_Output	LED
5	PH0 - OSC_IN	I/O	RCC_OSC_IN	
6	PH1 - OSC_OUT	I/O	RCC_OSC_OUT	
7	NRST	Reset		
8	VSSA	Power		
9	VDDA	Power		
12	PA2	I/O	USART2_TX	
13	PA3	I/O	USART2_RX	
16	PA6 *	I/O	GPIO_Output	RS485EN
22	VCAP_1	Power		
23	VSS	Power		
24	VDD	Power		
29	PA8	I/O	TIM1_CH1	
30	PA9 *	I/O	GPIO_Output	TEST
32	PA11	I/O	CAN1_RX	
33	PA12	I/O	CAN1_TX	
34	PA13	I/O	SYS_JTMS-SWDIO	
35	VSS	Power		
36	VDD	Power		
37	PA14	I/O	SYS_JTCK-SWCLK	
39	PB3	I/O	SPI1_SCK	
40	PB4	I/O	SPI1_MISO	
41	PB5	I/O	SPI1_MOSI	
42	PB6 *	I/O	GPIO_Output	
44	BOOT0	Boot		
47	VSS	Power		
48	VDD	Power		

* The pin is affected with an I/O function

4. Clock Tree Configuration



5. Software Project

5.1. Project Settings

Name	Value
Project Name	neuron
Project Folder	/home/anzai/ros/aerial_robot_ws/src/aerial_robot/aerial_robot_nerve/neuron/neur
Toolchain / IDE	TrueSTUDIO
Firmware Package Name and Version	STM32Cube FW_F4 V1.21.0

5.2. Code Generation Settings

Name	Value
STM32Cube MCU packages and embedded software	Copy only the necessary library files
Generate peripheral initialization as a pair of '.c/.h' files	Yes
Backup previously generated files when re-generating	No
Delete previously generated files when not re-generated	Yes
Set all free pins as analog (to optimize the power consumption)	No

6. Power Consumption Calculator report

6.1. Microcontroller Selection

Series	STM32F4
Line	STM32F413/423
MCU	STM32F413CHUx
Datasheet	029162_Rev5

6.2. Parameter Selection

Temperature	25
Vdd	null

7. IPs and Middleware Configuration

7.1. CAN1

mode: Mode

7.1.1. Parameter Settings:

Bit Timings Parameters:

Prescaler (for Time Quantum)	4 *
Time Quantum	111.11111111111111 *
Time Quanta in Bit Segment 1	4 Times *
Time Quanta in Bit Segment 2	4 Times *
ReSynchronization Jump Width	1 Time

Basic Parameters:

Time Triggered Communication Mode	Disable
Automatic Bus-Off Management	Disable
Automatic Wake-Up Mode	Disable
No-Automatic Retransmission	Disable
Receive Fifo Locked Mode	Disable
Transmit Fifo Priority	Disable

Advanced Parameters:

Operating Mode	Normal
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7.2. GPIO

7.3. RCC

High Speed Clock (HSE): Crystal/Ceramic Resonator

7.3.1. Parameter Settings:

System Parameters:

VDD voltage (V)	3.3
Instruction Cache	Enabled
Prefetch Buffer	Enabled
Data Cache	Enabled
Flash Latency(WS)	2 WS (3 CPU cycle)

RCC Parameters:

HSI Calibration Value	16
TIM Prescaler Selection	Disabled

HSE Startup Timeout Value (ms)	100
LSE Startup Timeout Value (ms)	5000
Power Parameters:	
Power Regulator Voltage Scale	Power Regulator Voltage Scale 1

7.4. SPI1

Mode: Full-Duplex Master

7.4.1. Parameter Settings:

Basic Parameters:

Frame Format	Motorola
Data Size	8 Bits
First Bit	MSB First

Clock Parameters:

Prescaler (for Baud Rate)	8 *
Baud Rate	9.0 MBits/s *
Clock Polarity (CPOL)	Low
Clock Phase (CPHA)	1 Edge

Advanced Parameters:

CRC Calculation	Disabled
NSS Signal Type	Software

7.5. SYS

Debug: Serial Wire

Timebase Source: SysTick

7.6. TIM1

Clock Source : Internal Clock

Channel1: PWM Generation CH1

7.6.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value)	1 *
Counter Mode	Center Aligned mode1 *
Counter Period (AutoReload Register - 16 bits value)	36000 *

Internal Clock Division (CKD)	No Division
Repetition Counter (RCR - 8 bits value)	0
Trigger Output (TRGO) Parameters:	
Master/Slave Mode (MSM bit)	Disable (Trigger input effect not delayed)
Trigger Event Selection	Reset (UG bit from TIMx_EGR)

Break And Dead Time management - BRK Configuration:

BRK State	Disable
BRK Polarity	High

Break And Dead Time management - Output Configuration:

Automatic Output State	Disable
Off State Selection for Run Mode (OSSR)	Disable
Off State Selection for Idle Mode (OSSI)	Disable
Lock Configuration	Off

PWM Generation Channel 1:

Mode	PWM mode 1
Pulse (16 bits value)	18000 *
Fast Mode	Disable
CH Polarity	High
CH Idle State	Reset

7.7. USART2

Mode: Asynchronous

7.7.1. Parameter Settings:

Basic Parameters:

Baud Rate	1000000 *
Word Length	8 Bits (including Parity)
Parity	None
Stop Bits	1

Advanced Parameters:

Data Direction	Receive and Transmit
Over Sampling	16 Samples

* User modified value

8. System Configuration

8.1. GPIO configuration

IP	Pin	Signal	GPIO mode	GPIO pull/up pull down	Max Speed	User Label
CAN1	PA11	CAN1_RX	Alternate Function Push Pull	No pull-up and no pull-down	High *	
	PA12	CAN1_TX	Alternate Function Push Pull	No pull-up and no pull-down	High *	
RCC	PH0 - OSC_IN	RCC_OSC_IN	n/a	n/a	n/a	
	PH1 - OSC_OUT	RCC_OSC_OUT	n/a	n/a	n/a	
SPI1	PB3	SPI1_SCK	Alternate Function Push Pull	No pull-up and no pull-down	High *	
	PB4	SPI1_MISO	Alternate Function Push Pull	No pull-up and no pull-down	High *	
	PB5	SPI1_MOSI	Alternate Function Push Pull	No pull-up and no pull-down	High *	
SYS	PA13	SYS_JTMS-SWDIO	n/a	n/a	n/a	
	PA14	SYS_JTCK-SWCLK	n/a	n/a	n/a	
TIM1	PA8	TIM1_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	
USART2	PA2	USART2_TX	Alternate Function Push Pull	Pull-up	High *	
	PA3	USART2_RX	Alternate Function Push Pull	Pull-up	High *	
GPIO	PC13	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	LED
	PA6	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	RS485EN
	PA9	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	TEST
	PB6	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	

8.2. DMA configuration

nothing configured in DMA service

8.3. NVIC configuration

Interrupt Table	Enable	Preenmption Priority	SubPriority
Non maskable interrupt	true	0	0
Hard fault interrupt	true	0	0
Memory management fault	true	0	0
Pre-fetch fault, memory access fault	true	0	0
Undefined instruction or illegal state	true	0	0
System service call via SWI instruction	true	0	0
Debug monitor	true	0	0
Pendable request for system service	true	0	0
System tick timer	true	0	0
CAN1 RX1 interrupt	true	0	0
USART2 global interrupt	true	0	0
PVD interrupt through EXTI line 16	unused		
Flash global interrupt	unused		
RCC global interrupt	unused		
CAN1 TX interrupts	unused		
CAN1 RX0 interrupts	unused		
CAN1 SCE interrupt	unused		
TIM1 break interrupt and TIM9 global interrupt	unused		
TIM1 update interrupt and TIM10 global interrupt	unused		
TIM1 trigger and commutation interrupts and TIM11 global interrupt	unused		
TIM1 capture compare interrupt	unused		
SPI1 global interrupt	unused		
FPU global interrupt	unused		

* User modified value

9. Software Pack Report